

A criterion for periodicity of multi-continued fraction expansion of multi-formal Laurent series

by

ZONGDUO DAI, PING WANG, KUNPENG WANG
and XIUTAO FENG (Beijing)

1. Introduction. We start with the classical continued fraction algorithm over the formal Laurent series field $F((z^{-1}))$. Let \mathbb{Z} be the ring of integers and F be a field. Denote by

$$F((z^{-1})) = \left\{ \sum_{i=t}^{\infty} a_i z^{-i} \mid a_i \in F, t \in \mathbb{Z} \right\}$$

the formal Laurent series field over F in z^{-1} . For any non-zero element $r = \sum_{i=t}^{\infty} a_i z^{-i}$ in $F((z^{-1}))$ with $t \leq 0$, set

$$[r] = \sum_{i=t}^0 a_i z^{-i} \quad \text{and} \quad \{r\} = \sum_{i=1}^{\infty} a_i z^{-i}.$$

They are called the *polynomial part* and *remainder part* of r respectively. The *classical continued fraction algorithm* [14] over $F((z^{-1}))$ is recalled below:

Let $r \in F((z^{-1}))$. Initially, set $a_0 = [r]$ and $\alpha_0 = \{r\}$. Suppose that for $k \geq 1$, we have obtained $[a_0, a_1, \dots, a_{k-1}]$ and α_{k-1} . If $\alpha_{k-1} = 0$, let $\mu = k-1$ and the algorithm terminates; otherwise, do the following steps iteratively:

- (1) set $\varrho_k = 1/\alpha_{k-1}$,
- (2) set $a_k = \lfloor \varrho_k \rfloor$, $\alpha_k = \varrho_k - a_k$.

If the above procedure never stops, let $\mu = \infty$.

The output $[a_0, a_1, \dots]$ of the algorithm with input r is called the *classical continued fraction expansion* $C(r)$ of r .

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The continued fraction algorithm is a useful tool in dealing with many number-theoretic problems and numerical computation problems [9, 10, 12]. It is well-known that the continued fraction expansion $C(r)$ gives the optimal rational approximation of a single element r [14]. Many people have contrived to construct multi-dimensional continued fractions in dealing with the rational approximation problem for multi-reals. One construction is the Jacobi–Perron algorithm (JPA) [1]. This algorithm and its modification are extensively studied [7, 8, 11, 13]. These algorithms have been adapted to study the same problem for multi-dimensional formal Laurent series [4, 6]. But none of these algorithms guarantees optimal rational approximations to the general multi-dimensional formal Laurent series.

Let $C(r) = [a_0, a_1, \dots]$ be the classical continued fraction expansion of r . It is called (λ, T) -periodic if there exist integers $\lambda \geq 1$ and $T \geq 1$ such that $a_{\lambda+T+k} = a_{\lambda+k}$ for all $k \geq 0$. We then also call $C(r)$ periodic for short. It is known that $C(r)$ is (λ, T) -periodic if and only if the $(\lambda - 1)$ th partial remainder $\alpha_{\lambda-1}$ and the $(\lambda + T - 1)$ th partial remainder $\alpha_{\lambda+T-1}$ are equal. In [2, 3], the classical continued fraction algorithm is generalized to an algorithm acting on a multi-formal Laurent series \underline{r} in $F((z^{-1}))^m$, $m > 1$, and called the *multi-continued fraction algorithm* (or *multi-dimensional continued fraction algorithm*), m-CFA for short. Likewise, the m-CFA provides a multi-continued fraction expansion of a multi-series \underline{r} in $F((z^{-1}))^m$ and a method of finding the optimal rational approximation of \underline{r} as well. It is natural to ask whether the same criterion of periodicity is valid for multi-continued fraction expansions. Unfortunately, equality of the $(\lambda - 1)$ th and $(\lambda + T - 1)$ th partial remainders is not enough for $C(\underline{r})$ to be (λ, T) -periodic for $m > 1$.

In this paper, we provide a criterion to determine whether a multi-continued fraction expansion is (λ, T) -periodic.

This paper is organized as follows. In Section 2, some preliminaries are provided, which include the indexed valuation over $F((z^{-1}))^m$, the m-CFA, some parameters and some main properties of multi-continued fraction expansions. The main theorem, a criterion of periodicity of multi-continued fraction expansions, is stated in Section 3. Some preparatory lemmas and the proof of the main theorem are given in Sections 4 and 5 respectively.

2. Preliminaries. In this section we briefly recall some concepts such as the indexed valuation and m-CFA, all of which may be found in [2, 3].

2.1. Indexed valuation over $F((z^{-1}))^m$. Let F be a field and m be a positive integer. We denote by $F[z]^m$ and $F((z^{-1}))^m$ the spaces of column m -vectors over the polynomial ring $F[z]$ and over the formal Laurent series field

$F((z^{-1}))$ respectively. Before introducing the concept of indexed valuation over $F((z^{-1}))^m$, we first define an order over $Z_m \times \mathbb{Z}$, where Z_m denotes the set $\{1, \dots, m\}$.

DEFINITION 2.1. For any (h, v) and (h', v') in $Z_m \times \mathbb{Z}$, we define $(h, v) < (h', v')$ if $v < v'$ or $v = v', h < h'$.

It is clear that the order defined above is linear [5].

Let $r = \sum_{i=t}^{\infty} a_i z^{-i}$ be a non-zero element in $F((z^{-1}))$. Then the integer t is called the *discrete valuation* [5] of r if $a_t \neq 0$, and is denoted by $v(r)$. By convention, $v(0) = \infty$.

