

ON MARTINET'S SINGULAR SYMPLECTIC STRUCTURES

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Introduction. Let V be a stratified subspace of R^N . We call it symplectic if there exists a differential 2-form ω on R^N such that the restriction of ω to each stratum is a symplectic form. In the Marsden-Weinstein singular reduction theory these spaces were studied by several authors [5, 4, 9, 1]. In this paper we classify the symplectic spaces modelled on the so-called symplectic flag S . First we prove the corresponding Darboux theorem and then we show that the only reasonable symplectic structures on S are those with underlying Martinet's singular symplectic structure of type $\Sigma_{2,0}$. Finally we find the normal form for this structure and show the similar result for an example of a stratified symplectic space with singular boundary of the maximal stratum.

1. Singular symplectic spaces. A stratified differential space with each stratum being a symplectic manifold is called a stratified symplectic space. This notion was introduced in [9] (see also [4]) in the context of standard symplectic reduction. For our purpose, in the first step we need embedded symplectic spaces.

DEFINITION 1.1. Let S be a stratified subset of R^N with each stratum S_i (even dimensional) endowed with a symplectic structure ω_{S_i} . We assume that there exists a closed two-form ω on R^N such that $\omega|_{S_i} = \omega_{S_i}$. Then the pair (S, ω) is called a *singular symplectic space*.

A representative model of a singular symplectic space is a disjoint union of semialgebraic sets. We consider the following elementary symplectic flag:

$$S = S_{2n} \cup S_{2n-2} \subset R^{2n};$$
$$S_{2n} = \{(x, y) \in R^{2n} : x_1 > 0\}, \quad S_{2n-2} = \{(x, y) \in R^{2n} : x_1 = 0, y_1 = 0\}$$

endowed with a symplectic structure ω . By $\iota_k : S_i \rightarrow R^N$ we denote the canonical inclusions of S_{2n-k} . Here $S_{2n-1} = \{x \in R^{2n} : x_1 = 0\}$.

1991 *Mathematics Subject Classification*: 57R45, 53B21.

The paper is in final form and no version of it will be published elsewhere.

EXAMPLE 1.1. Let $V \subset (M, \omega)$ be an algebraic hypersurface. Let \mathcal{X}_V be its Whitney stratification. By V^d we denote an element of \mathcal{X}_V , $V^d \in \mathcal{X}_V$, of dimension d . We say V is a coisotropic hypersurface if and only if each stratum of \mathcal{X}_V is a coisotropic or an isotropic submanifold of (M, ω) . We easily see that a typical hypersurface V defined by the polynomial equation $F(p) = 0$ is not coisotropic. As an example let us consider the cusp-edge surface V in R^{2n} endowed with a symplectic form ω in general position with respect to V . In this case $\omega|_{\text{Sing}V}$ is a symplectic form. It is shown in [2] that (V, ω) is diffeomorphic to $(\{x_1^3 - y_1^2 = 0\}, \sum_{i=1}^n dx_i \wedge dy_i)$ and the reduced symplectic space of $V - \text{Sing}V$ is isomorphic to the singular edge of V (cf. [4]).

We conjecture that if $\text{Sing}V$ is a coisotropic submanifold of (R^{2n}, ω) , then (V, ω) is diffeomorphic to $(\{x_1^3 - x_2^2 = 0\}, \sum_{i=1}^n dx_i \wedge dy_i)$. Let $\Phi : R^{2n-1} \rightarrow R^{2n}$ be the parameterization of $\{x_1^3 - x_2^2 = 0\}$,

$$\Phi(s, y_1, y_2, x_3, y_3, \dots, x_n, y_n) = (s^2, y_1, s^3, y_2, x_3, y_3, \dots, x_n, y_n).$$

Then

$$\Phi^* \omega = ds \wedge d(3s^2 y_2 + 2s y_1) + \sum_{i=3}^n dx_i \wedge dy_i.$$

Let $\pi : R^{2n-1} \rightarrow R^{2n-2}$ be the mapping

$$\pi(s, y_1, y_2, x_3, y_3, \dots, x_n, y_n) = (s, 3s^2 y_2 + 2s y_1, x_3, y_3, \dots, x_n, y_n).$$

Let S be the image of π . Then

$$S = \{(x, y) \in R^{2n-2} : x_1 \neq 0\} \cup \{(x, y) \in R^{2n-2} : x_1 = 0, x_2 = 0\}$$

and

$$\pi^* \left(\sum_{i=1}^{n-1} dx_i \wedge dy_i \right) = \Phi^* \omega.$$

The reduced space S endowed with the Darboux form on R^{2n-2} is a singular symplectic space.

