

A Preconditioned GMRES Method for Solving the Sideways Parabolic Equation in Two Space Dimensions

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Outline

- 2D Sideways Parabolic Equation with variable coefficients
- Generalized Minimum Residual method (GMRES)
- Preconditioner
- Implementation
- Numerical Experiments
- Summary

Two Dimensional Sideways Parabolic Equation

We want to solve the following problem:

$$\begin{aligned} u_t &= (a(x, y)u_x)_x + (b(x, y)u_y)_y, & 0 < x < 1, & \quad 0 < y < 1, & \quad 0 \leq t \leq 1 \\ u(x, y, 0) &= 0, & 0 \leq x \leq 1, & \quad 0 \leq y \leq 1 \\ u(1, y, t) &= g(t, y), & 0 \leq y \leq 1, & \quad 0 \leq t \leq 1 \\ u_x(1, y, t) &= 0, & 0 \leq y \leq 1, & \quad 0 \leq t \leq 1 \\ u_y(x, 0, t) &= 0, & 0 \leq x \leq 1, & \quad 0 \leq t \leq 1 \\ u(x, 1, t) &= 0, & 0 \leq x \leq 1, & \quad 0 \leq t \leq 1 \end{aligned}$$

where $u(0, y, t) = f(y, t)$ is sought from the data at the right boundary.

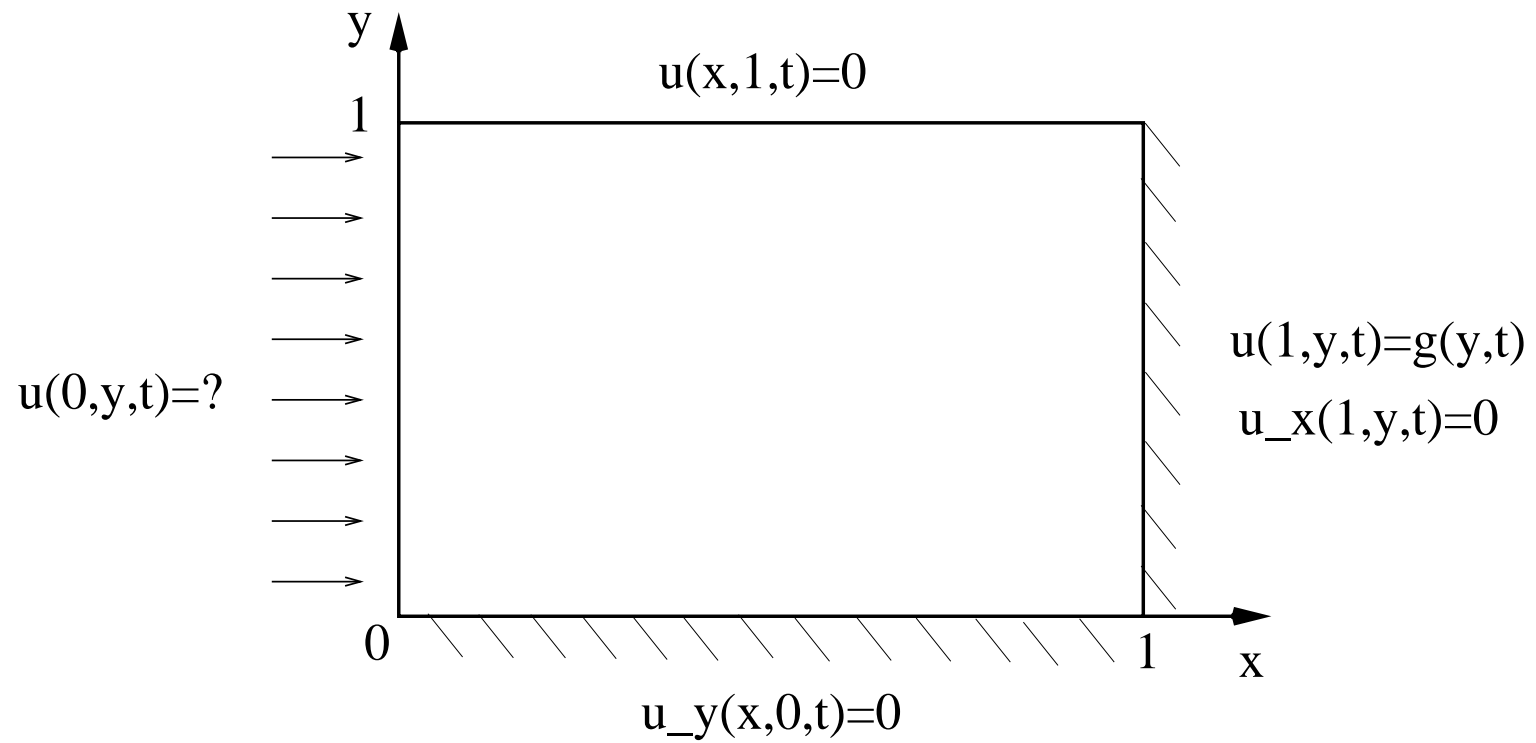
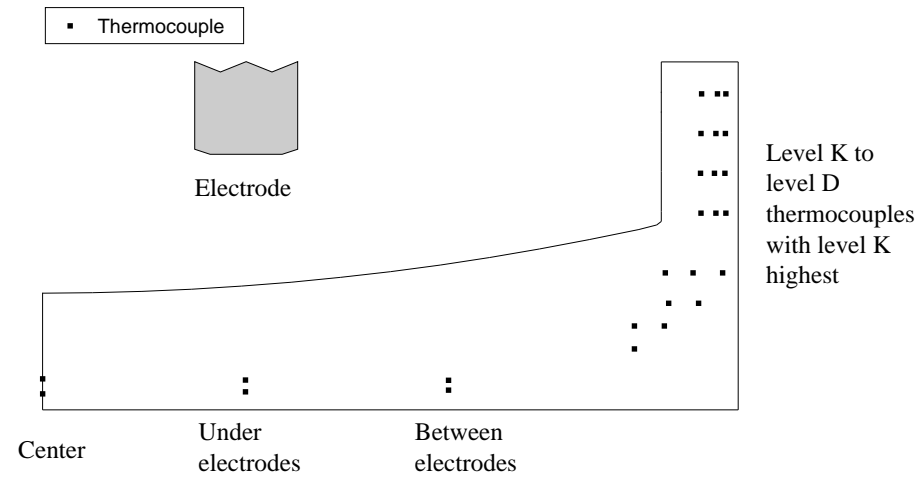


Figure 1: Two dimensional sideways heat problem.

