

YOUSSEF AKDIM and CHAKIR ALLALOU (Taza)

## EXISTENCE OF A RENORMALIZED SOLUTION OF NONLINEAR DEGENERATE ELLIPTIC PROBLEMS

*Abstract.* We study a general class of nonlinear elliptic problems associated with the differential inclusion  $\beta(u) - \operatorname{div}(a(x, Du) + F(u)) \ni f$  in  $\Omega$  where  $f \in L^\infty(\Omega)$ . The vector field  $a(\cdot, \cdot)$  is a Carathéodory function. Using truncation techniques and the generalized monotonicity method in function spaces we prove existence of renormalized solutions for general  $L^\infty$ -data.

**1. Introduction.** Let  $\Omega$  be a bounded open subset of  $\mathbb{R}^N$  ( $N \geq 1$ ) with Lipschitz boundary if  $N \geq 2$ , let  $p$  be a real number such that  $1 < p < \infty$  and  $w = \{w_i(x), 0 \leq i \leq N\}$  be a vector of weight functions on  $\Omega$  (i.e., every component  $w_i(x)$  is a measurable function which is positive a.e. in  $\Omega$ ). Let  $W_0^{1,p}(\Omega, w)$  be the weighted Sobolev space associated with the vector  $w$ . Our aim is to show existence of renormalized solutions to the nonlinear elliptic equation

$$(E, f) \quad \begin{cases} \beta(u) - \operatorname{div}(a(x, Du) + F(u)) \ni f & \text{in } \Omega, \\ u = 0 & \text{on } \partial\Omega. \end{cases}$$

with right-hand side  $f \in L^\infty(\Omega)$ . Furthermore,  $F$  and  $\beta$  are functions satisfying the following assumption:

(A<sub>0</sub>)  $F: \mathbb{R} \rightarrow \mathbb{R}^N$  is locally Lipschitz continuous and  $\beta: \mathbb{R} \rightarrow 2^{\mathbb{R}}$  a set valued, maximal monotone mapping such that  $0 \in \beta(0)$ . Moreover,

$$(1.1) \quad \beta^0(l) \in L^1(\Omega)$$

for each  $l \in \mathbb{R}$ , where  $\beta^0$  denotes the minimal selection of the graph of  $\beta$ , that is,  $\beta_0(l) = \inf\{|r| \mid r \in \mathbb{R} \text{ and } r \in \beta(l)\}$ .

Moreover,  $a: \Omega \times \mathbb{R}^N \rightarrow \mathbb{R}^N$  is a Carathéodory function satisfying the following assumptions:

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2010 *Mathematics Subject Classification*: Primary 35J70; Secondary 35J85.

*Key words and phrases*: weighted Sobolev spaces, Hardy inequality, degenerate elliptic.

(A<sub>1</sub>) There exists a positive constant  $\lambda$  such that

$$a(x, \xi) \cdot \xi \geq \lambda \sum_{i=1}^N w_i |\xi_i|^p$$

for all  $\xi \in \mathbb{R}^N$  and almost every  $x \in \Omega$ .

(A<sub>2</sub>)  $|a_i(x, \xi)| \leq \alpha w_i^{1/p}(x) [k(x) + \sum_{j=1}^N w_j^{1/p'}(x) |\xi_j|^{p-1}]$  for almost every  $x \in \Omega$ , all  $i = 1, \dots, N$ , and every  $\xi \in \mathbb{R}^N$ , where  $k(\cdot)$  is a non-negative function in  $L^{p'}(\Omega)$ ,  $p' = p/(p - 1)$ , and  $\alpha > 0$ .

(A<sub>3</sub>)  $(a(x, \xi) - a(x, \eta)) \cdot (\xi - \eta) \geq 0$  for almost every  $x \in \Omega$  and every  $\xi, \eta \in \mathbb{R}^N$ .

Note that in the case with variable exponents and Orlicz spaces the problem was studied by Wittbold et al. [9, 12]. Other work in this direction can be found in [2, 5, 6].

