

Can you hear the shape of a drum ? and Deformational Spectral Rigidity

V. Kaloshin

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- Laplace spectrum, Inverse problems
- Length spectrum and Laplace spectrum
- Spectral Rigidity for domains
- Spectral Rigidity for Anosov geodesic flow,
Burns-Katok Conjecture
- Linearized Isospectral Operators and X-ray
transforms

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Can you hear the shape of a drum?

M. Kac'66: Can you hear the shape of a drum?



Can you hear the shape of a drum?

Consider the Dirichlet problem in a domain $\Omega \subset \mathbb{R}^2$.

$$\begin{cases} \Delta u + \lambda^2 u = 0 \\ u|_{\partial\Omega} = 0. \end{cases}$$

$\Delta(\Omega) := \{0 < \lambda_1 \leq \lambda_2 \leq \dots\}$ — Laplace spectrum.

Example 1 Let $\Omega_C = [0, \pi] \times [0, \pi] \ni (x, y)$. For any pair $k, m \in \mathbb{Z}_+ \setminus 0$ let

$$u(x, y) = \sin kx \cdot \sin my \quad \text{and} \quad \lambda = \sqrt{k^2 + m^2}.$$

The Laplace spectrum $\Delta(\Omega_C) = \cup_{k, m \in \mathbb{Z}_+ \setminus 0} \sqrt{k^2 + m^2}$.

Question (M. Kac'66) Does $\Delta(\Omega)$ determine Ω up to isometry?

Weyl law (H. Weyl'11) $N(\lambda) := \#$ eigenvalues (w multiplicity) in $(0, \lambda^2]$, then

$$\lim_{\lambda \rightarrow \infty} \lambda^{-1} N(\lambda) = (4\pi)^{-1} \text{Area}(\Omega).$$

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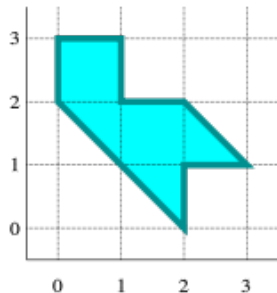
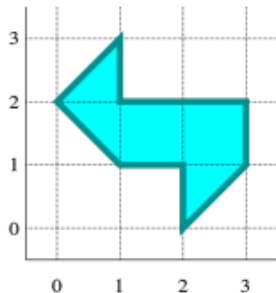
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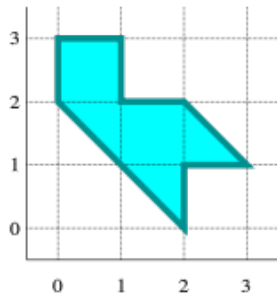
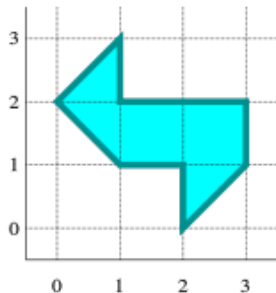
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Gordon–Webb–Wolpert'92



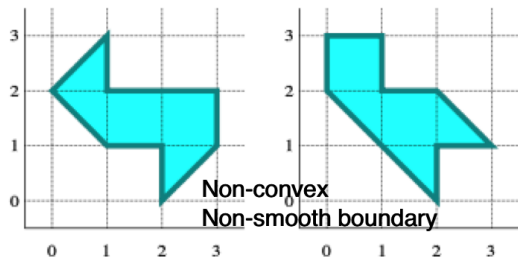
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Consider domains with a smooth or an analytic boundary!

Osgood-Phillips-Sarnak A C^∞ isospectral set is compact.