Application



Skaar, I. Monitoring the Lining of a Melting Furnace Norwegian University of Science and Technology, Trondheim, Department of Mathematics, 2001

We want to solve

$$Kf = g$$

where f is the solution and K is the operator that maps f to the data g .

GMRES

The algorithm GMRES

1. Compute $r_0 = g - Kx_0$, $\beta = \|r_0\|_2$, and $v_1 = r_0/\beta$
2. **for** $j = 1, \dots, m$, (m is a regularization parameters)
 Compute $w := Kv_j$
 for $i = 1, \dots, j$ **do** (Gram-Schmidt)
 $h_{i,j} := w^T v_i$
 $w := w - h_{i,j}v_i$
 end
 Compute $h_{j+1,j} = \|w\|_2$ and $v_{j+1} = w/h_{j+1,j}$
 end
3. Define $V_m := [v_1, \dots, v_m]$, $\bar{H}_m = \{h_{i,j}\}_{1 \leq i \leq j+1, 1 \leq j \leq m}$
4. Compute $y_m = \operatorname{argmin}_y \|\beta e_1 - \bar{H}_m y\|_2$ and $x_m = x_0 + V_m y_m$

The multiplication by the operator,

$$w = Kv_j,$$

corresponds solving the following well-posed parabolic problem in two space dimensions.

$$\begin{aligned} u_t &= (a(x, y)u_x)_x + (b(x, y)u_y)_y, & 0 < x < 1, & \quad 0 < y < 1, & \quad 0 \leq t \leq 1, \\ u(x, y, 0) &= 0, & 0 \leq x \leq 1, & \quad 0 \leq y \leq 1, \\ u(0, y, t) &= v_j(y, t), & 0 \leq y \leq 1, & \quad 0 \leq t \leq 1, \\ u_x(1, y, t) &= 0, & 0 \leq y \leq 1, & \quad 0 \leq t \leq 1, \\ u_y(x, 0, t) &= 0, \quad u(x, 1, t) = 0, & 0 \leq x \leq 1, & \quad 0 \leq t \leq 1, \end{aligned} \tag{1}$$

and evaluating the solution at $x = 1$ to get w . This can be done efficiently using any standard method for the solution of a 2D parabolic equation.

GMRES dose not work without preconditioner

Preconditioner

Let M represent a discretization of the 2D sideways heat equation with constant coefficients, where the **constants are chosen as the mean values of the respective variable coefficients in the original problem 2D SHE**. If the variations of the coefficients $a(x, y)$ and $b(x, y)$ are moderate then M is close to the operator K , and it is appropriate to use it as a preconditioner.

$$KM^{-1}\psi = g, \quad \text{where} \quad \psi = Mf.$$

Instead of M^{-1} we use the pseudo-inverse M^\dagger .

2D SHE with constant Coefficients

Consider the following equations,

$$\begin{aligned} u_t &= au_{xx} + bu_{yy}, & 0 < x < 1, & \quad 0 < y < 1, & \quad 0 \leq t \leq 1, \\ u(x, y, 0) &= 0, & 0 \leq x \leq 1, & \quad 0 \leq y \leq 1, \\ u(1, y, t) &= g(y, t), & 0 \leq y \leq 1, & \quad 0 \leq t \leq 1 \\ u_x(1, y, t) &= 0, & 0 \leq y \leq 1, & \quad 0 \leq t \leq 1 \\ u_y(x, 0, t) &= 0, \quad u(x, 1, t) = 0, & 0 \leq x \leq 1, & \quad 0 \leq t \leq 1. \end{aligned}$$

Lemma. [Reinhardt:91] The explicit representation of the solution of 2D SHE in terms of the unknown function $f(y, t)$ is

$$u(x, y, t) = \int_0^t 2a \sum_{n,j=0}^{\infty} (-1)^n \nu_n \exp(-(a\nu_n^2 + b\mu_j^2)(t-s)) \Psi_{nj}(x, y) f_j(s) ds,$$

where

$$\nu_n = (2n + 1)\frac{\pi}{2}, \quad \mu_j = (2j + 1)\frac{\pi}{2},$$

$$\Psi_{nj}(x, y) = \cos(\nu_n(1 - x)) \cos(\mu_j y),$$

and

$$f_j(s) = 2 \int_0^1 f(y, s) \cos(\mu_j y) dy, \quad j = 0, 1, \dots$$

From Lemma we have for $x = 1$,

$$\begin{aligned} g(y, t) &= u(1, y, t) \\ &= \int_0^t 2a \sum_{n,j=0}^{\infty} (-1)^n \nu_n \exp(-(a\nu_n^2 + b\mu_j^2)(t-s)) \cos(\mu_j y) f_j(s) ds, \end{aligned}$$

Expanding $g(y, t)$ in the same cosine series

$$g(y, t) = \sum_{j=0}^{\infty} g_j(t) \cos(\mu_j y),$$

leads to

$$g_j(t) = \int_0^t 2a \sum_{n,j=0}^{\infty} (-1)^n \nu_n \exp(-(a\nu_n^2 + b\mu_j^2)(t - s)) f_j(s) ds.$$

1. Compute the **cosine transform** of the data function:

$$g_j(t) = 2 \int_0^1 g(y, t) \cos(\mu_j y) dy, \quad j = 0, 1, \dots$$

2. Solve the **Volterra integral equations**

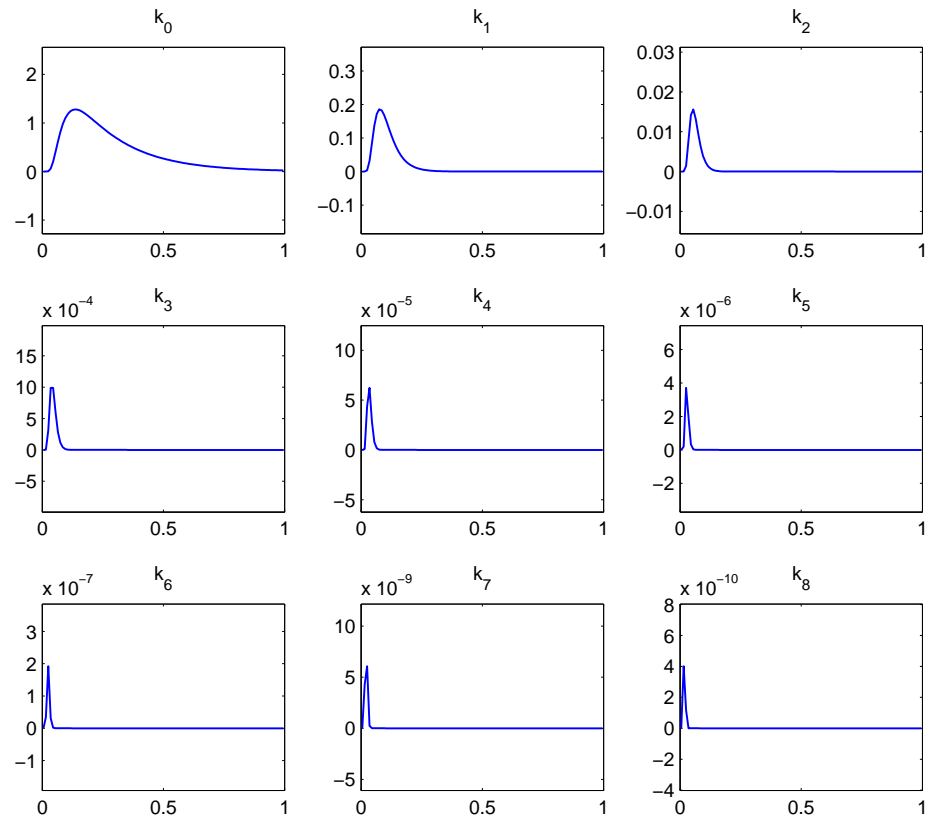
$$g_j(t) = \int_0^t k_j(t - s) f_j(s) ds, \quad j = 0, 1, \dots$$