**2. Preliminaries.** Let  $\Omega$  be a bounded open subset of  $\mathbb{R}^N$  ( $N \geq 1$ ), let  $p$  be a real number such that  $1 < p < \infty$ , and let  $w = \{w_i(x), 0 \leq i \leq N\}$  be a vector of weight functions, i.e., every component  $w_i(x)$  is a measurable function which is positive a.e. in  $\Omega$ . Further, we suppose in all our considerations that

(2.1) 
$$w_i \in L^1_{\text{loc}}(\Omega),$$

(2.2) 
$$w_i^{-1/(p-1)} \in L^1_{\text{loc}}(\Omega),$$

for any  $0 \leq i \leq N$ . We denote by  $W^{1,p}(\Omega, w)$  the space of all real-valued functions  $u \in L^p(\Omega, w_0)$  such that the derivatives in the sense of distributions fulfill  $\partial u / \partial x_i \in L^p(\Omega, w_i)$  for  $i = 1, \dots, N$ , which is a Banach space under the norm

(2.3) 
$$\|u\|_{1,p,w} = \left[ \int_{\Omega} |u(x)|^p w_0(x) dx + \sum_{i=1}^N \int_{\Omega} \left| \frac{\partial u(x)}{\partial x_i} \right|^p w_i(x) dx \right]^{1/p}.$$

The condition (2.1) implies that  $C^\infty_0(\Omega)$  is a subspace of  $W^{1,p}(\Omega, w)$ , and consequently we can define the subspace  $X = W^{1,p}_0(\Omega, w)$  of  $W^{1,p}(\Omega, w)$  as the closure of  $C^\infty_0(\Omega)$  with respect to the norm (2.3). Moreover, condition (2.2) implies that  $W^{1,p}(\Omega, w)$  as well as  $W^{1,p}_0(\Omega, w)$  are reflexive Banach spaces. We recall that the dual space of  $W^{1,p}_0(\Omega, w)$  is equivalent to  $W^{-1,p'}(\Omega, w^*)$ , where  $w^* = \{w_i^* = w_i^{1-p'}, i = 0, \dots, N\}$  and where  $p'$  is the conjugate of  $p$ , i.e.  $p' = p/(p - 1)$  (for more details we refer to [10]).

ASSUMPTION (H1). The expression

$$\|u\|_X = \left( \sum_{i=1}^N \int_{\Omega} \left| \frac{\partial u(x)}{\partial x_i} \right|^p w_i(x) dx \right)^{1/p}$$

is a norm defined on  $X$  and is equivalent to the norm (2.3). There exist a weight function  $\sigma$  on  $\Omega$  and a parameter  $q$ ,  $1 < q < \infty$ , such that

$$(2.4) \quad \sigma^{1-q'} \in L^1(\Omega),$$

with  $q' = q/(q - 1)$ . The Hardy inequality,

$$(2.5) \quad \left( \int_{\Omega} |u(x)|^q \sigma \, dx \right)^{1/q} \leq c \left( \sum_{i=1}^N \int_{\Omega} \left| \frac{\partial u(x)}{\partial x_i} \right|^p w_i(x) \, dx \right)^{1/p},$$

holds for every  $u \in X$  with a constant  $c > 0$  independent of  $u$ , and moreover the imbedding

$$(2.6) \quad X \hookrightarrow L^q(\Omega, \sigma),$$

expressed by the inequality (2.5), is compact. Note that  $(X, \|\cdot\|_X)$  is a uniformly convex (and thus reflexive) Banach space.

### 3. Notion of solutions and existence results

DEFINITION 3.1. A *renormalized solution* to  $(E, f)$  is a pair of functions  $(u, b)$  satisfying the following conditions:

(R1)  $u : \Omega \rightarrow \mathbb{R}$  is measurable,  $b \in L^1(\Omega)$ ,  $u(x) \in \mathcal{D}(\beta(x))$  and  $b(x) \in \beta(u(x))$  for a.e.  $x \in \Omega$ .

(R2) For each  $k > 0$ ,  $T_k(u) \in W_0^{1,p}(\Omega, w)$  and

$$(3.1) \quad \int_{\Omega} b \cdot h(u)\varphi + \int_{\Omega} (a(x, Du) + F(u)) \cdot D(h(u)\varphi) = \int_{\Omega} fh(u)\varphi$$

for all  $h \in C_c^1(\mathbb{R})$  and all  $\varphi \in W_0^{1,p}(\Omega, w) \cap L^\infty(\Omega)$ , where  $T_k(\cdot)$  is truncation at height  $k$ .

(R3)  $\int_{\{k \leq |u| \leq k+1\}} a(x, Du) \cdot Du \rightarrow 0$  as  $k \rightarrow \infty$ .

THEOREM 3.2. Under assumptions  $(H_1)$ ,  $(A_0)$ – $(A_3)$  and  $f \in L^\infty(\Omega)$  there exists at least one renormalized solution  $(u, b)$  to  $(E, f)$ .

