

GLOBAL REGULAR SOLUTIONS TO THE NAVIER-STOKES EQUATIONS IN A CYLINDER

WOJCIECH M. ZAJĄCZKOWSKI

Institute of Mathematics, Polish Academy of Sciences

Śniadeckich 8, 00-956 Warszawa, Poland

E-mail: wz@impan.gov.pl

and

Institute of Mathematics and Cryptology, Cybernetics Faculty

Military University of Technology

S. Kaliskiego 2, 00-908 Warszawa, Poland

Abstract. The existence and uniqueness of solutions to the Navier-Stokes equations in a cylinder Ω and with boundary slip conditions is proved. Assuming that the azimuthal derivative of cylindrical coordinates and azimuthal coordinate of the initial velocity and the external force are sufficiently small we prove long time existence of regular solutions such that the velocity belongs to $W_{5/2}^{2,1}(\Omega \times (0, T))$ and the gradient of the pressure to $L_{5/2}(\Omega \times (0, T))$. We prove the existence of solutions without any restrictions on the lengths of the initial velocity and the external force.

1. Introduction. We examine the following problem (see [7]):

$$\begin{aligned}
 v_{,t} + v \cdot \nabla v - \operatorname{div} \mathbb{T}(v, p) &= f && \text{in } \Omega^T = \Omega \times (0, T), \\
 \operatorname{div} v &= 0 && \text{in } \Omega^T, \\
 (1.1) \quad v \cdot \bar{n} &= 0 && \text{on } S^T = S \times (0, T), \\
 \bar{n} \cdot \mathbb{D}(v) \cdot \bar{\tau}_\alpha &= 0, \quad \alpha = 1, 2, && \text{on } S^T, \\
 v|_{t=0} &= v(0) && \text{in } \Omega,
 \end{aligned}$$

where $\Omega \subset \mathbb{R}^3$ is a cylinder with the boundary S .

By $v = (v_1, v_2, v_3) \in \mathbb{R}^3$ we denote the velocity of the fluid, $p \in \mathbb{R}$ the pressure, $f = (f_1, f_2, f_3) \in \mathbb{R}^3$ the external force, \bar{n} is the unit outward vector normal to S , $\bar{\tau}_\alpha$,

2000 *Mathematics Subject Classification:* 35Q35, 35K20, 76D05, 76D03.

Key words and phrases: global existence of regular solutions, Navier-Stokes equations, incompressible fluid, solutions with large initial velocity and external force, solutions close to axially symmetric.

The paper is in final form and no version of it will be published elsewhere.

$\alpha = 1, 2$, are tangent to S . Moreover, the dot \cdot denotes the scalar product in \mathbb{R}^3 . By $\mathbb{T}(v, p)$ we denote the stress tensor of the form

$$(1.2) \quad \mathbb{T}(v, p) = \nu \mathbb{D}(v) - pI,$$

where ν is the constant viscosity coefficient, $\mathbb{D}(v)$ the dilatation tensor of the form

$$(1.3) \quad \mathbb{D}(v) = \{v_{i,x_j} + v_{j,x_i}\}_{i,j=1,2,3},$$

and I is the unit matrix.

Let (x_1, x_2, x_3) be a local Cartesian system such that the x_3 axis is the axis of the cylinder Ω . Let (r, φ, z) be the cylindrical coordinates such that $x_1 = r \cos \varphi$, $x_2 = r \sin \varphi$, $x_3 = z$.

Let for given $R > 0$, $a > 0$

$$\Omega = \{x \in \mathbb{R}^3 : r < R, \varphi \in [0, 2\pi], z \in (-a, a)\},$$

$S = S_1 \cup S_2$ where

$$S_1 = \{x \in \mathbb{R}^3 : r = R, \varphi \in [0, 2\pi], z \in (-a, a)\},$$

$$S_2 = \{x \in \mathbb{R}^3 : r < R, \varphi \in [0, 2\pi], z \text{ is either } -a \text{ or } a\}.$$

To prove the existence of solutions to problem (1.1) we apply the Leray-Schauder fixed point theorem. For this purpose we define a mapping Φ whose fixed point is a solution to problem (1.1).

Let

$$\begin{aligned} \mathfrak{M}(\Omega^T) &= L_4(0, T; L_\infty(\Omega)) \cap L_2(0, T; W_3^1(\Omega)) \cap L_\infty(0, T; W_{2,-\delta}^1(\Omega)) \\ &\cap L_\infty(0, T; L_{4,-\delta}(\Omega)) \cap L_2(0, T; W_{6/(1-2\varepsilon_0)}^1(\Omega)), \end{aligned}$$

where $\delta \in (0, 1/2)$, $\varepsilon_0 \in (0, 1/2)$.

Now we construct the mapping Φ . Let $v' \in \mathfrak{M}(\Omega^T)$ be given. By Lemmas 3.1–3.4 and inequalities (4.4), (4.13) there exists a solution to problem below (2.12) denoted by $\tilde{v} = \tilde{v}(v') \in \mathfrak{M}_0(\Omega^T) = L_{10}(\Omega^T) \cap L_{10/3}(0, T; W_{10/3}^1(\Omega))$. The relation $\tilde{v} = \tilde{v}(v')$ defines the mapping

$$(1.4) \quad \Phi_1 : \mathfrak{M}(\Omega^T) \ni v' \mapsto \Phi_1(v') = \tilde{v} \in \mathfrak{M}_0(\Omega^T).$$

Then problem (5.1) generates the mapping Φ_2 ,

$$(1.5) \quad v = \Phi_2(\tilde{v}, \lambda)$$

such that

$$\Phi_2 : \mathfrak{M}_0(\Omega^T) \times [0, 1] \rightarrow \mathfrak{M}_*(\Omega^T) = W_{5/2}^{2,1}(\Omega^T) \subset \mathfrak{M}(\Omega^T).$$

From (1.4) and (1.5) we define the transformation

$$(1.6) \quad \Phi : \mathfrak{M}(\Omega^T) \times [0, 1] \rightarrow \mathfrak{M}_*(\Omega^T)$$

by

$$\Phi(v', \lambda) = \Phi_2(\Phi_1(v'), \lambda).$$

From Lemmas 5.1 and 5.2 we have that Φ is uniformly continuous and compact. Moreover, index $\Phi|_{\lambda=0} = 1$.

Let us introduce the vectors: $\bar{e}_r = (\cos \varphi, \sin \varphi, 0)$, $\bar{e}_\varphi = (-\sin \varphi, \cos \varphi, 0)$, $\bar{e}_z = (0, 0, 1)$ connected with the cylindrical coordinates r, φ, z , respectively. The cylindrical coordinates of any vector u are $u_r = u \cdot \bar{e}_r$, $u_\varphi = u \cdot \bar{e}_\varphi$, $u_z = u \cdot \bar{e}_z$. Let $g = f_{r,\varphi}\bar{e}_r + f_{\varphi,\varphi}\bar{e}_\varphi + f_{z,\varphi}\bar{e}_z$, $h = v_{r,\varphi}\bar{e}_r + v_{\varphi,\varphi}\bar{e}_\varphi + v_{z,\varphi}\bar{e}_z$, $F = \text{rot } f$, $F' = (F_r, F_z)$, $\alpha = \text{rot } v$, $\alpha' = (\alpha_r, \alpha_z)$, $w = v_\varphi$. Assume that the following quantities are finite:

$$(1.7) \quad \begin{aligned} X(t) &= \|g\|_{L_{2,-(1+\varepsilon_*)}(\Omega^t)} + \|f_\varphi\|_{L_{2,-(1/2+\varepsilon_0)}(\Omega^t)} + \|F'\|_{L_2(0,t;L_{6/5}(\Omega))} \\ &\quad + \|h(0)\|_{H_{-(1+\varepsilon_*)}^1(\Omega)} + \|w(0)\|_{H_0^1(\Omega)} + \|\alpha'(0)\|_{L_2(\Omega)} + \|v_z(0)\|_{L_2(\Omega)} < \infty, \\ Y_1(t) &= \|F_\varphi\|_{L_{2,-1}(\Omega^t)} + \|\alpha_\varphi(0)\|_{L_{2,-1}(\Omega^t)} < \infty, \\ Y_2(t) &= \|f\|_{L_{5/2}(\Omega^t)} + \|v(0)\|_{W_{5/2}^{6/5}(\Omega)} < \infty, \end{aligned}$$

where $\varepsilon_* > 0$.

Let φ_1 be a nonnegative positive function which appears in (4.1). Let $A = \sigma[\varphi_1(0)Y_1^2 + c_1Y_2]$, where $\sigma \geq 2$ and c_1 is the constant from (4.1). Then for sufficiently small X Lemma 4.2 implies the estimate for a fixed point of mapping Φ ,

$$(1.8) \quad \|v\|_{W_{5/2}^{2,1}(\Omega^T)} + \|\nabla p\|_{L_{5/2}(\Omega^T)} \leq A.$$

Hence, the Leray-Schauder fixed point theorem implies

THEOREM 1.1. *Let (1.7) hold. Let X be sufficiently small. Then there exists a solution to problem (1.1) such that $v \in W_{5/2}^{2,1}(\Omega^T)$, $\nabla p \in L_{5/2}(\Omega^T)$ and (1.8) holds.*

2. Notation and auxiliary results. By c we denote generic constants and by $c(\sigma)$ we denote generic positive increasing functions depending on σ .

To simplify considerations we introduce

$$\begin{aligned} |u|_{p,Q} &= \|u\|_{L_p(Q)}, \quad Q \in \{\Omega, S, \Omega^T, S^T\}, \quad p \in [1, \infty], \\ \|u\|_{s,Q} &= \|u\|_{H^s(Q)}, \quad Q \in \{\Omega, S\}, \quad s \in \mathbb{R}_+ \cup \{0\}, \\ \|u\|_{s,Q} &= \|u\|_{W_2^{s,s/2}(Q)}, \quad Q \in \{\Omega^T, S^T\}, \quad s \in \mathbb{R}_+ \cup \{0\}, \end{aligned}$$

where $\|u\|_{0,Q} = |u|_{2,Q}$.

