# Littlewood-Paley $g$-functions with rough kernels on homogeneous groups 

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#### Abstract

Let $\mathbb{G}$ be a homogeneous group on $\mathbb{R}^{n}$ whose multiplication and inverse operations are polynomial maps. In 1999, T. Tao proved that the singular integral operator with $L \log ^{+} L$ function kernel on $\mathbb{G}$ is both of type $(p, p)$ and of weak type $(1,1)$. In this paper, the same results are proved for the Littlewood-Paley $g$-functions on $\mathbb{G}$.


1. Introduction. Let $\Omega$ be a function defined on the Euclidean unit sphere $S^{n-1}$ in $\mathbb{R}^{n}(n \geq 2)$ and satisfying the cancellation condition

$$
\begin{equation*}
\int_{S^{n-1}} \Omega(\theta) d \theta=0 \tag{1.1}
\end{equation*}
$$

Denote by $T_{\Omega}$ the singular integral operator defined by

$$
T_{\Omega} f(x)=\text { p.v. } \int_{\mathbb{R}^{n}} \frac{\Omega(y /|y|)}{|y|^{n}} f(x-y) d y
$$

for $f$ in the Schwartz class $\mathcal{S}\left(\mathbb{R}^{n}\right)$. These operators, known as CalderónZygmund singular integral operators, were first studied by Calderón and Zygmund in their famous article [CZ1]. They proved $L^{p}$ boundedness of $T_{\Omega}$ when the kernels are regular. Later in 1960, Hörmander [Hor] showed that the same results hold when the kernel only satisfies a weaker condition which is referred to as Hörmander's condition today.

An important and interesting question is whether the regularity conditions on the convolution kernels are necessary for the $L^{p}(1<p<\infty)$ boundedness of the Calderón-Zygmund singular integral operators. In 1956, Calderón and Zygmund [CZ2] gave a negative answer. Using the method of rotations, Calderón and Zygmund proved that $T_{\Omega}$ is still bounded on $L^{p}$ for $1<p<\infty$ when $\Omega$ is odd in $L^{1}\left(S^{n-1}\right)$, or even in $L \log ^{+} L\left(S^{n-1}\right)$ satisfy-

[^0]ing (1.1). In 1988, Hofmann [Hof] proved that the rough singular integral operator $T_{\Omega}$ is of weak type $(1,1)$ in $\mathbb{R}^{2}$ for $\Omega \in L^{q}\left(S^{1}\right), q>1$. In an unpublished work, M. Christ obtained a weak type (1,1) inequality for $T_{\Omega}$ for $\Omega \in L \log ^{+} L\left(S^{n-1}\right)$ in dimension $n \leq 7$. In 1996, Seeger [Se] showed that $T_{\Omega}$ is of weak type $(1,1)$ if $\Omega \in L \log ^{+} L\left(S^{n-1}\right)$ with the mean zero condition (1.1) for all dimensions $n \geq 2$. In [GS], Grafakos and Stefanov gave a nice survey, which contains a thorough discussion of the history of the operator $T_{\Omega}$.

It is well known that a homogeneous group $\mathbb{G}$ is a Lie group equipped with multiplication, inverse, dilation, and norm structures

$$
\begin{equation*}
(x, y) \mapsto x y, \quad x \mapsto x^{-1}, \quad(t, x) \mapsto t \circ x, \quad x \mapsto \rho(x) \tag{1.2}
\end{equation*}
$$

for $x, y \in \mathbb{G}$ and $t>0$. Here the multiplication and inverse operations are polynomial maps, while the dilation structure preserves the group operations and is given in coordinates by

$$
\begin{equation*}
t \circ\left(x_{1}, \ldots, x_{n}\right)=\left(t^{\alpha_{1}} x_{1}, \ldots, t^{\alpha_{n}} x_{n}\right) \tag{1.3}
\end{equation*}
$$

for some constants $0<\alpha_{1} \leq \cdots \leq \alpha_{n}$ and satisfies $\rho(t \circ x)=t \rho(x)$. It can be shown that Lebesgue measure $d x$ is a Haar measure on $\mathbb{G}$ and that $\rho(x) \sim$ $\rho\left(x^{-1}\right)$. We call $n$ the Euclidean dimension of $\mathbb{G}$, and $N=\alpha_{1}+\cdots+\alpha_{n}$ the homogeneous dimension of $\mathbb{G}$. Denote by $\Sigma=\{x \in \mathbb{G}: \rho(x)=1\}$ the "unit sphere" of $\mathbb{G}$.

When $\Omega$ satisfies a much stronger smoothness condition, $T_{\Omega}$ is a bounded operator on $L^{p}(\mathbb{G})$ for $1<p<\infty$ (see [St2]). By analyzing the results on rough singular integral operators $T_{\Omega}$ mentioned above, it is natural to conjecture that analogous results also hold on the homogeneous group $\mathbb{G}$. However, there exist many difficulties in this generalization. In fact, the method based on Fourier transform estimates is not available on the general homogeneous group $\mathbb{G}$, and this method plays a key role in studying the $L^{2}$ and weak $(1,1)$ boundedness for the rough operator $T_{\Omega}$ on $\mathbb{R}^{n}$. In 1999, using a variant of Littlewood-Paley theory and an iterated $T T^{*}$ method, Tao $[\mathrm{T}]$ generalized the results in $[\mathrm{CZ} 2]$ and $[\mathrm{Se}]$ to the homogeneous group $\mathbb{G}$. To be precise, Tao proved the weak type $(1,1)$ and $(2,2)$ boundedness of $T$ with kernels belonging to the class $L \log ^{+} L$ on $\mathbb{G}$, and hence the $(p, p)$ boundedness of $T$ for $1<p<\infty$ follows easily by interpolation and duality. Tao's work in $[\mathrm{T}]$ is very significant because the ideas presented there pave the way to the theory of rough operators on general homogeneous groups.

On the other hand, it is well known that the Littlewood-Paley operators play an important role in harmonic analysis on $\mathbb{R}^{n}$, PDE, characterizing function spaces, etc. The Littlewood-Paley operators in high dimensions were first introduced by Stein in [St1]. If $\Omega \in L^{1}\left(S^{n-1}\right)$ satisfies (1.1), set $\varphi(x)=\Omega(x /|x|)|x|^{-n+1} \chi_{\{|x| \leq 1\}}(x)$ and $\varphi_{t}(x)=t^{-n} \varphi(x / t)$ for $t>0$. Then
the Littlewood-Paley $g$-function $g_{\Omega}$ with homogeneous kernel is defined by

$$
g_{\Omega}(f)(x)=\left(\int_{0}^{\infty}\left|\varphi_{t} * f(x)\right|^{2} \frac{d t}{t}\right)^{1 / 2} .
$$

In [St1], Stein proved that if $\Omega \in \operatorname{Lip}_{\alpha}\left(S^{n-1}\right), 0<\alpha \leq 1$, then $g_{\Omega}$ is of weak type ( 1,1 ) and of type ( $p, p$ ) for $1<p \leq 2$. In 1962, Benedek, Calderón and Panzone [BCP] showed if $\Omega \in C^{1}\left(S^{n-1}\right)$, then $g_{\Omega}$ is of type $(p, p)$ for $1<$ $p<\infty$. In 2000, Ding, Fan and Pan [DFP2] proved that if $\Omega \in H^{1}\left(S^{n-1}\right)$, the Hardy space on $S^{n-1}$ (see [Con] or [RW] for the definition), then $g_{\Omega}$ is still of type ( $p, p$ ) for $1<p<\infty$. In 2001, Fan and Sato [FaSa] established the weak $(1,1)$ boundedness of $g_{\Omega}$ if $\Omega \in L \log ^{+} L\left(S^{n-1}\right)$. The results in [DFP2] and [FaSa] show that the regularity condition imposed on $\Omega$ is not necessary for the $L^{p}(1<p<\infty)$ and weak $(1,1)$ boundedness of $g_{\Omega}$. See also [DFP1] and [AACP] for more results about the rough Littlewood-Paley $g$-function on $\mathbb{R}^{n}$.

Inspired by Tao's pioneering work, in this paper, we will discuss some mapping properties of the Littlewood-Paley $g$-functions with rough kernels on the homogeneous group $\mathbb{G}$.