*Proof.* STEP 1: *Approximate problem.* First we approximate  $(E, f)$  for  $f \in L^\infty(\Omega)$  by problems for which existence can be proved by standard variational arguments. For  $0 < \varepsilon \leq 1$ , let  $\beta_\varepsilon : \mathbb{R} \rightarrow \mathbb{R}$  be the Yosida approximation of  $\beta$  (see [7]). We introduce the operators

$$A_{1,\varepsilon} : W_0^{1,p}(\Omega, w) \rightarrow W^{-1,p'}(\Omega, w^*), \quad u \mapsto \beta_\varepsilon(T_{1/\varepsilon}(u)) - \operatorname{div} a(x, Du),$$

$$A_{2,\varepsilon} : W_0^{1,p}(\Omega, w) \rightarrow W^{-1,p'}(\Omega, w^*), \quad u \mapsto -\operatorname{div} F(T_{1/\varepsilon}(u)).$$

Because of  $(A_2)$  and  $(A_3)$ ,  $A_{1,\varepsilon}$  is well-defined and monotone (see [11, p. 157]). Since  $\beta_\varepsilon \circ T_{1/\varepsilon}$  is bounded and continuous and thanks to the growth condition  $(A_2)$  on  $a$ , it follows that  $A_{1,\varepsilon}$  is hemicontinuous (see [11, p. 157]). From the continuity and boundedness of  $F \circ T_{1/\varepsilon}$  it follows that  $A_{2,\varepsilon}$  is strongly continuous. Therefore  $A_\varepsilon := A_{1,\varepsilon} + A_{2,\varepsilon}$  is pseudomonotone. Using

the monotonicity of  $\beta_\varepsilon$ , the Gauss–Green Theorem for Sobolev functions and the boundary condition on the convection term  $\int_\Omega F(T_{1/\varepsilon}(u)) \cdot Du$ , we show by similar arguments to [5] that  $A_\varepsilon$  is coercive and bounded. Then it follows from [11, Theorem 2.7] that  $A_\varepsilon$  is surjective, i.e., for each  $0 < \varepsilon \leq 1$  and  $f \in W^{-1,p'}(\Omega, w^*)$  there exists a solution  $u_\varepsilon \in W_0^{1,p}(\Omega, w)$  to the problem

$$(E_\varepsilon, f) \quad \begin{cases} \beta_\varepsilon(T_{1/\varepsilon}(u_\varepsilon)) - \operatorname{div}(a(x, Du_\varepsilon) + F(T_{1/\varepsilon}(u_\varepsilon))) = f & \text{in } \Omega, \\ u_\varepsilon = 0 & \text{on } \partial\Omega, \end{cases}$$

such that

$$(3.2) \quad \int_\Omega \beta_\varepsilon(T_{1/\varepsilon}(u_\varepsilon))\varphi + \int_\Omega (a(x, Du_\varepsilon) + F(T_{1/\varepsilon}(u_\varepsilon))) \cdot D\varphi = \langle f, \varphi \rangle$$

for all  $\varphi \in W_0^{1,p}(\Omega, w)$ .

STEP 2: *A priori estimates*

LEMMA 3.3. *For  $0 < \varepsilon \leq 1$  and  $f \in L^\infty(\Omega)$  let  $u_\varepsilon \in W_0^{1,p}(\Omega, w)$  be a solution of  $(E_\varepsilon, f)$ . Then:*

- (i) *There exists a constant  $C_1 = C_1(\|f\|_\infty, \lambda, p, N) > 0$ , not depending on  $\varepsilon$ , such that*

$$(3.3) \quad \|u_\varepsilon\| \leq C_1.$$

(ii)

$$(3.4) \quad \|\beta_\varepsilon(T_{1/\varepsilon}(u_\varepsilon))\|_\infty \leq \|f\|_\infty$$

- (iii) *For all  $l, k > 0$  we have*

$$(3.5) \quad \int_{\{|u_\varepsilon| \leq l+k\}} a(x, Du_\varepsilon) \cdot Du_\varepsilon \leq k \int_{\{|u_\varepsilon| > l\}} |f|.$$

*Proof.* (i) Taking  $u_\varepsilon$  as a test function in (3.2) we obtain

$$\int_\Omega \beta_\varepsilon(T_{1/\varepsilon}(u_\varepsilon))u_\varepsilon \, dx + \int_\Omega a(x, Du_\varepsilon) \cdot Du_\varepsilon \, dx + \int_\Omega F(T_{1/\varepsilon}(u_\varepsilon)) \cdot Du_\varepsilon \, dx = \int_\Omega f u_\varepsilon \, dx$$

