

Hamilton-Jacobi theory in Cauchy data space

Manuel de León
Instituto de Ciencias Matemáticas (ICMAT)
Consejo Superior de Investigaciones Científicas

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- Multisymplectic geometry is the natural arena to develop Classical Field Theories of first order.
- A multisymplectic manifold is a natural extension of symplectic manifolds: the canonical models for multisymplectic structures are the bundles of forms on a manifold in the same vein that cotangent bundles (1-forms) provide the canonical models for symplectic manifolds.
- One can exploit this parallelism between Classical Mechanics and Classical Field Theories.
 - In fact, instead of a configuration manifold, we have now a configuration bundle $\pi : E \longrightarrow M$ such that its sections are the fields (the manifold M represents the space-time manifold).
 - An important difference with the case of mechanics is that now we are dealing with partial differential equations. In any case, the solutions in both sides are interpreted as integral sections of Ehresmann connections.

- The Lagrangian density depends on the space-time coordinates, the fields and its derivatives, so it is very natural to take the manifold of 1-jets of sections of π , $J^1\pi$, as the generalization of the tangent bundle in Classical Mechanics.
- Then a Lagrangian density is a fibered mapping $\mathcal{L} : J^1\pi \longrightarrow \Lambda^{m+1}M$ (we are assuming that $\dim M = m + 1$). From the Lagrangian density one can construct the Poincaré-Cartan form which gives the evolution of the system.

- On the other hand, the spaces of 1- and 2-horizontal $m + 1$ -forms on E with respect to the projection π , denoted respectively by $\Lambda_1^{m+1}E$ and $\Lambda_2^{m+1}E$, are the arena where the Hamiltonian picture of the theory is developed. To be more precise, the phase space is just the quotient

$$\mathcal{M}^o\pi = \Lambda_2^{m+1}E / \Lambda_1^{m+1}E$$

and the Hamiltonian density is a section of $\Lambda_2^{m+1}E \rightarrow \mathcal{M}^o\pi$ (the Hamiltonian function H appears when a volume form η on M is chosen, such that $\mathcal{H} = H\eta$). The Hamiltonian section \mathcal{H} permits just to pull-back the canonical multisymplectic form of $\Lambda_2^{m+1}E$ to a multisymplectic form on $\mathcal{M}^o\pi$.

- Both descriptions are related by the Legendre transform which send solutions of the Euler-Lagrange equations into solutions of the Hamilton equations.

- The Hamilton-Jacobi problem for a Hamiltonian classical field theory given by a Hamiltonian H consists in finding a family of functions $S^i = S^i(x^i, u^a)$ such that

$$\frac{\partial S^i}{\partial x^i} + H(x^i, u^a, \frac{\partial S^i}{\partial u^a}) = f(x^i) \quad (1)$$

for some function $f(x^i)$; (x^i, u^a) are bundle coordinates in E .

- We shall develop a geometric Hamilton-Jacobi theory in the context of multisymplectic manifolds.

- There is an alternative way to study Classical Field Theories, in an infinite dimensional setting. The idea is to split the space-time manifold M in the space and time pieces. To do this, we need to take a Cauchy surface, that is, an m -dimensional submanifold N of M such that (at least locally) we have $M = \mathbb{R} \times N$. So, the space of embeddings from N to $\mathcal{M}^o\pi$ is known as the Cauchy space of data for a particular choice of a Cauchy surface. This allows us to integrate the multisymplectic form on $\mathcal{M}^o\pi$ to the Cauchy data space and obtain a presymplectic infinite dimensional system, whose dynamics is related to the de Donder-Hamilton equations for H .
- The aim of the paper is to show how we can “integrate” a solution of the Hamilton-Jacobi problem for H in order to get a solution for the Hamilton-Jacobi problem for the infinite-dimensional presymplectic system.

A multisymplectic point of view of Classical Field Theory

We begin by briefly introducing the multisymplectic approach to Classical Field Theory: the Lagrangian setting and its Hamiltonian counterpart. The theory is set in a configuration fiber bundle, $E \rightarrow M$, whose sections represent the fields.

From a Lagrangian density defined on the first jet bundle of the fibration π , say $\mathcal{L} : J^1\pi \rightarrow \Lambda^{m+1}M$, we derive the Euler-Lagrange equations.

On the Hamiltonian side, we start with a Hamiltonian density $\mathcal{H} : J^1\pi^\dagger \rightarrow \Lambda^{m+1}M$ to obtain Hamilton's equations.

Here, $J^1\pi^\dagger$ is the dual jet bundle, the field theoretic analogue of the cotangent bundle.

The relation among these two settings is given, under proper regularity, by the Legendre transform.

From now on, $\pi: E \rightarrow M$ will always denote a fiber bundle of rank n over an $(m + 1)$ -dimensional manifold, i.e. $\dim M = m + 1$ and $\dim E = m + 1 + n$.

Fibered coordinates on E will be denoted by (x^i, u^α) , $0 \leq i \leq m$, $1 \leq \alpha \leq n$; where (x^i) are local coordinates on M .

The shorthand notation $d^{m+1}x = dx^0 \wedge \dots \wedge dx^m$ will represent the local volume form that (x^i) defines and we will also use the notation $d^m x_i = i_{\frac{\partial}{\partial x^i}} dx^0 \wedge dx^1 \wedge \dots \wedge dx^m$ for the contraction with the coordinate vector fields.

Many bundles will be considered over M and E , but all of them vectorial or affine. For these bundles, we will only consider natural coordinates. In general, indexes denoted with lower case Latin letters (resp. Greek letters) will range between 0 and m (resp. 1 and n). The Einstein sum convention on repeated crossed indexes is always understood.

Furthermore, we assume M to be orientable with fixed orientation, together with a determined volume form η . Its pullback to any bundle over M will still be denoted η , as for instance $\pi^*\eta$.

In addition, local coordinates on M will be chosen compatible with η , which means such that $\eta = d^{m+1}x$.

Multisymplectic structures We begin reviewing the basic notions of multisymplectic geometry and presenting some examples.

Definition

Let V denote a finite dimensional real vector space. A $(k + 1)$ -form Ω on V is said to be *multisymplectic* if it is non-degenerate, i.e., if the linear map

$$\begin{aligned} b_{\Omega}: V &\longrightarrow \Lambda^k V^* \\ v &\longmapsto b_{\Omega}(v) := i_v \Omega \end{aligned}$$

is injective. In such a case, the pair (V, Ω) is said to be a *multisymplectic* vector space of order $k + 1$.

Definition

A *multisymplectic structure of order $k + 1$* on a manifold P is a closed $(k + 1)$ -form Ω on P such that $(T_x P, \Omega(x))$ is multisymplectic for each $x \in P$. The pair (P, Ω) is called a *multisymplectic manifold of order $k + 1$* .

Examples

The canonical example of a multisymplectic manifold is the bundle of forms over a manifold N , that is, the manifold $P = \Lambda^k N$.

Let N be a smooth manifold of dimension n , $\Lambda^k N$ be the bundle of k -forms on N and $\nu: \Lambda^k N \rightarrow N$ be the canonical projection ($1 \leq k \leq n$). The *Liouville form of order k* is the k -form Θ over $\Lambda^k N$ given by

$$\Theta(\omega)(X_1, \dots, X_k) := \omega((T_\omega \nu)(X_1), \dots, (T_\omega \nu)(X_k)),$$

for any $\omega \in \Lambda^k N$ and any $X_1, \dots, X_k \in T_\omega(\Lambda^k N)$. Then, the *canonical multisymplectic $(k+1)$ -form* is

$$\Omega := -d\Theta.$$

If (x^i) are local coordinates on N and $(x^i, p_{i_1 \dots i_k})$, with $1 \leq i_1 < \dots < i_k \leq n$, are the corresponding induced coordinates on $\Lambda^k N$, then

$$\Theta = \sum_{i_1 < \dots < i_k} p_{i_1 \dots i_k} dx^{i_1} \wedge \dots \wedge dx^{i_k}, \quad (2)$$

and

$$\Omega = \sum_{i_1 < \dots < i_k} -dp_{i_1 \dots i_k} \wedge dx^{i_1} \wedge \dots \wedge dx^{i_k}. \quad (3)$$

Let $\pi: E \rightarrow M$ be a fibration, that is, π is a surjective submersion. Assume that $\dim M = m + 1$ and $\dim E = m + 1 + n$. Given $1 \leq r \leq n$, we consider the vector subbundle $\Lambda_r^k E$ of $\Lambda^k E$ whose fiber at a point $u \in E$ is the set of k -forms at u that are r -horizontal with respect to π , that is, the set

$$(\Lambda_r^k E)_u = \{\omega \in \Lambda_u^k E : i_{v_r} \dots i_{v_1} \omega = 0 \quad \forall v_1, \dots, v_r \in \text{Vert}_u(\pi)\},$$

where $\text{Vert}_u(\pi) = \ker(T_u \pi)$ is the space of tangent vectors at $u \in E$ that are vertical with respect to π .

We denote by ν_r , Θ_r and Ω_r the restriction to $\Lambda_r^k E$ of ν , Θ and Ω respectively. It is easy to see that $(\Lambda_r^k E, \Omega_r)$ is a multisymplectic manifold. The case in which $r = 1, 2$ and $k = m + 1$ are the interesting cases for multisymplectic field theory.