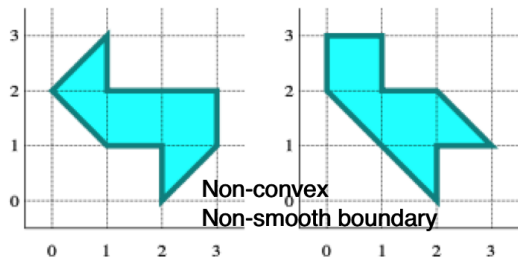
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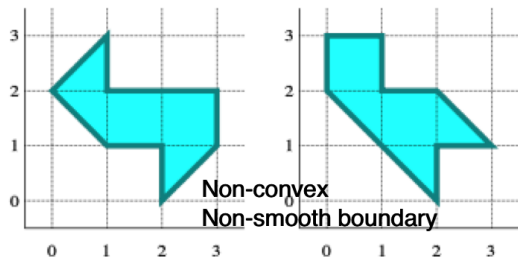
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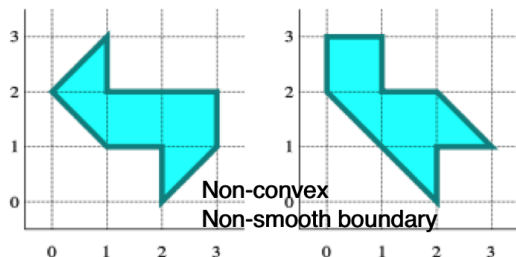
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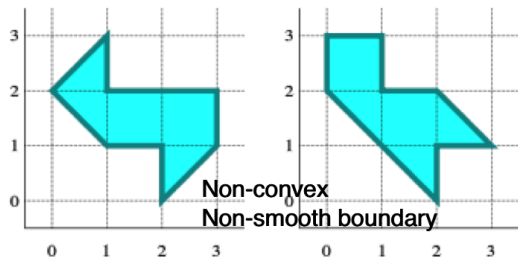
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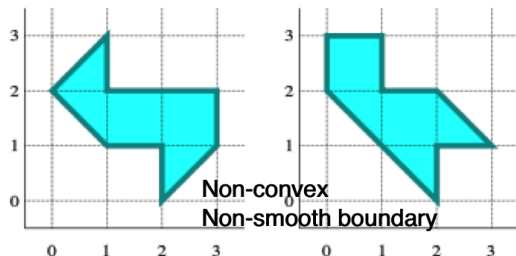
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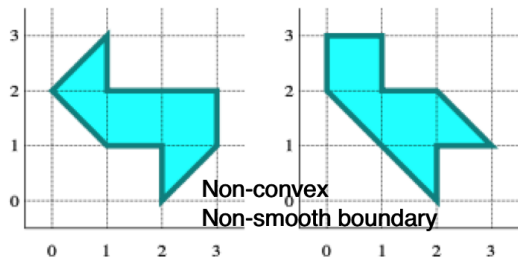
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Can you hear the shape of a Riemannian manifold?

Let (M, g) be a Riemannian compact manifold. Consider the spectrum of the Laplace-Beltrami operator $\Delta(M, g)$.

Question Does $\Delta(M, g)$ determine (M, g) up to an isometry?

Sunada, Vingeras* \exists isospectral sets of arbitrary finite cardinality.

Conjecture (Sarnak'90) A C^∞ isospectr. set consists of isolated points.

Call Ω *spectrally rigid* (SR) if any smooth isospectral deformation $\{\Omega_t\}_t$ is an isometry, i.e. $\Delta(\Omega_t) \equiv \Delta(\Omega_0)$.

Conjecture (Sarnak'90) Any planar domain is SR.

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Conjecture (Sarnak'90) Any planar domain is SR.

Can you hear the shape of a Riemannian manifold?

Let (M, g) be a Riemannian compact manifold. Consider the spectrum of the Laplace-Beltrami operator $\Delta(M, g)$.

Question Does $\Delta(M, g)$ determine (M, g) up to an isometry?

Sunada, Vingeras* \exists isospectral sets of arbitrary finite cardinality.

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Length spectrum and Laplace spectrum

Let $\Omega \subset \mathbb{R}^2$ be a strictly convex domain. Define

the length spectrum $\mathcal{L}(\Omega) := \cup_P L(P) \cup \mathbb{N} L(\partial\Omega)$,

$L(P)$ – perimeter of a periodic orbit, \cup – over all per orbits.

Theorem (Chazarian, Anderson-Melrose, Guillemin, Duistermaat, ...) The Laplace $\Delta(\Omega)$ determines the length $\mathcal{L}(\Omega)$, generically. More exactly, *the wave trace*

$$w(t) = \operatorname{Re} \sum_{\lambda_j \in \Delta(\Omega)} \exp(i\lambda_j t)$$

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Theorem [GL'19] Let g be a negatively curved metric. Then for $N > \frac{3}{2} \dim M + 8$ there exists $\varepsilon > 0$ s. t. for any smooth metric g with same marked length spectrum as g_0 and s. t. $\|g - g_0\|_{C^N(M)} < \varepsilon$, then g and g_0 are isometric, i.e. there exists a diffeomorphism $\phi : M \rightarrow M$ s. t. $\phi^*g = g_0$.

