APPLICATIONES MATHEMATICAE 31,1 (2004), pp. 107–115

I. Malinowska (Lublin) D. Szynal (Lublin)

## ON A FAMILY OF BAYESIAN ESTIMATORS AND PREDICTORS FOR A GUMBEL MODEL BASED ON THE *k*TH LOWER RECORDS

Abstract. Bayesian estimation for the two parameters of a Gumbel distribution are obtained based on kth lower record values. Prediction, either point or interval, for future kth lower record values is also presented from a Bayesian view point. Some of the results of [4] can be obtained as special cases of our results (k = 1).

**1. Introduction.** Let  $\{X_n, n \ge 1\}$  be a sequence of independent identically distributed (iid) random variables with a cumulative distribution function (cdf) F(x) and a probability density function (pdf) f(x). The *j*th order statistic of a sample  $(X_1, \ldots, X_n)$  is denoted by  $X_{j:n}$ . For a fixed  $k \ge 1$  we define the sequence  $L_k(n), n \ge 1$ , of *k*th *lower record times* of  $\{X_n, n \ge 1\}$  as follows:

$$L_k(1) = 1,$$
  

$$L_k(n+1) = \min\{j > L_k(n) : X_{k:L_k(n)+k-1} > X_{k:j+k-1}\}, \quad n \ge 1.$$

The sequence  $\{Z_n^{(k)}, n \ge 1\}$  with

$$Z_n^{(k)} = X_{k:L_k(n)+k-1}, \quad n \ge 1,$$

is called the sequence of kth lower record values of  $\{X_n, n \ge 1\}$ . Note that  $Z_1^{(k)} = \max\{X_1, \ldots, X_k\}$  and  $Z_n^{(1)} = X_{L(n)}, n \ge 1$ , are lower record values.

<sup>2000</sup> Mathematics Subject Classification: 62F15, 62G99.

 $Key\ words\ and\ phrases:$  Bayesian inference, prediction,  $k{\rm th}$  record values, Gumbel model.

It is known that

(1)  

$$f_{Z_n^{(k)}}(z) = \frac{k^n}{(n-1)!} \left[-\ln F(z)\right]^{n-1} (F(z))^{k-1} f(z), \quad z \in \mathbb{R},$$

$$f_{Z_1^{(k)}, \dots, Z_n^{(k)}}(z_1, \dots, z_n) = k^n (F(z_n))^{k-1} f(z_n) \prod_{i=1}^{n-1} \frac{f(z_i)}{F(z_i)},$$

$$z_1 > \dots > z_n$$

(cf. [6]). A random variable X is said to have a *Gumbel distribution*, which we shall denote by  $G(\mu, \sigma)$ , if its cdf is

(2) 
$$F(x;\mu,\sigma) = \exp\left(-\exp\left(-\frac{x-\mu}{\sigma}\right)\right), \quad -\infty < x < \infty$$
  
 $(-\infty < \mu < \infty, \ \sigma > 0).$ 

The Gumbel pdf may be written in the form

(3) 
$$f(x;\mu,\sigma) = \frac{1}{\sigma} \exp\left(-\frac{x-\mu}{\sigma}\right) F(x;\mu,\sigma), \quad -\infty < x < \infty.$$

In [1], [2] the maximum likelihood (ML), best linear invariant (BLI) and minimum variance unbiased (MVU) estimators of the Gumbel parameters  $\mu$ ,  $\sigma$  were obtained. In those papers there are also given two types of predictors of the *s*th record values based on the first m (m < s) record values. The Bayesian estimators of the Gumbel parameters  $\mu$  and  $\sigma$  based on record values were furnished in [4]. Bayesian prediction of the *s*th lower record, both point or interval, was also presented.

In this note, the Bayesian estimators of the Gumbel parameters  $\mu$  and  $\sigma$  are obtained via the *k*th lower record values. Point and interval Bayesian prediction of the *s*th one of the *k*th record values is also obtained. In fact, families of the Bayesian estimators and predictors are given.

