

A REVIEW ON δ -STRUCTURABLE ALGEBRAS

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Abstract. In this paper we give a review on δ -structurable algebras. A connection between Malcev algebras and a generalization of δ -structurable algebras is also given.

1. Introduction. The history of nonassociative algebras, the subject of this paper, started with Hamilton, Cayley and Hurwitz and further with Artin and Zorn, who studied alternative and nearly associative algebras. Thereafter Freudenthal, Tits ([51]), I.L. Kantor ([32]-[34]) and Koecher ([36]) studied constructions of Lie algebras from nonassociative algebras and triple systems, in particular Jordan algebras, while B.N. Allison ([1], [2]) defined the concept of structurable algebras, containing Jordan algebras. Recently, we have studied constructions of Lie superalgebras as well as Lie algebras from triple systems ([23], [25], [27]-[28]). Hence within the general framework of (ε, δ) -Freudenthal Kantor triple systems, $\varepsilon, \delta = \pm 1$, (for short (ε, δ) -FKTSs) and the standard embedding Lie (super)algebra construction studied in [6], [7], [12]-[14], [25] (see also references therein) we defined δ -structurable algebras ([27]) as a class of nonassociative algebras with involution which coincides with the class of structurable algebras for $\delta = 1$ as intro-

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duced and studied in [1], [2]. Structurable algebras are a class of nonassociative algebras with involution that include Jordan algebras (with trivial involution), associative algebras with involution, and alternative algebras with involution. They are related to generalized Jordan triple systems (for short GJTSs) of 2nd order, or $(-1, 1)$ -FKTSs, as introduced and studied in [32], [33] and further studied in [3], [4], [31], [40]-[43], [49] (see also references therein). Their importance lies with constructions of five graded Lie algebras. For $\delta = -1$ the anti-structurable algebras ([27]) are a new class of nonassociative algebras that may similarly shed light on the notion of $(-1, -1)$ -FKTSs hence (by [6], [7], [29], [30]) on the construction of Lie superalgebras and Jordan algebras. Specially, nonassociative algebras such as Jordan and Lie (super)algebras ([11]) play an important role in many mathematical and physical subjects ([5], [8]-[12], [14], [24], [26], [35], [45], [46], [53]). We also note that the construction and characterization of these algebras can be expressed in terms of the notion of triple systems ([21], [22], [47]) by using the standard embedding method ([20], [37], [39], [48]). As a final comment of this section, we notice that our subject will be applied to normed algebras, in particular to the case of normed triple systems containing Jordan and Banach algebras.

2. Preliminaries

2.1. (ϵ, δ) -Freudenthal Kantor triple systems, δ -Lie triple systems, Lie (super)algebras. We are concerned in this paper with triple systems which have finite dimension over a field Φ of characteristic $\neq 2$ or 3 , unless otherwise specified.

DEFINITION 2.1. A vector space V over a field Φ endowed with a trilinear operation $V \times V \times V \rightarrow V$, $(x, y, z) \mapsto (xyz)$ is said to be a *GJTS of 2nd order* if

$$(ab(xyz)) = ((abx)yz) - (x(bay)z) + (xy(abz)) \quad (1)$$

$$K(K(a, b)x, y) - L(y, x)K(a, b) - K(a, b)L(x, y) = 0 \quad (2)$$

where $L(a, b)c := (abc)$ and $K(a, b)c := (acb) - (bca)$.

DEFINITION 2.2. A *Jordan triple system* (for short JTS) satisfies (1) and $(abc) = (cba)$.

We can generalize the concept of GJTS of 2nd order as follows ([12], [13], [16], [52]).