DEFINITION 2.2. Let $\underline{r} = (r_1, \dots, r_m)^\tau \in F((z^{-1}))^m \setminus \{0\}$, where τ means transpose. We define

$$Iv(\underline{r}) = (h, v),$$

where

$$v = \min\{v(r_j) \mid j \in Z_m\}, \quad h = \min\{j \in Z_m \mid v(r_j) = v\}$$

and call $Iv(\underline{r})$ the *indexed valuation* of \underline{r} , v the *valuation* of \underline{r} , denoted by $v(\underline{r})$, and h the *index* of \underline{r} , denoted by $I(\underline{r})$. By convention, $Iv(\underline{0}) = (1, \infty)$.

For each $j \in Z_m$, let $\underline{e}_j = (e_{j,1}, \dots, e_{j,m})^\tau$, where $e_{j,i} = 0$ for $i \neq j$ and $e_{j,j} = 1$, which is exactly the j th standard basis element in the column vector space of dimension m over $F((z^{-1}))$. For any non-zero element $\underline{r} = (r_1, \dots, r_m)^\tau$ in $F((z^{-1}))^m$, where $r_j = \sum_i r_{j,i} z^{-i}$ for each $j \in Z_m$, if $Iv(\underline{r}) = (h, v)$, we call $r_{h,v} z^{-v} \underline{e}_h$ the *leading term* of \underline{r} , denoted by $Ld_0(\underline{r})$. The indexed valuation over $F((z^{-1}))^m$ has the following basic properties:

PROPOSITION 2.3. Let $\underline{\alpha}, \underline{\beta} \in F((z^{-1}))^m$. Then

- (1) $Iv(\underline{\alpha}) \neq (1, \infty)$ if and only if $\underline{\alpha} \neq \underline{0}$.
- (2) If $Iv(\underline{\alpha}) = (h, v)$, then $Iv(r\underline{\alpha}) = (h, v + v(r))$ for any non-zero r in $F((z^{-1}))$.
- (3) $Iv(\underline{\alpha} - \underline{\beta}) \geq \min\{Iv(\underline{\alpha}), Iv(\underline{\beta})\}$, and equality holds if and only if $Ld_0(\underline{\alpha}) \neq Ld_0(\underline{\beta})$.

2.2. m-CFA. We first introduce some related notations and concepts. For any $\underline{r} = (r_1, \dots, r_m)^\tau \in F((z^{-1}))^m$, we define

$$[\underline{r}] = (\lfloor r_1 \rfloor, \dots, \lfloor r_m \rfloor)^\tau, \quad \{\underline{r}\} = (\{r_1\}, \dots, \{r_m\})^\tau,$$

which are called the *polynomial part* and *remainder part* of \underline{r} .

In this paper, we denote by $\text{Diag}(\beta_1, \dots, \beta_m)$ the diagonal matrix with the i th diagonal element being β_i .

The m-CFA can be described as below:

m-CFA: Let $\underline{r} \in F((z^{-1}))^m$. Initially, set $\underline{a}_0 = \lfloor \underline{r} \rfloor$, $\underline{\alpha}_0 = \{\underline{r}\}$, $\Delta_0 = I_m$. Suppose that for $k \geq 1$, we have obtained

$$\begin{bmatrix} h_1 & \cdots & h_{k-1} \\ \underline{a}_0 & \underline{a}_1 & \cdots & \underline{a}_{k-1} \end{bmatrix},$$

$$\underline{\alpha}_{k-1} = (\alpha_{k-1,1}, \dots, \alpha_{k-1,m}) \in F((z^{-1}))^m,$$

and

$$\Delta_{k-1} = \text{Diag}(z^{-v_{k-1,1}}, \dots, z^{-v_{k-1,m}}).$$

If $\underline{\alpha}_{k-1} = \underline{0}$, let $\mu = k - 1$ and the algorithm terminates; otherwise, do the following steps iteratively:

- (1) set $(h_k, v_k) = Iv(\Delta_{k-1}\underline{\alpha}_{k-1})$,
- (2) set $\Delta_k = \text{Diag}(z^{-v_{k,1}}, \dots, z^{-v_{k,m}})$, where

$$v_{k,j} = \begin{cases} v_{k-1,j} & \text{if } j \neq h_k, \\ v_k & \text{if } j = h_k, \end{cases}$$

- (3) set $\underline{\varrho}_k = (\varrho_{k,1}, \dots, \varrho_{k,m})^\tau$, where

$$\varrho_{k,j} = \begin{cases} \alpha_{k-1,j}/\alpha_{k-1,h_k} & \text{if } j \neq h_k, \\ 1/\alpha_{k-1,h_k} & \text{if } j = h_k, \end{cases}$$

- (4) set $\underline{a}_k = \lfloor \underline{\varrho}_k \rfloor$, $\underline{\alpha}_k = \{\underline{\varrho}_k\}$.

If the above procedure never stops, let $\mu = \infty$.

It is proved that m-CFA is well defined, that is, $\alpha_{k-1,h_k} \neq 0$ for $1 \leq k \leq \mu$. As a result of the m-CFA acting on \underline{r} , we obtain a sequence pair

$$C(\underline{r}) = (\underline{h}, \underline{a}) = \begin{bmatrix} h_1 & \cdots & h_\mu \\ \underline{a}_0 & \underline{a}_1 & \cdots & \underline{a}_\mu \end{bmatrix},$$

where $\underline{h} = \{h_k\}_{1 \leq k \leq \mu}$, $\underline{a} = \{\underline{a}_k\}_{0 \leq k \leq \mu}$, $1 \leq h_k \leq m$ and $\underline{a}_k \in F[z]^m$. We call $C(\underline{r})$ the *multi-continued fraction expansion* of \underline{r} , and call μ the *length* of $C(\underline{r})$.