Suppose that a function $\Omega$ defined on $\mathbb{G}$ satisfies the following conditions:

$$
\begin{align*}
\Omega(t \circ x)= & \Omega(x) \quad \text { for } t>0 \text { and } x \in \mathbb{G},  \tag{1.4}\\
& \int_{\Sigma} \Omega(x) d \sigma(x)=0, \tag{1.5}
\end{align*}
$$

and $\Omega \in L^{1}(\Sigma)$, that is,

$$
\begin{equation*}
\int_{\Sigma}|\Omega(x)| d \sigma(x)<\infty, \tag{1.6}
\end{equation*}
$$

where $\sigma$ is a Radon measure on $\Sigma$ (see [FoSt, p. 14]). The Littlewood-Paley $g$-function on $\mathbb{G}$ is defined by

$$
g_{\Omega} f(x)=\left(\int_{0}^{\infty}\left|f * \kappa_{t}\right|^{2} \frac{d t}{t}\right)^{1 / 2}
$$

where $\kappa_{t}(x)=t^{-1} \Omega(x) \rho(x)^{1-N} \chi_{\{\rho(x) \leq t\}}(x)(t>0, x \in \mathbb{G})$ and $\Omega$ satisfies the conditions (1.4)-(1.6).

In this paper, we will prove the weak type $(1,1)$ and $(p, p)$ boundedness of the Littlewood-Paley $g$-function on the homogeneous group $\mathbb{G}$ if the size condition (1.6) is replaced by the following $L \log ^{+} L(\Sigma)$ condition:

$$
\begin{equation*}
\int_{\Sigma}|\Omega(x) \log (2+\Omega(x))| d \sigma(x)<\infty . \tag{1.7}
\end{equation*}
$$

Our main results are as follows.

ThEOREM 1.1. If $\Omega \in L \log ^{+} L(\Sigma)$ satisfies (1.4) and (1.5), then $g_{\Omega}$ is bounded on $L^{2}(\mathbb{G})$.

Theorem 1.2. If $\Omega \in L \log ^{+} L(\Sigma)$ and $g_{\Omega}$ is bounded on $L^{2}(\mathbb{G})$, then $g_{\Omega}$ is of weak type $(1,1)$ on $\mathbb{G}$.

By an interpolation theorem, we get
Corollary 1.3. Suppose $\Omega \in L \log ^{+} L(\Sigma)$ satisfies (1.4) and (1.5). Then $g_{\Omega}$ is bounded on $L^{p}(\mathbb{G})$ for $1<p \leq 2$ and is of weak type $(1,1)$ on $\mathbb{G}$.

The basic idea of proving our theorems is to view the Littlewood-Paley $g$-function as a vector-valued singular integral (see Section 2). It should be pointed out that some ideas used in this work are borrowed from Tao's paper [ T$]$. However, the extra integral in $t$ causes some essential difficulties so that we do not use the method in $[\mathrm{T}]$ directly in many estimates. Here, we point out three major differences:
(1) The singular integral operator $T$ and its adjoint operator $T^{*}$ are essentially the same. Hence, the properties of $T$ can be translated to $T^{*}$. However, the Littlewood-Paley $g$-function $g_{\Omega}$ and its adjoint $g_{\Omega}^{*}$ are essentially different, since $g_{\Omega}$ maps a scalar-valued function to a Hilbert-valued function and its adjoint operator $g_{\Omega}^{*}$ is a mapping from a Hilbert-valued function space to a scalar-valued function space.
(2) In the proof of Theorem 1.1, we view the Littlewood-Paley $g$-function as a vector-valued singular integral. However, in estimating the nondegenerate portion of the integral, there are some additional difficulties caused by the extra $t$ integral coming from vector-valued duality (see Remark 4.4 at the end of Section 4).

To avoid this problem, we iterate $T m+1$ times instead of $m$ times, and then "throw out" the extra $t$ integral to reduce the estimate for a vectorvalued integral to a scalar-valued one.

In the weak $(1,1)$ case, we shall iterate $T m+2$ times for symmetry considerations. Also more careful estimates are required for the reduction (see Section 7).
(3) In the proof of weak type $(1,1)$ boundedness, we are led to estimate the derivatives of homogeneous norms. We show that any homogeneous norm on the homogeneous group satisfies certain regularity conditions (see Theorem 7.1). Then we get the desired estimates by using left-invariant differentiation structures developed by Tao (see Lemma 7.2).

Remark 1.4. In 1960, Hörmander [Hor] proved the $L^{p}$ boundedness of a parameterized Littlewood-Paley $g$-function. Using our argument, one can prove results similar to ours for the parameterized Littlewood-Paley
$g$-function $g_{\Omega, \nu}$ defined by

$$
g_{\Omega, \nu} f(x)=\left(\int_{0}^{\infty}\left|f * \kappa_{t}^{\nu}\right|^{2} \frac{d t}{t}\right)^{1 / 2}
$$

where $\kappa_{t}^{\nu}(x)=t^{-\nu} \Omega(x) \rho(x)^{\nu-N} \chi_{\{\rho(x) \leq t\}}(x)$ for $t, \nu>0$ and $x \in \mathbb{G}$, and $\Omega$ satisfies the conditions (1.4)-(1.6).

Throughout this paper, we will work exclusively with real-valued functions. The letters $C$ (resp. $c, \varepsilon$ ) will always be used to denote large (resp. small) positive constants only depending on the homogeneous group $\mathbb{G}$ and any other specified quantities. The values of these constants are not necessarily the same at each occurrence. We use $A \lesssim B$ to denote $A \leq C B$, and we write $A \sim B$ if $A \lesssim B \lesssim A$.
2. $L^{2}$ estimate I : Kernel truncation and frequency localization. Let $K(x)=\Omega(x) \rho(x)^{-N}$ and $h_{t}(x)=t^{-1} \rho(x) \chi_{\{\rho(x) \leq t\}}(x)$. Set $K_{0}:=$ $K \chi_{A_{0}}$ with $A_{0}=\{x \in \mathbb{G}: 1 \leq \rho(x) \leq 2\}$. Then we may normalize $\left\|K_{0}\right\|_{L \log ^{+} L(\mathbb{G})}=1$ since $\Omega \in L \log ^{+} L(\Sigma)$. Let $\mathcal{H}$ be the Hilbert space $L^{2}\left(\mathbb{R}_{+}, d t / t\right)$ with the norm and inner product denoted by $|\cdot|_{\mathcal{H}}$ and $\langle\cdot, \cdot\rangle_{\mathcal{H}}$, respectively. Thus, the Littlewood-Paley $g$-function $g_{\Omega}$ can be written as

$$
\begin{equation*}
g_{\Omega}(f)(x)=\left(\int_{0}^{\infty}\left|f *\left(h_{t} K\right)(x)\right|^{2} \frac{d t}{t}\right)^{1 / 2}=\left|f *\left(h_{(\cdot)} K\right)(x)\right|_{\mathcal{H}} \tag{2.1}
\end{equation*}
$$

For each $u>0$, define the scaling map $\Delta[u]$ by $\Delta[u] f(y)=u^{-N} f\left(u^{-1} \circ y\right)$. Then we have the identity

$$
\begin{equation*}
K(x)=\frac{1}{\log 2} \int_{0}^{\infty} \Delta[u] K_{0}(x) d u \tag{2.2}
\end{equation*}
$$

Take a nonnegative function $\varphi \in C_{0}^{\infty}(\mathbb{R}) \operatorname{such}$ that $\operatorname{supp}(\varphi) \subset(1 / 4,4)$, $\varphi(u) \equiv 1$ for $1 / 2 \leq u \leq 2$ and $\sum_{j \in \mathbb{Z}} 2^{-j} \varphi\left(2^{-j} u\right)=1 / \log 2$. For $j \in \mathbb{Z}$, define an operator $S_{j}$ by

$$
S_{j} F(x)=2^{-j} \int_{0}^{\infty} \varphi\left(2^{-j} u\right) \Delta[u] F(x) d u
$$

Then by (2.2), we have a dyadic decomposition $K=\sum_{j \in \mathbb{Z}} S_{j} K_{0}$. It is easy to see that

$$
\begin{equation*}
\left\|S_{j} f\right\|_{L^{1}(\mathbb{G})} \lesssim\|f\|_{L^{1}(\mathbb{G})} \quad \text { uniformly in } j \tag{2.3}
\end{equation*}
$$

and

$$
\begin{equation*}
\left|h_{(\cdot)}(x)\right|_{\mathcal{H}} \lesssim 1 \quad \text { uniformly in } x \in \mathbb{G} . \tag{2.4}
\end{equation*}
$$

We now define the $\mathcal{H}$-valued $L^{q}$ spaces. For $1 \leq q<\infty$, let

$$
L^{q}(\mathcal{H})=\left\{f(x, t):\|f\|_{L^{q}(\mathcal{H})}:=\left\{\int_{\mathbb{G}}\left(\int_{0}^{\infty}|f(x, t)|^{2} \frac{d t}{t}\right)^{q / 2} d x\right\}^{1 / q}<\infty\right\}
$$

In view of Minkowski's inequality and the classical Young inequality, the following version of Young's inequality on $L^{q}(\mathcal{H})$ is obvious.