where the kernel k_j is given by

$$k_j(r) = 2a \sum_{n=0}^{\infty} (-1)^n \nu_n \exp(-(a\nu_n^2 + b\mu_j^2)r)$$

3. Evaluate the solution $f(y, t)$ by computing the **inverse cosine transform**:

$$f(y, t) = \sum_{j=0}^{\infty} f_j(t) \cos(\mu_j y).$$



Kernel functions $k_j(r)$, $j = 0, 1, 2, \dots, 8$.

PGMRES

The algorithm GMRES with Right Preconditioning

1. Compute $r_0 = g - Kx_0$, $\beta = \|r_0\|_2$, and $v_1 = r_0/\beta$
2. **for** $j = 1, \dots, m$,
 Compute $w := KM^\dagger v_j$
 for $i = 1, \dots, j$ **do**
 $h_{i,j} := w^T v_i$
 $w := w - h_{i,j}v_i$
 end
 Compute $h_{j+1,j} = \|w\|_2$ and $v_{j+1} = w/h_{j+1,j}$
 end
3. Define $V_m := [v_1, \dots, v_m]$, $\bar{H}_m = \{h_{i,j}\}_{1 \leq i \leq j+1, 1 \leq j \leq m}$
4. Compute $y_m = \operatorname{argmin}_y \|\beta e_1 - \bar{H}_m y\|_2$ and $x_m = x_0 + M^\dagger V_m y_m$

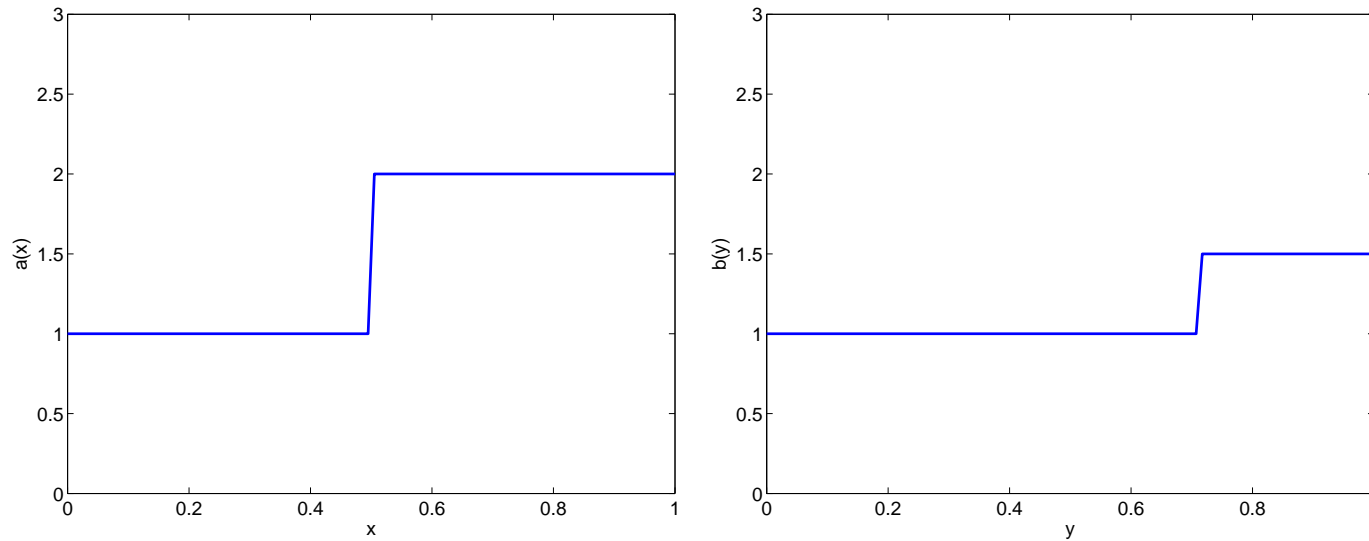
Implementation

Implementation of the preconditioner $M^\dagger v$:

1. $\hat{v} = \text{DFT}(v)$, $\hat{v} = (\hat{v}_1^T \ \cdots \ \hat{v}_n^T)^T$
2. **for** $j = 1, p$
 $\hat{v}_j = \hat{v}(j, :)$,
 Solve $M_j \hat{u}_j = \hat{v}_j$ by Tikhonov regularization
 $\hat{u}(j, :) = \hat{u}_j$
3. **end**
4. $\hat{u} = (\hat{u}_1^T, \cdots, \hat{u}_p^T, 0, \cdots, 0)^T$
5. $u = \text{IDFT}(\hat{u})$

