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## SOME RESULTS ON STRONGLY NONLINEAR ANISOTROPIC DIFFERENTIAL EQUATIONS

Abstract. The paper concerns the existence of weak solutions to nonlinear elliptic equations of the form $A(u)+g(x, u, \nabla u)=f$, where $A$ is an operator from an appropriate anisotropic function space to its dual and the right hand side term is in $L^{1+m}$ with $0<m<1$. We assume a sign condition on the nonlinear term $g$, but no growth restrictions on $u$.

1. Introduction. Let $\Omega$ be an open bounded subset of $\mathbb{R}^{N}, N \geq 3$. Let $p_{1}, \ldots, p_{N}$ be $N$ real numbers with $p_{i}>2, i=1, \ldots, N$. Let $X$ be the Banach space, called an anisotropic Sobolev space, obtained as the closure of $C_{0}^{1}(\Omega)$ with respect to the norm

$$
\|u\|=\|u\|_{1+1 / m}+\sum_{i=1}^{N}\left\|\frac{\partial u}{\partial x_{i}}\right\|_{p_{i}}
$$

where $m$ is a real number such that $1 /\left(p_{i}-1\right)<m<1$.
Let $A$ be the nonlinear operator from $X$ into the dual $X^{*}$ defined as

$$
A u=-\operatorname{div}(a(x, u, \nabla u))
$$

where $a(x, s, \xi)=\left\{a_{i}(x, s, \xi)\right\}: \Omega \times \mathbb{R} \times \mathbb{R}^{N} \rightarrow \mathbb{R}^{N}, i=1, \ldots, N$, is a Carathéodory vector-valued function, that is, measurable with respect to $x$ in $\Omega$ for every $(s, \xi)$ in $\mathbb{R} \times \mathbb{R}^{N}$, and continuous with respect to $(s, \xi)$ in $\mathbb{R} \times \mathbb{R}^{N}$ for almost every $x$ in $\Omega$. Suppose that $A$ satisfies the following conditions of strict monotonicity, coerciveness and growth: there exist positive constants $\alpha$ and $\beta$ and a nonnegative function $k \in L^{1}(\Omega)$ such that

[^0](A1) for a.e. $x \in \Omega$, all $(s, \xi) \in \mathbb{R} \times \mathbb{R}^{N}$ and all $i=1, \ldots, N$,
$$
\left|a_{i}(x, s, \xi)\right| \leq \beta\left[k(x)+|s|^{1+1 / m}+\sum_{j=1}^{N}\left|\xi_{j}\right|^{p_{j}}\right]^{1-1 / p_{i}}
$$
(A2) for a.e. $x \in \Omega$ and every $\xi, \xi^{*} \in \mathbb{R}^{N}$ with $\xi \neq \xi^{*}$,
$$
\left[a(x, s, \xi)-a\left(x, s, \xi^{*}\right)\right] \cdot\left[\xi-\xi^{*}\right]>0
$$
(A3) for a.e. $x \in \Omega$ and every $(s, \xi) \in \mathbb{R} \times \mathbb{R}^{N}$,
$$
a(x, s, \xi) \cdot \xi \geq \alpha \sum_{i=1}^{N}\left|\xi_{i}\right|^{p_{i}}
$$

Consider the nonlinear elliptic equation

$$
\begin{equation*}
A u+g(x, u, \nabla u)=f \quad \text { in } \Omega \tag{1.1}
\end{equation*}
$$

where $g$ is a nonlinear lower-order term having no growth conditions with respect to $|u|$ and satisfying the following assumption:
(G) $g: \Omega \times \mathbb{R} \times \mathbb{R}^{N} \rightarrow \mathbb{R}$ is a Carathéodory function satisfying

$$
|g(x, s, \xi)| \leq h(|s|)\left[c(x)+\sum_{i=1}^{N}\left|\xi_{i}\right|^{p_{i}}\right]^{\frac{1-m}{2(1+m)}}
$$

for a.e. $x \in \Omega$ and all $(s, \xi) \in \mathbb{R} \times \mathbb{R}^{N}$, where $h: \mathbb{R}^{+} \rightarrow \mathbb{R}^{+}$is a continuous increasing function such that $h(u) \in L^{2}(\Omega)$ for all $u \in X$, $c$ is a positive function in $L^{1}(\Omega)$, and $m$ satisfies $1 /\left(p_{i}-1\right)<m<1$. We also assume the "sign condition" $g(x, s, \xi) s \geq 0$ for a.e. $x \in \Omega$ and all $s \in \mathbb{R}$.

