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## CHARACTERIZING EXPERIMENTAL DESIGNS BY PROPERTIES OF THE STANDARD QUADRATIC FORMS OF OBSERVATIONS

Abstract. For any orthogonal multi-way classification, the sums of squares appearing in the analysis of variance may be expressed by the standard quadratic forms involving only squares of the marginal and total sums of observations. In this case the forms are independent and nonnegative definite. We characterize all two-way classifications preserving these properties for some and for all of the standard quadratic forms.

1. Background. Consider an experimental design with two-way classification of observations. Let $y_{i j k}$ be the $k$ th observation in the $(i, j)$ th cell, and let

$$
\mathbf{y}=\left(y_{111}, \ldots, y_{11 n_{11}} ; \ldots ; y_{t v 1}, \ldots, y_{t v n_{t v}}\right)^{T}
$$

be the vector composed of the observations. A statistical model of $\mathbf{y}$ is usually derived from the following framework:

$$
\begin{equation*}
y_{i j k}=\mu+\alpha_{i}+\beta_{j}+\gamma_{i j}+e_{i j k}, \tag{1.1}
\end{equation*}
$$

$i=1, \ldots, t ; j=1, \ldots, v ; k=1, \ldots, n_{i j}$, where $\mu, \alpha_{i}, \beta_{j}$ and $\gamma_{i j}$ are deterministic real values, while $e_{i j k}$ is a random quantity representing the experimental error. The following assumptions about the error are standard:
(a) Vanishing expectation, i.e. $E\left(e_{i j k}\right)=0$ for all $i, j$ and $k$,
(b) Homogeneity of variances, say $\operatorname{var}\left(e_{i j k}\right)=\sigma^{2}$ for all $i, j$ and $k$,
(c) Vanishing covariances, i.e. $\operatorname{cov}\left(e_{i j k}, e_{i^{\prime} j^{\prime} k^{\prime}}\right)=0$ for $(i j k) \neq\left(i^{\prime} j^{\prime} k^{\prime}\right)$.

For testing problems an additional assumption about the distribution of the vector $\mathbf{y}$ is required. Usually it is assumed that $e_{i j k}$ is normally distributed.

[^0]Consequently, (1.1) leads to the following model:

$$
\begin{equation*}
y_{i j k} \sim \mathcal{N}\left(\mu+\alpha_{i}+\beta_{j}+\gamma_{i j}, \sigma^{2}\right) \text { and are independent. } \tag{1.2}
\end{equation*}
$$

We mention that the quantities $\mu, \alpha_{i}, \beta_{j}$ and $\gamma_{i j}$ are not parameters in the proper sense, because they are not identifiable by distributions. The standard likelihood ratio tests for hypotheses concerning $\alpha$ 's, $\beta$ 's and $\gamma$ 's are based on the following quadratic forms of $\mathbf{y}$ :

$$
\begin{align*}
S_{A}= & \min _{\mu} \sum_{i, j, k}\left(y_{i j k}-\mu\right)^{2}-\min _{\mu, \alpha_{i}} \sum_{i, j, k}\left(y_{i j k}-\mu-\alpha_{i}\right)^{2},  \tag{1.3}\\
S_{B}= & \min _{\mu} \sum_{i, j, k}\left(y_{i j k}-\mu\right)^{2}-\min _{\mu, \beta_{j}} \sum_{i, j, k}\left(y_{i j k}-\mu-\beta_{j}\right)^{2}  \tag{1.4}\\
S_{A, B}= & \min _{\mu, \alpha_{i, \beta_{j}}} \sum_{i, j, k}\left(y_{i j k}-\mu-\alpha_{i}-\beta_{j}\right)^{2}  \tag{1.5}\\
& -\min _{\mu, \alpha_{i, \beta_{j}}, \gamma_{i j}} \sum_{i, j, k}\left(y_{i j k}-\mu-\alpha_{i}-\beta_{j}-\gamma_{i j}\right)^{2} \\
S_{E}= & \min _{\mu, \alpha_{i, \beta_{j}}, \gamma_{i j}} \sum_{i, j, k}\left(y_{i j k}-\mu-\alpha_{i}-\beta_{j}-\gamma_{i j}\right)^{2} \tag{1.6}
\end{align*}
$$

(cf. Scheffé, 1959, or Lehmann, 1986). These quadratics represent the sums of squares for $\alpha, \beta$, interaction $\alpha \times \beta$ and error, respectively.

