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## BUTLER GROUPS SPLITTING OVER A BASE ELEMENT

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**Abstract.** We characterize a particular kind of decomposition of a Butler group that is the general case for Butler B(1)-groups; and exhibit a decomposition of a B(2)-group which is not of that kind.

**Introduction.** All groups in the following are torsionfree Abelian of finite rank. A Butler B(n)-group G is a torsionfree Abelian group that is the sum of  $m \ge n$  rank 1 groups,  $G = \langle g_1 \rangle_* + \cdots + \langle g_m \rangle_*$  (where  $_*$  indicates pure closure), subject to n independent relations involving all of the m rank 1 groups. B(0) is the class of completely decomposable groups; in the following we suppose  $n \ge 1$ . B(1)-groups have been amply studied (for history, see [1]), using, as a basic equivalence, quasi-isomorphism [6] instead of isomorphism; this is also what we do in this paper; in fact, we will write isomorphic, indecomposable, direct decomposition,... instead of "quasi-isomorphic, strongly indecomposable, quasi-direct decomposition,...".

Direct decompositions of B(1)-groups were studied in [7], [3], and many other papers; when a B(1)-group G splits, it always has a decomposition  $G = G' \oplus G''$  such that all but one of the base elements  $g_1, \ldots, g_m$  belong either to G' or to G''; we call this a decomposition over a base element. This is not the case in general: in Section 2 we give a necessary and sufficient condition for a Butler B(n)-group to split over a base element. The condition consists of two parts, mirroring the double nature of Butler groups: an ordertheoretical one, which is the one that is necessary and sufficient in the B(1)case, and guarantees G = G' + G''; and an additional linear one, ensuring that  $G' \cap G'' = 0$ . In Section 3 we give two examples showing a decomposition of a B(2)-group that does not occur over a base element.

1. Notation and first remarks. Lower case Greek letters will denote rational numbers. We will use extensively the notation and tools developed in our previous papers on B(1)-groups (see in particular [2], [3]); we recall here some of them.

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By type we mean the isomorphism type of an additive subgroup of  $\mathbb{Q}$ .  $\mathbb{T}(\vee, \wedge)$  denotes the lattice of all types, with the added maximum  $\infty$  for the type of the 0 group; if w is an element of a group W,  $t_W(w)$  denotes the type of w in W.

Throughout,  $I = \{1, ..., m\}$ ; partitions of I are ordered by "bigger = coarser"; blocks of partitions are nonempty by definition.

If  $w_1, \ldots, w_m$  are elements of a group W and  $E \subseteq I$ , we define

$$w_E = \sum \{ w_i \mid i \in E \}, \quad \text{with} \quad w_{\emptyset} = 0,$$
$$W_E = \langle w_i \mid i \in E \rangle_* = \sum \{ \langle w_i \rangle_* \mid i \in E \} + \langle w_E \rangle_*$$

(the last equality is proved in [5]).

If  $W = \langle w_1 \rangle_* + \cdots + \langle w_m \rangle_*$ , and  $w = \beta_1 w_{C_1} + \cdots + \beta_h w_{C_h}$  with  $\beta_i \neq \beta_j$ if  $i \neq j$ , then  $\mathcal{C} = \{C_1, \ldots, C_h\}$  will be called a *partition of I into equal*coefficient blocks for w.

In our B(n)-group

$$G = \langle g_1 \rangle_* + \dots + \langle g_m \rangle_*$$

the elements  $g_1, \ldots, g_m$  are the base elements, and are fixed throughout; setting  $t_i = t_G(g_i)$  for all  $i \in I$ , the  $t_i$  are the base types of G;  $(t_1, \ldots, t_m)$  is the type-base of G.

It is not difficult to show (see also [5]) that there is no loss of generality in supposing that the relations are of the form

$$g_{I} = g_{1} + \dots + g_{m} = 0 \quad \text{(the first, or diagonal, relation)},$$
  

$$\alpha_{2,1}g_{A_{1}} + \dots + \alpha_{2,k}g_{A_{k}} = 0,$$
  

$$\alpha_{3,1}g_{A_{1}} + \dots + \alpha_{3,k}g_{A_{k}} = 0,$$
  

$$\vdots$$
  

$$\alpha_{n,1}g_{A_{1}} + \dots + \alpha_{n,k}g_{A_{k}} = 0,$$

where each  $A_j \subseteq I$  collects some indices of generators with equal coefficients, and moreover if  $j \neq j' = 1, ..., k$  there is at least one row r = 2, ..., n such that  $\alpha_{r,j} \neq \alpha_{r,j'}$ . Clearly,  $n \leq k \leq m$ . The ensuing partition

