

Biologia matematyczna jako źródło trudnych problemów w równaniach różniczkowych cząstkowych

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1. B. Perthame, J. Skrzeczkowski,
Fast reaction limit with nonmonotone reaction function,
Communications on Pure and Applied Mathematics,
doi: 10.1002/cpa.22042.
2. J. Skrzeczkowski,
*Fast reaction limit and forward-backward diffusion:
a Radon-Nikodym approach*,
Comptes Rendus Mathématique,
tome 360, p. 189-203, 2022.

My target: explain in understandable way what is in these papers and why is it difficult?

Crash course on evolutionary PDEs

- We consider functions $u(t; x)$ of time t and space $x = (x_1; \dots; x_d) \in \mathbb{R}^d$,
- We write $@_t u$ for derivative of u with respect to time,
- We write ∇u for gradient of u with respect to x

$$\nabla u = (u_{x_1}; \dots; u_{x_d});$$

- For vector-valued function $u = (u^1; \dots; u^d)$ we write $\operatorname{div} u$ for

$$\operatorname{div} u = u_{x_1}^1 + u_{x_2}^2 + \dots + u_{x_d}^d;$$

- We write Δu for laplacian of u

$$\Delta u = u_{x_1; x_1} + u_{x_2; x_2} + \dots + u_{x_d; x_d};$$

- usual setting: $u \in L^p((0; T) \times \Omega)$ if

$$\int_{(0;T) \times \Omega} |u(t; x)|^p dx dt < \infty:$$

- u is weakly differentiable if there exists function v such that

$$\int_{(0;T) \times \Omega} u \operatorname{div}' \varphi dx dt = - \int_{(0;T) \times \Omega} v \cdot \varphi dx dt$$

for all smooth compactly supported test functions

$$\varphi = (\varphi_1; \dots; \varphi_d),$$

- we write $v = \nabla u$; if u and v are in L^p we say that $u \in W^{1;p}(\cdot)$.

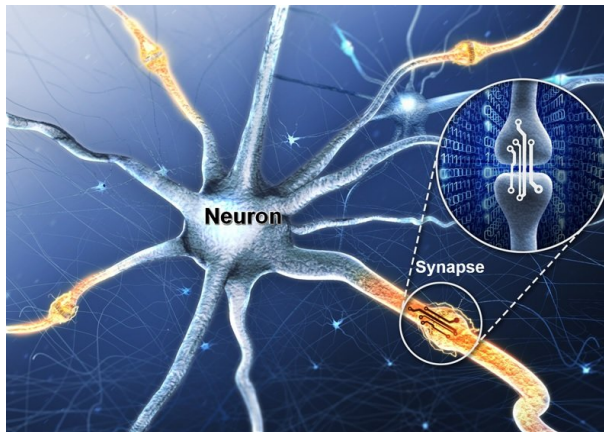
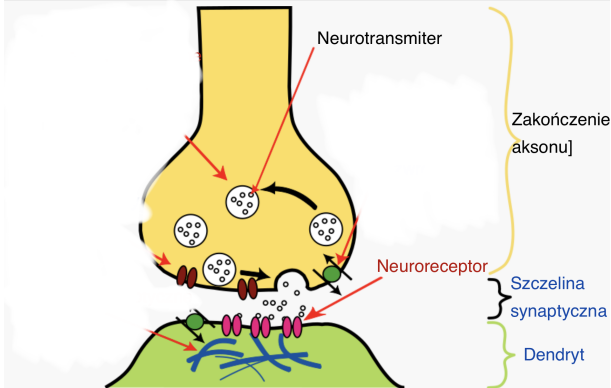


Figure: Different parts of the brain communicate by fast electric signals transmitted by neurons. Neurons communicate via synapses (electrical or chemical).

Our problem

Struktura typowej synapsy chemicznej



$$\partial_t u'' = d_1 u'' + \frac{v'' - F(u'')}{\tau}$$

$$\partial_t v'' = d_2 v'' + \frac{F(u'') - v''}{\tau}$$

Fast reaction system

- We consider reaction-diffusion system on $[0; T] \times$

$$\partial_t u'' = d_1 u'' + \frac{v'' - F(u'')}{\tau}$$

$$\partial_t v'' = d_2 v'' + \frac{F(u'') - v''}{\tau}$$

equipped with initial conditions $u_0(x)$, $v_0(x)$ and Neumann no-flux boundary condition.