As the first term on the left-hand side is nonnegative and the integral over the convection term vanishes, by (A<sub>1</sub>) we have

$$\begin{aligned} \lambda \sum_{i=1}^N \int_\Omega \left| \frac{\partial u_\varepsilon}{\partial x_i} \right|^p w_i(x) \, dx &\leq \sum_{i=1}^N \int_\Omega a_i(x, Du_\varepsilon) \cdot \frac{\partial u_\varepsilon}{\partial x_i} \, dx \leq \int_\Omega f u_\varepsilon \, dx \\ &\leq C \|f\|_\infty \left( \sum_{i=1}^N \int_\Omega \left| \frac{\partial u_\varepsilon(x)}{\partial x_i} \right|^p w_i(x) \, dx \right)^{1/p} \left( \int_\Omega \sigma^{1-q'} \, dx \right)^{1/q'} \end{aligned}$$

(due to (2.5)). Thus  $\|u_\varepsilon\|^p \leq C_2 \|u_\varepsilon\|$  where  $C_2$  is a positive constant. Hence we can deduce that  $u_\varepsilon$  remains bounded in  $W_0^{1,p}(\Omega, w)$ , i.e.,  $\|u_\varepsilon\| \leq C_1$ .

(ii) Taking  $\frac{1}{\delta} [T_{k+\delta}(\beta_\varepsilon(T_{1/\varepsilon}(u_\varepsilon))) - T_k(\beta_\varepsilon(T_{1/\varepsilon}(u_\varepsilon)))]$  as a test function in (3.2), letting  $\delta \rightarrow 0$  and choosing  $k > \|f\|_\infty$  we obtain (ii).

(iii) For  $k, l > 0$  fixed we take  $T_k(u_\varepsilon - T_l(u_\varepsilon))$  as a test function in (3.2). Using  $\int_\Omega a(x, Du_\varepsilon) \cdot DT_k(u_\varepsilon - T_l(u_\varepsilon)) dx = \int_{\{l < |u_\varepsilon| < l+k\}} a(x, Du_\varepsilon) \cdot Du_\varepsilon dx$ , and as the first term on the left-hand side is nonnegative and the convection term vanishes, we get

$$\int_{\{l < |u_\varepsilon| < l+k\}} a(x, Du_\varepsilon) \cdot Du_\varepsilon dx \leq \int_\Omega f T_k(u_\varepsilon - T_l(u_\varepsilon)) dx \leq k \int_{\{|u_\varepsilon| > l\}} |f| dx.$$

REMARK 3.4. For  $k > 0$ , since

$$(3.6) \quad |\{|u_\varepsilon| > l\}| \leq \frac{C_2}{l^{1-1/p}},$$

from Lemma 3.3(iii) we deduce that

$$(3.7) \quad \int_{\{l \leq |u_\varepsilon| \leq l+k\}} a(x, Du_\varepsilon) \cdot Du_\varepsilon \leq k \|f\|_\infty |\{|u_\varepsilon| > l\}| \leq \frac{C_2(k)}{l^{1-1/p}}.$$

STEP 3: Basic convergence results

LEMMA 3.5. For  $0 < \varepsilon \leq 1$  and  $f \in L^\infty(\Omega)$  let  $u_\varepsilon \in W_0^{1,p}(\Omega, w)$  be the solution of  $(E_\varepsilon, f)$ . There exist  $u \in W_0^{1,p}(\Omega, w)$  and  $b \in L^\infty(\Omega)$  such that for a not relabeled subsequence of  $(u_\varepsilon)_{0 < \varepsilon \leq 1}$  as  $\varepsilon \downarrow 0$ :

$$(3.8) \quad u_\varepsilon \rightharpoonup u \quad \text{in } W_0^{1,p}(\Omega, w) \text{ and a.e. in } \Omega,$$

$$(3.9) \quad T_k(u_\varepsilon) \rightharpoonup T_k(u) \quad \text{in } W_0^{1,p}(\Omega, w) \text{ and strongly in } L^q(\Omega, \sigma),$$

$$(3.10) \quad \beta_\varepsilon(T_{1/\varepsilon}(u_\varepsilon)) \rightharpoonup b \quad \text{in } L^\infty(\Omega),$$

Moreover, for any  $k > 0$

$$(3.11) \quad DT_k(u_\varepsilon) \rightharpoonup DT_k(u) \quad \text{in } \prod_{i=1}^N L^p(\Omega, w_i),$$

$$(3.12) \quad a(x, DT_k(u_\varepsilon)) \rightharpoonup a(x, DT_k(u)) \quad \text{in } \prod_{i=1}^N L^{p'}(\Omega, w_i^*).$$

*Proof.* (3.10) follows directly from Lemma 3.3 and Remark 3.4. From (3.6), (3.3) and (2.6) we deduce with a classical argument (see, e.g., [1]) that for a subsequence still indexed by  $\varepsilon$ , (3.8)–(3.9) and (3.11) hold as  $\varepsilon$  tend to 0, where  $u$  is a measurable function defined on  $\Omega$ .