DEFINITION 2.3. For $\epsilon = \pm 1$ and $\delta = \pm 1$ a triple product that satisfies the identities

$$(ab(xyz)) = ((abx)yz) + \epsilon(x(bay)z) + (xy(abz)) \quad (3)$$

$$K(K(a, b)x, y) - L(y, x)K(a, b) + \epsilon K(a, b)L(x, y) = 0 \quad (4)$$

where

$$L(a, b)c := (abc), \quad K(a, b)c := (acb) - \delta(bca) \quad (5)$$

is called an (ϵ, δ) -FKTS.

REMARK. We note that $K(b, a) = -\delta K(a, b)$.

Let U be an (ϵ, δ) -FKTS and $V_k, k = 1, 2, 3$, be subspaces of U . We denote by (V_1, V_2, V_3) the subspace of U spanned by elements (x_1, x_2, x_3) , $x_k \in V_k, k = 1, 2, 3$.

DEFINITION 2.4. A subspace V of U is called an *ideal* of an (ε, δ) -FKTS U if the following relations hold $(V, U, U) \subseteq V$, $(U, V, U) \subseteq V$, $(U, U, V) \subseteq V$.

U is called *simple* if $(, ,)$ is not a zero map and U has no non-trivial ideal.

We denote triple products by (xyz) , $\{xyz\}$, $[xyz]$ and $\langle xyz \rangle$ depending on the case.

REMARK. We note that the concept of GJTS of 2nd order coincides with that of $(-1, 1)$ -FKTS. Thus we can construct the simple Lie algebras by means of the standard embedding method ([6], [12]-[25], [34], [52]).

For an (ε, δ) -FKTS U and $L(a, b)$ defined by (5) we denote

$$S(a, b) := L(a, b) + \varepsilon L(b, a), \quad A(a, b) := L(a, b) - \varepsilon L(b, a).$$

REMARK. We note that $S(a, b) = \varepsilon S(b, a)$.

$S(a, b)$ (respectively $A(a, b)$) is a derivation (respectively anti-derivation) of U ([28]).

DEFINITION 2.5. For $\delta = \pm 1$, a triple system $(a, b, c) \mapsto [abc]$, $a, b, c \in V$ is called a δ -Lie triple system (for short δ -LTS) if the following identities are fulfilled

$$\begin{aligned} [abc] &= -\delta[bac], \\ [abc] + [bca] + [cab] &= 0, \\ [ab[xyz]] &= [[abx]yz] + [x[aby]z] + [xy[abz]], \end{aligned}$$

where $a, b, x, y, z \in V$. An 1-LTS is a LTS, while a -1 -LTS is called an anti-LTS, by [13].

PROPOSITION 2.6 ([13], [20]). Let $U(\varepsilon, \delta)$ be a (ε, δ) -FKTS. If J is an endomorphism of $U(\varepsilon, \delta)$ such that $J(xyz) = \langle JxJyJz \rangle$ and $J^2 = -\varepsilon\delta Id$, then $(U(\varepsilon, \delta), [xyz])$ is a LTS (if $\delta = 1$) or an anti-LTS (if $\delta = -1$) with respect to the product (6).

$$[xyz] := \langle xJyz \rangle - \delta \langle yJxz \rangle + \delta \langle xJzy \rangle - \langle yJzx \rangle \tag{6}$$

COROLLARY 2.7. Let $U(\varepsilon, \delta)$ be a (ε, δ) -FKTS. Then the vector space $T(\varepsilon, \delta) = U(\varepsilon, \delta) \oplus U(\varepsilon, \delta)$ becomes a LTS (if $\delta = 1$) or an anti-LTS (if $\delta = -1$) with respect to the product

$$\left[\begin{pmatrix} a \\ b \end{pmatrix} \begin{pmatrix} c \\ d \end{pmatrix} \begin{pmatrix} e \\ f \end{pmatrix} \right] = \begin{pmatrix} L(a, d) - \delta L(c, b) & \delta K(a, c) \\ -\varepsilon K(b, d) & \varepsilon(L(d, a) - \delta L(b, c)) \end{pmatrix} \begin{pmatrix} e \\ f \end{pmatrix}. \tag{7}$$