- This system may have nonconstant (oscillating) steady states only for nonmonotone F **motivating nonlinearity**.
- These equations can model some reactions in brain cell membrane where systems are rather unstable while reactions are fast

A. Moussa, B. Perthame, and D. Salort. *Backward parabolicity, cross-diffusion and Turing instability*. J. Nonlinear Sci., 29(1):139–162, 2019

Our problem: what happens when $\epsilon \rightarrow 0$?

$$\partial_t u'' = d_1 \Delta u'' + \frac{v'' - F(u'')}{\epsilon}$$

$$\partial_t v'' = d_2 \Delta v'' + \frac{F(u'') - v''}{\epsilon}$$

1. D. Bothe and D. Hilhorst. *A reaction-diffusion system with fast reversible reaction*. J. Math. Anal. Appl., 286(1):125–135, 2003.
2. D. Bothe, M. Pierre, G. Rolland. *Cross-diffusion limit for a reaction-diffusion system with fast reversible reaction*. Comm. Partial Differential Equations, 37(11):1940–1966, 2012.
3. E. S. Daus, L. Desvillettes, A. Jüngel. *Cross-diffusion systems and fast-reaction limits*. Bull. Sci. Math., 159:102824, 29, 2020.

and many more...

Compactness = a fundamental thing in PDEs.

- In \mathbb{R}^d , any bounded sequence has a converging subsequence.
- In infinite dimensional spaces (like function spaces, L^p , $W^{1;p}$) this is no longer true (Riesz).
- To possible ways to overcome this problem:
 - 1 (Banach-Alaoglu) there exists a subsequence converging weakly, i.e. for all linear functionals ϕ , we have $\phi(u_n) \rightarrow \phi(u)$ - nice for linear PDEs
 - 2 impose stronger assumptions on the sequence rather than just boundedness - usual in nonlinear PDEs

Standard examples of the second way

- 1 (Arzela-Ascoli) $\{u_n\}$ is compact in $C(\bar{\Omega})$ if $\{u_n\}$ is bounded in $C(\bar{\Omega})$ and equicontinuous:

$$\forall \epsilon > 0 \quad \exists \delta > 0 \quad \forall x, y: |x - y| < \delta \quad \forall n \quad |u_n(x) - u_n(y)| \leq \epsilon:$$

(this is true if ∇u_n is uniformly bounded on Ω for instance)

- 2 (Reillich-Kondrachov) $\{u_n\}$ is compact in $L^p(\Omega)$ if $\{\nabla u_n\}$ is bounded in $L^p(\Omega)$,
- 3 (Lions-Aubin) $\{u_n(t; x)\}$ is compact in $L^p((0; T) \times \Omega)$ if $\{u_n(t; x)\}$ is bounded in L^p and $\{u_{n,t}(t; x)\}$ is bounded as a functional on some Sobolev space.

To have compactness in L^p , we need to control derivatives in some sense

Theorem (Fréchet–Kolmogorov theorem)

\mathcal{F} is compact in $L^p(\mathbb{R}^d)$ if and only if it is a bounded set in $L^p(\mathbb{R}^d)$ and it is equicontinuous

$$\lim_{|h| \rightarrow 0} \int_{\mathbb{R}^d} |f(x+h) - f(x)|^p dx = 0 \quad \text{uniformly in } f \in \mathcal{F};$$

and equi-tight

$$\forall \epsilon > 0 \quad \exists K \subset \mathbb{R}^d \text{ compact s.t. } \int_{\mathbb{R}^d \setminus K} |f|^p \leq \epsilon;$$

Derivatives for our problem

We have to multiply equations by something **good**

$$\partial_t u'' = d_1 \left(u'' + \frac{v'' - F(u'')}{\epsilon} \right) \cdot F(u'')$$

$$\partial_t v'' = d_2 \left(v'' + \frac{F(u'') - v''}{\epsilon} \right) \cdot v''$$

With $G(t) = \int_0^t F(s) ds$ we have

$$\partial_t G(u'') = d_1 \left(u'' F(u'') + \frac{v'' - F(u'')}{\epsilon} F(u'') \right)$$

$$\frac{1}{2} \partial_t (v'')^2 = d_2 \left(v'' v'' + \frac{F(u'') - v''}{\epsilon} v'' \right)$$

Integrating in space,

$$\begin{aligned} \int_{\Omega} u'' F(u'') &= - \int_{\Omega} \nabla u'' F'(u'') \nabla u'' + \int_{\partial\Omega} F(u'') \frac{\partial u''}{\partial \mathbf{n}} \\ &= - \int_{\Omega} F'(u'') |\nabla u''|^2 \end{aligned}$$

Derivatives for our problem (2)

With $G(t) = \int_0^t F(s) ds$ we have

$$\partial_t G(u'') = d_1 \quad u'' F(u'') + \frac{v'' - F(u'')}{''} F(u'')$$

$$\frac{1}{2} \partial_t (v'')^2 = d_2 \quad v'' v'' + \frac{F(u'') - v''}{''} v''$$

Therefore,

$$\begin{aligned} \partial_t \int_{\Omega} G(u'') + (v'')^2 &= \\ &= -d_1 \int_{\Omega} F'(u'') |\nabla u''|^2 - d_2 \int_{\Omega} |\nabla v''|^2 - \int_{\Omega} \frac{(v'' - F(u''))^2}{''} \end{aligned}$$

If F' can be negative, this identity is useless...