$$\mathcal{A} = \{A_1, \ldots, A_k\}$$

of *I* is the *basic partition* of (the given base of) *G*; its blocks  $A_j$  are called the *sections* of *G*. Note that if  $0 = \beta_1 g_{C_1} + \cdots + \beta_h g_{C_h}$  with  $\beta_i \neq \beta_j$  if  $i \neq j$ then  $\mathcal{C} = \{C_1, \ldots, C_h\} \geq \mathcal{A}$ . Replacing each nondiagonal relation with the difference

$$\alpha_{r,1}g_{A_1} + \dots + \alpha_{r,k}g_{A_k} - \alpha_{r,1}(g_1 + \dots + g_m) = 0$$

we may suppose that  $\alpha_{r,1} = 0$  for all  $r = 2, \ldots, n$ . Then the matrix

$$M = \begin{bmatrix} \alpha_{2,2} & \cdots & \alpha_{2,k} \\ \vdots & \ddots & \vdots \\ \alpha_{n,2} & \cdots & \alpha_{n,k} \end{bmatrix},$$

a reduced matrix of G, is of rank n-1.

**2.** Splitting over a base element. For completeness, let us first sketch the situation of a nontrivial splitting  $G = G' \oplus G''$  in which all of the base elements belong either to G' or to G''; the conditions will turn out to be only linear. Note that this is, in fact, the case when we consider the direct sum of a B(n')-group G' and a B(n'')-group G'', and choose for a base the union of the two bases and for the linear system the union of the two systems; in this case the B(n)-group G will be called *degenerate*.

Examining necessary conditions, setting  $E' = \{i \in I \mid g_i \in G'\}, E'' = \{i \in I \mid g_i \in G''\}$ , we have  $G' = G_{E'} (= \sum \{\langle g_i \rangle_* \mid i \in E\} + \langle g_E \rangle_*), G'' = G_{E''}$ . The diagonal relation  $g_I = g_{E'} + g_{E''} = 0$  provides a common element to the two summands, hence we have the two relations  $g_{E'} = -g_{E''} = 0$ ; in particular, this yields  $\{E', E''\} \ge A$ . Analogously, each nondiagonal relation in G yields two relations, one in  $G_{E'}$  and one in  $G_{E''}$ , therefore among the n relations thus obtained there will be r' independent ones in  $G_{E'}$ , and r'' in  $G_{E''}$ , with r' + r'' = n. Replacing the initial relations with these makes the matrix M block-diagonal, where the columns of one block are indexed by j's such that  $A_j \subseteq E'$ , and those of the other by j's such that  $A_j \subseteq E''$ . Conversely, if the matrix M of G is (equivalent to) a block-diagonal one, with E' resp. E'' gathering the indices of base elements involved in the first resp. second block, it is not difficult to prove that  $G = G_{E'} \oplus G_{E''}$ . Note that this situation cannot occur for B(1)-groups; for more about degenerate B(2)-groups see [4]. Thus we have

## PROPOSITION 2.1. A decomposition in which all base elements belong to some summand is possible if and only if the matrix is equivalent to a block-diagonal one, that is, if and only if the group is degenerate.

An interesting observation can be drawn from the above considerations. Recall that a B(1)-group G is decomposable [7] if and only if there exist a subset E of I and an index  $i \in I$  with  $i \notin E$  such that  $t_i \leq t_G(g_E)$ . Necessity derives from the following two facts:

I) If  $\operatorname{rk} G(t_i) = 1$  for all  $i \in I$ , then G is indecomposable. (The proof consists in noting that if G did decompose then each base element would have to belong to some summand, an impossibility, as noted above.) De-

composability then follows from the existence of elements of maximal type different from (not proportional to) base elements.

II) The maximal types of G are of the form  $t_G(g_E)$  for some  $E \subseteq I$ .

Neither of these two facts holds any more if G is a B(n)-group with  $n \ge 2$ : I) has been examined above, II) is shown to fail in Example 1. Therefore, while for  $n \ge 2$  a condition  $t_i \le t_G(g_E)$  may stand a chance among sufficient conditions, for necessary conditions we must look elsewhere.