REMARK. Thus we can obtain the standard embedding Lie algebra (if $\delta = 1$) or Lie superalgebra (if $\delta = -1$), $L(\varepsilon, \delta) = D(T(\varepsilon, \delta), T(\varepsilon, \delta)) \oplus T(\varepsilon, \delta)$, associated to $T(\varepsilon, \delta)$ where $D(T(\varepsilon, \delta), T(\varepsilon, \delta))$ is the set of inner derivations of $T(\varepsilon, \delta)$, i.e.

$$D(T(\varepsilon, \delta), T(\varepsilon, \delta)) := \left\{ \left(\begin{array}{cc} L(a, b) & \delta K(c, d) \\ -\varepsilon K(e, f) & \varepsilon L(b, a) \end{array} \right) \right\}_{span},$$

$$T(\varepsilon, \delta) := \left\{ \left(\begin{array}{c} x \\ y \end{array} \right) \middle| x, y \in U(\varepsilon, \delta) \right\}_{span}.$$

REMARK. $L(\varepsilon, \delta) = L_{-2} \oplus L_{-1} \oplus L_0 \oplus L_1 \oplus L_2$ is the 5-graded Lie (super)algebra such that $L_{-1} \oplus L_1 = T(\varepsilon, \delta)$, $D(T(\varepsilon, \delta), T(\varepsilon, \delta)) = L_{-2} \oplus L_0 \oplus L_2$ and $[L_i, L_j] \subseteq L_{i+j}$. This Lie (super)algebra construction is one of the reasons to study nonassociative algebras and triple systems.

2.2. δ -structurable algebras. Throughout the section it is assumed that $(\mathcal{A}, -)$ is a finite dimensional nonassociative unital algebra with involution (involutive anti-automorphism, i.e. $\overline{\overline{x}} = x$ and $\overline{xy} = \overline{y}\overline{x}$ for $x, y \in \mathcal{A}$) over Φ . The identity element of \mathcal{A} is denoted by 1.

REMARK. $\mathcal{A} = \mathcal{H} \oplus \mathcal{S}$, where $\mathcal{H} = \{a \in \mathcal{A} | \overline{a} = a\}$ and $\mathcal{S} = \{a \in \mathcal{A} | \overline{a} = -a\}$, by [1].

Put $[x, y] := xy - yx$, $[x, y, z] := (xy)z - x(yz)$, $x, y, z \in \mathcal{A}$. Note that (8) is valid.

$$\overline{[x, y, z]} = -[\overline{z}, \overline{y}, \overline{x}]. \quad (8)$$

Let L_x, R_x be defined by $L_x(y) := xy$, $R_x(y) := yx$, $x, y \in \mathcal{A}$. For $\delta = \pm 1$ define:

$${}^\delta V_{x,y} := L_{L_x(\overline{y})} + \delta(R_x R_{\overline{y}} - R_y R_{\overline{x}}), \quad (9)$$

$${}^\delta B_{\mathcal{A}}(x, y, z) := {}^\delta V_{x,y}(z) = (x\overline{y})z + \delta[(z\overline{y})x - (z\overline{x})y], \quad x, y, z \in \mathcal{A}. \quad (10)$$

DEFINITION 2.8. ${}^+B_{\mathcal{A}}(x, y, z)$ is called the *triple system obtained from the algebra $(\mathcal{A}, -)$* . We call ${}^-B_{\mathcal{A}}(x, y, z)$ the *anti-triple system obtained from the algebra $(\mathcal{A}, -)$* .

We shall write for short $V_{x,y} := {}^\delta V_{x,y}$, $B_{\mathcal{A}} := ({}^\delta B_{\mathcal{A}}, \mathcal{A})$.

REMARK. The upper left index notation is chosen in order not to be mixed with the upper right index notation of [1] which has a different meaning.

