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NOTE ON STABILITY ESTIMATION IN SEQUENTIAL HYPOTHESIS TESTING

Abstract. We introduce a quantitative measure Δ of stability in optimal sequential testing of two simple hypotheses about a density of observations: $f = f_0$ versus $f = f_1$. The index Δ represents an additional cost paid when a stopping rule optimal for the pair (f_0, f_1) is applied to test the hypothesis $f = f_0$ versus a “perturbed alternative” $f = \tilde{f}_1$. An upper bound for Δ is established in terms of the total variation distance between $f_1(X)/f_0(X)$ and $\tilde{f}_1(X)/f_0(X)$ with $X \sim f_0$.

1. Problem setting. Consider two probability densities f_0 and f_1 with respect to a given σ -finite measure on $(\mathbb{R}, \mathcal{B}(\mathbb{R}))$, and suppose that a sequence X_1, X_2, \dots of i.i.d. random variables (observations defined on a suitable probability space (Ω, \mathcal{F})) has a common density f_0 or f_1 . The sequential hypothesis testing f_0 versus f_1 we deal with consists in finding an a.s. *finite stopping time* τ and a terminal decision function δ which minimize the following cost functional:

$$W(\tau, \delta) := c_0 E_0 \tau + c_1 \alpha(\tau, \delta) + c_2 \beta(\tau, \delta),$$

where E_0 represents the expectation corresponding to the density f_0 , α and β are probabilities of errors of type I and type II, respectively, and c_0, c_1, c_2 are given “penalty costs”, which are strictly positive.

In [N1] and [GNZ] it was proven (using the results from [L]) that the above problem reduces to the minimization over stopping times of the functional

$$(1) \quad V(\tau) := c_0 E_0 \tau + E_0 \min\{c_1, c_2 e^{S_\tau}\},$$

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where $S_0 := 0$ and $S_n := \sum_{k=1}^n \log[f_1(X_k)/f_0(X_k)]$, $n \geq 1$; here X_k , $k \geq 1$, are i.i.d. random variables with density f_0 . Furthermore, for certain constants $-\infty < A \leq 0 \leq B < \infty$, the a.s. finite stopping time

$$(2) \quad \tau_* = \inf\{n \geq 0 : S_n \notin (A, B)\}$$

is optimal, that is, $V(\tau_*) = \inf_{\tau} V(\tau)$.

To set the stability estimating problem we assume that the density f_1 is interpreted as some “theoretical approximation” to a “real” alternative density \tilde{f}_1 about which the statistician is not certain. Such an alternative can be set, for example, as in the problems of robust statistics, namely $\tilde{f}_1 := (1 - \varepsilon)f_1 + \varepsilon f'$ (see e.g. [H] and [J], [K1], [K2] on robust procedures for sequential hypothesis testing).

For the pair of densities (f_0, \tilde{f}_1) the cost functional $\tilde{V}(\tau)$ is defined as in (1) with S_{τ} replaced by \tilde{S}_{τ} :

$$(3) \quad \tilde{V}(\tau) := c_0 E_0 \tau + E_0 \min\{c_1, c_2 e^{\tilde{S}_{\tau}}\},$$

where

$$\tilde{S}_0 := 0, \quad \tilde{S}_n := \sum_{k=1}^n \log \left[\frac{\tilde{f}_1(X_k)}{f_0(X_k)} \right], \quad X_k \sim f_0, \quad n \geq 1.$$

Again, there exist constants $-\infty < \tilde{A} \leq 0 \leq \tilde{B} < \infty$ such that the stopping time

$$(4) \quad \tilde{\tau}_* := \inf\{n \geq 0 : \tilde{S}_n \notin (\tilde{A}, \tilde{B})\}$$

is optimal in testing f_0 against \tilde{f}_1 , i.e. $\tilde{V}(\tilde{\tau}_*) = \inf_{\tau} \tilde{V}(\tau)$.

