## Regularity of domains of parameterized families of closed linear operators

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To Professor Józef Siciak on the occasion of his 70th birthday

Abstract. The purpose of this paper is to provide a method of reduction of some problems concerning families  $A_t = (A(t))_{t \in \mathcal{T}}$  of linear operators with domains  $(\mathcal{D}_t)_{t \in \mathcal{T}}$ to a problem in which all the operators have the same domain  $\mathcal{D}$ . To do it we propose to construct a family  $(\Psi_t)_{t \in \mathcal{T}}$  of automorphisms of a given Banach space X having two properties: (i) the mapping  $t \mapsto \Psi_t$  is sufficiently regular and (ii)  $\Psi_t(\mathcal{D}) = \mathcal{D}_t$  for  $t \in \mathcal{T}$ . Three effective constructions are presented: for elliptic operators of second order with the Robin boundary condition with a parameter; for operators in a Hilbert space for which eigenspaces form a complete orthogonal system of closed linear subspaces; and for a class of closed operators having bounded inverses.

**1. Introduction.** Most of the results concerning differential operators with a parameter t in the coefficients have been obtained under the assumption that the operators  $(A_t = A(t))_{t \in \mathcal{T}}$  of a given family have domains independent of t (see e.g. [2, 6, 7, 8]).

One of possible ways of handling some problems concerning operators  $(A_t)_{t\in\mathcal{T}}$  with domains  $\mathcal{D}_t \subset X$  depending on t is to find a sufficiently regular (with respect to  $t\in\mathcal{T}$ ) family  $\Psi_t$  of automorphisms of the Banach space X such that  $\Psi_t(\mathcal{D}_t) = \mathcal{D}$ , where  $\mathcal{D}$  is a fixed linear subspace of X.

In general, the domain of a differential operator is determined by some boundary conditions. Thus it would be useful to find an effective construction of a family  $\Psi_t$  using the boundary conditions only. Such a construction for a family of elliptic operators of order two with the Robin boundary condition with a parameter (i.e.  $\partial u/\partial n + a(x,t)u = 0$  on  $\partial \Omega$ ) is presented in 2.1. The problem of existence and construction of a family  $(\Psi_t)_{t\in\mathcal{T}}$  for general types of boundary conditions is more delicate and still open.

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In Section 2.2 there is a construction of a continuous family  $\Psi_t$  for some families  $(\mathcal{D}_t)_{t\in\mathcal{T}}$  of domains of operators in a Hilbert space H for which the corresponding eigenspaces form a complete orthogonal system of closed linear subspaces of H.

If  $\mathcal{D}_t$  is the domain of a closed invertible operator  $A_t : X \to X$  and  $R_t = A_t^{-1}$ , for  $t \in \mathcal{T}$ , then the natural candidate for  $\Phi_t = \Psi_t^{-1}$  is  $\overline{R_{t_0}A_t}$  whenever  $R_{t_0}A_t$  is closable. If it is closable then we may use some results presented in [3] concerning the topology of generalized convergence to prove that the expected family is good (for more details see Section 3). Unfortunately, if  $\mathcal{D}_t$  depends on t, it may happen that  $R_{t_0}A_t$  is not closable.

**2. Regularity of families of linear subspaces.** Let X be a Banach space,  $\mathcal{T}$  an interval in  $\mathbb{R}$ , and  $(\mathcal{D}_t)_{t \in \mathcal{T}}$  a family of linear subspaces of X.

DEFINITION 1. We say that the family  $(\mathcal{D}_t)_{t\in\mathcal{T}}$  is of class  $\mathcal{C}_a{}^k$  (resp. strongly of class  $\mathcal{C}_a{}^k$ ) if there exist a linear subspace  $\mathcal{D}$  of X and a family  $(\Psi_t)_{t\in\mathcal{T}}$  of automorphisms of X such that

• the mapping  $\mathcal{T} \ni t \mapsto \Psi_t \in \operatorname{Aut}(X)$  is of class  $\mathcal{C}^k$  (resp. strongly of class  $\mathcal{C}^k$  (<sup>1</sup>) and

•  $\Psi_t(\mathcal{D}) = \mathcal{D}_t$  for  $t \in \mathcal{T}$ .

Considering a family  $(A_t)_{t\in\mathcal{T}}$  of closed linear operators with the family of domains  $(\mathcal{D}_t = \mathcal{D}(A_t))_{t\in\mathcal{T}}$  of class  $\mathcal{C}_a{}^k$  we may reduce some problems to a family with a constant domain. For example, suppose that u is a classical solution of the evolution equation

(1) 
$$\frac{du}{dt} = A(t)u + f(t)$$

in which the family of domains  $(\mathcal{D}_t = \mathcal{D}(A_t) = \mathcal{D}(A(t)))_{t \in \mathcal{T}}$  is of class  $\mathcal{C}_a^1$ . Let  $(\Psi_t)_{t \in \mathcal{T}}$  be a family of automorphisms of X as above and  $(\Phi_t = \Psi_t^{-1})_{t \in \mathcal{T}}$  the family of inverses.