Now we have a natural extension problem: let $\tilde{\omega}$ be a symplectic form on S_{2n-2} , we ask for the existence of the closed two-form on R^N such that $\omega|_{S_{2n-2}} = \tilde{\omega}$ and $\omega|_{S_{2n}}$ is symplectic. The first step in approaching this problem is to classify singular symplectic spaces (S, ω) , where ω provides a symplectic structure on R^{2n} .

By G_S we denote the group of germs of diffeomorphisms $(R^{2n}, 0) \rightarrow (R^{2n}, 0)$ preserving S , i.e. if $\Phi \in G_S$ then $\Phi(S_{2n}) \subset S_{2n}$, and $\Phi(S_{2n-2}) \subset S_{2n-2}$.

Let $\Phi \in G_S$. Then using the standard setting of singularity theory (cf. [7]) we have

$$\Phi(x_1, y_1, \dots, x_n, y_n) = (x_1 \phi_1(x, y), x_1 \phi_{12}(x, y) + y_1 \phi_{22}(x, y), \phi_3(x, y), \dots, \phi_{2n}(x, y)),$$

where $\phi_1, \phi_{12}, \phi_{22}, \phi_3, \dots, \phi_{2n}$ are smooth germs of functions on $(R^{2n}, 0)$.

Let ω_1, ω_2 be two symplectic structures on S (closed two-forms on $(R^{2n}, 0)$).

DEFINITION 1.2. We say that ω_1 and ω_2 are S -equivalent ($\omega_1 \sim_S \omega_2$) if and only if there exists $\Phi \in G_S$ such that $\Phi^* \omega_1 = \omega_2$.

THEOREM 1.1 (Darboux form). *Let ω be a symplectic structure on S . Assume ω is a symplectic form on R^{2n} . Then ω is S -equivalent to the Darboux form:*

$$\omega \sim_S \sum_{i=1}^n dx_i \wedge dy_i.$$

Proof. We take the homotopy (cf. [8]) $\omega_t = t\omega_1 + (1-t)\omega_0$, $t \in [0, 1]$. One can check that ω_t is a nondegenerate form for every $t \in [0, 1]$. We seek for a smooth family $t \rightarrow \Phi_t$ such that

$$(1) \quad \Phi_t^* \omega_t = \omega_0, \quad \Phi_0 = id_{R^{2n}}.$$

Differentiating (1) we have

$$L_{V_t} \omega_t + \omega_1 - \omega_0 = 0,$$

where L_{V_t} is the Lie derivative along the vector field V_t generated by the flow Φ_t . But

$$L_{V_t} \omega_t = d(V_t \lrcorner \omega_t) + V_t \lrcorner d\omega_t = d(V_t \lrcorner \omega_t).$$

We have $d(\omega_0 - \omega_1) = 0$ and $\iota_{2n-1}^*(\omega_0 - \omega_1) = 0$. So by the relative Poincaré Lemma (see e.g. [11]) there exists a one-form α such that $d\alpha = \omega_0 - \omega_1$ and α vanishes on S_{2n-1} . Thus we have

$$(2) \quad V_t \lrcorner \omega_t = \alpha \quad \text{and} \quad \alpha|_{(x,y)} = 0 \quad \text{for every } (x, y) \in S_{2n-1}.$$

Because ω_t is a nondegenerate form, (2) is always solvable with respect to V_t and moreover $V_t(x, y) = 0$ for every $(x, y) \in S_{2n-1}$. We deduce Φ_t exists, $\Phi_t \in G_S$ and by compactness of the interval $[0, 1]$ we have $\Phi^* \omega_1 = \omega_0$. ■

2. Martinet's singular symplectic spaces. Before we pass to the more detailed analysis of the degenerate case we recall the basic results on the standard classification of singularities of differential forms [6].