Lemma 2.1. Suppose $1 \leq p, q, r \leq \infty, 1 / p+1 / q=1+1 / r, f \in L^{q}(\mathcal{H})$ and $g \in L^{p}(\mathbb{G})$. Then

$$
\|f * g\|_{L^{r}(\mathcal{H})} \leq C\|g\|_{L^{p}(\mathbb{G})}\|f\|_{L^{q}(\mathcal{H})} .
$$

With the above notations, by (2.3) and (2.4) we have

$$
\begin{equation*}
\left\|h_{t} S_{j} f\right\|_{L^{1}(\mathcal{H})} \lesssim\|f\|_{L^{1}(\mathbb{G})} \quad \text { uniformly in } j \tag{2.5}
\end{equation*}
$$

To prove Theorem 1.1, by (2.1), it suffices to show that

$$
\begin{equation*}
\left\|f * \sum_{j}\left(h_{t} S_{j} K_{0}\right)\right\|_{L^{2}(\mathcal{H})} \lesssim\|f\|_{L^{2}(\mathbb{G})} . \tag{2.6}
\end{equation*}
$$

For $s \geq 0$, define

$$
A_{0}^{s}=\left\{x \in A_{0}: 2^{2^{s}} \leq 2+\left|K_{0}(x)\right|<2^{2^{s+1}}\right\}
$$

and $k_{0}^{s}=K_{0} \chi_{A_{0}^{s}}$. Let

$$
K_{0}^{s}=k_{0}^{s}-\frac{\chi A_{0}}{\left|A_{0}\right|} \int_{A_{0}} k_{0}^{s}(x) d x
$$

Then $K_{0}=\sum_{s \geq 0} K_{0}^{s}$ and each $K_{0}^{s}$ has mean zero. Note that

$$
\sum_{s \geq 0} 2^{s}\left\|K_{0}^{s}\right\|_{L^{1}(\mathbb{G})} \lesssim \sum_{s \geq 0} 2^{s}\left\|k_{0}^{s}\right\|_{L^{1}(\mathbb{G})} \lesssim\left\|K_{0}\right\|_{L \log ^{+} L(\mathbb{G})}=1
$$

Thus, (2.6) will follow if we can show that for some $\varepsilon>0$ and all $s \geq 0$,

$$
\begin{equation*}
\left\|f * \sum_{j}\left(h_{t} S_{j} K_{0}^{s}\right)\right\|_{L^{2}(\mathcal{H})} \lesssim\|f\|_{L^{2}(\mathbb{G})}\left(2^{s}\left\|K_{0}^{s}\right\|_{L^{1}(\mathbb{G})}+2^{s} 2^{-\varepsilon 2^{s}}\right) . \tag{2.7}
\end{equation*}
$$

Now we fix $s$. For each integer $k$, let $T_{k}$ denote the operator

$$
T_{k} f=f * \sum_{j=k 2^{s}}^{(k+1) 2^{s}-1}\left(h_{t} S_{j} K_{0}^{s}\right)
$$

To get (2.7), it is sufficient to show the following operator norm estimate:

$$
\begin{equation*}
\left\|\sum_{k} T_{k}\right\|_{L^{2}(\mathbb{G}) \rightarrow L^{2}(\mathcal{H})} \lesssim 2^{s}\left\|K_{0}^{s}\right\|_{L^{1}(\mathbb{G})}+2^{s} 2^{-\varepsilon 2^{s}} \tag{2.8}
\end{equation*}
$$

By Lemma 2.1 and (2.5), we have

$$
\left\|T_{k} f\right\|_{L^{2}(\mathcal{H})} \lesssim\|f\|_{L^{2}(\mathbb{G})} 2^{s}\left\|K_{0}^{s}\right\|_{L^{1}(\mathbb{G})} \quad \text { uniformly in } k .
$$

Hence, $T_{k}$ is a bounded operator from $L^{2}(\mathbb{G})$ to $L^{2}(\mathcal{H})$. Then the adjoint operator $T_{k}^{*}$ of $T_{k}$, defined by

$$
T_{k}^{*} g_{t}(x)=\sum_{j=k 2^{s}}^{(k+1) 2^{s}-1} \int_{0}^{\infty} g_{t} *\left(h_{t} S_{j} \tilde{K}_{0}^{s}\right)(x) \frac{d t}{t},
$$

is bounded from $L^{2}(\mathcal{H})$ to $L^{2}(\mathbb{G})$ with the same operator norm as $T_{k}$, where $\tilde{K}_{0}^{s}(x)=K_{0}^{s}\left(x^{-1}\right)$ for each $x \in \mathbb{G}$. Thus for all $k, k^{\prime}$, we have

$$
\max \left\{\left\|T_{k} T_{k^{\prime}}^{*}\right\|_{L^{2}(\mathcal{H}) \rightarrow L^{2}(\mathcal{H})},\left\|T_{k}^{*} T_{k^{\prime}}\right\|_{L^{2}(\mathbb{G}) \rightarrow L^{2}(\mathbb{G})}\right\} \lesssim\left(2^{s}\left\|K_{0}^{s}\right\|_{L^{1}(\mathbb{G})}\right)^{2} .
$$

Therefore, by the Cotlar-Stein lemma (see [St2]), to obtain the estimate (2.8), it suffices to show that there exists a large constant $C$ such that when $\left|k-k^{\prime}\right| \geq C$,

$$
\begin{equation*}
\max \left\{\left\|T_{k^{\prime}} T_{k}^{*}\right\|_{L^{2}(\mathcal{H}) \rightarrow L^{2}(\mathcal{H})},\left\|T_{k^{\prime}}^{*} T_{k}\right\|_{L^{2}(\mathbb{G}) \rightarrow L^{2}(\mathbb{G})}\right\} \lesssim 2^{2 s} 2^{-\varepsilon 2^{s}\left|k-k^{\prime}\right|} . \tag{2.9}
\end{equation*}
$$

By the definitions of $T_{k^{\prime}}$ and $T_{k}^{*}$, we need to prove that

$$
\begin{aligned}
& \left\|\sum_{j=k 2^{s}}^{(k+1) 2^{s}-1} \sum_{j^{\prime}=k^{\prime} 2^{s}}^{\left(k^{\prime}+1\right) 2^{s}-1} \int_{0}^{\infty} g_{t_{1}} *\left(h_{t_{1}} S_{j} \tilde{K}_{0}^{s}\right) *\left(h_{t_{2}} S_{j^{\prime}} K_{0}^{s}\right) \frac{d t_{1}}{t_{1}}\right\|_{L^{2}(\mathcal{H})} \\
& \lesssim 2^{2 s} 2^{-\varepsilon 2^{s}\left|k-k^{\prime}\right|}\left\|g_{t_{1}}\right\|_{L^{2}(\mathcal{H})} \\
& \begin{array}{c}
\sum_{j=k 2^{s}}^{(k+1) 2^{s}-1} \sum_{j^{\prime}=k^{\prime} 2^{s}}^{\left(k^{\prime}+1\right) 2^{s}-1} \int_{0}^{\infty} f *\left(h_{t} S_{j} K_{0}^{s}\right) *\left(h_{t} S_{j^{\prime}} \tilde{K}_{0}^{s}\right) \frac{d t}{t} \|_{L^{2}(\mathbb{G})} \\
\lesssim 2^{2 s} 2^{-\varepsilon 2^{s}\left|k-k^{\prime}\right|}\|f\|_{L^{2}(\mathbb{G})}
\end{array}
\end{aligned}
$$

By the triangle inequality, it suffices to show that for all integers $j, j^{\prime}$ with $\left|j-j^{\prime}\right|>C 2^{s}$,

$$
\begin{align*}
& \| \int_{0}^{\infty} g_{t_{1}} *\left(h_{t_{1}} S_{j} \tilde{K}_{0}^{s}\right) *\left(h_{t_{2}} S_{j^{\prime}} K_{0}^{s}\right) \frac{d t_{1}}{t_{1}} \|_{L^{2}(\mathcal{H})}  \tag{2.10}\\
& \lesssim 2^{-\varepsilon\left|j-j^{\prime}\right|}\left\|g_{t_{1}}\right\|_{L^{2}(\mathcal{H})} \\
&\left\|\int_{0}^{\infty} f *\left(h_{t} S_{j} K_{0}^{s}\right) *\left(h_{t} S_{j^{\prime}} \tilde{K}_{0}^{s}\right) \frac{d t}{t}\right\|_{L^{2}(\mathbb{G})}
\end{align*} \lesssim 2^{-\varepsilon\left|j-j^{\prime}\right|}\|f\|_{L^{2}(\mathbb{G})} .
$$