Uncertainty about \tilde{f}_1 does not allow one to find \tilde{A} and \tilde{B} . However, we suppose that for the pair of densities (f_0, f_1) the constants (A, B) in (2) can be obtained (at least “theoretically”), and that the stopping rule determined by (A, B) is applied to \tilde{S}_n . Thus, in order to test f_0 against \tilde{f}_1 , instead of the inaccessible stopping rule (4), the following stopping rule is exercised: stop on first exit of the sequence \tilde{S}_n , $n \geq 1$, from the interval (A, B) . This procedure generates the stopping time $\tilde{\tau}$:

$$(5) \quad \tilde{\tau} := \inf\{n \geq 0 : \tilde{S}_n \notin (A, B)\}.$$

The following *stability index* (see, for instance, [GY]) measures an extra cost paid for using $\tilde{\tau}$ instead of the optimal stopping time $\tilde{\tau}_*$:

$$(6) \quad \Delta = \tilde{V}(\tilde{\tau}) - \tilde{V}(\tilde{\tau}_*) \geq 0,$$

where the functional \tilde{V} is as defined in (3).

The goal of this note is to prove the following “stability inequality”:

$$(7) \quad \Delta \leq \mathbf{Var} \left(\frac{f_1(X)}{f_0(X)}, \frac{\tilde{f}_1(X)}{f_0(X)} \right) \left\{ (c_0 + c_1) \left[\log_\beta \left(\frac{1}{4} \mathbf{Var} \left(\frac{f_1(X)}{f_0(X)}, \frac{\tilde{f}_1(X)}{f_0(X)} \right) \right) \right]^2 + b \log_\beta \left(\frac{1}{4} \mathbf{Var} \left(\frac{f_1(X)}{f_0(X)}, \frac{\tilde{f}_1(X)}{f_0(X)} \right) \right) \right\},$$

where $\beta \in (0, 1)$ and $b < \infty$ are certain constants (which can be evaluated for some particular classes of densities), X has density f_0 , and \mathbf{Var} denotes the total variation distance.

REMARK 1. In the paper [GNZ], which dealt with the same problem, a different “stability inequality” was obtained. After the publication of the paper, it was realized that the proof given in [GNZ] is correct only for another definition of the stability index Δ , which is different from (and less practical than) that given in (6). Moreover, for such a proof rather restrictive assumptions on densities have to be used.

2. Stability index estimation

ASSUMPTION 1. Let X denote a random variable with density f_0 . We assume that there exists a Borel set $D \subset \mathbb{R}$ such that $\int_D f_0(x) dx = 1$, and $f_0(x), f_1(x), \tilde{f}_1(x) > 0$ for all $x \in D$.

In what follows we denote $Y = f_1(X)/f_0(X)$ and $\tilde{Y} = \tilde{f}_1(X)/f_0(X)$.

THEOREM 1. *There are constants $\beta \in (0, 1)$ and $b < \infty$ such that*

$$(8) \quad \Delta \leq \mathbf{Var}(Y, \tilde{Y}) \left\{ (c_0 + c_1) \left[\log_\beta \left(\frac{1}{4} \mathbf{Var}(Y, \tilde{Y}) \right) \right]^2 + b \log_\beta \left(\frac{1}{4} \mathbf{Var}(Y, \tilde{Y}) \right) \right\}.$$

REMARK 2. The proof in Section 4 shows that if in (7) and (8), $\mathbf{Var}(Y, \tilde{Y})$ is small enough, then β and b are completely determined by the densities (f_0, f_1) , and so can be chosen independently of \tilde{f}_1 .

To prove (8) we use the well-known exponential inequalities (from [S2]) for the probabilities of “tails” of stopping times defined in (2), (4) and (5). In general, these inequalities are very rough. This implies that the constant $\beta < 1$ in (8) can be too close to 1. (And in some examples this is indeed the case.) For this reason, inequality (8) does not have much quantitative value, and the simplest exponential bound on “tail probabilities” is used only to indicate the way to obtain inequalities of this type. The advantage of the inequalities in [S2] is that they hold without any additional restrictions. Using more accurate bounds on “tail probabilities”, which hold under certain

restrictions on the densities f_0, f_1 and \tilde{f}_1 , one can prove more precise versions of (8) by applying the same arguments as in Section 4. For example, assuming the existence of exponential moments of Y and \tilde{Y} , the inequalities for “tail probabilities” of stopping times can be derived from exponential inequalities for sums of i.i.d. random variables (see for instance [S1], [PU]).