$C(\underline{r})$ provides an optimal rational approximation to \underline{r} by the following procedure:

Let

$$A(\underline{a}_k) = \begin{pmatrix} I_m & \underline{a}_k \\ \mathbf{0} & 1 \end{pmatrix}, \quad 0 \leq k \leq \mu,$$

and

$$B_0 = A(\underline{a}_0), \quad B_k = B_{k-1}E_{h_k}A(\underline{a}_k), \quad k \geq 1,$$

where I_m is the identity matrix of order m , and E_{h_k} is a permutation matrix of order $m + 1$ obtained by exchanging the h_k th and $(m + 1)$ th columns of I_{m+1} .

Let

$$\begin{pmatrix} p_k \\ q_k \end{pmatrix} = B_k \begin{pmatrix} 0 \\ 1 \end{pmatrix},$$

the rightmost column of B_k , where $\underline{p}_k \in F[z]^m$ and $q_k \in F[z]$. We call \underline{p}_k/q_k the k th rational fraction of $C(\underline{r})$. In [2, 3], we proved that \underline{p}_k/q_k is an optimal rational approximant of \underline{r} for all $0 \leq k \leq \mu$.

To see how close to \underline{r} the k th rational fraction \underline{p}_k/q_k is and further study the properties of $C(\underline{r})$, we have to recall some parameters.

For all $1 \leq k \leq \mu$, let $\underline{a}_k = (a_{k,1}, \dots, a_{k,m})$ and denote by $\deg(a_{k,j})$ the degree of $a_{k,j}$. It is known [2, 3] that $a_{k,h_k} \neq 0$ and $\deg(a_{k,h_k}) \geq 1$.

For all $1 \leq k \leq \mu$, we define

$$t_k = \deg(a_{k,h_k}), \quad d_k = \sum_{1 \leq i \leq k} t_i.$$

DEFINITION 2.4. Let $S \subseteq Z_m$. Denote by $D(S, z^{-c})$ the diagonal matrix

$$\text{Diag}(z^{-c_1}, \dots, z^{-c_m})$$

where

$$c_j = \begin{cases} c & \text{if } j \in S, \\ 0 & \text{if } j \notin S. \end{cases}$$

When $S = \{h\}$, we simply denote $D(S, z^{-c})$ by $D(h, z^{-c})$.

Then we have

THEOREM 2.5 ([2, 3]).

- (1) $\alpha_{k-1,h_k} \neq 0$ and $t_k = v(\alpha_{k-1,h_k}) \geq 1$ for all $1 \leq k \leq \mu$.
- (2) For any $1 \leq k \leq \mu$, $1 \leq j \leq m$, we have

$$v_{k,j} = \sum_{\substack{1 \leq i \leq k \\ h_i = j}} t_i, \quad v_k = v_{k,h_k}, \quad v_{0,j} = 0.$$

As a consequence, $\Delta_k = \Delta_{k-1}D(h_k, z^{-t_k})$.

- (3) $Iv(\Delta_k \underline{a}_k) = Iv(\Delta_k \underline{q}_k) = (h_k, v_{k-1,h_k}) < Iv(\Delta_k \underline{\alpha}_k) = (h_{k+1}, v_{k+1})$ for all $1 \leq k \leq \mu$, where we let $(h_{\mu+1}, v_{\mu+1}) = (1, \infty)$ if $\mu < \infty$.
- (4) Let

$$(-I_m, \underline{r})B_k = (-R_{k-1}, \underline{r}_k)$$

for $k \geq 1$, where R_{k-1} is a square matrix of order m and \underline{r}_k is an element in $F((z^{-1}))^m$. Then R_{k-1} is invertible and

$$\begin{cases} \underline{r}_k = \underline{r}q_k - \underline{p}_k = \{\underline{r}q_k\} = R_{k-1}\underline{\alpha}_k, \\ Iv(\underline{r}_k) = (h_{k+1}, v_{k+1}) \end{cases}$$

for any $0 \leq k \leq \mu$. As a consequence, $\underline{r}_k \neq \underline{0}$ for any $0 \leq k < \mu$, and $\underline{r}_\mu = \underline{0}$ if $\mu < \infty$.

THEOREM 2.6 ([2, 3]).

(1) $\deg(q_k) = d_k$ and

$$Iv(\underline{r} - \underline{p}_k/q_k) = (h_{k+1}, d_k + v_{k+1})$$

for all $0 \leq k \leq \mu$.

(2) We have

$$\underline{r} = \begin{cases} \lim_{k \rightarrow \infty} \frac{\underline{p}_k}{q_k} & \text{if } \mu = \infty, \\ \frac{\underline{p}_\mu}{q_\mu} & \text{if } \mu < \infty. \end{cases}$$

As a consequence, $\mu < \infty$ if and only if $\underline{r} \in F(z)^m$.

(3) \underline{p}_k/q_k is an optimal rational approximant of \underline{r} . Moreover, if \underline{p}/q is an optimal rational approximant of \underline{r} , then $\deg(q) = d_k$ for some k .

3. Periodicity of multi-continued fraction expansion. In the following, we only study infinite multi-continued fraction expansions, that is, we assume $\mu = \infty$.

DEFINITION 3.1. We say that $C(\underline{r})$ is (λ, T) -periodic, where $\lambda \geq 1$ and $T \geq 1$, if

$$(h_{\lambda+k+T}, \underline{a}_{\lambda+k+T}) = (h_{\lambda+k}, \underline{a}_{\lambda+k}) \quad \text{for all } k \geq 0.$$

m-CFA is an iterative algorithm. A practical problem is how to determine whether $C(\underline{r})$ is (λ, T) -periodic. In this paper, we provide a criterion that permits one to determine whether $C(\underline{r})$ is (λ, T) -periodic only by means of the data obtained in the process of m-CFA.