It will be shown that the sums of squares (1.3), (1.4) and (1.6) reduce, respectively, to the quadratic forms

$$
\begin{align*}
& Q_{A}(\mathbf{y})=\sum_{i} \frac{y_{i .}^{2}}{n_{i .}}-\frac{y^{2}}{n}  \tag{1.7}\\
& Q_{B}(\mathbf{y})=\sum_{j} \frac{y_{\cdot j}^{2}}{n_{\cdot j}}-\frac{y^{2}}{n}  \tag{1.8}\\
& Q_{E}(\mathbf{y})=\sum_{i, j, k} y_{i j k}^{2}-\sum_{i, j} \frac{y_{i j}^{2}}{n_{i j}} \tag{1.9}
\end{align*}
$$

where $y_{i j}=\sum_{k} y_{i j k}, y_{i .}=\sum_{j} y_{i j}, y_{. j}=\sum_{i} y_{i j}$ and $y=\sum_{i} y_{i .}$, but computing the sum of squares $S_{A, B}$ may not be easy in general. Fortunately, as we will show in the next sections, this computation simplifies considerably in the case of proportional frequencies in cells, i.e. when

$$
\begin{equation*}
n_{i j}=\frac{n_{i \cdot .} n_{\cdot j}}{n} \quad \text { for } i=1, \ldots, t ; j=1, \ldots, v \tag{1.10}
\end{equation*}
$$

where $n_{i .}=\sum_{j} n_{i j}, n_{. j}=\sum_{i} n_{i j}$ and $n=\sum_{i, j} n_{i j}$.
The condition (1.10) may be written in the concise form $\operatorname{rank}(\mathbf{N})=1$, where $\mathbf{N}=\left(n_{i j}\right)$ is the incidence matrix. It will be shown that in this regular
case $S_{A, B}$ may be represented as the quadratic form

$$
\begin{equation*}
Q_{A, B}(\mathbf{y})=\sum_{i, j} \frac{y_{i j}^{2}}{n_{i j}}-\sum_{i} \frac{y_{i .}^{2}}{n_{i .}}-\sum_{j} \frac{y_{\cdot j}^{2}}{n_{\cdot j}}+\frac{y^{2}}{n} \tag{1.11}
\end{equation*}
$$

Of course the expression (1.11) makes sense for arbitrary $\mathbf{N}$ with positive entries, although it may no longer coincide with the sum of squares $S_{A, B}$. We shall refer to (1.11) as the standard quadratic form. The aim of this paper is to characterize the experimental designs (i.e. matrices $\mathbf{N}$ ) for which the quadratic form $Q_{A, B}$ :
(i) coincides with the corresponding sum of squares $S_{A, B}$,
(ii) is nonnegative definite,
(iii) is independent of the other quadratic forms $Q_{A}, Q_{B}$ and $Q_{E}$.

Throughout this paper we shall assume that the incidence matrix $\mathbf{N}=\left(n_{i j}\right)$ is complete in the sense that

$$
\begin{equation*}
n_{i j}>0 \quad \text { for all } i=1, \ldots, t ; j=1, \ldots, v \tag{1.12}
\end{equation*}
$$

i.e. all cells in the two-way classification are non-empty.
2. Sums of squares in a two-way classification with proportional frequencies. Most of the statistical literature on this subject focuses on experiments with equal frequencies (cf. Scheffé, 1959, or Lehmann, 1986), or on general experiments with arbitrary frequencies in cells (see Searle, 1971). It is understandable that in the latter case the formulae derived are rather far from being explicit. Some more complete results concerning proportional frequencies can be found in Oktaba and Mikos (1970) in the context of models with restraints (weighted and nonweighted). They noted that the two kinds of restraints may lead to different tests. To avoid this disadvantage, we shall use a coordinate-free approach (cf. Lehmann, 1986, Sect. 7) based on the formulae (1.3)-(1.6).

