## Flexibility of Lyapunov exponents

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Setting and questions

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Results in any dim.



#### State College, 2016

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Proofs 0000000



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Proofs

## SETTING AND QUESTIONS

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Proofs

Fix:

- a class of smooth dynamical systems (action of  $\mathbb{Z}_+$  or  $\mathbb{Z}$  or  $\mathbb{R}$ );
- one or more dynamically invariant quantities (like entropies or Lyapunov exponents with respect to a relevant measure).

Flexibility paradigm:

There should be no restrictions on the dynamical quantities apart from a few "obvious" ones.

☞Alena Erchenko's talk yesterday.

# Setting for today: conservative diffeos; Lyapunov exponents

- M = compact connected manifold of dimension  $d \ge 2$ .
- *m* = normalized volume measure on *M*.

If  $f: M \rightarrow M$  is a conservative (i.e., *m*-preserving) ergodic diffeomorphism, the *Lyapunov exponents* are:

$$\lambda_i(f) \coloneqq \lim_{n \to +\infty} \frac{1}{n} \log(i \text{-th singular value of } Df^n(x))$$

(for *m*-a.e.  $x \in M$ ).

Note: 
$$\lambda_1(f) \geq \cdots \geq \lambda_d(f)$$
 and  $\sum_{i=1}^d \lambda_i(f) = 0$ .

• Lyapunov spectrum  $\vec{\lambda}(f) = (\lambda_1(f), \dots, \lambda_d(f))$ . • The Lyapunov spectrum is called *simple* if these

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abore are all different

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## Problem

Which Lyapunov spectra  $\vec{\lambda}(f) = (\lambda_1(f), \dots, \lambda_d(f))$  may appear for  $C^{\infty}$  ergodic diffeomorphisms f?

Apart from the obvious restrictions that the  $\lambda_i$ 's should be ordered and their sum should be zero, no other conditions are known.

## Conjecture (Weak flexibility – general)

Fix (M, m). Given  $\xi_1 \ge \cdots \ge \xi_d$  with  $\sum_i \xi_i = 0$ , then there exists ergodic  $f \in \text{Diff}_m^{\infty}(M)$  such that  $\left| \vec{\lambda}(f) = (\xi_1, \dots, \xi_d) \right|$ .

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## Existence of ergodic smooth diffeomorphisms

- All exponents zero: Anosov–Katok (early 70's)
- No exponents zero: Katok (1979) for d = 2; Dolgopyat–Pesin (2002)

Even more ambitious: fix homotopy class.

### Conjecture (Strong flexibility – general)

Fix (M, m). Fix a connected component  $C \subseteq \text{Diff}_m^{\infty}(M)$ . Given  $\xi_1 \geq \cdots \geq \xi_d$  with  $\sum_i \xi_i = 0$ , then there exists ergodic  $f \in C$  such that  $\overline{\lambda}(f) = (\xi_1, \dots, \xi_d)$ .

Terminology:

- "Strong" means prescribed homotopy class.
- "Weak" means we don't care about homotopy class

Let's work on the more manageable class of *conservative Anosov smooth diffeomorphisms* (which are automatically ergodic).

Conjecture (Weak flexibility – Anosov)

Given  $\xi_1 \ge \cdots \ge \xi_d$  with  $\sum_i \xi_i = 0$  and each  $\xi_i \ne 0$ , then there exists an Anosov  $f \in \text{Diff}_m^{\infty}(\mathbb{T}^d)$  such that

 $\vec{\lambda}(f) = (\xi_1, \ldots, \xi_d)$ 

As a corollary of our main result, we prove this conjecture in the case of simple spectrum:  $\xi_1 > \cdots > \xi_d$ .

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# For Anosov, there is a new "obvious" restriction (given the homotopy class)

Given a conservative smooth Anosov  $f: \mathbb{T}^d \to \mathbb{T}^d$ , take  $L = \pi_1(f) \in GL(d, \mathbb{Z})$ ; then f is homotopic (and topologically conjugate) to the automorphism  $F_L: \mathbb{T}^d \to \mathbb{T}^d$ . Let u be the unstable index (dim $E^u$ ) of either f or  $F_L$ . Then:

$$\sum_{i=1}^{u} \lambda_i(f) \leq \sum_{i=1}^{u} \lambda_i(L)$$

"entropy condition"

Proof:

 $\sum_{i=1}^{u} \lambda_i(f) = h_m(f)$  (Pesin's formula)  $\leq h_{top}(f)$  (variational principle)  $= h_{top}(F_L)$  (topological conjugacy)  $= \sum_{i=1}^{u} \lambda_i(L)$ 

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Are there other restrictions?