Now we use the Littlewood-Paley theory to show (2.10) and (2.11). Take a $C^{\infty}$ function $\phi$ supported on the unit ball with $\|\phi\|_{C^{1}} \lesssim 1$ and $\int \phi=1$. We may also assume that $\phi=\widetilde{\phi}$, where $\widetilde{\phi}(x)=\phi\left(x^{-1}\right)$ for $x \in \mathbb{G}$. For each integer $k$, write

$$
\psi_{k}=\Delta\left[2^{k-1}\right] \phi-\Delta\left[2^{k}\right] \phi .
$$

Note that $\psi_{k}$ is supported on the annulus of radius $C 2^{k}$, that is, on the set $\left\{x \in \mathbb{G}: C 2^{k-1} \leq \rho(x) \leq C 2^{k+1}\right\}$ for some absolute constant $C$. Moreover,
$\psi_{k}$ has mean zero and $\widetilde{\psi}_{k}=\psi_{k}$. Since

$$
\sum_{k} \psi_{k} * f(x)=f(x)=\sum_{k} f * \psi_{k}(x)
$$

for $x \neq 0$, we may write

$$
\begin{equation*}
f *\left(h_{t} S_{j} K_{0}^{s}\right) *\left(h_{t} S_{j^{\prime}} \tilde{K}_{0}^{s}\right)=\sum_{k} \sum_{k^{\prime}} f *\left(h_{t} S_{j} K_{0}^{s}\right) * \psi_{k} * \psi_{k^{\prime}} *\left(h_{t} S_{j^{\prime}} \tilde{K}_{0}^{s}\right) . \tag{2.12}
\end{equation*}
$$

We need the following lemma to prove (2.10) and (2.11).
Lemma 2.2. For any integers $j, k$ and any $L^{\infty}(\mathbb{G})$ function $K_{0}$ on the unit annulus with mean zero, we have

$$
\begin{equation*}
\left\|f *\left(h_{t} S_{j} K_{0}\right) * \psi_{k}\right\|_{L^{2}(\mathcal{H})} \lesssim 2^{-\varepsilon|j-k|}\|f\|_{L^{2}(\mathbb{G})}\left\|K_{0}\right\|_{L^{\infty}(\mathbb{G})} \tag{2.13}
\end{equation*}
$$

and

$$
\begin{equation*}
\left\|f * \psi_{k} *\left(h_{t} S_{j} K_{0}\right)\right\|_{L^{2}(\mathcal{H})} \lesssim 2^{-\varepsilon|j-k|}\|f\|_{L^{2}(\mathbb{G})}\left\|K_{0}\right\|_{L^{\infty}(\mathbb{G})} . \tag{2.14}
\end{equation*}
$$

The proof of Lemma 2.2 will be postponed until the next section. Now let us complete the proof of (2.10) and (2.11) by applying Lemma 2.2. In fact, by (2.13), we have

$$
\begin{equation*}
\left\|f *\left(h_{t} S_{j} K_{0}^{s}\right) * \psi_{k}\right\|_{L^{2}(\mathcal{H})} \lesssim 2^{2^{s+1}} 2^{-\varepsilon|j-k|}\|f\|_{L^{2}(\mathbb{G})} \tag{2.15}
\end{equation*}
$$

and (by duality)

$$
\begin{equation*}
\left\|\int_{0}^{\infty} g_{t} * \psi_{k^{\prime}} *\left(h_{t} S_{j^{\prime}} \tilde{K}_{0}^{s}\right) \frac{d t}{t}\right\|_{L^{2}(\mathbb{G})} \lesssim 2^{2^{s+1}} 2^{-\varepsilon\left|k^{\prime}-j^{\prime}\right|}\left\|g_{t}\right\|_{L^{2}(\mathcal{H})} . \tag{2.16}
\end{equation*}
$$

Using the estimates (2.15) and (2.16), we get

$$
\begin{align*}
\| \int_{0}^{\infty} f *\left(h_{t} S_{j} K_{0}^{s}\right) * \psi_{k} * \psi_{k^{\prime}} * & \left(h_{t} S_{j^{\prime}} \tilde{K}_{0}^{s}\right) \frac{d t}{t} \|_{L^{2}(\mathbb{G})}  \tag{2.17}\\
& \lesssim 2^{2^{s+2}} 2^{-\varepsilon|j-k|} 2^{-\varepsilon\left|k^{\prime}-j^{\prime}\right|}\|f\|_{L^{2}(\mathbb{G})} .
\end{align*}
$$

Similarly, it follows from (2.14) that

$$
\begin{align*}
\| & \int_{0}^{\infty} f_{t_{1}} *\left(h_{t_{1}} S_{j} \tilde{K}_{0}^{s}\right) * \psi_{k} * \psi_{k^{\prime}} *\left(h_{t_{2}} S_{j^{\prime}} K_{0}^{s}\right) \frac{d t_{1}}{t_{1}} \|_{L^{2}(\mathcal{H})}  \tag{2.18}\\
& \lesssim 2^{2^{s+2}} 2^{-\varepsilon|j-k|} 2^{-\varepsilon\left|k^{\prime}-j^{\prime}\right|}\left\|f_{t_{1}}\right\|_{L^{2}(\mathcal{H})}
\end{align*}
$$

On the other hand, from the smoothness and mean zero conditions on $\psi_{k}, \psi_{k^{\prime}}$, we have

$$
\begin{equation*}
\left\|\psi_{k} * \psi_{k^{\prime}}\right\|_{L^{1}(\mathbb{G})} \lesssim 2^{-\varepsilon\left|k-k^{\prime}\right|} . \tag{2.19}
\end{equation*}
$$

By Hölder's inequality and (2.4),

$$
\left|\left\langle h_{(\cdot)}(x), h_{(\cdot)}(y)\right\rangle_{\mathcal{H}}\right| \leq\left|h_{(\cdot)}(x)\right|_{\mathcal{H}} \cdot\left|h_{(\cdot)}(y)\right|_{\mathcal{H}} \lesssim 1
$$

uniformly in $x, y \in \mathbb{G}$. This estimate together with Young's inequality, (2.19) and (2.3) yields

$$
\begin{align*}
\| \int_{0}^{\infty} f * & \left(h_{t} S_{j} K_{0}^{s}\right) * \psi_{k} * \psi_{k^{\prime}} *\left(h_{t} S_{j^{\prime}} \tilde{K}_{0}^{s}\right) \frac{d t}{t} \|_{L^{2}(\mathbb{G})}  \tag{2.20}\\
& \lesssim\left\|\int_{0}^{\infty}\left(h_{t} S_{j} K_{0}^{s}\right) * \psi_{k} * \psi_{k^{\prime}} *\left(h_{t} S_{j^{\prime}} \tilde{K}_{0}^{s}\right) \frac{d t}{t}\right\|_{L^{1}(\mathbb{G})}\|f\|_{L^{2}(\mathbb{G})} \\
& \lesssim\left\|\left|S_{j} K_{0}^{s}\right| *\left|\psi_{k} * \psi_{k^{\prime}}\right| *\left|S_{j^{\prime}} \tilde{K}_{0}^{s}\right|\right\|_{L^{1}(\mathbb{G})}\|f\|_{L^{2}(\mathbb{G})} \\
& \lesssim\left\|S_{j} K_{0}^{s}\right\|_{L^{1}(\mathbb{G})}\left\|\psi_{k} * \psi_{k^{\prime}}\right\|_{L^{1}(\mathbb{G})}\left\|S_{j^{\prime}} \tilde{K}_{0}^{s}\right\|_{L^{1}(\mathbb{G})}\|f\|_{L^{2}(\mathbb{G})} \\
& \lesssim 2^{-\varepsilon\left|k-k^{\prime}\right|}\|f\|_{L^{2}(\mathbb{G})}
\end{align*}
$$

By Minkowski's inequality and (2.4), we get

$$
\begin{align*}
\| \int_{0}^{\infty} f_{t_{1}} * & \left(h_{t_{1}} S_{j} \tilde{K}_{0}^{s}\right) * \psi_{k} * \psi_{k^{\prime}} *\left(h_{t_{2}} S_{j^{\prime}} K_{0}^{s}\right) \frac{d t_{1}}{t_{1}} \|_{L^{2}(\mathcal{H})}  \tag{2.21}\\
& \lesssim\left\|\left|\int_{0}^{\infty} f_{t_{1}} *\left(h_{t_{1}} S_{j} \tilde{K}_{0}^{s}\right) \frac{d t_{1}}{t_{1}}\right| *\left|\psi_{k} * \psi_{k^{\prime}}\right| *\left|S_{j^{\prime}} K_{0}^{s}\right|\right\|_{L^{2}(\mathbb{G})}
\end{align*}
$$