Since  $u(t) \in \mathcal{D}_t$ , there exists  $v(t) \in \mathcal{D}$  such that  $\Psi_t(v(t)) = u(t)$ . We have

$$\frac{du}{dt} = \frac{d\Psi_t}{dt}v(t) + \Psi_t \frac{dv}{dt}$$

and after a standard calculation we obtain

$$\frac{dv}{dt} = \underbrace{\left(\Phi_t A(t)\psi_t - \frac{d\psi_t}{dt}\right)}_{B(t)} v(t) + \underbrace{\Phi_t f(t)}_{F(t)}.$$

Thus v is a classical solution of the evolution equation

(2) 
$$\frac{dv}{dt} = B(t)v + F(t)$$

with the family  $(B_t = B(t))_{t \in \mathcal{T}}$  of operators having domains independent of t.

<sup>(&</sup>lt;sup>1</sup>) This means that for any  $x \in X$  the mapping  $t \mapsto \Psi_t x$  is of class  $\mathcal{C}^k$ .

**2.1.** Construction using boundary conditions. Now we produce an example of a family  $(\mathcal{D}_t)_{t\in\mathcal{T}}$  of class  $\mathcal{C}_a{}^k$ ,  $k \geq 1$ , of the domains for elliptic operators of order two which is a nonconstant family of linear subspaces of  $X = \mathcal{L}^2(\Omega)$ .

Let  $\Omega$  be a bounded domain in  $\mathbb{R}^n$  with boundary  $S = \partial \Omega$  of class  $\mathcal{C}^{k+1}$ ,  $\mathcal{T} = [0, T]$ , and let  $a : \overline{\Omega} \times \mathcal{T} \to \mathbb{R}$  be a function of class  $\mathcal{C}^k$  nonvanishing on S. The sets

(3) 
$$\mathcal{D}_t = \left\{ u \in \mathcal{L}^2(\Omega) : u \in H^2(\Omega) \text{ and } \frac{\partial u}{\partial n} + a(x,t)u = 0 \text{ on } \partial \Omega \right\},$$

(4) 
$$\mathcal{D} = \left\{ u \in \mathcal{L}^2(\Omega) : u \in H^2(\Omega) \text{ and } \frac{\partial u}{\partial n} = 0 \text{ on } \partial \Omega \right\}$$

are dense linear subspaces of  $\mathcal{L}^2(\Omega)$ , where *n* is the interior unit normal vector field on *S*.

Let  $\eta: \overline{\Omega} \times \mathcal{T} \to \mathbb{R}$  be a function of class  $\mathcal{C}^k$  such that

(5) 
$$1/2 \le \eta_t(x) = \eta(x,t) \quad \text{for } x \in \overline{\Omega}, \ t \in \mathcal{T},$$

(6) 
$$\eta_t(x) = 1$$
 and  $\frac{\partial \eta_t(x)}{\partial n} = a(x,t)$  for  $x \in \partial \Omega, t \in \mathcal{T}$ .

The function  $\eta$  can be constructed in the following way. We consider S as the retract of class  $\mathcal{C}^k$  (for  $\varepsilon > 0$  small enough) of the open  $\varepsilon$ -tube

 $\mathrm{TUB}^{\varepsilon}(S) = \{ x + \tau n(x) : x \in S, \ |\tau| < \varepsilon \}.$ 

Then we take a function  $h_{\varepsilon}$  of class  $\mathcal{C}^{\infty}$  in  $\mathbb{R}^n$  satisfying the following conditions:

$$h_{\varepsilon}(x) = 0 \qquad \text{for } x \in \mathbb{R}^n \setminus \text{TUB}^{\varepsilon}(S),$$
  

$$h_{\varepsilon}(x) = 1 \qquad \text{for } x \in \text{TUB}^{\varepsilon/2}(S),$$
  

$$h_{\varepsilon}(x) \in [0, 1] \qquad \text{for } x \in \mathbb{R}^n.$$

The function

(7) 
$$f_{\varepsilon}: \mathrm{TUB}^{\varepsilon}(S) \ni x + \tau n(x) \mapsto a(t, x)\tau \in \mathbb{R}$$

is of class  $\mathcal{C}^k$ , and for  $\varepsilon$  small enough, the function  $\eta = h_{\varepsilon} f_{\varepsilon} + 1$  is one we have been looking for.