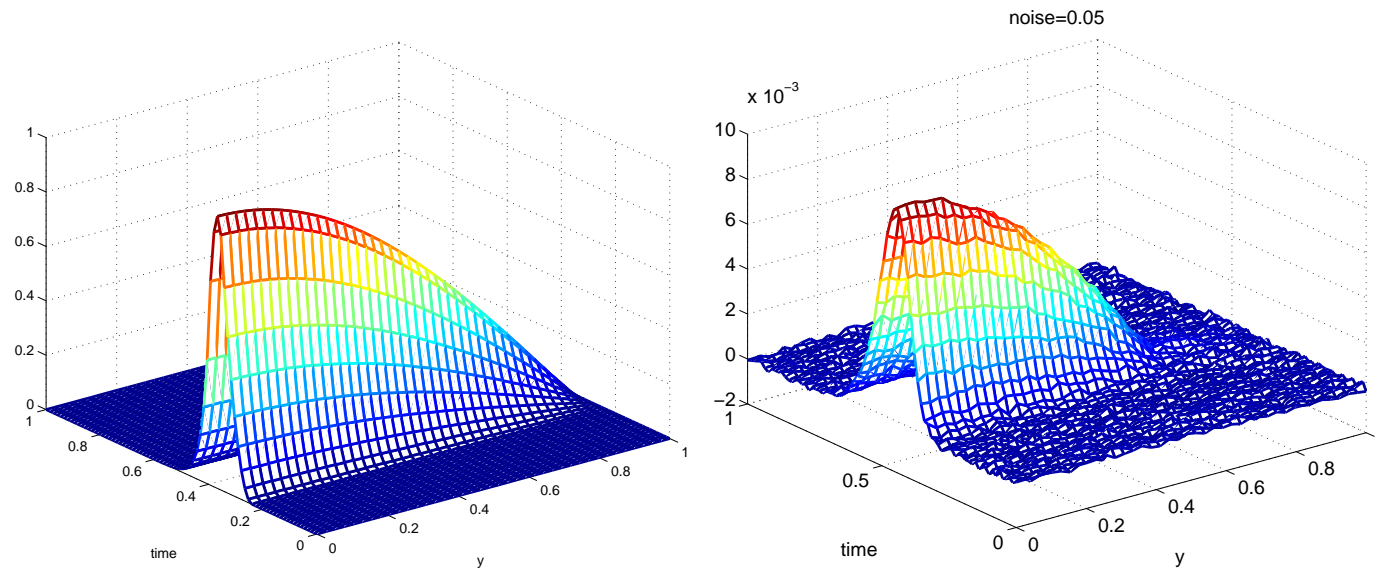
Here p is the number of terms in the cosine expansion.

Numerical Experiments

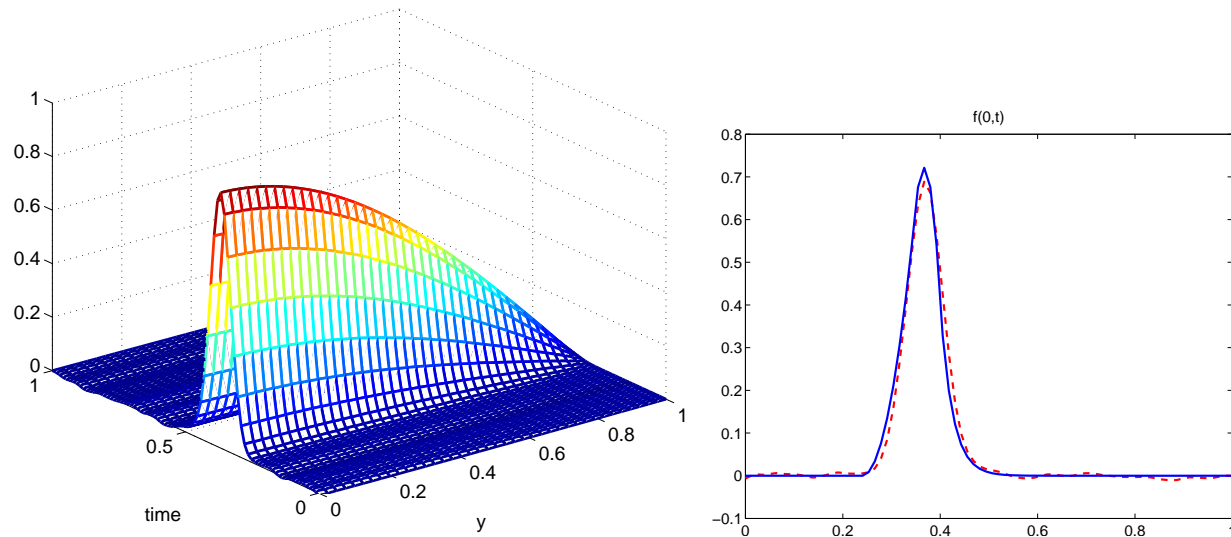


Plot of variable coefficients $a(x)$ (left) and $b(y)$ (right).

Test example 1:

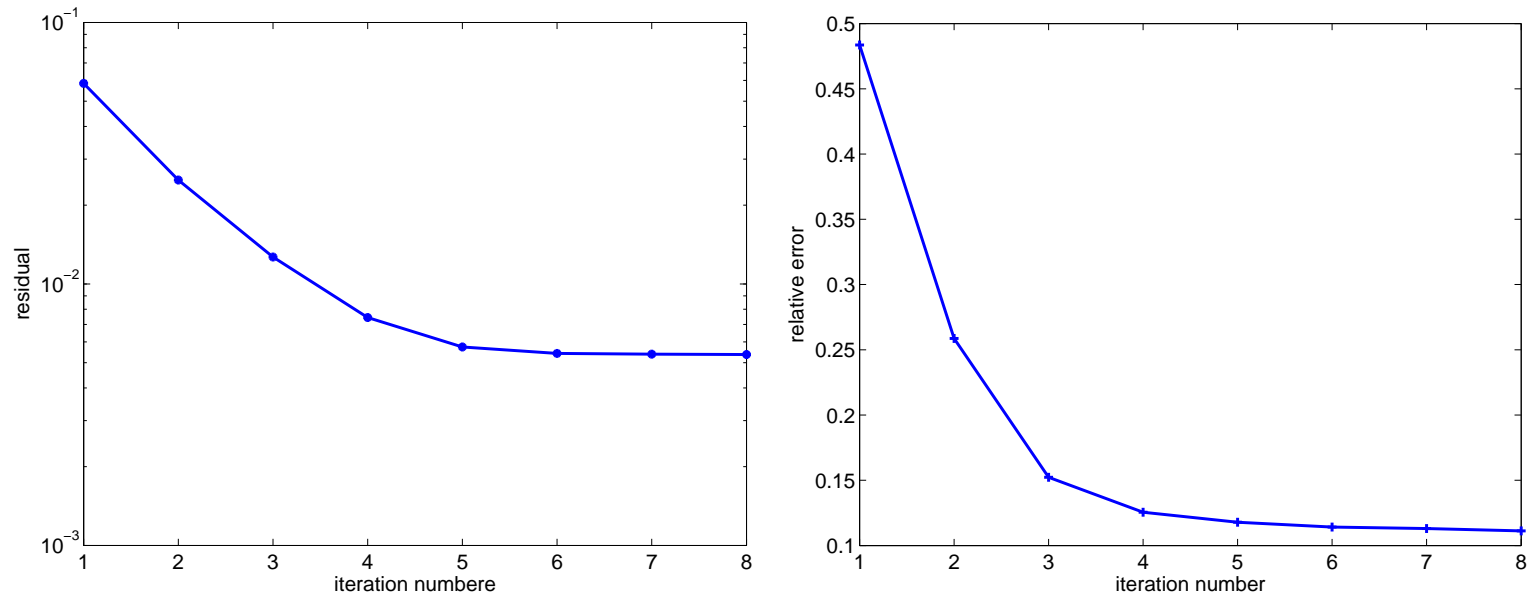


Example 1. Exact solution $f(y, t)$ (left) and data function with 5% noise(right)