When $m = 1$, the multi-continued fraction expansions are exactly the classical continued fraction expansions. In this case, we have $\underline{q}_k = 1/\underline{\alpha}_{k-1}$. The continued fraction expansion $C(\underline{r})$ of \underline{r} is (λ, T) -periodic if and only if $\underline{\alpha}_{\lambda-1} = \underline{\alpha}_{\lambda+T-1}$. However, when $m \geq 2$, the condition $\underline{\alpha}_{\lambda-1} = \underline{\alpha}_{\lambda+T-1}$ alone does not guarantee that $C(\underline{r})$ is (λ, T) -periodic.

DEFINITION 3.2. Let $\underline{\alpha} = (\alpha_1, \dots, \alpha_m)^\tau \in F((z^{-1}))^m$. We define

$$J^*(\underline{\alpha}) = \{j \mid \alpha_j \neq 0, 1 \leq j \leq m\}.$$

For the given multi-continued fraction expansion $C(\underline{r})$ of \underline{r} obtained by m-CFA, we give a simple criterion to decide whether $C(\underline{r})$ is periodic.

THEOREM 3.3 (Main Theorem). For $\lambda \geq 1$ and $T \geq 1$, the following three conditions are equivalent:

(1) $C(\underline{r})$ is (λ, T) -periodic.

$$(2) \begin{cases} \underline{\alpha}_{\lambda+T-1} = \underline{\alpha}_{\lambda-1}, \\ \Delta_{\lambda-1}^{-1} \Delta_{\lambda+T-1} = D(J^*(\underline{\alpha}_{\lambda-1}), z^{-c}), \end{cases}$$

where c is a positive integer.

$$(3) \begin{cases} \underline{\varrho}_{\lambda+T} = \underline{\varrho}_{\lambda}, \\ \Delta_{\lambda}^{-1} \Delta_{\lambda+T} = D(J^*(\underline{\varrho}_{\lambda}), z^{-c}), \end{cases}$$

where c is a positive integer.

REMARK. In Theorem 3.3, neither $\underline{\alpha}_{\lambda+T-1} = \underline{\alpha}_{\lambda-1}$ (resp. $\underline{\varrho}_{\lambda+T} = \underline{\varrho}_{\lambda}$) nor $\Delta_{\lambda-1}^{-1} \Delta_{\lambda+T-1} = D(J^*(\underline{\alpha}_{\lambda-1}), z^{-c})$ (resp. $\Delta_{\lambda}^{-1} \Delta_{\lambda+T} = D(J^*(\underline{\varrho}_{\lambda}), z^{-c})$) in condition (2) (resp. (3)) can be rejected, since the following examples show that $\underline{\alpha}_{\lambda+T-1} = \underline{\alpha}_{\lambda-1}$ (resp. $\underline{\varrho}_{\lambda+T} = \underline{\varrho}_{\lambda}$) does not imply $\Delta_{\lambda-1}^{-1} \Delta_{\lambda+T-1} = D(J^*(\underline{\alpha}_{\lambda-1}), z^{-c})$ (resp. $\Delta_{\lambda}^{-1} \Delta_{\lambda+T} = D(J^*(\underline{\varrho}_{\lambda}), z^{-c})$), and vice versa.

EXAMPLE 3.4. Let $m = 2$ and $\underline{r} = \begin{pmatrix} r_1 \\ r_2 \end{pmatrix} \in F_2((z^{-1}))^2$, where $r_1 = 1/(z + r_2)$ and $r_2 = \sum_i c_i z^{-i} \in F_2((z^{-1}))$, where

$$c_i = \begin{cases} 0 & \text{if } i < 4, \\ 1 & \text{if } i = 4, \\ \sum_{j=2}^{k-1} c_j c_{i-2j-4} & \text{if } i = 2k > 4, \\ c_{k-1} + c_k + \sum_{j=2}^{k-1} c_j c_{i-2j-4} & \text{if } i = 2k + 1 > 4. \end{cases}$$

It is straightforward to check that r_2 is a root of the algebraic equation $X^3 + (z + z^3)X^2 + z^4X + 1 = 0$ over $F_2((z^{-1}))$, and $v(r_2) = 4$. By [4], this algebraic equation is irreducible over $F_2(z)$. So, by Theorem 2.6, $\mu = \infty$.

Then, by m-CFA, we have

Parameters obtained in the process of m-CFA with input \underline{r}					
k	h_k	Δ_k	\underline{a}_k	$\underline{\alpha}_k$	$\underline{\varrho}_k$
0		I_2	$\underline{0}$	$\begin{pmatrix} r_1 \\ r_2 \end{pmatrix}$	
1	1	$\text{Diag}(z^{-1}, 1)$	$\begin{pmatrix} z \\ 0 \end{pmatrix}$	$\begin{pmatrix} r_2 \\ r_1^{-1} r_2 \end{pmatrix}$	$\begin{pmatrix} z + r_2 \\ r_1^{-1} r_2 \end{pmatrix}$
2	2	$\text{Diag}(z^{-1}, z^{-3})$	$\begin{pmatrix} 0 \\ z^3 \end{pmatrix}$	$\begin{pmatrix} r_1 \\ r_2 \end{pmatrix}$	$\begin{pmatrix} r_1 \\ z^3 + r_2 \end{pmatrix}$
3	1	$\text{Diag}(z^{-2}, z^{-3})$	$\begin{pmatrix} z \\ 0 \end{pmatrix}$	$\begin{pmatrix} r_2 \\ r_1^{-1} r_2 \end{pmatrix}$	$\begin{pmatrix} z + r_2 \\ r_1^{-1} r_2 \end{pmatrix}$