It is left to prove (3.12). For this, by  $(A_2)$  and (3.3) it follows that given any subsequence of  $(a(x, DT_k(u_\varepsilon)))_\varepsilon$ , there exists a subsequence, still denoted by  $(a(x, DT_k(u_\varepsilon)))_\varepsilon$ , such that  $a(x, DT_k(u_\varepsilon)) \rightharpoonup \Phi_k$  in  $\prod_{i=1}^N L^{p'}(\Omega, w_i^*)$ . We will prove that  $\Phi_k = a(x, DT_k(u))$  a.e. on  $\Omega$ . The proof consists of three steps.

*Step i:* For every  $h \in W^{1,\infty}(\mathbb{R})$ ,  $h \geq 0$  and  $\text{supp}(h)$  compact, we will prove that

$$(3.13) \quad \limsup_{\varepsilon \rightarrow 0} \int_{\Omega} a(x, DT_k(u_\varepsilon)) \cdot D[h(u_\varepsilon)(T_k(u_\varepsilon) - T_k(u))] dx \leq 0.$$

Taking  $h(u_\varepsilon)(T_k(u_\varepsilon) - T_k(u))$  as a test function in (3.2) we have

$$(3.14) \quad \begin{aligned} & \int_{\Omega} \beta_\varepsilon(T_{1/\varepsilon}(u_\varepsilon))h(u_\varepsilon)(T_k(u_\varepsilon) - T_k(u)) + \int_{\Omega} a(x, Du_\varepsilon) \cdot D[h(u_\varepsilon)(T_k(u_\varepsilon) - T_k(u))] \\ & + \int_{\Omega} F(T_{1/\varepsilon}(u_\varepsilon)) \cdot D[h(u_\varepsilon)(T_k(u_\varepsilon) - T_k(u))] = \int_{\Omega} fh(u_\varepsilon)(T_k(u_\varepsilon) - T_k(u)). \end{aligned}$$

Using  $|h(u_\varepsilon)(T_k(u_\varepsilon) - T_k(u))| \leq 2k\|h\|_\infty$ , by Lebesgue's dominated convergence theorem we find that  $\lim_{\varepsilon \rightarrow 0} \int_{\Omega} fh(u_\varepsilon)(T_k(u_\varepsilon) - T_k(u)) = 0$  and  $\lim_{\varepsilon \rightarrow 0} \int_{\Omega} F(T_{1/\varepsilon}(u_\varepsilon))D[h(u_\varepsilon)(T_k(u_\varepsilon) - T_k(u))] = 0$ . By using the same arguments as in [4] we can prove that

$$\limsup_{\varepsilon \rightarrow 0} \int_{\Omega} \beta_\varepsilon(T_{1/\varepsilon}(u_\varepsilon)) \cdot [h(u_\varepsilon)(T_k(u_\varepsilon) - T_k(u))] dx \geq 0.$$

Passing to the limit in (3.14) and using the above results we obtain (3.13).

*Step ii:* We now prove that for every  $k > 0$ ,

$$(3.15) \quad \limsup_{\varepsilon \rightarrow 0} \int_{\Omega} a(x, DT_k(u_\varepsilon)) \cdot [DT_k(u_\varepsilon) - DT_k(u)] dx \leq 0.$$

Indeed, for  $k > l$ , take  $h_l(u_\varepsilon)(T_k(u_\varepsilon) - T_k(u))$  as a test function in (3.2). Letting  $\varepsilon \downarrow 0$  and then  $l \rightarrow \infty$  we obtain

$$\begin{aligned} & \int_{\Omega} a(x, DT_k(u_\varepsilon)) \cdot D[h_l(u_\varepsilon)(T_k(u_\varepsilon) - T_k(u))] dx \\ & = \int_{[|u_\varepsilon| \leq k]} h_l(u_\varepsilon)a(x, DT_k(u_\varepsilon)) \cdot [DT_k(u_\varepsilon) - DT_k(u)] dx \\ & \quad + \int_{[|u_\varepsilon| > k]} h_l(u_\varepsilon)a(x, DT_k(u_\varepsilon)) \cdot (-DT_k(u)) dx \\ & \quad + \int_{\Omega} h'_l(u_\varepsilon)(T_k(u_\varepsilon) - T_k(u))a(x, DT_k(u_\varepsilon)) \cdot Du_\varepsilon dx \\ & = E_1 + E_2 + E_3. \end{aligned}$$