Let (x^i, u^α) denote adapted coordinates on E , where $0 \leq i \leq m$ and $1 \leq \alpha \leq n$, then they induce coordinates $(x^i, u^\alpha, p, p_\alpha^i)$ on $\Lambda_2^{m+1}E$ such that any element $\omega \in \Lambda_2^{m+1}E$ has the form $\omega = pd^{m+1}x + p_\alpha^i du^\alpha \wedge d^m x_i$, where $d^{m+1}x = dx^0 \wedge \dots \wedge dx^m$ and $d^m x_i = i \frac{\partial}{\partial x^i} d^{m+1}x$. Therefore, we have that Θ_2 and Ω_2 are locally given by the expressions

$$\Theta_2 = pd^{m+1}x + p_\alpha^i du^\alpha \wedge d^m x_i, \quad (4)$$

and

$$\Omega_2 = -dp \wedge d^{m+1}x - dp_\alpha^i \wedge du^\alpha \wedge d^m x_i. \quad (5)$$

In an analogous fashion, we can induce coordinates (x^i, u^α, p) on $\Lambda_1^{m+1}E$, such that any element $\omega \in \Lambda_1^{m+1}E$ has the form $\omega = pd^{m+1}x$.

Lagrangian formalism The Lagrangian formulation of Classical Field Theory is stated on the *first jet manifold* $J^1\pi$ of the configuration bundle $\pi: E \rightarrow M$.

This manifold is defined as the collection of tangent maps of local sections of π :

$$J^1\pi := \{ T_x\phi : \phi \in \text{Sec}_x(\pi), x \in M \} .$$

The elements of $J^1\pi$ are denoted $j_x^1\phi$ and called the *1st-jet of ϕ at x* . Adapted coordinates (x^i, u^α) on E induce coordinates $(x^i, u^\alpha, u_i^\alpha)$ on $J^1\pi$ such that $u_i^\alpha(j_x^1\phi) = \frac{\partial}{\partial x^i}[\phi^\alpha]x^i|_x$.

It is clear that $J^1\pi$ fibers over E and M through the canonical projections $\pi_{1,0}: J^1\pi \rightarrow E$ and $\pi_1: J^1\pi \rightarrow M$, respectively, and that $\pi_1 = \pi \circ \pi_{1,0}$.

In local coordinates, these projections are given by $\pi_{1,0}(x^i, u^\alpha, u_i^\alpha) = (x^i, u^\alpha)$ and $\pi_1(x^i, u^\alpha, u_i^\alpha) = (x^i)$; notice that $\pi_1 = \pi \circ \pi_{1,0}$.

Despite the conceptual similarities with the tangent bundle of a manifold, the first jet manifold is not a vector bundle but an affine one, which is a crucial difference.

To be precise, the first jet manifold $J^1\pi$ is an affine bundle over E modeled on the vector bundle $V(J^1\pi) = \pi^*(T^*M) \otimes_E \text{Vert}(\pi)$

$\text{Vert}(\pi)$ is just the vector bundle $\ker(T\pi)$ with the obvious projection over E .

The dynamics of a Lagrangian field system are governed by a *Lagrangian density*, a fibered map $\mathcal{L}: J^1\pi \rightarrow \Lambda^{m+1}M$ over M .

The real valued function $L: J^1\pi \rightarrow \mathbb{R}$ that satisfies $\mathcal{L} = L\eta$ is called the *Lagrangian function*, where η is a volume form on M .

Both Lagrangians permit to define the so-called *Poincaré-Cartan forms*:

$$\Theta_{\mathcal{L}} = L\eta + \langle S_{\eta}, dL \rangle \in \Omega^{m+1}(J^1\pi) \quad \text{and} \quad \Omega_{\mathcal{L}} = -d\Theta_{\mathcal{L}} \in \Omega^{m+2}(J^1\pi), \quad (6)$$

where S_{η} is a $(1, n)$ tensor field on $J^1\pi$ called *vertical endomorphism* and whose local expression is

$$S_{\eta} = (du^{\alpha} - u_j^{\alpha} dx^j) \wedge d^{m-1}x_i \otimes \frac{\partial}{\partial u_i^{\alpha}}. \quad (7)$$

In local coordinates, the Poincaré-Cartan forms read as follows

$$\Theta_{\mathcal{L}} = \left(L - u_i^\alpha \frac{\partial L}{\partial u_i^\alpha} \right) d^{m+1}x + \frac{\partial L}{\partial u_i^\alpha} du^\alpha \wedge d^m x_i, \quad (8)$$

$$\Omega_{\mathcal{L}} = - (du^\alpha - u_j^\alpha dx^j) \wedge \left(\frac{\partial L}{\partial u^\alpha} d^{m+1}x - d \left(\frac{\partial L}{\partial u_i^\alpha} \right) \wedge d^m x_i \right). \quad (9)$$

A *critical point* of \mathcal{L} is a (local) section ϕ of π such that

$$(j^1\phi)^*(i_X\Omega_{\mathcal{L}}) = 0,$$

for any vector field X on $J^1\pi$. A straightforward computation shows that this implies that

$$(j^1\phi)^* \left(\frac{\partial L}{\partial u^\alpha} - \frac{d}{dx^i} \frac{\partial L}{\partial u_i^\alpha} \right) = 0, \quad 1 \leq \alpha \leq n. \quad (10)$$

The above equations are called *Euler-Lagrange equations*.

Hamiltonian formalism

The dual formulation of the Lagrangian formalism is the Hamiltonian one, which is set in the affine dual bundles of $J^1\pi$.

The (*extended*) affine dual bundle $J^1\pi^\dagger$ is the collection of real-valued affine maps defined on the fibers of $\pi_{1,0} : J^1\pi \rightarrow E$, namely

$$(J^1\pi)^\dagger := \text{Aff}(J^1\pi, \mathbb{R}) = \{A \in \text{Aff}(J_u^1\pi, \mathbb{R}) : u \in E\} .$$

The (*reduced*) affine dual bundle $J^1\pi^\circ$ is the quotient of $J^1\pi^\dagger$ by constant affine maps, namely

$$(J^1\pi)^\circ := \text{Aff}(J^1\pi, \mathbb{R}) / \{f : E \rightarrow \mathbb{R}\} .$$

It is again clear that $J^1\pi^\dagger$ and $J^1\pi^\circ$ are fiber bundles over E but, in contrast to $J^1\pi$, they are vector bundles. Moreover, $J^1\pi^\dagger$ is a principal \mathbb{R} -bundle over $J^1\pi^\circ$. The respective canonical projections are denoted $\pi_{1,0}^\dagger : J^1\pi^\dagger \rightarrow E$, $\pi_1^\dagger = \pi \circ \pi_{1,0}^\dagger$, $\pi_{1,0}^\circ : J^1\pi^\circ \rightarrow E$, $\pi_1^\circ = \pi \circ \pi_{1,0}^\circ$ and $\mu : J^1\pi^\dagger \rightarrow J^1\pi^\circ$. The natural pairing between the elements of $J^1\pi^\dagger$ and those of $J^1\pi$ will be denoted by the usual angular bracket,

$$\langle \cdot, \cdot \rangle : J^1\pi^\dagger \times_E J^1\pi \longrightarrow \mathbb{R} .$$

We note here that $J^1\pi^\circ$ is isomorphic to the dual bundle of $V(J^1\pi) = \pi^*(T^*M) \otimes_E \text{Vert}(\pi)$.

Besides defining the affine duals of $J^1\pi$, we must also introduce the *extended and reduced multimomentum spaces*

$$\mathcal{M}\pi := \Lambda_2^{m+1}E \quad \text{and} \quad \mathcal{M}^\circ\pi := \Lambda_2^{m+1}E / \Lambda_1^{m+1}E.$$

By definition, these spaces are vector bundles over E and we denote their canonical projections $\nu: \mathcal{M}\pi \rightarrow E$, $\nu^\circ: \mathcal{M}^\circ\pi \rightarrow E$ and $\mu: \mathcal{M}\pi \rightarrow \mathcal{M}^\circ\pi$ (some abuse of notation here).

Again, $\mu: \mathcal{M}\pi \rightarrow \mathcal{M}^\circ\pi$ is a principal \mathbb{R} -bundle.

We recall that $\mathcal{M}\pi$ has a canonical multisymplectic structure which we denote Ω .

On the contrary, $\mathcal{M}^\circ\pi$ has not canonical multisymplectic structure, but Ω can still be pulled back by any section of $\mu: \mathcal{M}\pi \rightarrow \mathcal{M}^\circ\pi$ to give rise to a multisymplectic structure on $\mathcal{M}^\circ\pi$.

An interesting and important fact is how the four bundles we have defined so far are related. We have that

$$J^1\pi^\dagger \cong \mathcal{M}\pi \quad \text{and} \quad J^1\pi^\circ \cong \mathcal{M}^\circ\pi, \quad (11)$$

although these isomorphisms depend on the base volume form η . In fact, the bundle isomorphism $\Psi : \mathcal{M}\pi \rightarrow J^1\pi^\dagger$ is characterized by the equation

$$\langle \Psi(\omega), j_x^1\phi \rangle \eta = \phi_x^*(\omega), \quad \forall j_x^1\phi \in J_{\nu(\omega)}^1\pi, \quad \forall \omega \in \mathcal{M}\pi.$$

We therefore identify $\mathcal{M}\pi$ with $J^1\pi^\dagger$ (and $\mathcal{M}^\circ\pi$ with $J^1\pi^\circ$) and use this isomorphism to pullback the duality nature of $J^1\pi^\dagger$ to $\mathcal{M}\pi$.