Let now G split over a base element, that is,  $G = G' \oplus G''$ , and for some  $i' \in I$  and all  $i \in I$ ,  $i \neq i'$ ,  $g_i$  belongs either to G' or to G''. There is no loss of generality in supposing

$$i' = 1 \in A_1;$$

then for

$$E = \{ i \in I \mid g_i \in G' \}, \quad F = \{ i \in I \mid g_i \in G'' \}$$

we have  $I = \{1\} \cup E \cup F$ , a disjoint union.

Observe that in the above notation  $G_E \leq_* G'$  and  $G_F \leq_* G''$ ; the diagonal relation  $g_1 = -g_E - g_F$  yields  $(G_E + G_F)_* = G$ ; then for the splitting we need  $G_E = G'$  and  $G_F = G''$ ; that is,  $G_E + G_F = G$  and  $G_E \cap G_F = 0$ .

LEMMA 2.2. If  $I = \{1\} \cup E \cup F$  is a disjoint union, then  $t_1 = t_G(g_E) \land t_G(g_F)$  if and only if  $t_1 \leq t_G(g_E)$ .

*Proof.* One way is obvious; the other follows from the fact that, if  $t_1 = t_G(g_1) \leq t_G(g_E)$ , then  $t_1 \leq t_G(g_E + g_1) = t_G(g_F)$ ; but  $g_1 = -g_E - g_F$  implies  $t_1 \geq t_G(g_E) \wedge t_G(g_F)$ .

Clearly, a necessary condition for  $G = G_E \oplus G_F$  is  $t_1 \leq t_G(g_E)$ ; moreover from Lemma 2.2 we have

PROPOSITION 2.3. If  $I = \{1\} \cup E \cup F$  is a disjoint union, then  $t_1 \leq t_G(g_E)$  implies  $G = G_E + G_F$ .

*Proof.* By Lemma 2.2, we have  $t_1 = t_G(g_E) \wedge t_G(g_F)$ , hence  $\langle g_1 \rangle_*$  is contained in  $G_E + G_F$ , which then equals G.

Consider now the condition  $G_E \cap G_F = 0$ . It does not involve the diagonal relation; but if we set  $E_j = E \cap A_j$  and  $F_j = F \cap A_j$  for all  $j = 1, \ldots, k$ , then any other relation (with zero as the first coefficient)

$$\alpha_{r,2}g_{A_2} + \dots + \alpha_{r,k}g_{A_k} = 0$$

may yield a nonzero common element  $g = \alpha_{r,2}g_{E_2} + \cdots + \alpha_{r,k}g_{E_k} = -(\alpha_{r,2}g_{F_2} + \cdots + \alpha_{r,k}g_{F_k})$ , unless

(\*) either E or F is contained in  $A_1$ .

If (\*) holds, then  $G_E \cap G_F = 0$ : for if, say,  $E = E_1$ , a common element  $0 \neq \sum \{\beta_i g_i \mid i \in E_1\} = \sum \{\gamma_i g_i \mid i \in F\}$  would yield  $0 = \sum \{\beta_i g_i \mid i \in E_1\}$ 

 $-\sum \{\gamma_i g_i \mid i \in F\}$ , absurd since this element has a partition that is not  $\geq \mathcal{A}$  (it splits  $A_1$ ). Note that (\*) obviously always holds in a B(1)-group, where  $I = A_1$ .

If (\*) does not hold, the above element  $g \in G_E \cap G_F$  is certainly nonzero if there is a  $j \in \{2, \ldots, k\}$  such that both  $E_j$  and  $F_j$  are nonempty, for then g has a partition that is not  $\geq \mathcal{A}$ . Therefore a first necessary condition for  $G_E \cap G_F = 0$  is that, for every  $j = 2, \ldots, k$ , one of  $E_j$ ,  $F_j$  be empty; that is, each  $A_j$  with  $j \neq 1$  must be contained either in E or in F.

Let then without loss of generality  $A_2, \ldots, A_s \subseteq E, A_{s+1}, \ldots, A_k \subseteq F$ with  $2 \leq s \leq k$ . As above, each relation except the diagonal one provides an element  $a_r \in G_E \cap G_F$  with  $2 \leq r \leq n$ ,

$$a_r = \sum \{ \alpha_{r,j} g_{A_j} \mid 2 \le j \le s \} = \sum \{ \alpha_{r,j} g_{A_j} \mid s+1 \le j \le k \}.$$

To get  $G_E \cap G_F = 0$  we need  $a_r = 0$  for all r = 2, ..., n. At this point we can already draw a conclusion for n = 2: the unique second relation does not allow  $a_2 = 0$  for any choice of E and F, therefore (\*) is a necessary condition.