Let 
$$\Phi_t : \mathcal{L}^2(\Omega) \to \mathcal{L}^2(\Omega)$$
 be given by  
(8)  $\Phi_t(u) = \eta_t \cdot u \quad \text{for } u \in \mathcal{L}^2(\Omega), \ t \in [0,T]$ 

and let  $\Psi_t = \Phi_t^{-1}$ . One can verify that

- $\Phi_t \in \operatorname{Aut}(\mathcal{L}^2(\Omega)),$
- $\Phi_t(\mathcal{D}_t) = \mathcal{D}$  and  $\Psi_t(\mathcal{D}) = \mathcal{D}_t$ ,
- the mapping  $\mathcal{T} \ni t \mapsto \Phi_t \in \mathcal{B}(\mathcal{L}^2(\Omega))$  is of class  $\mathcal{C}^k$ . Thus the mapping  $\mathcal{T} \ni t \to \Psi_t \in \mathcal{B}(\mathcal{L}^2(\Omega))$  is also of class  $\mathcal{C}^k$ .

Considering parametrized boundary conditions of the form

(9) 
$$\frac{\partial u}{\partial \mu_t} + a(x,t)u = 0 \quad \text{on } \partial \Omega.$$

where  $\mu_t$  is a vector field on S parametrized by  $t \in \mathcal{T}$ , one can look for  $\Phi_t$  of the form

(10) 
$$\Phi_t u = \eta_t \cdot (u \circ \varphi_t) \quad \text{for } u \in \mathcal{L}^2(\Omega),$$

where  $\varphi_t$  is a diffeomorphism of  $\overline{\Omega}$  such that  $\varphi'_t(x).n(x) = \mu_t(x), \varphi_t(x) = x$ for  $x \in S, t \in \mathcal{T}$ , and  $\eta$  is as in (8). Indeed, if u satisfies (9) then

$$\frac{\partial(u\circ\varphi)}{\partial n}(x) + a(x,t)(u\circ\varphi)(x) = \frac{\partial u}{\partial \mu_t} + a(x,t)u = 0 \quad \text{ on } \partial\Omega.$$

Thus,  $v = u \circ \varphi_t \in \mathcal{D}_t$ ,  $\eta_t v \in \mathcal{D}$  and vice versa.

Let us remark that the boundary conditions (9) parametrized by t are natural, for example, when we consider the family  $(A_t = tA + (1-t)\Delta)_{t \in [0,1]}$ in which A is a strongly elliptic operator of the second order. For an application see the second part of the proof of Theorem 3.4 in [1].

**2.2.** Construction using eigenspaces. Let H be a Hilbert space, and  $H_j$ ,  $j = 1, 2, \ldots$ , a complete orthogonal sequence of closed linear subspaces of H. We will use the following well known facts from the theory of Fourier series.

LEMMA 1. If  $a_j \in H_j$  for j = 1, 2, ... then the series  $\sum_{j=1}^{\infty} a_j$  converges to a point  $a \in H$  if and only if the series  $\sum_{j=1}^{\infty} ||a_j||^2$  is convergent. Moreover, if

$$a = \sum_{j=1}^{\infty} a_j$$

then

$$||a||^2 = \sum_{j=1}^{\infty} ||a_j||^2$$
 and  $a_j = p_j(a)$  for  $j = 1, 2, ...,$ 

where  $p_j : H \to H_j$  is the orthogonal projection of H onto  $H_j$  for j = 1, 2, ...

To any sequence  $\lambda = \{\lambda_j\}_{j=1}^{\infty}$  of real (complex if H is a complex space) numbers corresponds a closed linear operator  $A = A_{\lambda}(t) : H \to H$  given by

$$Ax = A_{\lambda}x = \sum_{j=1}^{\infty} \lambda_j p_j(x).$$

The operator A with domain

$$\mathcal{D} := \mathcal{D}(A) = \left\{ x \in H : \sum_{j=1}^{\infty} \lambda_j p_j(x) \text{ is convergent} \right\}$$

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is a closed densely defined linear operator and  $\lambda_j$  is an eigenvalue of A corresponding to the eigenspace  $H_j$ .

From now on we assume that  $H_j$  and  $\lambda_j$  depend on the parameter  $t \in \mathcal{T}$ . This implies that the projections  $p_j$ ,  $j = 1, 2, \ldots$ , also depend on t. Thus,  $H_j(t), \lambda_j(t), p_j(t), j = 1, 2, \ldots$ , are sequences of closed subspaces, numbers and projections, respectively, parametrized by  $t \in \mathcal{T}$ .