In any case, inequality (8) ensures that if the “approximating density” f_1 approaches to \tilde{f}_1 in the sense that $\mathbf{Var}(Y, \tilde{Y}) \rightarrow 0$, then the stability index Δ (defined in (6)) tends to zero. To grasp what the rate of convergence $\Delta \rightarrow 0$ could be, we present in Section 3 some evaluations of Δ in the simplest example of exponential densities. These data are obtained by simulations and numerical optimization.

3. Calculations of stability index for exponential densities. In functionals (1) and (3), we have chosen $c_0 = 1$ and $c_1 = c_2 = 100$. Let $f_0 \sim \text{Exp}(\lambda = 1)$, $f_1 \sim \text{Exp}(\lambda = 2)$, $\tilde{f}_{1,\varepsilon} \sim \text{Exp}(\lambda = 2 + \varepsilon)$, $\varepsilon > 0$. We denote $Y = f_1(X)/f_0(X)$, $\tilde{Y}_\varepsilon = \tilde{f}_{1,\varepsilon}(X)/f_0(X)$, where $X \sim f_0$. For this example it is easy to calculate $\mathbf{Var}(Y, \tilde{Y}_\varepsilon)$ in (8) (see Table 1). The constants β and b in (8) can also be evaluated, but they are of little help for estimating the stability index Δ quantitatively (since β is too close to 1). Table 1 displays the results of numerical calculations of $\Delta = \Delta(\varepsilon)$. To carry out these calculations we used Monte-Carlo optimizations of the corresponding stopping rules in (2), (4) and (5).

Table 1. Numerical evaluation of Δ

(f_0, f_1)		$V(\tau_*) = \inf_{\tau} V(\tau) = 15.1995$			
	ε	$\mathbf{Var}(Y, \tilde{Y}_\varepsilon)$	$\tilde{V}(\tilde{\tau}_*) = \inf_{\tau} \tilde{V}(\tau)$	$\tilde{V}(\tilde{\tau})$	$\Delta = \Delta(\varepsilon)$
$(f_0, \tilde{f}_{1,\varepsilon})$	0.1	0.1464	13.6410	13.8312	0.1902
	0.01	0.01448	15.0676	15.2301	0.1626
	10^{-3}	0.001446	15.2509	15.3564	0.1055
	10^{-5}	0.00001446	15.2966	15.2966	0.1024
	10^{-6}	1.1931×10^{-6}	15.2597	15.3289	0.0692

4. Proof of inequality (8). For the random variable X with density f_0 we denote

$$(9) \quad \mu(f_1, \tilde{f}_1) := \mathbf{Var}\left(\frac{f_1(X)}{f_0(X)}, \frac{\tilde{f}_1(X)}{f_0(X)}\right) \equiv \mathbf{Var}(Y, \tilde{Y}).$$

In view of Assumption 1, when calculating $\mathbf{Var}(Y, \tilde{Y})$ in (9) we can restrict ourselves to the set D where $Y, \tilde{Y} \in (0, \infty)$. Then using the definition

of the total variation distance and the monotonicity of log, it can be easily shown that $\mu(f_1, \tilde{f}_1) = \mathbf{Var}(\log Y, \log \tilde{Y})$.

For $k = 1, 2, \dots$ we set

$$(10) \quad Z_k = \log \left[\frac{f_1(X_k)}{f_0(X_k)} \right], \quad \tilde{Z}_k = \log \left[\frac{\tilde{f}_1(X_k)}{f_0(X_k)} \right],$$

with Z and \tilde{Z} being the corresponding generic random variables. In (10), X_1, X_2, \dots are i.i.d. random variables with density f_0 . Also as before we denote

$$S_n = \sum_{k=1}^n Z_k, \quad \tilde{S}_n = \sum_{k=1}^n \tilde{Z}_k, \quad n \geq 1, \quad S_0 = \tilde{S}_0 := 0.$$