From the above computations, we see that

$$\begin{cases} \underline{\alpha}_0 = \underline{\alpha}_2, \\ \Delta_0^{-1} \Delta_2 = \text{Diag}(z^{-1}, z^{-3}) \neq D(J^*(\underline{\alpha}_0), z^{-c}) = z^{-c} I_2, \end{cases}$$

and

$$\begin{cases} \underline{\varrho}_1 = \underline{\varrho}_3, \\ \Delta_1^{-1} \Delta_3 = \text{Diag}(z^{-1}, z^{-3}) \neq D(J^*(\underline{\varrho}_1), z^{-c}) = z^{-c} I_2. \end{cases}$$

EXAMPLE 3.5. Let $m = 2$ and

$$\underline{\alpha}_0 = \underline{r} = \begin{pmatrix} (z^2 + r_1)^{-1} \\ r_2(z^2 + r_1)^{-1} \end{pmatrix} \in F_2((z^{-1}))^2,$$

where r_1 and r_2 are as in Example 3.4. Just as in Example 3.4, $C(\underline{r})$ is infinite, that is, $\mu = \infty$.

Then, by m-CFA, we have

Parameters obtained in the process of m-CFA with input \underline{r}					
k	h_k	Δ_k	\underline{a}_k	$\underline{\alpha}_k$	$\underline{\varrho}_k$
0		I_2	$\underline{0}$	$\begin{pmatrix} (z^2 + r_1)^{-1} \\ (z^2 + r_1)^{-1} r_2 \end{pmatrix}$	
1	1	$\text{Diag}(z^{-2}, 1)$	$\begin{pmatrix} z^2 \\ 0 \end{pmatrix}$	$\begin{pmatrix} r_1 \\ r_2 \end{pmatrix}$	$\begin{pmatrix} z^2 + r_1 \\ r_2 \end{pmatrix}$
2	1	$\text{Diag}(z^{-3}, 1)$	$\begin{pmatrix} z \\ 0 \end{pmatrix}$	$\begin{pmatrix} r_2 \\ r_1^{-1} r_2 \end{pmatrix}$	$\begin{pmatrix} z + r_2 \\ r_1^{-1} r_2 \end{pmatrix}$
3	2	$\text{Diag}(z^{-3}, z^{-3})$	$\begin{pmatrix} 0 \\ z^3 \end{pmatrix}$	$\begin{pmatrix} r_1 \\ r_2 \end{pmatrix}$	$\begin{pmatrix} r_1 \\ z^3 + r_2 \end{pmatrix}$
4	1	$\text{Diag}(z^{-4}, z^{-3})$	$\begin{pmatrix} z \\ 0 \end{pmatrix}$	$\begin{pmatrix} r_2 \\ r_1^{-1} r_2 \end{pmatrix}$	$\begin{pmatrix} z + r_2 \\ r_1^{-1} r_2 \end{pmatrix}$
5	2	$\text{Diag}(z^{-4}, z^{-6})$	$\begin{pmatrix} 0 \\ z^3 \end{pmatrix}$	$\begin{pmatrix} r_1 \\ r_2 \end{pmatrix}$	$\begin{pmatrix} r_1 \\ z^3 + r_2 \end{pmatrix}$
6	1	$\text{Diag}(z^{-5}, z^{-6})$	$\begin{pmatrix} z \\ 0 \end{pmatrix}$	$\begin{pmatrix} r_2 \\ r_1^{-1} r_2 \end{pmatrix}$	$\begin{pmatrix} z + r_2 \\ r_1^{-1} r_2 \end{pmatrix}$
7	1	$\text{Diag}(z^{-9}, z^{-6})$	$\begin{pmatrix} z^4 \\ z \end{pmatrix}$	$\begin{pmatrix} z^3 r_2 + r_1^{-1} r_2 \\ r_2 \end{pmatrix}$	$\begin{pmatrix} z^4 + z^3 r_2 + r_1^{-1} r_2 \\ r_1^{-1} \end{pmatrix}$

From the above computations, we see that

$$\begin{cases} \underline{\alpha}_0 \neq \underline{\alpha}_3, \\ \Delta_0^{-1} \Delta_3 = \text{Diag}(z^{-3}, z^{-3}) = D(J^*(\underline{\alpha}_0), z^{-3}) = z^{-3} I_2, \end{cases}$$

and

$$\begin{cases} \underline{\varrho}_2 \neq \underline{\varrho}_7, \\ \Delta_2^{-1} \Delta_7 = \text{Diag}(z^{-6}, z^{-6}) = D(J^*(\underline{\varrho}_2), z^{-6}) = z^{-6} I_2. \end{cases}$$

4. Some lemmas. Before proving the main theorem, we need to prepare some lemmas.

LEMMA 4.1.