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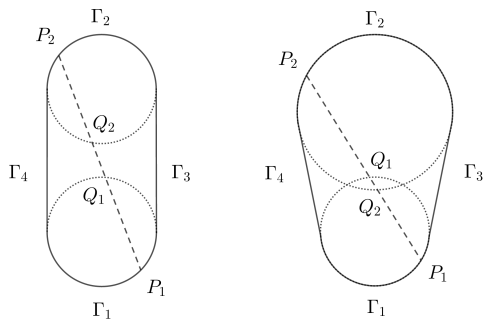
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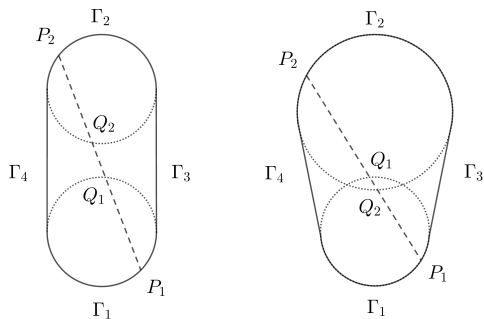
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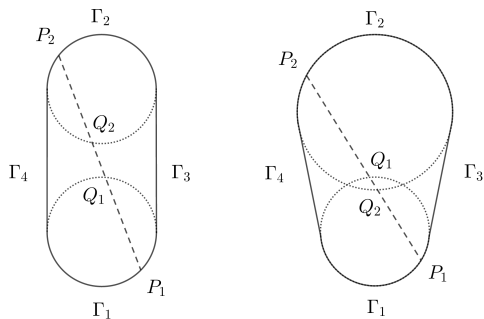
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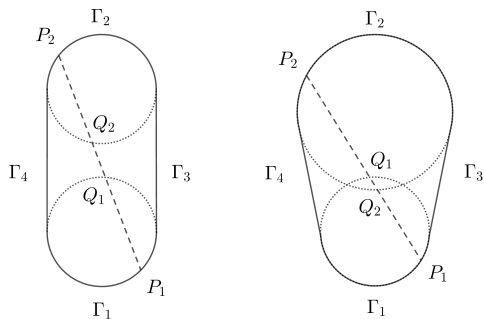
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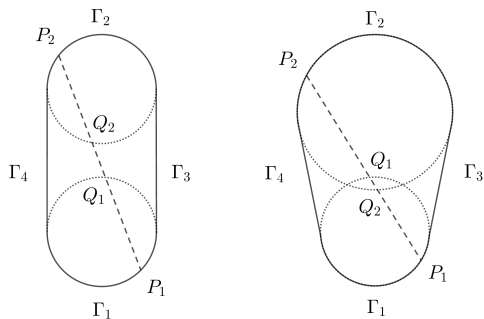
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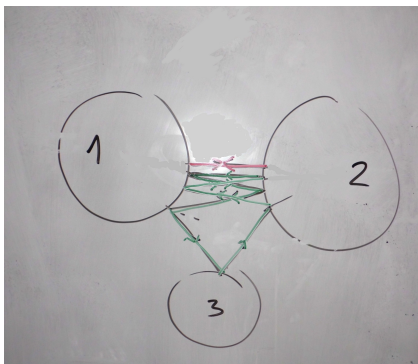
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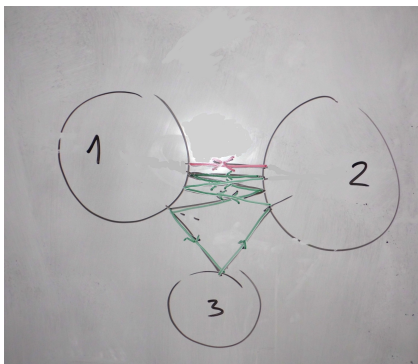
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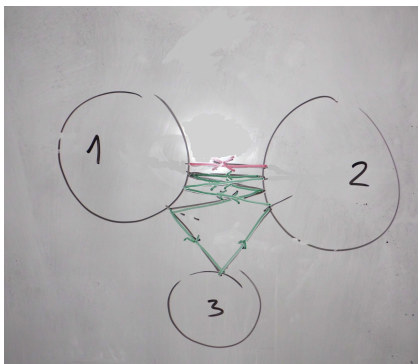
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Croke, Otal'90 the marked length spectrum determines (S, g) upto isometry.