PROPOSITION 2. Suppose that for given  $t, t_0 \in \mathcal{T}, \Phi_j(t) : H \to H$ ,  $j = 1, 2, \ldots$ , are bounded linear mappings satisfying the following conditions:

(i)  $\Phi_j(t)(H_j(t)) = H_j(t_0)$  and  $\Phi_j(t)|_{H_j(t)} : H_j(t) \to H_j(t_0)$  is an isomorphism of Banach spaces for j = 1, 2, ...,

(ii) there exist positive constants M(t), m(t) > 0 such that

$$m(t)||x|| \le ||\Phi_j(t)x|| \le M(t)||x||$$
 for  $x \in H_j(t), \ j = 1, 2, ...,$ 

(iii) there exist positive constants  $\delta(t), \Delta(t) > 0$  such that

$$\delta(t) \le \left| \frac{\lambda_j(t_0)}{\lambda_j(t)} \right| \le \Delta(t) \quad \text{for } j = 1, 2, \dots$$

Then

(11) 
$$\Phi_t := \Phi(t) = \sum_{j=1}^{\infty} \Phi_j(t) \circ p_j(t)$$

is an automorphism of H such that  $\Phi_t(\mathcal{D}_t) = \mathcal{D}_{t_0}$ .

*Proof.* We begin by proving that  $\Phi_t$  is well defined. Since

$$\|\Phi_j(t)(p_j(t)x)\|^2 \le \|\Phi_j(t)\|^2 \|p_j(t)x\|^2 \le M^2(t) \|p_j(t)x\|^2$$

and the series  $\sum_{j=1}^{\infty} \|p_j(t)x\|^2$  is convergent (because  $\sum_{j=1}^{\infty} p_j(t)x$  is convergent), the series defining  $\Phi_t x$  is convergent for any  $(t, x) \in I \times H$ .

Since

$$\|\Phi_t x\|^2 = \sum_{j=1}^{\infty} \|\Phi_j(t)p_j(t)x\|^2 \le M^2(t)\|x\|^2,$$

the operator  $\Phi_t$  is bounded.

Injectivity of  $\Phi_t$  follows from Lemma 1. Indeed,

$$\ker \Phi_t = \{ x \in H : \Phi_j(t) p_j(t) x = 0, \ j = 1, 2, \ldots \} = \{ 0 \}.$$

Let  $y \in H$  and

(12) 
$$x = \sum_{j=1}^{\infty} (\Phi_j(t))^{-1} p_j(t_0) y.$$

To prove surjectivity we must prove that the series (12) defining x is convergent and that  $\Phi_t x = y$ .

Assuming the convergence for the moment, we have

$$\Phi_t x = \sum_{j=1}^{\infty} \Phi_j(t) p_j(t) x = \sum_{j=1}^{\infty} \Phi_j(t) (\Phi_j(t))^{-1} p_j(t_0) y = \sum_{j=1}^{\infty} p_j(t_0) y = y.$$

The convergence of  $\sum_{j=1}^{\infty} (\Phi_j(t))^{-1} p_j(t_0) y$  follows from Lemma 1, because of the estimates

$$\|(\Phi_j(t))^{-1}p_j(t_0)y\|^2 \le \frac{1}{m(t)} \|p_j(t)y\|^2 \text{ for } j=1,2,\ldots, y \in X.$$

For  $x \in \mathcal{D}_t$  the series  $\sum_{j=1}^{\infty} \lambda_j(t) p_j(t) x$  is convergent and we have  $\Phi_t x = y = \sum_{j=1}^{\infty} p_j(t_0) y$ . Thus

$$\sum_{j=1}^{\infty} \Phi_j(t) p_j(t) x = \sum_{j=1}^{\infty} p_j(t_0) y,$$

which implies that

(13)  $p_j(t_0)y = \Phi_j(t)p_j(t)x.$ 

Since

$$\left\|\frac{\lambda_j(t_0)}{\lambda_j(t)} \varPhi_j(t)(\lambda_j(t)p_j(t))x\right\|^2 \le \left|\frac{\lambda_j(t_0)}{\lambda_j(t)}\right|^2 M^2(t) \|\lambda_j(t)p_j(t)\|^2$$
$$\le \Delta^2(t) M^2(t) \|\lambda_j(t)p_j(t)\|^2,$$

the series

$$\sum_{j=1}^{\infty} \frac{\lambda_j(t_0)}{\lambda_j(t)} \Phi_j(t) (\lambda_j(t) p_j(t)) x$$

is convergent and hence, because of (13), so is  $\sum_{j=1}^{\infty} \lambda_j(t_0) p_j(t_0) y$ . This means that  $\Phi_t(\mathcal{D}_t) \subset \mathcal{D}_{t_0}$ . The proof of the inverse inclusion is similar.

REMARK 1. If, in Proposition 2,  $\Phi_j(t) : H_j(t) \to H_j(t_0)$  is an isometry for all j and t, then  $\Phi_t$  is also an isometry.