But there is a trick to get something...

New system:

$$\partial_t u'' = \cancel{d_1} \cancel{u''} + \frac{v'' - F(u'')}{\cancel{''}};$$

$$\partial_t v'' = d_2 v'' + \frac{F(u'') - v''}{''};$$

Now, energy equality reads:

$$\begin{aligned} \frac{d}{dt} \int_{\Omega} G(u'') + \frac{1}{2} (v'')^2 dx &= \\ &= \cancel{-d_1 \int_{\Omega} |\nabla u''|^2 F'(u'') dx} - d_2 \int_{\Omega} |\nabla v''|^2 dx - \frac{1}{''} \int_{\Omega} (F(u'') - v'')^2 dx; \end{aligned}$$

Function F

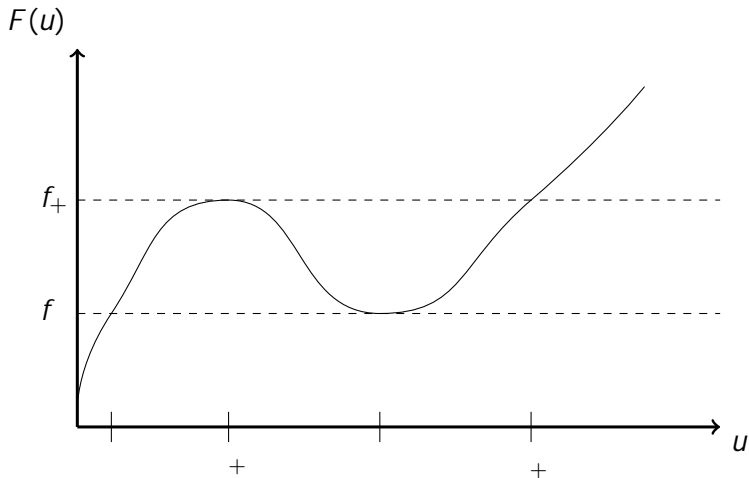


Figure: Plot of a typical function F . It is strictly increasing in intervals $(-\infty; +) \cup (-; \infty)$ and strictly decreasing in $(+; -)$.

Evolution of u'' and v''

Figure: Evolution of u'' (continuous line) and v'' (dash-dotted line) solving the system above with fixed and small value of $\epsilon > 0$.

Results

For the system

$$\begin{aligned} @_t u'' &= \frac{v'' - F(u'')}{\epsilon}; \\ @_t v'' &= v'' + \frac{F(u'') - v''}{\epsilon} \end{aligned}$$

we have a priori estimates in L^2 for

$$\{\nabla v''\}_{L^2(0;1)} \quad \frac{F(u'') - v''}{\sqrt{\epsilon}} \quad L^2(0;1)$$

and we prove

$$v'' \rightarrow v \text{ in } L^2 \quad \text{and} \quad F(u'') \rightarrow v \text{ in } L^2:$$

This means

$$\int_0^T \int_{\Omega} |v''(t;x) - v(t;x)|^2 dx dt \rightarrow 0 \text{ as } \epsilon \rightarrow 0:$$

What about u'' as $\epsilon \rightarrow 0$?

Oscillations and why we don't like it?

Sequences that oscillates do not converge a.e. (even after passing to the subsequence...)

In particular, we cannot say a priori anything about $F(u_n)$ if u_n is oscillating...

Strong vs. weak convergence in $L^2(0;1)$

$f_n \rightarrow f$ strongly in $L^2(0;1)$ if

$$\int_0^1 |f_n(x) - f(x)|^2 dx \rightarrow 0:$$

$f_n \rightharpoonup f$ weakly in $L^2(0;1)$ if for all $\varphi \in L^2(0;1)$

$$\int_0^1 (f_n(x) - f(x)) \varphi(x) dx \rightarrow 0$$

Exercise: let $f : (0;1) \rightarrow \mathbb{R}$ be continuous with $f(0) = f(1)$; $f_n = f(nx)$. Then, $f_n \rightharpoonup \int_0^1 f(x) dx$ in $L^2(0;1)$.