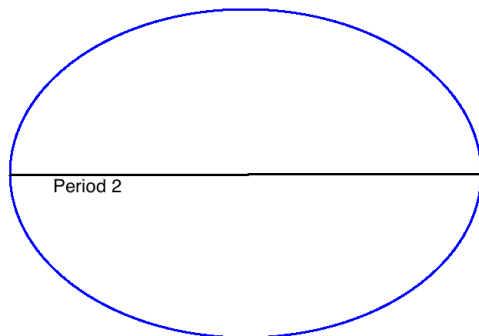
Croke-Sharafutdinov'98 any negatively curved manifold (M, g) is spectrally rigid.

Ideas of proof of Dynamical Spectral Rigidity

- 'Skeleton' of the dynamics. Birkhoff proved

Lemma

For any convex domain Ω and any $q > 1$ there is a periodic orbit of period q , given by inscribed q -gons and denoted $S_q = S_q(\Omega)$. If Ω is axis-symmetric, then S_q can be chosen axis-symmetric.

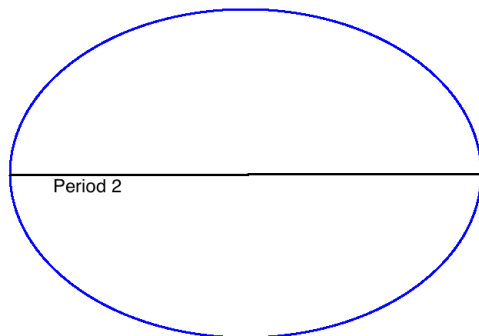


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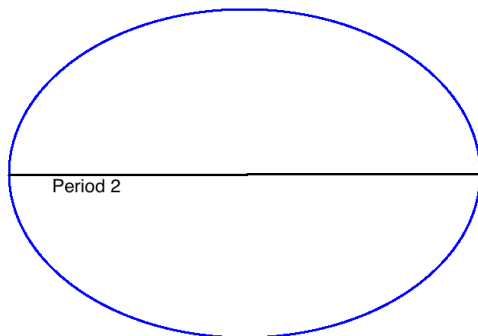


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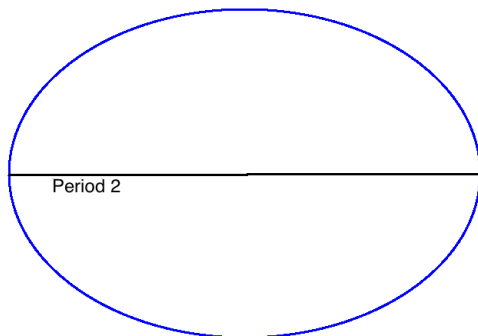


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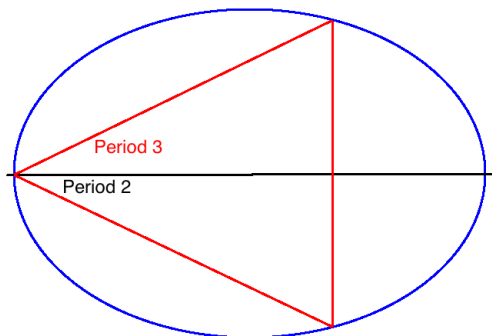


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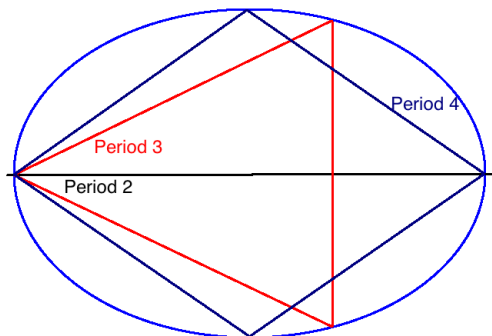


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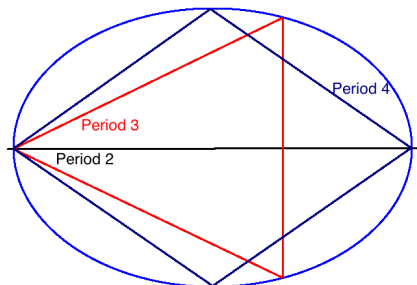
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$\mathcal{S}_q = (x_q^{(k)}, \varphi_q^{(k)})$, $q > 1$. $\mathcal{S}^r(\mathbb{T})$ – space of C^r -symmetric functions.