DEFINITION 2.9. A unital non-associative algebra with involution $(\mathcal{A}, -)$ is called a *δ -structurable algebra* if the following identity is fulfilled

$$[V_{u,v}, V_{x,y}] = V_{V_{u,v}(x),y} - V_{x,V_{v,u}(y)}. \quad (11)$$

$(\mathcal{A}, -)$ is called a *structurable algebra* ([1]) if the identity (11) is fulfilled for $V_{u,v} = {}^+V_{u,v}$, $V_{x,y} = {}^+V_{x,y}$, $u, v, x, y \in \mathcal{A}$, and we will call $(\mathcal{A}, -)$ an *anti-structurable algebra* if the identity (11) is fulfilled for $V_{u,v} = {}^-V_{u,v}$, $V_{x,y} = {}^-V_{x,y}$.

REMARK. If $(\mathcal{A}, -)$ is structurable then, in the terminology of [33], the triple system $B_{\mathcal{A}}$ is called a GJTS and by [8], $B_{\mathcal{A}}$ is a GJTS of 2nd order, i.e. satisfies (3) and (4).

DEFINITION 2.10. If $(\mathcal{A}, -)$ is anti-structurable then we call $B_{\mathcal{A}}$ an *anti-GJTS*.

Put $T_x := V_{x,1}$, $x \in \mathcal{A}$. Then, by (9), $T_x = L_x + \delta R_{x-\overline{x}}$ for $x \in \mathcal{A}$ thus $T_h = L_h$, $h \in \mathcal{H}$.

REMARK. (i) If $u = h \in \mathcal{H}$ and $x, y \in \mathcal{A}$, (11) becomes

$$[L_h, V_{x,y}] = V_{hx,y} - V_{x,hy}. \quad (12)$$

(ii) Suppose $-$ is the identity map and hence \mathcal{A} is commutative. If $(\mathcal{A}, -)$ is δ -structurable then \mathcal{A} is a Jordan algebra, by [27]. Conversely, by [36]§3, any Jordan algebra satisfies (12) if $V_{x,y} = {}^+V_{x,y}$ for $x, y \in \mathcal{A}$, hence it is structurable. By [27], any Jordan algebra is anti-structurable if $((hx)y)z - h((xy)z) = (x(yh))z - (xy)(hz)$, for $h, x, y, z \in \mathcal{A}$.

Clearly, the last identity is fulfilled by an associative algebra.

DEFINITION 2.11. For $s \in \mathcal{S}$ and $h \in \mathcal{H}$ we say that $(\mathcal{A}, -)$ is \mathcal{S} *skew-alternative* if $[s, x, y] = -[x, s, y]$ while $(\mathcal{A}, -)$ is \mathcal{H} *skew-alternative* if $[h, x, y] = -[x, h, y]$ for $x, y \in \mathcal{A}$.

REMARK. If $(\mathcal{A}, -)$ is \mathcal{S} skew-alternative then by [1], $[s, x, y] = -[x, s, y] = [x, y, s]$, $s \in \mathcal{S}$, $x, y \in \mathcal{A}$. If $(\mathcal{A}, -)$ is \mathcal{H} skew-alternative then by (8), $[h, x, y] = -[x, h, y] = [x, y, h]$, $h \in \mathcal{H}$, $x, y \in \mathcal{A}$.

PROPOSITION 2.12 ([27]). *If $(\mathcal{A}, \bar{})$ is structurable, then $(\mathcal{A}, \bar{})$ is \mathcal{S} skew-alternative. If $(\mathcal{A}, \bar{})$ is anti-structurable, then $(\mathcal{A}, \bar{})$ is \mathcal{H} skew-alternative.*

REMARK. Let $(\mathcal{A}, \bar{})$ be a δ -structurable algebra and let $\text{Der}(\mathcal{A}, \bar{})$ be the set of derivations of \mathcal{A} that commute with $\bar{}$. By [27], $T_{\mathcal{A}} \cap \text{Der}(\mathcal{A}, \bar{}) = 0$ and so we may define the *structure algebra* $\text{Str}(\mathcal{A}, \bar{}) := T_{\mathcal{A}} \oplus \text{Der}(\mathcal{A}, \bar{})$. This algebra plays an important role in the structure study of structurable algebras ([1]) and may play a role in the structure study of anti-structurable algebras, a theory to be presented elsewhere.