Adapted coordinates in $\mathcal{M}\pi$ (resp. $\mathcal{M}^\circ\pi$) will be of the form $(x^i, u^\alpha, p, p_\alpha^i)$ (resp. $(x^i, u^\alpha, p_\alpha^i)$), such that

$$pd^{m+1}x + p_\alpha^i du^\alpha \wedge d^m x_i \in \Lambda_2^{m+1} E \quad (pd^{m+1}x \in \Lambda_1^m E).$$

Under these coordinates, the canonical projections have the expression

$$\nu(x^i, u^\alpha, p, p_\alpha^i) = (x^i, u^\alpha), \quad \nu^\circ(x^i, u^\alpha, p_\alpha^i) = (x^i, u^\alpha)$$

and

$$\mu(x^i, u^\alpha, p, p_\alpha^i) = (x^i, u^\alpha, p_\alpha^i);$$

and the above pairing takes the form

$$\langle (x^i, u^\alpha, p, p_\alpha^i), (x^i, u^\alpha, u_i^\alpha) \rangle = p + p_\alpha^i u_i^\alpha.$$

We also recall the local description of the canonical multisymplectic form Ω of $\mathcal{M}\pi$,

$$\Omega = -dp \wedge d^{m+1}x - dp_\alpha^i \wedge du^\alpha \wedge d^m x_i.$$

Now, we focus on the principal \mathbb{R} -bundle structure of $\mu: \mathcal{M}\pi \rightarrow \mathcal{M}^\circ\pi$. This structure arises from the \mathbb{R} -action

$$\begin{aligned}\mathbb{R} \times \mathcal{M}\pi &\longrightarrow \mathcal{M}\pi \\ (t, \omega) &\longmapsto t \cdot \eta_{\nu(\omega)} + \omega.\end{aligned}$$

In coordinates,

$$(t, (x^i, u^\alpha, p, p_\alpha^i)) \longmapsto (x^i, u^\alpha, t + p, p_\alpha^i).$$

We will denote by $V_\mu \in \mathfrak{X}(\mathcal{M}\pi)$ the infinitesimal generator of the action of \mathbb{R} on $\mathcal{M}\pi$, which in coordinates is nothing else but $V_\mu = \frac{\partial}{\partial p}$. Since the orbits of this action are the fiber of μ , then V_μ is also a generator of the vertical bundle $\text{Vert}(\mu)$.

The dynamics of a Hamiltonian field system is governed by a *Hamiltonian section*, say a section $h: \mathcal{M}^\circ\pi \rightarrow \mathcal{M}\pi$ of $\mu: \mathcal{M}\pi \rightarrow \mathcal{M}^\circ$. In presence of the base volume form η , the set of Hamiltonian sections $\text{Sec}(\mu)$ is in one-to-one correspondence with the set of functions $\{\bar{H} \in \mathcal{C}^\infty(\mathcal{M}\pi) : V_\mu(\bar{H}) = 1\}$ and with the set of *Hamiltonian densities*, that is, fibered maps $\mathcal{H}: \mathcal{M}\pi \rightarrow \Lambda^{m+1}M$ over M such that $i_{V_\mu} d\mathcal{H} = \eta$.

Given a Hamiltonian section $h: \mathcal{M}^\circ\pi \rightarrow \mathcal{M}\pi$, the corresponding Hamiltonian density is

$$\mathcal{H}(\omega) = \omega - h(\mu(\omega)), \quad \forall \omega \in \mathcal{M}\pi.$$

Conversely, given a Hamiltonian density $\mathcal{H}: \mathcal{M}\pi \rightarrow \Lambda^{m+1}M$, the corresponding Hamiltonian section is characterized by the condition

$$\text{im}h = \mathcal{H}^{-1}(0).$$

Obviously, $\mathcal{H} = \bar{H}\eta$.

In adapted coordinates,

$$h(x^i, u^\alpha, p_\alpha^j) = (x^i, u^\alpha, p = -H(x^i, u^\alpha, p_\alpha^j), p_\alpha^j), \quad (12)$$

$$\mathcal{H}(x^i, u^\alpha, p, p_\alpha^j) = (p + H(x^i, u^\alpha, p_\alpha^j)) d^{m+1}x. \quad (13)$$

A *critical point* of \mathcal{H} is a (local) section τ of $\pi \circ \nu: \mathcal{M}\pi \rightarrow M$ that satisfies the (*extended*) *Hamilton-De Donder-Weyl equation*

$$\tau^* i_X(\Omega + d\mathcal{H}) = 0, \quad (14)$$

for any vector field X on $\mathcal{M}\pi$.

A *critical point* of h is a (local) section τ of $\pi \circ \nu^\circ: \mathcal{M}^\circ\pi \rightarrow M$ that satisfies the (*reduced*) *Hamilton-De Donder-Weyl equation*

$$\tau^*(i_X\Omega_h) = 0, \quad (15)$$

for any vector field X on $\mathcal{M}^\circ\pi$ and where $\Omega_h = h^*(\Omega + d\mathcal{H}) = h^*\Omega$.

A straightforward computation shows that both equations are equivalent to the following set of local equations known as *Hamilton's equations*:

$$\frac{\partial \tau^\alpha}{\partial x^i} = \frac{\partial H}{\partial p_\alpha^i} \circ \tau, \quad \frac{\partial \tau_\alpha^i}{\partial x^i} = -\frac{\partial H}{\partial u^\alpha} \circ \tau, \quad (16)$$

where $\tau^\alpha = u^\alpha \circ \tau$ and $\tau_\alpha^i = p_\alpha^i \circ \tau$.

Ehresmann Connections

Let $\pi : E \rightarrow M$ be a fibred bundle (that is, π is a surjective submersion). Denote by VE the vertical bundle defined by $\ker \pi$ which is a vector sub-bundle of $TE \rightarrow E$.

Definition

An Ehresmann connection in $\pi : E \rightarrow M$ is a distribution \mathbf{H} on E which is complementary to the vertical bundle, say

$$TE = \mathbf{H} \oplus VE \quad (17)$$

\mathbf{H} is called the horizontal distribution.

Given a connection \mathbf{H} in $\pi : E \rightarrow M$ we have two complementary projectors:

$$\begin{aligned}h &: TE \rightarrow \mathbf{H} \\v &: TE \rightarrow VE\end{aligned}$$

h and v are called the horizontal and vertical projectors, respectively. Obviously, we have $\mathbf{H} = \text{Im}(h)$ and $VE = \text{Im}(v)$. Consequently, any tangent vector $X \in T_e E$ can be decomposed in its horizontal and vertical parts, say

$$X = hX + vX$$

In addition, given a tangent vector $Y \in T_x M$, there exists a unique tangent vector X at any point of the fiber over x , say $e \in \pi^{-1}(x)$ such that X is horizontal and projects onto Y ; X is called the horizontal lift of Y to e .

The curvature of a connection \mathbf{H} (or h with some abuse of notation) can be defined as the Schouten-Nijenhuis bracket

$$R = -\frac{1}{2}[h, h]$$

such that \mathbf{H} is flat if and only if $R = 0$.

A connection \mathbf{H} should not be flat in general; let us introduce the notion of integral section.

Definition

A section $\gamma : M \rightarrow E$ is called an integrable section of \mathbf{H} if $\gamma(M)$ is an integral submanifold of the horizontal distribution. The connection \mathbf{H} is integrable if and only if there are integral sections passing through any point of E .

Therefore, we easily have the following result.

Theorem

A connection \mathbf{H} is integrable if and only if it is flat.

Indeed, $R = 0$ which is just the condition for the integrability of the distribution \mathbf{H} .

We introduce now Ehresmann connections in order to write the infinitesimal counterpart of the previous equations.

Thus, an Ehresmann connection on the bundle $\mathcal{M}\pi^\circ \rightarrow M$ is given by a distribution \mathbf{H} in $T\mathcal{M}\pi^\circ$ which is complementary to the vertical one, $\text{Vert}(\pi \circ \nu^\circ) = \ker(T\pi \circ \nu^\circ)$.

Let h be the horizontal projector of an Ehresmann connection in the bundle π_1° .

Proposition If the horizontal projector h of an Ehresmann connection satisfies

$$i_h \Omega_h = m \Omega_h. \quad (18)$$

then any horizontal integral section σ of the connection is a solution of Hamilton's equations.

An equivalent proposition could be set on the Lagrangian side using the form $\Omega_{\mathcal{L}}$.

Equivalence between both formalisms

Let \mathcal{L} be a Lagrangian density. The (*extended*) Legendre transform is the bundle morphism $\text{Leg}_{\mathcal{L}}: J^1\pi \rightarrow \mathcal{M}\pi$ over E defined as follows:

$$\text{Leg}_{\mathcal{L}}(j_x^1\phi)(X_1, \dots, X_m) := (\Theta_{\mathcal{L}})_{j_x^1\phi}(\tilde{X}_1, \dots, \tilde{X}_m), \quad (19)$$

for all $j_x^1\phi \in J^1\pi$ and $X_i \in T_{\phi(x)}E$, where $\tilde{X}_i \in T_{j_x^1\phi}J^1\pi$ are such that $T\pi_{1,0}(\tilde{X}_i) = X_i$.

The (*reduced*) Legendre transform is the composition of $\text{Leg}_{\mathcal{L}}$ with μ , that is, the bundle morphism

$$\text{leg}_{\mathcal{L}} := \mu \circ \text{Leg}_{\mathcal{L}}: J^1\pi \rightarrow \mathcal{M}^{\circ}\pi. \quad (20)$$

In local coordinates,

$$\text{Leg}_{\mathcal{L}}(x^i, u^{\alpha}, u_i^{\alpha}) = \left(x^i, u^{\alpha}, L - \frac{\partial L}{\partial u_i^{\alpha}} u_i^{\alpha}, \frac{\partial L}{\partial u_i^{\alpha}} \right), \quad (21)$$

$$\text{leg}_{\mathcal{L}}(x^i, u^{\alpha}, u_i^{\alpha}) = \left(x^i, u^{\alpha}, \frac{\partial L}{\partial u_i^{\alpha}} \right), \quad (22)$$

where L is the Lagrangian function associated to \mathcal{L} , i.e. $\mathcal{L} = L\eta$.