Since  $l > k$ , on the set  $[|u_\varepsilon| \leq k]$  we have  $h_l(u_\varepsilon) = 1$  so that we can write

$$\limsup_{\varepsilon \rightarrow 0} E_1 = \limsup_{\varepsilon \rightarrow 0} \int_{\Omega} a(x, DT_k(u_\varepsilon)) \cdot (DT_k(u_\varepsilon) - DT_k(u)) dx.$$

For  $E_2$ , using Lebesgue’s dominated convergence theorem we get

$$\lim_{\varepsilon \rightarrow 0} E_2 = - \int_{[|u|>k]} h_l(u)\Phi_{l+1} \cdot DT_k(u) \, dx = 0.$$

For  $E_3$ , we have

$$\begin{aligned} - \int_{\Omega} h'_l(u_\varepsilon)(T_k(u_\varepsilon) - T_k(u))a(x, DT_k(u_\varepsilon))Du_\varepsilon \, dx \\ \leq 2k \int_{[l<|u_\varepsilon|\leq l+1]} a(x, Du_\varepsilon)Du_\varepsilon \, dx. \end{aligned}$$

Using (3.7) we deduce that

$$\limsup_{l \rightarrow \infty} \limsup_{\varepsilon \rightarrow 0} \left( - \int_{\Omega} h'_l(u_\varepsilon)(T_k(u_\varepsilon) - T_k(u))a(x, DT_k(u_\varepsilon)) \cdot Du_\varepsilon \, dx \right) \leq 0.$$

Applying (3.13) with  $h$  replaced by  $h_l$ ,  $l > k$ , we get

$$\begin{aligned} \limsup_{\varepsilon \rightarrow 0} \int_{\Omega} a(x, DT_k(u_\varepsilon)) \cdot (DT_k(u_\varepsilon) - DT_k(u)) \, dx \\ \leq \limsup_{\varepsilon \rightarrow 0} \left( - \int_{\Omega} h'_l(u_\varepsilon)(T_k(u_\varepsilon) - T_k(u))a(x, DT_k(u_\varepsilon)) \cdot Du_\varepsilon \, dx \right). \end{aligned}$$

Now letting  $l \rightarrow \infty$  yields (3.15).

*Step iii:* In this step we prove by monotonicity arguments that for  $k > 0$ ,  $\Phi_k = a(x, DT_k(u))$  for almost every  $x \in \Omega$ . Let  $\varphi \in \mathcal{D}(\Omega)$  and  $\tilde{\alpha} \in \mathbb{R}$ . Using (3.15), we have

$$\tilde{\alpha} \lim_{\varepsilon \rightarrow 0} \int_{\Omega} a(x, DT_k(u_\varepsilon)) \cdot D\varphi \, dx \geq \tilde{\alpha} \int_{\Omega} a(x, D(T_k(u) - \tilde{\alpha}\varphi)) \cdot D\varphi \, dx.$$

Dividing by  $\tilde{\alpha} > 0$  and by  $\tilde{\alpha} < 0$  and letting  $\tilde{\alpha} \rightarrow 0$  we obtain

$$\lim_{\varepsilon \rightarrow 0} \int_{\Omega} a(x, DT_k(u_\varepsilon)) \cdot D\varphi \, dx = \int_{\Omega} a(x, DT_k(u)) \cdot D\varphi \, dx.$$

This means that for all  $k > 0$ ,  $\int_{\Omega} \Phi_k \cdot D\varphi \, dx = \int_{\Omega} a(x, DT_k(u)) \cdot D\varphi \, dx$  and so  $\Phi_k = a(x, DT_k(u))$  in  $\mathcal{D}'(\Omega)$  for all  $k > 0$ . Hence  $\Phi_k = a(x, DT_k(u))$  a.e. in  $\Omega$  and so  $a(x, DT_k(u_\varepsilon)) \rightharpoonup a(x, DT_k(u))$  weakly in  $\prod_{i=1}^N L^{p'}(\Omega, w_i^*)$ .

