

Logarithmic Resolution of Singularities

M. Temkin

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A joint project with D. Abramovich and J. Włodarczyk on resolution of singularities of morphisms and log varieties.

References:

- [ATW17] "Principalization of ideals on logarithmic orbifolds", JEMS **22**, 2020.
- [ATW20] "Relative desingularization and principalization of ideals".
- [ATW19] "Functorial embedded resolution via weighted blowings up".

Classical resolution

- For simplicity, we only consider varieties over a field k . The characteristic is zero. Also, can take $k = \mathbb{C}$ and work with analytic spaces (using the usual topology instead of the étale one).
- Resolution of singularities associates to an integral variety Z a modification (i.e. proper birational) $Z_{\text{res}} \rightarrow Z$ with a smooth Z_{res} .
- Hironaka 1964 (the Fields medal work): a resolution exists.
- Hironaka, Giraud 70ies: simplifications, maximal contact.
- Villamayor, Bierstone-Milman 80ies-90ies: algorithmic and canonical resolution.
- Włodarczyk 2005: smooth-functoriality, i.e. $Z'_{\text{res}} = Z' \times_Z Z_{\text{res}}$ for any smooth $Z' \rightarrow Z$. This both simplifies the arguments and has stronger applications (e.g. equivariant resolution).

Relative and logarithmic resolution

- [ATW17] The classical algorithm has a logarithmic analogue associating to each generically log smooth log variety X a modification $X_{\text{res}} \rightarrow X$ with a log smooth log DM stack X_{res} . It is functorial w.r.t. log smooth morphisms $Y \rightarrow X$.
- [ATW20] The same logarithmic resolution algorithm applies to a morphism $f: X \rightarrow B$ of log schemes: it constructs $X_{\text{res}} \rightarrow X$ with a log smooth $X_{\text{res}} \rightarrow B$, but can fail when $\dim(B) > 1$.
- The new ingredient: there exists a modification $h: B' \rightarrow B$ s.t. the algorithm does not fail for the base change $f': X' \rightarrow B'$. Moreover, $X'_{\text{res}} \rightarrow X_{\text{res}}$ is compatible with further base changes $B'' \rightarrow B'$.
- In the current version h is not canonical, so resolution of morphisms is only relatively functorial.
- Work in progress: h can be chosen canonically.

Plan

- 1 Classical resolution
 - General framework
 - Induction on dimension
- 2 Logarithmic geometry
- 3 Logarithmic algorithms

Embedded resolution

- All canonical methods before [ATW17] construct essentially the same algorithm built on Hironaka's framework. Everything is done locally and glues due to the functoriality.
- The resolution is embedded: one (locally) embeds X into a manifold (i.e. a smooth variety) M . To the pair (M, X) one associates a modification of manifolds $f : M_{\text{res}} \rightarrow M$ and $X_{\text{res}} \hookrightarrow X \times_M M_{\text{res}}$ is a certain transform of X under f .
- Functorial embedded resolution implies functorial non-embedded one because an embedding $X \hookrightarrow M$ with minimal $\dim(M)$ is unique (étale) locally.

Main choices

The following choices are done in the classical resolution:

- (1) Class of modifications: the algorithm iteratively blows up submanifolds $V \subset M$. Notation: $f_i: M_{i+1} = \text{Bl}_{V_i}(M_i) \rightarrow M_i$.
- (2) Transforms: one pullbacks X and subtracts a multiple of the exceptional divisor: $X_{i+1} = f_i^{-1}(X_i) - dE_{f_i}$.
- (3) Choice of centers: the order $d = d_1$ of $I = I_X$ at $x \in M$ is a (very crude) primary invariant.
- (4) The history: to avoid loops the algorithm encodes history in the iterated exceptional sncd E . The number $s(x)$ of its components at x is another primary invariant.
- (5) Induction: one iteratively restricts to hypersurfaces of maximal contact, getting induction on $n = \dim(M)$. The actual invariant, whose maximal locus is blown up, is closer to $(d_1, s_1, d_2, s_2, \dots, d_n)$ with the lex order.

History and a dream algorithm

The classical algorithm has a subtle inductive structure and encodes history of the process in the boundary. With our choices a no-history algorithm does not exist:

Example (No progress.)