THEOREM 3. If the mappings

$$I \ni t \mapsto p_j(t) \quad and \quad I \ni t \mapsto \Phi_j(t) \quad for \ j = 1, 2, \dots$$

are continuous and there exist M, m > 0 such that

$$m||x|| \le ||\Phi_j(t)x|| \le M||x||$$
 for  $j = 1, 2, \dots, x \in X$ ,

then for any compact set  $K \subset I \times H$ , the mapping  $K \ni (t, x) \mapsto \Phi_t x$  is continuous.

*Proof.* By Dini's theorem, the sequence

$$S_{\nu}(t,x) = \sum_{j=1}^{\nu} \|p_j(t)x\|^2, \quad \nu = 1, 2, \dots,$$

converges uniformly to  $||x||^2$  on compact subsets of  $I \times H$ . Since

$$\left\|\sum_{j=p}^{p+s} \Phi_j(t)(p_j(t)x)\right\|^2 \le M^2 \sum_{j=p}^{p+s} \|p_j(t)x\|^2,$$

the Cauchy condition of uniform convergence is satisfied for the series  $\sum_{j=1}^{\infty} \Phi_j(t)(p_j(t)x)$  and so  $\Phi$  is continuous on K.

To obtain a higher regularity for the family  $(\Phi_t)$  we must assume a higher regularity for  $\Phi_j(t)$  and some assumptions that guarantee differentiability of series term by term.

EXAMPLE 1. The mapping

$$\Phi_i(t) := p_i(t_0) \circ p_i(t) : H \to H_i(t_0) \subset H$$

is a bounded linear map. Assuming, for example, that

$$H_{i}^{\perp}(t_{0}) \cap H_{j}(t) = \{0\}$$

we see that  $\Phi_i(t)$  is injective.

If additionally we assume that  $\dim H_j(t)=k_j<\infty$  is independent of t then

$$\Phi_j(t)|_{H_j(t)}: H_j(t) \to H_j(t_0)$$

is an isomorphism. Moreover

$$\|\Phi_j(t)x\|^2 \le \|p_j(t)x\|^2$$
 and  $\Phi_j(t_0) = p_j(t_0)$ .

Therefore, using the same method as in the proof of Theorem 3, we may prove that the continuity of the mapping  $I \times H \ni (t, x) \mapsto p_j(t)x \in H$  for  $j = 1, 2, \ldots$  implies the continuity of  $\Phi$  on compact subsets of  $I \times H$ .

**3.** Families of closed operators with bounded inverses. Let X, Ybe Banach spaces over the field  $\mathbb{K}$  of real or complex numbers. We endow the space C(X,Y) of closed linear operators  $A: X \to Y$  with the topology of generalized convergence [3, Ch. IV]. The domain of a given operator  $A: X \to Y$  is denoted by  $\mathcal{D}(A)$ . The space of bounded linear operators  $A: X \to Y$  is denoted by  $\mathcal{B}(X,Y)$ , and  $\operatorname{Isom}(X,Y)$  is the subspace of  $\mathcal{B}(X,Y)$  of bijective bounded linear operators with bounded inverses. The subspace of C(X, Y) consisting of the invertible densely defined operators A such that  $A^{-1} \in \mathcal{B}(Y, X)$  will be denoted by  $\mathcal{R}(X, Y)$ . If X = Y we will write  $C(X), \mathcal{B}(X), \operatorname{Aut}(X), \mathcal{R}(X)$  instead of  $C(X, X), \mathcal{B}(X, X), \operatorname{Isom}(X, X),$  $\mathcal{R}(X,X)$ , respectively. Since  $\mathcal{B}(X,Y) \subset C(X,Y)$ , we may consider  $\mathcal{B}(X,Y)$ with the induced topology, which by [3, Ch. IV, Theorem 2.23] is equivalent to the norm topology in  $\mathcal{B}(X,Y)$ . Let us also recall that by the same theorem, the convergence of  $A_n$  to A in  $\mathcal{R}(X, Y)$  is equivalent to the convergence of  $A_n^{-1}$  to  $A^{-1}$  in  $\mathcal{B}(Y, X)$ , Isom(X, Y) is open in C(X, Y) and Aut(X) is open in C(X).

LEMMA 4. Let  $\mathcal{H}$  be a metric space,  $A_h \in \mathcal{R}(X, Y)$  and  $\Phi_h \in \operatorname{Aut}(X)$ for  $h \in \mathcal{H}$ . If the mappings

(14) 
$$\mathcal{H} \ni h \mapsto A_h \in C(X, Y) \quad and \quad \mathcal{H} \ni h \mapsto \Phi_h \in \mathcal{B}(X)$$

are continuous then the mapping

(15) 
$$\mathcal{H} \ni h \mapsto A_h \circ \Phi_h \in \mathcal{R}(X, Y)$$

is also continuous.