Let us mention that in the isotropic case $\left(p_{i}=p, i=1, \ldots, N\right)$, the problem (1.1) has been investigated by Bensoussan, Boccardo and Murat [4]. In particular, they proved the existence of solutions using different ideas based essentially on the strong convergence of the positive and negative parts of the approximate solution.

Note that some results have been proved for the problem (1.1) in the isotropic case in the framework of weighted Sobolev spaces; for more details, we refer the reader to [2].

The purpose of this paper is to study the above problem in the anisotropic case. More precisely, under the hypotheses (A1)-(A3) and (G), we prove an existence result for the anisotropic problem (1.1). Our study is motivated by an anisotropic Sobolev inequality due to Troisi [18].

Let us point out that interesting work in the anisotropic case has been done e.g. in [7], [10] and [14]. Finally, when $g$ does not depend on $\nabla u$, we refer the reader to the recent works [3] and [8], dealing with elliptic equations
for a general class of operators of finite and infinite order, and proving the existence of solutions in anisotropic spaces.

As a prototype example, one can consider the problem

$$
-\sum_{i=1}^{N} \frac{\partial}{\partial x_{i}}\left(\left|\frac{\partial u}{\partial x_{i}}\right|^{p_{i}-2} \frac{\partial u}{\partial x_{i}}\right)+g(x, u, \nabla u)=f \quad \text { in } \Omega
$$

where

$$
g(x, s, \xi)=\operatorname{sgn}(s)(1+|s|)\left[\sum_{i=1}^{N}\left|\xi_{i}\right|^{p_{i}}\right]^{\frac{1-m}{2(1+m)}}
$$

with $p_{i}>2$ and $1 /\left(p_{i}-1\right)<m<1$ for $i=1, \ldots, N$.

## 2. Preliminaries

Anisotropic Sobolev spaces. We start by recalling that anisotropic Sobolev spaces were introduced and studied by Nikol'skiı̆ [12], Slobodeckiŭ [17], and Troisi [18], and later by Trudinger [19] in the framework of Orlicz spaces.

Let $\Omega$ be a bounded open subset of $\mathbb{R}^{N}(N \geq 3)$ and let $p_{0}, p_{1}, \ldots, p_{N}$ be real numbers with $1<p_{i}<\infty, i=0, \ldots, N$. We denote by $W^{1, p_{i}}(\Omega)$ the anisotropic Sobolev space consisting of all real-valued functions $u \in L^{p_{0}}(\Omega)$ whose derivatives in the sense of distributions satisfy

$$
\frac{\partial u}{\partial x_{i}} \in L^{p_{i}}(\Omega) \quad \text { for all } i=1, \ldots, N .
$$

This set of functions forms a Banach space under the norm

$$
\|u\|_{1, p_{i}}=\left(\int_{\Omega}|u(x)|^{p_{0}} d x\right)^{1 / p_{0}}+\sum_{i=1}^{N}\left(\int_{\Omega}\left|\frac{\partial u(x)}{\partial x_{i}}\right|^{p_{i}} d x\right)^{1 / p_{i}}
$$

The space $W_{0}^{1, p_{i}}(\Omega)$ is the closure of $C_{0}^{\infty}(\Omega)$ with respect to the norm $\|\cdot\|_{1, p_{i}}$. The theory of anisotropic Sobolev spaces was developed in [13, [15], 16] and [18]. It was proved that $\left(W_{0}^{1, p_{i}}(\Omega),\|\cdot\|_{1, p_{i}}\right)$ is a reflexive Banach space for any $p_{0}, \ldots, p_{N}$ with $1<p_{i}<\infty, i=0, \ldots, N$. The dual space of $W_{0}^{1, p_{i}}(\Omega)$ is equivalent to $W^{-1, p_{i}^{\prime}}(\Omega)$, where $p_{i}^{\prime}$ is the conjugate of $p_{i}$, i.e., $p_{i}^{\prime}=p_{i} /\left(p_{i}-1\right)$, $i=0, \ldots, N$.