**2. Bayesian estimation of the parameters.** Suppose we observe m kth lower record values  $Z_1^{(k)} = x_1^{(k)}, Z_2^{(k)} = x_2^{(k)}, \ldots, Z_m^{(k)} = x_m^{(k)}$  from the Gumbel distribution  $G(\mu, \sigma)$ , with cdf and pdf given by (2) and (3), respectively. By (1) the likelihood function is as follows:

(4) 
$$L(\mu, \sigma | \underline{x}^{(k)}) = k^m \left( \prod_{i=1}^{m-1} \frac{f(x_i^{(k)})}{F(x_i^{(k)})} \right) [F(x_m^{(k)})]^{k-1} f(x_m^{(k)})$$
$$= \frac{k^m}{\sigma^m} \exp\left[ -m \left( \frac{\overline{x}^{(k)} - \mu}{\sigma} \right) - k \exp\left( -\frac{x_m^{(k)} - \mu}{\sigma} \right) \right],$$
$$x_1^{(k)} > x_2^{(k)} > \dots > x_m^{(k)},$$

where

$$\underline{x}^{(k)} = (x_1^{(k)}, x_2^{(k)}, \dots, x_m^{(k)}), \quad \overline{x}^{(k)} = \sum_{i=1}^m x_i^{(k)} / m.$$

Assume that a bivariate prior distribution of the parameters  $\mu$  and  $\sigma$  has the form

(5) 
$$g(\mu, \sigma) = g_1(\mu \mid \sigma)g_2(\sigma),$$

where

(6) 
$$g_1(\mu \mid \sigma) \propto 1/\sigma, \quad -\infty < \mu < \infty,$$

which is the Jeffreys non-informative prior distribution (cf. [5]) of  $\mu$  for a fixed value of  $\sigma$ , i.e. the distribution with pdf proportional to the square root of the Fisher information function  $(I(\sigma) = 1/\sigma^2)$ , and

(7) 
$$g_2(\sigma) = \frac{\beta^{\alpha}}{\Gamma(\alpha)\sigma^{\alpha+1}} e^{-\beta/\sigma}, \quad \sigma > 0; \ \alpha > 0, \ \beta > 0,$$

which is the conjugate prior distribution of  $\sigma$  for a fixed value of  $\mu$ . Substituting (6) and (7) in (5), we get

(8) 
$$g(\mu,\sigma) \propto \frac{\beta^{\alpha}}{\Gamma(\alpha)\sigma^{\alpha+2}} e^{-\beta/\sigma}, \quad -\infty < \mu < \infty; \ \sigma > 0.$$

By the Bayes theorem, the posterior distribution of  $\mu$  and  $\sigma$  is

(9) 
$$h(\mu, \sigma | \underline{x}^{(k)}) = AL(\mu, \sigma | \underline{x}^{(k)})g(\mu, \sigma), \quad -\infty < \mu < \infty, \ \sigma > 0,$$

where  $L(\mu, \sigma | \underline{x}^{(k)})$  is the likelihood function given by (4),  $g(\mu, \sigma)$  is the joint prior density given by (8) and A is the normalizing constant. If we apply (4) and (8) in (9), then the joint posterior density is

(10) 
$$h(\mu, \sigma \mid \underline{x}^{(k)}) = \frac{Ak^m}{\sigma^{m+\alpha+2}} \exp\left[-\frac{m}{\sigma}\left((\overline{x}^{(k)} - \mu) + \frac{\beta}{m}\right) - k \exp\left(-\frac{x_m^{(k)} - \mu}{\sigma}\right)\right], -\infty < \mu < \infty, \ \sigma > 0,$$

where

$$A = \frac{(\eta(\underline{x}^{(k)}))^{m+\alpha}}{\Gamma(m)\Gamma(m+\alpha)}$$

with

(11) 
$$\eta(\underline{x}^{(k)}) = m(\overline{x}^{(k)} - x_m^{(k)}) + \beta.$$

Assuming a squared error loss function, the Bayes estimate of a parameter is its posterior mean. Therefore, the Bayes estimate of the parameter  $\sigma$  is

109

given by

(12) 
$$\widehat{\sigma}_B^{(k)} = \int_0^\infty \sigma h_1(\sigma \,|\, \underline{x}^{(k)}) \, d\sigma,$$

where  $h_1(\sigma | \underline{x}^{(k)})$  is the marginal posterior density of  $\sigma$  obtained from (10) by integrating out the parameter  $\mu$ . Thus

