

# On irregular modified $A$ -hypergeometric systems and Borel summation method

Tatsuya KOIKE

Kobe Univ.

Formal and Analytic Solutions of Differential, Difference and Discrete Equations  
at Będlewo  
August 29, 2013

- This is a joint work with Francisco-Jesús Castro-Jiménez, María-Cruz Fernández-Fernández and Nobuki Takayama.
- To appear in Transactions of AMS. (arXiv:1207.1533).

## A-hypergeometric systems (GKZ systems)

- $A = (a_{ij}) = (a_1, a_2, \dots, a_n) \in M(d \times n, \mathbb{Z}), \quad a_i \in \mathbb{Z}^d.$

## A-hypergeometric systems (GKZ systems)

- $A = (a_{ij}) = (a_1, a_2, \dots, a_n) \in M(d \times n, \mathbb{Z}), \quad a_i \in \mathbb{Z}^d.$
- We assume  $\mathbb{Z}a_1 + \dots + \mathbb{Z}a_n = \mathbb{Z}^d.$

## A-hypergeometric systems (GKZ systems)

- $A = (a_{ij}) = (a_1, a_2, \dots, a_n) \in M(d \times n, \mathbb{Z})$ ,  $a_i \in \mathbb{Z}^d$ .
- We assume  $\mathbb{Z}a_1 + \dots + \mathbb{Z}a_n = \mathbb{Z}^d$ .
- $\beta = (\beta_i) \in \mathbb{C}^d$ : complex parameters.

## A-hypergeometric systems (GKZ systems)

- $A = (a_{ij}) = (a_1, a_2, \dots, a_n) \in M(d \times n, \mathbb{Z})$ ,  $a_i \in \mathbb{Z}^d$ .
- We assume  $\mathbb{Z}a_1 + \dots + \mathbb{Z}a_n = \mathbb{Z}^d$ .
- $\beta = (\beta_i) \in \mathbb{C}^d$ : complex parameters.
- Then the A-hypergeometric system is

$$H_A(\beta) : \begin{cases} \left( \sum_{j=1}^n a_{ij} x_j \partial_j - \beta_i \right) \cdot \phi = 0 & (i = 1, 2, \dots, d), \\ \left( \prod_{i=1}^n \partial_i^{u_i} - \prod_{i=1}^n \partial_i^{v_i} \right) \cdot \phi = 0 \end{cases}$$

( $\forall u, v \in \mathbb{N}_0^n$  with  $Au = Av$ .)

## A-hypergeometric systems (GKZ systems)

- $A = (a_{ij}) = (a_1, a_2, \dots, a_n) \in M(d \times n, \mathbb{Z})$ ,  $a_i \in \mathbb{Z}^d$ .
- We assume  $\mathbb{Z}a_1 + \dots + \mathbb{Z}a_n = \mathbb{Z}^d$ .
- $\beta = (\beta_i) \in \mathbb{C}^d$ : complex parameters.
- Then the A-hypergeometric system is

$$H_A(\beta) : \begin{cases} \left( \sum_{j=1}^n a_{ij} x_j \partial_j - \beta_i \right) \cdot \phi = 0 & (i = 1, 2, \dots, d), \\ \left( \prod_{i=1}^n \partial_i^{u_i} - \prod_{i=1}^n \partial_i^{v_i} \right) \cdot \phi = 0 \end{cases}$$

( $\forall u, v \in \mathbb{N}_0^n$  with  $Au = Av$ .)

- We denote by  $M_A(\beta)$  the corresponding left  $D_n$ -module. It is known that  $M_A(\beta)$  is holonomic.

$$H_A(\beta) : (A \cdot \theta - \beta) \cdot \phi = 0, \quad (\partial^u - \partial^v) \cdot \phi = 0$$
$$(\forall u, v \in \mathbb{N}_0^n \text{ with } Au = Av.)$$



$$H_A(\beta) : (A \cdot \theta - \beta) \cdot \phi = 0, \quad (\partial^u - \partial^v) \cdot \phi = 0$$
$$(\forall u, v \in \mathbb{N}_0^n \text{ with } Au = Av.)$$

- Gelfand, Zelvinski and Kapranov introduced this system (1989).

$$H_A(\beta) : (A \cdot \theta - \beta) \cdot \phi = 0, \quad (\partial^u - \partial^v) \cdot \phi = 0$$

$$(\forall u, v \in \mathbb{N}_0^n \text{ with } Au = Av.)$$

■ Gelfand, Zelvinski and Kapranov introduced this system (1989).

■  $\phi(x) = \sum_{k \in \text{Ker}_{\mathbb{Z}} A} \frac{x^{k+\gamma}}{\Gamma(k + \gamma + 1)}$  is a formal solution, where

$$A\gamma = \beta, \quad \text{Ker}_{\mathbb{Z}} A = \{k \in \mathbb{Z}^n; Ak = 0\}.$$

$$H_A(\beta) : (A \cdot \theta - \beta) \cdot \phi = 0, \quad (\partial^u - \partial^v) \cdot \phi = 0$$

$$(\forall u, v \in \mathbb{N}_0^n \text{ with } Au = Av.)$$

■ Gelfand, Zelvinski and Kapranov introduced this system (1989).