- (1) For all $k \geq 1$, $\alpha_{k-1, h_{k+1}} \neq 0$.
- (2) If $\alpha_{k, j} = 0$, then $\alpha_{l, j} = 0$ for all $l \geq k$. As a consequence, $J^*(\underline{\alpha}_{k+1}) \subseteq J^*(\underline{\alpha}_k)$ for all $k \geq 0$.
- (3) $\lim_{k \rightarrow \infty} v_k = \infty$.
- (4) For all $l > k \geq 1$, define

$$B_{k, l} = E_{h_{k+1}} A(\underline{a}_{k+1}) \cdots E_{h_l} A(\underline{a}_l).$$

Let $\left(\frac{p_{k, l}}{q_{k, l}}\right)$ be the last column of $B_{k, l}$, where $\underline{p}_{k, l} \in F[z]^m$ and $q_{k, l} \in F[z]$. Then $q_{k, l} \neq 0$, and

$$\underline{\alpha}_k = \lim_{l \rightarrow \infty} \frac{\underline{p}_{k, l}}{q_{k, l}}.$$

Proof. (1) Noting that $\Delta_k \underline{\alpha}_k \neq \underline{0}$ and $h_{k+1} = I(\Delta_k \underline{\alpha}_k)$, we have $v_{k, h_{k+1}} + v(\alpha_{k, h_{k+1}}) = v(\Delta_k \underline{\alpha}_k) = v_{k+1} \in \mathbb{Z}$. Thus, $v(\alpha_{k, h_{k+1}}) = v_{k+1} - v_{k, h_{k+1}} \in \mathbb{Z}$. Hence, $\{\varrho_{k, h_{k+1}}\} = \alpha_{k, h_{k+1}} \neq 0$. So, $\varrho_{k, h_{k+1}} \neq 0$. By the definition of $\underline{\varrho}_k$, $\alpha_{k-1, h_{k+1}} \neq 0$.

(2) We have $\varrho_{k+1, j} = \alpha_{k, j} / \alpha_{k, h_k} = 0$. Thus, $\alpha_{k+1, j} = \{\varrho_{k+1, j}\} = 0$. Repeating this process, we have $\alpha_{l, j} = 0$ for any $l \geq k$.

(3) Let

$$H_\infty = \{j \mid \text{there exist infinitely many } k\text{'s such that } h_k = j, k \geq 1\},$$

$$K_j = \{k \mid h_k = j, k \geq 1\}.$$

By definition, $|K_j| = \infty$ for any $j \in H_\infty$. Moreover, there exists k_0 such that

$$\bigcup_{j \in H_\infty} K_j = \{k \mid k \geq k_0\} \cup S,$$

where S is a finite integer set.

By Theorem 2.5,

$$v_k = \sum_{\substack{1 \leq i \leq k \\ h_i = h_k}} t_i, \quad \text{so} \quad \lim_{\substack{k \rightarrow \infty \\ k \in K_j}} v_k = \infty$$

for any $j \in H_\infty$. Further,

$$\lim_{k \rightarrow \infty} v_k = \lim_{\substack{k \rightarrow \infty \\ k \geq k_0}} v_k = \lim_{k \in \bigcup_{j \in H_\infty} K_j} v_k = \infty.$$

(4) Noting that

$$B_l = B_k B_{k, l} \quad \text{and} \quad (-R_{k-1}, T_k) = (-I_m, T) B_k,$$

we have

$$(-R_{l-1}, r_l) = (-I_m, r)B_l = (-R_{k-1}, r_k)B_{k,l}.$$

Then

$$r_l = (-R_{k-1}, r_k) \begin{pmatrix} \underline{p}_{k,l} \\ \underline{q}_{k,l} \end{pmatrix}.$$

Suppose $q_{k,l} = 0$. Then $\underline{p}_{k,l} \neq 0$ and $\underline{p}_{k,l} = -R_{k-1}^{-1}r_l$. Thus

$$v(-R_{k-1}^{-1}r_l) = v(\underline{p}_{k,l}) \leq 0.$$

Since $\lim_{l \rightarrow \infty} v_l = \infty$, we have

$$\lim_{l \rightarrow \infty} v(r_l) = \lim_{l \rightarrow \infty} v_{l+1} = \infty.$$

So there exists some integer l such that $v(-R_{k-1}^{-1}r_l) > 0$, a contradiction. Hence, $q_{k,l} \neq 0$.

By Theorem 2.5, we have

$$r_l = (-R_{k-1}, R_{k-1}\underline{\alpha}_k) \begin{pmatrix} \underline{p}_{k,l} \\ \underline{q}_{k,l} \end{pmatrix} = R_{k-1}(-\underline{p}_{k,l} + \underline{\alpha}_k \underline{q}_{k,l}).$$

Then since $\lim_{l \rightarrow \infty} v(r_l) = \lim_{l \rightarrow \infty} v_{l+1} = \infty$, we have

$$\lim_{l \rightarrow \infty} v\left(\underline{\alpha}_k - \frac{\underline{p}_{k,l}}{\underline{q}_{k,l}}\right) = \lim_{l \rightarrow \infty} v\left(\frac{R_{k-1}^{-1}r_l}{\underline{q}_{k,l}}\right) = \infty.$$

So,

$$\underline{\alpha}_k = \lim_{l \rightarrow \infty} \frac{\underline{p}_{k,l}}{\underline{q}_{k,l}}. \quad \blacksquare$$

LEMMA 4.2.

(1) If $h_{\lambda+T} = h_\lambda$ and $t_{\lambda+T} = t_\lambda$, then

$$\Delta_\lambda^{-1} \Delta_{\lambda+T} = \Delta_{\lambda-1}^{-1} \Delta_{\lambda+T-1}.$$

(2) If $h_{\lambda+T} = h_\lambda$, then

$$\underline{\varrho}_{\lambda+T} = \underline{\varrho}_\lambda \Leftrightarrow \underline{\alpha}_{\lambda+T-1} = \underline{\alpha}_{\lambda-1}.$$

(3) Let $\underline{\alpha} \in F((z^{-1}))^m$. Then

$$D(J^*(\underline{\alpha}), z^{-c})\underline{\alpha} = z^{-c}\underline{\alpha}.$$

(4) If $\underline{\alpha}_{k+l} = \underline{\alpha}_k$ for some $l \geq 1$, then

$$J^*(\underline{\alpha}_{k+i}) = J^*(\underline{\alpha}_k) \quad \text{for any } 0 \leq i \leq l.$$

(5) $J^*(\underline{\varrho}_k) = J^*(\underline{\alpha}_{k-1})$ for any $k \geq 1$.