*Proof.* Since  $A_h \in \mathcal{R}(X, Y)$ , the continuity of  $\mathcal{H} \ni h \mapsto A_h \in C(X, Y)$  is equivalent to the continuity of  $\mathcal{H} \ni h \mapsto A_h^{-1} \in \mathcal{B}(Y, X)$ . Thus the mapping  $\mathcal{H} \ni h \mapsto (A_h \circ \Phi_h)^{-1} = \Phi_h^{-1} \circ A_h^{-1} \in \mathcal{B}(Y, X)$  is continuous, and hence so is the mapping (15).

LEMMA 5. Let  $A_j \in \mathcal{R}(X, Y)$  and  $R_j = A_j^{-1}$  for j = 1, 2. If  $R_j \circ A_i$  is bounded for i, j = 1, 2, then  $\mathcal{D}(A_1^*) = \mathcal{D}(A_2^*)$ .

*Proof.* By symmetry, it is enough to prove that  $\mathcal{D}(A_1^*) \subset \mathcal{D}(A_2^*)$ . Take  $y^* \in \mathcal{D}(A_1^*)$ . Since

$$\begin{aligned} |\langle A_2 x, y^* \rangle| &= |\langle A_1 \circ (R_1 \circ A_2) x, y^* \rangle| = |\langle (R_1 \circ A_2) x, A_1^* y^* \rangle| \\ &\leq ||A_1^* y^*|| \cdot ||R_1 \circ A_2|| \cdot ||x|| \quad \text{for } x \in \mathcal{D}(A_2), \end{aligned}$$

we have  $y^* \in \mathcal{D}(A_2^*)$  and so  $\mathcal{D}(A_1^*) \subset \mathcal{D}(A_2^*)$ .

LEMMA 6. If  $A \in C(X, Y)$  and  $\Phi \in \mathcal{B}(X)$  is such that  $\mathcal{D}(A \circ \Phi)$  is dense in X then  $\mathcal{D}(A^*) \subset \mathcal{D}((A \circ \Phi)^*)$ . Moreover, if  $\Phi \in \operatorname{Aut}(X)$  then  $\mathcal{D}(A^*) = \mathcal{D}((A \circ \Phi)^*)$ .

*Proof.* Let  $y^* \in \mathcal{D}(A^*)$ . Since  $\Phi$  is continuous, for  $x \in \mathcal{D}(A \circ \Phi)$  we have  $|\langle (A \circ \Phi)x, y^* \rangle| = |\langle \Phi x, A^* y^* \rangle| \le ||A^* y^*|| \cdot ||\Phi x|| \le ||A^* y^*|| \cdot ||\Phi|| \cdot ||x||$ and so  $y^* \in \mathcal{D}((A \circ \Phi)^*)$ .

If  $\Phi$  is invertible then by the above  $\mathcal{D}((A \circ \Phi)^*) \subset \mathcal{D}((A \circ \Phi \circ \Phi^{-1})^*) = \mathcal{D}(A^*)$ .

THEOREM 7. Let  $(\mathcal{H}, \varrho)$  be a connected metric space and  $(A_h)_{h \in \mathcal{H}}$  a family of linear operators  $A_h \in \mathcal{R}(X, Y)$ . If  $R_k \circ A_h$  is closable for each  $h, k \in \mathcal{H}$ , and for each  $k \in \mathcal{H}$  the mapping

(16) 
$$\mathcal{H} \ni h \mapsto \overline{R_k \circ A_h} \in C(X)$$

is continuous, then:

(i) 
$$\overline{R_k \circ A_h} \in \operatorname{Aut}(X)$$
 for each  $h, k \in \mathcal{H}$ ,

(ii) for any  $h, k \in \mathcal{H}$  there exist m, M > 0 such that

$$\|R_h y\| \le \|R_k y\| \le M \|R_h y\| \quad \text{for } y \in Y,$$

(iii)  $\mathcal{D}(A_h^*) = \mathcal{D}^* = \text{const},$ (iv)  $\mathcal{D}(A_h^* \circ R_k^*) = X^* \text{ for all } h, k \in \mathcal{H}.$ 

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*Proof.* Since  $\operatorname{Aut}(X)$  is open in C(X) and  $\overline{R_k \circ A_k} = \operatorname{Id}_X \in \operatorname{Aut}(X)$ , there exists  $\delta = \delta(k) > 0$  such that  $\overline{R_k \circ A_h} \in \operatorname{Aut}(X)$  for any  $h \in \mathcal{H}$  such that  $\varrho(h, k) < \delta$ . Thus, for a given  $k \in \mathcal{H}$ ,

$$\mathfrak{M} = \{h \in \mathcal{H} : \overline{R_k \circ A_h} \in \operatorname{Aut}(X)\} \neq \emptyset.$$