■  $\phi(x) = \sum_{k \in \text{Ker}_{\mathbb{Z}} A} \frac{x^{k+\gamma}}{\Gamma(k + \gamma + 1)}$  is a formal solution, where

$$A\gamma = \beta, \quad \text{Ker}_{\mathbb{Z}} A = \{k \in \mathbb{Z}^n; Ak = 0\}.$$

■ They assumed  $\exists c \in \mathbb{Z}^d$  s.t.  $c \cdot A = (1, \dots, 1)$ .

$$H_A(\beta) : (A \cdot \theta - \beta) \cdot \phi = 0, \quad (\partial^u - \partial^v) \cdot \phi = 0$$

$$(\forall u, v \in \mathbb{N}_0^n \text{ with } Au = Av.)$$

- Gelfand, Zelvinski and Kapranov introduced this system (1989).

- $\phi(x) = \sum_{k \in \text{Ker}_{\mathbb{Z}} A} \frac{x^{k+\gamma}}{\Gamma(k+\gamma+1)}$  is a formal solution, where

$$A\gamma = \beta, \quad \text{Ker}_{\mathbb{Z}} A = \{k \in \mathbb{Z}^n; Ak = 0\}.$$

- They assumed  $\exists c \in \mathbb{Z}^d$  s.t.  $c \cdot A = (1, \dots, 1)$ .
- It is known that  $M_A(\beta)$  is regular holonomic (Hotta, 1998) if

$$\exists q \in \mathbb{Q}^d \quad \text{such that} \quad q \cdot A = (1, \dots, 1).$$

$$H_A(\beta) : (A \cdot \theta - \beta) \cdot \phi = 0, \quad (\partial^u - \partial^v) \cdot \phi = 0$$
$$(\forall u, v \in \mathbb{N}_0^n \text{ with } Au = Av.)$$

- Adolphson studied the irregular case (1994).

$$H_A(\beta) : (A \cdot \theta - \beta) \cdot \phi = 0, \quad (\partial^u - \partial^v) \cdot \phi = 0$$
$$(\forall u, v \in \mathbb{N}_0^n \text{ with } Au = Av.)$$

- Adolphson studied the irregular case (1994).
- Combinatric description of slopes along a coordinate space:
  - Castro-Takayama (2003), Hartillo(2003) when  $d = 1$  or  $n = d + 1$ .
  - Schulze-Walther (2008)

$$H_A(\beta) : (A \cdot \theta - \beta) \cdot \phi = 0, \quad (\partial^u - \partial^v) \cdot \phi = 0$$

$$(\forall u, v \in \mathbb{N}_0^n \text{ with } Au = Av.)$$

- Adolphson studied the irregular case (1994).
- Combinatric description of slopes along a coordinate space:
  - Castro-Takayama (2003), Hartillo(2003) when  $d = 1$  or  $n = d + 1$ .
  - Schulze-Walther (2008)
- Study of Gevrey series solutions along a coordinate space:
  - Castro-Fernández (2011) when  $d = 1$ .
  - Fernández (2010).

We consider the irregular  $A$ -hypergeometric system and study the asymptotic properties of

$$\phi(t^{w_1}x_1, \dots, t^{w_n}x_n)$$

as  $t \rightarrow 0$  with an appropriate  $w = (w_1, \dots, w_n) \in \mathbb{Z}$ .



We consider the irregular  $A$ -hypergeometric system and study the asymptotic properties of

$$\phi(t^{w_1}x_1, \dots, t^{w_n}x_n)$$

as  $t \rightarrow 0$  with an appropriate  $w = (w_1, \dots, w_n) \in \mathbb{Z}$ .

- $f(t, x_1, \dots, x_n) = \phi(t^{w_1}x_1, \dots, t^{w_n}x_n)$  satisfies the modified  $A$ -hypergeometric system introduced by Takayama (2009).

We consider the irregular  $A$ -hypergeometric system and study the asymptotic properties of

$$\phi(t^{w_1}x_1, \dots, t^{w_n}x_n)$$

as  $t \rightarrow 0$  with an appropriate  $w = (w_1, \dots, w_n) \in \mathbb{Z}$ .

- $f(t, x_1, \dots, x_n) = \phi(t^{w_1}x_1, \dots, t^{w_n}x_n)$  satisfies the modified  $A$ -hypergeometric system introduced by Takayama (2009).
- We study the Gevrey series solutions of the modified  $A$ -hypergeometric systems.

We consider the irregular  $A$ -hypergeometric system and study the asymptotic properties of

$$\phi(t^{w_1}x_1, \dots, t^{w_n}x_n)$$

as  $t \rightarrow 0$  with an appropriate  $w = (w_1, \dots, w_n) \in \mathbb{Z}$ .

- $f(t, x_1, \dots, x_n) = \phi(t^{w_1}x_1, \dots, t^{w_n}x_n)$  satisfies the modified  $A$ -hypergeometric system introduced by Takayama (2009).
- We study the Gevrey series solutions of the modified  $A$ -hypergeometric systems.
- Under some condition, Gevrey series solutions of the modified  $A$ -hypergeometric systems is Borel summable (1-summable).