In the following, we assume

$$
p_{i}>2 \quad \text { for all } i=1, \ldots, N \quad \text { and } \quad \sum_{i=1}^{N} \frac{1}{p_{i}}>1
$$

Let $m$ be a real number such that $1 /\left(p_{i}-1\right)<m<1$ for all $i=1, \ldots, N$.

We define $X$ to be the closure of $C_{0}^{1}(\Omega)$ with respect to the norm

$$
\begin{equation*}
\|u\|=\|u\|_{1+1 / m}+\sum_{i=1}^{N}\left\|\frac{\partial u}{\partial x_{i}}\right\|_{p_{i}} \tag{2.1}
\end{equation*}
$$

Remark 2.1. $X$ endowed with the norm (2.1) is a reflexive Banach space. This can be easily deduced by constructing an isometric isomorphism from $X$ to a closed subspace of $L^{1+1 / m}(\Omega) \times \prod_{i=1}^{N} L^{p_{i}}(\Omega)$.

We prove the existence of distributional solutions for the nonlinear elliptic equation

$$
(P)\left\{\begin{array}{l}
A u+g(x, u, \nabla u)=f \quad \text { in } \Omega \\
u=0 \text { in } \partial \Omega
\end{array}\right.
$$

where $f \in L^{1+m}(\Omega)$. Herein, the operator $A$ and the function $g$ satisfy (A1)-(A3) and (G) respectively.

We use the following anisotropic Sobolev inequality given by Troisi [18].
THEOREM 2.1. Let $q_{i} \geq 1, i=1, \ldots, N$, and $u \in C_{0}^{\infty}(\Omega)$. If $\sum_{i=1}^{N} 1 / q_{i}$ $>1$, then

$$
\|u\|_{\bar{q}^{*}} \leq C \prod_{i=1}^{N}\left\|\frac{\partial u}{\partial x_{i}}\right\|_{q_{i}}^{1 / N}
$$

where

$$
\frac{1}{\bar{q}^{*}}=\frac{1}{N}\left(-1+\sum_{i=1}^{N} \frac{1}{q_{i}}\right)
$$

and $C$ depends only on $q_{i}$ and $N$.
Now we state the main result of the paper.
TheOrem 2.2. Let $m$ be a real number with $1 /\left(p_{i}-1\right)<m<1, i=$ $1, \ldots, N$. Assume that (A1)-(A3) and (G) hold and $f \in L^{1+m}(\Omega)$. Then the problem $(P)$ has at least one solution $u \in X$ such that

$$
\left\{\begin{array}{l}
g(x, u, \nabla u) \in L^{1}(\Omega) \quad \text { and } \quad g(x, u, \nabla u) u \in L^{1}(\Omega), \\
\langle A u, v\rangle+\int_{\Omega} g(x, u, \nabla u) v d x=\langle f, v\rangle \quad \forall v \in X
\end{array}\right.
$$

Remark 2.2. Note that $v \in X$, therefore $v \in L^{1+1 / m}(\Omega)$. Then the condition (G) guarantees that $\int_{\Omega} g(x, u, \nabla u) v d x$ is well defined since $h(u) \in$ $L^{2}(\Omega)$ and $m<1$.

REmARK 2.3. To enlarge the class of operators $A$ for which the conclusion of Theorem 2.2 remains true, we can also assume instead of (A1) the following condition:
(A1)' for a.e. $x \in \Omega$, all $(s, \xi) \in \mathbb{R} \times \mathbb{R}^{N}$, all $i=1, \ldots, N$ and some function $k \in L^{p_{i}^{\prime}}(\Omega)$,

$$
\left|a_{i}(x, s, \xi)\right| \leq \beta\left[k(x)+|s|^{(1+1 / m) / p_{i}^{\prime}}+\left(\sum_{j=1}^{N}\left|\xi_{j}\right|^{p_{j}}\right)^{1 / p_{i}^{\prime}}\right]
$$