Let $\phi = x^2 - yzt$ and $X = V(\phi)$ in $M = \mathbb{A}^4$. Then $V = 0$ is the only smooth S_3 -equivariant subscheme containing 0 in X_{sing} , but $M' = \text{Bl}_V(M)$ has charts with $X' = f^{-1}(X) - 2E$ having the same singularity, e.g. in M'_y we have

$$\phi = (x'y')^2 - y'(y'z')(y't') = y'^2(x'^2 - y'z't').$$

A similar computation shows that blowing up the pinch point of Whitney umbrella $V(x^2 - y^2z)$ yields a pinch point again.

Using weighted blow ups we have constructed in [ATW19] a dream algorithm which just iteratively blows up the maximal invariant locus, so that the invariant drops. No history is needed there.

The boundary

- After a blow up $f: M' \rightarrow M$ each point $x \in E = V(t)$ has a good given coordinate t (unique up to a unit) coming from the history of the resolution. One only uses coordinate systems which include t .
- Inductively, for a sequence $f_i: M_{i+1} \rightarrow M_i$ we set $E_{i+1} = f_i^{-1}(E_i) \cup E_{f_i}$ and call it the accumulated boundary of M .
- We always work with coordinates t_1, \dots, t_n s.t. $V_i = V(t_{i_1}, \dots, t_{i_j})$ and $E_i = (t_{n-r+1} \dots t_n)$. So, E_i is an snc (simple normal crossings) divisor and V_i has simple normal crossings with E_i (lies in few components and is transversal to others).
- We call the boundary coordinates exceptional or monomial and denote them m_1, \dots, m_r . So, $(t_1, \dots, t_n) = (t_1, \dots, t_{n-r}, m_1, \dots, m_r)$.

The role of the boundary

Good news:

- Using canonical monomial coordinates decreases choices, makes the construction more canonical, helps to avoid loops.
- Boundary can accumulate parts of $I = I_X$: we set $I = I^{\text{mon}} I^{\text{pure}}$, where $I^{\text{mon}} = (m_1^{l_1} \dots m_r^{l_r})$ and I^{pure} is purely non-monomial.

Bad news/another side of the same coin:

- Must treat E and monomial coordinates with a special care.
- Less possibilities for coordinates, centers must have snc with E .

Remark

Many technical complications of the classical algorithm are due to a bad separation of regular and exceptional coordinates because both are used to define the order.

Principalization

- All algorithms operate algebraically with $I = I_X$ and solve the following principalization problem: find a sequence of submanifold blow ups $(M_n, E_n) \rightarrow \cdots \rightarrow (M, E)$ such that $I_n = I_X \mathcal{O}_{X_n}$ is invertible and monomial (i.e. supported on E_n).
- Magic: the last non-empty strict transform $X_I \subset M_I$ of X equals to V_I . So, it is smooth and transversal to E_I .
- Thus, principalization implies resolution $X_I \rightarrow X$ and even resolves the boundary $E_I|_{X_I}$ (a strong smell of a log geometry).
- A great profit: working with ideals provides a lot of flexibility.

Order reduction

- The main invariant of the algorithm is $d = \text{ord}(I^{\text{pure}})$, where $\text{ord}(J) = \min_{f \in J} \text{ord}(f)$. For example, $\text{ord}(x^2 - yz^2)$ is 2 at any point of the z -axis and $\text{ord}_O(x^5 + y^7, x^3z^3) = 5$.
- One works with marked (or weighted) ideals (I, d) where $d \geq 1$, only uses $M' = Bl_V(M)$ with $V \subseteq (I, d)_{\text{sing}} := \{x \in M \mid \text{ord}_x(I) \geq d\}$, and updates I by $I' = (I\mathcal{O}_{M'})|_{E'}^{-d}$. E.g., as we have computed earlier $(x^2 - yzt, 2)' = (x'^2 - y'z't', 2)$ on the y -chart.
- Order reduction finds a sequence $M_n \rightarrow \dots \rightarrow M$ of such (I, d) -admissible blow ups so that $(I_n, d)_{\text{sing}} = \emptyset$. Its existence implies principalization just by taking $d = 1$.

Remark

The so-called max order case when $d = \text{ord}(I^{\text{pure}})$ is the main one. It implies the general one relatively easily (and characteristic free). One has to consider the general case due to a bad (inductive) karma.

