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Semi-formal Stokes phenomenon for non-linear systems of ordinary differential equations

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Nonlinear semi-formal systems

Throughout, let a system $z^{r+1} x' = \check{g}(z, x)$ be given, where the *Poincaré rank* r is a positive integer, $x = (x_1, \dots, x_\nu)^T$ is a vector of dimension $\nu \geq 1$, and

$$\check{g}(z, x) = \sum_{|p| \geq 1} g_p(z) x^p = G(z) x + \sum_{|p| \geq 2} g_p(z) x^p.$$

As usual, $p = (p_1, \dots, p_\nu)$ is a multi-index, $|p| := p_1 + \dots + p_\nu$ denotes the *length* of p , and $x^p := x_1^{p_1} \cdot \dots \cdot x_\nu^{p_\nu}$. We emphasize that we assume (formally) $\check{g}(z, 0) = 0$, so $x(z) \equiv 0$ is a (formal) solution.

While the power series for $\check{g}(z, x)$ may diverge for every $x \neq 0$, we require the coefficients $g_p(z)$ to be holomorphic functions in a fixed disc $\mathcal{D}_\rho$ of radius $\rho > 0$ about the origin.

Normalizations

Assumptions: The corresponding linear system $z^{r+1}x' = G(z)x$ has a formal fundamental solution $\hat{X}(z) = \hat{F}(z)z^L e^{Q(z)}$, where

- $\hat{F}(z)$ is a formal matrix power series whose constant term is the identity matrix.
- $Q(z) = \text{diag} [q_1(z), \dots, q_\nu(z)]$ is a diagonal matrix of, not necessarily distinct, polynomials in the variable $w := z^{-1}$ without constant terms.
- $L = \Lambda + N$, with a diagonal matrix $\Lambda = \text{diag} [\lambda_1, \dots, \lambda_\nu]$ and a nilpotent matrix N that commutes with both Λ and $Q(z)$.

The formal series $\hat{F}(z)$ is known to be multi-summable in every non-singular multi-direction $d = (d_1, \dots, d_r)$. Its corresponding sum shall be denoted as $F(z; d)$, and we set

$$X(z; d) := F(z; d) z^L e^{Q(z)}.$$

Semi-formal solutions

Every system of the form considered here has a semi-formal solution of the form

$$\check{x}(z, c) = \sum_{|p| \geq 1} x_p(z) c^p = X(z) c + \sum_{|p| \geq 2} x_p(z) c^p,$$

where $X(z)$ is a fundamental solution of the corresponding linear system, and for every multi-index $p \neq 0$

$$z^{r+1} x'_p(z) = G(z) x_p(z) + \sum_{2 \leq |q| \leq |p|} x_{qp}(z) g_q(z),$$

with $x_{qp}(z)$ depending upon coefficients $x_q(z)$ with $|q| < |p|$ only.

Every other semi-formal solution is of the form $\check{x}(z, v(c))$, with suitable

$$v(c) = \sum_{|p| \geq 1} v_p c^p = V c + \sum_{|p| \geq 2} v_p c^p.$$

Semi-formal normal solutions

Set

$$q(z, p) = \sum_{j=1}^{\nu} p_j q_j(z) , \quad \lambda(p) = r + \sum_{j=1}^{\nu} p_j (\lambda_j - r) .$$

Theorem 1. *For every non-singular multi-direction d there exists a unique semi-formal solution*

$$\check{x}(z, c; d) = \sum_{|p| \geq 1} x_p(z; d) c^p$$

whose linear part is the normal solution $X(z; d)$ of the corresponding linear equation. The coefficients $x_p(z; d)$ all are logarithmic-exponential expressions of type $(q(z, p), \lambda(p))$ which are recursively obtained by means of the identity

$$x_p(z; d) = X(z; d) \int X^{-1}(z; d) \left[\sum_{2 \leq |q| \leq |p|} x_{qp}(z; d) g_q(z) \right] \frac{dz}{z^{r+1}} .$$

Stokes functions

Given two non-singular multi-directions d and $\tilde{d}$, there exists a unique formal expression $\check{v}(c; \tilde{d}, d) = \sum_p v_p(\tilde{d}, d) c^p$ for which

$$\check{x}(z, c; d) = \check{x}(z, \check{v}(c; \tilde{d}, d); \tilde{d}).$$

This $\check{v}(c; \tilde{d}, d)$ will be referred to as the (formal) *Stokes function* corresponding to d and $\tilde{d}$.

Theorem 2. *For any normalized system, all Stokes functions are invertible with respect to formal composition, and for any three non-singular multi-directions $d, \tilde{d}, \hat{d}$ we have $v(c; d, d) = c$, i. e. is the identity element of $\mathbb{G}(c)$, while $\check{v}(c; \tilde{d}, d)$ and $\check{v}(c; d, \tilde{d})$ are inverse to one another. Moreover,*

$$\check{v}(c; \hat{d}, d) = \check{v}(\check{v}(c; \tilde{d}, d); \hat{d}, \tilde{d}).$$

Altogether, this shows that the the Stokes functions form a subgroup of the group $\mathbb{G}(c)$.

This talk is based on a manuscript that may be downloaded via my homepage. Also compare the following

References

- [1] Werner Balser. Formal solutions of non-linear systems of ordinary differential equations. In *The Stokes phenomenon and Hilbert's 16th problem (Groningen, 1995)*, pages 25–49. World Sci. Publ., River Edge, NJ, 1996.
- [2] Werner Balser. Existence and structure of complete formal solutions of non-linear meromorphic systems of ordinary differential equations. *Asymptot. Anal.*, 15(3–4):261–282, 1997.