Let us rewrite model (1.2) in vector-matrix form

$$
\begin{equation*}
\mathbf{y} \sim \mathcal{N}\left(\mu \mathbf{1}_{n}+\mathbf{A} \boldsymbol{\alpha}+\mathbf{B} \boldsymbol{\beta}+\mathbf{C} \boldsymbol{\gamma}, \sigma^{2} \mathbf{I}_{n}\right) \tag{2.1}
\end{equation*}
$$

where $\mathbf{y}$ is the observation $n$-vector, $\boldsymbol{\alpha}=\left(\alpha_{1}, \ldots, \alpha_{t}\right)^{T}, \boldsymbol{\beta}=\left(\beta_{1}, \ldots, \beta_{v}\right)^{T}$ and $\gamma=\left(\gamma_{11}, \ldots, \gamma_{t v}\right)^{T}$ are vectors of parameters, $\mathbf{A}_{n \times t}=\left[\mathbf{a}_{1}, \ldots, \mathbf{a}_{t}\right]$ and $\mathbf{B}_{n \times v}=\left[\mathbf{b}_{1}, \ldots, \mathbf{b}_{v}\right]$ are matrices of zeros and ones satisfying the conditions

$$
\begin{equation*}
\sum_{i=1}^{t} \mathbf{a}_{i}=\sum_{j=1}^{v} \mathbf{b}_{j}=\mathbf{1}_{n} \tag{2.2}
\end{equation*}
$$

while

$$
\begin{equation*}
\mathbf{C}_{n \times t v}=\left[\mathbf{c}_{11}, \ldots, \mathbf{c}_{t v}\right] \tag{2.3}
\end{equation*}
$$

is the matrix with columns $\mathbf{c}_{i j}=\mathbf{a}_{i} * \mathbf{b}_{j}, i=1, \ldots, t ; j=1, \ldots, v$, where $*$ denotes the Hadamard product of vectors (see e.g. Stępniak, 1983).

We shall prove
Theorem 1. Given a complete incidence matrix $\mathbf{N}=\left(n_{i j}\right)$ let $y_{i j k}$, $i=1, \ldots, t ; j=1, \ldots, v ; k=1, \ldots, n_{i j}$, be observations represented by (1.1), $S_{A}, S_{B}, S_{A, B}$ and $S_{E}$ be the sums of squares defined by (1.3)-(1.6), and $Q_{A}, Q_{B}, Q_{E}$ and $Q_{A, B}$ be the quadratic forms of the observations defined by (1.7)-(1.9) and (1.11). Then $S_{A}=Q_{A}, S_{B}=Q_{B}$ and $S_{E}=Q_{E}$, while $S_{A, B}=Q_{A, B}$ providing $\operatorname{rank}(\mathbf{N})=1$.

The proof of this theorem is based on the following lemma:
LEMMA 1. Let $\mathbf{a}_{1}, \ldots, \mathbf{a}_{t}$ and $\mathbf{b}_{1}, \ldots, \mathbf{b}_{v}$ be arbitrary $n$-vectors of zeros and ones satisfying the conditions (2.2), $\mathbf{c}_{i j}, i=1, \ldots, t ; j=1, \ldots, v$, be vectors defined by (2.3), $\mathbf{N}=\left(n_{i j}\right)$ be the complete matrix defined by $n_{i j}=$ $\mathbf{a}_{i}^{T} \mathbf{b}_{j}$, with marginals $n_{i}$. and $n_{. j}$ for $i=1, \ldots, t ; j=1, \ldots, v$, and $\mathbf{1}_{n}, \mathbf{A}$, $\mathbf{B}$ and $\mathbf{C}$ be the matrices appearing in (2.1). Then the orthogonal projector onto the column space of $[\mathbf{A}, \mathbf{B}]$ is given by

$$
\mathbf{P}=\sum_{i=1}^{t} \frac{1}{n_{i .}} \mathbf{a}_{i} \mathbf{a}_{i}^{T}+\sum_{j=1}^{v} \frac{1}{n_{. j}} \mathbf{b}_{j} \mathbf{b}_{j}^{T}-\frac{1}{n} \mathbf{1}_{n} \mathbf{1}_{n}^{T}
$$

providing the condition (1.10) holds.
Proof. Let us rewrite $\mathbf{P}$ in the form

$$
\begin{equation*}
\mathbf{P}=\mathbf{P}_{1}+\mathbf{P}_{2}+\mathbf{P}_{3} \tag{2.4}
\end{equation*}
$$

where

$$
\begin{align*}
& \mathbf{P}_{1}=\sum_{i=1}^{t} \frac{1}{n_{i .}} \mathbf{a}_{i} \mathbf{a}_{i}^{T}-\frac{1}{n} \mathbf{1}_{n} \mathbf{1}_{n}^{T}  \tag{2.5}\\
& \mathbf{P}_{2}=\sum_{j=1}^{v} \frac{1}{n_{. j}} \mathbf{b}_{j} \mathbf{b}_{j}^{T}-\frac{1}{n} \mathbf{1}_{n} \mathbf{1}_{n}^{T}  \tag{2.6}\\
& \mathbf{P}_{3}=\frac{1}{n} \mathbf{1}_{n} \mathbf{1}_{n}^{T} \tag{2.7}
\end{align*}
$$