From the definitions, we deduce that

$$(\text{Leg}_{\mathcal{L}})^*(\Theta) = \Theta_{\mathcal{L}}, (\text{Leg}_{\mathcal{L}})^*(\Omega) = \Omega_{\mathcal{L}}$$

where Θ is the Liouville m -form on $\mathcal{M}\pi$ and Ω is the canonical multisymplectic $(m + 1)$ -form.

In addition, we have that the Legendre transformation $\text{leg}_{\mathcal{L}}: J^1\pi \rightarrow \mathcal{M}^\circ\pi$ is a local diffeomorphism, if and only if, the Lagrangian function L is *regular*, that is, the Hessian $\left(\frac{\partial^2 L}{\partial u_i^\alpha \partial u_j^\beta}\right)$ is a regular matrix.

When $\text{leg}_{\mathcal{L}}: J^1\pi \rightarrow \mathcal{M}^\circ\pi$ is a global diffeomorphism, we say that the Lagrangian L is *hyper-regular*. In this case, we may define the Hamiltonian section $h: \mathcal{M}^\circ\pi \rightarrow \mathcal{M}\pi$ by

$$h = \text{Leg}_{\mathcal{L}} \circ \text{leg}_{\mathcal{L}}^{-1}, \quad (23)$$

whose associated Hamiltonian density is

$$\mathcal{H}(\omega) = \langle \omega, \text{leg}_{\mathcal{L}}^{-1}(\mu(\omega)) \rangle \eta - (\mathcal{L} \circ \text{leg}_{\mathcal{L}}^{-1})(\mu(\omega)), \quad \forall \omega \in \mathcal{M}\pi. \quad (24)$$

In coordinates,

$$h(x^i, u^\alpha, p_\alpha^i) = (x^i, u^\alpha, L(x^i, u^\alpha, u_i^\alpha) - p_\alpha^i u_i^\alpha, p_\alpha^i), \quad (25)$$

where $u_i^\alpha = u_i^\alpha(\text{leg}_{\mathcal{L}}^{-1}(x^i, u^\alpha, p_\alpha^i))$. Accordingly,

$$\mathcal{H}(x^i, u^\alpha, p, p_\alpha^i) = (p + p_\alpha^i u_i^\alpha - L) d^{m+1}x \quad (26)$$

and the Hamiltonian function is

$$H(x^i, u^\alpha, p_\alpha^i) = p_\alpha^i u_i^\alpha - L. \quad (27)$$

Theorem

Assume \mathcal{L} is a hyper-regular Lagrangian density. If ϕ is a solution of the Euler-Lagrange equations for \mathcal{L} , then $\varphi = \text{leg}_{\mathcal{L}} \circ j^1\phi$ is a solution of the Hamilton's equations for h . Conversely, if φ is a solution of the Hamilton's equations for h , then $\text{leg}_{\mathcal{L}}^{-1} \circ \varphi$ is of the form $j^1\phi$, where ϕ is a solution of the Euler-Lagrange equations for \mathcal{L} .

From now on, we will assume that every Lagrangian to be regular.

Hamilton-Jacobi theory for multisymplectic systems

We start recalling the standard Hamilton-Jacobi theory from Classical Mechanics.

Let Q be the configuration manifold of a mechanical system and T^*Q the corresponding phase space, which is equipped with the canonical symplectic form

$$\omega_Q = dq^\alpha \wedge dp_\alpha,$$

where (q^α, p_α) are natural coordinates in T^*Q . We denote

$\pi_Q: T^*Q \rightarrow Q$ the canonical projection.

Let $H: T^*Q \rightarrow \mathbb{R}$ be a Hamiltonian function and X_H the corresponding Hamiltonian vector field, that is, the one that satisfies

$$i_{X_H}\omega_Q = dH.$$

The integral curves $(q^\alpha(t), p_\alpha(t))$ of X_H satisfy the Hamilton's equations:

$$\frac{dq^\alpha}{dt} = \frac{\partial H}{\partial p_\alpha} \quad \text{and} \quad \frac{dp_\alpha}{dt} = -\frac{\partial H}{\partial q^\alpha}.$$

The following theorem gives the relation between the Hamilton-Jacobi equation and the solutions of Hamilton's equations.

Theorem

Let λ be a closed 1-form on Q . The following conditions are equivalent:

- 1 If $\sigma: I \rightarrow Q$ satisfies the equation

$$\frac{dq^\alpha}{dt} = \frac{\partial H}{\partial p_\alpha} \circ \lambda,$$

then $\lambda \circ \sigma$ is a solution of the Hamilton's equations;

- 2 $d(H \circ \lambda) = 0$.

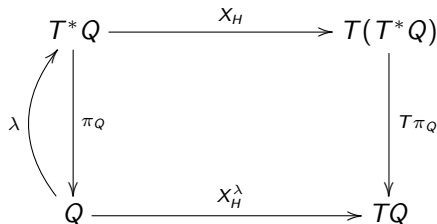
Remark Since λ is closed, locally we have $\lambda = dS$ for a function S depending on the local coordinates (q^α) . Then, the equation $d(H \circ \lambda) = 0$ reads locally $d\left(H(q^\alpha, \frac{\partial S}{\partial q^\alpha})\right) = 0$. Moreover, on each

connected component, the previous equation becomes $H(q^\alpha, \frac{\partial S}{\partial q^\alpha}) = E$, where E is a real constant. The last formula is known as the Hamilton-Jacobi equation.

We can give the following interpretation. Define on Q the vector field

$$X_H^\lambda = T\pi_Q \circ X_H \circ \lambda$$

whose construction is illustrated by the below diagram



We then have the intrinsic version of the above result.

Theorem

Let λ be a closed 1-form on Q . Then the conditions below are equivalent:

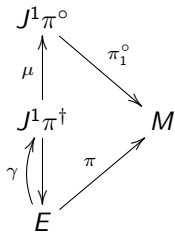
- 1 X_H^λ and X_H are λ -related;
- 2 $d(H \circ \lambda) = 0$.

In the Classical Field framework, the role of the Hamiltonian vector field X_H is played by a solution h of the field equation, while the role of the 1-form λ above is now played by γ , a 2-semibasic $(m + 1)$ -form, otherwise a section of the bundle $\pi_{1,0}^\dagger: J^1\pi^\dagger \rightarrow E$.

We project along γ the Ehresmann connection on $J^1\pi_1^\circ \rightarrow M$ to an Ehresmann connection on $E \rightarrow M$ whose horizontal projector is

$$\begin{aligned} h^\gamma(e): T_e E &\longrightarrow T_e E \\ X &\longmapsto h^\gamma(e)(X) = T_f \pi_{1,0}^\circ(h(f)(Y)), \end{aligned} \quad (28)$$

where $f = (\mu \circ \gamma)(e)$ and Y is any vector of $T_f J^1\pi^\dagger$ which projects onto X by $T\pi_{1,0}^\circ$. The Ehresmann connection given by h^γ plays the role of the projected vector field X_H^λ in mechanics.



Connection h on $J^1\pi^\circ \rightarrow M$

using γ induces

Connection h^γ on $E \rightarrow M$

Theorem

Assume that γ is closed and that the induced connection on $E \rightarrow M$, h^γ , is flat. Then the following conditions are equivalent:

- 1 If σ is an integral section of h then $\mu \circ \gamma \circ \sigma$ is a solution of the Hamilton's equations.
- 2 The $(m+1)$ -form $h \circ \mu \circ \gamma$ is closed.

The condition $d(h \circ \mu \circ \gamma) = 0$ which happens to be equivalent to $(\mu \circ \gamma)^* \Omega_h = 0$, corresponds to the generalization to Classical Field Theory of the Hamilton-Jacobi equation. Therefore we will refer to a form γ satisfying it as a *solution of the Hamilton-Jacobi equation*.

Remark It can be seen that if we assume that $\lambda = dS$, where S is a 1-semibasic m -form, then in local coordinates the equation

$d(h \circ \mu \circ \gamma) = 0$ is equivalent to $\frac{\partial S^i}{\partial x^i} + H(x^i, u^\alpha, \frac{\partial S^i}{\partial u^\alpha}) = f(x^i)$, where $f(x^i)$ is a function on M . This is the usual way to write the Hamilton-Jacobi equations for Classical Field Theory.

The space of Cauchy data

We shall develop the infinite-dimensional formulation of Hamilton's equations in order to introduce the Hamilton-Jacobi theory in infinite dimensions. We start introducing some basic definitions.

Definition

We say that an m -dimensional, compact, oriented and embedded submanifold Σ of the base manifold M is a *Cauchy surface*.

We will assume that that Σ is endowed with a volume form, η_Σ , such that

$$\int_{\Sigma} \eta_{\Sigma} = 1.$$

Definition

A *slicing* of M is a diffeomorphism between M and $\mathbb{R} \times \Sigma$, say

$$\chi_M: \mathbb{R} \times \Sigma \rightarrow M.$$

Observe that for each fixed $t \in \mathbb{R}$, $\chi_M(t, \cdot): \Sigma \rightarrow M$ defines an embedding

We denote by $\Sigma_t = \text{Im}((\chi_M)_t)$ the image of Σ by $(\chi_M)_t$ and by \tilde{M} the space of such embeddings

$$\tilde{M} = \{(\chi_M)_t \text{ such that } t \in \mathbb{R}\},$$

which happens to be equivalent to \mathbb{R} , $\tilde{M} \cong \mathbb{R}$. Without loss of generality, we may assume that Σ is given by one of these embeddings, *i.e.* there exists t_0 such that $\Sigma = \Sigma_{t_0}$. We will also use $(\chi_M)_t$ to denote the restriction of this map to its image, which happens to be a diffeomorphism between Σ and Σ_t .