By the Fubini theorem and Hölder's inequality, for every $x \in \mathbb{G}$,

$$
\begin{aligned}
\left|\int_{0}^{\infty} f_{t_{1}} *\left(h_{t_{1}} S_{j} \tilde{K}_{0}^{s}\right)(x) \frac{d t_{1}}{t_{1}}\right| & \leq \int_{\mathbb{G}}\left|\int_{0}^{\infty} f_{t_{1}}\left(x y^{-1}\right) h_{t_{1}}(y) \frac{d t_{1}}{t_{1}}\right|\left|S_{j} \tilde{K}_{0}^{s}(y)(y)\right| d y \\
& \leq \int_{\mathbb{G}}\left|f_{t_{1}}\left(x y^{-1}\right)\right| \mathcal{H}\left|S_{j} \tilde{K}_{0}^{s}(y)\right| d y \\
& =\left(\left|f_{t_{1}}\right| \mathcal{H} *\left|S_{j} \tilde{K}_{0}^{s}\right|\right)(x)
\end{aligned}
$$

Inserting this estimate into (2.21) and using Young's inequality, (2.3) and (2.19), we get

$$
\begin{align*}
& \left\|\int_{0}^{\infty} f_{t_{1}} *\left(h_{t_{1}} S_{j} \tilde{K}_{0}^{s}\right) * \psi_{k} * \psi_{k^{\prime}} *\left(h_{t_{2}} S_{j^{\prime}} K_{0}^{s}\right) \frac{d t_{1}}{t_{1}}\right\|_{L^{2}(\mathcal{H})}  \tag{2.22}\\
& \quad \lesssim\left\|\left(\int_{0}^{\infty}\left|f_{t_{1}}(\cdot)\right|^{2} \frac{d t_{1}}{t_{1}}\right)^{1 / 2} *\left|S_{j} \tilde{K}_{0}^{s}\right| *\left|\psi_{k} * \psi_{k^{\prime}}\right| *\left|S_{j^{\prime}} K_{0}^{s}\right|\right\|_{L^{2}(\mathbb{G})} \\
& \quad \lesssim\left\|S_{j} \tilde{K}_{0}^{s}\right\|_{L^{1}(\mathbb{G})}\left\|\psi_{k} * \psi_{k^{\prime}}\right\|_{L^{1}(\mathbb{G})}\left\|S_{j^{\prime}} K_{0}^{s}\right\|_{L^{1}(\mathbb{G})}\left\|f_{t_{1}}\right\|_{L^{2}(\mathcal{H})} \\
& \quad \lesssim 2^{-\varepsilon\left|k-k^{\prime}\right|}\left\|f_{t_{1}}\right\|_{L^{2}(\mathcal{H})} .
\end{align*}
$$

Taking the geometric mean of (2.17) and (2.20) and then summing over $k$ and $k^{\prime}$, we obtain

$$
\left\|\int_{0}^{\infty} f *\left(h_{t} S_{j} K_{0}\right) *\left(h_{t} S_{j^{\prime}} \tilde{K}_{0}\right) \frac{d t}{t}\right\|_{L^{2}(\mathbb{G})} \lesssim 2^{2^{s+1}}\left|j-j^{\prime}\right| 2^{-\varepsilon\left|j-j^{\prime}\right| / 2}\|f\|_{L^{2}(\mathbb{G})},
$$

which gives (2.11) for some $\varepsilon>0$ if $\left|j-j^{\prime}\right|>C 2^{s}$ for a sufficiently large $C$. In the same way we can deduce (2.10) from (2.18) and (2.22). Thus, to finish the proof of Theorem 1.1, it remains to show Lemma 2.2.
3. $L^{2}$ estimate II: Iterated $T T^{*}$ method. The proof of Lemma 2.2 will be given in this section. We only verify (2.13) here since (2.14) can be proved in a similar way. First we normalize $K_{0}$ so that $\left\|K_{0}\right\|_{\infty}=1$. By dilation invariance,

$$
\left\|\left(h_{t} S_{j} K_{0}\right) * \psi_{k}\right\|_{L^{1}(\mathcal{H})}=\left\|\left(h_{t} S_{0} K_{0}\right) * \psi_{k-j}\right\|_{L^{1}(\mathcal{H})}
$$

so we only need to show (2.13) for $j=0$. If $k \geq-C$, then by the mean zero condition on $K_{0}$ and the smoothness of $\psi_{k}$, we have

$$
\begin{equation*}
\left\|\left(h_{t} S_{0} K_{0}\right) * \psi_{k}\right\|_{L^{1}(\mathcal{H})} \lesssim 2^{-\varepsilon k} \tag{3.1}
\end{equation*}
$$

By Young's inequality (Lemma 2.1) and (3.1), we get (2.13) for $k \geq-C$, where $C$ is a constant large enough to be determined later. Thus in the following we may assume that $k<-C$.

Fix $k=-s$ for some $s>C$. If we define an operator $L_{\psi}$ by

$$
L_{\psi} f(x, t)=f *\left(h_{t} S_{0} K_{0}\right) * \psi_{-s}
$$

then it is easy to see that $L_{\psi}$ is a bounded operator from $L^{2}(\mathbb{G})$ to $L^{2}(\mathcal{H})$. Denote by $L_{\psi}^{*}$ the adjoint operator of $L_{\psi}$, that is, for $g_{t} \in L^{2}(\mathcal{H})$,

$$
L_{\psi}^{*}\left(g_{t}\right)(x)=\int_{0}^{\infty} g_{t} * \psi_{-s} *\left(h_{t} S_{0} \tilde{K}_{0}\right) \frac{d t}{t}
$$

Thus, (2.13) will follow from the following estimates:

$$
\begin{aligned}
& \left\|L_{\psi} L_{\psi}^{*}\left(g_{t_{0}}\right)\right\|_{L^{2}(\mathcal{H})} \\
& \quad=\left\|\left(\int_{0}^{\infty} g_{t_{0}} * \psi_{-s} *\left(h_{t_{0}} S_{0} \tilde{K}_{0}\right) \frac{d t_{0}}{t_{0}}\right) *\left(h_{t_{1}} S_{0} K_{0}\right) * \psi_{-s}\right\|_{L^{2}(\mathcal{H})} \\
& \quad \lesssim 2^{-\varepsilon s}\left\|g_{t_{0}}\right\|_{L^{2}(\mathcal{H})}
\end{aligned}
$$

and

$$
\begin{aligned}
\left\|L_{\psi}^{*} L_{\psi}(f)\right\|_{L^{2}(\mathbb{G})} & =\left\|\int_{0}^{\infty} f * \psi_{-s} *\left(h_{t} S_{0} \tilde{K}_{0}\right) *\left(h_{t} S_{0} K_{0}\right) * \psi_{-s} \frac{d t}{t}\right\|_{L^{2}(\mathbb{G})} \\
& \lesssim 2^{-\varepsilon s}\|f\|_{L^{2}(\mathbb{G})} .
\end{aligned}
$$

From the operator norm identity $\left\|L_{\psi} L_{\psi}^{*}\right\|=\left\|\left(L_{\psi} L_{\psi}^{*}\right)^{n+1}\right\|^{1 /(n+1)}$, it suffices
to show

$$
\begin{align*}
& \| \int_{0}^{\infty} \ldots \int_{0}^{\infty} f_{t_{0}} * \psi_{-s} *\left(h_{t_{0}} S_{0} \tilde{K}_{0}\right) \frac{d t_{0}}{t_{0}} *\left(h_{t_{1}} S_{0} K_{0}\right) * \psi_{-s}  \tag{3.2}\\
& \quad * \psi_{-s} *\left(h_{t_{1}} S_{0} \tilde{K}_{0}\right) \frac{d t_{1}}{t_{1}} *\left(h_{t_{2}} S_{0} K_{0}\right) * \psi_{-s} \\
& \quad \ldots \\
& \quad * \psi_{-s} *\left(h_{t_{n}} S_{0} \tilde{K}_{0}\right) \frac{d t_{n}}{t_{n}} *\left(h_{t_{n+1}} S_{0} K_{0}\right) * \psi_{-s} \|_{L^{2}(\mathcal{H})} \\
& \quad \lesssim 2^{-\varepsilon s}\left\|f_{t_{0}}\right\|_{L^{2}(\mathcal{H})}
\end{align*}
$$

and

$$
\begin{array}{rl}
\| \int_{0}^{\infty} \ldots \int_{0}^{\infty} f & * \psi_{-s} *\left(h_{t_{1}} S_{0} \tilde{K}_{0}\right) *\left(h_{t_{1}} S_{0} K_{0}\right) * \psi_{-s} \frac{d t_{1}}{t_{1}}  \tag{3.3}\\
& * \psi_{-s} *\left(h_{t_{2}} S_{0} \tilde{K}_{0}\right) *\left(h_{t_{2}} S_{0} K_{0}\right) * \psi_{-s} \frac{d t_{2}}{t_{2}} \\
& \ldots \\
& * \psi_{-s} *\left(h_{t_{n}} S_{0} \tilde{K}_{0}\right) *\left(h_{t_{n}} S_{0} K_{0}\right) * \psi_{-s} \frac{d t_{n}}{t_{n}} \|_{L^{2}(\mathbb{G})} \\
& \lesssim 2^{-\varepsilon s}\|f\|_{L^{2}(\mathbb{G})}
\end{array}
$$