Let ω be a germ of a closed two-form on R^{2n} at zero. We denote

$$\Sigma_k(\omega) = \{x \in R^{2n} : \text{rank} \omega(x) = 2n - k\}, \quad k \text{ is even.}$$

Let $\omega^n = f\Omega$, where Ω is the volume form on R^{2n} .

(i) If $f(0) \neq 0$ then ω is a symplectic form (according to the standard notation denoted by Σ_0) and by the Darboux theorem we obtain

$$(3) \quad \omega = \sum_{i=1}^n dx_i \wedge dy_i$$

in local coordinates around zero.

(ii) Next we assume $f(0) = 0$ while $(df)(0) \neq 0$. We have $\Sigma_2(\omega) = \{f = 0\}$ and let $\iota : \Sigma_2(\omega) \rightarrow R^{2n}$ be the inclusion. If $\iota^* \omega^{n-1}(0) \neq 0$ then in local coordinates

$$(4) \quad \omega = x_1 dx_1 \wedge dy_1 + \sum_{i=2}^n dx_i \wedge dy_i$$

and this type of singular form ω is denoted by $\Sigma_{2,0}$ (and called Martinet's singular form).

Both types of forms Σ_0 , $\Sigma_{2,0}$ are locally stable (see [6]) and this is why we use them in what follows.

PROPOSITION 2.1. *Let ω be a symplectic structure on S . Assume $f(0) = 0$ and $df_0 \neq 0$ (stability conditions), then ω is a singular form of type $\Sigma_{2,0}$ at zero, i.e. ω belongs to the standard orbit of (ii) (4).*

Remark 2.1. We see that the symplectic form ω on S may be very singular in general. The singular set of ω is not visible from S (see Fig. 1). The above proposition says that the typical symplectic forms on S can only have $\Sigma_{2,0}$ or Σ_0 type singularities in the ambient space. Thus the two remaining stable cases $\Sigma_{2,2,0}$ are naturally excluded from our approach (cf. [3]).

Proof of Proposition 2.1. We see that ω is a symplectic form on S_{2n-2} . Let

$$\tilde{S} = \Sigma_2(\omega) = \{f = 0\},$$

where $\omega^n = f\Omega$ and Ω is the standard volume form on R^{2n} . We have $T_0\tilde{S} = T_0S_{2n-1}$, because ω is symplectic on S_{2n} . $S_{2n-2} \subset S_{2n-1}$ so $T_0S_{2n-2} \subset T_0S_{2n-1}$ and $T_0S_{2n-2} \subset T_0\tilde{S}$. By assumption $\iota_{2n-2}^*\omega$ is symplectic. Thus $(\iota_{2n-2}^*\omega)^{n-1} \neq 0$ and this implies $(\iota^*\omega)^{n-1} \neq 0$, where $\iota: \tilde{S} \rightarrow R^{2n}$ is the embedding of \tilde{S} . ■

LEMMA 2.1. *By means of a diffeomorphism $\Phi \in G_S$ of the form*

$$\Phi(x, y) = (\phi(x, y), x_2, \dots, x_n, y_1, \dots, y_n)$$

one can reduce f to the following normal form:

$$f(x_1, y_1, \dots, x_n, y_n) = \pm(x_1 - \psi(y_1, x_2, y_2, \dots, x_n, y_n)).$$

DEFINITION 2.1. We say that ψ_1, ψ_2 are *contact equivalent* if and only if there exists a diffeomorphism $\Phi: (R^{2n-1}, 0) \rightarrow (R^{2n-1}, 0)$ and a smooth function-germ $g: (R^{2n-1}, 0) \rightarrow R$, $g(0) \neq 0$, such that

$$\psi_1 = g \cdot (\psi_2 \circ \Phi).$$

Let ω_1, ω_2 be two symplectic forms on S . Let f_1, f_2 define their corresponding singular hypersurfaces, $\omega_1^n = f_1\Omega$ and $\omega_2^n = f_2\Omega$ and ψ_1, ψ_2 are as in Lemma 2.1. By straightforward check we obtain the following