An example:  $A = (1, 2)$ ,  $\beta$ : generic

$$H_A(\beta) : \quad (\theta_1 + 2\theta_2 - \beta) \cdot \phi = 0, \quad (\partial_1^2 - \partial_2) \cdot \phi = 0,$$

## An example: $A = (1, 2)$ , $\beta$ : generic

$$H_A(\beta) : \quad (\theta_1 + 2\theta_2 - \beta) \cdot \phi = 0, \quad (\partial_1^2 - \partial_2) \cdot \phi = 0,$$

1. A formal solution: 
$$\phi(x_1, x_2) = \sum_{m=0}^{\infty} \frac{[\beta]_{2m}}{m!} x_1^{\beta-2m} x_2^m,$$
$$[\beta]_{2m} = \beta(\beta - 1) \cdots (\beta - 2m + 1).$$

## An example: $A = (1, 2)$ , $\beta$ : generic

$$H_A(\beta) : \quad (\theta_1 + 2\theta_2 - \beta) \cdot \phi = 0, \quad (\partial_1^2 - \partial_2) \cdot \phi = 0,$$

1. A formal solution:  $\phi(x_1, x_2) = \sum_{m=0}^{\infty} \frac{[\beta]_{2m}}{m!} x_1^{\beta-2m} x_2^m$ ,  
 $[\beta]_{2m} = \beta(\beta - 1) \cdots (\beta - 2m + 1)$ .
2. For a weight vector  $w = (0, 1)$ ,

$$f(x_1, x_2, t) = \phi(x_1, t \cdot x_2) = \sum_{m=0}^{\infty} \frac{[\beta]_{2m}}{m!} x_1^{\beta-2m} x_2^m t^m.$$

## An example: $A = (1, 2)$ , $\beta$ : generic

$$H_A(\beta): \quad (\theta_1 + 2\theta_2 - \beta) \cdot \phi = 0, \quad (\partial_1^2 - \partial_2) \cdot \phi = 0,$$

1. A formal solution:  $\phi(x_1, x_2) = \sum_{m=0}^{\infty} \frac{[\beta]_{2m}}{m!} x_1^{\beta-2m} x_2^m,$

$$[\beta]_{2m} = \beta(\beta - 1) \cdots (\beta - 2m + 1).$$

2. For a weight vector  $w = (0, 1)$ ,

$$f(x_1, x_2, t) = \phi(x_1, t \cdot x_2) = \sum_{m=0}^{\infty} \frac{[\beta]_{2m}}{m!} x_1^{\beta-2m} x_2^m t^m.$$

3. Its Borel transform is

$$\begin{aligned} f_B(x_1, x_2, \tau) &= \sum_{m=0}^{\infty} \frac{[\beta]_{2m}}{m!} x_1^{\beta-2m} x_2^m \frac{\tau^m}{m!} \\ &= x_1^\beta \cdot {}_2F_1\left(-\frac{\beta}{2}, \frac{1-\beta}{2}, 1; \frac{4x_2}{x_1^2} \tau\right) \end{aligned}$$

So starting from

$$f(x_1, x_2, t) = \phi(x_1, t \cdot x_2) = \sum_{m=0}^{\infty} \frac{[\beta]_{2m}}{m!} x_1^{\beta-2m} x_2^m t^m,$$

we obtain

$$F(x_1, x_2, t) := \int_0^{\infty} e^{-\tau/t} \left[ x_1^{\beta} \cdot {}_2F_1\left(-\frac{\beta}{2}, \frac{1-\beta}{2}, 1; \frac{4x_2}{x_1^2}\tau\right) \right] \frac{d\tau}{t}.$$



So starting from

$$f(x_1, x_2, t) = \phi(x_1, t \cdot x_2) = \sum_{m=0}^{\infty} \frac{[\beta]_{2m}}{m!} x_1^{\beta-2m} x_2^m t^m,$$

we obtain

$$F(x_1, x_2, t) := \int_0^{\infty} e^{-\tau/t} \left[ x_1^{\beta} \cdot {}_2F_1\left(-\frac{\beta}{2}, \frac{1-\beta}{2}, 1; \frac{4x_2}{x_1^2}\tau\right) \right] \frac{d\tau}{t}.$$

- $f(x_1, x_2, t)$  is 1-summable and the singular direction is  $\arg \tau = 2 \arg x_1 - \arg x_2$ .

So starting from

$$f(x_1, x_2, t) = \phi(x_1, t \cdot x_2) = \sum_{m=0}^{\infty} \frac{[\beta]_{2m}}{m!} x_1^{\beta-2m} x_2^m t^m,$$

we obtain

$$F(x_1, x_2, t) := \int_0^{\infty} e^{-\tau/t} \left[ x_1^{\beta} \cdot {}_2F_1\left(-\frac{\beta}{2}, \frac{1-\beta}{2}, 1; \frac{4x_2}{x_1^2} \tau\right) \right] \frac{d\tau}{t}.$$

- $f(x_1, x_2, t)$  is 1-summable and the singular direction is  $\arg \tau = 2 \arg x_1 - \arg x_2$ .
- $F(x_1, x_2, t) \sim f(x_1, x_2, t)$  as  $S(0, \pi + \varepsilon) \ni t \rightarrow 0$ .

So starting from

$$f(x_1, x_2, t) = \phi(x_1, t \cdot x_2) = \sum_{m=0}^{\infty} \frac{[\beta]_{2m}}{m!} x_1^{\beta-2m} x_2^m t^m,$$

we obtain

$$F(x_1, x_2, t) := \int_0^{\infty} e^{-\tau/t} \left[ x_1^{\beta} \cdot {}_2F_1\left(-\frac{\beta}{2}, \frac{1-\beta}{2}, 1; \frac{4x_2}{x_1^2}\tau\right) \right] \frac{d\tau}{t}.$$

- $f(x_1, x_2, t)$  is 1-summable and the singular direction is  $\arg \tau = 2 \arg x_1 - \arg x_2$ .
- $F(x_1, x_2, t) \sim f(x_1, x_2, t)$  as  $S(0, \pi + \varepsilon) \ni t \rightarrow 0$ .
- $\Phi(x_1, x_2) = F(x_1, x_2, 1)$  is a solution of  $H_A(\beta)$  and

$$\Phi(x_1, t \cdot x_2) \sim \phi(x_1, t \cdot x_2) \quad \text{as} \quad S(0, \pi + \varepsilon) \ni t \rightarrow 0.$$

(Note:  $F(x_1, x_2, t) = \Phi(x_1, t \cdot x_2)$ .)