(13) 
$$\widehat{\sigma}_{B}^{(k)} = \int_{0}^{\infty} \int_{-\infty}^{\infty} \sigma h(\mu, \sigma \mid \underline{x}^{(k)}) d\mu d\sigma$$
$$= Ak^{m} \int_{0}^{\infty} \int_{-\infty}^{\infty} \frac{1}{\sigma^{\alpha+m+1}} \exp\left(-\left(\frac{m}{\sigma}(\overline{x}^{(k)} - \mu) + \frac{\beta}{\sigma}\right)\right)$$
$$\times \exp\left(-k \exp\left(-\frac{x_{m}^{(k)} - \mu}{\sigma}\right)\right) d\mu d\sigma$$
$$= \frac{\eta(\underline{x}^{(k)})}{m + \alpha - 1},$$

where  $\eta(\underline{x}^{(k)})$  is given by (11). Similarly, the Bayes estimate of  $\mu$  is given by

$$\begin{aligned} \widehat{\mu}_{B}^{(k)} &= \int_{0}^{\infty} \int_{-\infty}^{\infty} \mu h(\mu, \sigma \,|\, \underline{x}^{(k)}) \, d\mu \, d\sigma \\ &= Ak^{m} \int_{0}^{\infty} \int_{-\infty}^{\infty} \mu \, \frac{1}{\sigma^{\alpha+m+2}} \exp\left(-\left(\frac{m}{\sigma}(\overline{x}^{(k)} - \mu) + \frac{\beta}{\sigma}\right)\right) \\ &\times \exp\left(-k \exp\left(-\frac{x_{m}^{(k)} - \mu}{\sigma}\right)\right) d\mu \, d\sigma. \end{aligned}$$

Hence after standard evaluations we get

(14) 
$$\widehat{\mu}_{B}^{(k)} = x_{m}^{(k)} - (\nu(m) + \ln k)\widehat{\sigma}_{B}^{(k)},$$

where

$$\nu(m) = \nu(m-1) - \frac{1}{m-1}, \quad m \ge 2,$$

and  $\nu(1) = \gamma$ , which is Euler's constant ( $\gamma = 0.57722$ ). Note that  $\hat{\sigma}_B^{(1)}$  and  $\hat{\mu}_B^{(1)}$  are the estimators given in [4], i.e.

$$\widehat{\sigma}_B^{(1)} = \frac{\eta(\underline{x}^{(1)})}{m+\alpha-1}, \quad \widehat{\mu}_B^{(1)} = x_m^{(1)} - \nu(m)\widehat{\sigma}_B^{(1)}.$$

When m = 1,

$$\widehat{\sigma}_B^{(1)} = \frac{\eta(\underline{x}^{(1)})}{\alpha} = \frac{\beta}{\alpha}, \quad \widehat{\mu}_B^{(1)} = X_1 - \gamma \frac{\beta}{\alpha}$$

110

are the estimators based on a sample of size 1. Our approach allows us to give the Bayesian estimators of  $\mu$  and  $\sigma$  using a sample of size k. Namely, for m = 1 we have

$$\widehat{\sigma}_B^{(k)} = \frac{\beta}{\alpha},$$

$$\widehat{\mu}_B^{(k)} = x_1^{(k)} - (\gamma + \ln k)\widehat{\sigma}_B^{(k)} = \max\{X_1, \dots, X_k\} - (\gamma + \ln k)\frac{\beta}{\alpha}.$$

Note that as  $\alpha$  and  $\beta$  tend to zero, the estimators (13), (14) tend to the estimators

$$\widehat{\sigma}_B^{(k)} = \frac{m(\overline{x}^{(k)} - x_m^{(k)})}{m - 1} = (m - 1)^{-1} \sum_{i=1}^{m-1} x_i^{(k)} - x_m^{(k)}$$
$$\widehat{\mu}_B^{(k)} = x_m^{(k)} - (\nu(m) + \ln k) \frac{m(\overline{x}^{(k)} - x_m^{(k)})}{m - 1},$$

respectively, which are for k = 1 the minimum variance unbiased estimators (MVUE) of the two parameters  $\sigma$  and  $\mu$ , given in [2], [3], i.e.

$$\hat{\sigma}_B^{(1)} = \frac{m(\overline{x}^{(1)} - x_m^{(1)})}{m - 1},$$
$$\hat{\mu}_B^{(1)} = x_m^{(1)} - \nu(m) \frac{m(\overline{x}^{(1)} - x_m^{(1)})}{m - 1}$$