The aim of the slicing χ_M is to split M onto time plus space and, particularly, to outline a 1-dimensional direction, which may be recovered infinitesimally. Let $\frac{\partial}{\partial x^0}$ denote the vector field on $\mathbb{R} \times \Sigma$ characterizing the time translations $(t, x) \mapsto (t + s, x)$.

Definition

The vector field $\xi_M = (\chi_M)_* \left(\frac{\partial}{\partial x^0} \right) \in \mathfrak{X}(M)$ is the (*infinitesimal*) generator of χ_M . Its dual counterpart $(\chi_M^{-1})^*(dt) \in \Omega^1(M)$ will still be denoted dt .

Let $\pi: E \rightarrow M$ be any bundle, then the set

$$\tilde{E} = \{\sigma: \Sigma \rightarrow E \mid \sigma \text{ is an embedding and } \pi \circ \sigma = (\chi_M)_t \text{ for some } t \in \mathbb{R}\}$$

is called the *space of χ -sections* of E . Indeed, it is a line bundle

$$\begin{aligned} \tilde{\pi}: \tilde{E} &\longrightarrow \mathbb{R} \\ \sigma &\longmapsto t \text{ s.t. } \pi \circ \sigma = (\chi_M)_t. \end{aligned}$$

Consequently, a section of $\pi: E \rightarrow M$ induces a section of $\tilde{\pi}: \tilde{E} \rightarrow \mathbb{R}$, and conversely.

This correspondence just relates the finite (multisymplectic) picture and the infinite (presymplectic) one for a Classical Field Theory.

Remark We assume that these spaces of embeddings are topologized in a way that they become infinite-dimensional smooth manifolds.

Remark Observe that we still have the previous bundle structures by composition, for instance, from the bundle $\pi_{1,0}^\circ : J^1\pi^\circ \rightarrow E$ we can construct the bundle

$$\begin{aligned} \widetilde{\pi_{1,0}^\circ} : \widetilde{J^1\pi^\circ} &\longrightarrow \widetilde{E} \\ \sigma_{J^1\pi^\circ} &\longrightarrow \widetilde{\pi_{1,0}^\circ}(\sigma_{J^1\pi^\circ}) = \pi_{1,0}^\circ \circ \sigma_{J^1\pi^\circ}. \end{aligned}$$

We will use this procedure and notation to construct new bundles in the infinite dimensional setting from the ones on the finite dimensional framework.

For example, in the same fashion we have the bundles $\widetilde{\pi} : \widetilde{E} \rightarrow \mathbb{R}$ and $\widetilde{\pi_1^\circ} : \widetilde{J^1\pi^\circ} \rightarrow \mathbb{R}$ since $\widetilde{M} \equiv \mathbb{R}$.

Now we give a short description of *tangent vectors* and some forms on the manifolds of embeddings.

We give the description in the $\widetilde{J^1\pi^0}$ case, which is going to play the main role in what follows, being the others analogous.

Consider a differentiable curve from an open real interval

$c: (-\epsilon, \epsilon) \rightarrow \widetilde{J^1\pi^0}$ where ϵ is a positive real number and such that $c(0) = \sigma_{J^1\pi^0}$.

Computing $\frac{dc}{dt}(0)$ it is easy to see that a *tangent vector*, \tilde{X} , at a point $\sigma_{J^1\pi^0} \in \widetilde{J^1\pi^0}$ is given by a map $\tilde{X}: \Sigma \rightarrow TJ^1\pi^0$ such that the following diagram is commutative

$$\begin{array}{ccc}
 \Sigma & \xrightarrow{\tilde{X}} & TJ^1\pi^0 \\
 & \searrow \sigma_{J^1\pi^0} & \downarrow \tau_{J^1\pi^0} \\
 & & J^1\pi^0
 \end{array}$$

This implies that there exists a constant $k \in \mathbb{R}$ in a way that

$$T\pi_1^\circ(\tilde{X}(p)) = k\xi_M(\pi_1^\circ(\sigma_{J^1\pi^\circ}(p))), \text{ for all } p \in \Sigma,$$

where we recall that ξ_M denotes the generator introduced above, and $\tau_{J^1\pi^\circ}$ is the natural projection from the tangent bundle onto its base manifold..

We show now how to construct *forms on the infinite dimensional setting from forms on the finite dimensional side*.

We also give the description in the $\widetilde{J^1\pi^\circ}$ case being the others analogous.

Let α be a $(k + m)$ -form on $J^1\pi^\circ$, we define the k -form $\tilde{\alpha}$ on $\widetilde{J^1\pi^\circ}$, such that for a point $\sigma_{J^1\pi^\circ} \in \widetilde{J^1\pi^\circ}$ and k tangent vectors $\tilde{X}_i \in T_{\sigma_{J^1\pi^\circ}}\widetilde{J^1\pi^\circ}$ the pairing is given by

$$\tilde{\alpha}(\sigma_{J^1\pi^\circ})(\tilde{X}_1, \dots, \tilde{X}_k) = \int_{\Sigma} \sigma_{J^1\pi^\circ}^*(i_{\tilde{X}_1, \dots, \tilde{X}_k} \alpha) \quad (29)$$

The next lemma will be useful.

Lemma

Let α be a $k + m$ -form, then $d(\widetilde{\alpha}) = \widetilde{d\alpha}$.

Remark The 2-form $\widetilde{\Omega}_h$, made out of Ω_h by this procedure, will play an important role describing the solutions of Hamilton's equations as an infinite dimensional dynamical system.

Remark The form $\widetilde{dt \wedge \eta_\Sigma}$ is equal to $(\widetilde{\pi_1^0})^* dt$.

Now, we introduce local coordinates on the manifolds of embeddings using coordinates adapted to the slicing on M .

Let us work in coordinates adapted to the slicing on M , i.e., (x^0, x^1, \dots, x^n) are such that locally the Σ_t are given by the level sets of the function x^0 , moreover, we assume that in these coordinates the generator vector field ξ_M is given by $\frac{\partial}{\partial x^0}$, which can be always achieved re-scaling the variable x^0 . Actually we can assume that the coordinate x^0 is given by the function t under the identification $\chi_M: \mathbb{R} \times \Sigma \rightarrow M$, where

$$\begin{aligned} t: \mathbb{R} \times \Sigma &\longrightarrow \mathbb{R} \\ (t_0, p) &\longrightarrow t(t_0, p) = t_0. \end{aligned}$$

Thus, from now on, making some abuse of notation (we are using t to denote $t \circ \chi_M^{-1}$) we are working with coordinates (t, x^1, \dots, x^n) as described above.

We want to explain that the choice of this coordinate t is by no means arbitrary, it suggests the existence of a time parameter and so the generator vector field ξ a time evolution direction. This is motivated by what happens for instance in Relativity.

Now, choosing coordinates adapted to the fibration and to the base coordinates (t, x^i) , $1 \leq i \leq m$ (adapted to the slicing), say (t, x^i, u^α) , a point on \tilde{E} is given by specifying functions $u^\alpha(\cdot)$ that depend on the coordinates on Σ_t , i.e. (x^i) , $i = 1, \dots, n$.

So “coordinates” on \tilde{E} are given by

$$(t, u^\alpha(\cdot)), \quad t \in \mathbb{R}, \quad u^\alpha = u^\alpha(x^1, \dots, x^n) \quad (30)$$

where the functions u^α belong to the chosen functional space.

Remark Let us notice that this construction does not provide true local coordinates, but it is a nice way to determine elements of these different spaces of mappings.

In the same way, choosing coordinates adapted to the slicing on M as above and to the bundles $J^1\pi^\circ \rightarrow M$ and $J^1\pi^\dagger \rightarrow M$, say $(t, x^i, p_\alpha^t, p_\alpha^i)$ and $(t, x^i, p, p_\alpha^t, p_\alpha^i)$, defined by

$$(x^i, u^\alpha, p_\alpha^t, p_\alpha^i) \rightarrow [p_\alpha^t du^\alpha \wedge d^m x - p_\alpha^i du^\alpha \wedge dt \wedge d^{m-1} x_i] \in \mathcal{M}\pi_{|(x^i, u^\alpha)}^\circ.$$

and

$$(x^i, u^\alpha, p, p_\alpha^t, p_\alpha^i) \rightarrow p dt \wedge d^m x + p_\alpha^t du^\alpha \wedge d^m x - p_\alpha^i du^\alpha \wedge dt \wedge d^{m-1} x_i \in \mathcal{M}\pi_{|(x^i, u^\alpha)}$$

respectively, where $[\cdot]$ denotes the equivalence class in the quotient and are using that $d^m x = dx^1 \wedge dx^2 \dots \wedge dx^m$ and $d^{m-1} x_i = i_{\frac{\partial}{\partial x^i}} d^m x$.

There is certain abuse of notation here, but there is no room for confusion. Notice that we are using the identifications $J^1\pi^\dagger \equiv \mathcal{M}\pi$ and $J^1\pi^\circ \equiv \mathcal{M}\pi^\circ$ again.

Therefore we deduce that, the points of $\widetilde{J^1\pi^\circ}$ and $\widetilde{J^1\pi^\dagger}$ are given by specifying respectively functions $p_\alpha^t(\cdot)$, $p_\alpha^i(\cdot)$, and $p(\cdot)$, $p_\alpha^t(\cdot)$, $p_\alpha^i(\cdot)$ that depend on (x^i) , following the same construction that we have introduced in the \widetilde{E} case.

Thus, local coordinates on $\widetilde{J^1\pi^\circ}$ are given by

$$(t, u^\alpha(\cdot), p_\alpha^t(\cdot), p_\alpha^i(\cdot)) \quad (31)$$

where $u^\alpha = u^\alpha(x^1, \dots, x^n)$, $p_\alpha^t = p_\alpha^t(x^1, \dots, x^n)$ and $p_\alpha^i = p_\alpha^i(x^1, \dots, x^n)$.