Moreover, $|u|_{p,q,Q^T} = \|u\|_{L_q(0,T;L_p(Q))}$ and

$$|u|_{p,q,\mu,Q^T} = \|u\|_{L_q(0,T;L_{p,\mu}(Q))}, \quad Q \in \{\Omega, S\}, \quad p, q \in [1, \infty], \quad \mu \in \mathbb{R}.$$

Let us introduce

$$\|v\|_{V_2^s(\Omega^T)} = \sup_{t \leq T} \|v(t)\|_{H^s(\Omega)} + \left(\int_0^T \|\nabla v(t)\|_{H^s(\Omega)}^2 dt \right)^{1/2}.$$

Finally, we introduce weighted spaces. Let $L_{p,\mu}(Q)$ be the set of functions u such that

$$\|u\|_{L_{p,\mu}(Q)} = \left(\int_Q |u|^p r^{p\mu} dx \right)^{1/p} < \infty, \quad p \in [1, \infty], \quad \mu \in \mathbb{R}, \quad Q \in \{\Omega, S, \Omega^T, S^T\}$$

with the notation

$$|u|_{p,\mu,Q} = \|u\|_{L_{p,\mu}(Q)}.$$

Let us define $H_\mu^s(Q)$ for $Q \in \{\Omega, S\}$, $s \in \mathbb{Z}_+ \cup \{0\}$, $\mu \in \mathbb{R}$ by

$$\|u\|_{H_\mu^s(Q)} = \left(\sum_{|\alpha| \leq s} \int_Q |D_x^\alpha u|^2 r^{2(\mu-s+|\alpha|)} dQ \right)^{1/2} < \infty$$

and $H_\mu^{s,s/2}(Q)$ for $Q \in \{\Omega^T, S^T\}$, $\frac{s}{2} \in \mathbb{Z}_+ \cup \{0\}$, $\mu \in \mathbb{R}$ by

$$\|u\|_{H_\mu^{s,s/2}(Q)} = \left(\sum_{|\alpha|+2i \leq s} \int_Q |D_x^\alpha \partial_t^i u|^2 r^{2(\mu-s+|\alpha|+2i)} dQ \right)^{1/2} < \infty.$$

To simplify notation we introduce

$$\|u\|_{s,\mu,Q} = \|u\|_{H_\mu^s(Q)} \quad \text{for } Q \in \{\Omega, S\}$$

and

$$\|u\|_{s,\mu,Q} = \|u\|_{H_\mu^{s,s/2}(Q)} \quad \text{for } Q \in \{\Omega^T, S^T\}.$$

Finally, we define

$$V_{p,\mu}^s(\Omega) = \left\{ u : \|u\|_{V_{p,\mu}^s(\Omega)} = \left(\sum_{|\alpha| \leq s} \int_\Omega |D_x^\alpha u|^p r^{p(\mu-s+|\alpha|)} dx \right)^{1/p} < \infty \right\}.$$

Now we recall inequalities and imbedding theorems used in this paper.

From [5] we have the imbedding

$$(2.1) \quad \|u\|_{V_{q,\beta+s-l+\frac{n}{p}-\frac{n}{q}}^s(\Omega)} \leq c \|u\|_{V_{p,\beta}^l(\Omega)}, \quad \Omega \subset \mathbb{R}^n,$$

and $s - l + \frac{n}{p} - \frac{n}{q} \leq 0$.

From Lemmas 4.2.3 and 4.2.4 in [7] we have the following Korn inequality:

$$(2.2) \quad \|v\|_{1,\Omega}^2 \leq c \left(E_\Omega(v) + \left| \int_\Omega v_\varphi(0) r dx \right|^2 + \left| \int_{\Omega^t} f_\varphi r dx dt' \right|^2 \right),$$

where

$$E_\Omega(v) = \int_\Omega (v_{i,x_j} + v_{j,x_i})^2 dx,$$

and the summation convention over the repeated indices is assumed. Moreover, to show (2.2) we used the conservation law

$$\int_\Omega v_\varphi(t) r dx = \int_{\Omega^t} f_\varphi r dx dt' + \int_\Omega v_\varphi(0) r dx.$$

In view of (2.2) we have the following energy inequality for solutions to problem (1.1)

LEMMA 2.1. *Assume that $v(0) \in L_2(\Omega)$, $v_\varphi \in L_2(\Omega^t)$, $f \in L_2(\Omega^t) \cap L_{2,1}(\Omega^t)$, $t \leq T$. Then*

$$(2.3) \quad \|v\|_{V_2^0(\Omega^t)} \leq c(|v(0)|_{2,\Omega} + |f|_{2,\Omega^t} + |v_\varphi|_{2,\Omega^t}), \quad t \leq T,$$

where c does not depend on T .

Let us introduce the quantities

$$(2.4) \quad \begin{aligned} h &= v_{r,\varphi} \bar{e}_r + v_{\varphi,\varphi} \bar{e}_\varphi + v_{z,\varphi} \bar{e}_z, \quad q = p,\varphi \\ \alpha &= \text{rot } v, \quad \chi = \alpha_\varphi, \quad w = v_\varphi, \quad F = \text{rot } f, \\ u &= v_{\varphi,z}, \quad g = f_{r,\varphi} \bar{e}_r + f_{\varphi,\varphi} \bar{e}_\varphi + f_{z,\varphi} \bar{e}_z. \end{aligned}$$

From Section 4.3 in [7] we have the following problem for χ ,

$$(2.5) \quad \begin{aligned} & \chi_{,t} + v \cdot \nabla \chi + (v_{r,r} + v_{z,z})\chi - \nu \left[\left(r \left(\frac{\chi}{r} \right)_{,r} \right)_{,r} + \frac{1}{r^2} \chi_{,\varphi\varphi} + \chi_{,zz} + 2 \left(\frac{\chi}{r} \right)_{,r} \right] \\ &= \frac{2\nu}{r} \left(-h_{\varphi,z} + \frac{1}{r} h_{z,\varphi} \right) - \frac{1}{r} \left(w_{,z} h_r - w_{,r} h_z + \frac{w}{r} h_z \right) + \frac{2}{r} v_\varphi v_{\varphi,z} + F_\varphi, \\ & \quad \chi|_S = 0, \\ & \quad \chi|_{t=0} = \chi(0), \end{aligned}$$

where v, h, w are treated as given functions.

Moreover, from Section 4.3 in [7] we obtain the problem for w ,

$$(2.6) \quad \begin{aligned} w_{,t} + v \cdot \nabla w + \frac{v_r}{r} w - \nu \Delta w + \nu \frac{w}{r^2} &= \frac{1}{r} q + \frac{2\nu}{r^2} h_r + f_\varphi & \text{in } \Omega^T, \\ w_{,r} &= \frac{1}{R} w & \text{on } S_1^T, \\ w_{,z} &= 0 & \text{on } S_2^T, \\ w|_{t=0} &= w(0) & \text{in } \Omega, \end{aligned}$$

where v, q, h are treated as given functions.

We need also the relations

$$(2.7) \quad \begin{aligned} \alpha_r &= \frac{h_z}{r} - w_{,z} \\ \alpha_\varphi &= v_{r,z} - v_{z,r} \equiv \chi, \\ \alpha_z &= w_{,r} + \frac{1}{r} w - \frac{1}{r} h_r. \end{aligned}$$

Finally we need the following problems for α_r (see (5.2.3) in [7])

$$(2.8) \quad \begin{aligned} \alpha_{r,t} + v \cdot \nabla \alpha_r - (v_{r,r} \alpha_r + v_{r,z} \alpha_z) - \frac{\chi}{r} h_r - \nu \Delta \alpha_r \\ + \nu \frac{\alpha_r}{r^2} &= -\frac{2\nu}{r^2} (h_{r,z} - h_{z,r}) + F_r & \text{in } \Omega^T, \\ \alpha_{r,r} &= -\frac{1}{R^2} h_z - \frac{1}{R} w_{,z} & \text{on } S_1^T, \\ \alpha_r &= 0 & \text{on } S_2^T, \\ \alpha_r|_{t=0} &= \alpha_r(0) & \text{in } \Omega \end{aligned}$$

and for α_z (see (5.2.5) in [7])

$$(2.9) \quad \begin{aligned} \alpha_{z,t} + v \cdot \nabla \alpha_z - (v_{z,r} \alpha_r + v_{z,z} \alpha_z) - \frac{\chi}{r} h_z \\ - \nu \Delta \alpha_z &= F_2 & \text{in } \Omega^T, \\ \alpha_z &= \frac{2}{R} w & \text{on } S_1^T, \\ \alpha_{z,z} &= 0 & \text{on } S_2^T, \\ \alpha_z|_{t=0} &= \alpha_z(0) & \text{in } \Omega. \end{aligned}$$

Differentiating (2.6) with respect to z yields the problem

$$\begin{aligned}
(2.10) \quad & u_{,t} + v \cdot \nabla u + \frac{v_r}{r} u - \nu \Delta u + \nu \frac{u}{r^2} = -v_{,z} \cdot \nabla w - \frac{v_{r,z}}{r} w \\
& + f_{\varphi,z} + \frac{1}{r} q_{,z} + \frac{2\nu}{r^2} h_{r,z} \quad \text{in } \Omega^T, \\
& u_{,r} = \frac{1}{R} u \quad \text{on } S_1^T, \\
& u = 0 \quad \text{on } S_2^T, \\
& u|_{t=0} = u(0) \quad \text{in } \Omega,
\end{aligned}$$

where the functions v, w, q and h are treated as given.

Next, for a given v we see that (h, q) is a solution to the problem

$$\begin{aligned}
(2.11) \quad & h_{,t} - \operatorname{div} \mathbb{T}(h, q) = -v \cdot \nabla h - h \cdot \nabla v + g \equiv G \quad \text{in } \Omega^T, \\
& \operatorname{div} h = 0 \quad \text{in } \Omega^T, \\
& \bar{n} \cdot h = 0, \quad \bar{n} \cdot \mathbb{T}(h, q) \cdot \bar{\tau}_\alpha = 0, \quad \alpha = 1, 2 \quad \text{on } S^T, \\
& h|_{t=0} = h(0) \quad \text{in } \Omega.
\end{aligned}$$

Finally, we consider the elliptic problem

$$\begin{aligned}
(2.12) \quad & \operatorname{rot} v = \alpha \quad \text{in } \Omega, \\
& \operatorname{div} v = 0 \quad \text{in } \Omega, \\
& v \cdot \bar{n} = 0 \quad \text{on } S.
\end{aligned}$$

LEMMA 2.2. *Assume that $g \in L_2(0, T; L_{6/5}(\Omega))$, $h(0) \in L_2(\Omega)$, $v \in L_2(0, T; W_3^1(\Omega))$. Then solutions to problem (2.11) satisfy*

$$(2.13) \quad |h(t)|_{2,\Omega} + \nu_* \|h\|_{L_2(0,t;H^1(\Omega))} \leq c \exp(|v_{,x}|_{3,2,\Omega^t}^2) (\|g\|_{6/5,2,\Omega^t} + |h(0)|_{2,\Omega}), \quad t \leq T,$$

where c does not depend on T and $0 < \nu_* < \nu$.

Proof. Multiplying (2.11)₁ by h , integrating over Ω , and using the boundary conditions yields

$$\frac{1}{2} \frac{d}{dt} |h|_{2,\Omega}^2 + \nu |\mathbb{D}(h)|_{2,\Omega}^2 \leq \int_{\Omega} |h \cdot \nabla v \cdot h| dx + \int_{\Omega} |g \cdot h| dx.$$

Using the Korn inequality $\|h\|_{1,\Omega} \leq c|\mathbb{D}(h)|_{2,\Omega}$, and applying the Hölder and Young inequalities we have

$$\frac{1}{2} \frac{d}{dt} |h|_{2,\Omega}^2 + \nu_* \|h\|_{1,\Omega}^2 \leq \varepsilon_1 |h|_{6,\Omega}^2 + c(1/\varepsilon_1) |\nabla v|_{3,\Omega}^2 |h|_{2,\Omega}^2 + \varepsilon_2 |h|_{6,\Omega}^2 + c(1/\varepsilon_2) |g|_{6/5,\Omega}^2,$$

where $\nu_* < \nu$.

