
GEOMETRY OF THE SPACE OF DENSITY STATES

Jesús Clemente Gallardo

`jcg@unizar.es`



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- ▣ Geometric Quantum Mechanics.
- ▣ The space of density states.
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Collaboration with Giuseppe Marmo.

Results from: J. F. Cariñena, J. Grabowski, M. Kus, V. I. Manko, G. Sudarshan...

Based on: Kibble, Ashtekar, Brody and Hughston, Cirelly and co, Benvegnu and co



GEOMETRIC QUANTUM MECHANICS

Usual Quantum Mechanics

$$\psi \in \mathcal{H}$$

$$\dim_{\mathbb{C}} \mathcal{H} = n$$

$\langle \cdot, \cdot \rangle$ Hermitian

$$A : \mathcal{H} \rightarrow \mathcal{H}$$

$$AB$$

$$AB + BA$$

$$[A, B]$$

Schrödinger eq.

$$A|\psi\rangle = \lambda|\psi\rangle$$

Geometric QM

$$\psi \in \mathcal{H}_{\mathbb{R}}$$

$$\dim \mathcal{H}_{\mathbb{R}} = 2n$$

(g, ω, J) Kähler

$$\begin{cases} T_A : (\phi, \psi) \rightarrow (\phi, A\psi) \\ X_A : \psi \rightarrow (\psi, A\psi) \\ Y_A : \psi \rightarrow (\psi, JA\psi) \\ f_A(\psi) = \langle \psi, A\psi \rangle \quad e_A(\psi) = \frac{\langle \psi, A\psi \rangle}{\langle \psi, \psi \rangle} \end{cases}$$

$$f_A \star f_B$$

$$f_{AB+BA} = G(df_A, df_B)$$

$$f_{[A,B]} = \{f_A, f_B\}$$

$$f_A f_B$$

Flow of Y_H

$$de_A(\psi) = 0 \quad e_A(\psi) = \lambda$$

CONT

In Geometric Quantum Mechanics observables belong to $i\mathfrak{u}(\mathcal{H})$. By using the Killing-Cartan form

$$\langle A, B \rangle = \text{Tr}AB \Rightarrow \langle A, \cdot \rangle \in \mathfrak{u}^*(\mathcal{H}) \Rightarrow \text{Poisson}$$

This relation is one-to-one.

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A, B

$AB + BA$

$[A, B]$

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Heisenberg eq.

Geometric QM

\hat{A}, \hat{B}

$R(d\hat{A}, d\hat{B})(\xi) = \xi(AB + BA)$

$\Lambda(d\hat{A}, s\hat{B})(\xi) = \xi(AB - BA)$

$\widehat{AB}(\xi) = \xi(AB) = \hat{A} \star \hat{B}$

$\dot{\hat{A}} = \frac{i}{\hbar} \{\hat{H}, \hat{A}\}$

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In Geometric Quantum Mechanics observables belong to $\mathfrak{u}(\mathcal{H})$. By using the Killing-Cartan form

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On $\mathfrak{u}^*(\mathcal{H})$ we can consider thus a Jordan product, a Poisson product and a nonlocal product which translate the properties of the algebra of observables of our quantum system.

UNIFYING FRAMEWORKS

Consider the natural action $U(N) \times \mathcal{H} \rightarrow \mathcal{H}$ and the corresponding momentum mapping

$$\mu : \mathcal{H} \rightarrow \mathfrak{u}^*(\mathcal{H}) \quad \mu(\psi) = |\psi\rangle\langle\psi| = \rho_\psi$$

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PROJECTING

If we consider the complex projective space $\pi : \mathcal{H}_0 \rightarrow \mathcal{P}\mathcal{H}$ everything works

$$\tilde{\mu} : \mathcal{P}\mathcal{H} \rightarrow \mathfrak{u}^*(\mathcal{H}) \quad \tilde{\mu}(\psi) = \frac{|\psi\rangle\langle\psi|}{\langle\psi, \psi\rangle} = \rho_{[\psi]}$$

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Lemma:

$$\tilde{\mu}_*(\pi_*(Y_H)) = \{\hat{H}, \cdot\}$$

THE SPACE OF DENSITY MATRICES

μ embeds the set of pure states on $u^*(\mathcal{H})$. We can consider a basis $\{\rho_i\}$ of those, satisfying

$$\rho_k^2 = \rho_k \quad \rho_k^\dagger = \rho_k \quad \text{Tr} \rho_k = 1$$

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We call **density states** to the set of convex combinations

$$\mathcal{D}(\mathcal{H}) = \left\{ \rho = \sum_k p_k \rho_k \mid \sum_k p_k = 1 \right\}$$