Let (A, B) and (\tilde{A}, \tilde{B}) be the pairs of constants in (2) and (4), respectively. The stopping times obtained using rules as in (2) applied to $\{Z_k\}$ and $\{\tilde{Z}_k\}$ will be denoted by $\Psi(Z)$ and $\Psi(\tilde{Z})$ respectively. In particular, $\Psi(\tilde{Z})$ is the stopping time defined in (5). On the other hand, the stopping times obtained from rules as in (4) applied to $\{Z_k\}$ and $\{\tilde{Z}_k\}$ will be denoted by $\tilde{\Psi}(Z)$ and $\tilde{\Psi}(\tilde{Z})$ respectively. Considering the cases of practical interest, we can assume that $c_0 < c_1$. Using the results obtained in [N1], [N2] it can be proven that $A, \tilde{A} \geq A_* := \log(c_0/c_1)$, and that the constant B_* can be chosen independently of \tilde{f}_1 in such a way that $B_* \geq B, \tilde{B}$. Since $f_0 \neq f_1$ and $f_0 \neq \tilde{f}_1$, it can be easily shown that there are constants $\gamma, \tilde{\gamma}, \delta, \tilde{\delta} > 0$ such that

$$(11) \quad P(Z \leq -\gamma) \geq \delta, \quad P(\tilde{Z} \leq -\tilde{\gamma}) \geq \tilde{\delta}.$$

We suppose that for the densities under consideration, constants γ_*, δ_* are given for which the following inequalities hold: $0 < \gamma_* \leq \min(\gamma, \tilde{\gamma})$ and $0 < \delta_* \leq \min(\delta, \tilde{\delta})$.

In view of (4)–(6) and the above definition of Ψ , we have

$$(12) \quad \begin{aligned} \Delta &= \tilde{V}[\Psi(\tilde{Z})] - \tilde{V}[\tilde{\Psi}(\tilde{Z})] \\ &= \tilde{V}[\Psi(\tilde{Z})] - V[\Psi(Z)] + \max_{\Psi' \in \{\Psi, \tilde{\Psi}\}} V[\Psi'(Z)] - \max_{\Psi' \in \{\Psi, \tilde{\Psi}\}} \tilde{V}[\Psi'(\tilde{Z})] \\ &\leq 2 \max_{\Psi' \in \{\Psi, \tilde{\Psi}\}} |V[\Psi'(Z)] - \tilde{V}[\Psi'(\tilde{Z})]|. \end{aligned}$$

Estimation of each term under the “max” sign in (12) is accomplished in the same manner. Choose, for example, $\Psi' = \Psi$. Denoting $g(x) = \min\{c_1, c_2 e^x\}$, for $x \in [0, \infty)$, $\tau = \Psi(Z)$ and $\tilde{\tau} = \Psi(\tilde{Z})$, we obtain (see (1) and (3)) for any $n \geq 1$ that

$$\begin{aligned}
(13) \quad & |V[\Psi(Z)] - \tilde{V}[\Psi(\tilde{Z})]| \leq c_0 |E_0\tau - E_0\tilde{\tau}| + |E_0g(S_\tau) - E_0g(\tilde{S}_{\tilde{\tau}})| \\
& \leq c_0 |E_0\tau I_{\{\tau \leq n\}} - E_0\tilde{\tau} I_{\{\tilde{\tau} \leq n\}}| + |E_0g(S_\tau) I_{\{\tau \leq n\}} - E_0g(\tilde{S}_{\tilde{\tau}}) I_{\{\tilde{\tau} \leq n\}}| \\
& \quad + c_0 E_0\tau I_{\{\tau > n\}} + c_0 E_0\tilde{\tau} I_{\{\tilde{\tau} > n\}} + E_0g(S_\tau) I_{\{\tau > n\}} + E_0g(\tilde{S}_{\tilde{\tau}}) I_{\{\tilde{\tau} > n\}} \\
& =: I_1 + I_2 + I_3 + I_4.
\end{aligned}$$

On the right-hand side of (13), $\tau I_{\{\tau \leq n\}}$ and $g(S_\tau) I_{\{\tau \leq n\}}$ are nonnegative bounded functions of the random vector $\bar{Z}_n = (Z_1, \dots, Z_n)$. Thus denoting $\tilde{\bar{Z}}_n = (\tilde{Z}_1, \dots, \tilde{Z}_n)$ we find that in (13),

$$(14) \quad I_1 \leq c_0(n/2) \mathbf{Var}(\bar{Z}_n, \tilde{\bar{Z}}_n), \quad I_2 \leq (1/2) \mathbf{Var}(\bar{Z}_n, \tilde{\bar{Z}}_n).$$