For sufficiently small ε_1 and ε_2 we obtain

$$\frac{d}{dt} |h|_{2,\Omega}^2 + \nu_* \|h\|_{1,\Omega}^2 \leq c |\nabla v|_{3,\Omega}^2 |h|_{2,\Omega}^2 + c |g|_{6/5,\Omega}^2.$$

Integrating the above with respect to t implies (2.13). This ends the proof. ■

Let $\delta \in (0, 1)$ and

$$\mathfrak{N}(\Omega^T) = L_\infty(0, T; L_{4,-\delta}(\Omega)) \cap L_\infty(0, T; W_{2,-\delta}^1(\Omega)) \cap L_2(0, T; W_3^1(\Omega)).$$

LEMMA 2.3. Let $v \in \mathfrak{N}(\Omega^T)$, $\delta \in (0, 1)$, $g \in L_2(0, T; L_{6/5}(\Omega)) \cap L_{2,-(1+\varepsilon_*)}(\Omega^T)$, $h(0) \in H^1(\Omega) \cap H_{-(1+\varepsilon_*)}^1(\Omega)$, $0 < \varepsilon_* < \delta$ and let ε_* be sufficiently small. Then solutions of (2.11) satisfy

$$(2.14) \quad \begin{aligned} & \|h\|_{2,-(1+\varepsilon_*)}, \Omega^T + \|q\|_{L_2(0,T;H_{-(1+\varepsilon_*)}^2(\Omega))} \\ & \leq \varphi(\|v\|_{\mathfrak{N}(\Omega^T)})(|g|_{6/5,2,\Omega^T} + |h(0)|_{2,\Omega}) \\ & \quad + c(|g|_{2,-(1+\varepsilon_*)}, \Omega^T + \|h(0)\|_{1,-(1+\varepsilon_*)}, \Omega), \end{aligned}$$

where φ is an increasing positive function and c does not depend on T .

Proof. For solutions to problem (2.11) we have (see [8])

$$(2.15) \quad \begin{aligned} & \|h\|_{2,-(1+\varepsilon_*)}, \Omega^T + \|q\|_{L_2(0,T;H_{-(1+\varepsilon_*)}^1(\Omega))} \\ & \leq c(|G|_{2,-(1+\varepsilon_*)}, \Omega^T + \|h(0)\|_{1,-(1+\varepsilon_*)}, \Omega). \end{aligned}$$

By some interpolation inequalities we obtain

$$(2.16) \quad \begin{aligned} & \left(\int_0^T |v \cdot \nabla h|_{2,-1-\varepsilon_*}, \Omega^T dt \right)^{1/2} \leq \left(\int_0^T |v|_{4,-\delta,\Omega}^2 |\nabla h|_{4,\delta-1-\varepsilon_*}, \Omega^T dt \right)^{1/2} \\ & \leq \varepsilon_1 \|h\|_{2,\delta-1-\varepsilon_*}, \Omega^T + \varphi_1(1/\varepsilon_1, |v|_{4,\infty,-\delta,\Omega^T}) |h|_{2,\delta-1-\varepsilon_*}, \Omega^T, \end{aligned}$$

where φ_1 is an increasing positive function.

By the Hardy inequality and for $\delta > \varepsilon_*$ we have

$$(2.17) \quad |h|_{2,\delta-1-\varepsilon_*}, \Omega^T \leq c |\nabla h|_{2,\delta-\varepsilon_*}, \Omega^T \leq c |\nabla h|_{2,\Omega^T},$$

for a bounded domain. Similarly,

$$(2.18) \quad \begin{aligned} & \left(\int_0^T |h \cdot \nabla v|_{2,-1-\varepsilon_*}, \Omega^T dt \right)^{1/2} \leq \left(\int_0^T |\nabla v|_{2,-\delta,\Omega}^2 |h|_{\infty,\delta-1-\varepsilon_*}, \Omega^T dt \right)^{1/2} \\ & \leq \varepsilon_2 \|h\|_{2,\delta-1-\varepsilon_*}, \Omega^T + \varphi_2(1/\varepsilon_2, |\nabla v|_{2,\infty,-\delta,\Omega^T}) |h|_{2,\delta-1-\varepsilon_*}, \Omega^T, \end{aligned}$$

where the last norm is estimated by (2.17) and φ_2 is an increasing positive function.

Assuming $\varepsilon_1, \varepsilon_2$ sufficiently small we obtain from (2.13), (2.16), (2.18) inequality (2.14). This ends the proof. ■

3. Estimates. In this section we obtain a global a priori estimate for solutions to (1.1). From Lemma 4.3.1 from [7] we have

LEMMA 3.1. Assume that $h \in H_{-1}^{2,1}(\Omega^T)$, $u \in L_2(0, T; L_{4,-\frac{3}{4}-\varepsilon_0}(\Omega))$, $w \in L_\infty(0, T; H^1(\Omega))$, $f_\varphi \in L_{2,-1}(\Omega^T)$, $\chi(0) \in L_{2,-1}(\Omega)$ and $\varepsilon_0 > 0$ is any small number. Then solutions to problem (2.5) satisfy

$$(3.1) \quad \begin{aligned} & |\chi(t)|_{2,-1,\Omega}^2 + \nu \int_0^t \|\chi(t')/r\|_{1,\Omega}^2 dt' \leq c \exp(c \|h\|_{3,2,-1,\Omega^t}^2) \cdot \\ & \quad \left[(1 + \sup_{t' \leq t} \|w(t')\|_{1,0,\Omega}^2) \|h\|_{L_2(0,t;H_{-1}^2(\Omega))}^2 \right. \\ & \quad \left. + \sup_{t' \leq t} \|w(t')\|_{1,0,\Omega}^2 \int_0^t |u(t')|_{4,-3/4-\varepsilon_0,\Omega}^2 dt' + |F_\varphi|_{2,-1,\Omega^t}^2 + |\chi(0)|_{2,-1,\Omega}^2 \right], \quad t \leq T, \end{aligned}$$

where the constant c does not depend on T .

To estimate the second factor from the second term on the r.h.s. of (3.1) we need

LEMMA 3.2. *Assume that $v \in L_2(0, T; L_\infty(\Omega))$, $w \in L_\infty(0, T; H_0^1(\Omega)) \cap L_2(\Omega^T)$, $v_{,z} \in L_2(0, T; L_{\frac{3}{1-\mu}}(\Omega))$, $f_\varphi \in L_{2,-\mu}(\Omega^T)$, $q \in L_{2,-(1+\mu)}(\Omega^T)$, $h \in L_{2,-(1+\mu)}(\Omega^T)$, $u(0) \in L_{2,-\mu}(\Omega)$ and $\mu \in (0, 1)$. Then solutions of (2.10) satisfy the inequality*

$$(3.2) \quad \begin{aligned} & |u(t)|_{2,-\mu,\Omega}^2 + |\nabla u|_{2,-\mu,\Omega^t}^2 + |u|_{2,-(1+\mu),\Omega^t}^2 \\ & \leq c \exp(ct + c|v|_{\infty,2,\Omega^t}^2) [\sup_t \|w\|_{1,0,\Omega}^2 |v_{,z}|_{\frac{3}{1-\mu},2,\Omega^t}^2 \\ & \quad + |f_\varphi|_{2,-\mu,\Omega^t}^2 + |q|_{2,-(1+\mu),\Omega^t}^2 + |h|_{2,-(2+\mu),\Omega^t}^2 + |u(0)|_{2,-\mu,\Omega}^2], \end{aligned}$$

where $t \leq T$ and c does not depend on T .

Proof. Multiplying (2.10)₁ by $ur^{-2\mu}$ and integrating over $\Omega_{\varepsilon_*} = \{x \in \Omega : 0 < \varepsilon_* < r\}$ and using that $u|_{r=\varepsilon_*} = 0$ yields

$$(3.3) \quad \begin{aligned} & \frac{1}{2} \frac{d}{dt} |u|_{2,-\mu,\Omega_{\varepsilon_*}}^2 + \nu(1 - \varepsilon_0) |\nabla u|_{2,-\mu,\Omega_{\varepsilon_*}}^2 + \nu \left(1 - \frac{\mu^2}{\varepsilon_0}\right) |u|_{2,-(1+\mu),\Omega_{\varepsilon_*}}^2 \\ & \leq - \int_{\Omega_{\varepsilon_*}} \left(v \cdot \nabla u \frac{u}{r^{2\mu}} + \frac{v_r}{r} \frac{u^2}{r^{2\mu}} \right) dx - \int_{\Omega_{\varepsilon_*}} \left(v_{,z} \cdot \nabla w + \frac{v_{r,z}}{r} w \right) \frac{u}{r^{2\mu}} dx \\ & \quad + \nu \int_{\Omega_{\varepsilon_*}} \operatorname{div}(\nabla u u r^{-2\mu}) dx + \int_{\Omega_{\varepsilon_*}} f_{\varphi,z} \frac{u}{r^{2\mu}} dx + \int_{\Omega_{\varepsilon_*}} \left(\frac{1}{r} q_{,z} + \frac{2\nu}{r^2} h_{r,z} \right) \frac{u}{r^{2\mu}} dx. \end{aligned}$$

The first term on the r.h.s. equals

$$-(1 + \mu) \int_{\Omega_{\varepsilon_*}} \frac{v_r}{r} \frac{u^2}{r^{2\mu}} dx \equiv I_1,$$

where

$$|I_1| \leq \varepsilon_1 |u|_{2,-(1+\mu),\Omega_{\varepsilon_*}}^2 + c(1/\varepsilon_1) |v|_{\infty,\Omega_{\varepsilon_*}}^2 |u|_{2,-\mu,\Omega_{\varepsilon_*}}^2.$$

The second term on the r.h.s. of (3.3) is estimated by

$$\varepsilon_2 |u|_{\frac{2s}{s-2},-2\mu,\Omega_{\varepsilon_*}}^2 + c(1/\varepsilon_2) |v_{,z}|_{s,\Omega_{\varepsilon_*}}^2 \|w\|_{1,0,\Omega_{\varepsilon_*}}^2,$$

where $\frac{3}{s} = 1 - \mu$, $s > 2$.