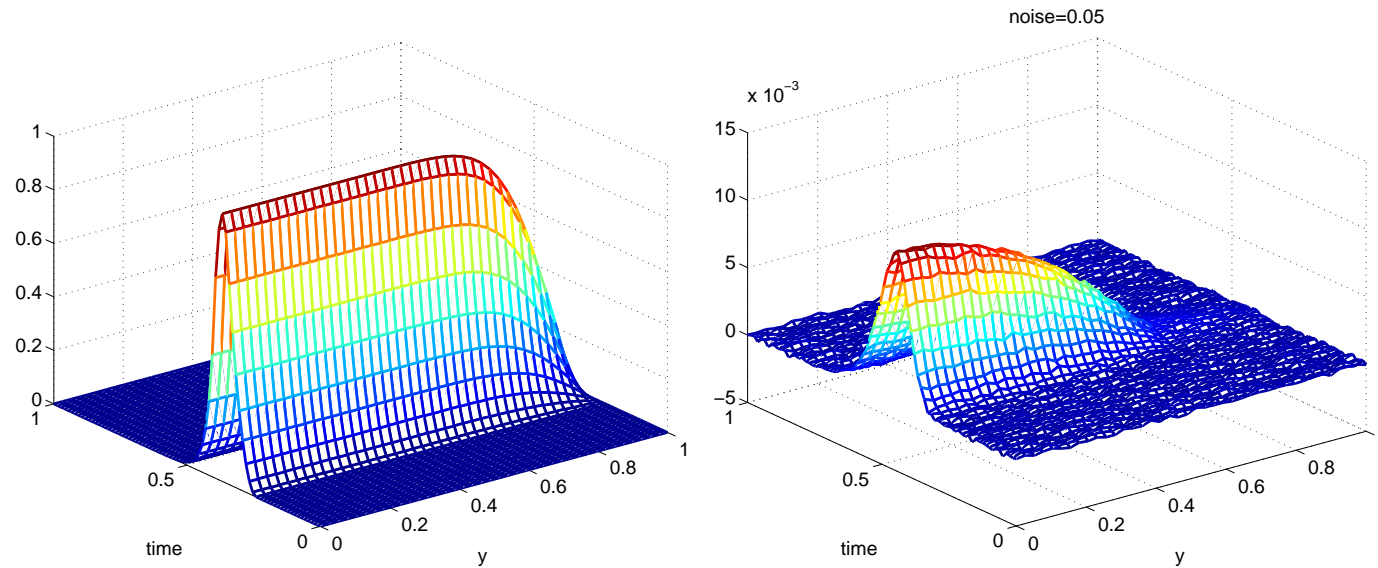
Example 1. Approximate solution after 6 iterations of PGMRES for $0 \leq y \leq 1$ (left) and plot of f and the approximated solution at $y = 1/2$ (right).

$$\lambda \in (0.05, 0.5) \text{ and } p = 1$$

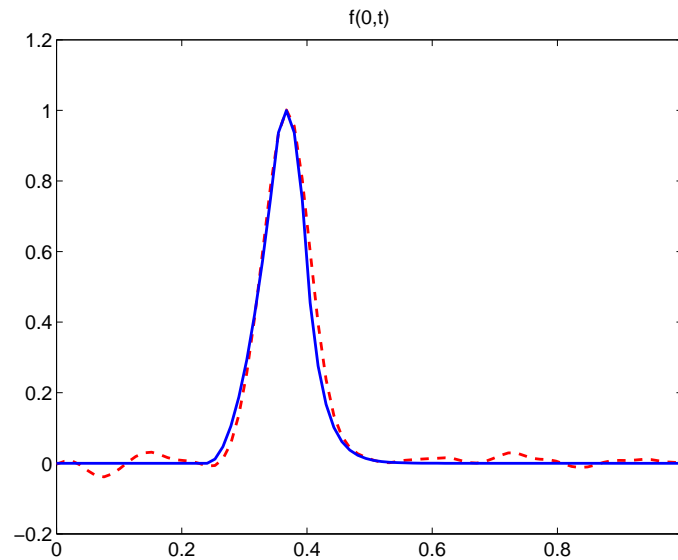
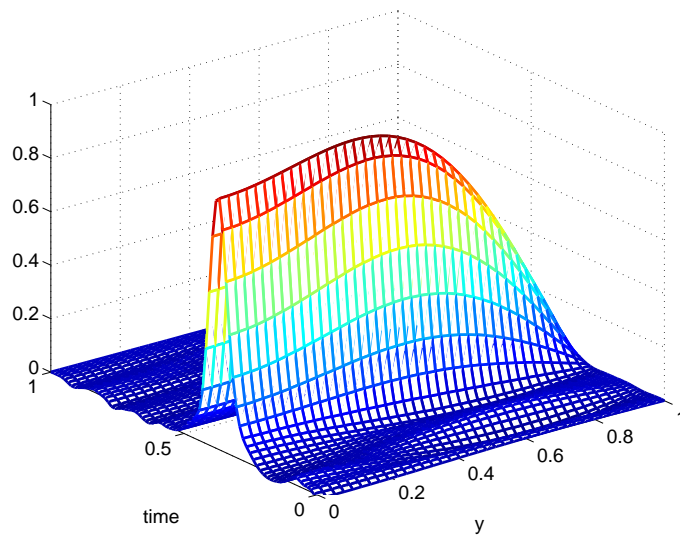


Example 1. Residuals (left) and relative errors (right) of PGMRES as functions of iteration index for 5% perturbation in the data.