By Young's inequality, it is easy to see that (3.3) follows from

$$
\begin{align*}
& \| \int_{0}^{\infty} \ldots \int_{0}^{\infty} \psi_{-s} *\left(h_{t_{1}} S_{0} K_{0}\right) *\left(h_{t_{1}} S_{0} \tilde{K}_{0}\right) * \psi_{-s} \frac{d t_{1}}{t_{1}} * \psi_{-s} *\left(h_{t_{2}} S_{0} K_{0}\right)  \tag{3.4}\\
& \quad * \cdots * \psi_{-s} *\left(h_{t_{n}} S_{0} \tilde{K}_{0}\right) *\left(h_{t_{n}} S_{0} K_{0}\right) * \psi_{-s} \frac{d t_{n}}{t_{n}} \|_{L^{1}(\mathbb{G})} \lesssim 2^{-\varepsilon s} .
\end{align*}
$$

Next, we want to show that (3.2) will follow from an $L^{1}(\mathbb{G})$ norm (not $L^{1}(\mathcal{H})$ norm $)$ estimate similar to (3.4). This is a key step since if we worked with a vector-valued integral $\left(L^{1}(\mathcal{H})\right.$ estimate), some essential difficulties would arise (see Remark 4.4 in the next section).

By Hölder's inequality,

$$
\begin{aligned}
\left\|\int_{0}^{\infty} f_{t_{0}} * \psi_{-s} *\left(h_{t_{0}} S_{0} \tilde{K}_{0}\right) \frac{d t_{0}}{t_{0}}\right\|_{L^{2}(\mathbb{G})} & \leq\left\||f|_{\mathcal{H}} *\left|\psi_{-s}\right| *\left|h_{(\cdot)} S_{0} \tilde{K}_{0}\right|_{\mathcal{H}}\right\|_{L^{2}(\mathbb{G})} \\
& \leq\|f\|_{L^{2}(\mathcal{H})}\left\|\psi_{-s}\right\|_{L^{1}(\mathbb{G})}\left\|h_{(\cdot)} S_{0} \tilde{K}_{0}\right\|_{L^{1}(\mathcal{H})} \\
& \lesssim\|f\|_{L^{2}(\mathcal{H})}
\end{aligned}
$$

Thus, on applying Young's inequality again, (3.2) will follow from

$$
\begin{align*}
& \| \int_{0}^{\infty} \ldots \int_{0}^{\infty}\left(h_{t_{1}} S_{0} K_{0}\right) * \psi_{-s} * \psi_{-s} *\left(h_{t_{1}} S_{0} \tilde{K}_{0}\right) \frac{d t_{1}}{t_{1}} *\left(h_{t_{2}} S_{0} K_{0}\right) * \psi_{-s}  \tag{3.5}\\
& \quad * \cdots * \psi_{-s} *\left(h_{t_{n}} S_{0} \tilde{K}_{0}\right) \frac{d t_{n}}{t_{n}} *\left(h_{t_{n+1}} S_{0} K_{0}\right) * \psi_{-s} \|_{L^{1}(\mathcal{H})} \lesssim 2^{-\varepsilon s} .
\end{align*}
$$

Noting that $h_{t_{n+1}} S_{0} K_{0} * \psi_{-s} \in L^{1}(\mathcal{H})$, by Minkowski's inequality we see that (3.5) is implied by

$$
\begin{align*}
& \| \int_{0}^{\infty} \ldots \int_{0}^{\infty}\left(h_{t_{1}} S_{0} K_{0}\right) * \psi_{-s} * \psi_{-s} *\left(h_{t_{1}} S_{0} \tilde{K}_{0}\right) \frac{d t_{1}}{t_{1}}  \tag{3.6}\\
& \quad \\
& \quad * \cdots *\left(h_{t_{n}} S_{0} K_{0}\right) * \psi_{-s} * \psi_{-s} *\left(h_{t_{n}} S_{0} \tilde{K}_{0}\right) \frac{d t_{n}}{t_{n}} \|_{L^{1}(\mathbb{G})} \lesssim 2^{-\varepsilon s}
\end{align*}
$$

Thus, to get (3.2) and (3.3), it remains to show (3.4) and (3.6).
Now we will use the following idea. Let $\phi$ be an $L^{1}$ function supported in $B$. Then

$$
|\phi * f(x)| \leq\|\phi\|_{L^{1}} \sup _{w \in B}\left|\delta_{w} * f(x)\right|
$$

where $\delta_{w}$ is the Dirac measure supported at $w$. Since the functions $\psi_{-s} * S_{0} \tilde{K}_{0}$ and $\psi_{-s} * \psi_{-s} * S_{0} \tilde{K}_{0}$ are bounded in $L^{1}(B(0, C))$, we have

$$
\left|\psi_{-s} *\left(h_{t} S_{0} \tilde{K}_{0}\right) * f(x)\right| \lesssim \sup _{w \in B(0, C), \xi \in A_{0}}\left|\delta_{w} * f(x) h_{t}(\xi)\right|
$$

Thus to show (3.6), it suffices to prove

$$
\begin{align*}
& \| \int_{[0, \infty)^{n}}\left(\left(h_{t_{1}} S_{0} K_{0}\right) * \delta_{w_{2}} * \cdots\right.  \tag{3.7}\\
& \left.\quad * \delta_{w_{n}} *\left(h_{t_{n}} S_{0} K_{0}\right) * \psi_{-s} * \delta_{w_{n+1}}\right) \prod_{m=1}^{n} h_{t_{m}}\left(\xi_{m}\right) \frac{d t}{t} \|_{L^{1}(\mathbb{G})} \lesssim 2^{-\varepsilon s}
\end{align*}
$$

uniformly for $\left(w_{2}, \ldots, w_{n+1}\right) \in(B(0, C))^{n}$ and $\left(\xi_{1}, \ldots, \xi_{n}\right) \in A_{0}^{n}$, where $\delta_{w_{j}}$ is the Dirac measure supported at $w_{j}$ for $j=2, \ldots, n+1$. Moreover, $\frac{d t}{t}=\frac{d t_{1}}{t_{1}} \otimes \cdots \otimes \frac{d t_{n}}{t_{n}}$. In the same way, to show (3.4), it suffices to verify

$$
\begin{align*}
& \| \int_{[0, \infty)^{n}}\left(\delta_{w_{1}} *\left(h_{t_{1}} S_{0} K_{0}\right) * \delta_{w_{2}}\right.  \tag{3.8}\\
& \left.\quad * \cdots * \delta_{w_{n}} *\left(S_{0} K_{0} h_{t_{n}}\right) * \psi_{-s}\right) \prod_{m=1}^{n} h_{t_{m}}\left(\xi_{m}\right) \frac{d t}{t} \|_{L^{1}(\mathbb{G})} \lesssim 2^{-\varepsilon s}
\end{align*}
$$

uniformly for $\left(w_{1}, \ldots, w_{n}\right) \in(B(0, C))^{n}$ and $\left(\xi_{1}, \ldots, \xi_{n}\right) \in A_{0}^{n}$.