By (2.1) we have

$$(3.4) \quad |u|_{\frac{2s}{s-2},-2\mu,\Omega} \leq c\|u\|_{1,-\mu,\Omega}.$$

The last two terms on the r.h.s. of (3.3) equal

$$- \int_{\Omega_{\varepsilon_*}} \left(f_\varphi + \frac{q}{r} + \frac{2\nu}{r^2} h_r \right) \frac{u_{,z}}{r^{2\mu}} dx \equiv I_2,$$

so

$$|I_2| \leq \varepsilon_3 |u_{,z}|_{2,-\mu,\Omega_{\varepsilon_*}}^2 + c(1/\varepsilon_3) (|f_\varphi|_{2,-\mu,\Omega_{\varepsilon_*}}^2 + |q|_{2,-(1+\mu),\Omega_{\varepsilon_*}}^2 + |h|_{2,-(2+\mu),\Omega_{\varepsilon_*}}^2).$$

In view of the boundary conditions (2.10)_{2,3} the third term on the r.h.s. of (3.3) equals

$$\frac{\nu}{R^{1+2\mu}} \int_{S_1} u^2 dS_1 \equiv I_3.$$

By the extension theorem we have

$$I_3 \leq \varepsilon_4 |\nabla u|_{2,\Omega_*}^2 + c(1/\varepsilon_4) |u|_{2,\Omega_*}^2.$$

Using the above estimates in (3.3) yields

$$(3.5) \quad \begin{aligned} & \frac{1}{2} \frac{d}{dt} |u|_{2,-\mu,\Omega_{\varepsilon_*}}^2 + \nu(1 - \varepsilon_0 - \varepsilon_2 - \varepsilon_3 - \varepsilon_4) |\nabla u|_{2,-\mu,\Omega_{\varepsilon_*}}^2 \\ & + \nu \left(1 - \frac{\mu^2}{\varepsilon_0} - \varepsilon_1 - \varepsilon_2 - \varepsilon_3 \right) |u|_{2,-(1+\mu),\Omega_{\varepsilon_*}}^2 \\ & \leq c|v|_{\infty,\Omega_{\varepsilon_*}}^2 |u|_{2,-\mu,\Omega_{\varepsilon_*}}^2 + c|v_z|_{\frac{3}{1-\mu},\Omega_{\varepsilon_*}}^2 \|w\|_{1,0,\Omega_{\varepsilon_*}}^2 \\ & + c(|f_\varphi|_{2,-\mu,\Omega_{\varepsilon_*}}^2 + |q|_{2,-(1+\mu),\Omega_{\varepsilon_*}}^2 + |h|_{2,-(2+\mu),\Omega_{\varepsilon_*}}^2) + c|u|_{2,\Omega_{\varepsilon_*}}^2. \end{aligned}$$

Assuming that $\varepsilon_0 - \varepsilon_4$ are such that the coefficients near the last two terms on the l.h.s. of (3.5) are positive, integrating the result with respect to time and passing with ε_* to 0 we obtain (3.2). This ends the proof. ■

Let us consider problem (2.6).

LEMMA 3.3. *Let $v \in L_2(0, T; L_\infty(\Omega))$, $q \in L_2(\Omega^T)$, $h \in L_2(0, T; L_{2,-1}(\Omega))$, $f_\varphi \in L_2(\Omega^T)$, $w(0) \in L_2(\Omega)$. Then solutions of (2.6) satisfy*

$$(3.6) \quad \begin{aligned} & |w(t)|_{2,\Omega}^2 + \nu \int_0^t \|w(t')\|_{1,0,\Omega}^2 dt' \leq c \exp(ct + c\|v\|_{\infty,2,\Omega^t}^2) \\ & \times [|q|_{2,\Omega^t}^2 + |h|_{2,-1,\Omega^t}^2 + |f_\varphi|_{2,\Omega^t}^2 + |w(0)|_{2,\Omega}^2], \quad t \leq T, \end{aligned}$$

where c does not depend on t .

Proof. Multiplying (2.6)₁ by w and integrating over Ω_{ε_*} (for the definition see the proof of Lemma 3.2) yields

$$(3.7) \quad \begin{aligned} & \frac{1}{2} \frac{d}{dt} |w|_{2,\Omega_{\varepsilon_*}}^2 + \nu |\nabla w|_{2,\Omega_{\varepsilon_*}}^2 + \nu |w|_{2,-1,\Omega_{\varepsilon_*}}^2 - \frac{\nu}{R} |w|_{2,S_1}^2 \\ & = - \int_{\Omega_{\varepsilon_*}} \frac{v_r}{r} w^2 dx + \int_{\Omega_{\varepsilon_*}} \left(\frac{1}{r} q + \frac{2\nu}{r^2} h_r + f_\varphi \right) w dx. \end{aligned}$$

The last term on the l.h.s. is estimated by

$$\varepsilon_1 |\nabla w|_{2,\Omega_{\varepsilon_*}}^2 + c(1/\varepsilon_1) |w|_{2,\Omega_{\varepsilon_*}}^2.$$

By the Young and the Hölder inequalities we estimate the first term on the r.h.s. of (3.7) by

$$\varepsilon_2 |w|_{2,-1,\Omega_{\varepsilon_*}}^2 + c(1/\varepsilon_2) |v|_{\infty,\Omega_*}^2 |w|_{2,\Omega_{\varepsilon_*}}^2.$$

Finally, the last term on the r.h.s. of (3.7) is estimated by

$$\varepsilon_3 |w|_{2,-1,\Omega_{\varepsilon_*}}^2 + c(1/\varepsilon_3) (|q|_{2,\Omega_*}^2 + |h|_{2,-1,\Omega_{\varepsilon_*}}^2 |f_\varphi|_{2,\Omega_{\varepsilon_*}}^2).$$

Using the above estimates in (3.7) with sufficiently small $\varepsilon_1 - \varepsilon_3$ we obtain

$$(3.8) \quad \begin{aligned} & \frac{d}{dt} |w|_{2,\Omega_{\varepsilon_*}}^2 + \nu |\nabla w|_{2,\Omega_{\varepsilon_*}}^2 + \nu |w|_{2,-1,\Omega_{\varepsilon_*}}^2 \\ & \leq c|w|_{2,\Omega_{\varepsilon_*}}^2 + c|v|_{\infty,\Omega_{\varepsilon_*}}^2 |w|_{2,\Omega_{\varepsilon_*}}^2 + c(|q|_{2,\Omega_{\varepsilon_*}}^2 + |h|_{2,-1,\Omega_{\varepsilon_*}}^2 + |f_\varphi|_{2,\Omega_{\varepsilon_*}}^2). \end{aligned}$$

Integrating (3.8) with respect to time and passing with ε_* to 0 yields (3.6). This concludes the proof. ■

Formula (5.3.22) from [7] yields

$$(3.9) \quad \|w(t)\|_{1,0,\Omega}^2 \leq c \exp(c\|v\|_{\infty,2,\Omega^t}^2) [(1 + \|v\|_{\infty,4,\Omega^t}^4) \sup_t |w(t)|_{2,1,\Omega}^2 + |w|_{2,\Omega^t}^2 + |q|_{2,\Omega^t}^2 + |h|_{2,-1,\Omega^t}^2 + |f_\varphi|_{2,1,\Omega^t}^2 + e^{-t} \|w(0)\|_{1,0,\Omega}^2],$$

where Lemma 6.3.5 from [7] gives

$$(3.10) \quad |w(t)|_{2,1,\Omega} \leq |w(0)|_{2,1,\Omega} + c \int_0^t (|q(t')|_{2,\Omega} + |h(t')|_{2,-1,\Omega} + |f_\varphi(t')|_{2,1,\Omega}) dt', \quad t \leq T.$$

Finally we obtain an estimate for solutions to problems (2.8), (2.9):

LEMMA 3.4. *Assume that $\alpha' = (\alpha_r, \alpha_z)$, $v \in L_2(0, T; W_3^1(\Omega)) \cap L_\infty(0, T; L_3(\Omega))$, $w \in W_2^{1,1/2}(\Omega^T) \cap L_\infty(0, T; H^s(\Omega))$, $s > 1/2$, $h \in L_\infty(0, T; L_{3/2}(\Omega)) \cap L_2(0, T; H_{-1}^1(\Omega))$, $u \in L_2(0, T; H^1(\Omega))$, $\chi/r \in L_2(0, T; L_6(\Omega))$, $F' = (F_r, F_z) \in L_2(0, T; L_{6/5}(\Omega))$, $\alpha'(0) \in L_2(\Omega)$.*

Then solutions of problems (2.8) and (2.9) satisfy

$$(3.11) \quad |\alpha'(t)|_{2,\Omega}^2 + \nu \int_0^t \|\alpha'(t')\|_{1,\Omega}^2 dt' \leq c \exp(\|v_x\|_{3,2,\Omega^t}^2) \left[\|v\|_{3,\infty,\Omega^t}^2 \|w\|_{W_2^{1,1/2}(\Omega^t)}^2 + \|v_x\|_{3,2,\Omega^t}^2 \|w\|_{L_\infty(0,t;H^s(\Omega))}^2 + \|h\|_{3/2,\infty,\Omega^t}^2 |\chi/r|_{6,2,\Omega^t}^2 + \int_0^t (\|h(t')\|_{1,-1,\Omega}^2 + \|u(t')\|_{1,\Omega}^2) dt' + \|F'\|_{6/5,2,\Omega^t}^2 + |\alpha'(0)|_{2,\Omega}^2 \right] + \|w\|_{L_\infty(0,t;H^s(\Omega))} + \|w\|_{W_2^{1,1/2}(\Omega^t)},$$

where $t \leq T$ and $s - \frac{1}{2}$ is an arbitrary small positive number.

Proof. Multiplying (2.8)₁ by α_r and integrating over Ω yields

$$(3.12) \quad \begin{aligned} \frac{1}{2} \frac{d}{dt} |\alpha_r|_{2,\Omega}^2 + \nu \|\alpha_r\|_{1,0,\Omega}^2 &\leq \left| \int_{S_1} \left(\frac{1}{R^3} h_z + \frac{1}{R} u \right) \alpha_r dS_1 \right| \\ &+ \left| \int_\Omega \frac{\chi}{r} h_r \alpha_r dx \right| + \int_\Omega |v_x| (\alpha_r^2 + \alpha_z^2) dx + 2\nu \int_\Omega \frac{1}{r^2} |h_{,x}| |\alpha_r| dx \\ &+ \left| \int_\Omega F_r \alpha_r dx \right|. \end{aligned}$$

The first term on the r.h.s. is estimated by

$$c|\alpha_r|_{4,S_1} (|h|_{4/3,S_1} + |u|_{4/3,S_1}) \leq \varepsilon_1 \|\alpha_r\|_{1,\Omega}^2 + c(1/\varepsilon_1) (\|h\|_{1,\Omega}^2 + \|u\|_{1,\Omega}^2),$$

the second by

$$\varepsilon_2 |\alpha_r|_{6,\Omega}^2 + c(1/\varepsilon_2) |\chi/r|_{6,\Omega}^2 |h|_{3/2,\Omega}^2,$$

the third by

$$\varepsilon_3 (|\alpha_r|_{6,\Omega}^2 + |\alpha_z|_{6,\Omega}^2) + c(1/\varepsilon_3) |v_x|_{3,\Omega}^2 (|\alpha_r|_{2,\Omega}^2 + |\alpha_z|_{2,\Omega}^2),$$

the fourth by

$$\varepsilon_4 |\alpha_r|_{2,-1,\Omega}^2 + c(1/\varepsilon_4) |h_{,x}|_{2,-1,\Omega}^2,$$

and the last by

$$\varepsilon_5 |\alpha_r|_{6,\Omega}^2 + c(1/\varepsilon_5) |F_r|_{6/5,\Omega}^2.$$

Hence, for sufficiently small $\varepsilon_1 - \varepsilon_5$ we have

$$(3.13) \quad \begin{aligned} \frac{d}{dt} |\alpha_r|_{2,\Omega}^2 + \nu \|\alpha_r\|_{1,0,\Omega}^2 &\leq c(\|h\|_{1,\Omega}^2 + \|u\|_{1,\Omega}^2 + |h|_{3/2,\Omega}^2 |\chi/r|_{6,\Omega}^2 \\ &+ |v_{,x}|_{3,\Omega}^2 (|\alpha_r|_{2,\Omega}^2 + |\alpha_z|_{2,\Omega}^2) + |h_{,x}|_{2,-1,\Omega}^2 + |F_r|_{6/5,\Omega}^2). \end{aligned}$$