For n > 2 the conditions  $a_r = 0$  for all r = 2, ..., n yield a set of 2(n-1) relations, among which there will be n-1 independent ones; then the matrix M can be replaced by a block-diagonal matrix

$$M' = \begin{bmatrix} M(E) & 0\\ 0 & M(F) \end{bmatrix},$$

where (after possibly re-ordering rows) the columns of M(E) are indexed by j's such that  $A_j \subseteq E$ , and those of M(F) are indexed by j's such that  $A_j \subseteq F$ .

We can now reach a conclusion:

THEOREM 2.4. Let  $G = \langle g_1 \rangle_* + \cdots + \langle g_m \rangle_*$  be a B(n)-group. Then G splits over one of its base elements—without loss of generality over  $g_1$ —if and only if there is a partition  $\{\{1\}, E, F\}$  of I such that

(a)  $t_1 \leq t_G(g_E)$ ,

(b) one of the following two conditions holds:

(\*) one of E, F is contained in  $A_1$ ;

(\*\*) a reduced matrix of G is block-diagonal of the form

$$M = \begin{bmatrix} M(E) & 0\\ 0 & M(F) \end{bmatrix},$$

with the above notation.

In particular: if G is a B(1)-group, then (a) is also sufficient; if G is B(2), then G splits over  $t_1$  if and only if (a) and (\*) hold.

*Proof.* Necessity has been proved above. For sufficiency, note that Proposition 2.3(a) implies  $G = G_E + G_F$ . Now if (\*) holds, we proved above that  $G_E \cap G_F = 0$ . If (\*\*) holds, let  $g \in G_E \cap G_F$ ; then  $g = \sum \{\beta_i g_i \mid i \in E\} = \sum \{\beta_j g_j \mid j \in F\}$ , hence  $\sum \{\beta_i g_i \mid i \in E\} - \sum \{\beta_j g_j \mid j \in F\} = 0$ . This relation is then a linear combination of nondiagonal basic relations, which by (\*\*) separate into those indexed in E and those indexed in F. This in turn implies that each of the two terms is 0, that is, g = 0.

**3. Examples.** With our definitions, not all *m*-tuples of types are bases of B(n)-groups; "regularity" must be imposed [5], and all our examples are checked for it. We will use the notation of [2]–[5], where a type with all zeros but a finite number of infinities is denoted by replacing each infinity by its prime and each zero by a dot, while eliminating infinite tails of zeros [3]; e.g.

$$\sigma = 0.0 \propto \infty 0 \ldots$$
 zeros  $\ldots = \cdot \cdot 5.7 = \cdot \cdot p q$ .

EXAMPLE 1 (of a type which is maximal but not of the form  $t_G(g_E)$ ). Let  $m = 8, n = 2, k = 4, \mathcal{A} = \{\{1, 2\}, \{3, 4\}, \{5, 6\}, \{7, 8\}\}$ , with relations

 $g_1 + \dots + g_8 = 0, \quad g_{\{3,4\}} - 2g_{\{5,6\}} + g_{\{7,8\}} = 0.$ 

Let the base types be:

$A_1$	$t_1 = \cdots$
	$t_2 = \cdots$
$A_2$	$t_3 = p_1 \cdot p_3$
	$t_4 = p_1 p_2 \cdot$
$A_3$	$t_5 = p_1 \cdot p_3$
	$t_6 = \cdot p_2 p_3$
$A_4$	$t_7 = p_1 p_2 \cdot$
	$t_8 = \cdot p_2 p_3$

The element  $g = -2g_3 - 3g_4 + 4g_5 - 3g_7 = -g_4 - 4g_6 - g_7 + 2g_8 = g_3 - 2g_5 - 6g_6 + 3g_8$  (obtained by adding  $2(g_{\{3,4\}} - 2g_{\{5,6\}} + g_{\{7,8\}})$  resp.  $3(g_{\{3,4\}} - 2g_{\{5,6\}} + g_{\{7,8\}}))$  is clearly divisible by  $p_1$ ,  $p_2$  and  $p_3$ , hence has maximum type, while a computation shows that no element of the form  $g_E$  reaches the maximum type.