2.3. Examples. For examples of structurable algebras we refer to [1] and [2].

Let $\mathcal{M}_{m,n}(\Phi)$ denote the vector space of $m \times n$ matrices over Φ and for $x \in \mathcal{M}_{m,n}(\Phi)$ denote by x^{\top} the transposed matrix.

LEMMA 2.13 ([27]). *$(\mathcal{M}_{m,n}(\Phi), \{x, y, z\})$ is a $(-1, \delta)$ -FKTS, where $\{x, y, z\}$ is defined by*

$$\{x, y, z\} := xy^{\top}z + \delta(zy^{\top}x - zx^{\top}y), \quad x, y, z \in \mathcal{M}_{m,n}(\Phi) \tag{13}$$

THEOREM 2.14 ([27]). *$\mathcal{M}_{n,n}(\Phi)$ with the involution $x \mapsto x^{\top}$ is a δ -structurable algebra.*

EXAMPLE 2.15. *$(\mathcal{M}_{m,n}(\mathbf{C}), \{x, y, z\})$ is a $(-1, \delta)$ -FKTS, where $\{x, y, z\}$ is defined by*

$$\{x, y, z\} := x\bar{y}^{\top}z + \delta(z\bar{y}^{\top}x - z\bar{x}^{\top}y), \quad x, y, z \in \mathcal{M}_{m,n}(\mathbf{C}) \tag{14}$$

Indeed, it is straightforward calculation to show that the identities (3) and (4) hold. Hence $\mathcal{M}_{n,n}(\mathbf{C})$ with the involution $x \mapsto \bar{x}^{\top}$ is a δ -structurable algebra.

REMARK. By [25], the following construction of Lie superalgebras is obtained by the standard embedding method. If $U(-1, -1) := \mathcal{M}_{2n,m}(\Phi)$ with the product (13) then the corresponding standard embedding Lie superalgebra is $osp(2n|2m) = D(n, m)$ (as defined by [11]), hence the standard embedding Lie superalgebra of the anti-structurable algebra $\mathcal{M}_{2n,2n}(\Phi)$ is $osp(2n|4n)$. Similarly, if $U(-1, -1) := \mathcal{M}_{2n+1,m}(\Phi)$ with the product (13) then the corresponding standard embedding Lie superalgebra is $osp(2n+1|2m) = B(n, m)$ (as defined by [11]), hence the standard embedding Lie superalgebra of the anti-structurable algebra $\mathcal{M}_{2n+1,2n+1}(\Phi)$ is $osp(2n+1|4n+2)$.

3. Malcev algebras and generalized quasi δ -structurable algebras. We give in this section a connection between Malcev algebras ([38], [50]) and a generalization of δ -structurable algebras ([17], [18]).

DEFINITION 3.1. An algebra $(\mathcal{A}, \bar{})$ over Φ is called *quasi δ -structurable* if it is a δ -structurable algebra with no assumption of existence of identity element.

DEFINITION 3.2. An algebra \mathcal{A} over Φ is called *generalized structurable* ([17]) if it is a nonassociative algebra equipped with a non-trivial derivation $D(x, y)$, $x, y \in \mathcal{A}$, such that the following conditions are fulfilled:

- (i) $D(x, y) = D(y, x)$,
- (ii) $D(xy, z) + D(yz, x) + D(zx, y) = 0, \quad x, y, z \in \mathcal{A}$.

REMARK ([17]). A structurable algebra $(\mathcal{A}, \bar{})$ is a generalized structurable algebra.