### Problem (Strong flexibility – Anosov)

Let  $L \in GL(d, \mathbb{Z})$  be hyperbolic matrix with unstable index u. Given  $\xi_1 \ge \cdots \ge \xi_u > 0 > \xi_{u+1} \ge \cdots \ge \xi_d$  such that

$$\sum_{i=1}^d \xi_i = 0$$
 and  $\sum_{i=1}^u \xi_i \leq \sum_{i=1}^u \lambda_i(L)$ ,

does there exist a conservative Anosov diffeomorphism f homotopic to  $F_L$  such that  $\vec{\lambda}(f) = (\xi_1, \dots, \xi_d)$ ?

<sup>IP</sup>More about this problem in a couple of minutes.

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# A RESULT FOR $\mathbb{T}^3$

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# **Dominated splittings**

A simple dominated splitting (SDS) for  $f \in \text{Diff}_m^1(M)$  is a *Df*-inv. splitting

 $TM = E_1 \oplus \cdots \oplus E_d$  with each dim  $E_i = 1$ 

such that  $\exists n_0 > 0$  s.t.  $\forall x \in M$  and all unit vectors  $v_1 \in E_1(x), \ldots, v_d \in E_d(x)$ ,

$$||Df^{n_0}(v_1)|| > \cdots > ||Df^{n_0}(v_d)||.$$

Then Lyapunov exponents are given by integrals:

$$\lambda_i(f) = \int \log \|Df|_{E_i}\|\,dm$$

and the spectrum is simple:  $\lambda_1(f) > \cdots > \lambda_d(f)$ .

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## Theorem (B-K-RH)

Fix  $L \in GL(3, \mathbb{Z})$  hyperbolic matrix with simple spectrum. Suppose  $\xi_1 > \xi_2 > \xi_3$  have the same signs as  $\lambda_1(L) > \lambda_2(L) > \lambda_3(L)$ ,

$$\xi_1 \le \lambda_1(L),$$
  
 $\xi_1 + \xi_2 \le \lambda_1(L) + \lambda_2(L), \text{ and }$   
 $\xi_1 + \xi_2 + \xi_3 = 0.$ 

Then there exists a Anosov  $f \in \text{Diff}_m^{\infty}(T)$  with SDS homotopic to  $F_L$  such that  $\vec{\lambda}(f) = (\xi_1, \xi_2, \xi_3)$ .

Furthermore, the converse holds.

Note that there is an **extra** not-so-obvious inequality (related to SDS).

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# Proof of the "converse" (inequalities are necessary)

- Taking inverses if necessary, assume  $\lambda_2(L) > 0$ , i.e., dim  $E^u = 2$ .
- Then  $\lambda_1(f) + \lambda_2(f) \le \lambda_1(L) + \lambda_2(L)$  is the "entropy condition".
- By contradiction, suppose that  $\lambda_1(f) > \lambda_1(L)$ .
- For a.e. x, and  $n \gg 1$  the curve  $\Gamma = f^n(W_{loc}^{uu}(x))$  has length  $\gtrsim e^{\lambda_1(f)n}$ .
- The distance between the endpoints of the lifted curve  $\tilde{\Gamma} \subset \mathbb{R}^3$  is ~  $e^{\lambda_1(L)n}$  (much smaller).
- This contradicts Brin–Burago–Ivanov'09 ( $\widetilde{W}^{uu}$  leaves are quasi-isometric).

Here is a more modest version of the Problem "Strong Flexibility – Anosov":

#### Problem

Is there a  $C^{\infty}$  conservative Anosov diffeo of  $\mathbb{T}^3$  with dim  $E^u = 2$  and  $\lambda_1(f) > \lambda_1(L)$  (where  $L \in GL(3, \mathbb{Z})$  is the homotopy type)?

If cannot have a simple dominated splitting, so it cannot be a  $C^1$ -perturbation of its linear part. If The Pesin 1-dim manifolds  $W^{uu}(x)$  should be very twisted inside the 2-dim leaves  $W^u(x)$ .

Idea: Try  $f = L^1$ -perturbation of another (well-chosen) linear Anosov...

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## MAIN RESULT

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Proofs 0000000

# The majorization partial order

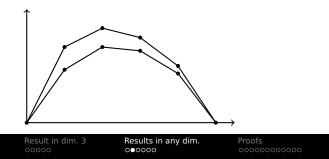
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Let  $\vec{\xi} = (\xi_1, \dots, \xi_d)$  be an ordered vector  $(\xi_i \ge \xi_{i+1})$  with  $\xi_1 + \dots + \xi_d = 0$ .

Define a partial order on the set of such vectors:

 $\vec{\xi} \preccurlyeq \vec{\eta} \iff \xi_1 + \dots + \xi_i \le \eta_1 + \dots + \eta_i \quad \forall i \in \{1, \dots, d-1\}.$ We say  $\vec{\xi}$  is majorized by  $\vec{\eta}$ . If the inequalities are strict:  $\vec{\xi} \prec \vec{\eta}$  ( $\vec{\xi}$  is strictly majorized by  $\vec{\eta}$ .)