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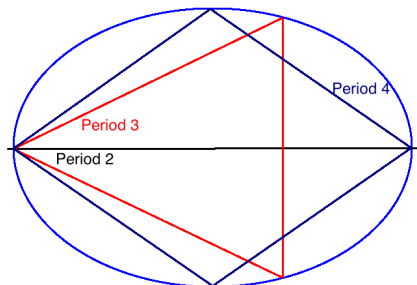


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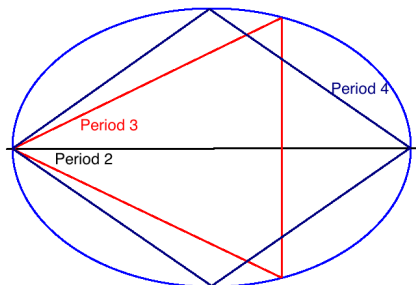


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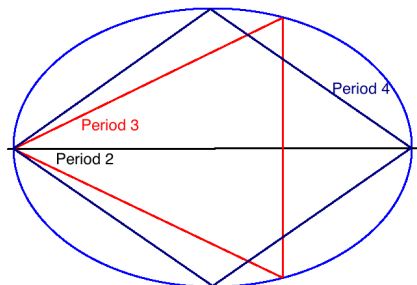


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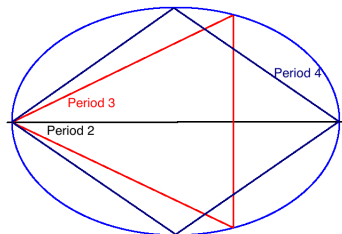
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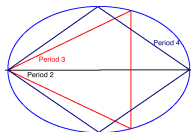
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Lemma

If \mathcal{L}_Ω is injective, then Ω is DSR.



The Linearized Isospectral Operator for the circle

Consider an isospectral deformation $\{\Omega_t\}_t \subset \mathcal{S}^r$, of the circle. In polar coordinates $(r, s) \in \mathbb{R}_+ \times \mathbb{T}$

$$\partial\Omega_t = \{r = 1 + t \cdot n(s) + O(t^2)\}, \quad n \in \mathcal{S}^r(\mathbb{T}).$$

Then

$$\ell_q(n) = \sum_{k=1}^q n\left(\frac{k}{q}\right) = 0.$$

Lemma

Let $n(s) = \sum_{k \in \mathbb{Z}_+} n_k \cos ks$ be the Fourier expansion. Then $\ell_q(n) = 0$ implies $n_{kq} = 0$ for $k \geq 1$.

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The X-ray transform

Let g_0 be a negatively curved metric. Let g be close to g_0 . Denote $h = g_0 - g$ and γ_c the closed geodesic in the homotopy class c . Consider the first variation:

$$(d\mathcal{L}(g_0) \cdot h)(c) = \frac{1}{2L_{g_0}(c)} \int_0^{L_{g_0}(c)} h_{\gamma_c(t)}(\dot{\gamma}_c(t), \dot{\gamma}_c(t)) dt.$$

The X-ray transform and solenoidal injectivity

Let g_0 be a negatively curved metric. Let g be close to g_0 . Denote $C^\infty(M, S^2 T^* M)$ the space of symmetric 2-tensors, $h = g_0 - g$ be the symmetric 2-tensor and γ_c the closed geodesic in the homotopy class c . Call

$$(I_{g_0} \cdot h)(c) = \frac{1}{2L_{g_0}(c)} \int_0^{L_{g_0}(c)} h_{\gamma_c(t)}(\dot{\gamma}_c(t), \dot{\gamma}_c(t)) dt.$$

the X-transform. The divergence operator is its formal adjoint given by $D^* f := -\text{Tr}(\nabla f)$ with the trace Tr naturally defined.

Theorem

Paternain-Salo-Uhlmann Let (M, g_0) be a smooth Riemannian manifold and assume that the geodesic flow of g_0 is Anosov. Then I_{g_0} is solenoidal injective, i.e.

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