Maximal contact

- The miracle enabling induction on dimension is that in the maximal order case, order reduction of (I, d) is equivalent to that of $(C(I)|_H, d!)$, i.e. a blow up sequence reduces the order of (I, d) iff it reduces the order of $(C(I)|_H, d!)$. Here $C(I)$ is a coefficient ideal and H is a hypersurface of maximal contact.
- The Main Example: if $I = (t^d + a_2 t^{d-2} + \dots + a_d)$ with $t = t_1$ and $a_i(t_2, \dots, t_n)$, then $H = V(t)$ and $C(I) = (a_2^{d!/2}, \dots, a_d^{d!/d})$.

Remark

- (i) Why coefficient ideal? Because, unlike $C(I)|_H$, the stupid restriction $I|_H = (a_d)|_H$ loses a lot of information.
- (ii) Each coefficient a_i has natural weight i .
- (iii) No problem to have $a_1 = 0$ in characteristic zero (enough $d \in k^\times$).

Derivations

The main tool for a choice-free description of the algorithm is the derivation ideals $D(I) = D^1(I)$ generated by the elements of I and their derivations, and its iterations $D^n(I) = D(D^{n-1}(I))$. Note that $\text{ord}_x(I) = \text{ord}_x(D(I)) + 1$ for $x \in V(I)$. The derivation provides a conceptual way to define all basic ingredients excluding the monomial ones:

- (1) $\text{ord}_x(I)$ is the minimal d such that $D^d(I_x) = \mathcal{O}_x$.
- (2) Maximal contact is any $H = V(t)$, where t is a regular coordinate in $D^{d-1}(I_x)$ (in particular, H is smooth).
- (3) The coefficient ideal $C(I)$ is just $\sum_{i=0}^{d-1} (D^i(I))^{d!/(d-i)}$.

Remark

The only serious difficulty in proving canonicity of the algorithm is to show independence of the choice of a maximal contact.

Log derivations

The module of logarithmic derivations D^{\log} is spanned by $m_j \partial_{m_j}$ and ∂_{t_i} for regular t_i 's. These are the derivations preserving E (i.e. taking I_E to itself). For almost all needs it is easier and more conceptual to use D^{\log} , but it does not compute the order. This is why one has to use the usual derivations and runs into two complications as follows.

Choice of the maximal contact

- (1) If E is not transversal to H then $E|_H$ makes no sense for us, hence we loose the control on the choice of centers having snc with E .

Solution: new boundary is transversal to H (and any center lying in it), so first iteratively reduce the order of I along the locus where the multiplicity s of the old boundary is maximal (practically, work with $I + I_{E(s)}^d$). Thus, our primary invariant is (d, s^{old}) ordered lexicographically.

Monomial contribution to the order

- (2) When $\text{ord}(I) \geq d$ but $\text{ord}(I^{\text{pure}}) < d$ we cannot proceed by looking only at I^{pure} . This happens because I^{mon} contributes to the order and causes that $(I, d)_{\text{sing}} \neq \emptyset = (I^{\text{pure}}, d)_{\text{sing}}$.

Solution:

1. Reduce $e = \text{ord}(I^{\text{pure}})$ only along the locus where $\text{ord}(I^{\text{mon}}) \geq d - e$. Practically, we resolve the so-called companion ideal, which is the weighted sum of (I^{pure}, e) and $(I^{\text{mon}}, d - e)$.
2. Once $e = 0$ (i.e. $I^{\text{pure}} = (1)$), apply a purely combinatorial step to I^{mon} .

What is the boundary?

To proceed let us try to understand what the boundary really is.

- Unlike the embedded scheme X , I think it is wrong to view E as a subscheme of M (though it is determined by it). This is hinted at by functoriality: we consider blow ups $(M', E') \rightarrow (M, E)$ which do not take E' to E : one has that $f^{-1}(E) \hookrightarrow E'$ instead of $E' \hookrightarrow f^{-1}(E)$.
- The boundary is also determined by the sheaf of monomials $\mathcal{M}_M = \mathcal{M}_M(\log E) = \mathcal{O}_{M \setminus E}^\times \cap \mathcal{O}_M \subset (\mathcal{O}_M, \cdot)$ consisting of elements invertible outside of E . This gives the right functoriality: $f^*(\mathcal{M}_M(\log E)) \rightarrow \mathcal{M}_{M'}(\log E')$.
- In fact, the sheaf of monomials $\mathcal{M}_M(\log E)$ is precisely what we need from E !
- Locally $\mathcal{M}_M = \mathcal{O}_M^\times \times \mathbb{N}^s$ but this splitting (called a monoidal chart) is non-canonical: it is given by fixing exceptional coordinates m_1, \dots, m_s .