Proof of Theorem 2.2.
STEP 1: Existence for the approximate problem. Let $\varphi \in C_{c}^{\infty}\left(\mathbb{R}^{N}\right)$ be such that $0<\varphi<1$ and $\varphi=1$ in some neighbourhood of 0 . Set

$$
g_{k}(x, u, \nabla u)=\varphi(x / k) T_{k} g(x, u, \nabla u), \quad b_{k}(u, v)=\int_{\Omega} g_{k}(x, u, \nabla u) v d x
$$

for a.e. $x \in \Omega$ for all $u, v \in X$, where $T_{k}$ is the usual truncation given by

$$
T_{k} \mu= \begin{cases}\mu & \text { if }|\mu| \leq k \\ k \mu /|\mu| & \text { if }|\mu|>k\end{cases}
$$

Observe that $b_{k}(u, v)$ is well defined since $g_{k}(x, u, \nabla u)$ is bounded with compact support. Define the following operator:

$$
G_{k} u: X \rightarrow \mathbb{R}, \quad v \mapsto \int_{\Omega} g_{k}(x, u, \nabla u) v d x
$$

Since $v \in L^{1+1 / m}(\Omega)$ it is easy to see that $G_{k}: X \rightarrow X^{*}$ is well defined.
Proposition 2.1. Under the assumptions (A1)-(A3), the operator $A+G_{k}$ is coercive, strictly monotone, hemicontinuous and bounded. Precisely:
(i) $\lim _{\|u\| \rightarrow+\infty}\left\langle\left(A+G_{k}\right) u, u\right\rangle /\|u\|=+\infty$.
(ii) $\left\langle\left(A+G_{k}\right) u-\left(A+G_{k}\right) v, u-v\right\rangle>0$ if $u \neq v, u, v \in X$.
(iii) The $\operatorname{map} \lambda \in \mathbb{R} \mapsto\left\langle\left(A+G_{k}\right)(u+\lambda v)\right.$, w is continuous for each $u, v, w \in X$.
(iv) If $Y \subset X$ is bounded, then $\left(A+G_{k}\right)(Y)$ is bounded.

Proof. (i) Let $i_{0}$ be such that

$$
\left\|\frac{\partial u}{\partial x_{i_{0}}}\right\|_{p_{i_{0}}}=\max \left\{\left\|\frac{\partial u}{\partial x_{i}}\right\|_{p_{i}}: i=1, \ldots, N\right\}
$$

Since $1 /\left(p_{i}-1\right)<m<1$, we have $1+1 / m<p_{i}$ for all $i=1, \ldots, N$. This easily implies that

$$
1+\frac{1}{m} \leq \bar{p}^{*} \quad \text { where } \quad \frac{1}{\bar{p}^{*}}=\frac{1}{N}\left(-1+\sum_{i=1}^{N} \frac{1}{p_{i}}\right)
$$

Then by Theorem 2.1 we have

$$
\|u\|_{1+1 / m} \leq \tilde{K}\|u\|_{\bar{p}^{*}} \leq K\left\|\frac{\partial u}{\partial x_{i_{0}}}\right\|_{p_{i_{0}}}
$$

where $\tilde{K}, K$ are positive constants. Hence, thanks to (A3) and (G) we obtain

$$
\begin{aligned}
\frac{\left\langle\left(A+G_{k}\right) u, u\right\rangle}{\|u\|} & \geq \frac{\int_{\Omega} \alpha \sum_{i=1}^{N}\left|\frac{\partial u}{\partial x_{i}}\right|^{p_{i}} d x}{\|u\|} \\
& \geq \frac{\int_{\Omega}\left(\frac{\alpha}{2} \sum_{i=1}^{N}\left|\frac{\partial u}{\partial x_{i}}\right|^{p_{i}}+\frac{\alpha}{2}\left|\frac{\partial u}{\partial x_{i_{0}}}\right|^{p_{i_{0}}}\right) d x}{\|u\|_{1+1 / m}+\left\|\frac{\partial u}{\partial x_{i_{0}}}\right\|_{p_{0}}} \\
& \geq K^{\prime} \frac{\|u\|_{1+1 / m}^{p_{i 0}}+\| \frac{\partial u}{\partial x_{i_{0}}}}{\|u\|_{1+1 / m}+\left\|\frac{\partial u}{\partial x_{i_{0}}}\right\|_{p_{i_{0}}}^{p_{i_{0}}}}
\end{aligned}
$$

where $K^{\prime}$ is a suitable positive constant. Then the coercivity follows immediately since the powers in the numerator are greater than those of the denominator in the above inequality.
(ii) The strict monotonicity of $A+G_{k}$ follows easily from (A2) and (G).
(iii) To show that $A+G_{k}$ is hemicontinuous, we will prove that