To examine problem (2.9) we introduce a function β such that

$$(3.14) \quad \begin{aligned} \beta_{,t} - \nu \Delta \beta &= 0 && \text{in } \Omega^T, \\ \beta|_{S_1} &= \frac{2}{R} w && \text{on } S_1^T, \\ \beta_{,z}|_{S_2} &= 0 && \text{on } S_2^T, \\ \beta|_{t=0} &= 0 && \text{in } \Omega. \end{aligned}$$

Introducing the new function

$$(3.15) \quad \alpha'_z = \alpha_z - \beta,$$

we see that it is a solution to the problem

$$(3.16) \quad \begin{aligned} \alpha'_{z,t} - \nu \Delta \alpha'_z &= -v \cdot \nabla \alpha_z + (\alpha_r v_{z,r} + \alpha_z v_{z,z}) + \frac{\chi}{r} h_z + F_z && \text{in } \Omega^T, \\ \alpha'_z|_{S_1} &= 0, \quad \alpha'_{z,z}|_{S_2} = 0, \quad \alpha'_z|_{t=0} = \alpha_z(0). \end{aligned}$$

Multiplying (3.16)₁ by α'_z and integrating over Ω we obtain

$$(3.17) \quad \begin{aligned} \frac{1}{2} \frac{d}{dt} |\alpha'_z|_{2,\Omega}^2 + \nu \|\alpha'_z\|_{1,\Omega}^2 &= - \int_{\Omega} v \cdot \nabla \alpha_z \alpha'_z \, dx \\ &+ \int_{\Omega} (\alpha_r v_{z,r} + \alpha_z v_{z,z}) \alpha'_z \, dx + \int_{\Omega} \frac{\chi}{r} h_z \alpha'_z \, dx + \int_{\Omega} F_z \alpha'_z \, dx. \end{aligned}$$

The first term on the r.h.s. equals

$$- \int_{\Omega} v \cdot \nabla (\alpha'_z + \beta) \cdot \alpha'_z \, dx = - \int_{\Omega} v \cdot \nabla \beta \alpha'_z \, dx \equiv I_1,$$

where

$$|I_1| \leq \varepsilon_1 |\alpha'_z|_{6,\Omega}^2 + c(1/\varepsilon_1) |v|_{3,\Omega}^2 |\nabla \beta|_{2,\Omega}^2.$$

The second term on the r.h.s. of (3.17) is estimated by

$$\varepsilon_2 |\alpha'_z|_{6,\Omega}^2 + c(1/\varepsilon_2) |v_{,x}|_{3,\Omega}^2 (|\alpha_r|_{2,\Omega}^2 + |\alpha_z|_{2,\Omega}^2),$$

the third term by

$$\varepsilon_3 |\alpha'_z|_{6,\Omega}^2 + c(1/\varepsilon_3) |\chi/r|_{6,\Omega}^2 |h|_{3/2,\Omega}^2,$$

and finally the last term by

$$\varepsilon_4 |\alpha'_z|_{6,\Omega}^2 + c(1/\varepsilon_4) |F_z|_{6/5,\Omega}^2.$$

In view of the above estimates and for sufficiently small ε_1 through ε_4 we obtain from (3.17) the inequality

$$(3.18) \quad \begin{aligned} \frac{d}{dt} |\alpha'_z|_{2,\Omega}^2 + \nu \|\alpha'_z\|_{1,\Omega}^2 &\leq c [|v|_{3,\Omega}^2 |\nabla \beta|_{2,\Omega}^2 \\ &+ |v_{,x}|_{3,\Omega}^2 (|\alpha_r|_{2,\Omega}^2 + |\alpha_z|_{2,\Omega}^2) + |\chi/r|_{6,\Omega}^2 |h|_{3/2,\Omega}^2 + |F_z|_{6/5,\Omega}^2]. \end{aligned}$$

Using (3.15) in (3.13),

$$(3.19) \quad \begin{aligned} \frac{d}{dt} |\alpha_r|_{2,\Omega}^2 + \nu \|\alpha_r\|_{1,0,\Omega}^2 &\leq c |v_x|_{3,\Omega}^2 (|\alpha_r|_{2,\Omega}^2 + |\alpha_z'|_{2,\Omega}^2) \\ &+ c |v_x|_{3,\Omega}^2 |\beta|_{2,\Omega}^2 + c (\|h\|_{1,\Omega}^2 + \|u\|_{1,\Omega}^2) + c |h|_{3/2,\Omega}^2 |\chi/r|_{6,\Omega}^2 \\ &+ c |h_x|_{2,-1,\Omega}^2 + c |F_r|_{6/5,\Omega}^2 \end{aligned}$$

and in (3.18),

$$(3.20) \quad \begin{aligned} \frac{d}{dt} |\alpha_z'|_{2,\Omega}^2 + \nu \|\alpha_z'\|_{1,\Omega}^2 &\leq c |v_x|_{3,\Omega}^2 (|\alpha_r|_{2,\Omega}^2 + |\alpha_z'|_{2,\Omega}^2) \\ &+ c (|v|_{3,\Omega}^2 |\nabla \beta|_{2,\Omega}^2 + |v_x|_{3,\Omega}^2 |\beta|_{2,\Omega}^2) + c |h|_{3/2,\Omega}^2 |\chi/r|_{6,\Omega}^2 \\ &+ c |F_z|_{6/5,\Omega}^2. \end{aligned}$$

Adding (3.19) and (3.20) and integrating the result with respect to time yields

$$(3.21) \quad \begin{aligned} |\alpha_r(t)|_{2,\Omega}^2 + |\alpha_z'(t)|_{2,\Omega}^2 + \nu \int_0^t (\|\alpha_r(t')\|_{1,0,\Omega}^2 + \|\alpha_z'(t')\|_{1,\Omega}^2) dt' \\ \leq c \exp(c |v_x|_{3,2,\Omega^t}^2) \left[|v|_{3,\infty,\Omega^t}^2 |\nabla \beta|_{2,\Omega^t}^2 + |v_x|_{3,2,\Omega^t}^2 |\beta|_{2,\infty,\Omega^t}^2 \right. \\ + |h|_{3/2,\infty,\Omega^t}^2 |\chi/r|_{6,2,\Omega^t}^2 + \int_0^t (\|h(t')\|_{1,\Omega}^2 + \|u(t')\|_{1,\Omega}^2 + |h_x(t')|_{2,-1,\Omega}^2) dt' \\ \left. + |F'|_{6/5,2,\Omega^t}^2 + |\alpha'(0)|_{2,\Omega}^2 \right], \end{aligned}$$

where $F' = (F_r, F_z)$, $\alpha' = (\alpha_r, \alpha_z)$.

Using again (3.15) we obtain

$$(3.22) \quad \begin{aligned} |\alpha'(t)|_{2,\Omega}^2 + \nu \int_0^t \|\alpha'(t')\|_{1,\Omega}^2 dt' &\leq c \exp(c |v_x|_{3,2,\Omega^t}^2) \\ &\cdot \left[|v|_{3,\infty,\Omega^t}^2 |\nabla \beta|_{2,\Omega^t}^2 + |v_x|_{3,2,\Omega^t}^2 |\beta|_{2,\infty,\Omega^t}^2 \right. \\ &+ |h|_{3/2,\infty,\Omega^t}^2 |\chi/r|_{6,2,\Omega^t}^2 + \int_0^t (\|h(t')\|_{1,-1,\Omega}^2 + \|u(t')\|_{1,\Omega}^2) dt' \\ &\left. + |F'|_{6/5,2,\Omega^t}^2 + |\alpha'(0)|_{2,\Omega}^2 \right] + |\beta|_{2,\infty,\Omega^t}^2 + \nu \int_0^t \|\beta(t')\|_{1,\Omega}^2 dt'. \end{aligned}$$

By the potential theory techniques we have (see Lemmas 6.1, 6.2)

$$(3.23) \quad \begin{aligned} |\beta|_{2,\infty,S^t} &\leq c |w|_{2,\infty,S^t} \leq c \sup_t \|w\|_{s,\Omega}, \quad s > \frac{1}{2}, \\ \left(\int_0^t \|\beta(t')\|_{1,\Omega}^2 dt' \right)^{1/2} &\leq c \|w\|_{W_2^{1/2,1/4}(S^t)} \leq c \|w\|_{W_2^{1,1/2}(\Omega^t)}. \end{aligned}$$

Employing (3.23) in (3.22) yields (3.11). This concludes the proof. ■

To estimate the second factor of the second term in the square bracket on the r.h.s. of (3.1) we employ (3.2) for $\mu = \frac{1}{2} + \varepsilon_0$. Then (3.1) takes the form

$$(3.24) \quad |\chi(t)|_{2,-1,\Omega}^2 + \nu \int_0^t \|\chi(t')/r\|_{1,\Omega}^2 dt' \leq c \exp(c |h|_{3,2,-1,\Omega^t}^2)$$

$$\begin{aligned} & \times [(1 + \|w\|_{L_\infty(0,t;H_0^1(\Omega))}^2) \|h\|_{L_2(0,t;H_{-1}^2(\Omega))}^2 + \|w\|_{L_\infty(0,t;H_0^1(\Omega))}^2 \exp(ct + c|v|_{\infty,2,\Omega^t}^2) \\ & \quad \times (\|w\|_{L_\infty(0,t;H_0^1(\Omega))}^2 |v_z|_{\frac{6}{1-2\varepsilon_0},2,\Omega^t}^2 \\ & \quad + |f_\varphi|_{2,-\frac{1}{2}-\varepsilon_0,\Omega^t}^2 + |q|_{2,-(\frac{3}{2}+\varepsilon_0),\Omega^t}^2 + |h|_{2,-(\frac{5}{2}+\varepsilon_0),\Omega^t}^2 + |u(0)|_{2,-(\frac{1}{2}+\varepsilon_0),\Omega^t}^2 \\ & \quad + |F_\varphi|_{2,-1,\Omega^t}^2 + |\chi(0)|_{2,-1,\Omega^t}^2], \quad t \leq T. \end{aligned}$$

4. Estimate of a fixed point. First we obtain an inequality implying an estimate for a fixed point of transformation (1.6).

LEMMA 4.1. *Let*

$$\begin{aligned} Z_0(t) &= \|v\|_{2,5/2,\Omega^t}, \\ X(t) &= |g|_{2,-(1+\varepsilon_*),\Omega^t} + |f_\varphi|_{2,-(1/2+\varepsilon_0),\Omega^t} + |F'|_{6/5,2,\Omega^t} \\ &+ \|h(0)\|_{1,-(1+\varepsilon_*),\Omega} + \|w(0)\|_{1,0,\Omega} + |\alpha'(0)|_{2,\Omega} + |u(0)|_{2,\Omega} < \infty, \\ Y_1(t) &= |F_\varphi|_{2,-1,\Omega^t} + |\chi(0)|_{2,-1,\Omega^t} < \infty, \\ Y_2(t) &= |f|_{5/2,\Omega^t} + \|v(0)\|_{6/5,5/2,\Omega} < \infty, \end{aligned}$$

where $\varepsilon_*, \varepsilon_0$ are positive arbitrary small numbers and $t \leq T$. Then

$$(4.1) \quad Z_0 \leq \varphi_1(\varphi(t)Z_0X)[\varphi_1(t,Z_0)X(1+Y_1) + Y_1]^2 + c_1Y_2,$$

where φ, φ_1 are increasing positive functions.