Proof. Put $D(x, y)z := \frac{1}{3}[[x, y] + [\bar{x}, \bar{y}], z] + [z, y, x] - [z, \bar{x}, \bar{y}]$, where $[x, y] = xy - yx$, $[x, y, z] = (xy)z - x(yz)$, $x, y, z \in \mathcal{A}$. Then, by [17], the identities (i) and (ii) of definition 3.2 are fulfilled. ■

DEFINITION 3.3. An algebra A with multiplication $[x, y]$, $x, y \in A$ over a field of arbitrary characteristic, is called a *Malcev algebra* ([44]) if it satisfies the anticommutative law

$$[x, x] = 0, \quad (15)$$

and

$$J(x, y, [x, z]) = [J(x, y, z), x], \quad x, y, z \in A, \quad (16)$$

where $J(x, y, z) := [[x, y], z] + [[y, z], x] + [[z, x], y]$ is the *Jacobian*.

REMARK ([17]). A Malcev algebra A is a generalized structurable algebra.

Proof. Put

$$D(x, y) := [L_x, L_y] + L_{xy}, \quad (17)$$

where $[x, y] = xy - yx$, $L_x(y) := xy$, $x, y \in A$. Then, by [17], the identities (i) and (ii) of definition 3.2 are fulfilled. ■

PROPOSITION 3.4. *Let A be a Malcev algebra with involution defined by $\bar{x} := -x$, $x \in A$. Then A is a quasi structurable algebra.*

Proof. By (10), for $\delta = 1$, we have

$${}^+B_A(x, y, z) = {}^+V_{x,y}(z) = (x\bar{y})z + (z\bar{y})x - (z\bar{x})y = -(xy)z - (zy)x + (zx)y, \quad x, y, z \in A, \quad (18)$$

since $\bar{x} := -x$, $x \in A$. Thus ${}^+V_{x,y} = -([L_x, L_y] + L_{xy})(z) = -D(x, y)$, by (18) and (17), hence the identity (11) is fulfilled. ■

COROLLARY 3.5. *Let A be a Lie algebra with involution defined by $\bar{x} := -x$, $x \in A$. Then A is a quasi structurable algebra.*

PROPOSITION 3.6. *Let A be a Lie algebra with involution defined by $\bar{x} := -x$, $x \in A$. Then A is a (trivial) quasi anti-structurable algebra.*

Proof. By (10), for $\delta = -1$, we have

$${}^-B_A(x, y, z) = {}^-V_{x,y}(z) = (x\bar{y})z - (z\bar{y})x + (z\bar{x})y = -(xy)z + (zy)x - (zx)y, \quad x, y, z \in A, \quad (19)$$

since $\bar{x} := -x$, $x \in A$. Now, it follows ${}^-B_A(x, y, z) = -(xy)z - (yz)x - (zx)y$, by anti-symmetry and (19), hence ${}^-B_A(x, y, z) \equiv 0$, by Jacobi identity. ■

REMARK. From the last proposition and corollary it follows that Lie algebras are quasi δ -structurable algebras.

PROPOSITION 3.7. *A quasi anti-structurable algebra $(\mathcal{A}, {}^-)$ with involution defined by $\bar{x} := -x$, $x \in \mathcal{A}$ is a $(-1, -1)$ -JTS.*

Proof. Indeed, $K(x, y) \equiv 0$, $x, y \in \mathcal{A}$, where $K(x, y)$ is defined by (5), for $\delta = -1$. Then clearly the identities (3) and (4) are fulfilled, for $\varepsilon = \delta = -1$. ■

REMARK. If the assumption of finite dimensionality on algebras and triple systems is not required it seems that our concept can be generalized to Banach and Jordan algebras as well as to JB^* algebras and JB^* triples. In future work, we will discuss nonassociative normed algebras and triple systems containing Banach algebras.

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