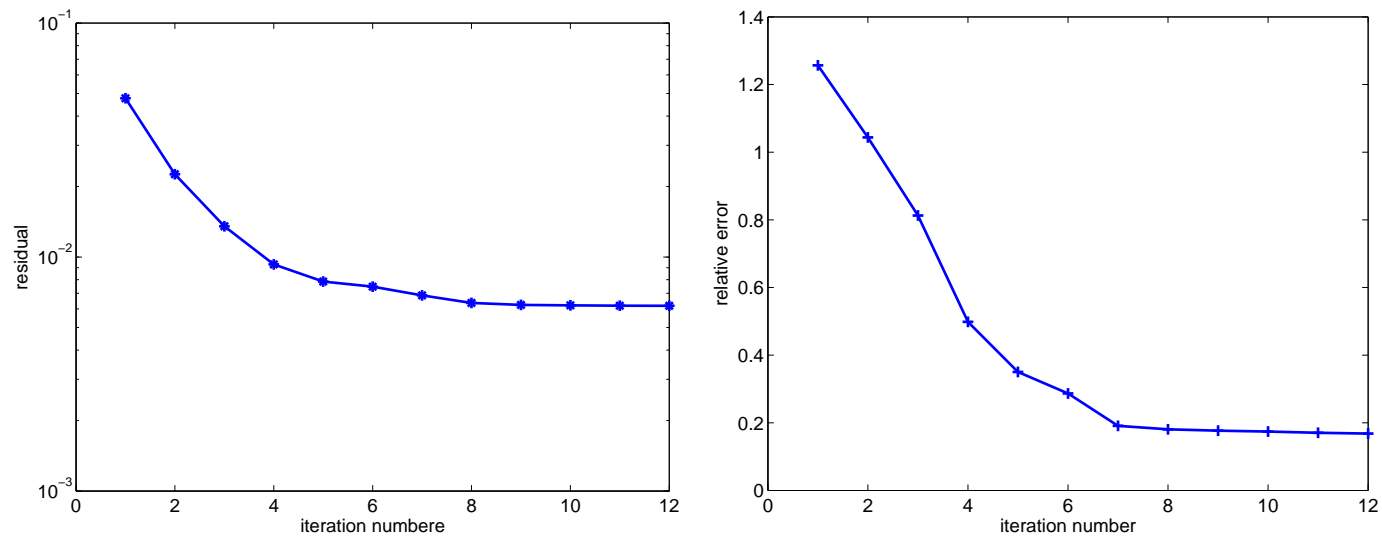
Test exapmle 2:



Example 2. Exact solution $f(y, t)$ and data function $g_\delta(y, t)$ with 5% noise.



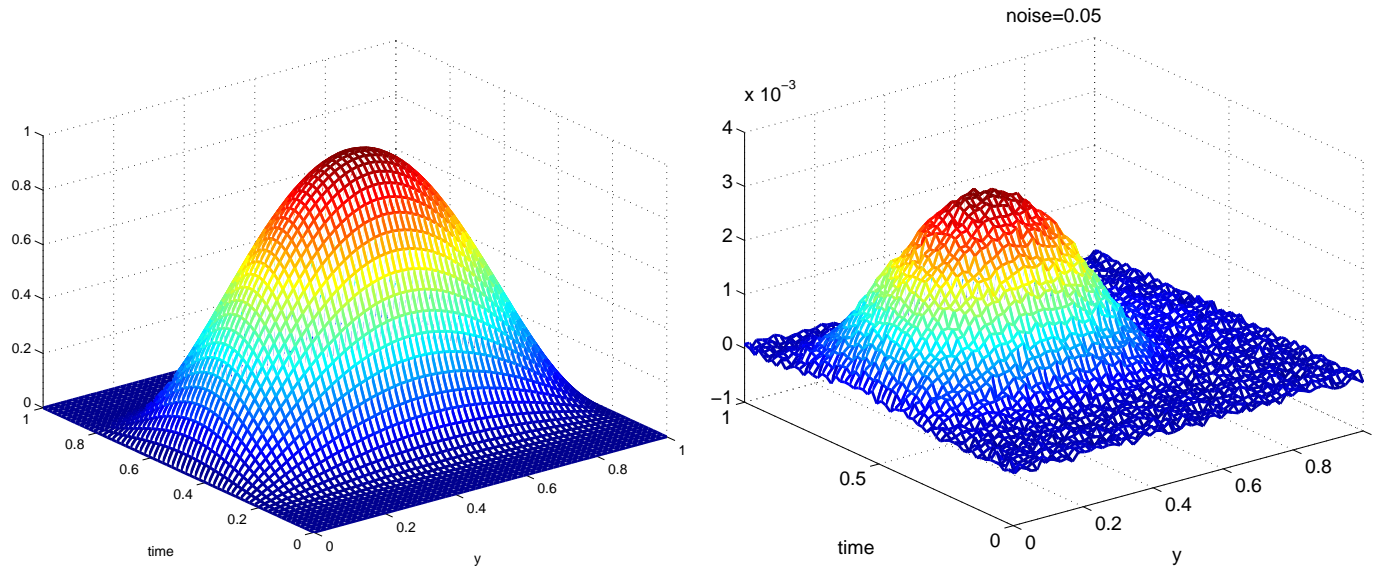
Example 2. Approximate solution (left), and the exact solution(solid) and the approximate solution (dashed) at $y = 1/2$ after 12 iterations of PGMRES with 5% perturbation in the data, and $\lambda = 0.06$ and $p = 2$.



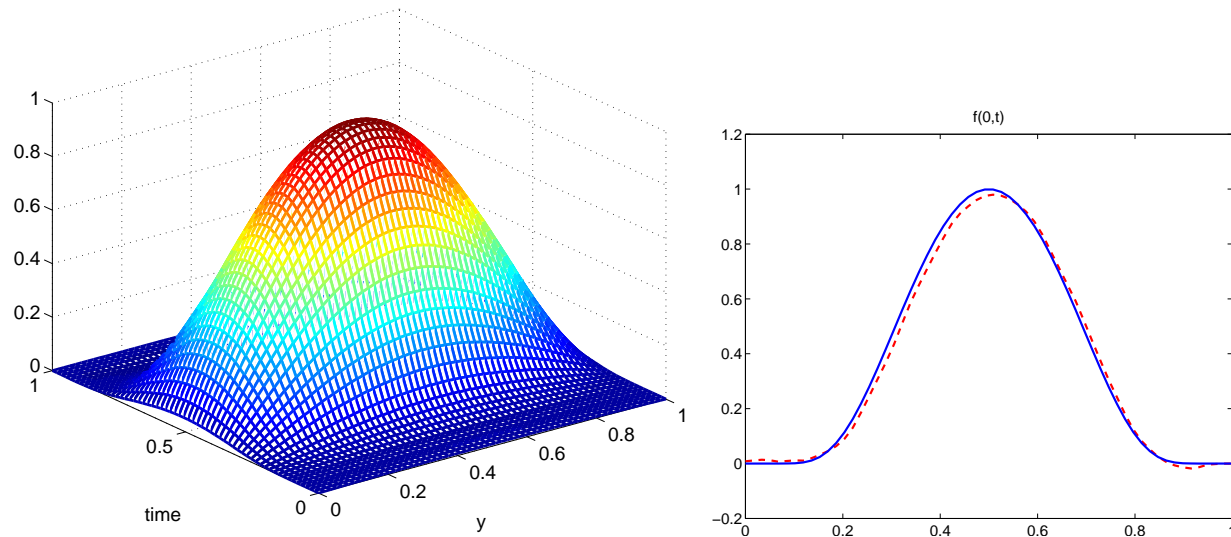
Example 2. Residuals (left) and relative errors (right) of PGMRES as functions of iteration index.