$$
\left\langle\left(A+G_{k}\right)(u+\lambda v), w\right\rangle \rightarrow\left\langle\left(A+G_{k}\right)\left(u+\lambda_{0} v\right), w\right\rangle
$$

as $\lambda \rightarrow \lambda_{0}$ for all $u, v, w \in X$. Since for a.e. $x \in \Omega$,

$$
a_{i}(x, u+\lambda v, \nabla(u+\lambda v)) \rightarrow a_{i}\left(x, u+\lambda_{0} v, \nabla\left(u+\lambda_{0} v\right)\right)
$$

as $\lambda \rightarrow \lambda_{0}$, thanks to the growth condition (A1) we have
$a_{i}(x, u+\lambda v, \nabla(u+\lambda v)) \rightarrow a_{i}\left(x, u+\lambda_{0} v, \nabla\left(u+\lambda_{0} v\right)\right)$ weakly in $\prod_{i=1}^{N} L^{p_{i}}(\Omega)$ as $\lambda \rightarrow \lambda_{0}$. Therefore

$$
\langle A(u+\lambda v), w\rangle \rightarrow\left\langle A\left(u+\lambda_{0} v\right), w\right\rangle \quad \text { as } \lambda \rightarrow \lambda_{0} .
$$

On the other hand,

$$
g_{k}(x, u+\lambda v, \nabla(u+\lambda v)) \rightarrow g\left(x, u+\lambda_{0} v, \nabla\left(u+\lambda_{0} v\right)\right)
$$

as $\lambda \rightarrow \lambda_{0}$ for a.e. $x \in \Omega$. Then

$$
g_{k}(x, u+\lambda v, \nabla(u+\lambda v)) \rightarrow g\left(x, u+\lambda_{0} v, \nabla\left(u+\lambda_{0} v\right)\right) \quad \text { in } L^{1}(\Omega)
$$

as $\lambda \rightarrow \lambda_{0}$ since $\left(g_{k}(x, u+\lambda v, \nabla(u+\lambda v))\right)_{\lambda}$ is bounded in $L^{1}(\Omega)$. Therefore

$$
\left\langle G_{k}(u+\lambda v), w\right\rangle \rightarrow\left\langle G_{k}\left(u+\lambda_{0} v\right), w\right\rangle \quad \text { as } \lambda \rightarrow \lambda_{0}
$$

(iv) For the boundedness we have

$$
\begin{aligned}
& \left|\left\langle\left(A+G_{k}\right) u, v\right\rangle\right|=\langle A u, v\rangle+\int_{\Omega} g_{k}(x, u, \nabla u) v d x \\
& \leq \\
& \quad \beta \sum_{i=1}^{N}\left[\left(\int_{\Omega}\left(k(x)+|u|^{1+1 / m}+\sum_{j=1}^{N}\left|\frac{\partial u}{\partial x_{j}}\right|^{p_{j}}\right) d x\right)^{1 / p_{i}^{\prime}}\left(\int_{\Omega}\left|\frac{\partial v}{\partial x_{i}}\right|^{p_{i}} d x\right)^{1 / p_{i}}\right] \\
& \quad+c_{1}\|v\|_{1+1 / m} \\
& \leq c_{2}\|v\|\left(c_{3}+\|u\|\right)^{\gamma_{1}}
\end{aligned}
$$

where $c_{1}$ and $c_{2}$ are positive constants and $\gamma_{1}$ is a positive number. This implies the boundedness of $A+G_{k}$.

Therefore, thanks to Theorem 2.1 of [11], there exists a solution $u_{k} \in X$ of the problem

$$
A u_{k}+g_{k}\left(x, u_{k}, \nabla u_{k}\right)=f
$$

or variationally

$$
\begin{equation*}
\sum_{i=1}^{N} \int_{\Omega} a_{i}\left(x, u_{k}, \nabla u_{k}\right) \frac{\partial v}{\partial x_{i}} d x+\int_{\Omega} g_{k}\left(x, u_{k}, \nabla u_{k}\right) v d x=\langle f, v\rangle \tag{2.2}
\end{equation*}
$$

for all $v \in X$.
STEP 2: A priori estimates. Substituting $v=u_{k}$ in (2.2) and using (A3) and (G) results in

$$
\alpha \sum_{i=1}^{N} \int_{\Omega}\left|\frac{\partial u_{k}}{\partial x_{i}}\right|^{p_{i}} d x \leq c\|f\|_{L^{1+m}(\Omega)}\left\|u_{k}\right\|
$$

where $c$ is a positive constant. Then similarly to the proof of (i) in Proposition 2.1 , we get