## An example: $A = (1, 2)$ , $\beta$ : generic

$$H_A(\beta) : \quad (\theta_1 + 2\theta_2 - \beta) \cdot \phi = 0, \quad (\partial_1^2 - \partial_2) \cdot \phi = 0,$$

1. A formal solution:  $\phi(x_1, x_2) = \sum_{m=0}^{\infty} \frac{[\beta]_{2m}}{m!} x_1^{\beta-2m} x_2^m,$   
 $[\beta]_{2m} = \beta(\beta - 1) \cdots (\beta - 2m + 1).$

2. For a weight vector  $w = (0, 1)$ ,

$$f(x_1, x_2, t) = \phi(x_1, t \cdot x_2) = \sum_{m=0}^{\infty} \frac{[\beta]_{2m}}{m!} x_1^{\beta-2m} x_2^m t^m$$

3. Its Borel transform is

$$\begin{aligned} f_B(x_1, x_2, \tau) &= \sum_{m=0}^{\infty} \frac{[\beta]_{2m}}{m!} x_1^{\beta-2m} x_2^m \cdot \frac{\tau^m}{m!} \\ &= x_1^\beta \cdot {}_2F_1\left(-\frac{\beta}{2}, \frac{1-\beta}{2}, 1; \frac{4x_2}{x_1^2} \tau\right) \end{aligned}$$

## An example: $A = (1, 2)$ , $\beta$ : generic

$$H_A(\beta) : \quad (\theta_1 + 2\theta_2 - \beta) \cdot \phi = 0, \quad (\partial_1^2 - \partial_2) \cdot \phi = 0,$$

1. A formal solution:  $\phi(x_1, x_2) = \sum_{m=0}^{\infty} \frac{[\beta]_{2m}}{m!} x_1^{\beta-2m} x_2^m$ , Construction
- $$[\beta]_{2m} = \beta(\beta - 1) \cdots (\beta - 2m + 1).$$

2. For a weight vector  $w = (0, 1)$ ,

$$f(x_1, x_2, t) = \phi(x_1, t \cdot x_2) = \sum_{m=0}^{\infty} \frac{[\beta]_{2m}}{m!} x_1^{\beta-2m} x_2^m t^m$$

3. Its Borel transform is

$$\begin{aligned} f_B(x_1, x_2, \tau) &= \sum_{m=0}^{\infty} \frac{[\beta]_{2m}}{m!} x_1^{\beta-2m} x_2^m \cdot \frac{\tau^m}{m!} \\ &= x_1^\beta \cdot {}_2F_1\left(-\frac{\beta}{2}, \frac{1-\beta}{2}, 1; \frac{4x_2}{x_1^2} \tau\right) \end{aligned}$$

## An example: $A = (1, 2)$ , $\beta$ : generic

$$H_A(\beta) : \quad (\theta_1 + 2\theta_2 - \beta) \cdot \phi = 0, \quad (\partial_1^2 - \partial_2) \cdot \phi = 0,$$

1. A formal solution:  $\phi(x_1, x_2) = \sum_{m=0}^{\infty} \frac{[\beta]_{2m}}{m!} x_1^{\beta-2m} x_2^m$ , **Construction**  
 $[\beta]_{2m} = \beta(\beta - 1) \cdots (\beta - 2m + 1).$

2. For a weight vector  $w = (0, 1)$ , **Choice of  $w$**

$$f(x_1, x_2, t) = \phi(x_1, t \cdot x_2) = \sum_{m=0}^{\infty} \frac{[\beta]_{2m}}{m!} x_1^{\beta-2m} x_2^m t^m$$

3. Its Borel transform is

$$\begin{aligned} f_B(x_1, x_2, \tau) &= \sum_{m=0}^{\infty} \frac{[\beta]_{2m}}{m!} x_1^{\beta-2m} x_2^m \cdot \frac{\tau^m}{m!} \\ &= x_1^\beta \cdot {}_2F_1\left(-\frac{\beta}{2}, \frac{1-\beta}{2}, 1; \frac{4x_2}{x_1^2} \tau\right) \end{aligned}$$

## An example: $A = (1, 2)$ , $\beta$ : generic

$$H_A(\beta) : \quad (\theta_1 + 2\theta_2 - \beta) \cdot \phi = 0, \quad (\partial_1^2 - \partial_2) \cdot \phi = 0,$$

1. A formal solution:  $\phi(x_1, x_2) = \sum_{m=0}^{\infty} \frac{[\beta]_{2m}}{m!} x_1^{\beta-2m} x_2^m$ , **Construction**
- $$[\beta]_{2m} = \beta(\beta - 1) \cdots (\beta - 2m + 1).$$

2. For a weight vector  $w = (0, 1)$ , **Choice of  $w$**

$$f(x_1, x_2, t) = \phi(x_1, t \cdot x_2) = \sum_{m=0}^{\infty} \frac{[\beta]_{2m}}{m!} x_1^{\beta-2m} x_2^m t^m$$

3. Its Borel transform is **Gevrey order**

$$\begin{aligned} f_B(x_1, x_2, \tau) &= \sum_{m=0}^{\infty} \frac{[\beta]_{2m}}{m!} x_1^{\beta-2m} x_2^m \cdot \frac{\tau^m}{m!} \\ &= x_1^\beta \cdot {}_2F_1\left(-\frac{\beta}{2}, \frac{1-\beta}{2}, 1; \frac{4x_2}{x_1^2} \tau\right) \end{aligned}$$