Logarithmic varieties

Definition

A logarithmic variety (X, \mathcal{M}_X) consists of a variety X with a sheaf of monoids \mathcal{M}_X and a homomorphism $\alpha_X: \mathcal{M}_X \rightarrow (\mathcal{O}_X, \cdot)$ such that $\mathcal{M}_X^\times = \alpha_X^{-1}(\mathcal{O}_X^\times)$. A morphism is a compatible pair $f: X' \rightarrow X$ and $f^*\mathcal{M}_X \rightarrow \mathcal{M}_{X'}$.

- The example covering our needs is $(X, \mathcal{M}_X(\log D))$ for a divisor D . Morphisms are $f: X' \rightarrow X$ s.t. $f^{-1}(D) \hookrightarrow D'$.
- Many constructions extend to log geometry, e.g. $\Omega_{(X, \mathcal{M}_X)}$ is generated by Ω_X and elements δm for $m \in M_X$ subject to relations $d\alpha(m) = \alpha(m)\delta m$ (i.e. δm is the log differential of m).
- One also defines log smooth morphisms. As in the classical case, they have locally free sheaves of relative differentials of expected rank.

Toroidal varieties

- Log smooth varieties are just toroidal ones: étale (analytically or formally) locally it suffices to work with the chart $X = \text{Spec } \mathbb{C}[M][t_1, \dots, t_l]$ at its origin O , where M is the monoid of integral points in a rational polyhedral cone. The log structure is induced by M , and $\Omega_{(X, M)}$ is freely generated by dt_i and δm_i , where $\{m_i\}$ is any basis of M^{gp} . The classical notation is (X, U) or (X, D) with $D = \cup_{m \in M} V(m)$ and $U = X \setminus D$.
- In other words, $\mathcal{O}_{X, x} = \mathbb{C}[[M]][[t_1, \dots, t_l]]$. We view t_i as regular coordinates and all elements of M as monomial coordinates.
- Monomial democracy: M does not have to be free anymore and there is no canonical base of M^{gp} .

Toroidal morphisms

Log smooth morphisms of toroidal varieties are just toroidal morphisms, i.e. they are (étale-locally) modelled on toric maps and formally-locally look as

$$\mathbb{C}[[M]][[t_1, \dots, t_r]] \hookrightarrow \mathbb{C}[[N]][[t_1, \dots, t_n]], M \hookrightarrow N.$$

Example

(i) Semistable maps with appropriate log structures. For example, $\mathrm{Spec} \mathbb{C}[x, y] \rightarrow \mathrm{Spec} \mathbb{C}[\pi]$ given by $\pi = x^a y^b$ is log smooth for the log structures given by $x^{\mathbb{N}} \times y^{\mathbb{N}}$ and $\pi^{\mathbb{N}}$. The relative differentials are spanned by $\delta x = -\frac{b}{a} \delta y$.

(ii) Kummer log-étale covers are obtained when $N \subset \frac{1}{d}M$ and $r = n$. Relative log differentials vanish. Finite but usually non-flat, e.g. $\mathrm{Spec} \mathbb{C}[x, y] \rightarrow \mathrm{Spec} \mathbb{C}[x^2, xy, y^2]$ with the log structures of monomials in x, y .

Some remarks

Remark

Toroidal morphisms are log smooth maps of log smooth varieties. In a sense, log geometry extends both to the non-smooth case (and \mathbb{Z} -schemes).

Remark

The most interesting feature of the new algorithm is functoriality w.r.t. Kummer log-étale covers, e.g. obtained by extracting roots of the monomial coordinates in the classical setting, or obtained by extracting roots of π in the semistable reduction case. This is out of reach (and unnatural) for the classical algorithms.

Main results

Ignoring an orbifold aspect, our main result is:

Theorem (Log principalization)

Given a toroidal variety X with an ideal $I \subset \mathcal{O}_X$ there exists a sequence of admissible blowings up of toroidal varieties $X_n \rightarrow \cdots \rightarrow X$ such that the ideal $I\mathcal{O}_{X_n}$ is monomial. This sequence is compatible with log smooth morphisms $X' \rightarrow X$.