If we suppose towards a contradiction that $\left\|u_{k}\right\|$ is not bounded, the left hand side of the above inequality becomes unbounded since

$$
\lim _{x+y \rightarrow+\infty} \frac{x^{t}+y^{t}}{x+y}=+\infty \quad \text { for } x, y \in \mathbb{R}_{+} \text {and } t>1
$$

Thus,

$$
\begin{gather*}
\left\|u_{k}\right\| \leq C  \tag{2.3}\\
\int_{\Omega} g_{k}\left(x, u_{k}, \nabla u_{k}\right) u_{k} d x \leq C \tag{2.4}
\end{gather*}
$$

for some constant $C>0$ independent of $k$. By a similar argument, we can prove that $A$ is a bounded operator, and we get

$$
\begin{equation*}
\left\|A u_{k}\right\|_{X^{*}} \leq C^{\prime} \tag{2.5}
\end{equation*}
$$

for some constant $C^{\prime}>0$ independent of $k$.
Step 3: Convergence of $u_{k}$. In view of Remark 2.1, $X$ is reflexive, and we deduce from (2.3) and (2.5) that

$$
\begin{array}{rlrl}
u_{k} & \rightarrow u & \text { weakly in } X \\
\frac{\partial u_{k}}{\partial x_{i}} & \rightarrow \frac{\partial u}{\partial x_{i}} & & \text { weakly in } L^{p_{i}^{\prime}}(\Omega) \\
A u_{k} & \rightarrow \chi & & \text { weakly in } X^{*}
\end{array}
$$

This implies that we can take a subsequence still denoted by $u_{k}$ such that

$$
\begin{equation*}
u_{k} \rightarrow u \quad \text { a.e. in } \Omega . \tag{2.6}
\end{equation*}
$$

This is not sufficient to pass to the limit in $g_{k}$. We need for instance

$$
\begin{equation*}
\nabla u_{k} \rightarrow \nabla u \quad \text { a.e. in } \Omega . \tag{2.7}
\end{equation*}
$$

We will not give the proof of this since it is identical to one in (4). In fact, we can prove as in [4] that

$$
u_{k}^{+} \rightarrow u^{+}, \quad u_{k}^{-} \rightarrow u^{-} \quad \text { and } \quad \nabla u_{k} \rightarrow \nabla u \quad \text { a.e. }
$$

Therefore, since $g$ is continuous, we get the conclusions

$$
\begin{aligned}
g_{k}\left(x, u_{k}, \nabla u_{k}\right) \rightarrow g(x, u, \nabla u) & \text { a.e. in } \Omega, \\
g_{k}\left(x, u_{k}, \nabla u_{k}\right) u_{k} \rightarrow g(x, u, \nabla u) u & \text { a.e. in } \Omega .
\end{aligned}
$$

From (2.4) and in view of Fatou's lemma, we obtain

$$
\int_{\Omega} g(x, u, \nabla u) u d x \leq \lim _{k \rightarrow+\infty} \int_{\Omega} g_{k}\left(x, u_{k}, \nabla u_{k}\right) u_{k} d x \leq C,
$$

which implies that $g(x, u, \nabla u) u \in L^{1}(\Omega)$.
Now let $\delta>0$. Since $\left|g_{k}(x, s, \xi)\right| \delta \leq\left|g_{k}(x, s, \xi) s\right|$ for $|s| \geq \delta$, we obtain $\left|g_{k}(x, s, \xi)\right| \leq \delta^{-1}\left|g_{k}(x, s, \xi) s\right|$ for $|s| \geq \delta$. In view of Hölder's inequality, for any measurable subset $E$ of $\Omega$,