Proof. Applying Lemmas 2.2 and 2.3 we obtain from (3.6), (3.9), (3.10) the inequality

$$(4.2) \quad \|w(t)\|_{1,0,\Omega} \leq \varphi(t, Z_1(t))X_1(t),$$

where φ is an increasing positive function and

$$\begin{aligned} (4.3) \quad Z_1(t) &= |v|_{\infty,4,\Omega^t} + |v_x|_{3,2,\Omega^t} + |v_x|_{2,\infty,-\delta,\Omega^t} + |v|_{4,\infty,-\delta,\Omega^t}, \\ X_1(t) &= |g|_{2,-(1+\varepsilon_*),\Omega^t} + |f_\varphi|_{2,\Omega^t} + \|h(0)\|_{1,-(1+\varepsilon_*),\Omega} + \|w(0)\|_{1,0,\Omega}, \end{aligned}$$

and $1 > \delta > \varepsilon_* > 0$.

In virtue of (4.2) and Lemma 2.3 inequality (3.24) assumes the form

$$(4.4) \quad \|\chi/r\|_{V_2^0(\Omega^t)} \leq \varphi(t, Z_2(t))X_2(t) + \varphi(Z_2(t)X_2(t))Y_1(t),$$

where φ is an increasing positive function and

$$\begin{aligned} (4.5) \quad Z_2(t) &= Z_1(t) + |v_x|_{\frac{6}{1-2\varepsilon_0},2,\Omega^t}, \\ X_2(t) &= X_1(t) + |f_\varphi|_{2,-(1/2+\varepsilon_0),\Omega^t}, \\ Y_1(t) &= |F_\varphi|_{2,-1,\Omega^t} + |\chi(0)|_{2,-1,\Omega}, \end{aligned}$$

where $\varepsilon_0 > 0$ is an arbitrary small number. Next, (3.11) yields

$$\begin{aligned} (4.6) \quad \|\alpha'\|_{V_2^0(\Omega^t)} &\leq \varphi(Z_2)[\|w\|_{W_2^{1,1/2}(\Omega^t)} + \|w\|_{L_\infty(0,t;H^1(\Omega))} + X_2\|\chi/r\|_{V_2^0(\Omega^t)} \\ &\quad + X_1(t) + \|u\|_{L_2(0,t;H^1(\Omega))} + X_3(t)], \end{aligned}$$

where

$$(4.7) \quad X_3(t) = |F'|_{6/5,2,\Omega^t} + |\alpha'(0)|_{2,\Omega}.$$

In view of (4.2) and (4.4) we obtain

$$(4.8) \quad \begin{aligned} \|\alpha'\|_{V_2^0(\Omega^t)} &\leq \varphi(Z_2)[\varphi(t)(X_4(t) + X_2Y_1) \\ &\quad + \|w\|_{L_2(\Omega; W^{1/2}(0,t))} + \|u\|_{L_2(0,t; H^1(\Omega))}], \end{aligned}$$

where

$$(4.9) \quad X_4(t) = X_2(t) + X_3(t).$$

Using (3.2) for $\mu = 0$, (4.2) and Lemma 2.3 we obtain

$$(4.10) \quad \|u\|_{V_2^0(\Omega^t)} \leq \varphi(t, Z_2)(X_2 + |u(0)|_{2,\Omega}).$$

From Lemma 6.3.3 from [7] we have

$$(4.11) \quad \begin{aligned} |w_{,t}|_{2,\Omega^t} &\leq c\|w(0)\|_{1,0,\Omega} \|v\|_{\infty,2,\Omega^t} + c(|q|_{2,-1,\Omega^t} + |h|_{2,-2,\Omega^t} + |f_\varphi|_{2,\Omega^t}) \\ &\quad + c\|w\|_{L_2(0,t; H^1(\Omega))} + c\|w(0)\|_{1,0,\Omega}. \end{aligned}$$

Using (4.2) and Lemma 2.3 in (4.11) implies

$$(4.12) \quad |w_{,t}|_{2,\Omega^t} \leq \varphi(t, Z_2)X_1(t).$$

Employing (4.10) and (4.12) in (4.8) yields

$$(4.13) \quad \|\alpha'\|_{V_2^0(\Omega^t)} \leq \varphi(t, Z_2)X(t)(1 + Y_1),$$

where

$$(4.14) \quad X(t) = X_4 + |u(0)|_{2,\Omega}.$$

In view of (4.4) and (4.13) we obtain for solutions to problem (2.12) the inequality

$$(4.15) \quad |v|_{10,\Omega^t} + |\nabla v|_{10/3,\Omega^t} \leq \varphi(t, ZX)Y_1 + \varphi(t, Z)X(1 + Y_1),$$

where $Z = Z_1 + Z_2$. In view of (4.15) and the estimate

$$(4.16) \quad Z(t) \leq cZ_0(t),$$

we obtain for solutions of problem (1.1) inequality (4.1). This concludes the proof. ■

LEMMA 4.2. *Let the assumptions of Lemma 4.1 hold. Let $T < \infty$ be given. Let $A = \sigma[\varphi_1(0)Y_1^2 + c_1Y_2]$, where $\sigma \geq 2$ and let φ_1 be the function from (4.1). Then for sufficiently small X ,*

$$(4.17) \quad Z_0(t) \leq A.$$

The proof follows directly from (4.1).

5. Existence. To prove the existence of solutions to problem (1.1) we construct a mapping Φ_2 defined by the problem (see [4])

$$(5.1) \quad \begin{aligned} v_{,t} - \operatorname{div}\mathbb{T}(v, p) &= -\lambda\tilde{v}(v') \cdot \nabla\tilde{v}(v') + f && \text{in } \Omega^T, \\ \operatorname{div}v &= 0 && \text{in } \Omega^T, \\ v \cdot \bar{n} = 0 \quad \bar{n} \cdot \mathbb{T}(v, p) \cdot \bar{\tau}_\alpha &= 0, \quad \alpha = 1, 2, && \text{on } S^T, \\ v|_{t=0} &= v(0) && \text{in } \Omega, \end{aligned}$$

where $\lambda \in [0, 1]$. Hence

$$(5.2) \quad v = \Phi_2(\tilde{v}, \lambda).$$

The quantity \tilde{v} is calculated from problem (2.12) where α is determined by (4.4), (4.8) with $Z_2 = Z_2(v')$ and v' is assumed to be a prescribed element of the space

$$\mathfrak{M}(\Omega^T) = \{u : Z_2(u) < \infty\}.$$

Then problem (2.12) determines the transformation

$$\mathfrak{M}(\Omega^T) \ni v' \rightarrow \Phi_1(v') = \tilde{v} \in \mathfrak{M}_0(\Omega^T)$$

where

$$\mathfrak{M}_0(\Omega^T) = \{u : u \in L_{10}(\Omega^T) \text{ and } \nabla u \in L_{\frac{10}{3}}(\Omega^T)\}.$$

Hence

$$\Phi_2 : \mathfrak{M}_0(\Omega^T) \times [0, 1] \rightarrow \mathfrak{M}_*(\Omega^T) = W_{5/2}^{2,1}(\Omega^T).$$

Defining

$$\Phi = \Phi_2 \circ \Phi_1$$

we see that (4.17) is the estimate of a fixed point of Φ .

To prove the existence of solutions to problem (1.1) we apply the Leray-Schauder fixed point theorem. Therefore we have to show the following properties of the mapping

$$\Phi : \mathfrak{M}(\Omega^T) \times [0, 1] \rightarrow \mathfrak{M}_*(\Omega^T) :$$

- Compactness.
- Continuity.
- Existence of a unique solution for $\lambda = 0$.

LEMMA 5.1. *The mapping Φ is compact and for $\lambda = 0$ index $\Phi = 1$.*

Proof. Compactness follows from the compact imbedding $\mathfrak{M}_*(\Omega^T) \subset \mathfrak{M}(\Omega^T)$.

For $\lambda = 0$ the unique existence of solutions to the corresponding Stokes system follows from [1]. This ends the proof. ■

Finally, we show the continuity.

LEMMA 5.2. *Let the assumptions of Lemmas 4.1 and 4.2 hold. Then the mapping $\Phi : \mathfrak{M}(\Omega^T) \times [0, 1] \rightarrow \mathfrak{M}_*(\Omega^T)$ is continuous.*

Proof. Assume that functions $v'_s \in \mathfrak{M}(\Omega^T)$, $s = 1, 2$, are given. Then we have problems (2.5), (2.6), (2.8), (2.9), (2.10), (2.11) for functions h_s , q_s , u_s , w_s , χ_s , $\alpha'_s = (\alpha_{sr}, \alpha_{sz})$, corresponding to v'_s , $s = 1, 2$. Then problem (2.12) determines \tilde{v}_s corresponding to α_s , $s = 1, 2$. Introducing the differences

$$\begin{aligned} V' &= v'_1 - v'_2, & H &= h_1 - h_2, & Q &= q_1 - q_2, & W &= w_1 - w_2, & K &= \chi_1 - \chi_2, \\ U &= u_1 - u_2, & A_r &= \alpha_{1r} - \alpha_{2r}, & A_z &= \alpha_{1z} - \alpha_{2z}, & \tilde{V} &= \tilde{v}_1 - \tilde{v}_2, \end{aligned}$$

we see that they are solutions to the problems

$$\begin{aligned} (5.3) \quad H_{,t} - \operatorname{div} \mathbb{T}(H, Q) &= -V' \cdot \nabla h_1 - v'_2 \cdot \nabla H - H \cdot \nabla v'_1 - h_2 \cdot \nabla V', \\ &\quad \operatorname{div} H = 0, \\ \bar{n} \cdot H &= 0, \quad \bar{n} \cdot \mathbb{D}(H) \cdot \bar{\tau}_\alpha = 0, \quad \alpha = 1, 2, \quad \text{on } S^T, \\ H|_{t=0} &= 0; \end{aligned}$$

$$\begin{aligned}
(5.4) \quad & W_{,t} - \nu \Delta W + \nu \frac{W}{r^2} = -V' \cdot \nabla w_1 - v'_2 \cdot \nabla W \\
& - \frac{V'_r}{r} w_1 - \frac{v'_{2r}}{r} W + \frac{1}{r} Q + \frac{2\nu}{r^2} H, \\
& W_{,r} = \frac{1}{R} W \quad \text{on } S_1^T, \quad W_{,z} = 0 \quad \text{on } S_2^T, \\
& W|_{t=0} = 0;
\end{aligned}$$

$$\begin{aligned}
(5.5) \quad & K_{,t} + V' \cdot \nabla \chi_1 + v'_2 \cdot \nabla K + (V'_{r,r} + V'_{z,z}) \chi_1 + (v'_{2r,r} + v'_{2z,z}) K \\
& - \nu \Delta K + \nu \frac{K}{r^2} = \frac{2\nu}{r} \left(-H_{\varphi,z} + \frac{1}{r} H_{z,\varphi} \right) - \frac{1}{r} (W_{,z} h_{1r} + w_{2,z} H_r) \\
& - W_{,r} h_{1z} - w_{2,r} H_z + \frac{W}{r} h_{1z} + \frac{w_2}{r} H_z + \frac{2}{r} W u_1 + \frac{2}{r} w_2 U, \\
& K = 0 \quad \text{on } S^T, \quad K|_{t=0} = 0;
\end{aligned}$$