Let us show by induction that

$$(15) \quad \mathbf{Var}(\bar{Z}_n, \tilde{\bar{Z}}_n) \leq n \mathbf{Var}(Z, \tilde{Z}), \quad n = 1, 2, \dots$$

Indeed, by the triangle inequality,

$$\begin{aligned}
(16) \quad & \mathbf{Var}[(Z_1, \dots, Z_n, Z_{n+1}), (\tilde{Z}_1, \dots, \tilde{Z}_n, \tilde{Z}_{n+1})] \\
& \leq \mathbf{Var}[(Z_1, \dots, Z_n, Z_{n+1}), (\tilde{Z}_1, \dots, \tilde{Z}_n, Z_{n+1})] \\
& \quad + \mathbf{Var}[(\tilde{Z}_1, \dots, \tilde{Z}_n, Z_{n+1}), (\tilde{Z}_1, \dots, \tilde{Z}_n, \tilde{Z}_{n+1})].
\end{aligned}$$

For every function $\varphi : \mathbb{R}^{n+1} \rightarrow \mathbb{R}$ bounded by 1 we obtain (by independence)

$$\begin{aligned}
& |E_0\varphi(Z_1, \dots, Z_n, Z_{n+1}) - E_0\varphi(\tilde{Z}_1, \dots, \tilde{Z}_n, Z_{n+1})| \\
& \leq \int_{\mathbb{R}} |E_0\varphi(Z_1, \dots, Z_n, z) - E_0\varphi(\tilde{Z}_1, \dots, \tilde{Z}_n, z)| P_Z(dz) \\
& \leq \mathbf{Var}(\bar{Z}_n, \tilde{\bar{Z}}_n) \leq n \mathbf{Var}(Z, \tilde{Z}).
\end{aligned}$$

Consequently, the first summand on the right-hand side of (16) is less than $n \mathbf{Var}(Z, \tilde{Z})$. Applying again independence and conditioning on $\tilde{Z}_1, \dots, \tilde{Z}_n$, we conclude that the second term on the right-hand side of (16) is less than $\mathbf{Var}(Z, \tilde{Z})$.

To bound the terms I_3 and I_4 in (13) we use the simple exponential inequalities for $P_0(\tau > n)$, $P_0(\tilde{\tau} > n)$ obtained in [S2]. Denoting

$$m := [(B_* - A_*)/\gamma_*] + 1, \quad \beta := (1 - \delta_*^m)^{1/m},$$

($[\cdot]$ stands for integer part) we can see that, from the result in [S2],

$$(17) \quad \max\{P_0(\tau > n), P_0(\tilde{\tau} > n)\} \leq \gamma\beta^n, \quad n = 1, 2, \dots, \quad \text{where } \gamma = \beta^{-m}.$$

Using these inequalities, after simple calculations we find that

$$(18) \quad I_3 \leq \beta^{n+1} n \left(2c_0 \frac{\gamma(2-\beta)}{\beta(1-\beta)} \right), \quad n = 1, 2, \dots$$

Applying (17) again we see that

$$(19) \quad I_4 \leq \beta^{n+1}(2c_1\gamma/\beta), \quad n = 1, 2, \dots$$

Combining inequalities (12)–(15), (18) and (19) we establish that for every $n \geq 1$,

$$(20) \quad \Delta \leq 2 \left[\frac{c_0}{2} n^2 \mu(f_1, \tilde{f}_1) + \frac{c_1}{2} n \mu(f_1, \tilde{f}_1) \right. \\ \left. + \beta^{n+1} n \left(2c_0 \frac{\gamma(2-\beta)}{\beta(1-\beta)} \right) + \beta^{n+1} (2c_1\gamma/\beta) \right] \\ \leq (c_0 + c_1) n^2 \mu(f_1, \tilde{f}_1) + \beta^{n+1} n \left[\frac{4\gamma}{\beta} \left(c_0 \frac{2-\beta}{1-\beta} + c_1 \right) \right].$$

Now we choose in (20) $n = [\log_\beta \frac{1}{4} \mu(f_1, \tilde{f}_1)]$ (the integer part). Then inequality (8) follows from (20). ■

REMARK 3. In view of (11), if $\mathbf{Var}(Z, \tilde{Z})$ is small enough, the constants γ_* and δ_* can be chosen in such a way that they do not depend on the density f_1 .

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