## An example: $A = (1, 2)$ , $\beta$ : generic

$$H_A(\beta): \quad (\theta_1 + 2\theta_2 - \beta) \cdot \phi = 0, \quad (\partial_1^2 - \partial_2) \cdot \phi = 0,$$

1. A formal solution:  $\phi(x_1, x_2) = \sum_{m=0}^{\infty} \frac{[\beta]_{2m}}{m!} x_1^{\beta-2m} x_2^m$ , **Construction**
- $$[\beta]_{2m} = \beta(\beta - 1) \cdots (\beta - 2m + 1).$$

2. For a weight vector  $w = (0, 1)$ , **Choice of  $w$**

$$f(x_1, x_2, t) = \phi(x_1, t \cdot x_2) = \sum_{m=0}^{\infty} \frac{[\beta]_{2m}}{m!} x_1^{\beta-2m} x_2^m t^m$$

3. Its Borel transform is **Gevrey order**

$$f_B(x_1, x_2, \tau) = \sum_{m=0}^{\infty} \frac{[\beta]_{2m}}{m!} x_1^{\beta-2m} x_2^m \cdot \frac{\tau^m}{m!}$$

**Analytic continuation**

$$= x_1^\beta \cdot {}_2F_1\left(-\frac{\beta}{2}, \frac{1-\beta}{2}, 1; \frac{4x_2}{x_1^2} \tau\right)$$



## Modified $A$ -hypergeometric systems (Takayama, 2009)

$f(x_1, \dots, x_n, t) = \phi(t^{w_1}x_1, \dots, t^{w_n}x_n)$  ( $w = (w_1, \dots, w_n) \in \mathbb{Z}^n$ ) solves

$$H_{A,w}(\beta) : \left\{ \begin{array}{l} \left( \sum_{j=1}^n a_{ij}x_j\partial_j - \beta_i \right) \cdot f = 0 \quad (1 \leq i \leq d), \\ \left( \sum_{j=1}^n w_jx_j\partial_j - t\partial_t \right) \cdot f = 0, \\ \left( t^{u_{n+1}} \prod_{i=1}^n \partial_i^{u_i} - t^{v_{n+1}} \prod_{i=1}^n \partial_i^{v_i} \right) \cdot f = 0 \\ \text{for } \forall u, v \in \mathbb{N}_0^{n+1} \text{ such that } \tilde{A}u = \tilde{A}v. \end{array} \right.$$

Here

$$\tilde{A} = \begin{pmatrix} A & 0 \\ w & 1 \end{pmatrix} = \begin{pmatrix} a_1 & a_2 & \cdots & a_n & 0 \\ w_1 & w_2 & \cdots & w_n & 1 \end{pmatrix}.$$

## Formal solutions of $M_{A,w}(\beta)$

- $T = \{t = 0\} \subset \mathbb{C}_x^n \times \mathbb{C}_t$
- $\mathcal{O}_{\widehat{X|T}}$ : the sheaf of formal series along  $T$ .

### Theorem

Assume  $\beta \in \mathbb{C}^d$  is very generic and  $w \in \mathbb{Z}^n$ . Then

$$\dim_{\mathbb{C}} \left[ \text{Sol}(M_{A,w}(\beta), \sum_{b(\gamma)=0} t^\gamma \mathcal{O}_{\widehat{X|T}})_{(p,0)} \right] = \deg(\text{In}_w(I_A)).$$

Here

- $b(\gamma)$  is the indicial polynomial of  $H_{A,w}(\beta)$  along  $T$ .
- $I_A = \langle \partial^u - \partial^v; u, v \in \mathbb{N}_0^n \text{ with } Au = Av \rangle \subset \mathbb{C}[\partial]$  is the toric ideal and  $\text{in}_w(I_A)$  is the initial ideal of  $I_A$  with respect to  $w$ .

## Slopes of $M_{A,w}(\beta)$

Slopes for  $D$ -module (Laurent (1987)).

- We consider a filtration  $L_r = F + rV$  ( $r \geq 0$ ) of  $D_{n+1}$ -module, where  $F = (0, \dots, 0; 1, \dots, 1)$ ,  $V = (0, \dots, 0, -1; 0, \dots, 0, 1)$ .
- If  $\text{Ch}^{L_r}(M_{A,w}(\beta))$  “changes” at  $r = r_0$ , we call  $s = r_0 + 1$  a slope.

## Slopes of $M_{A,w}(\beta)$

### Slopes for $D$ -module (Laurent (1987)).

- We consider a filtration  $L_r = F + rV$  ( $r \geq 0$ ) of  $D_{n+1}$ -module, where  $F = (0, \dots, 0; 1, \dots, 1)$ ,  $V = (0, \dots, 0, -1; 0, \dots, 0, 1)$ .
- If  $\text{Ch}^{L_r}(M_{A,w}(\beta))$  “changes” at  $r = r_0$ , we call  $s = r_0 + 1$  a slope.

### Schulze-Walther (2008)

- They gave a description of  $\text{Ch}^{L_r}(M_A(\beta))$  by  $(A, L_r)$ -umbrella. Slopes for  $M_A(\beta)$  was also studied.

## Slopes of $M_{A,w}(\beta)$

Slopes for  $D$ -module (Laurent (1987)).