**3. Bayesian prediction of future records.** Assume that we have m kth lower records  $Z_1^{(k)} = x_1^{(k)}, Z_2^{(k)} = x_2^{(k)}, \ldots, Z_m^{(k)} = x_m^{(k)}$  from the Gumbel distribution  $G(\mu, \sigma)$ . Based on such a sample, prediction, either point or interval, is needed for the sth one of the kth lower record values, 1 < m < s. Now let  $Y^{(k)} = Z_s^{(k)}$  be the sth lower record value, 1 < m < s. The conditional pdf of  $Y^{(k)}$  given the parameters  $\mu$  and  $\sigma$  and the observed value  $x_m^{(k)}$  of  $Z_m^{(k)}$  is

,

where  $f(\cdot), F(\cdot)$  are the pdf and cdf, respectively, and  $H(\cdot) = -\ln F(\cdot)$ . Combining the posterior density, given by (10), and the conditional density, given by (15), and integrating out the parameters  $\mu$  and  $\sigma$ , one may get the Bayesian predictive density function of  $Y^{(k)} = Z_s^{(k)}$  given the past m kth lower record values, in the form

$$\begin{split} q(y_s^{(k)} \mid \underline{x}^{(k)}) &= \int_{0}^{\infty} \int_{-\infty}^{\infty} f^*(y_s^{(k)} \mid \mu, \sigma) h(\mu, \sigma \mid \underline{x}^{(k)}) \, d\mu \, d\sigma \\ &= \frac{Ak^s}{\Gamma(s-m)} \int_{0}^{\infty} \int_{-\infty}^{\infty} \frac{1}{\sigma^{m+\alpha+3}} \\ &\times \left[ \exp\left(-\frac{y_s^{(k)} - \mu}{\sigma}\right) - \exp\left(-\frac{x_m^{(k)} - \mu}{\sigma}\right) \right]^{s-m-1} \\ &\times \exp\left(-\frac{y_s^{(k)} - \mu}{\sigma}\right) \exp\left[-k \exp\left(-\frac{y_s^{(k)} - \mu}{\sigma}\right)\right] \\ &\times \exp\left[k \exp\left(-\frac{x_m^{(k)} - \mu}{\sigma}\right)\right] \\ &\times \exp\left[k \exp\left(-\frac{x_m^{(k)} - \mu}{\sigma}\right)\right] \\ &\times \exp\left[-\frac{m}{\sigma}\left((\overline{x}^{(k)} - \mu) + \frac{\beta}{m}\right) - k \exp\left(-\frac{x_m^{(k)} - \mu}{\sigma}\right)\right] d\mu \, d\sigma. \end{split}$$
 We obtain

(16) 
$$q(y_s^{(k)} | \underline{x}^{(k)}) = \frac{\alpha + m}{B(m, s - m)} \sum_{i=0}^{s - m - 1} {\binom{s - m - 1}{i}} (-1)^i \\ \times \frac{(\eta(\underline{x}^{(k)}))^{\alpha + m}}{[m(\overline{x}^{(k)} - y_s^{(k)}) + i(x_m^{(k)} - y_s^{(k)}) + \beta]^{\alpha + m + 1}},$$

where  $\eta(\underline{x}^{(k)})$  is given by (11), and B(a, b) is the beta function, i.e.

$$B(a,b) = \int_{0}^{1} t^{a-1} (1-t)^{b-1} dt, \quad a > 0, \ b > 0.$$

The Bayes point predictor of the sth one of the kth lower record values is given by

$$\begin{split} E(y_s^{(k)} \mid \underline{x}^{(k)}) &= \int_{-\infty}^{x_m^{(k)}} y_s^{(k)} q(y_s^{(k)} \mid \underline{x}^{(k)}) \, dy_s^{(k)} \\ &= \frac{\alpha + m}{B(m, s - m)} \int_{-\infty}^{x_m^{(k)}} y_s^{(k)} \bigg\{ \sum_{i=0}^{s - m - 1} \binom{s - m - 1}{i} (-1)^i \\ &\times \frac{(\eta(\underline{x}^{(k)}))^{\alpha + m}}{[m(\overline{x}^{(k)} - y_s^{(k)}) + i(x_m^{(k)} - y_s^{(k)}) + \beta]^{\alpha + m + 1}} \bigg\} \, dy_s^{(k)}. \end{split}$$