First we will show that

$$
\mathbf{P}_{i} \mathbf{P}_{j}= \begin{cases}\mathbf{P}_{i} & \text { if } i=j,  \tag{2.8}\\ \mathbf{0} & \text { otherwise } .\end{cases}
$$

It is easy to verify that $\mathbf{P}_{i}^{2}=\mathbf{P}_{i}$ for $i=1,2,3$ and $\mathbf{P}_{1} \mathbf{P}_{3}=\mathbf{P}_{2} \mathbf{P}_{3}=\mathbf{0}$. Moreover,

$$
\begin{aligned}
\mathbf{P}_{1} \mathbf{P}_{2} & =\left(\sum_{i=1}^{t} \frac{1}{n_{i .}} \mathbf{a}_{i} \mathbf{a}_{i}^{T}-\frac{1}{n} \mathbf{1}_{n} \mathbf{1}_{n}^{T}\right)\left(\sum_{j=1}^{v} \frac{1}{n_{\cdot j}} \mathbf{b}_{j} \mathbf{b}_{j}^{T}-\frac{1}{n} \mathbf{1}_{n} \mathbf{1}_{n}^{T}\right) \\
& =\sum_{i, j} \frac{n_{i j}}{n_{i \cdot n} n_{\cdot j}} \mathbf{a}_{i} \mathbf{b}_{j}^{T}-\frac{1}{n} \sum_{i} \mathbf{a}_{i} \mathbf{1}_{n}^{T}-\frac{1}{n} \sum_{j} \mathbf{1}_{n} \mathbf{b}_{j}^{T}+\frac{1}{n} \mathbf{1}_{n} \mathbf{1}_{n}^{T}
\end{aligned}
$$

Thus, by (1.10) and (2.2), we get

$$
\mathbf{P}_{1} \mathbf{P}_{2}=\frac{1}{n} \sum_{i} \mathbf{a}_{i}\left(\sum_{j} \mathbf{b}_{j}^{T}-\mathbf{1}_{n}^{T}\right)-\frac{1}{n} \mathbf{1}_{n}\left(\sum_{j} \mathbf{b}_{j}^{T}-\mathbf{1}_{n}^{T}\right)=\mathbf{0}
$$

In this way we have proved (2.8), which implies that $\mathbf{P}$ is idempotent.
Now it remains to show that range $(\mathbf{P})=\operatorname{range}\left(\left[\mathbf{a}_{1}, \ldots, \mathbf{a}_{t}, \mathbf{b}_{1}, \ldots, \mathbf{b}_{v}\right]\right)$. Indeed, $\mathbf{P x}=\mathbf{0}$ for any vector $\mathbf{x}$ such that $\mathbf{a}_{i}^{T} \mathbf{x}=\mathbf{b}_{j}^{T} \mathbf{x}=0$ for all $i$ and $j$. Moreover, by $(2.2), \operatorname{rank}\left(\left[\mathbf{a}_{1}, \ldots, \mathbf{a}_{t}, \mathbf{b}_{1}, \ldots, \mathbf{b}_{v}\right]\right) \leq t+v-1$, while $\operatorname{rank}(\mathbf{P})=$ $t+v-1$. This implies the desired condition and completes the proof of the lemma.

Proof of Theorem 1. In vector-matrix notation the sums of squares (1.3)(1.6) may be expressed as