STEP 4: *Proof of existence.* Let  $h \in C_c^1(\mathbb{R})$  and  $\phi \in W_0^{1,p}(\Omega, w) \cap L^\infty(\Omega)$ . Taking  $h_l(u_\varepsilon)h(u)\phi$  as a test function in (3.2), we obtain

$$(3.16) \quad I_{\varepsilon,l}^1 + I_{\varepsilon,l}^2 + I_{\varepsilon,l}^3 = I_{\varepsilon,l}^4$$

where

$$\begin{aligned} I_{\varepsilon,l}^1 &= \int_{\Omega} \beta_{\varepsilon}(T_{1/\varepsilon}(u_{\varepsilon})) h_l(u_{\varepsilon}) h(u) \phi, \\ I_{\varepsilon,l}^2 &= \int_{\Omega} a(x, Du_{\varepsilon}) \cdot D(h_l(u_{\varepsilon}) h(u) \phi), \\ I_{\varepsilon,l}^3 &= \int_{\Omega} F(T_{1/\varepsilon}(u_{\varepsilon})) \cdot D(h_l(u_{\varepsilon}) h(u) \phi), \\ I_{\varepsilon,l}^4 &= \int_{\Omega} f h_l(u_{\varepsilon}) h(u) \phi. \end{aligned}$$

*Step i:* Letting  $\varepsilon \downarrow 0$  using the convergence results (3.8), (3.10) from Lemma 3.5 we can immediately calculate the following limits:

$$(3.17) \quad \lim_{\varepsilon \rightarrow 0} I_{\varepsilon,l}^1 = \int_{\Omega} b h_l(u) h(u) \phi,$$

$$(3.18) \quad \lim_{\varepsilon \rightarrow 0} I_{\varepsilon,l}^4 = \int_{\Omega} f h_l(u) h(u) \phi.$$

We write  $I_{\varepsilon,l}^2 = I_{\varepsilon,l}^{2,1} + I_{\varepsilon,l}^{2,2}$  where

$$I_{\varepsilon,l}^{2,1} = \int_{\Omega} h_l'(u_{\varepsilon}) a(x, Du_{\varepsilon}) \cdot Du_{\varepsilon} h(u) \phi, \quad I_{\varepsilon,l}^{2,2} = \int_{\Omega} h_l(u_{\varepsilon}) a(x, Du_{\varepsilon}) \cdot D(h(u) \phi).$$

Using (3.7) we get the estimate

$$(3.19) \quad \left| \lim_{\varepsilon \rightarrow 0} I_{\varepsilon,l}^{2,1} \right| \leq \|h\|_{\infty} \|\phi\|_{\infty} \cdot C_2 l^{-(1-1/p)}.$$

By Lebesgue's dominated convergence theorem it follows that for any  $i \in \{1, \dots, N\}$  we have

$$h_l(u_{\varepsilon}) \frac{\partial}{\partial x_i} (h(u) \phi) \rightarrow h_l(u) \frac{\partial}{\partial x_i} (h(u) \phi) \quad \text{in } L^p(\Omega, \sigma) \text{ as } \varepsilon \downarrow 0.$$

Keeping in mind that  $I_{\varepsilon,l}^{2,2} = \int_{\Omega} h_l(u_{\varepsilon}) a(x, DT_{l+1}(u_{\varepsilon})) \cdot D(h(u) \phi)$ , by (3.12), we get

$$(3.20) \quad \lim_{\varepsilon \rightarrow 0} I_{\varepsilon,l}^{2,2} = \int_{\Omega} h_l(u) a(x, DT_{l+1}(u)) \cdot D(h(u) \phi).$$

Let us write  $I_{\varepsilon,l}^3 = I_{\varepsilon,l}^{3,1} + I_{\varepsilon,l}^{3,2}$ , where

$$\begin{aligned} I_{\varepsilon,l}^{3,1} &= \int_{\Omega} h_l'(u_{\varepsilon}) F(T_{1/\varepsilon}(u_{\varepsilon})) \cdot Du_{\varepsilon} h(u) \phi, \\ I_{\varepsilon,l}^{3,2} &= \int_{\Omega} h_l(u_{\varepsilon}) F(T_{1/\varepsilon}(u_{\varepsilon})) \cdot D(h(u) \phi). \end{aligned}$$



For any  $l \in \mathbb{N}$ , there exists  $\varepsilon_0(l)$  such that for all  $\varepsilon < \varepsilon_0(l)$ ,

$$(3.21) \quad I_{\varepsilon,l}^{3,1} = \int_{\Omega} h'_l(T_{l+1}(u_\varepsilon))F(T_{l+1}(u_\varepsilon)) \cdot DT_{l+1}(u_\varepsilon)h(u)\phi.$$