PROPOSITION 2.2. *If ω_1 and ω_2 are S -equivalent then ψ_1 and ψ_2 are contact equivalent.*

Let ω be a symplectic form on S , $\omega^n = f\Omega$, $f(0) = 0$ and $df_0 \neq 0$. We see that $\frac{\partial f}{\partial x_i}(0) = 0$ and $\frac{\partial f}{\partial y_j}(0) = 0$ for $i = 2, \dots, n, j = 1, \dots, n$, so $\frac{\partial f}{\partial x_1}(0) \neq 0$. Thus

$$df \wedge dy_1 \wedge dx_2 \wedge dy_2 \wedge \dots \wedge dx_n \wedge dy_n(0) \neq 0,$$

so $\{y_1, x_2, y_2, \dots, x_n, y_n\}$ defines a coordinate system on

$$\tilde{S} = \{f = 0\}.$$

Before we formulate the main theorem concerning the normal form of ω we need some necessary facts ([6]).

LEMMA 2.2. *Let τ be a k -form on R^n satisfying*

$$(5) \quad \frac{\partial}{\partial x_1} \lrcorner \tau = 0, \quad \frac{\partial}{\partial x_1} \lrcorner d\tau = 0.$$

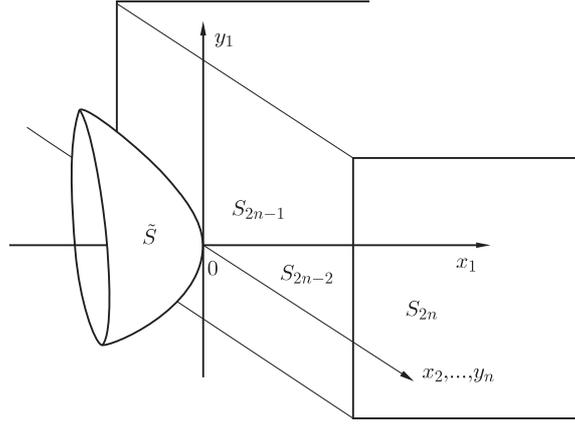


Fig. 1

Then $\tau = \pi^* \iota^* \tau$, where

$$\begin{aligned} \pi : R^n &\rightarrow \{x_1 = 0\}, & \pi(x_1, x_2, \dots, x_n) &= (0, x_2, \dots, x_n), \\ \iota : \{x_1 = 0\} &\rightarrow R^n, & \iota(x_2, \dots, x_n) &= (0, x_2, \dots, x_n). \end{aligned}$$

LEMMA 2.3. Let τ be a k -form on R^n satisfying

$$(6) \quad \frac{\partial}{\partial x_1} \lrcorner \tau = 0, \quad \frac{\partial}{\partial x_1} \lrcorner d\tau = \varphi \tau,$$

where φ is a smooth function on R^n . Then

$$\tau = \zeta \pi^* \iota^* \tau,$$

where ζ is a smooth function on R^n , and $\zeta|_{\{x_1=0\}} = 1$.

It is easy to prove the following lemmas.

LEMMA 2.4. Let α be a germ of a closed $(n-1)$ -form on R^n at 0 satisfying the following conditions:

1. $\alpha_0 \neq 0$,
2. a germ of a vector field X at 0 such that $X \lrcorner \alpha = 0$ and $X(0) \neq 0$ meets $\{x_1 = 0\}$ transversally at 0.

Then there exists a germ of diffeomorphism $\Phi : (R^n, 0) \rightarrow (R^n, 0)$, which preserves $\{x_1 = 0\}$ and

$$\Phi^* \alpha = dx_2 \wedge \dots \wedge dx_n,$$

where (x_1, \dots, x_n) is a coordinate system on R^n .