$$
\begin{aligned}
S_{A}(\mathbf{y}) & =\left\|\mathbf{y}-\mathbf{P}_{1_{n}} \mathbf{y}\right\|^{2}-\left\|\mathbf{y}-\mathbf{P}_{A} \mathbf{y}\right\|^{2}=\mathbf{y}^{T} \mathbf{P}_{A} \mathbf{y}-\frac{1}{n} \mathbf{y}^{T} \mathbf{1}_{n} \mathbf{1}_{n}^{T} \mathbf{y}=\mathbf{y}^{T} \mathbf{P}_{1} \mathbf{y} \\
S_{B}(\mathbf{y}) & =\left\|\mathbf{y}-\mathbf{P}_{1_{n}} \mathbf{y}\right\|^{2}-\left\|\mathbf{y}-\mathbf{P}_{B} \mathbf{y}\right\|^{2}=\mathbf{y}^{T} \mathbf{P}_{B} \mathbf{y}-\frac{1}{n} \mathbf{y}^{T} \mathbf{1}_{n} \mathbf{1}_{n}^{T} \mathbf{y}=\mathbf{y}^{T} \mathbf{P}_{2} \mathbf{y} \\
S_{A, B}(\mathbf{y}) & =\|\mathbf{y}-\mathbf{P} \mathbf{y}\|^{2}-\left\|\mathbf{y}-\mathbf{P}_{C} \mathbf{y}\right\|^{2}=\mathbf{y}^{T} \mathbf{P}_{C} \mathbf{y}-\mathbf{y}^{T} \mathbf{P} \mathbf{y} \\
S_{E}(\mathbf{y}) & =\left\|\mathbf{y}-\mathbf{P}_{C} \mathbf{y}\right\|^{2}=\mathbf{y}^{T} \mathbf{y}-\mathbf{y}^{T} \mathbf{P}_{C} \mathbf{y}
\end{aligned}
$$

where $\mathbf{P}_{M}$ denotes the orthogonal projector onto the column space of $\mathbf{M}$, $\mathbf{C}$ is defined by (2.3), while $\mathbf{P}, \mathbf{P}_{1}$ and $\mathbf{P}_{2}$ are defined by (2.4)-(2.5) and (2.6). Now the theorem follows from Lemma 1.
3. Characterizing experimental designs by standard quadratic forms. Let $\mathbf{y}=\left(y_{111}, \ldots, y_{11 n_{11}} ; \ldots ; y_{t v 1}, \ldots, y_{t v n_{t v}}\right)^{T}$ be subject to the normal linear model $\mathcal{N}\left(\mu \mathbf{1}_{n}+\mathbf{A} \boldsymbol{\alpha}+\mathbf{B} \boldsymbol{\beta}+\mathbf{C} \boldsymbol{\gamma}, \sigma^{2} \mathbf{I}_{n}\right)$, and let $Q_{A}, Q_{B}, Q_{E}$ and $Q_{A, B}$ be defined by (1.7)-(1.9) and (1.11). We are interested in properties of the quadratic form $Q_{A, B}$ and its relations with the remaining quadratics.

THEOREM 2. The quadratic form $Q_{A, B}$ is nonnegative definite if and only if the allocation of the observations in cells is proportional, i.e. $\operatorname{rank}(\mathbf{N})=1$.

Proof. Assume that $n_{i j}=n_{i .} n_{. j} / n$ for all $i$ and $j$. Then

$$
\sum_{i=1}^{t} \sum_{j=1}^{v} \frac{y_{i j}^{2}}{n_{i j}}-\sum_{i=1}^{t} \frac{y_{i .}^{2}}{n_{i .}}-\sum_{j=1}^{v} \frac{y_{\cdot j}^{2}}{n_{\cdot j}}+\frac{y^{2}}{n}=\sum_{i, j} n_{i j}\left(\frac{y_{i j}}{n_{i j}}-\frac{y_{i .}}{n_{i .}}-\frac{y_{. j}}{n_{. j}}+\frac{y}{n}\right)^{2}
$$

implying $Q_{A, B}(\mathbf{y}) \geq 0$ for all $\mathbf{y}$.

Conversely, assume that $Q_{A, B}(\mathbf{y}) \geq 0$ for all $\mathbf{y}$ and set

$$
y_{i j}= \begin{cases}n_{i j} & \text { if } j=k \\ 0 & \text { otherwise }\end{cases}
$$

where $k$ is fixed but arbitrary. Then $Q_{A, B}(\mathbf{y})$ reduces to $n_{. k}^{2} / n-\sum_{i} n_{. k}^{2} / n_{i .}$, and consequently, it may be presented in the form $Q_{A, B}(\mathbf{y})=-n \operatorname{Var}(X)$, where $X$ is a random variable taking values $x_{i}=n_{i k} / n_{i}$. with probabilities $p_{i}=n_{i .} / n$ for $i=1, \ldots, t$. Thus the condition $Q_{A, B}(\mathbf{y}) \geq 0$ for all $\mathbf{y}$ implies

$$
\begin{equation*}
n_{i k}=c n_{i .}, \quad i=1, \ldots, t \tag{3.1}
\end{equation*}
$$

for some $c$. On the other hand, by the definition $n_{. k}=\sum_{i} n_{i k}$ we get

$$
\begin{equation*}
c=\frac{n_{. k}}{n} . \tag{3.2}
\end{equation*}
$$

Combining (3.1) and (3.2) we obtain $n_{i k}=n_{i .} n_{. k} / n$ for $i=1, \ldots, t$. This completes the proof of necessity, and hence the proof of Theorem 2.