Below we only give the proof of (3.7), since (3.8) can be proved similarly. Fix $\vec{w}:=\left(w_{2}, \ldots, w_{n+1}\right) \in(B(0, C))^{n}$ and $\vec{\xi}:=\left(\xi_{1}, \ldots, \xi_{n}\right) \in A_{0}^{n}$. By duality, it suffices to show that the quantity

$$
\begin{align*}
& \mid\left\langle\int _ { [ 0 , \infty ) ^ { n } } \left(\left(h_{t_{1}} S_{0} K_{0}\right) * \cdots * \delta_{w_{n}}\right.\right.  \tag{3.9}\\
& \left.\left.\quad *\left(h_{t_{n}} S_{0} K_{0}\right) * \psi_{-s} * \delta_{w_{n+1}}\right) \prod_{m=1}^{n} h_{t_{m}}\left(\xi_{m}\right) \frac{d t}{t}, g\right\rangle \mid
\end{align*}
$$

is $\lesssim 2^{-\varepsilon s}$ for all test functions $g$ with $\|g\|_{L^{\infty}(\mathbb{G})} \leq 1$. For a fixed $g$, performing the $t$ integration and taking $w_{1} \in B(0, C)$, we can rewrite (3.9) as

$$
\begin{align*}
& \mid \iiint \psi_{-s}(x) g\left(w_{1}^{-1} \Phi_{\vec{y}}(\vec{u}) x w_{n+1}\right)  \tag{3.10}\\
& \left.\quad \times \prod_{i=1}^{n} \varphi\left(u_{i}\right) K_{0}\left(y_{i}\right) \min \left\{\frac{u_{i} \rho\left(y_{i}\right)}{\rho\left(\xi_{i}\right)}, \frac{\rho\left(\xi_{i}\right)}{u_{i} \rho\left(y_{i}\right)}\right\} d x d \vec{u} d \vec{y} \right\rvert\,,
\end{align*}
$$

where $x \in \mathbb{G}, \vec{u}:=\left(u_{1}, \ldots, u_{n}\right) \in[-C, C]^{n}, \vec{y}:=\left(y_{1}, \ldots, y_{n}\right) \in A_{0}^{n}$ and

$$
\Phi_{\vec{y}}(\vec{u}):=\prod_{i=1}^{n} w_{i}\left(u_{i} \circ y_{i}\right) .
$$

To see this, we only check this equality for $n=2$. In this case, it is easy to see that (3.9) equals

$$
\begin{array}{r}
\iint_{[0, \infty)^{n}}\left\{\int_{\mathbb{G}} \psi_{-s}(x)\left(\left(h_{t_{2}} S_{0} \tilde{K}_{0}\right) * \delta_{w_{2}^{-1}} *\left(h_{t_{1}} S_{0} \tilde{K}_{0}\right) * g * \delta_{w_{3}^{-1}}\right)(x) d x\right\}  \tag{3.11}\\
\times h_{t_{1}}\left(\xi_{1}\right) h_{t_{2}}\left(\xi_{2}\right) \frac{d t_{1} d t_{2}}{t_{1} t_{2}} .
\end{array}
$$

Expanding the first two convolutions, we get

$$
\begin{aligned}
& \left(h_{t_{2}} S_{0} \tilde{K}_{0}\right) * \delta_{w_{2}^{-1}} *\left(h_{t_{1}} S_{0} \tilde{K}_{0}\right) * g * \delta_{w_{3}^{-1}}(x) \\
& \quad=\int_{A_{0}} h_{t_{2}}\left(y_{2}\right) S_{0} \tilde{K}_{0}\left(y_{2}\right)\left(\delta_{w_{2}^{-1}} *\left(h_{t_{1}} S_{0} \tilde{K}_{0}\right) * g * \delta_{w_{3}^{-1}}\right)\left(y_{2}^{-1} x\right) d y_{2} \\
& \quad=\int_{A_{0}} h_{t_{2}}\left(y_{2}\right) S_{0} \tilde{K}_{0}\left(y_{2}\right)\left(\left(h_{t_{1}} S_{0} \tilde{K}_{0}\right) * g * \delta_{w_{3}^{-1}}\right)\left(w_{2} y_{2}^{-1} x\right) d y_{2} .
\end{aligned}
$$

Recalling

$$
S_{0} \tilde{K}_{0}(x)=\int_{0}^{\infty} \varphi(s) s^{-N} \tilde{K}_{0}\left(s^{-1} \circ x\right) d s
$$

and $\tilde{K}_{0}(x)=K_{0}\left(x^{-1}\right)$, we have

$$
\begin{aligned}
\left(h_{t_{2}} S_{0} \tilde{K}_{0}\right) * \delta_{w_{2}^{-1}} * & \left(h_{t_{1}} S_{0} \tilde{K}_{0}\right) * g * \delta_{w_{3}^{-1}}(x) \\
= & \int_{A_{0}} h_{t_{2}}\left(u_{2} \circ y_{2}\right)\left(\int_{0}^{\infty} \varphi\left(u_{2}\right) \tilde{K}_{0}\left(y_{2}\right) d u_{2}\right) \\
& \times\left(\left(h_{t_{1}} S_{0} \tilde{K}_{0}\right) * g * \delta_{w_{3}^{-1}}\right)\left(w_{2}\left(u_{2} \circ y_{2}^{-1}\right) x\right) d y_{2} \\
= & \int_{A_{0}}^{\infty} \int_{0}^{\infty} h_{t_{2}}\left(u_{2} \circ y_{2}^{-1}\right) \varphi\left(u_{2}\right) K_{0}\left(y_{2}\right) \\
& \times\left(\left(h_{t_{1}} S_{0} \tilde{K}_{0}\right) * g * \delta_{w_{3}^{-1}}\right)\left(w_{2}\left(u_{2} \circ y_{2}\right) x\right) d u_{2} d y_{2} .
\end{aligned}
$$

Similarly, we can expand the other two convolutions to obtain

$$
\begin{align*}
& \left(h_{t_{2}} S_{0} \tilde{K}_{0}\right) * \delta_{w_{2}^{-1}} *\left(h_{t_{1}} S_{0} \tilde{K}_{0}\right) * g * \delta_{w_{3}^{-1}}(x)  \tag{3.12}\\
& \quad=\int_{A_{0} \times A_{0}} \int_{0}^{\infty} \int_{0}^{\infty} h_{t_{2}}\left(u_{2} \circ y_{2}^{-1}\right) h_{t_{1}}\left(u_{1} \circ y_{1}^{-1}\right) \varphi\left(u_{2}\right) \varphi\left(u_{1}\right) K_{0}\left(y_{2}\right) K_{0}\left(y_{1}\right) \\
& \quad \times g\left(\left(u_{1} \circ y_{1}\right) w_{2}\left(u_{2} \circ y_{2}\right) x w_{3}\right) d u_{1} d u_{2} d y_{1} d y_{2} .
\end{align*}
$$

Inserting (3.12) into (3.11), we get (3.10) by noting that

$$
\begin{aligned}
& \int_{0}^{\infty} \int_{0}^{\infty} h_{t_{1}}\left(u_{1} \circ y_{1}\right) h_{t_{2}}\left(u_{2} \circ y_{2}\right) h_{t_{1}}\left(\xi_{1}\right) h_{t_{2}}\left(\xi_{2}\right) \frac{d t_{1}}{t_{1}} \frac{d t_{2}}{t_{2}} \\
&=\left(\int_{0}^{\infty} h_{t_{1}}\left(u_{1} \circ y_{1}\right) h_{t_{1}}\left(\xi_{1}\right) \frac{d t_{1}}{t_{1}}\right)\left(\int_{0}^{\infty} h_{t_{2}}\left(u_{2} \circ y_{2}\right) h_{t_{2}}\left(\xi_{2}\right) \frac{d t_{2}}{t_{2}}\right) \\
&=\frac{u_{1} \rho\left(y_{1}\right) \rho\left(\xi_{1}\right)}{2\left(\max \left\{u_{1} \rho\left(y_{1}\right), \rho\left(\xi_{1}\right)\right)\right\}^{2}} \cdot \frac{u_{2} \rho\left(y_{2}\right) \rho\left(\xi_{2}\right)}{2\left(\max \left\{u_{2} \rho\left(y_{2}\right), \rho\left(\xi_{2}\right)\right\}^{2}\right.} \\
&=\frac{1}{4} \min \left\{\frac{u_{1} \rho\left(y_{1}\right)}{\rho\left(\xi_{1}\right)}, \frac{\rho\left(\xi_{1}\right)}{u_{1} \rho\left(y_{1}\right)}\right\} \cdot \min \left\{\frac{u_{2} \rho\left(y_{2}\right)}{\rho\left(\xi_{2}\right)}, \frac{\rho\left(\xi_{2}\right)}{u_{2} \rho\left(y_{2}\right)}\right\} .
\end{aligned}
$$