LEMMA 2.5. Let α be a germ of a 1-form on R^{2k+1} at 0 satisfying the following conditions:

1. $\alpha \wedge (d\alpha)_0^k \neq 0$,
2. a germ of a vector field X at 0 such that

$$X \lrcorner \alpha \wedge (d\alpha)^k = (d\alpha)^k$$

meets $\{z = 0\}$ transversally at 0,

3. $\iota^* \alpha_0 \neq 0$, where $\iota : \{z = 0\} \hookrightarrow R^{2k+1}$ is the canonical inclusion.

Then there exists a germ of diffeomorphism $\Phi : (R^{2k+1}, 0) \rightarrow (R^{2k+1}, 0)$, which preserves $\{z = 0\}$ and

$$\Phi^* \alpha = dz + dy_1 + \sum_{i=1}^k x_i dy_i,$$

where $(z, x_1, \dots, x_n, y_1, \dots, y_n)$ is a coordinate system on R^n .

Now we prove the main theorem obtaining the normal form (with moduli) of the symplectic structure on S . The geometrical contents of this theorem is illustrated in Fig. 1.

THEOREM 2.1. *Let ω be a symplectic structure on S . Assume $f(0) = 0$ and $df_0 \neq 0$. Then ω is S -equivalent to the form*

$$(7) \quad (x_1 - \psi(x_2, \dots, x_n, y_1, \dots, y_n))d(x_1 - \psi(x_2, \dots, x_n, y_1, \dots, y_n)) \wedge dy_1 + \sum_{i=2}^n dx_i \wedge dy_i,$$

where ψ is a germ at 0 of a smooth function, $\psi(0) = 0$, $\frac{\partial \psi}{\partial x_i}(0) = 0$, $i = 2, \dots, n$, $\frac{\partial \psi}{\partial y_i}(0) = 0$, $i = 1, \dots, n$.

Proof. By Lemma 2.1 we have $f = \pm(x_1 - q)$, where q does not depend on x_1 . We are searching for a 1-form α satisfying the following conditions:

1. $d\alpha = \omega$,
2. $\iota^* \alpha \wedge (d\iota^* \alpha)_0^{n-1} \neq 0$, where $\iota : \tilde{S} \hookrightarrow R^{2n}$ is the canonical inclusion,
3. $\tilde{\iota}^* \alpha_0 \neq 0$, where $\tilde{\iota} : \tilde{S} \cap \{y_1 = 0\} \hookrightarrow R^{2n}$ is the canonical inclusion.

ω is closed, then there exists a 1-form α such that $d\alpha = \omega$. If α fails to satisfy condition 3 then we replace it by the 1-form $\alpha + dy_2$, which satisfies conditions 1 and 3.

Since S_{2n-2} is symplectic and $T_0 S_{2n-2} = T_0(\tilde{S} \cap \{y_1 = 0\})$, we have $(\tilde{\iota}^* d\alpha)_0^{n-1} = (\tilde{\iota}^* \omega)_0^{n-1} \neq 0$. Hence by Lemma 2.4, we obtain

$$\delta^* \iota^* (d\alpha)^{n-1} = dx_2 \wedge \dots \wedge dx_n \wedge dy_1 \wedge \dots \wedge dy_n,$$

where $\delta : (\tilde{S}, 0) \rightarrow (\tilde{S}, 0)$ is a diffeomorphism which preserves $\tilde{S} \cap \{y_1 = 0\}$. Therefore

$$\iota^* d(\Delta^* \alpha)^{n-1} = dx_2 \wedge \dots \wedge dx_n \wedge dy_1 \wedge \dots \wedge dy_n,$$

where $\Delta \in G_S$ and

$$\Delta(x, y) = (x_1, \delta(x_2, \dots, x_n, y_1, \dots, y_n)).$$

If $\Delta^* \alpha$ fails to satisfy condition 2, then we replace it by the 1-form $\Delta^* \alpha + dy_1$, which satisfies all the conditions.