- We consider a filtration  $L_r = F + rV$  ( $r \geq 0$ ) of  $D_{n+1}$ -module, where  $F = (0, \dots, 0; 1, \dots, 1)$ ,  $V = (0, \dots, 0, -1; 0, \dots, 0, 1)$ .
- If  $\text{Ch}^{L_r}(M_{A,w}(\beta))$  “changes” at  $r = r_0$ , we call  $s = r_0 + 1$  a slope.

Schulze-Walther (2008)

- They gave a description of  $\text{Ch}^{L_r}(M_A(\beta))$  by  $(A, L_r)$ -umbrella. Slopes for  $M_A(\beta)$  was also studied.

By Fourier transformation w.r.t.  $t$  ( $t \mapsto -\partial_t$ ,  $\partial_t \mapsto t$ ),

$$\blacksquare M_{A,w}(\beta) \begin{array}{c} \xrightarrow{\mathcal{F}} \\ \xleftarrow{\mathcal{F}^{-1}} \end{array} M_{\tilde{A}}(\tilde{\beta}) \quad \text{with} \quad \tilde{\beta} = (\beta, -1)$$

$$\blacksquare \text{Ch}^{L_r}(M_{A,w}(\beta)) = \mathcal{F}^{-1} \left( \text{Ch}^{\tilde{L}_r}(M_{\tilde{A}}(\tilde{\beta})) \right), \text{ where } \tilde{L}_r = \mathcal{F}L_r$$

## Definition of $(\tilde{A}, \tilde{L}_r)$ -umbrella

We assume

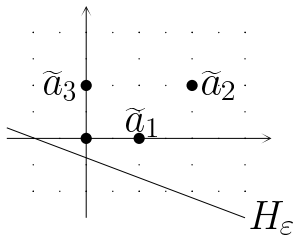
$$\tilde{A} = (\tilde{a}_1, \dots, \tilde{a}_{n+1})$$

is pointed, i.e., there exists  $h \in \text{Hom}_{\mathbb{Q}}(\mathbb{Q}^n, \mathbb{Q})$  such that  $h(\tilde{a}_i) > 0$ .  
Following Schulze-Walther, we define

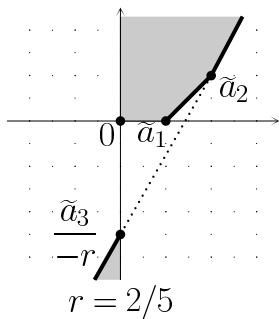
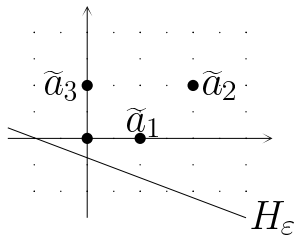
### Definition

- (i) The  $(\tilde{A}, \tilde{L}_r)$ -polyhedron is  $\Delta_{\tilde{A}}^{\tilde{L}_r} = \text{conv}_{H_\varepsilon} \left( \left\{ \mathbf{0}, \tilde{a}_1, \dots, \tilde{a}_n, \frac{\tilde{a}_{n+1}}{-r} \right\} \right)$  in  $\mathbb{P}_{\mathbb{R}}^{d+1}$ , where  $\varepsilon$  is sufficiently small and  $H_\varepsilon = h^{-1}(-\varepsilon)$ .
- (ii) The  $(\tilde{A}, \tilde{L}_r)$ -umbrella  $\Phi^{\tilde{L}_r}$  is the set of faces of  $\Delta_{\tilde{A}}^{\tilde{L}_r}$  which do not contain the origin.

Let  $A = (1, 2)$  and  $w = (0, 1)$ . Then  $\tilde{A} = \begin{pmatrix} 1 & 2 & 0 \\ 0 & 1 & 1 \end{pmatrix} = (\tilde{a}_1, \tilde{a}_2, \tilde{a}_3)$ .

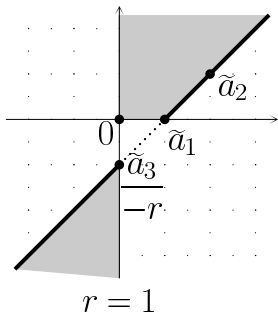
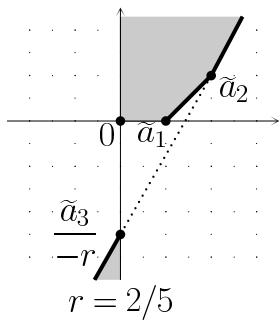
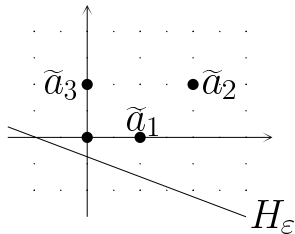


Let  $A = (1, 2)$  and  $w = (0, 1)$ . Then  $\tilde{A} = \begin{pmatrix} 1 & 2 & 0 \\ 0 & 1 & 1 \end{pmatrix} = (\tilde{a}_1, \tilde{a}_2, \tilde{a}_3)$ .

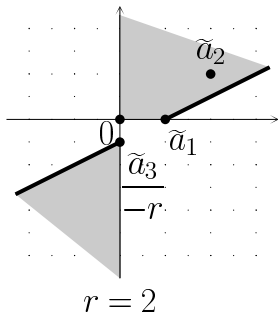
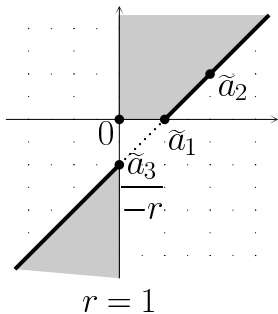
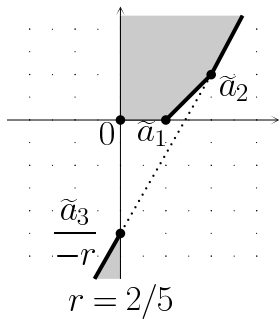
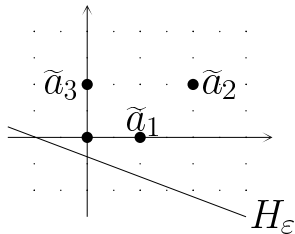




Let  $A = (1, 2)$  and  $w = (0, 1)$ . Then  $\tilde{A} = \begin{pmatrix} 1 & 2 & 0 \\ 0 & 1 & 1 \end{pmatrix} = (\tilde{a}_1, \tilde{a}_2, \tilde{a}_3)$ .