Proof. (1) By Theorem 2.5, we have

$$\Delta_{\lambda+T} = \Delta_{\lambda+T-1}D(h_{\lambda+T}, z^{-t_{\lambda+T}}), \quad \Delta_\lambda = \Delta_{\lambda-1}D(h_\lambda, z^{-t_\lambda}).$$

So,

$$\Delta_{\lambda}^{-1} \Delta_{\lambda+T} = \Delta_{\lambda-1}^{-1} \Delta_{\lambda+T-1}.$$

(2) & (3) Obvious.

(4) By Lemma 4.1, we have

$$J^*(\underline{\alpha}_k) = J^*(\underline{\alpha}_{k+l}) \subseteq \cdots \subseteq J^*(\underline{\alpha}_{k+1}) \subseteq J^*(\underline{\alpha}_k).$$

So, $J^*(\underline{\alpha}_{k+i}) = J^*(\underline{\alpha}_k)$ for any $0 \leq i \leq l$.

(5) Obvious. ■

5. The proof of the main theorem. In this section, we will prove the main theorem.

(1) \Rightarrow (2). Since $C(r)$ is (λ, T) -periodic, we have $h_{\lambda+k} = h_{\lambda+k+T}$ and $B_{\lambda+k, \lambda+l} = B_{\lambda+k+T, \lambda+l+T}$ for any $l > k \geq 0$. Then

$$\left(\frac{p_{\lambda+k, \lambda+l}}{q_{\lambda+k, \lambda+l}} \right) = \left(\frac{p_{\lambda+k+T, \lambda+l+T}}{q_{\lambda+k+T, \lambda+l+T}} \right).$$

Thus

$$\underline{\alpha}_{\lambda+k-1} = \lim_{l \rightarrow \infty} \frac{p_{\lambda+k, \lambda+l}}{q_{\lambda+k, \lambda+l}} = \lim_{l \rightarrow \infty} \frac{p_{\lambda+k+T, \lambda+l+T}}{q_{\lambda+k+T, \lambda+l+T}} = \underline{\alpha}_{\lambda+k+T-1}$$

for all $k \geq 0$ from Lemma 4.1.

Define $v_{\lambda+T-1, j} - v_{\lambda-1, j} = c_j$. Then

$$\Delta_{\lambda-1}^{-1} \Delta_{\lambda+T-1} = \text{Diag}(z^{-c_1}, \dots, z^{-c_m}), \quad \text{where } c_j = \sum_{\substack{\lambda \leq i < \lambda+T \\ h_i=j}} t_i.$$

Let $J = \{h_k \mid \lambda \leq k < \lambda + T\}$. Then

$$(*) \quad c_j \begin{cases} = 0 & \text{if } j \notin J, \\ > 0 & \text{if } j \in J. \end{cases}$$

We claim that c_j is a positive constant c for all $j \in J$, hence $\Delta_{\lambda-1}^{-1} \Delta_{\lambda+T-1} = D(J, z^{-c})$. In fact, for $k \geq \lambda, n \geq 1$ and $1 \leq j \leq m$, we have

$$(**) \quad v_k + nc_{h_k} = v_{k, h_k} + nc_{h_k} = v_{k+nT, h_k} = v_{k+nT, h_{k+nT}} = v_{k+nT} \\ \leq v_{k+nT-1, j} + v(\alpha_{k+nT-1, j}) = v_{k-1, j} + nc_j + v(\alpha_{k-1, j}),$$

where the inequality comes from the fact that

$$(h_k, v_{k+nT}) = (h_{k+nT}, v_{k+nT}) = Iv(\Delta_{k+nT-1} \underline{\alpha}_{k+nT-1}) \\ \leq (j, v_{k+nT-1, j} + v(\alpha_{k+nT-1, j})).$$

Then taking $j = h_{k+1}$, we have

$$v_k + nc_{h_k} \leq v_{k-1, h_{k+1}} + nc_{h_{k+1}} + t,$$

where $t = v(\alpha_{k-1, h_{k+1}}) \in \mathbb{Z}$, since $\alpha_{k-1, h_{k+1}} \neq 0$. This implies $c_{h_k} \leq c_{h_{k+1}}$ for any $k \geq \lambda$, since otherwise,

$$-n \geq n(c_{h_{k+1}} - c_{h_k}) \geq v_k - v_{k-1, h_{k+1}} - t$$

for all $n \geq 1$, a contradiction. So

$$c_{h_\lambda} \leq c_{h_{\lambda+1}} \leq \cdots \leq c_{h_{\lambda+T-1}} \leq c_{h_{\lambda+T}} = c_{h_\lambda}.$$

Thus $c_j = c_{h_\lambda}$ for any $j \in J$, i.e., c_j is equal to a positive constant c .

We claim that $J = J^*(\underline{\alpha}_{\lambda-1})$. In fact, if $j \in J$, then $j = h_k$ and $\alpha_{k-1, j} = \alpha_{k-1, h_k} \neq 0$ for some k satisfying $\lambda \leq k < \lambda + T$. Thus, $j \in J^*(\underline{\alpha}_{k-1}) \subseteq J^*(\underline{\alpha}_{\lambda-1})$ from Lemma 4.1.