From condition 2 it follows that a vector field X which satisfies the conditions

$$X \lrcorner \alpha \wedge (d\alpha)^{n-1} = 0, \quad X(0) \neq 0,$$

meets \tilde{S} transversally at 0. Hence X also meets S_{2n-1} transversally at 0. Therefore by means of elements from G_S one can reduce X to the form $\pm \frac{\partial}{\partial x_1}$. Thus \tilde{S} is locally a graph

of a smooth function $\theta : (S_{2n-1}, 0) \rightarrow (R, 0)$. Hence $(x_2, \dots, x_n, \dots, y_1, \dots, y_n)$ define a coordinate system on \tilde{S} . From 2 and 3 it follows that $\iota^*\alpha$ satisfies the assumptions of Lemma 2.5. Therefore we have

$$\phi^* \iota^* \alpha = dy_1 + dy_2 + \sum_{i=2}^n x_i dy_i,$$

where $\phi : (\tilde{S}, 0) \rightarrow (\tilde{S}, 0)$ is a diffeomorphism which preserves $\tilde{S} \cap \{y_1 = 0\}$. Let $\Phi \in G_S$ be such that

$$\Phi(x, y) = (x_1, \phi(x_2, \dots, x_n, y_1, \dots, y_n)).$$

Hence we obtain

$$\iota^* \Phi^* \alpha = dy_1 + dy_2 + \sum_{i=2}^n x_i dy_i.$$

It is easy to check that the vector field X satisfies the following conditions:

$$(8) \quad X \lrcorner \alpha = 0 \quad \text{and} \quad X \lrcorner d\alpha = \varphi \alpha,$$

where $\varphi : R^{2n} \rightarrow R$ is a smooth function. Thus by Lemma 2.3, we obtain

$$\alpha = h \left(dy_1 + dy_2 + \sum_{i=2}^n x_i dy_i \right),$$

where $h : R^n \rightarrow R$ is a smooth function such that $h|_{\tilde{S}} = 1$. We have

$$(d\alpha)^n = n! h^{n-1} \frac{\partial h}{\partial x_1} \Omega.$$

On the other hand, by Lemma 2.1, $\omega^n = \pm(x_1 - g)\Omega$. Hence $n! h^{n-1} \frac{\partial h}{\partial x_1} = \pm(x_1 - g)$, and

$$\frac{\partial h^n}{\partial x_1} = \pm \frac{1}{(n-1)!} (x_1 - g)$$

with an extra condition $h|_{\{x_1=g\}} = 1$. Solving this equation we get

$$h = \sqrt[n]{\frac{\pm 1}{2(n-1)!} (x_1 - g)^2 + 1}.$$

By the diffeomorphism $\Lambda^{-1} \in G_\Sigma$, where

$$\Lambda(x, y) = (x_1, h(x, y)x_2, \dots, h(x, y)x_n, y_1, \dots, y_n),$$

we reduce α to

$$\alpha = h(dy_1 + dy_2) + \sum_{i=2}^n x_i dy_i,$$

The diffeomorphism

$$\Upsilon(x, y) = \left((x_1 - \zeta) \sqrt{(n-1)! \sum_{i=0}^{n-1} \binom{n}{i+1} \left(\frac{\pm(x_1 - \zeta)^2}{2} \right)^i} - g, y_1, \dots, x_n, y_n \right),$$

where ζ is a function which does not depend on x_1 and satisfies

$$\sqrt[n]{\frac{\pm 1}{2(n-1)!} g^2 + 1} = \pm \frac{\zeta^2}{2} + 1,$$

preserves the sets S_{2n-1} , S_{2n-2} and

$$\Upsilon^* \alpha = \left(\pm \frac{(x_1 - \zeta)^2}{2} + 1 \right) (dy_1 + dy_2) + \sum_{i=2}^n x_i dy_i.$$

If Υ does not belong to G_Σ then we replace it by $\Theta \circ \Upsilon$, where

$$\Theta(x, y) = (-x_1, x_2, \dots, x_n, y_1, \dots, y_n).$$

Hence we obtain

$$\alpha = \left(1 \pm \frac{1}{2}(x_1 - \psi)^2 \right) (dy_1 + dy_2) + \sum_{i=2}^n x_i dy_i.$$