Analogously, coordinates on $\widetilde{J^1\pi^\dagger}$ can be given by

$$(t, u^\alpha(\cdot), p(\cdot), p_\alpha^t(\cdot), p_\alpha^i(\cdot)). \quad (32)$$

By the previous constructions we can consider the manifold $\widetilde{J^1\pi^\circ}$ endowed with the form $\widetilde{\Omega}_h$ obtained by the construction outlined above, such that $(\widetilde{J^1\pi^\circ}, \widetilde{\Omega}_h)$ becomes a presymplectic manifold.

There is a bijective correspondence between sections of the bundle $\widetilde{\pi_1^\circ}: \widetilde{J^1\pi^\circ} \rightarrow \mathbb{R}$ and sections of the bundle $\pi_1^\circ: J^1\pi^\circ \rightarrow M$.

Given σ a section of the bundle π_1° consider the section of $\widetilde{\pi_1^\circ}$ given by $c(t) = \sigma|_{\Sigma_t} \circ (\chi_M)_t \in \widetilde{J^1\pi^\circ}$.

Conversely given c a section of $\widetilde{\pi_1^\circ}$ using the slicing $(\chi_M)_t$ in the obvious way we can construct a section of π_1° .

The following theorem allows us to interpret Hamilton's equations as an infinite dimensional dynamical system.

Proposition A section σ of π_1° satisfies Hamilton's equations if and only if the corresponding curve $c(t)$ verifies

$$i_{\dot{c}(t)} \widetilde{\Omega}_h = 0$$

where $\dot{c}(t)$ denotes the time derivative of the curve.

Remark One could easily check that since c is a section of $\widetilde{\pi}_1^\circ$, then $\widetilde{dt} \wedge \eta_\Sigma(\dot{c}(t)) = 1$.

Hamilton-Jacobi theory on the space of Cauchy data

Assume now that we have a solution γ of the Hamilton-Jacobi equation and a connection h on the bundle π_1° satisfying the field equations and consider the reduced connection h^γ on the bundle π constructed above.

Next, we show how to induce a solution of the Hamilton-Jacobi equation in the infinite dimensional setting as well as the meaning of the Hamilton-Jacobi problem in this setting.

Following the previous constructions we can induce a section of the bundle $\widetilde{\pi}_{1,0}^\circ: \widetilde{J^1\pi^\circ} \rightarrow \widetilde{E}$ by

$$\begin{aligned}\widetilde{\gamma}: \quad \widetilde{E} &\longrightarrow \widetilde{J^1\pi^\circ} \\ \sigma_E &\longrightarrow \widetilde{\gamma}(\sigma_E) = \mu \circ \gamma \circ \sigma_E.\end{aligned}$$

On the other hand we can induce vector fields \tilde{X}^h and \tilde{X}^{h^γ} from the connections h and h^γ by

$$\begin{aligned} \tilde{X}^h: \widetilde{J^1\pi^\circ} &\longrightarrow T\widetilde{J^1\pi^\circ} \\ \sigma_{J^1\pi^\circ} &\rightarrow \tilde{X}^h(\sigma) : \Sigma \rightarrow T\widetilde{J^1\pi^\circ} \\ p &\rightarrow \tilde{X}^h(\sigma)(p) \\ &= \text{Hor}(\xi((\chi_M)_t(p)))(\sigma_{J^1\pi^\circ}(p)), \end{aligned}$$

where $\text{Hor}(X)(y)$ represents the horizontal lift of the tangent vector X to the point y .

In the same way we can construct the vector field \tilde{X}^{h^γ} on \tilde{E} using the horizontal lift with respect to the connection h^γ .

Remark Notice that the vector field \tilde{X}^{h^γ} just described can also be defined as the $\tilde{\gamma}$ -projection of the vector field \tilde{X}^h , i.e. we have

$$\tilde{X}^{h^\gamma}(\sigma_E) = T\widetilde{\pi_{1,0}^\circ}(\tilde{X}^h(\tilde{\gamma}(\sigma_E))), \text{ where } \sigma_E \in \tilde{E}.$$

In local coordinates, assuming that

$$\gamma(t, x^i, u^\alpha) = (t, x^i, u^\alpha, \gamma_p(t, x^i, u^\alpha), \gamma_{p_\alpha^t}(t, x^i, u^\alpha), \gamma_{p_\alpha^i}(t, x^i, u^\alpha)) \quad (33)$$

and using the following notation in local coordinates

$$\tilde{\gamma}(t, \sigma_E^\alpha(\cdot)) = (t, \cdot, \sigma_E^\alpha(\cdot), \gamma_{p_\alpha^t}(t, x^i, \sigma_E^\alpha(\cdot)), \gamma_{p_\alpha^i}(t, x^i, \sigma_E^\alpha(\cdot)))$$

where $\sigma_E^\alpha = u^\alpha \circ \sigma_E$ for $\sigma_E \in \tilde{E}$, the expressions $\tilde{X}^h(\tilde{\gamma}(\sigma_E))$ and $\tilde{X}^{h^\gamma}(\sigma_E)$ become

$$\begin{aligned} \tilde{X}^h(\tilde{\gamma}(t, \sigma_E^\alpha(\cdot))) &= \frac{\partial}{\partial t} + \Gamma_\alpha^0(\tilde{\gamma}(t, \sigma_E^\alpha(\cdot))) \frac{\partial}{\partial u^\alpha} + (\Gamma_0)_\alpha^0(\tilde{\gamma}(t, \sigma_E^\alpha(\cdot))) \frac{\partial}{\partial p_\alpha^t} \\ &\quad + (\Gamma_0)_\alpha^i(\tilde{\gamma}(t, \sigma_E^\alpha(\cdot))) \frac{\partial}{\partial p_\alpha^i} \end{aligned} \quad (34)$$

and

$$\tilde{X}^{h^\gamma}(t, \sigma_E^\alpha(\cdot)) = \frac{\partial}{\partial t} + \Gamma_\alpha^0(\tilde{\gamma}(t, \sigma_E^\alpha(\cdot))) \frac{\partial}{\partial u^\alpha}. \quad (35)$$

Notice that for each $t_0 \in \mathbb{R}$ we have the bundle given by restriction

$$\pi_t: E_t \rightarrow \Sigma_t \quad (36)$$

where $\pi_t = \pi|_{\Sigma_t}$ and $E_t = E|_{\Sigma_t}$. This bundle will play an important role.

Observe that the space of sections $\Gamma(\pi_t)$ is just the fiber $\tilde{\pi}^{-1}(t)$.

Definition

For each of these bundles we can induce the *restricted connection*, h_t^γ in the obvious way, i.e., the horizontal projector of the restricted connection is given by the restriction of the horizontal projector of the connection h^γ .

Now we will prove one of the main results, that is, $\tilde{\gamma}$ is a solution of the Hamilton-Jacobi equation.

This means that $\tilde{\gamma}^* \tilde{\Omega}_h = 0$ and in addition for any point $\sigma_E \in \tilde{E}$ which is an integral manifold of the corresponding restricted connection we have that $T\tilde{\gamma}(\sigma_E)(\tilde{X}^{h^\gamma})$ satisfies $i_{T\tilde{\gamma}(\sigma_E)(\tilde{X}^{h^\gamma})} \tilde{\Omega}_h = 0$.

The following remark clarifies the above terminology

Remark In the Hamilton–Jacobi theory on classical Hamiltonian systems (T^*Q, ω_Q, H) , a solution of the Hamilton-Jacobi problem is a (closed) section $\gamma : Q \rightarrow T^*Q$ of $\pi_Q : T^*Q \rightarrow Q$ (i.e. a closed 1-form on Q) such that $H \circ \gamma = \text{const}$. But $d\gamma = 0$ iff $\gamma^* \omega_Q = 0$, because the last equation just means that $\gamma(Q)$ is a lagrangian submanifold of (T^*Q, ω_Q) . This fact justifies the chosen notion of solution for the Hamilton-Jacobi problem in the current context.

Theorem

The section $\tilde{\gamma}$ satisfies:

- 1 $\tilde{\gamma}^* \tilde{\Omega}_h = 0$.
- 2 $i_{T\tilde{\gamma}(\sigma_E)(\tilde{X}^{h\gamma})} \tilde{\Omega}_h = 0$ for all $\sigma_E \in \tilde{E}$ which is an integral submanifold of the connection $h_{\tilde{\pi}(\sigma_E)}^\gamma$.

Lemma

If $d\gamma = 0$, then the following assertions are equivalent

- 1 $d(h \circ \mu \circ \gamma) = 0$
- 2
$$\frac{\partial H}{\partial u^\alpha} + \frac{\partial H}{\partial p_\beta^i} \frac{\partial \gamma_\beta^i}{\partial u^\alpha} + \frac{\partial H}{\partial p_\beta^0} \frac{\partial \gamma_\beta^0}{\partial u^\alpha} + \frac{\partial \gamma_\alpha^i}{\partial x^i} + \frac{\partial \gamma_\alpha^0}{\partial t} = 0$$

The space $\mathbb{T}^* \tilde{E}$ ($T^* \mathcal{E}^\tau$)

In this section we are going to introduce the phase space $\mathbb{T}^* \tilde{E}$, which in the terminology of GIMMSY is the space denoted by “ $T^* \mathcal{E}^t$ ”.

In order to do that, we have to start with a Lagrangian density.

Recall that $\pi: E \rightarrow M$ denotes a fiber bundle of rank n over an $(m + 1)$ -dimensional manifold and $J^1 \pi$ its first jet bundle, where we assume a Lagrangian density is given $\mathcal{L}: J^1 E \rightarrow \Lambda^{m+1} M$.