$$\begin{aligned}
(5.6) \quad & U_{,t} + V' \cdot \nabla u_1 + v'_2 \cdot \nabla U + \frac{V'_r}{r} u_1 + \frac{v'_{2r}}{r} U - \nu \Delta U + \nu \frac{U}{r^2} \\
& = -V'_{,z} \cdot \nabla w_1 - v'_{2,z} \cdot \nabla W - \frac{V'_{r,z}}{r} w_1 - \frac{v'_{2r,z}}{r} W + \frac{1}{r} Q_{,z} + \frac{2\nu}{r^2} H_{,z}, \\
& U_{,r} = \frac{1}{R} U \quad \text{on } S_1^T, \quad U = 0 \quad \text{on } S_2^T, \quad U|_{t=0} = 0;
\end{aligned}$$

$$\begin{aligned}
(5.7) \quad & A_{r,t} + V' \cdot \nabla \alpha_{1r} + v'_2 \cdot \nabla A_r - (V'_{r,r} \alpha_{1r} + V'_{r,z} \alpha_{1z}) \\
& - (v'_{2r,r} A_r + v'_{2r,z} A_z) - \frac{K}{r} h_{1r} - \frac{\chi_2}{r} H_r - \nu \Delta A_r + \nu \frac{A_r}{r^2} \\
& = -\frac{2\nu}{r^2} (H_{r,z} - H_{z,r}),
\end{aligned}$$

$$A_{r,r} = -\frac{1}{R^2} H_z - \frac{1}{R} W_{,z} \quad \text{on } S_1^T, \quad A_r = 0 \quad \text{on } S_2^T, \quad A_r|_{t=0} = 0;$$

$$\begin{aligned}
(5.8) \quad & A_{z,t} + V' \cdot \nabla \alpha_{1z} + v'_2 \cdot \nabla A_z - (V'_{r,r} \alpha_{1r} + V'_{z,z} \alpha_{1z}) - (v'_{2z,r} A_r + v'_{2z,z} A_z) \\
& - \frac{K}{r} h_{1z} - \frac{\chi_2}{r} H_z - \nu \Delta A_z = 0, \\
& A_z = \frac{2}{R} W \quad \text{on } S_1^T, \quad A_{z,z} = 0 \quad \text{on } S_2^T, \quad A_z|_{t=0} = 0;
\end{aligned}$$

$$\begin{aligned}
(5.9) \quad & \operatorname{rot} \tilde{V} = \bar{A}, \\
& \operatorname{div} \tilde{V} = 0 \\
& \tilde{V} \cdot \bar{n}|_S = 0,
\end{aligned}$$

where $\bar{A} = (A_r, K, A_z)$, $A' = (A_r, A_z)$.

To obtain estimates for solutions to problems (5.3)–(5.9), we use Lemmas 4.1 and 4.2. Hence,

$$(5.10) \quad \|v'_s\|_{\mathfrak{M}(\Omega^t)} \leq A, \quad s = 1, 2.$$

In view of (5.10) we obtain for solutions to problems (2.5)–(2.11) the estimates

$$\begin{aligned}
& \|h_s\|_{2,-(1+\varepsilon_*)}, \Omega^t} + \|q_s\|_{L_2(0,t;H_{-(1+\varepsilon_*)}^1(\Omega))} \leq \varphi(A), \\
& \|\chi_s/r\|_{V_2^0(\Omega^t)} \leq \varphi(A), \\
(5.11) \quad & \|u_s\|_{V_{2,-\mu}^0(\Omega^t)} \leq \varphi(A), \quad \mu \in (0, 1), \\
& \|w_s\|_{L_\infty(0,t;H_0^1(\Omega))} + |w_{s,t}|_{2,\Omega^t} \leq \varphi(A), \\
& \|\alpha'_s\|_{V_2^0(\Omega^t)} \leq \varphi(A), \quad s = 1, 2, \quad t \leq T,
\end{aligned}$$

where $V_{2,-\mu}^0(\Omega^T)$ is $V_2^0(\Omega^T)$ with the $L_2(\Omega)$ norm replaced by $L_{2,-\mu}(\Omega)$.

In view of (5.11) we obtain for solutions to problems (5.3)–(5.8) the inequalities

$$\begin{aligned}
& \|H\|_{2,-(1+\varepsilon_*)}, \Omega^t} + \|Q\|_{L_2(0,t;H_{-(1+\varepsilon_*)}^1(\Omega))} \leq \varepsilon(A) \|V'\|_{\mathfrak{M}(\Omega^t)}, \\
& \|K/r\|_{V_2^0(\Omega^t)} \leq \varphi(A, t) (\|V'\|_{\mathfrak{M}(\Omega^t)} + \sup_t \|W(t)\|_{1,0,\Omega} \\
(5.12) \quad & + \|U\|_{L_2(0,t;L_{3,-1}(\Omega))}), \\
& \|U\|_{V_{2,-\mu}^0(\Omega^t)} \leq \varphi(A, t) [\|V'\|_{\mathfrak{M}(\Omega^t)} + \sup_t \|W\|_{1,0,\Omega}], \quad \mu \in (0, 1), \\
& \sup_t (\|W(t)\|_{1,0,\Omega} + |W(t)|_{2,\Omega}) + |W_{,t}|_{2,\Omega^t} \leq \varphi(A) \|V'\|_{\mathfrak{M}(\Omega^t)}, \\
& \|A'\|_{V_2^0(\Omega^t)} \leq \varphi(A, t) \|V'\|_{\mathfrak{M}(\Omega^t)}.
\end{aligned}$$

From (5.12) we have

$$\|\bar{A}\|_{V_2^0(\Omega^t)} \leq \varphi(A, t) \|V'\|_{\mathfrak{M}(\Omega^t)},$$

so problem (5.9) implies

$$(5.13) \quad \|\tilde{V}\|_{\mathfrak{M}_0(\Omega^t)} \leq \varphi(A, t) \|V'\|_{\mathfrak{M}(\Omega^t)}.$$

Let $V = v_1 - v_2$, $P = p_1 - p_2$. Then problem (5.1) implies

$$\begin{aligned}
(5.14) \quad & V_{,t} - \operatorname{div} \mathbb{T}(V, P) = -\lambda(V \cdot \nabla v_1 + v_2 \cdot \nabla V), \\
& \operatorname{div} V = 0 \\
& \bar{n} \cdot V|_S = 0, \quad \bar{n} \cdot \mathbb{T}(V, P) \cdot \bar{\tau}_\alpha|_S = 0, \quad \alpha = 1, 2, \\
& V|_{t=0} = 0.
\end{aligned}$$

Hence, (5.13) yields

$$(5.15) \quad \|V\|_{\mathfrak{M}_*(\Omega^t)} \leq \varphi(A) \|\tilde{V}\|_{\mathfrak{M}_0(\Omega^t)} \leq \varphi(A, t) \|V'\|_{\mathfrak{M}(\Omega^t)}.$$

This implies continuity of the mapping Φ and ends the proof. ■

6. Appendix. In this section we consider the problem

$$\begin{aligned}
(6.1) \quad & u_t - \Delta u = 0 \quad \text{in } \Omega^T, \\
& u|_S = \varphi \quad \text{on } S^T, \\
& u|_{t=0} = 0 \quad \text{in } \Omega.
\end{aligned}$$

First we examine problem (6.1) in the half-space $x_3 > 0$.

The fundamental solution to (6.1)₁ has the form

$$\begin{aligned}
(6.2) \quad & \Gamma(x, t) = \frac{1}{(4\pi t)^{3/2}} e^{-\frac{x^2}{4t}}, \quad t > 0, \\
& \Gamma(x, t) = 0, \quad t < 0.
\end{aligned}$$

Then a solution to problem (6.1) in the half-space $x_3 > 0$ has the form

$$(6.3) \quad u(x, t) = -2 \int_0^t dt' \int_{\mathbb{R}^2} \frac{\partial \Gamma(x' - y', x_3, t - t')}{\partial x_3} \varphi(y', t') dy'.$$

Using the form of Γ ,

$$(6.4) \quad \Gamma(x' - y', x_3, t - t') = \frac{1}{[4\pi(t - t')]^{3/2}} \exp\left[-\frac{(x' - y')^2 + x_3^2}{4(t - t')}\right]$$

we obtain (6.3) in the form

$$(6.5) \quad u(x, t) = \frac{x_3}{(4\pi)^{3/2}} \int_0^t \frac{dt'}{(t - t')^{5/2}} \int_{\mathbb{R}^2} \exp\left[-\frac{(x' - y')^2 + x_3^2}{4(t - t')}\right] \varphi(y', t') dy'.$$

where $x = (x', x_3)$, $x' = (x_1, x_2)$, $y' = (y_1, y_2)$.

To obtain an estimate we introduce new variables $\tau = t - t'$, $x' - y' = z'$. Hence we get

$$(6.6) \quad u(x, t) = \frac{x_3}{(4\pi)^{3/2}} \int_0^t \frac{d\tau}{\tau^{5/2}} \int_{\mathbb{R}^2} \exp\left[-\frac{z'^2 + x_3^2}{4\tau}\right] \varphi(x' - z', t - \tau) dz'.$$

First we estimate

$$(6.7) \quad \|u(x_3)\|_{L_q(0, T; L_p(\mathbb{R}^2))} \\ \leq \frac{x_3}{(4\pi)^{3/2}} \int_0^\infty \frac{d\tau}{\tau^{5/2}} \int_{\mathbb{R}^2} \exp\left[-\frac{z'^2 + x_3^2}{4\tau}\right] \|\varphi\|_{L_q(0, T; L_p(\mathbb{R}^2))} dz'.$$

Next we calculate

$$(6.8) \quad \left(\int_0^a \|u(x_3)\|_{L_q(0, T; L_p(\mathbb{R}^2))}^p dx_3 \right)^{1/p} \leq c \left(\int_0^a \left| x_3 \int_0^\infty e^{-\frac{x_3^2}{4\tau}} \frac{d\tau}{\tau^{5/2}} \int_{\mathbb{R}^2} e^{-\frac{z'^2}{4\tau}} dz' \right|^p dx_3 \right)^{1/p} \\ \times \|\varphi\|_{L_q(0, T; L_p(\mathbb{R}^2))}.$$

Let us calculate the integral on the r.h.s. of (6.8). Introducing the new variables

$$z'' = \frac{z'}{2\sqrt{\tau}}, \quad dz' = (2\sqrt{\tau})^2 dz'',$$

the integral takes the form

$$\left(\int_0^a \left| x_3 \int_0^\infty e^{-\frac{x_3^2}{4\tau}} \frac{d\tau}{\tau^{5/2}} 4\tau \int_{\mathbb{R}^2} e^{-z''^2} dz'' \right|^p dx_3 \right)^{1/p} \\ \leq c \left(\int_0^a \left| x_3 \int_0^\infty e^{-\frac{x_3^2}{4\tau}} \frac{d\tau}{\tau^{3/2}} \right|^p dx_3 \right)^{1/p} \equiv I_1.$$

Introducing $z = \frac{x_3}{2\sqrt{\tau}}$, $dz = -\frac{x_3}{4\tau^{3/2}} d\tau$ yields

$$I_1 \leq c \left(\int_0^a dx_3 \left| \int_0^\infty e^{-z^2} dz \right|^p \right)^{1/p} \leq c \left(\int_0^a dx_3 \right)^{1/p} \leq ca^{1/p}.$$

Finally, for $a < \infty$ the estimate

$$(6.9) \quad \|u\|_{L_p(0, a; L_q(0, T; L_p(\mathbb{R}^2)))} \leq c \|\varphi\|_{L_q(0, T; L_p(\mathbb{R}^2))}$$

holds.