As in the classical situation this implies

Theorem (Log resolution)

For any integral logarithmic variety Z there exists a modification $Z_{\text{res}} \rightarrow Z$ such that Z_{res} is log smooth. This is functorial w.r.t. log smooth morphisms $Z' \rightarrow Z$.

The method

In brief, we want to log-adjust all parts of the classical algorithm. The main adjustment is to only use log derivations:

- (1) $\text{logord}_X(I)$ is the minimal d such that $(D^{\text{log}})^d(I_X) = \mathcal{O}_X$.
- (2) Maximal contact is any $H = V(t)$, where t is any regular coordinate in $(D^{\text{log}})^{d-1}(I_X)$ (in particular, H is toroidal).
- (3) The coefficient ideal $C(I)$ is just $\sum_{i=0}^{d-1} ((D^{\text{log}})^i(I))^{d!/(d-i)}$.
- (4) In addition, J is (I, d) -admissible if $I \subseteq J^d$ and, for appropriate coordinates, $J = (t_1, \dots, t_l, m_1, \dots, m_r)$ for any set of monomials. Then $X' = Bl_J(X)$ is toroidal and the d -transform $I' = (I\mathcal{O}_{X'})/(J\mathcal{O}_{X'})^{-d}$ is defined. Note that J is submonomial – a monomial ideal on the log submanifold $V(t_1, \dots, t_l)$.

Infinite log order

- Note that $\text{logord}(t_i) = 1$ but $\text{logord}(m) = \infty$. This is the main novelty that allows functoriality w.r.t. extracting roots of monomials (Kummer covers).
- As a price we have to do something special when $\text{logord}(I) = \infty$, but this is simple: just start with blowing up the minimal monomial ideal I_{mon} containing I . For example, if $I = (\sum_{i \in \mathbb{N}^r} m_i t^i)$ then $I_{\text{mon}} = (m_i)$. The single toroidal blow up makes logord finite! (This result is due to Kollár.)
- Our algorithm is simpler, in particular, it avoids both complications (max contact is given by a regular coordinate!).
- In a sense, we completely separate dealing with regular coordinates via log order and dealing with monomials via combinatorics (i.e. toroidal blow ups).
- The invariant is just (d_n, \dots, d_1) with $d_i \in \mathbb{N}$, $d_1 \in \{0, \infty\}$.

Orbifolds

- Is all this so elementary? Where is the cheating?
- Well. Our algorithm does not distinguish monomials and their roots. In fact, we view this as a serious advantage (log smooth functoriality). As another side of the coin, to achieve correct weights and admissibility, the algorithm often insists to use Kummer monomials $m^{1/d}$.
- This can be by-passed by working on log-étale Kummer covers, which is ok due to the strong functoriality we prove. The Kummer-local description remains the same as we saw. However, in order to describe the algorithm via modifications of X we have to use orbifolds and non-representable modifications $X' \rightarrow X$ that we call Kummer blow ups.
- This is ok for applications, because we can remove the stacky structure afterwards by a separate torification algorithm. Though the latter is only compatible w.r.t. smooth morphisms.

An example

Example

(i) Take $X = \text{Spec } \mathbb{C}[t, m]$ and $I = (t^2 - m^2)$. Then $\text{logord}_O(I) = 2$, $H = V(t)$, $C(I)|_H = (m^2, 2)$, the order reduction of $C(I)|_H$ blows up $(m^2)^{1/2} = (m)$, and the order reduction of I blows up (t, m) . Just as in the classical case.

(ii) If $I = (t^2 - m)$ then $\text{logord}_O(I) = 2$, $H = V(t)$, $C(I)|_H = (m, 2)$, the order reduction of $C(I)|_H$ blows up $(m^{1/2})$, and the order reduction of I blows up $(t, m^{1/2})$. This is a non-representable Kummer blow up whose coarse moduli space $Bl_{(t^2, m)}(X)$ is not toroidal.

Remark

More generally, the weighted blow up of $((t_1, d_1), \dots, (t_r, d_r))$ in \mathbb{A}^n is the coarse space of a non-representable modification with a smooth source. They are used in the dream algorithm of [ATW19] and should be useful for other classical problems in birational geometry.