EXAMPLE 2 (showing that, in the above notation,  $t_1 \leq t_G(g_E)$  does not imply  $t_1 \leq t_G(g_{E_1})$ , which proves that condition (b) cannot be eliminated). Let m = 7, n = 2, with relations

$$g_1 + \dots + g_7 = 0,$$
  
$$\alpha_1 g_{\{1,2,3\}} + \alpha_2 g_4 + \alpha_3 g_5 + \alpha_4 g_6 + \alpha_5 g_7 = 0,$$

with pairwise different coefficients, thus  $\mathcal{A} = \{\{1, 2, 3\}, \{4\}, \{5\}, \{6\}, \{7\}\};$ let  $E = \{2, 4, 5\}$  (thus  $E_1 = \{2\}$ ),  $F = \{3, 6, 7\};$ 

	$t_1 = p q$
$A_1$	$t_2 = \cdot q$
	$t_3 = p \cdot$
$A_2$	$t_4 = \cdot q$
$A_3$	$t_5 = \cdot q$
$A_4$	$t_6 = p \cdot$
$A_5$	$t_7 = p \cdot$

Here  $t_1 = pq = t_G(g_E) > t_G(g_{E_1}) = t_2$ ; in fact we have  $0 \neq (\alpha_2 - \alpha_1)g_4 + (\alpha_3 - \alpha_1)g_5 = (\alpha_1 - \alpha_4)g_6 + (\alpha_1 - \alpha_5)g_7 \in G_{\{2,4,5\}} \cap G_{\{3,6,7\}}.$ 

We now give two examples of B(2)-group-splittings that do not occur over a single base element, showing that our study does not exhaust the decomposition problem.

EXAMPLE 3. Let n = 2,  $I = \{1, \dots, 8\}$ ,  $\mathcal{A} = \{A_1, A_2, A_3\} = \{\{1, 2, 3\}, \{4, 5\}, \{6, 7, 8\}\}$ ;  $E = \{3, 5, 7\}, F = \{2, 4, 6\}; E_j = E \cap A_j, F_j = F \cap A_j$  for j = 1, 2, 3; with the two relations  $g_I = 0, g_{A_1} + \alpha_2 g_{A_2} = 0$ , with  $\alpha_2 \neq 0, 1$ . Let

Here  $G = G' \oplus G''$ , where G' and G'' are B(2)-groups with relations  $g'_1 + g_E + g'_8 = 0 = g''_1 + g_F + g''_8$  (the diagonal relations) and  $g'_1 + g_{E_1} + \alpha_2 g_{E_2} = 0 = g''_1 + g_{F_1} + \alpha_2 g_{F_2}$  (the secondary relations). The relations ensure that the sum of the ranks of G' and G'' does not exceed the rank of G; we will have a direct sum if we show that the types  $t_1$  of  $g_1 = g'_1 + g''_1$  and  $t_8$  of  $g_8 = g'_8 + g''_8$  are fully recovered in  $G' \oplus G''$ . But this is the case because  $g'_1 = g_1 + g_2 + \alpha_2 g_4 = g'_1 - (g_{A_1} + \alpha_2 g_{A_2}) = -(g_3 + g_5)$  has the prime p'' in its first form and p' in its second form, thus completing  $t_1 = p'p''$ ; and analogously does g''. The same works for  $g'_8$  and  $g''_8$  with respect to q', q'' and  $t_8 = q'q''$ .

In order to see that G does not split over any of its base elements, it is enough to verify that no  $t_i$  is  $\leq t_E$  with E a subset of the section  $A_j$ containing i, with E disjoint from  $\{i\}$ . This is clear if E is a singleton. If not, then we are left with the sections  $A_1$  and  $A_3$ , whose situation is analogous. Starting with i = 1, we have  $t_1 = p'p''$ ; to get p' to divide the type of

$$g_E = g_{\{2,3\}} = g_{\{2,3\}} + \lambda g_I + \mu (g_{\{1,2,3\}} + \alpha_2 g_{\{4,5\}})$$
  
=  $(\lambda + \mu)g_1 + (\lambda + \mu + 1)g_{\{2,3\}} + (\lambda + \mu \alpha_2)g_{\{4,5\}} + \lambda g_{\{6,7,8\}}$ 

we must determine  $\lambda$ ,  $\mu$  in such a way as to eliminate  $g_2$ ,  $g_4$ ,  $g_6$ ,  $g_8$ , that is,

$$\lambda + \mu + 1 = \lambda + \mu \alpha_2 = \lambda = 0,$$

which is impossible. For i = 2 we have  $t_2 = p''q''$ ; for p'' to divide the type of

$$g_E = g_{\{1,3\}} = g_{\{1,3\}} + \lambda g_I + \mu (g_{\{1,2,3\}} + \alpha_2 g_{\{4,5\}})$$
  
=  $(\lambda + \mu)g_2 + (\lambda + \mu + 1)g_{\{1,3\}} + (\lambda + \mu \alpha_2)g_{\{4,5\}} + \lambda g_{\{6,7,8\}}$ 

we must determine  $\lambda$ ,  $\mu$  in such a way as to eliminate  $g_3$ ,  $g_5$ ,  $g_7$ ,  $g_8$ , which is impossible; the same happens for i = 3.