Thus

(17) 
$$E(y_s^{(k)} | \underline{x}^{(k)}) = \frac{1}{B(m, s - m)} \sum_{i=0}^{s - m - 1} {s - m - 1 \choose i} (-1)^i \times \left[ \frac{x_m^{(k)}}{i + m} - \frac{\eta(\underline{x}^{(k)})}{(\alpha + m - 1)(m + i)^2} \right].$$

The Bayesian prediction bounds for  $Y^{(k)} = Z_s^{(k)}$  are obtained by evaluating  $\Pr(Y^{(k)} \ge \Theta \mid \underline{x}^{(k)})$  for some given value of  $\Theta$ . It follows from (16) that

$$\begin{aligned} \Pr(Y^{(k)} \geq \Theta \,|\, \underline{x}^{(k)}) &= \int_{\Theta}^{x_m^{(k)}} q(y_s^{(k)} \,|\, \underline{x}^{(k)}) dy_s^{(k)} \\ &= \frac{\alpha + m}{B(m, s - m)} \int_{\Theta}^{x_m^{(k)}} \sum_{i=0}^{s - m - 1} \binom{s - m - 1}{i} (-1)^i \\ &\times \frac{(\eta(\underline{x}^{(k)}))^{\alpha + m}}{[m(\overline{x}^{(k)} - y_s^{(k)}) + i(x_m^{(k)} - y_s^{(k)}) + \beta]^{\alpha + m + 1}} \, dy_s^{(k)}. \end{aligned}$$

Thus

(18) 
$$\Pr(Y^{(k)} \ge \Theta \,|\, \underline{x}^{(k)}) = \frac{1}{B(m, s - m)} \sum_{i=0}^{s-m-1} \binom{s-m-1}{i} (-1)^{i} \\ \times \frac{1}{m+i} \left[ 1 - \left(\frac{\eta(\underline{x}^{(k)})}{\eta(\underline{x}^{(k)}) + (m+i)(x_{m}^{(k)} - \Theta)}\right)^{\alpha+m} \right], \\ -\infty < \theta < x_{m}^{(k)}.$$

The  $(1-\tau)100\%$  predictive interval for  $Y^{(k)} = Z_s^{(k)}$  is obtained by evaluating both the lower,  $L(\underline{x}^{(k)})$ , and upper,  $U(\underline{x}^{(k)})$ , limits which satisfy

(19) 
$$\Pr(Y^{(k)} > L(\underline{x}^{(k)}) | \underline{x}^{(k)}) = 1 - \frac{\tau}{2}, \quad \Pr(Y^{(k)} > U(\underline{x}^{(k)}) | \underline{x}^{(k)}) = \frac{\tau}{2}.$$

Thus, one may obtain  $L(\underline{x}^{(k)})$  and  $U(\underline{x}^{(k)})$  by equating (18) to  $1 - \tau/2$  and  $\tau/2$ , respectively, and solving, numerically, the resulting equations. For the special case when s = m + 1, which is of special practical interest, (16) simplifies to

(20) 
$$q(y_{m+1}^{(k)} | \underline{x}^{(k)}) = m(m+\alpha) \frac{(\eta(\underline{x}^{(k)}))^{\alpha+m}}{[m(\overline{x}^{(k)} - y_{m+1}^{(k)}) + \beta]^{\alpha+m+1}}, \\ -\infty < y_{m+1}^{(k)} < x_m^{(k)} < \infty.$$

This gives the Bayes point predictor of the next kth lower record value

 $Y_{m+1}^{(k)} = Z_{m+1}^{(k)}$  in the form

(21) 
$$E(y_{m+1}^{(k)} | \underline{x}^{(k)}) = x_m^{(k)} - \frac{\eta(\underline{x}^{(k)})}{m(\alpha + m - 1)}$$

and the  $(1 - \tau)100\%$  Bayesian predictive bounds  $L(\underline{x}^{(k)})$  and  $U(\underline{x}^{(k)})$  for  $Y_{m+1}^{(k)}$  are given by

$$L(\underline{x}^{(k)}) = x_m^{(k)} + \frac{\eta(\underline{x}^{(k)})}{m} \left[ 1 - \left(\frac{\tau}{2}\right)^{-1/(m+\alpha)} \right],$$
$$U(\underline{x}^{(k)}) = x_m^{(k)} + \frac{\eta(\underline{x}^{(k)})}{m} \left[ 1 - \left(1 - \frac{\tau}{2}\right)^{-1/(m+\alpha)} \right]$$