If $j \notin J$, then

$$v_\lambda + nc = v_\lambda + nc_{h_\lambda} \leq v_{\lambda-1, j} + nc_j + v(\alpha_{\lambda-1, j}) = v_{\lambda-1, j} + v(\alpha_{\lambda-1, j})$$

for any $n \geq 1$ from (*) and (**). Noting that $c > 0$, we have $v(\alpha_{\lambda-1, j}) = \infty$ and $\alpha_{\lambda-1, j} = 0$. Thus, $j \notin J^*(\underline{\alpha}_{\lambda-1})$.

From the above we get immediately

$$\Delta_{\lambda-1}^{-1} \Delta_{\lambda+T-1} = D(J, z^{-c}) = D(J^*(\underline{\alpha}_{\lambda-1}), z^{-c}).$$

(2) \Rightarrow (3). By Lemma 4.2,

$$\Delta_{\lambda+T-1} \underline{\alpha}_{\lambda+T-1} = \Delta_{\lambda-1} D(J^*(\underline{\alpha}_{\lambda-1}), z^{-c}) \underline{\alpha}_{\lambda-1} = z^{-c} \Delta_{\lambda-1} \underline{\alpha}_{\lambda-1}.$$

Then $h_{\lambda+T} = I(\Delta_{\lambda+T-1} \underline{\alpha}_{\lambda+T-1}) = I(z^{-c} \Delta_{\lambda-1} \underline{\alpha}_{\lambda-1}) = h_\lambda$. By Lemma 4.2, we have $\underline{\varrho}_{\lambda+T} = \underline{\varrho}_\lambda$. So, $\underline{a}_{\lambda+T} = \underline{a}_\lambda$, $\underline{\alpha}_{\lambda+T} = \underline{\alpha}_\lambda$ and $t_{\lambda+T} = t_\lambda$. By Lemma 4.2,

$$\Delta_\lambda^{-1} \Delta_{\lambda+T} = \Delta_{\lambda-1}^{-1} \Delta_{\lambda+T-1} = D(J^*(\underline{\alpha}_{\lambda-1}), z^{-c}) = D(J^*(\underline{\varrho}_\lambda), z^{-c}).$$

(3) \Rightarrow (2). By Lemma 4.2,

$$\Delta_{\lambda+T} \underline{\varrho}_{\lambda+T} = \Delta_\lambda D(J^*(\underline{\varrho}_\lambda), z^{-c}) \underline{\varrho}_\lambda = z^{-c} \Delta_\lambda \underline{\varrho}_\lambda.$$

Then by Theorem 2.5,

$$h_{\lambda+T} = I(\Delta_{\lambda+T} \underline{\varrho}_{\lambda+T}) = I(z^{-c} \Delta_\lambda \underline{\varrho}_\lambda) = h_\lambda,$$

and

$$\begin{aligned} t_{\lambda+T} &= \deg(a_{\lambda+T, h_{\lambda+T}}) = \deg(\lfloor \varrho_{\lambda+T, h_{\lambda+T}} \rfloor) = \deg(\lfloor \varrho_{\lambda, h_{\lambda+T}} \rfloor) \\ &= \deg(\lfloor \varrho_{\lambda, h_\lambda} \rfloor) = \deg(a_{\lambda, h_\lambda}) = t_\lambda. \end{aligned}$$

Thus by Lemma 4.2,

$$\Delta_{\lambda-1}^{-1} \Delta_{\lambda+T-1} = \Delta_\lambda^{-1} \Delta_{\lambda+T} = D(J^*(\underline{\varrho}_\lambda), z^{-c}) = D(J^*(\underline{\alpha}_{\lambda-1}), z^{-c}).$$

(3) \Rightarrow (1). We already know that conditions (2) and (3) are equivalent, so we can suppose that they both hold. We claim that

- (a) $(h_{\lambda+T}, \underline{a}_{\lambda+T}) = (h_\lambda, \underline{a}_\lambda)$;
- (b) $\underline{\rho}_{\lambda+1+T} = \underline{\rho}_{\lambda+1}$, $\Delta_{\lambda+1}^{-1} \Delta_{\lambda+1+T} = D(J^*(\underline{\rho}_{\lambda+1}), z^{-c})$.

Repeating this process, we find that $C(r)$ is (λ, T) -periodic.

In fact, in (3) \Rightarrow (2) above, we have proven $h_{\lambda+T} = h_\lambda$. By definitions, $\underline{\rho}_{\lambda+T} = \underline{\rho}_\lambda$ implies that

$$\underline{a}_{\lambda+T} = \underline{a}_\lambda, \quad \underline{\alpha}_{\lambda+T} = \underline{\alpha}_\lambda.$$

Since (3) implies (2), we have $\underline{\alpha}_{\lambda+T-1} = \underline{\alpha}_{\lambda-1}$. Then $J^*(\underline{\alpha}_\lambda) = J^*(\underline{\alpha}_{\lambda-1}) = J^*(\underline{\rho}_\lambda)$ from Lemma 4.2. So

$$\Delta_\lambda^{-1} \Delta_{\lambda+T} = D(J^*(\underline{\rho}_\lambda), z^{-c}) = D(J^*(\underline{\alpha}_\lambda), z^{-c}).$$

Since (2) implies (3), from the above we conclude that

$$\underline{\rho}_{\lambda+1+T} = \underline{\rho}_{\lambda+1}, \quad \Delta_{\lambda+1}^{-1} \Delta_{\lambda+1+T} = D(J^*(\underline{\rho}_{\lambda+1}), z^{-c}). \quad \blacksquare$$

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State Key Laboratory of Information Security
Graduate School of Chinese Academy of Sciences
Beijing, 100049, P.R. China
E-mail: daizongduo@is.ac.cn
wangping@gucas.ac.cn
kpwang@gucas.ac.cn
fengxt@gmail.com

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