Two concave graphs, one above the other:



Let *M* be a compact manifold. Let  $AS \subset \text{Diff}_m^{\infty}(M)$  be be formed by Anosov diffeomorphisms with SDS (simple dominated splitting).

#### Theorem (B,K,RH)

Let  $f \in \mathcal{AS}$ ; let  $u = \dim E^u$ . Let  $\vec{\xi} = (\xi_1, \dots, \xi_d)$  be such that:  $\xi_1 > \dots > \xi_u > 0 > \xi_{u+1} > \dots > \xi_d$  $\xi_1 + \dots + \xi_d = 0$ ,  $\vec{\xi} \prec \vec{\lambda}(f)$  (strict majorization)

Then there exists a continuous path  $(f_t)_{t \in [0,1]}$  in AS starting from  $f_0 = f$  such that  $\vec{\lambda}(f_1) = \vec{\xi}$ .

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The proof is essentially a optimized and global version of **Baraviera–Bonatti** perturbation method, which needs:

- special adapted metrics (a la Gourmelon) with a new "L<sup>1</sup>-property";
- careful linear algebra (in order to mix several exponents simultaneously);
- tower methods (Rokhlin + Vitali).
- More details later.

### Corollary

For all nonzero numbers  $\xi_1 > \cdots > \xi_d$  whose sum is 0, there exists a  $C^{\infty}$  conservative Anosov diffeo  $f : \mathbb{T}^d \to \mathbb{T}^d$ with SDS such that  $\vec{\lambda}(f) = \vec{\xi} := (\xi_1, \dots, \xi_d)$ .

#### Proof.

Given  $\vec{\xi}$ , we take a linear Anosov  $L \in SL(d, \mathbb{Z})$  with the same unstable index, and "large" enough so that:

$$\vec{\lambda}(L) \succ \vec{\xi}$$
.

Then we apply the Main Theorem.

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## PROOF

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Proofs 00000000

As the proof of our main result relies on the Baraviera–Bonatti strategy, let us recall (a particular case of) their result:

#### Theorem (Baraviera–Bonatti, 2003)

Let f be a stably ergodic  $C^{\infty}$  conservative diffeomorphism with a simple dominated splitting. Then, for each  $i \in \{1, ..., d\}$ , there exists a  $C^{\infty}$ conservative diffeomorphism  $\tilde{f}$  arbitrarily  $C^1$ -close to f such that  $\lambda_i(\tilde{f}) \neq \lambda_i(f)$ .

#### Remark

Origin of the method: Shub–Wilkinson, 2000.

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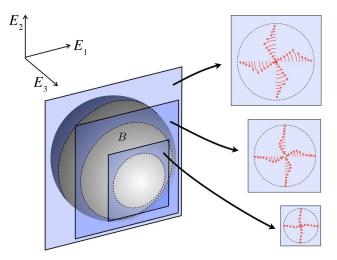
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Proofs ●oooooooooooo

# Construction of the Baraviera–Bonatti perturbation

- Consider e.g. *d* = 3, *i* = 1.
- Take a small ball *B* centered at a non-periodic point.
- Perturb f inside B in a conservative way, approximately preserving and rotating the E<sub>1</sub> ⊕ E<sub>2</sub> planes, obtaining some f̃. (See fig. next slide)
- Then one can show that the first two exponents "mix" a little (while the third almost doesn't move); in particular,  $\lambda_1(\tilde{f}) < \lambda_1(f)$ .

## Rotating the $E_1 \oplus E_2$ planes



Rem: On each sphere concentric to  $\partial B$  the perturbation is a rotation. Figure by Avila–Crovisier–Wilkinson

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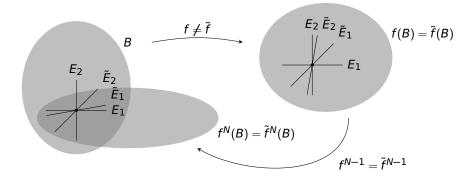
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Proofs ००●००००००००

## Why does $\lambda_1$ drop?

The new bundle  $\tilde{E}_3$  is very close to the original  $E_3$ . The other bundles move as follows:



## So $N \gg 1 \Rightarrow \measuredangle(\tilde{E}_1, E_1) \ll 1$ on B.

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Proofs ०००●०००००००

# Why does $\lambda_1$ drop? (continued)

To simplify notation, assume  $T_X M = \mathbb{R}^d$ ,  $E_i = \mathbb{R}e_i$ . Take nowhere-zero vector fields  $v \equiv e_1$  and  $\tilde{v}$  tangent to  $E_1$  and  $\tilde{E}_1$ , respectively.