Let us consider the case of bounded cylindrical domain with the boundary $S = S_1 \cup S_2$. Then solutions to (6.1) are expressed in the form (for more details see [4, Ch. 4, Sect. 16])

$$(6.10) \quad u(x, t) = \int_0^t d\tau \int_S n_i(\xi) \frac{\partial \Gamma(x - \xi, t - \tau)}{\partial \xi_i} \mu(\xi, \tau) dS_\xi,$$

where $\mu(\xi, \tau)$ is a density and $\bar{n} = (n_1, n_2, n_3)$ the unit normal vector to S .

Considering the limit

$$\lim_{x \rightarrow \eta \in S} u(x, t) = \int_0^t d\tau \int_S n_i(\xi) \frac{\partial \Gamma(\eta - \xi, t - \tau)}{\partial \xi_i} \mu(\xi, \tau) dS_\xi \mp \frac{1}{2} \mu(\eta, t)$$

we obtain the integral equation for μ

$$(6.11) \quad \mu(\eta, t) = 2 \int_0^t d\tau \int_S n_i(\xi) \frac{\partial \Gamma(\eta - \xi, t - \tau)}{\partial \xi_i} \mu(\xi, \tau) dS_\xi - 2\varphi(\eta, t)$$

in the case of the interior problem. This is a Volterra type equation with a weakly singular kernel. Hence μ has the same regularity as φ . Applying a partition of unity to the integral over S in (6.10), using estimate (6.9) and the Minkowski inequality (see [2, Ch. 1, Sect. 2])

$$\|u\|_{L_q(0, T; L_p(\mathbb{R}^2 \times (0, a)))} \leq c \|u\|_{L_p(0, a; L_q(0, T; L_p(\mathbb{R}^2)))}$$

which holds for $1 \leq p \leq q \leq \infty$, we get

LEMMA 6.1. *Let $\varphi \in L_q(0, T; L_p(S))$, $1 \leq p \leq q \leq \infty$. Then solutions of (6.1) are such that $u \in L_q(0, T; L_p(\Omega))$ and*

$$(6.12) \quad \|u\|_{L_q(0, T; L_p(\Omega))} \leq c \|\varphi\|_{L_q(0, T; L_p(S))}.$$

Problem (6.1) in the half-space $x_3 > 0$ has the form

$$(6.13) \quad \begin{aligned} u_t - \Delta u &= 0, & x_3 > 0, \\ u &= \varphi, & x_3 = 0, \\ u|_{t=0} &= 0, & x_3 > 0. \end{aligned}$$

To solve (6.13) we apply the Fourier-Laplace transform

$$(6.14) \quad \tilde{u}(\xi, x_3, s) = \int_0^\infty dt e^{-st} \int_{\mathbb{R}^2} e^{-ix' \cdot \xi} u(x, t) dx',$$

where $s = \gamma + i\xi_0$, $\operatorname{Re} s = \gamma > 0$, $x' = (x_1, x_2)$, $\xi = (\xi_1, \xi_2)$, $x' \cdot \xi = x_1 \xi_1 + x_2 \xi_2$. After transformation (6.14) problem (6.13) takes the form

$$(6.15) \quad \begin{aligned} (-\partial_{x_3}^2 + \tau^2) \tilde{u} &= 0, \\ \tilde{u}|_{x_3=0} &= \tilde{\varphi}, \end{aligned}$$

where $\tau^2 = s + |\xi|^2$, $\arg \tau \in (-\frac{\pi}{4}, \frac{\pi}{4})$.

To obtain (6.15) we used problem (6.13) with solution u extended by zero for $t < 0$. Looking for solutions of (6.15) vanishing for $x_3 = \infty$ we obtain

$$(6.16) \quad \tilde{u} = \tilde{\varphi} e^{-\tau x_3}.$$

Let us consider the norm (see [3, 6])

$$\|u\|_{1, \gamma, \mathbb{R}_+^3 \times \mathbb{R}}^2 = \int_{\mathbb{R}^2} d\xi \int_{-\infty}^\infty d\xi_0 \int_{\mathbb{R}_+} dx_3 [\tilde{u}(\xi, x_3, s)]^2 (|\xi|^2 + |s|) + |\partial_{x_3} \tilde{u}(\xi, x_3, s)|^2] \equiv I_1.$$

Using the estimates (see [3, 6])

$$\int_0^\infty |e^{-\tau x_3}|^2 dx_3 \leq c|\tau|^{-1}, \quad \int_0^\infty |\partial_{x_3} e^{-\tau x_3}|^2 dx_3 \leq c|\tau|,$$

we obtain for solutions (6.16) the estimate

$$(6.17) \quad \|u\|_{1,\gamma,\mathbb{R}_+^3 \times \mathbb{R}}^2 \leq c \int_{\mathbb{R}^2} d\xi \int_{\mathbb{R}} d\xi_0 |\tilde{\varphi}|^2 |\tau| = c \|\varphi\|_{1/2,\gamma,\mathbb{R}^2 \times \mathbb{R}}^2.$$

From [3, 6] we know the equivalence

$$c_1 \|u\|_{H^{l,1/2}} \leq \|u\|_{l,\gamma} \leq c_2 \|u\|_{H^{l,1/2}}.$$

Hence (6.17) assumes the form

$$(6.18) \quad \|u\|_{W_2^{1,1/2}(\mathbb{R}_+^3 \times \mathbb{R})} \leq c \|\varphi\|_{W_2^{1/2,1/4}(\mathbb{R}^2 \times \mathbb{R})}.$$

To obtain an estimate of the form (6.18) for solutions of (6.1) we examine (6.10). Let $\{\psi_\alpha(x)\}$ be a partition of unity for Ω and $\{\varphi_\beta(s)\}$, $s \in S$, be a partition of unity for S . Then, from (6.10) we have

$$(6.19) \quad \begin{aligned} \psi_\alpha u &= \psi_\alpha \int_0^t dt \int_S \sum_\beta \varphi_\beta(\xi) n_i(\xi) \frac{\partial \Gamma(x - \xi, t - \tau)}{\partial \xi_i} \mu(\xi, \tau) dS_\xi \\ &= \psi_\alpha \sum_\beta \int_0^t dt \int_{S \cap \text{supp } \varphi_\beta} \varphi_\beta(\xi) n_i(\xi) \frac{\partial \Gamma(x - \xi, t - \tau)}{\partial \xi_i} \mu(\xi, \tau) dS_\xi. \end{aligned}$$

We introduce the local coordinates $\eta = (\eta_1, \eta_2, \eta_3)$ on $S \cap \text{supp } \varphi_\beta$, and transform $S \cap \text{supp } \varphi_\beta$ on the plane $\eta_3 = 0$. Moreover, in $\text{supp } \psi_\alpha$ we introduce a local coordinate system $y = (y_1, y_2, y_3)$ such that $y_3 = 0$ is the plane $\eta_3 = 0$. Then (6.19) takes the form

$$(6.20) \quad u'(y_1, y_2, y_3) = \int_0^t d\tau \int_{\mathbb{R}^2} \frac{\partial \Gamma(y' - \eta', y_3, t - \tau)}{\partial y_3} \mu'(\eta', \tau) d\eta',$$

where μ' and u' have compact supports and $y' = (y_1, y_2)$, $\eta' = (\eta_1, \eta_2)$. Moreover, we have

$$(6.21) \quad \|\mu'\|_{W_2^{1/2,1/4}(\mathbb{R}^2 \times \mathbb{R}_+)} \leq c \|\mu\|_{W_2^{1/2,1/4}(S^T)}.$$

Formula (6.20) describes a solution of the problem

$$(6.22) \quad \begin{aligned} u'_{,t} - \Delta u' &= 0, \\ u'|_{x_3} &= \mu', \quad u'|_{t=0} = 0. \end{aligned}$$

In view of (6.18) we have for the solutions of (6.22) the estimate

$$(6.23) \quad \|u'\|_{L_2(\mathbb{R}_+; H^1(\mathbb{R}^2))} \leq c \|\mu'\|_{W_2^{1/2,1/4}(\mathbb{R}^2 \times \mathbb{R}_+)}.$$

Then for the solutions of the integral equation (6.11) we have

$$(6.24) \quad \|\mu\|_{W_2^{1/2,1/4}(S^T)} \leq c \|\varphi\|_{W_2^{1/2,1/4}(S^T)}.$$

Using (6.23), (6.21) and (6.24) and summing over all subdomains of the introduced partitions of unity we obtain the following estimate for solutions to problem (6.1),

$$(6.25) \quad \|u\|_{L_2(0,T; H^1(\Omega))} \leq c \|\varphi\|_{W_2^{1/2,1/4}(S^T)}.$$

Hence, we have

LEMMA 6.2. Let $\varphi \in W_2^{1/2,1/4}(S^T)$. Then there exists a solution to problem (6.1) such that $u \in L_2(0,T; H^1(\Omega))$ and (6.25) holds.

References

- [1] W. Alame, *On the existence of solutions for the nonstationary Stokes system with slip boundary conditions*, Appl. Math. 32 (2005), 195–223.
- [2] O. V. Besov, V. P. Il'in and S. M. Nikol'skiĭ, *Integral Representations of Functions and Imbedding Theorems*, Nauka, Moscow, 1975 (in Russian).
- [3] M. Burnat and W. M. Zajączkowski, *On local motion of a compressible barotropic viscous fluid with the boundary slip condition*, Topol. Meth. Nonlinear Anal. 10 (1997), 195–223.
- [4] O. A. Ladyzhenskaya, V. A. Solonnikov and N. N. Ural'tseva, *Linear and Quasilinear Equations of Parabolic Type*, Nauka, Moscow, 1967 (in Russian).
- [5] V. G. Maz'ya and B. A. Plamenevskii, *L_p -estimations for solutions of elliptic boundary value problems in domains with edges*, Trudy Mosk. Mat. Obshch. 37 (1978), 49–93 (in Russian).
- [6] V. A. Solonnikov, *An initial boundary value problem for the Stokes system that arises in the study of a problem with a free boundary*, Trudy Mat. Inst. Steklov. 188 (1990), 150–180 (in Russian); English translation: Proc. Steklov Inst. Math. 3 (1991), 191–239.
- [7] W. M. Zajączkowski, *Global special regular solutions to the Navier-Stokes equations in a cylindrical domain under boundary slip conditions*, Gakuto Series in Math. 21 (2004), 1–188.
- [8] W. M. Zajączkowski, *Existence of solutions to the Stokes system in $H_{-\mu-1}^{2,1}(\Omega^T)$, $\mu \in (0, 1)$* , preprint.