The submanifold Σ is endowed with a volume form η_Σ .

From now on, we assume that we have a slicing χ_M on the manifold M . We will also assume that we have a compatible slicing, accordingly with the following definition.

Definition

Let χ_M be a slicing on M , then a *compatible slicing* is a diffeomorphism

$$\chi_E: \mathbb{R} \times E|_{\Sigma} \rightarrow E$$

such that the following diagram is commutative

$$\begin{array}{ccc} \mathbb{R} \times E|_{\Sigma} & \xrightarrow{\chi_E} & E \\ \downarrow & & \downarrow \\ \mathbb{R} \times \Sigma & \xrightarrow{\chi_M} & M \end{array}$$

where the vertical arrows are the bundle projections.

Definition

Consider the vector field $\frac{\partial}{\partial t} \in \mathfrak{X}(\mathbb{R} \times E|_{\Sigma})$ constructed following the procedure introduced in the previous section to define ξ_M , then the vector field $\xi_E = (\chi_E)_*\left(\frac{\partial}{\partial t}\right)$ is called the *generator* of χ_E . Notice that this vector field projects onto ξ_M defined above.

Remark Remember that due to the slicing on M and the volume form η_{Σ} on Σ we can construct the volume form on M given by $dt \wedge \eta_{\Sigma}$. We are making some abuse of notation using dt to denote $\chi_M^* dt$.

Observe that a compatible slicing induces a trivialization on $J^1\pi^\dagger$ by pullback (we are now thinking about $J^1\pi^\dagger$ as a bundle of forms). So we have a diffeomorphism

$$\chi_{J^1\pi^\dagger} : \mathbb{R} \times (J^1\pi^\dagger)|_\Sigma \rightarrow J^1\pi^\dagger.$$

Definition

The *generator* of $\chi_{J^1\pi^\dagger}$ is the vector field defined by

$\xi_{J^1\pi^\dagger} = (\chi_{J^1\pi^\dagger})_* \left(\frac{\partial}{\partial t} \right)$, where $\frac{\partial}{\partial t} \in \mathfrak{X}(\mathbb{R} \times (J^1\pi^\dagger)|_\Sigma)$ is constructed as in the definition of ξ_E and ξ_M .

Definition

We define the *Cauchy data space*, and denote it by $\widetilde{J^1\pi}$, as the set of embeddings

$$\begin{aligned} \widetilde{J^1\pi} = \{ & \sigma_{J^1\pi} : \Sigma \rightarrow J^1\pi \text{ such that there exists, } \phi \in \Gamma(\pi) \\ & \text{satisfying } \sigma_{J^1\pi} = (j^1\phi) \circ \lambda, \text{ where } \lambda = \pi \circ \sigma_{J^1\pi} \in \widetilde{M} \} \end{aligned}$$

Using the extended and reduced Legendre transforms we can induce the maps

$$\begin{aligned}\widetilde{Leg}_{\mathcal{L}}: \quad \widetilde{J^1\pi} &\longrightarrow \widetilde{J^1\pi^\dagger} \\ \sigma_{J^1\pi} &\longrightarrow \widetilde{Leg}_{\mathcal{L}}(\sigma_{J^1\pi}) = Leg_{\mathcal{L}} \circ \sigma_{J^1\pi}\end{aligned}$$

and

$$\begin{aligned}\widetilde{leg}_{\mathcal{L}}: \quad \widetilde{J^1\pi} &\longrightarrow \widetilde{J^1\pi^\circ} \\ \sigma_{J^1\pi} &\longrightarrow \widetilde{leg}_{\mathcal{L}}(\sigma_{J^1\pi}) = Leg_{\mathcal{L}} \circ \sigma_{J^1\pi}\end{aligned}$$

We introduce now the phase space $\mathbb{T}^* \widetilde{E}$ and relate it with the previously defined space $\widetilde{J^1 \pi^0}$.

Recall that for each $t \in \mathbb{R}$ we have the bundle given by restriction to Σ_t that we described above. Remember that we used the notation

$$\pi_t: E_t \rightarrow \Sigma_t$$

where $E_t = E|_{\Sigma_t}$ and $\pi_t = \pi|_{\Sigma_t}$ and in the same way we have the analogous restrictions for all bundles involved in our constructions.

Remark The space of sections of each of these bundles is denoted in GIMMSY by \mathcal{E}_t , i.e., $\mathcal{E}_t = \Gamma(\pi_t)$. The points of \widetilde{E} can be identified with points in $\cup_{t \in \mathbb{R}} \mathcal{E}_t$. Let $\sigma_E \in \widetilde{E}$ and $\tilde{\pi}(\sigma_E) = t_0$, then we can consider $\sigma_E \circ (\chi_M)_{t_0}^{-1} \in \mathcal{E}_{t_0}$, where $(\chi_M)_{t_0}^{-1}$ is the inverse of the restriction to its image of $(\chi_M)_{t_0}$ as introduced previously. In that way, we have a bijection that allows us to identify $\widetilde{E} = \cup_{t \in \mathbb{R}} \mathcal{E}_t$. We assume that the spaces \mathcal{E}_t are infinite dimensional manifolds modeled on the corresponding functional space.

In the same way

$$(\pi_1^\dagger)_t: J^1\pi_t^\dagger \rightarrow \Sigma_t; \quad (\pi_1^\circ)_t: J^1\pi_t^\circ \rightarrow \Sigma_t, \quad (37)$$

where

$$\begin{aligned} J^1\pi_t^\circ &= J^1\pi_{|\Sigma_t}^\circ, & J^1\pi_t^\dagger &= J^1\pi_{|\Sigma_t}^\dagger, \\ (\pi_1^\circ)_t &= (\pi_1^\circ)_{|\Sigma_t}, & (\pi_1^\dagger)_t &= (\pi_1^\dagger)_{|\Sigma_t}. \end{aligned}$$

For a fixed t , taking a curve in \mathcal{E}_t it is easy to see that the *tangent vectors* of this manifold at a point σ_E are given by a section V of the bundle $\tau_{\text{Vert}}^t: \text{Vert}(\pi_t) \rightarrow \Sigma_t$ (τ_{Vert}^t is the natural projection), such that $\sigma_E = \tau_{\text{Vert}} \circ V$, that is

$$T_{\sigma_E} \mathcal{E}_t = \{V \in \Gamma(\tau_{\text{Vert}}), \text{ such that } \sigma_E = \tau_{\text{Vert}} \circ V\}.$$

So the *tangent bundle* is just

$$T\mathcal{E}_t = \bigcup_{\sigma_E \in \mathcal{E}_t} T_{\sigma_E} \mathcal{E}_t.$$

We proceed now to introduce the dual space of $T\mathcal{E}_t$. In order to do that, we need to introduce the dual of the bundle $\tau_{\text{Vert}}: \text{Vert}(\pi_t) \rightarrow \Sigma_t$, which we denote by

$$\pi_{\text{Vert}}: \text{Vert}^*(\pi_t) \rightarrow E_t.$$

The tensor product of the bundles $\pi_{\text{Vert}}: \text{Vert}^*(\pi_t) \rightarrow E_t$ and $\pi_t^*(\Lambda^m \Sigma_t) \rightarrow E_t$, which we refer to $\pi_{\otimes}: \text{Vert}^*(\pi_t) \otimes \pi_t^*(\Lambda^m \Sigma_t) \rightarrow E_t$ is the space whose sections will give us the dual elements of the tangent vectors.

Definition

The *smooth cotangent space* to \mathcal{E}_t at a point $\sigma_E \in \mathcal{E}_t$ is

$$T_{\sigma_E}^* \mathcal{E}_t = \{ \lambda: \Sigma \rightarrow V^* \pi_t \otimes \Lambda^n \Sigma_t \text{ such that } \pi_{\otimes} \circ \lambda = \sigma_E \}.$$

Definition

The *smooth cotangent bundle* is

$$T^* \mathcal{E}_t = \bigcup_{\sigma_E \in \mathcal{E}_t} T_{\sigma_E}^* \mathcal{E}_t.$$

There is a natural pairing between these two spaces. If $V \in T_{\sigma_E} \mathcal{E}_t$ and $\lambda \in T_{\sigma_E}^* \mathcal{E}_t$ the pairing is given locally by

$$\int_{\Sigma_t} \lambda(V)$$

Given coordinates adapted to the bundle $\pi_t: E_t \rightarrow \Sigma_t$, (x^i, u^α) , $1 \leq i \leq m$, $1 \leq \alpha \leq n$, local coordinates in the space $T\mathcal{E}_t$ are given by

$$(u^\alpha(\cdot), \dot{u}^\alpha(\cdot)) \rightarrow \dot{u}^\alpha(\cdot) \frac{\partial}{\partial u^\alpha}.$$

Then we have the corresponding coordinates in $T^*\mathcal{E}_t$

$$(u^\alpha(\cdot), \pi_\alpha(\cdot)) \rightarrow \pi_\alpha(\cdot) du^\alpha \otimes d^m x$$

where $d^m x = dx^1 \wedge \dots \wedge dx^m$.

Again, the $u^\alpha(\cdot)$, $\dot{u}^\alpha(\cdot)$ and $\pi_\alpha(\cdot)$ are functions that depend on the variables (x^1, \dots, x^m) and that belong to the chosen functional space.