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LEMMA $\mathcal{D}(\mathcal{H})$ inherits the geometric structure from $\mathfrak{u}^*(\mathcal{H})$:

- ▣ The Jordan structure $R_\xi(X_A) = (\xi, [\xi, A]_+)$
- ▣ The Poisson structure (which is degenerate) $J_\xi(X_A) = (\xi, [\xi, A])$
- ▣ A (generalized) complex structure $J^3 = -J$

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These objects define the corresponding distributions D_Λ and D_R . From them, we can define

$$D_0 = D_\Lambda \cap D_R \quad D_1 = D_\Lambda + D_R$$

CONT

THEOREM $\mathcal{D}(\mathcal{H})$ is a stratified manifold with respect to the GL -action

$$(T, \rho) \rightarrow \frac{T\rho T^\dagger}{\text{Tr}(T\rho T^\dagger)} :$$

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ADVANTAGES

- ▣ The use of tools borrowed from Classical Mechanics
- ▣ Simplicity from the algebraic point of view
- ▣ Formulation of quantum control problems from a classical perspective.

A SIMPLE PROBLEM

Consider the case of a system of two qubits. The Hilbert space in this case is

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We can consider a natural basis for $\mathfrak{u}(4)$ (called sometimes Fano basis)

$$\zeta = \{\mathbb{I}_4, i\sigma_i \otimes \mathbb{I}_2, i\mathbb{I}_2 \otimes \sigma_i, i\sigma_i \otimes \sigma_j | i, j = 1, 2, 3\}$$

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A point $\rho \in \mathcal{D}(\mathbb{C}^4) \subset \mathfrak{u}^*(4)$ will be represented thus by a set $\{\lambda_0, m_i, n_i, r_{ij}\}_{i,j=1,2,3}$ of real numbers:

$$\rho = i\lambda_0\mathbb{I}_4 + i \sum_i (m_i\sigma_i \otimes \mathbb{I}_2 + n_i\mathbb{I}_2 \otimes \sigma_i) + i \sum_{ij} (m_i n_j + r_{ij})\sigma_i \otimes \sigma_j$$

or also

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On this set we can consider the geometrical structures we defined above: the Jordan and the Poisson tensors and write them in these coordinates (the dual ones, on $\mathfrak{u}^*(4)$)

CONT

Excluding the y_0 coordinate which trivially is a Casimir of the structure we obtain

	y_1	y_2	y_3	y_4	y_5	y_6	y_7	y_8	y_9	y_{10}	y_{11}	y_{12}	y_{13}	y_{14}	y_{15}
y_1	0	y_3	$-y_2$	0	0	0	0	0	0	y_{13}	y_{14}	y_{15}	y_{10}	y_{11}	y_{12}
y_2	$-y_3$	0	y_1	0	0	0	y_{13}	y_{14}	y_{15}	0	0	0	y_7	y_8	y_9
y_3	y_2	$-y_1$	0	0	0	0	y_{10}	y_{11}	y_{12}	$-y_7$	$-y_8$	$-y_9$	0	0	0
y_4	0	0	0	0	y_6	$-y_5$	0	y_9	y_8	0	y_{12}	$-y_{11}$	0	y_{15}	$-y_{14}$
y_5	0	0	0	$-y_6$	0	y_4	$-y_9$	0	y_7	$-y_{12}$	0	y_{10}	$-y_{15}$	0	y_{13}
y_6	0	0	0	y_5	$-y_4$	0	y_8	$-y_7$	0	y_{11}	$-y_{10}$	0	y_{14}	$-y_{13}$	0
y_7	0	y_{13}	$-y_{10}$	0	y_9	$-y_8$	0	y_6	$-y_5$	y_3	0	0	$-y_2$	0	0
y_8	0	y_{14}	$-y_{11}$	$-y_9$	0	y_7	$-y_6$	0	y_4	0	y_9	0	0	$-y_2$	0
y_9	0	y_{15}	$-y_{12}$	y_8	$-y_7$	0	y_5	$-y_4$	0	0	0	y_9	0	0	$-y_2$
y_{10}	$-y_{13}$	0	y_7	0	y_{12}	$-y_{11}$	$-y_9$	0	0	0	y_6	$-y_5$	y_1	0	0
y_{11}	$-y_{14}$	0	y_8	$-y_{12}$	0	y_{10}	0	$-y_9$	0	$-y_6$	0	y_4	0	y_1	0
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ENTROPY AND CONCURRENCE