Now let us examine conditions for independence of the quadratic forms $Q_{A}, Q_{B}, Q_{A, B}$ and $Q_{E}$.

Theorem 3. Let $\mathbf{y}=\left(y_{111}, \ldots, y_{11 n_{11}} ; \ldots ; y_{t v 1}, \ldots, y_{t v n_{t v}}\right)^{T}$ be subject to the normal linear model $\mathcal{N}\left(\mu \mathbf{1}_{n}+\mathbf{A} \boldsymbol{\alpha}+\mathbf{B} \boldsymbol{\beta}+\mathbf{C} \gamma, \sigma^{2} \mathbf{I}_{n}\right)$, and let $Q_{A}, Q_{B}$, $Q_{E}$ and $Q_{A, B}$ be defined by (1.7)-(1.9) and (1.11), respectively. Then $Q_{E}$ is always independent of the other quadratic forms. Moreover the following conditions are equivalent:
(a) $\operatorname{rank}(\mathbf{N})=1$,
(b) $Q_{A}$ is independent of $Q_{B}$,
(c) $Q_{A}$ is independent of $Q_{A, B}$,
(d) $Q_{B}$ is independent of $Q_{A, B}$.

Proof. The first assertion follows immediately from the fact that in the simple normal sample the sample mean is independent of the sample variance.

Next, by Craig's theorem (e.g. Mathai and Provost, 1992, p. 209 or Harville and Kempthorne, 1997) two quadratic forms $\mathbf{y}^{T} \mathbf{M}_{1} \mathbf{y}$ and $\mathbf{y}^{T} \mathbf{M}_{2} \mathbf{y}$ are independent if and only if $\mathbf{M}_{1} \mathbf{M}_{2}=\mathbf{0}$. Recall that the matrices of the quadratics $Q_{A}, Q_{B}$, and $Q_{A, B}$, may be represented in the form $\mathbf{P}_{1}, \mathbf{P}_{2}$ and $\mathbf{P}_{0}-\mathbf{P}_{1}-\mathbf{P}_{2}$, where $\mathbf{P}_{1}$ and $\mathbf{P}_{2}$ are defined by (2.5) and (2.6), while

$$
\mathbf{P}_{0}=\sum_{i, j} \frac{1}{n_{i j}} \mathbf{c}_{i j} \mathbf{c}_{i j}^{T}-\frac{1}{n} \mathbf{1}_{n} \mathbf{1}_{n}^{T}
$$

$(\mathrm{a}) \Leftrightarrow(\mathrm{b})$. We observe that

$$
\mathbf{P}_{1} \mathbf{P}_{2}=\sum_{j=1}^{v}\left(\sum_{i=1}^{t} \frac{n_{i j}}{n_{i \cdot n_{. j}}} \mathbf{a}_{i}-\frac{1}{n} \mathbf{1}_{n}\right) \mathbf{b}_{j}^{T}
$$

and, by (2.2),

$$
\mathbf{P}_{1} \mathbf{P}_{2}=\sum_{j=1}^{v} \sum_{i=1}^{t}\left(\frac{n_{i j}}{n_{i . n_{\cdot j}}}-\frac{1}{n}\right) \mathbf{a}_{i} \mathbf{b}_{j}^{T} .
$$

Thus we get the equivalence of (a) and (b).
$(\mathrm{a}) \Leftrightarrow(\mathrm{c})$ and $(\mathrm{a}) \Leftrightarrow(\mathrm{d})$. Since $\mathbf{P}_{i}$ is idempotent for $i=0,1,2$, and $\mathbf{P}_{0} \mathbf{P}_{i}=$ $\mathbf{P}_{i}$ for $i=1,2$, we get $\left(\mathbf{P}_{0}-\mathbf{P}_{1}-\mathbf{P}_{2}\right) \mathbf{P}_{1}=\mathbf{P}_{2} \mathbf{P}_{1}$ and $\left(\mathbf{P}_{0}-\mathbf{P}_{1}-\mathbf{P}_{2}\right) \mathbf{P}_{2}=$ $\mathbf{P}_{1} \mathbf{P}_{2}$. Now the desired results follow from the equivalence of (a) and (b).

This completes the proof.
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