$$
\begin{align*}
& \int_{E}\left|g_{k}\left(x, u_{k}, \nabla u_{k}\right)\right| d x  \tag{2.8}\\
& \quad \leq \int_{|u| \leq \delta}\left|g_{k}\left(x, u_{k}, \nabla u_{k}\right)\right| d x+\delta^{-1} \int_{|u|>\delta}\left|g_{k}\left(x, u_{k}, \nabla u_{k}\right) u_{k}\right| d x \\
& \quad \leq h(\delta) \int_{E}\left[c(x)+\sum_{j=1}^{N}\left|\frac{\partial u_{k}}{\partial x_{i}}\right|^{p_{i}}\right]^{\frac{1-m}{2(1+m)}} d x+\delta^{-1} C \\
& \quad \leq h(\delta) c_{3}\left(c_{4}+c_{5}\left\|u_{k}\right\|^{\gamma_{2}}\right)|E|+\delta^{-1} C
\end{align*}
$$

where $c_{3}, c_{4}$ and $c_{5}$ are positive constants, $\gamma_{2}$ is a positive number and $C$ is the constant of (2.4). Thanks to (2.3), the above inequality implies the equiintegrability of $g_{k}\left(x, u_{k}, \nabla u_{k}\right)$.

For $|E|$ sufficiently small and $\delta=2 C / \varepsilon$ with $\varepsilon>0$ we obtain

$$
\int_{E}\left|g_{k}\left(x, u_{k}, \nabla u_{k}\right)\right| d x \leq \varepsilon .
$$

Thanks to (2.6), (2.7), (2.8) and Vitali's theorem we get

$$
g_{k}\left(x, u_{k}, \nabla u_{k}\right) \rightarrow g(x, u, \nabla u) \quad \text { strongly in } L^{1}(\Omega) .
$$

Hence $g(x, u, \nabla u) \in L^{1}(\Omega)$. Passing to the limit, we obtain

$$
\langle\chi, v\rangle+\int_{\Omega} g(x, u, \nabla u) v d x=\langle f, v\rangle \quad \text { for all } v \in X
$$

It remains to show that $A u=\chi$. For this purpose, note that since $A$ is bounded, hemicontinuous and monotone, it is pseudomonotone (see Proposition 2.5 of [11]). Now, substituting $v=u_{k}$ in (2.2), in view of Fatou's lemma we get

$$
\limsup _{k \rightarrow+\infty}\left\langle A u_{k}, u_{k}\right\rangle \leq\langle f, u\rangle-\int_{\Omega} g(x, u, \nabla u) u d x
$$

This implies

$$
\limsup _{k \rightarrow+\infty}\left\langle A u_{k}, u_{k}\right\rangle \leq\langle\chi, v\rangle
$$

Since $A$ is pseudomonotone, we obtain $\chi=A u$.
Finally, we conclude that

$$
\left\{\begin{array}{l}
g(x, u, \nabla u) \in L^{1}(\Omega), g(x, u, \nabla u) u \in L^{1}(\Omega), \\
\langle A u, v\rangle+\int_{\Omega} g(x, u, \nabla u) v d x=\langle f, v\rangle \quad \text { for all } v \in X .
\end{array}\right.
$$

This completes the proof.
3. Data in the dual case. Let $p_{i}, i=1, \ldots, N$, be $N$ real numbers such that

$$
p_{i}>1 \quad \text { for all } i=1, \ldots, N \quad \text { and } \quad \sum_{i=1}^{N} \frac{1}{p_{i}}>1 .
$$

Set $p=\min \left\{p_{i}: i=1, \ldots, N\right\}$ and suppose further that the nonlinear lower-order term $g$ satisfies the following condition instead of (G):
$\left(\mathrm{G}^{\prime}\right) g: \Omega \times \mathbb{R} \times \mathbb{R}^{N} \rightarrow \mathbb{R}$ is a Carathéodory function satisfying

$$
|g(x, s, \xi)| \leq h(|s|)\left[c(x)+\sum_{i=1}^{N}\left|\xi_{i}\right|^{p_{i}}\right]^{\frac{1}{1-1 / p-1 / q}}
$$

for a.e. $x \in \Omega$ and all $(s, \xi) \in \mathbb{R} \times \mathbb{R}^{N}$, where $h: \mathbb{R}^{+} \rightarrow \mathbb{R}^{+}$is a continuous increasing function such that $h(u) \in L^{q}(\Omega)$ for all $u \in X, c$ is a positive function in $L^{1}(\Omega)$, and $q$ satisfies $1<q<p$ with $1 / p+1 / q<1$. We also assume that $g(x, s, \xi) s \geq 0$ for a.e. $x \in \Omega$ and all $s \in \mathbb{R}$.
Define the anisotropic space $E$ to be the closure of $C_{0}^{1}(\Omega)$ with respect to the norm

$$
\|u\|=\|u\|_{p}+\sum_{i=1}^{N}\left\|\frac{\partial u}{\partial x_{i}}\right\|_{p_{i}} .
$$