Test example 3: 2D SHE with zero boundary values in y-direction, i.e,

$$u(x, 0, t) = u(x, 1, t) = 0$$

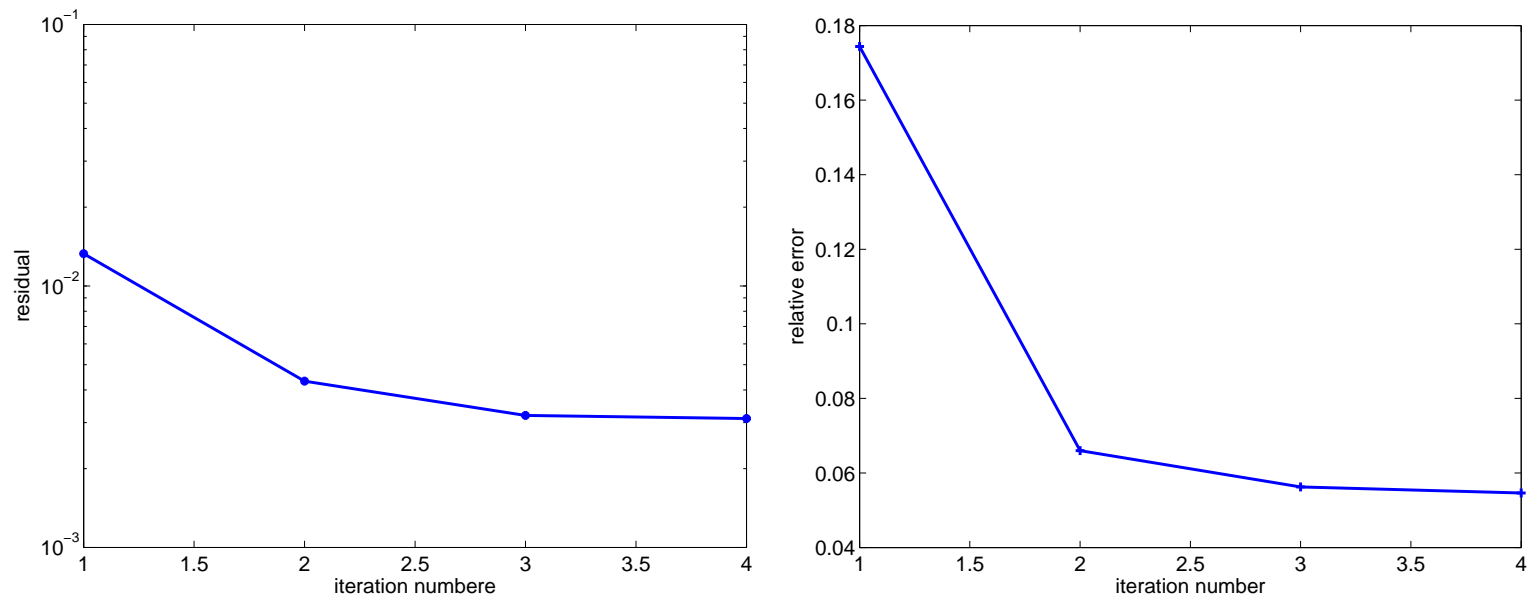


Exact solution $f(y, t)$ (left) and data function with 5% noise(right)



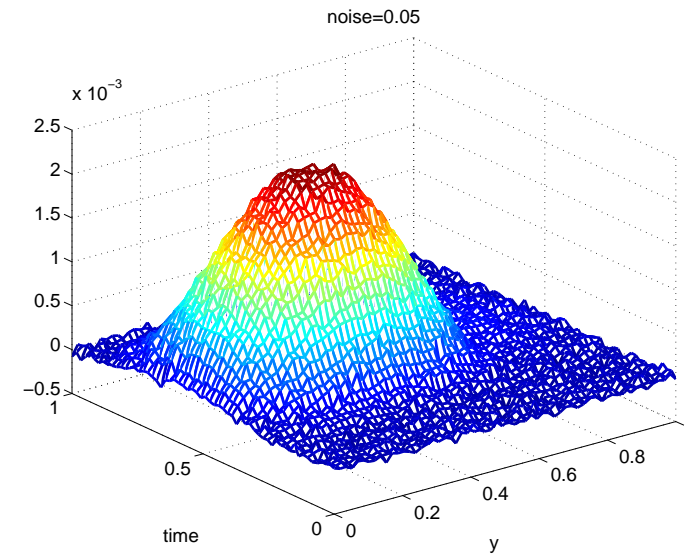
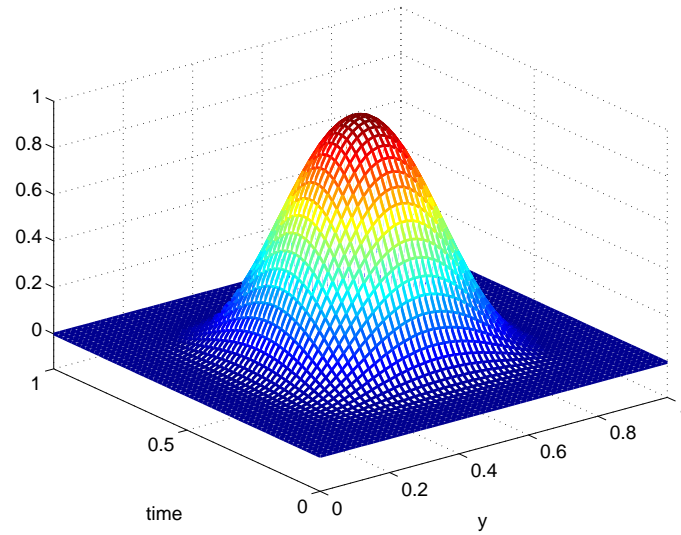
Approximate solution after 3 iterations of PGMRES for $0 \leq y \leq 1$ (left) and plot of f and the approximated solution at $y = 1/2$ (right).