Let  $A = (1, 2)$  and  $w = (0, 1)$ . Then  $\tilde{A} = \begin{pmatrix} 1 & 2 & 0 \\ 0 & 1 & 1 \end{pmatrix} = (\tilde{a}_1, \tilde{a}_2, \tilde{a}_3)$ .



## Gevrey series solutions

For the modified  $A$ -hypergeometric systems with very generic  $\beta$ , we can construct a Gevrey series solution

$$f(x, t) = \sum_{m=0}^{\infty} f_m(x) t^{\gamma+m}$$

along  $T = \{t = 0\}$ , where

- $f_m(x)$  is a holomorphic solution near  $p$  with  $(p, 0) \in T$ ,
- $\gamma$  is a root of the indicial polynomial  $b(\gamma)$  of  $H_{A,w}(\beta)$  along  $T$ ,
- the Gevrey order of it is  $s = r + 1$  with

$$r = \max \left\{ -\frac{|b_i|}{w \cdot b_i}; i \notin \sigma, w \cdot b_i > 0 \right\}.$$

Here  $\sigma$  is chosen so that  $(a_i)_{i \in \sigma}$  is a basis of  $\mathbb{R}^d$ , and  $\{b_i\}_{i \notin \sigma}$  is a basis of the kernel of  $A$  such that

$$(b_i)_j = 0 \quad \text{for all } j \notin \sigma \cup \{i\}, \quad (b_i)_i = 1.$$

- In the following we assume that the row span of the matrix

$$A_w = \begin{pmatrix} a_1 & \cdots & a_n \\ w_1 & \cdots & w_n \end{pmatrix}$$

contains  $(1, \dots, 1)$ .

## Borel sum of a formal solution

- In the following we assume that the row span of the matrix

$$A_w = \begin{pmatrix} a_1 & \cdots & a_n \\ w_1 & \cdots & w_n \end{pmatrix}$$

contains  $(1, \dots, 1)$ .

- In other words, the weight vector  $w$  is in the image of  $\overline{A}^T$ , where

$$\overline{A}^T = \begin{pmatrix} a_1 & \cdots & a_n \\ 1 & \cdots & 1 \end{pmatrix}.$$

## Borel sum of a formal solution

- In the following we assume that the row span of the matrix

$$A_w = \begin{pmatrix} a_1 & \cdots & a_n \\ w_1 & \cdots & w_n \end{pmatrix}$$

contains  $(1, \dots, 1)$ .

- In other words, the weight vector  $w$  is in the image of  $\overline{A}^T$ , where  $\overline{A}^T = \begin{pmatrix} a_1 & \cdots & a_n \\ 1 & \cdots & 1 \end{pmatrix}$ .
- Or, the weight vector  $w$  is in the intersection of the set of the secondary cones of  $\overline{A}$ .

## Borel sum of a formal solution

- In the following we assume that the row span of the matrix

$$A_w = \begin{pmatrix} a_1 & \cdots & a_n \\ w_1 & \cdots & w_n \end{pmatrix}$$

contains  $(1, \dots, 1)$ .

- In other words, the weight vector  $w$  is in the image of  $\overline{A}^T$ , where  $\overline{A}^T = \begin{pmatrix} a_1 & \cdots & a_n \\ 1 & \cdots & 1 \end{pmatrix}$ .
- Or, the weight vector  $w$  is in the intersection of the set of the secondary cones of  $\overline{A}$ .

In this case  $r = -\frac{|b_i|}{w \cdot b_i}$  holds for any  $i \in \sigma$ , and  $s = 1 + r$  is a slope of  $M_{A,w}(\beta)$ .

Let  $f(x, t) = \sum_{m=0}^{\infty} f_m(x)t^{m+\gamma}$  be a formal solutions of the modified hypergeometric system  $H_{A,w}(\beta)$  whose Gevrey index along  $T$  is  $s = r + 1$ .



Let  $f(x, t) = \sum_{m=0}^{\infty} f_m(x)t^{m+\gamma}$  be a formal solutions of the modified hypergeometric system  $H_{A,w}(\beta)$  whose Gevrey index along  $T$  is  $s = r + 1$ .