Consider two functions defined on our set of density matrices $\mathcal{D}(\mathcal{H})$:

- ▣ Von Neumann entropy $S(\rho) = -\text{Tr} \rho \log \rho$
- ▣ concurrence $C(\rho) = \max(0, 2\lambda_{\max}(\hat{\rho}) - \text{Tr}(\hat{\rho}))$, where $\hat{\rho}$ is defined as $\hat{\rho} = \sqrt{\rho} \sqrt{\rho(\sigma_2 \otimes \sigma_2) \rho^* (\sigma_2 \otimes \sigma_2)} \sqrt{\rho}$.

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From the geometrical point of view they are just functions

$$S : \mathcal{D}(\mathcal{H}) \rightarrow \mathbb{R} \quad C : \mathcal{D}(\mathcal{H}) \rightarrow \mathbb{R},$$

thus we can consider the problem of their independence.

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thus we can consider the problem of their independence.

DEFINITION: Two functions $f_1, f_2 \in \mathcal{F}(\mathcal{D}(\mathcal{H}))$ are said to be independent at a point $p \in M$ iff

$$(df_1 \wedge df_2)(p) \neq 0 \Leftrightarrow \left(\frac{\partial f_1}{\partial \lambda_i} \frac{\partial f_2}{\partial \lambda_j} - \frac{\partial f_1}{\partial \lambda_j} \frac{\partial f_2}{\partial \lambda_i} \right) (p) \neq 0 \quad \forall i, j$$

This is the problem we would like to study now.

CONT

It is quite difficult to study the problem in full generality, because of the dimension of $u^*(4)$.

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$$\mathcal{S} = \left\{ \left(\begin{array}{cccc} 0 & 0 & 0 & 0 \\ 0 & a & \frac{1}{2}ce^{i\phi} & 0 \\ 0 & \frac{1}{2}ce^{-i\phi} & b & 0 \\ 0 & 0 & 0 & 1 - a - b \end{array} \right) ; 0 \leq a + b \leq 1 \quad 0 \leq c \leq 1 \quad 4ab \geq c^2 \right\}$$

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It is quite difficult to study the problem in full generality, because of the dimension of $\mathfrak{u}^*(4)$. We are going to consider a simpler case by restricting the set of states to those of the form:

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\mathcal{S} is clearly a 4-dimensional submanifold of $\mathcal{D}(\mathcal{H})$. We can take an adapted basis for \mathcal{S} , considering the matrices

$$\begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & -1 \end{pmatrix}, \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & -1 \end{pmatrix}, \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & i & 0 \\ 0 & -i & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

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Let us consider now the restriction of S and C to \mathcal{S} : take $\rho \in \mathcal{S}$ and consider the coordinate system above. Then

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$$2S(\rho) = -2(-1 + a + b) \log[1 - a - b] + \\ \left(a + b - \sqrt{(a - b)^2 + c^2} \right) \log \left[\frac{1}{2} \left(a + b - \sqrt{(a - b)^2 + c^2} \right) \right] + \\ \left(a + b + \sqrt{(a - b)^2 + c^2} \right) \log \left[\frac{1}{2} \left(a + b + \sqrt{(a - b)^2 + c^2} \right) \right].$$

$$C(\rho_t) = c$$

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LEMMA

The concurrence and the von Neumann entropy on \mathcal{S} are functionally independent everywhere but on a submanifold \mathcal{I} of dimension 2.