Note that for m = 1 and k = 1,  $E(y_2^{(1)} | \underline{x}^{(1)}) = X_1 - \beta/\alpha$  is the Bayesian point predictor based on one observation. From (21) the point predictor based on a sample of size k is

$$E(y_2^{(k)} \mid \underline{x}^{(k)}) = \max\{X_1, \dots, X_k\} - \beta/\alpha.$$

Note that as  $\alpha$  and  $\beta$  tend to zero, the predictor (21) tends to the Bayesian point predictor

$$E(y_{m+1}^{(k)} | \underline{x}^{(k)}) = x_m^{(k)} - \frac{\overline{x}^{(k)} - x_m^{(k)}}{m-1}$$

which is for k = 1 the best linear unbiased predictor (BLUP), given in [2].

4. Characterization result. In this section we use a recurrence relation for conditional moments of nonadjacent kth record values to characterize the Gumbel distribution,  $G(\mu, \sigma)$ . By (1) we see that the conditional pdf of  $Z_m^{(k)} = x^{(k)}$  for given  $Z_s^{(k)} = t^{(k)}$ , 1 < m < s, is  $f(x^{(k)} | t^{(k)}) = D_{m,s}(t^{(k)})H^{m-1}(x^{(k)})[H(t^{(k)}) - H(x^{(k)})]^{s-m-1}r(x^{(k)}),$   $-\infty < t^{(k)} < x^{(k)} < \infty.$ 

where

$$r(x^{(k)}) = -\frac{dH(x^{(k)})}{dx^{(k)}}, \quad D_{m,s}(t^{(k)}) = \frac{\Gamma(s)}{\Gamma(m)\Gamma(s-m)H^{s-1}(t^{(k)})}.$$

Following the argument of Section 4 in [4] we have immediately a more general characterization of  $G(\mu, \sigma)$ .

THEOREM. The random variable X has the  $G(\mu, \sigma)$  distribution if and only if, for  $t^{(k)} < x^{(k)}$  and  $j = 1, 2, 3, \ldots$ , the recurrence relation

$$(m-1)E[\exp(-(j/\sigma)(Z_m^{(k)}-\mu)) | Z_s^{(k)} = t^{(k)}] = (j+m-1)E[\exp(-(j/\sigma)(Z_{m-1}^{(k)}-\mu)) | Z_s^{(k)} = t^{(k)}]$$

is satisfied for some  $k \geq 1$ .

114

Acknowledgments. The authors are grateful to the referee for useful suggestions and comments.

## References

- M. Ahsanullah, Estimation of the parameters of the Gumbel distribution based on the m record values, Comput. Statist. Quart. 6 (1990), 231–239.
- [2] —, Inference and prediction of the Gumbel distribution based on record values, Pak. J. Statist. 7(3) B (1991), 53–62.
- [3] —, *Record Statistics*, Nova Science, Commack, NY, 1995.
- [4] M. A. M. Ali Mousa, Z. F. Jaheen and A. A. Ahmed, Bayesian estimation, prediction and characterization for the Gumbel model based on records, Statistics 36 (2002), 65–74.
- [5] H. Jeffreys, *Theory of Probability*, Clarendon Press, Oxford, 1961.
- [6] P. Pawlas and D. Szynal, Relations for single and product moments of kth record values from exponential and Gumbel distributions, J. Appl. Statist. Sci. 7 (1998), 53-62.

I. MalinowskaD. SzynalDepartment of MathematicsInstitute of MathematicsLublin University of TechnologyMaria Curie-Skłodowska UniversityNadbystrzycka 38aPl. M. Curie-Skłodowskiej 120-618 Lublin, Poland20-031 Lublin, PolandE-mail: iwonamal@antenor.pol.lublin.plE-mail: szynal@golem.umcs.lublin.pl

Received on 28.4.2003; revised version on 22.10.2003

(1683)