It has been shown in [14] that $E$ is a reflexive Banach space. Consider the following nonlinear elliptic equation with Dirichlet boundary condition:

$$
\left(P^{\prime}\right)\left\{\begin{array}{l}
A u+g(x, u, \nabla u)=f \quad \text { in } \Omega, \\
u=0 \text { in } \partial \Omega,
\end{array}\right.
$$

where $f \in E^{*}$, with $E^{*}$ denoting the dual of $E$.
The existence result is the following.
Theorem 3.1. Assume ( A 1$)-(\mathrm{A} 3)$ and $\left(\mathrm{G}^{\prime}\right)$ hold and $f \in E^{*}$. Then the problem $\left(P^{\prime}\right)$ has at least one solution, i.e., there exists $u \in E$ such that

$$
\left\{\begin{array}{l}
g(x, u, \nabla u) \in L^{1}(\Omega) \quad \text { and } \quad g(x, u, \nabla u) u \in L^{1}(\Omega), \\
\langle A u, v\rangle+\int_{\Omega} g(x, u, \nabla u) v d x=\langle f, v\rangle \quad \forall v \in E .
\end{array}\right.
$$

The conclusion of Theorem 3.1 follows by adapting the techniques used in the proof of Theorem 2.2.

Remark 3.1. As in [14], consider the operator $A$ of the form

$$
A u=-\operatorname{div}(b(\nabla u)+a(x, u, \nabla u)),
$$

where $a(x, s, \xi)=\left\{a_{i}(x, s, \xi)\right\}, i=1, \ldots, N$, are as in the introduction and $b(\xi)=\left(b_{1} \xi_{1}, \ldots, b_{N} \xi_{N}\right)$ for $\xi=\left(\xi_{1}, \ldots, \xi_{N}\right) \in \mathbb{R}^{N}$ with

$$
b_{i} \in L^{\infty}(\Omega), \quad b_{i}(x)>0,
$$

for a.e. $x \in \Omega$ and all $i=1, \ldots, N$. Further, consider the weighted space associated to $b_{i}$ on $\Omega$ which is given by

$$
L^{2}\left(\Omega, b_{i}\right)=\left\{u=u(x): b_{i}^{1 / 2} u \in L^{2}(\Omega)\right\}
$$

In this space we define the norm

$$
\|u\|_{b_{i}}=\left(\int_{\Omega} b_{i}|u|^{2} d x\right)^{1 / 2}
$$

We define $X$ to be the anisotropic Banach space obtained as the closure of $C_{0}^{1}(\Omega)$ with respect to the norm

$$
\begin{equation*}
\|u\|=\|u\|_{1+1 / m}+\max _{i=1}^{N}\left[\left\|\frac{\partial u}{\partial x_{i}}\right\|_{p_{i}} \vee\left(\int_{\Omega} b_{i}|u|^{2} d x\right)^{1 / 2}\right] . \tag{3.1}
\end{equation*}
$$

The space $X$ endowed with the norm (3.1) is a reflexive Banach space. This can be deduced as in [14 by constructing an isometric isomorphism from $X$ to a closed subspace of

$$
L^{1+1 / m}(\Omega) \times \prod_{i=1}^{N}\left(L^{p_{i}}(\Omega) \cap L^{2}\left(\Omega, b_{i}\right)\right) .
$$

The authors of [14] have shown the reflexivity of the space $L^{p_{i}}(\Omega) \cap L^{2}\left(\Omega, b_{i}\right)$ endowed with the norm $\|\cdot\|_{p_{i}} \vee\|\cdot\|_{b_{i}}$ for $i=1, \ldots, N$.

Note that as in the previous section, Theorems 2.2 and 3.1 remain true for such operators.

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