PROOF

If we compute the expression $(dS \wedge dC)(\rho)$ for $\rho \in \mathcal{S}$ we obtain

$$dS(\rho) = \frac{\partial S}{\partial a} da + \frac{\partial S}{\partial b} db + \frac{\partial S}{\partial c} dc \\ dC(\rho) = \frac{\partial C}{\partial c} dc$$

Thus

$$(dS \wedge dC)(\rho) = 0 \Leftrightarrow \frac{\partial S(\rho)}{\partial a} = 0 = \frac{\partial S(\rho)}{\partial b}$$

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And these conditions become

$$2\text{Log}[1-a-b] + \text{Log} \left[ab - \frac{c^2}{4} \right] = 0 \quad \text{Log} [4ab - c^2] - 2\text{Log} \left[a + b + \sqrt{(a-b)^2 + c^2} \right] = 0$$

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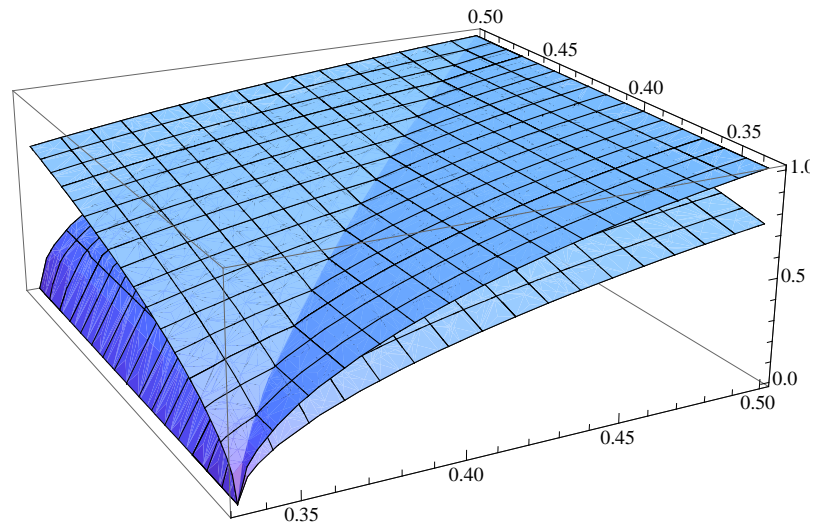
$$2\text{Log}[1-a-b] + \text{Log}\left[ab - \frac{c^2}{4}\right] = 0 \quad \text{Log}[4ab - c^2] - 2\text{Log}\left[a + b + \sqrt{(a-b)^2 + c^2}\right] = 0$$

These equations have a solution on

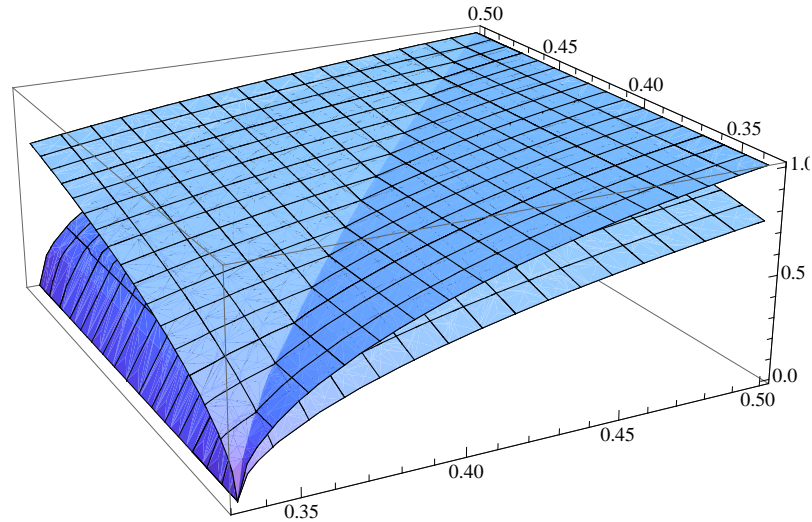
$$\frac{1}{3} < a < \frac{1}{2}; \quad b = a; \quad c = \sqrt{-4 + 8a - 4a^2 + 8b - 4ab - 4b^2}$$

If we represent the condition for c as a function of a and b we verify that it is well defined for all values of a and b (we represent the function

$c = \sqrt{-4 + 8a - 4a^2 + 8b - 4ab - 4b^2}$ and the function $c = \sqrt{-4 + 16a - 12a^2}$, which corresponds to the evaluation on the submanifold $a = b$).



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LEMMA The two functions $C(\rho)$ and $S(\rho)$ Poisson-commute on \mathcal{S}

PROOF: Direct computation.

FUTURE WORK

- ▣ Study the relation of this notion of independence with the action of local unitary transformations
- ▣ The behavior with respect to the Poisson/Jordan algebra structures.
- ▣ Simple test for pure states.