To prove that  $\mathfrak{M} = \mathcal{H}$  it is enough to prove that  $\mathfrak{M}$  is open and closed. For given  $h_0 \in \mathfrak{M}, h \in \mathcal{H}$  we have

$$\overline{R_k \circ A_h} = \overline{R_k \circ A_{h_0}} \circ \overline{R_{h_0} \circ A_h}.$$

Since  $\overline{R_k \circ A_{h_0}} \in \operatorname{Aut}(X)$ , and by the same argument as before there exists  $\delta = \delta(h_0) > 0$  such that  $\overline{R_{h_0} \circ A_h} \in \operatorname{Aut}(X)$  for any  $h \in \mathcal{H}$  satisfying  $\varrho(h, h_0) < \delta$ , the set  $\mathfrak{M}$  is open. Suppose now that  $h_n \in \mathfrak{M}$  for  $n = 1, 2, \ldots$  and  $h_n \to h_0 \in \mathcal{H}$  as  $n \to \infty$ . Then there exists  $n \in \mathbb{N}$  such that  $\overline{R_{h_0} \circ A_{h_n}} \in \operatorname{Aut}(X)$ , by the previous part of the proof. Since  $\overline{R_k \circ A_{h_n}} = \overline{R_k \circ A_{h_0}} \circ \overline{R_{h_0} \circ A_{h_n}}$  are automorphisms of X, it follows that  $h_0 \in \mathfrak{M}$  and so  $\mathfrak{M}$  is closed.

To prove (ii) fix  $h, k \in \mathcal{H}$ . Since  $\overline{R_k \circ A_h} \in \operatorname{Aut}(X)$ , there exist m, M > 0 such that

$$m\|x\| \le \|(R_k \circ A_h)x\| \le M\|x\| \quad \text{for } x \in \mathcal{D}(A_h).$$

Since  $A_h$  is onto, taking  $y = A_h x$  we get

 $m||R_h y|| \le ||R_k y|| \le M||R_h y|| \quad \text{for } y \in Y.$ 

To prove (iii) observe that for  $k, h \in \mathcal{H}$  we have  $A_h = A_k \circ \overline{R_k \circ A_h}$ . Thus, by Lemma 6,  $\mathcal{D}(A_h^*) = \mathcal{D}(A_k^*)$ , because  $\overline{R_k \circ A_h} \in \operatorname{Aut}(X)$ .

(iv) is a consequence of the fact that  $R_k^* \in \mathcal{B}(X^*, Y^*)$  is the inverse to  $A_k^*$  (see e.g. [3, Ch. III, Theorem 5.30]), which has the same domain as  $A_h^*$ , because of (3).

REMARK 2. Observe that for  $h, k \in \mathcal{H}$ , if  $R_k \circ A_h$  and  $R_h \circ A_k$  are closable then conditions (i)–(iv) of Theorem 7 are equivalent. If  $\mathcal{D}(A_h^* \circ R_k^*)$  is dense in  $X^*$  in the weak\* topology on  $X^*$  then  $R_k \circ A_h$  is closable. If condition (iii) of Theorem 7 is satisfied, then  $R_k \circ A_h$  is closable and (i), (ii), (iv) hold.

A sufficient condition for the assumptions of Theorem 7 to hold is presented in the following

PROPOSITION 8. If  $\mathcal{H} = [0, T]$ , all the operators of the family  $(A_t^*)_{t \in [0, T]}$ have the same domain  $\mathcal{D}^*$  and for every  $y^* \in \mathcal{D}^*$  the mapping

(17) 
$$[0,T] \ni t \mapsto A_t^* y^* \in X^*$$

is of class  $C^1$  then the family  $(A_t)_{t \in [0,T]}$  satisfies the assumptions of Theorem 7.

*Proof.* By [4, Ch. II, Lemma 1.5], the family  $(A_t^* \circ R_s^*)_{s,t \in [0,T]}$  of bounded operators is continuous with respect to (s,t). Since also  $A_t^* \circ R_s^* = (R_s \circ A_t)^*$ 

and  $\mathcal{D}((R_s \circ A_t)^*) = X^*$ , the mapping  $R_s \circ A_t$  is closable, and by [3, Ch. IV, Theorem 2.23], the continuity of the family  $(R_s \circ A_t)^*$  with respect to (s, t) implies the continuity of  $(\overline{R_s \circ A_t})$ .

**3.1.** Some remarks on the case of differential operators. Let  $\Omega$  be a bounded domain in  $\mathbb{R}^n$  with smooth boundary  $\partial \Omega$ , and  $\mathcal{H}$  a connected metric space. Let

(18) 
$$A_h = \sum_{|\alpha| \le m} a_{\alpha}(x, h) D^{\alpha} \quad \text{for } h \in \mathcal{H}$$

be a family of differential operators of order m with coefficients  $a_{\alpha}$  continuous in  $\overline{\Omega} \times \mathcal{H}$ . Closedness of  $A_h$  and continuity of the mapping  $h \mapsto A_h$ depend on the domain  $\mathcal{D}(A_h)$ , the space X in which  $\mathcal{D}(A_h)$  is contained, and the space Y of values of  $A_h$ .