Now, for each $t \in \mathbb{R}$ we have the maps defined by

$$\begin{aligned}
 R_t: \quad \widetilde{J^1\pi_t^\dagger} &\longrightarrow T^*\mathcal{E}_t \\
 \sigma_{J^1\pi^\dagger} &\longrightarrow R_t(\sigma_{J^1\pi^\dagger}): \quad T\mathcal{E}_t \quad \longrightarrow \quad \mathbb{R} \\
 &V \quad \longrightarrow \quad R_t(\sigma_{J^1\pi^\dagger})(V) = \int_{\Sigma_t} \phi^*(i_V\sigma_{J^1\pi^\dagger})
 \end{aligned}$$

and the map

$$\begin{aligned}
 R_t^\circ: \quad \widetilde{J^1\pi_t^\circ} &\longrightarrow T^*\mathcal{E}_t \\
 \sigma_{J^1\pi^\circ} &\longrightarrow R_t^\circ(\sigma_{J^1\pi^\circ}): \quad T\mathcal{E}_t \quad \longrightarrow \quad \mathbb{R} \\
 &V \quad \longrightarrow \quad R_t^\circ(\sigma_{J^1\pi^\circ})(V) = \int_{\Sigma_t} \phi^*(i_V\sigma_{J^1\pi^\circ})
 \end{aligned}$$

where $\phi = \nu^\circ \circ \sigma_{J^1\pi^\circ} \circ (\chi_M)_t^{-1}$. Notice that the contraction $i_V\sigma$ is well defined since V is a vertical vector field of the bundle π_t . In local coordinates

$$R_t(u^\alpha(\cdot), p(\cdot), p_\alpha^t(\cdot), p_\alpha^i(\cdot)) = (u^\alpha(\cdot), \pi_\alpha = p_\alpha^t(\cdot)).$$

Definition

For each $r \in \mathbb{R}$, the *instantaneous Hamiltonian function* is the function

$$\begin{aligned}\mathfrak{H}_t: T^*\mathcal{E}_t &\longrightarrow \mathbb{R} \\ \lambda &\longrightarrow \mathfrak{H}_t(\lambda) = - \int_{\Sigma_t} \sigma^*(i_{\xi_{J^1\pi^\dagger}} \Theta)\end{aligned}$$

where σ denotes any element in $Im(\widetilde{leg}_{\mathcal{L}}) \cap (R_t)^{-1}(\lambda)$.

Notice that in coordinates, if $\lambda = (u^\alpha(\cdot), \pi_\alpha(\cdot))$, that means that there exists a point $\sigma_{J^1\pi} \in \widetilde{J^1\pi}$ that locally reads $(t, u^\alpha(\cdot), u_i^\alpha(\cdot), u_0^\alpha(\cdot))$ and such that

$$\frac{\partial L}{\partial u_0^\alpha}(t, x^i, u^\alpha(x^i), u_i^\alpha(x^i), u_0^\alpha(x^i)) = \pi_\alpha(x^i) \quad \text{for all } (x^i).$$

Thus,

$$\int_{\Sigma_t} \lambda^*(i_{\xi_{J^1\pi^\dagger}} \Theta) = \int_{\Sigma_t} \left(-L + \frac{\partial L}{\partial u_0^\alpha} \frac{\partial u^\alpha}{\partial x^0}\right) d^m x_0.$$

Now we denote by $\mathbb{T}^* \tilde{E}$, the bundle over $\tilde{M} \equiv \mathbb{R}$ such that, for each $t \in \mathbb{R}$ the fiber is $T^* \mathcal{E}_t$. We use

$$\pi_{\mathbb{T}^* \tilde{E}}: \mathbb{T}^* \tilde{E} \rightarrow \mathbb{R}$$

to denote the projection onto \mathbb{R} . Notice that we have the following equality of sets $\mathbb{T}^* \tilde{E} = \bigcup_{t \in \mathbb{R}} T^* \mathcal{E}_t$.

Local coordinates in this bundle adapted to the fibration $\pi_{\mathbb{T}^* \tilde{E}}$ are

$$(t, u^\alpha(\cdot), \pi_\alpha(\cdot)) \rightarrow \pi_\alpha(\cdot) du^\alpha \otimes d^m x \in T^* \mathcal{E}_t.$$

where we also assume that ξ_M is given by $\frac{\partial}{\partial t}$ in this coordinates.

Remark Every tangent vector $X \in T_\lambda \mathbb{T}^* \tilde{E}$ can be locally written as

$$X = k \frac{\partial}{\partial t} + X_{u^\alpha} \frac{\partial}{\partial u^\alpha} + X_{\pi_\alpha} \frac{\partial}{\partial \pi_\alpha}.$$

On $T^*\mathcal{E}^t$ there is a form ω given in local coordinates by

$$\int_{\Sigma_t} du^\alpha \wedge d\pi_\alpha \otimes d^m x$$

we explain now that expression. Given two tangent vectors $X, Y \in T_\lambda \mathbb{T}^* \tilde{E}$ such that in adapted coordinates

$$X = X_t \frac{\partial}{\partial t} + X_{u^\alpha} \frac{\partial}{\partial u^\alpha} + X_{\pi_\alpha} \frac{\partial}{\partial \pi_\alpha}$$

$$Y = Y_t \frac{\partial}{\partial t} + Y_{u^\alpha} \frac{\partial}{\partial u^\alpha} + Y_{\pi_\alpha} \frac{\partial}{\partial \pi_\alpha}$$

then

$$\omega(X, Y) = \int_{\Sigma_t} (X_{u^\alpha} Y_{\pi_\alpha} - X_{\pi_\alpha} Y_{u^\alpha}) d^m x$$

Remark This form is obtained gluing together the canonical symplectic forms of the cotangent bundles $T^*\mathcal{E}_t$.

Definition

We define the *Hamiltonian function*, $\mathfrak{H}: \mathbb{T}^* \tilde{E} \rightarrow \mathbb{R}$ satisfying that for λ such that $\pi_{\mathbb{T}^* \tilde{E}}(\lambda) = t$, then $\mathfrak{H}(\lambda) = \mathfrak{H}_t(\lambda)$.

We construct the 2-form $\omega + d\mathfrak{H} \wedge dt$ on $\mathbb{T}^* \tilde{E}$.

Definition

A section $c(t)$ of the bundle $\mathbb{T}^* \tilde{E}$ is called a *dynamical trajectory* if

$$i_{\dot{c}(t)}(\omega + d\mathfrak{H} \wedge dt) = 0.$$

Notice that we are using that c is a curve and denoting by $\dot{c}(t)$ its derivative at time t .

Let ϕ be a section of π and $j^1\phi$ its first jet bundle. Set the section of π_1^\dagger given by $\sigma_{J^1\pi^\dagger} = \text{Leg}_{\mathcal{L}} \circ j^1\phi$ and construct the curve $c : \mathbb{R} \rightarrow \mathbb{T}^* \tilde{E}$

$$c(t) = R_t((\sigma_{J^1\pi^\dagger})|_{\Sigma_t}).$$

Proposition The section ϕ satisfies the Euler-Lagrange equations if and only if $c(t)$ is a dynamical trajectory.

The result below relates the dynamics on the manifold $J^1\pi^\circ$ with the dynamics on $\mathbb{T}^*\tilde{E}$. We introduce the map R which results from gluing the maps R_t

$$R: \widetilde{J^1\pi^\circ} \longrightarrow \mathbb{T}^*\tilde{E}$$

$$\sigma_{J^1\pi^\circ} \longrightarrow R_t(\sigma_{J^1\pi^\circ})$$

where $t = \widetilde{\pi}_1^\circ(\sigma_{J^1\pi^\circ})$.

Proposition We have $R^*(\omega + d\mathfrak{H} \wedge dt)(\sigma_{J^1\pi^\circ}) = \widetilde{\Omega}_h(\sigma_{J^1\pi^\circ})$ for all $\sigma_{J^1\pi^\circ} \in \text{Im}(\widetilde{\text{leg}}_{\mathcal{L}})$.

With this result at hand, we can now induce a Hamilton-Jacobi theory on the space $\mathbb{T}^*\widetilde{E}$ following the same pattern as above. Assume now that we have γ satisfying the Hamilton-Jacobi equation. We can define

$$\begin{aligned} \hat{\gamma}: \quad \widetilde{E} &\longrightarrow \mathbb{T}^*\widetilde{E} \\ \sigma_E &\longrightarrow \hat{\gamma}(\lambda) = R \circ \mu \circ \gamma \circ \sigma_E \end{aligned}$$

Remark We are assuming that $R \circ \widetilde{\text{leg}}_{\mathcal{L}}$ is a bijection between $\widetilde{J^1\pi}$ and $\mathbb{T}^*\widetilde{E}$, so in particular for any $\lambda \in \mathbb{T}^*\widetilde{E}$ there exists $\sigma_{J^1\pi^\circ} \in R^{-1}(\lambda) \cap \text{Im}(\widetilde{\text{leg}}_{\mathcal{L}})$.

As an immediate consequence of the previous theorem we conclude the following proposition.

Proposition Under the previous assumptions, we have:

- 1 $\hat{\gamma}^*(\omega + d\mathfrak{S} \wedge dt) = 0$
- 2 $i_{T\hat{\gamma}(\sigma_E)(X^{h\gamma})}(\omega + d\mathfrak{S} \wedge dt) = 0$ for all $\sigma_E \in \tilde{E}$ which is an integral submanifold of the connection $h_{\tilde{\pi}(\sigma_E)}^\gamma$.

We want to finish by setting some useful identifications.

- Using the vector field $\xi_{J^1\pi \circ}$ the space $\mathbb{T}^*\tilde{E}$ can be identified with $\mathbb{R} \times T^*\mathcal{E}_t$ for a fixed t .
- Under this identification the Hamiltonian function becomes a function on $\mathbb{R} \times T^*\mathcal{E}_t$ and the form ω becomes the canonical form on the cotangent bundle $\omega_{\mathcal{E}_t}$.

Happy birthday!
Feliz cumpleaños!
Wszystkiego Najlepszego!
Sto lat!