The seminorm  $||(a_1, ..., a_d)||_1 := |a_1|$  is good enough to compute the first Lyapunov exponent:

$$\lambda_{1}(f) = \int_{M} \log \frac{\|Df(x)v(x)\|_{1}}{\|v(x)\|_{1}} dm(x)$$
$$\lambda_{1}(\tilde{f}) = \int_{M} \log \frac{\|D\tilde{f}(x)\tilde{v}(x)\|_{1}}{\|\tilde{v}(x)\|_{1}} dm(x)$$

The two integrands are everywhere equal, except on *B*. On *B* we use that  $\tilde{v} \simeq v$  to compare the integrals. Jensen inequality  $\Rightarrow \lambda_1(\tilde{f}) < \lambda_1(f)$ .

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Proofs ००००●०००००० We rotate several  $E_i \oplus E_{i+1}$  planes so to manipulate (i.e., "mix") all the Lyapunov exponents simultaneously (careful Linear Algebra).

In order to maximize the effect of the Baraviera–Bonatti-like perturbations, it will be fundamental to use especially **adapted coordinates**.

# A new adapted metric for dominated splitting

Given the simple dominated splitting  $TM = E_1 \oplus \cdots \oplus E_d$ and a Riemannian norm  $\|\|\cdot\|\|$ , define *expansion functions*  $\rho_1, \ldots, \rho_d \colon M \to \mathbb{R}$ :

 $\rho_j(x) \coloneqq \log \frac{\||Df(x)v|\|}{\||v|\|} \quad (\text{arbitrary nonzero } v \in E_j(x)).$ 

Each  $\rho_j$  is continuous and its integral is  $\lambda_j(f)$ . We say that the Riemannian metric is *adapted* if:

 $\rho_1(x) > \rho_2(x) > \cdots > \rho_d(x) \quad \text{and} \quad E_i \perp E_j \; \forall i \neq j \,.$ 

Proposition (Adapted metric with  $L^1$  estimate)

Given  $\varepsilon > 0$ , we can choose an adpated metric such that  $\int_{M} |\rho_{i}(x) - \lambda_{i}(f)| dm(x) < \varepsilon$  for every *i*.

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Proofs ○○○○○○●○○○○○ Since we are assuming simple dominated splitting, the situation becomes essentially one-dimensional. The proof is a very simple and explicit averaging trick:

$$v \in E_j(x) \Rightarrow |||v||| \coloneqq \prod_{n=0}^{N-1} ||Df^n(x)v||^{1/N} \quad (N \gg 1)$$

We must be able to change (i.e., "mix") the Lyapunov spectrum  $\vec{\lambda}(f)$  of f by some small but constant amount that depends **not on** f **but only on**  $\vec{\lambda}(f)$  **itself.** 

- We take a disjoint family of small "good" balls  $B_i$  (in the adapted coordinates) whose union has  $N \gg 1$  disjoint iterates from itself (a tower).
- On each of these balls, we do Baraviera–Bonatti-like perturbations (rotating several planes).
- By Rokhlin Lemma, we can take  $m(\bigsqcup B_i)$  approximately equal to 1/N.

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# Sketch of proof of the main theorem (cont)

- Actually we will take height  $N \simeq C/GAP$ , where  $C \gg 1$  is fixed and  $GAP := \min_j [\lambda_j(f) \lambda_{j+1}(f)]$ . Using the  $L^1$  estimate for the adapted metrics, we see that for most points, time N is sufficient for cones to contract and therefore for the Baraviera–Bonatti perturbation to have a controllable and significant effect on the Lyapunov exponents.
- More precisely, the effect on the Lyapunov exponents is approximately proportional to

$$m(\bigsqcup B_i) \sim \frac{1}{N} \sim O(\text{GAP}).$$

 So we are able to change the Lyapunov spectrum by some small amount that depends not on f but only on λ(f) itself. Done!

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Proofs ○○○○○○○○●○○ In the situation of our flexibility theorem on  $\mathbb{T}^3$ , the starting Anosov diffeomophism is  $F_L$ . In particular, the invariant foliations are smooth. We can apply Baraviera–Bonatti preserving the (2-dim) center-unstable foliation (say) and therefore keeping  $\overline{\lambda_3(f_t) = \lambda_3(L)}$  along the deformation.

So we are able to realize spectra  $\preccurlyeq \vec{\lambda}(L)$  (non-strict majorization).

(In large dimension it doesn't work so well...)

## EXTENSIONS OF THE RESULTS?

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Proofs oooooooooooooo

Our (upgraded Baraviera–Bonatti) method is very adaptable: being Anosov is not really important, but domination is.

Beyond PH/dominated systems, we should be able to allow domination to degenerate in a controlled way in a small "singular" set (like Katok'79, Dolgopyat–Pesin'02).

So the general flexibility conjectures (arbitrary manifold) seem attackable, at least in some cases...

Another direction: symplectic maps.