EXAMPLE 4. Let n = 2, m = k = 6,  $\mathcal{A} = \{\{1\}, \{2\}, \{3\}, \{4\}, \{5\}, \{6\}\};$  $E = \{2, 3\}, F = \{4, 5\}; E_j = E \cap A_j, F_j = F \cap A_j \text{ for } j = 1, \dots, 6;$  with the two relations  $g_I = 0$ ,  $\alpha_2 g_2 + \alpha_3 g_3 + \alpha_4 g_4 + \alpha_5 g_5 + \alpha_6 g_6 = 0$ , with coefficients nonzero and pairwise different.

Let

$$\begin{array}{ll} \begin{array}{c} \begin{array}{c} \begin{array}{c} \begin{array}{c} \begin{array}{c} A_1 & t_1 = p_1 \, q_1 \, \cdot \, \cdot \\ \hline A_2 & t_2 = p_1 \, \cdot \, p_6 \, \cdot \\ \hline A_3 & t_3 = p_1 \, \cdot \, p_6 \, \cdot \\ \hline A_4 & t_4 = \, \cdot \, q_1 \, \cdot \, q_6 \\ \hline \hline A_5 & t_5 = \, \cdot \, q_1 \, \cdot \, q_6 \\ \hline \hline A_6 & t_6 = \, \cdot \, \cdot \, p_6 \, q_6 \end{array} \end{array} \end{array} \begin{array}{c} \begin{array}{c} \begin{array}{c} \begin{array}{c} g_1' = \alpha_6^{-1} ((\alpha_2 - \alpha_6) g_2 + (\alpha_3 - \alpha_6) g_3), \\ g_1'' = \alpha_6^{-1} ((\alpha_4 - \alpha_6) g_4 + (\alpha_5 - \alpha_6) g_5), \\ g_6' = -\alpha_6^{-1} (\alpha_2 g_2 + \alpha_3 g_3), \\ g_6'' = -\alpha_6^{-1} (\alpha_4 g_4 + \alpha_5 g_5), \end{array} \end{array} \\ \begin{array}{c} \begin{array}{c} \begin{array}{c} g_1'' = \alpha_6^{-1} (\alpha_4 g_4 + \alpha_5 g_5), \\ g_6'' = -\alpha_6^{-1} (\alpha_4 g_4 + \alpha_5 g_5), \end{array} \end{array} \end{array} \end{array} \\ \begin{array}{c} \begin{array}{c} \begin{array}{c} \end{array} \end{array} \end{array} \\ \begin{array}{c} \begin{array}{c} \end{array} \end{array} \end{array} \end{array} \begin{array}{c} \begin{array}{c} \end{array} \end{array} \\ \begin{array}{c} \end{array} \end{array}$$

We have  $\alpha_6 g'_1 = (\alpha_2 - \alpha_6)g_2 + (\alpha_3 - \alpha_6)g_3 = -\alpha_6(g_2 + g_3 + g_6) = -\alpha_6(g_1 + g_4 + g_5)$ , hence  $t_G(g'_1) \ge p_1q_1p_6$ ; analogously,  $t_G(g''_1) \ge p_1q_1q_6$ ;  $t_G(g''_6) \ge p_1p_6q_6$ ;  $t_G(g''_6) \ge q_1p_6q_6$ . We thus recover the types of  $g_1 = g'_1 + g''_1$  and of  $g_6 = g'_6 + g''_6$ , hence G' + G'' = G. Now, G' and G'' are B(2)-groups with relations  $g'_1 + g_E + g'_6 = 0 = g''_1 + g_F + g''_6$  (the diagonal relations) and  $\alpha_6g'_1 - (\alpha_2 - \alpha_6)g_{E_2} - (\alpha_3 - \alpha_6)g_{E_3} = 0 = \alpha_6g''_1 - (\alpha_4 - \alpha_6)g_{F_4} - (\alpha_5 - \alpha_6)g_{F_5}$  (the secondary relations). The relations ensure that the sum of the ranks of G' and G'' does not exceed the rank of G, hence the splitting is proved.

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