Therefore

$$\omega = d\alpha = \pm(x_1 - \psi)d(x_1 - \psi) \wedge dy_1 + d\left(x_2 \pm \frac{1}{2}(x_1 - \psi)^2\right) \wedge dy_2 + \sum_{i=3}^n dx_i \wedge dy_i.$$

Finally, by means of $\Xi \in G_\Sigma$, where

$$\Xi(x, y) = \left(x_1, x_2 \pm \frac{1}{2}(x_1 - \psi)^2, x_3, \dots, x_n, \pm y_1, y_2, y_3, \dots, y_n \right),$$

we reduce ω to the form 7. ■

Now we pass to the investigation of stability properties of symplectic structures on S .

DEFINITION 2.2. Let ω be a symplectic form on S . Then ω is *stable* at $p \in S_{2n-2}$ if for any neighbourhood U of p in S_{2n-2} there is a neighbourhood V of ω (in the C^∞ topology on closed 2-forms) such that if β is in V , then there is a point $q \in U$ and a germ of a diffeomorphism $\Phi : (R^{2n}, q) \rightarrow (R^{2n}, p)$ which preserves S and $\Phi^* \beta = \omega$.

It is easy to see that the Darboux form on S is stable.

PROPOSITION 2.3. *Let ω be a symplectic structure on S . Assume $f(0) = 0$ and $df_0 \neq 0$. Then ω is not stable at 0.*

Proof. From Theorem 2.1 it follows that ω can be reduced to the form

$$(x_1 - \psi)d(x_1 - \psi) \wedge dy_1 + \sum_{i=2}^n dx_i \wedge dy_i.$$

Suppose the proposition is false. Let U be a neighbourhood of $0 \in R^{2n}$. $\psi(0) = 0 \in R$ is a critical value of $\psi|_U$. From the Sard theorem we see that there is $\epsilon \in R$ which is not a critical value of $\psi|_U$, in any neighbourhood of $0 \in R$. Let $\beta = \alpha + \epsilon d(x_1 - \psi) \wedge dy_1$. Then we can find a diffeomorphism Φ which preserves S and $\Phi^* \beta = \omega$. Hence

$$\Phi^* \beta^n = \Phi^* ((x_1 - \psi + \epsilon)\Omega) = \omega^n = (x_1 - \psi)\Omega.$$

Since $\Sigma_2(\omega)$ is tangent to S_{2n-1} at 0, $\Sigma_2(\beta)$ is tangent to S_{2n-1} at $q = \Phi(0) \in S_{2n-2}$. Therefore, we obtain

$$\psi(q) = \epsilon, \quad d\psi_q = 0,$$

which contradicts the fact that ϵ is not a critical value of $\psi|_U$. ■

2.1. Remark. Let us consider the following semialgebraic set:

$$S = S_{2n} \cup S_{2n-2} \subset R^{2n};$$

$$S_{2n} = \{(x, y) \in R^{2n} : x_1^3 > y_1^2\}, \quad S_{2n-2} = \{(x, y) \in R^{2n} : x_1 = 0, y_1 = 0\}.$$

We notice the difference with the previous space: ∂S_{2n} is a singular set.

We endow S with a symplectic structure ω . As before G_S denotes the group of diffeomorphisms $(R^{2n}, 0) \rightarrow (R^{2n}, 0)$ preserving S . Let ω_1, ω_2 be two symplectic structures on S . We say that ω_1 and ω_2 are S -equivalent if and only if $\Phi^*\omega_1 = \omega_2$ for some $\Phi \in G_S$. Now we can show the following

PROPOSITION 2.4. *Let ω be a symplectic structure on S . Assume $f(0) = 0$ and $df_0 \neq 0$. Then ω is a singular form of type $\Sigma_{2,0}$ at zero.*

Proof. By straightforward use of the proof of Proposition 2.1.

An analogous Darboux theorem for the space S is proved by Arnold ([2]): Let ω be a symplectic structure on R^{2n} . Then ω is S -equivalent with respect to formal equivalence to the Darboux form:

$$\omega \sim \sum_{i=1}^n dx_i \wedge dy_i.$$

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