• If  $\mathcal{D}(A_h) = X = H^m(\Omega)$  and  $Y = \mathcal{L}^2(\Omega)$  then  $A_h$  is bounded and the mapping  $\mathcal{H} \ni h \mapsto A_h \in \mathcal{B}(X, Y)$  is continuous.

• Let  $X = Y = \mathcal{L}^2(\Omega)$  and let D be a closed subspace of  $H^m(\Omega)$  such that D is dense in  $\mathcal{L}^2(\Omega)$ , and the mapping  $A_h : D \to \mathcal{L}^2(\Omega)$  is one-to-one and onto for  $h \in \mathcal{H}$ . Then  $R_h = A_h^{-1} \in \mathcal{B}(Y, X)$  and the mapping  $\mathcal{H} \ni h \mapsto A_h \in C(X, Y)$  is continuous. This situation often occurs when considering strongly elliptic operators  $A_h$  with boundary operators independent of h,

(19) 
$$B_j = \sum_{|\alpha| \le m_j} b_{j\alpha}(x) D^{\alpha}, \quad 1 \le j \le m/2,$$

which cover  $A_h$  for each  $h \in \mathcal{H}$ . If additionally we know that  $\mathcal{D}(A_h^*) = \mathcal{D}^*$  is independent of h then  $R_k \circ A_h$  is closable for each h, k.

Now we show an example of a family  $(\widetilde{A}_t)_{t\in\mathcal{T}}$  of elliptic operators with pairwise different domains for which the corresponding family  $(\mathcal{D}_t)_{t\in\mathcal{T}}$  of domains is of class  $\mathcal{C}_a{}^k$  and the family of domains of the conjugate operators is independent of t.

Keep the notation of Section 2.1 and assume that a(x,t) = t. The sets  $\mathcal{D}_t$  given by (3) are dense linear subspaces of  $\mathcal{L}^2(\Omega)$  such that  $\mathcal{D}_t \neq \mathcal{D}_\tau$  for  $t \neq \tau \in [0,T]$  and  $\mathcal{D}_0 = \mathcal{D}$ , where  $\mathcal{D}$  is given by (4). The operator

(20) 
$$A = -\Delta + \lambda I$$

is well defined on  $H^2(\Omega)$ ; when considered as defined only on  $\mathcal{D}_t$ , it is closed, and for  $\lambda$  large enough, it is onto and one-to-one. By the closed graph theorem its inverse is bounded. Let  $A_t$  denote the operator given by (20) with domain  $\mathcal{D}_t$ .

EXAMPLE 2. The family

$$\widetilde{A}_t = A_0 \circ \Phi_t : \mathcal{D}_t \to \mathcal{L}^2(\Omega)$$

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parametrized by  $t \in [0, T]$  is a continuous (with respect to t) family of closed densely defined linear differential operators with pairwise different domains. Indeed, since  $(B_t = A_t \circ \Psi_t)_{t \in [0,T]}$  is a family of closed differential operators of order two with coefficients continuous with respect to both x and t, and with domains independent of t, the mapping  $[0,T] \ni t \mapsto B_t \in C(\mathcal{L}^2(\Omega))$ is continuous and, by Lemma 4, the mapping  $[0,T] \ni t \mapsto A_t = B_t \circ \Phi_t \in$  $C(\mathcal{L}^2(\Omega))$  is also continuous.

By Lemma 6, the domain  $\mathcal{D}(\widetilde{A}_t^*) = \mathcal{D}(A^*)$  is the same for all  $t \in [0, T]$ .

The next example show that in Theorem 7 the assumption of continuity of the mapping (16) cannot be replaced by the continuity of the family  $(A_h)_{h \in \mathcal{H}}$ .

EXAMPLE 3. Let  $(A_t)_{t\in[0,T]}$  be a family of self-adjoint operators with pairwise different domains, and with the same property for the family  $A_t^*$ . Since  $\mathcal{C}_0^{\infty}(\Omega) \subset \bigcap_{t\in[0,T]} \mathcal{D}_t, \mathcal{C}_0^{\infty}$  is dense in  $\mathcal{L}^2(\Omega), (R_{\tau} \circ A_t)u = (R_{\tau} \circ A_{\tau})u = u$  for  $u \in \mathcal{C}_0^{\infty}(\Omega)$  and  $(R_{\tau} \circ A_t)u \neq u$  for  $u \in D_t \setminus D_{\tau}$ , it follows that the operator  $R_{\tau} \circ A_t$  is not closable for  $t \neq \tau$ . Thus, the mapping (16) is even not well defined.

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