$\sin(2nx) \rightharpoonup 0$ but $\sin^2(2nx) \rightharpoonup \frac{1}{2} \neq 0$

Young measures to describe oscillations

1. For smooth $G: \mathbb{R} \rightarrow \mathbb{R}$ we have

$$G(u'') = \int_{\mathbb{R}} G(\cdot) d u''(t;x) \rightarrow \int_{\mathbb{R}} G(\cdot) d \mu_{t;x}$$

where $u''(t;x) \stackrel{*}{\rightharpoonup} \mu_{t;x}$.

If it is a single Dirac mass, the convergence is strong.

2. Example: Consider sequence of functions $\{u_n\}_{n \in \mathbb{N}}$ oscillating between 1, -1.

The Young measure reads: $\frac{1}{2} \delta_1 + \frac{1}{2} \delta_{-1}$

Results (once again)

For the system

$$\begin{aligned} @_t u'' &= \frac{v'' - F(u'')}{\epsilon}; \\ @_t v'' &= v'' + \frac{F(u'') - v''}{\epsilon} \end{aligned}$$

we have a priori estimates in L^2 for

$$\{\nabla v''\}_{\epsilon^2(0;1)} \quad \frac{F(u'') - v''}{\sqrt{\epsilon}} \quad \epsilon^2(0;1)$$

and we prove

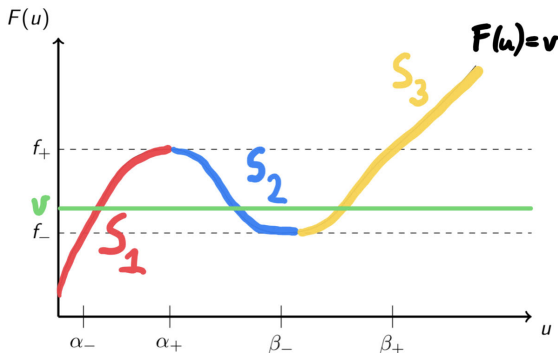
$$v'' \rightarrow v \text{ in } L^2 \quad \text{and} \quad F(u'') \rightarrow v \text{ in } L^2:$$

(without any bound on $@_t v'' \approx \frac{1}{\epsilon}$)

Results: representation of U

From $v''; F(u'') \rightarrow v$, Young measure generated by $\{u''\}_{\epsilon>0}$ reads

$$t;x = \prod_{i=1}^3 i(t;x) S_i(v(t;x)) \quad \prod_{i=1}^3 i(t;x) = 1$$



$u(t;x) = \prod_{i=1}^3 i(t;x) S_i(v(t;x))$ so $F(u) \neq v$ so u is not a stationary solution but rather its combination!

Proof of strong convergence $v'' \rightarrow v$ - STRATEGY

- **STEP 1:** Obtain a lot of energy inequalities of the form

$$\partial_t((u'') + (v'')) - (v'') \leq 0$$

for many functions ϕ and ψ .

- **STEP 2:** Use *compensated compactness* and energy identities to deduce that for many functions ϕ , ψ and χ weak limits behave nicely:

$$w\text{-}\lim_{j \rightarrow \infty} \int_0^{\cdot} (\phi'' + \psi'') \chi' (v'') = w\text{-}\lim_{j \rightarrow \infty} \int_0^{\cdot} (\phi'' + \psi'') w\text{-}\lim_{j \rightarrow \infty} \chi' (v'')$$

- **STEP 3:** As above holds for sufficiently many functions, use this to characterize Young measure and conclude that the **Young measure of v'' is Dirac mass.**

OPEN PROBLEM: The case of two diffusions

For the general problem

$$\partial_t u'' = d_1 \left(u'' + \frac{v'' - F(u'')}{\epsilon} \right);$$

$$\partial_t v'' = d_2 \left(v'' + \frac{F(u'') - v''}{\epsilon} \right)$$

we have bounds in L^2 for:

- $d_1 \nabla u'' + d_2 \nabla v''$
- $d_1 \sqrt{\epsilon} \left(u'' + \frac{v'' - F(u'')}{\epsilon} \right)$
- convergence $d_1 \left(u'' + \frac{v'' - F(u'')}{\epsilon} \right) \rightarrow 0$ in L^2

Hypothesis: u'' , v'' both oscillate but $d_1 u'' + d_2 v''$ converges strongly.

Y. Morita and N. Shinjo. *Reaction-diffusion models with a conservation law and pattern formations.* Josai Mathematical Monographs, 9:177–190, 2016.

- There are simple PDEs for which we cannot use standard compactness arguments.
- For some of them, we can develop rather difficult ways to deduce compactness; for some of them **not**.
- New compactness criteria???

DZIĘKUJĘ ZA UWAGĘ!