### Theorem

*The formal solution  $f(x, t)$  is  $1/r$ -summable (w.r.t  $t$ ) in all direction but finitely many directions. Furthermore its  $1/r$ -sum is a solution of  $H_{A,w}(\beta)$ .*

An important properties to prove Theorem is the following. We first set

$$\varphi(x, z) := \psi(x, t) \Big|_{t=z^r} = \sum_{m=0}^{\infty} C_m(x) z^{r(m+\gamma)}$$

Then

$$\mathcal{B}_1[\varphi](x, \zeta) = \sum_{m=0}^{\infty} \frac{C_m(x)}{\Gamma(1 + r(m + \gamma))} \zeta^{r(m+\gamma)} = \mathcal{B}_{1/r}[\psi](x, \zeta^r)$$

satisfies  $H_{A_B}(\beta_B)$ , where

$$A_B = \begin{pmatrix} A & 0 \\ w & -1/r \end{pmatrix}, \quad \beta_B = \begin{pmatrix} \beta \\ 0 \end{pmatrix}.$$

An important properties to prove Theorem is the following. We first set

$$\varphi(x, z) := \psi(x, t) \Big|_{t=z^r} = \sum_{m=0}^{\infty} C_m(x) z^{r(m+\gamma)}$$

Then

$$\mathcal{B}_1[\varphi](x, \zeta) = \sum_{m=0}^{\infty} \frac{C_m(x)}{\Gamma(1 + r(m + \gamma))} \zeta^{r(m+\gamma)} = \mathcal{B}_{1/r}[\psi](x, \zeta^r)$$

satisfies  $H_{A_B}(\beta_B)$ , where

$$A_B = \begin{pmatrix} A & 0 \\ w & -1/r \end{pmatrix}, \quad \beta_B = \begin{pmatrix} \beta \\ 0 \end{pmatrix}.$$

This system  $H_{A_B}(\beta_B)$  is regular holonomic since the row span of  $A_B$  contains  $(1, \dots, 1)$ .

An important properties to prove Theorem is the following. We first set

$$\varphi(x, z) := \psi(x, t) \Big|_{t=z^r} = \sum_{m=0}^{\infty} C_m(x) z^{r(m+\gamma)}$$

Then

$$\mathcal{B}_1[\varphi](x, \zeta) = \sum_{m=0}^{\infty} \frac{C_m(x)}{\Gamma(1+r(m+\gamma))} \zeta^{r(m+\gamma)} = \mathcal{B}_{1/r}[\psi](x, \zeta^r)$$

satisfies  $H_{A_B}(\beta_B)$ , where

$$A_B = \begin{pmatrix} A & 0 \\ w & -1/r \end{pmatrix}, \quad \beta_B = \begin{pmatrix} \beta \\ 0 \end{pmatrix}.$$

This system  $H_{A_B}(\beta_B)$  is regular holonomic since the row span of  $A_B$  contains  $(1, \dots, 1)$ .

By using this fact we can study the analytic continuation of the Borel transform of  $f(t, x)$  and estimate its growth order.

## Theorem

Assume  $\beta$  is very generic,

- $\tilde{A} = \begin{pmatrix} a_1 & \cdots & a_n & 0 \\ w_1 & \cdots & w_n & 1 \end{pmatrix}$  is pointed.
- the row span of  $A_w = \begin{pmatrix} a_1 & \cdots & a_n \\ w_1 & \cdots & w_n \end{pmatrix}$  contains  $(1, \dots, 1)$ .

Then

- $\exists$  a formal solution  $f(x, t) = \sum_{m=0}^{\infty} f_m(x) t^{m+\gamma}$  of  $H_{A,w}(\beta)$ .
- $f(x, t)$  is  $1/r$ -summable with  $r = -|b_i|/w \cdot b_i$ .
- If  $f(x, t)$  is  $1/r$ -summable in the direction 0,  $\Phi(x) = \mathcal{S}[f](x, t)|_{t=1}$  gives a solution of  $H_A(\beta)$ .
- $\Phi(t^{w_1}x_1, \dots, t^{w_n}x_n) \sim f(x, t)$  as  $t \rightarrow 0$ .

## Conclusion and discussion

1. Asymptotic behavior of  $\phi(t^w \cdot x)$  as  $t \rightarrow 0$  is discussed, where  $\phi(x)$  is a solution of  $A$ -hypergeometric systems.
2. To study this problem, we introduced the modified  $A$ -hypergeometric systems which  $f(t, x) = \phi(t^w \cdot x)$  is satisfied.
3. To determine the Gevrey order of  $f(t, x)$ , we apply Schulze-Walther theory to the Fourier transform of the modified  $A$ -hypergeometric system.
4. To show the Borel summability of  $f(t, x)$ , we impose some condition to  $w$ .

## Conclusion and discussion

1. Asymptotic behavior of  $\phi(t^w \cdot x)$  as  $t \rightarrow 0$  is discussed, where  $\phi(x)$  is a solution of  $A$ -hypergeometric systems.
  2. To study this problem, we introduced the modified  $A$ -hypergeometric systems which  $f(t, x) = \phi(t^w \cdot x)$  is satisfied.
  3. To determine the Gevrey order of  $f(t, x)$ , we apply Schulze-Walther theory to the Fourier transform of the modified  $A$ -hypergeometric system.
  4. To show the Borel summability of  $f(t, x)$ , we impose some condition to  $w$ .
- Relax the condition on  $w$ .
  - Multisummability of solutions should be discussed if the system has two or more slopes.

## Conclusion and discussion

1. Asymptotic behavior of  $\phi(t^w \cdot x)$  as  $t \rightarrow 0$  is discussed, where  $\phi(x)$  is a solution of  $A$ -hypergeometric systems.
  2. To study this problem, we introduced the modified  $A$ -hypergeometric systems which  $f(t, x) = \phi(t^w \cdot x)$  is satisfied.
  3. To determine the Gevrey order of  $f(t, x)$ , we apply Schulze-Walther theory to the Fourier transform of the modified  $A$ -hypergeometric system.
  4. To show the Borel summability of  $f(t, x)$ , we impose some condition to  $w$ .
- Relax the condition on  $w$ .
  - Multisummability of solutions should be discussed if the system has two or more slopes.

**Thank you!**