Using the Gauss–Green Theorem for Sobolev functions in (3.21) we get

$$(3.22) \quad I_{\varepsilon,l}^{3,1} = - \int_{\Omega} \int_0^{T_{l+1}(u_\varepsilon)} h'_l(r)F(r) \, dr \cdot D(h(u)\phi).$$

Now, using (3.8) and the Gauss–Green Theorem, after letting  $\varepsilon \downarrow 0$  we get

$$(3.23) \quad \lim_{\varepsilon \rightarrow 0} I_{\varepsilon,l}^{3,1} = \int_{\Omega} h'_l(u)F(u) \cdot Du h(u)\phi.$$

Choosing  $\varepsilon$  small enough, we can write

$$(3.24) \quad I_{\varepsilon,l}^{3,2} = \int_{\Omega} h_l(u_\varepsilon)F(T_{l+1}(u_\varepsilon)) \cdot D(h(u)\phi)$$

and conclude

$$(3.25) \quad \lim_{\varepsilon \rightarrow 0} I_{\varepsilon,l}^{3,2} = \int_{\Omega} h_l(u)F(u) \cdot D(h(u)\phi).$$

*Step ii:* We let  $l \rightarrow \infty$ . Combining (3.16) and (3.17)–(3.25) we find

$$(3.26) \quad I_l^1 + I_l^2 + I_l^3 + I_l^4 + I_l^5 = I_l^6$$

where

$$\begin{aligned} I_l^1 &= \int_{\Omega} bh_l(u)h(u)\phi, & I_l^2 &= \int_{\Omega} h_l(u)a(x, DT_{l+1}(u)) \cdot D(h(u)\phi), \\ |I_l^3| &\leq C_2 l^{-(1-1/p)} \|h\|_{\infty} \|\phi\|_{\infty}, & I_l^4 &= \int_{\Omega} h_l(u)F(u) \cdot D(h(u)\phi), \\ I_l^5 &= \int_{\Omega} h'_l(u)F(u) \cdot Du h(u)\phi, & I_l^6 &= \int_{\Omega} fh_l(u)h(u)\phi. \end{aligned}$$

Obviously, we have

$$(3.27) \quad \lim_{l \rightarrow \infty} I_l^3 = 0.$$

Choosing  $m > 0$  such that  $\text{supp } h \subset [-m, m]$ , we can replace  $u$  by  $T_m(u)$  in  $I_l^1, I_l^2, \dots, I_l^6$ , and

$$h'_l(u) = h'_l(T_m(u)) = 0 \text{ if } l + 1 > m, \quad h_l(u) = h_l(T_m(u)) = 1 \text{ if } l > m.$$

Therefore, letting  $l \rightarrow \infty$  and combining (3.26) with (3.27) we obtain

$$(3.28) \quad \int_{\Omega} bh(u)\phi + \int_{\Omega} (a(x, Du) + F(u)) \cdot D(h(u)\phi) = \int_{\Omega} fh(u)\phi$$

for all  $h \in C_c^1(\mathbb{R})$  and all  $\phi \in W_0^{1,p}(\Omega, w) \cap L^\infty(\Omega)$ .

*Step iii: Subdifferential argument.* It is left to prove that  $u(x) \in \mathcal{D}(\beta(x))$  and  $b(x) \in \beta(u(x))$  for almost all  $x \in \Omega$ . Since  $\beta$  is a maximal monotone graph, there exists a convex, l.s.c., proper function  $j : \mathbb{R} \rightarrow [0, \infty]$  such that  $\beta(r) = \partial j(r)$  for all  $r \in \mathbb{R}$ . According to [7], for  $0 < \varepsilon \leq 1$ ,  $j_\varepsilon : \mathbb{R} \rightarrow \mathbb{R}$  defined by  $j_\varepsilon(r) = \int_0^r \beta_\varepsilon(s) ds$  has the properties as in [12]. Using the same argument as in [12] we can prove that for all  $r \in \mathbb{R}$  and almost every  $x \in \Omega$ ,  $u \in \mathcal{D}(\beta)$  and  $b \in \beta(u)$  almost everywhere in  $\Omega$ . With this last step the proof of Theorem 3.2 is completed.

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Youssef Akdim, Chakir Allalou  
 LIMAO, Faculté Polydisciplinaire  
 B.P. 1223 Taza Gare, Taza, Morocco  
 E-mail: akdimyoussef@yahoo.fr  
 chakir.allalou@yahoo.fr

Received on 25.2.2014;  
 revised version on 18.7.2014

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