$$\lambda \in (0.05, 0.5) \text{ and } p = 1$$

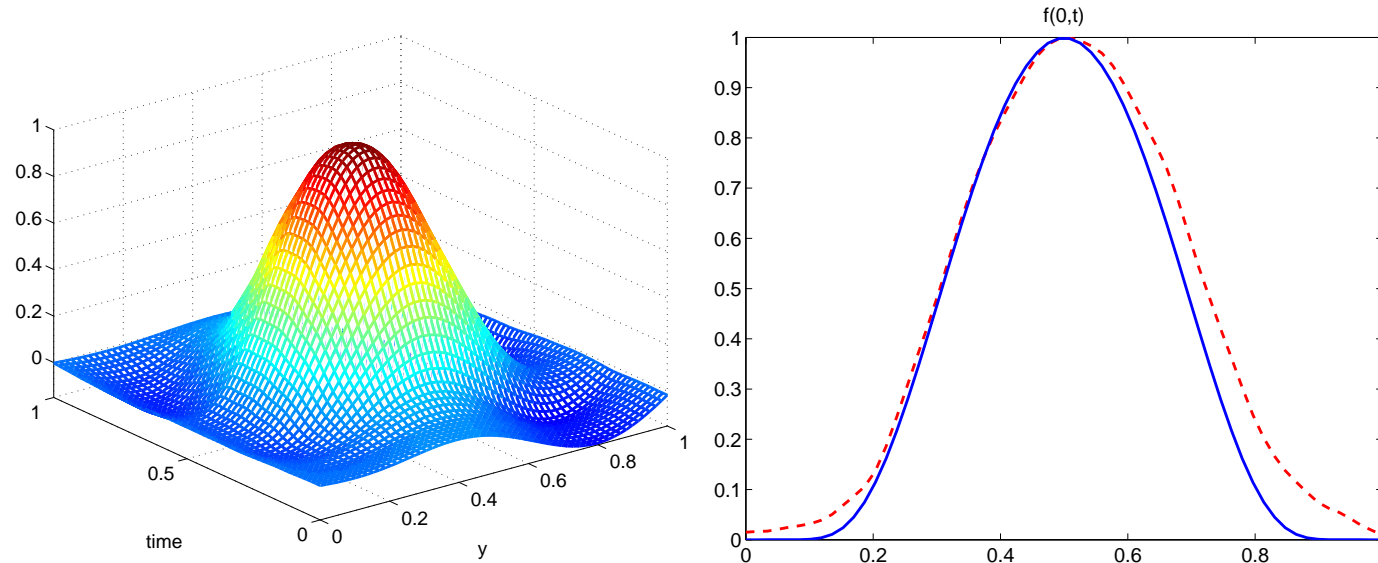


Residuals (left) and relative errors (right) of PGMRES as functions of iteration index for 5% perturbation in the data.

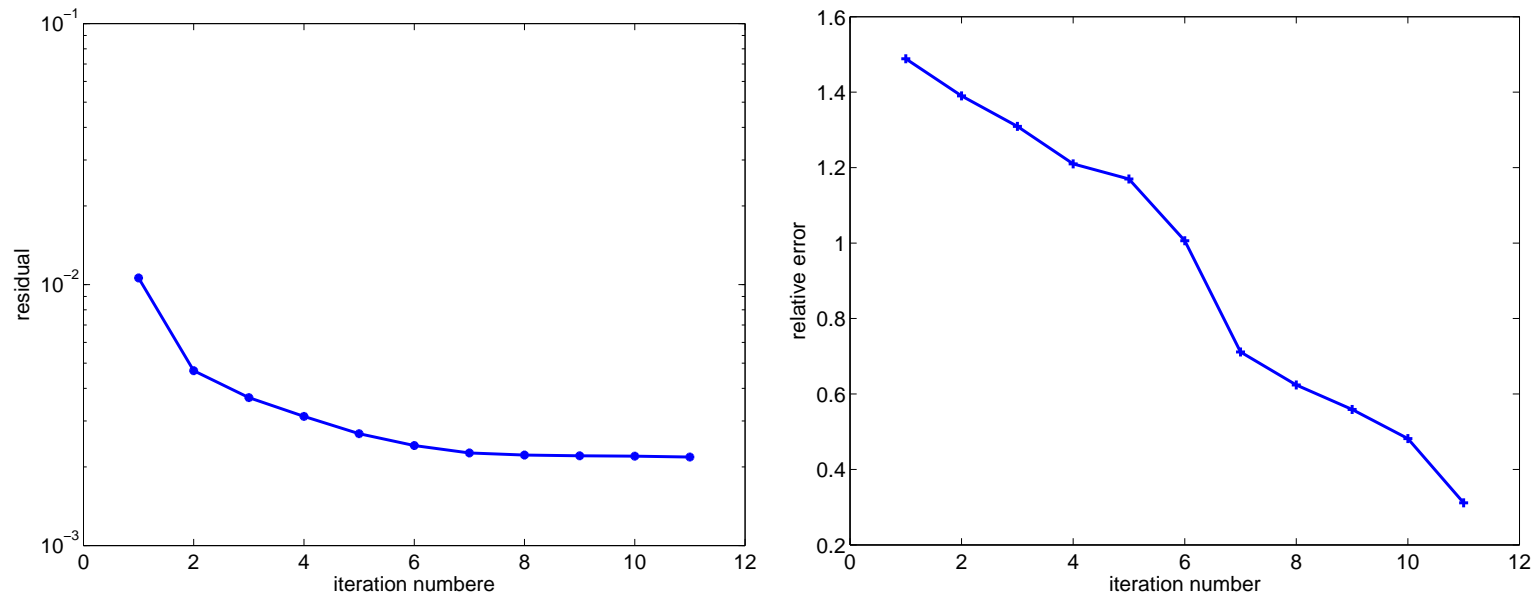
Test example 4:



Example 4. Exact solution $f(y, t)$ and data function $g_\delta(y, t)$ with 5% noise.



Example 4. Approximated solutions(left) and the exact solution(solid) and the approximate solution at $y = 1/2$ after 11 iterations of PGMRES with 5% perturbation in the data $\lambda = 0.09$ and $p = 3$.



Example 4. Residuals (left) and relative errors (right) of PGMRES as functions of iteration index.

This problem is difficult because, due to the closeness to zero in the vicinity of 0 and 1, it is not possible to approximate the solution in terms of a small number of sine functions.

Summary and future works

- PGMRES: A new method for solving 2D sideways parabolic problem with variable coefficients which seems to be very efficient.
- Very few iterations
- Preconditioner is close to the original operator: just differ in coefficients
- Regularization is incorporated in the preconditioner
- Algorithms are computational feasible since we use Discrete Fourier Transform.
- Numerical analysis is more on experimental side and need to more study on theoretical parts

- Extension to more general form of multidimensional problems