The general case can be obtained by iterating the above process.
The next step is to split the integral in (3.10) into two parts. We need the left-invariant differentiation structures exploited by Tao in $[\mathrm{T}]$. Let $f(t)$ be smooth functions from $\mathbb{R}$ to $\mathbb{G}$. The left-invariant derivative $\partial_{t}^{L} f(t)$ is defined by Newton's approximation:

$$
f(t+\varepsilon)=f(t)\left(\varepsilon \partial_{t}^{L} f(t)\right)+\varepsilon^{2} O(1), \quad \text { for } \varepsilon \text { small. }
$$

If $F(x)$ is a smooth function from $\mathbb{R}^{n}$ to $\mathbb{G}$, the left-invariant derivative $D_{x}^{L} F(x)$ is defined to be the matrix with columns given by

$$
D_{x}^{L} f(x)=\left(\partial_{x_{1}}^{L} F(x), \ldots, \partial_{x_{n}}^{L} F(x)\right) .
$$

Using the above notions, we split the integral in (3.10) into

$$
\begin{align*}
& \mid \int_{A_{0}^{n}} \int_{\left[C^{-1}, C\right]^{n}} \int_{\mathbb{G}} \psi_{-s}(x) g\left(w_{1}^{-1} \Phi_{\vec{y}}(\vec{u}) x w_{n+1}\right) \eta\left(2^{n \varepsilon s} \operatorname{det} D_{\vec{u}}^{L}\left(\Phi_{\vec{y}}\right)(\vec{u})\right)  \tag{3.13}\\
& \left.\times \prod_{i=1}^{n} \varphi\left(u_{i}\right) K_{0}\left(y_{i}\right) \min \left\{\frac{u_{i} \rho\left(y_{i}\right)}{\rho\left(\xi_{i}\right)}, \frac{\rho\left(\xi_{i}\right)}{u_{i} \rho\left(y_{i}\right)}\right\} d x d \vec{u} d \vec{y} \right\rvert\,
\end{align*}
$$

and

$$
\begin{align*}
& \mid \int_{A_{0}^{n}\left[C^{-1}, C\right]^{n}} \int_{\mathbb{G}} \psi_{-s}(x) g\left(w_{1}^{-1} \Phi_{\vec{y}}(\vec{u}) x w_{n+1}\right)\left[1-\eta\left(2^{n \varepsilon s} \operatorname{det} D_{\vec{u}}^{L}\left(\Phi_{\vec{y}}\right)(\vec{u})\right)\right]  \tag{3.14}\\
& \left.\times \prod_{i=1}^{n} \varphi\left(u_{i}\right) K_{0}\left(y_{i}\right) \min \left\{\frac{u_{i} \rho\left(y_{i}\right)}{\rho\left(\xi_{i}\right)}, \frac{\rho\left(\xi_{i}\right)}{u_{i} \rho\left(y_{i}\right)}\right\} d x d \vec{u} d \vec{y} \right\rvert\,
\end{align*}
$$

where $\eta$ is a smooth nonnegative bump function which equals 1 near $0 \in \mathbb{G}$.
To estimate (3.13), we simply replace everything by absolute values, and observe that it can be controlled by the "degenerate portion" of the integral (see Section 6 in [T]). More precisely, using the bounds on $g, \varphi$ and $K_{0}$, we see that the left hand side of (3.13) does not exceed

$$
\int_{\mathbb{G}\left[C^{-1}, C\right]^{n}} \int_{A_{0}^{n}}\left|\psi_{-s}(x)\right| \eta\left(2^{n \varepsilon s} \operatorname{det} D_{\vec{u}}^{L}\left(\Phi_{\vec{y}}\right)(\vec{u})\right) d \vec{y} d \vec{u} d x
$$

which is $\leq C 2^{-\varepsilon s}$ (see $\left.[\mathrm{T}]\right)$. So it remains to deal with (3.14).
4. $L^{2}$ estimate III: Nondegenerate portion of the integral. We first give the following result due to Tao.

Lemma 4.1 ([T, Lemma 7.1]). Let $f$ be a function on $B(0, C)$ with mean zero and $\|f\|_{1} \lesssim 1$. Then there exist functions $f_{1}, \ldots, f_{n}$ supported on a slightly larger ball $B(0, C)$ with $\left\|f_{i}\right\|_{1} \lesssim 1$ and $f(x)=\sum_{i=1}^{n} \partial_{x_{i}} f_{i}(x)$.

Let us continue the proof of the $L^{2}$ estimate. Note that $K_{0} \in L^{\infty}\left(A_{0}\right)$ implies $K_{0} \in L^{1}(\mathbb{G})$. Thus to prove $(3.14) \lesssim 2^{-\varepsilon s}$, it suffices to show

$$
\begin{aligned}
& \int_{\left[C^{-1}, C\right]^{n}} \int_{\mathbb{G}} \psi_{-s}(x) g\left(w_{1}^{-1} \Phi_{\vec{y}}(\vec{u}) x w_{n+1}\right)\left[1-\eta\left(2^{n \varepsilon s} \operatorname{det} D_{\vec{u}}^{L}\left(\Phi_{\vec{y}}\right)(\vec{u})\right)\right] \\
& \left.\times \prod_{i=1}^{n} \varphi\left(u_{i}\right) \min \left\{\frac{u_{i} \rho\left(y_{i}\right)}{\rho\left(\xi_{i}\right)}, \frac{\rho\left(\xi_{i}\right)}{u_{i} \rho\left(y_{i}\right)}\right\} d x d \vec{u} \right\rvert\, \lesssim 2^{-\varepsilon s}
\end{aligned}
$$

uniformly in $\vec{y} \in A_{0}^{n}$.
Since $\psi_{0}$ is supported on $B(0,16)$ with mean zero and $\|\psi\|_{L^{1}(\mathbb{G})} \lesssim 1$, by Lemma 4.1 we have $\psi_{-s}(x)=\sum_{j=1}^{n} \partial_{x_{j}} f_{j}(x)$, where the functions $f_{j}$ are
supported on $B\left(0,2^{4-s}\right)$ and satisfy

$$
\begin{equation*}
\left\|f_{j}\right\|_{1} \lesssim 2^{-\alpha_{j} s} . \tag{4.1}
\end{equation*}
$$

It thus suffices to bound the quantity

$$
\begin{equation*}
\left|\iint \partial_{x_{j}} f_{j}(x) g\left(w_{1}^{-1} \Phi_{\vec{y}}(\vec{u}) x w_{n+1}\right) a(\vec{u}) \prod_{i=1}^{n} \min \left\{\frac{u_{i} \rho\left(y_{i}\right)}{\rho\left(\xi_{i}\right)}, \frac{\rho\left(\xi_{i}\right)}{u_{i} \rho\left(y_{i}\right)}\right\} d \vec{u} d x\right| \tag{4.2}
\end{equation*}
$$

by $C 2^{-\varepsilon s}$ for all $j=1, \ldots, n$, where

$$
a(\vec{u})=\left[1-\eta\left(2^{n \varepsilon s} \operatorname{det} D_{\vec{u}}^{L}\left(\Phi_{\vec{y}}\right)(\vec{u})\right)\right] \prod_{i=1}^{n} \varphi\left(u_{i}\right)
$$

If we integrate by parts in the $x_{j}$ variable, (4.2) can be rewritten as

$$
\left|\iint f_{j}(x) \partial_{x_{j}} g(\tilde{\Phi}) a(\vec{u}) \prod_{i=1}^{n} \min \left\{\frac{u_{i} \rho\left(y_{i}\right)}{\rho\left(\xi_{i}\right)}, \frac{\rho\left(\xi_{i}\right)}{u_{i} \rho\left(y_{i}\right)}\right\} d \vec{u} d x\right|
$$

where we use $\tilde{\Phi}$ to denote $w_{1}^{-1} \Phi_{\vec{y}}(\vec{u}) x w_{n+1}$ for simplicity. By (4.1), if $\varepsilon$ is small enough, we only need to show

$$
\left|\int \partial_{x_{j}} g(\tilde{\Phi}) a(\vec{u}) \prod_{i=1}^{n} \min \left\{\frac{u_{i} \rho\left(y_{i}\right)}{\rho\left(\xi_{i}\right)}, \frac{\rho\left(\xi_{i}\right)}{u_{i} \rho\left(y_{i}\right)}\right\} d \vec{u}\right| \lesssim 2^{C \varepsilon s}
$$

uniformly in $x \in B(0,16)$ for some constant $C$.
The following result was proved in [T].
Lemma 4.2 ([T, Lemma 7.2]). Let $f: \mathbb{R} \times \mathbb{R}^{n} \rightarrow \mathbb{G}$ and $F: \mathbb{G} \rightarrow \mathbb{R}$ be smooth functions. Then

$$
\partial_{s} F(f(s, t))=\nabla_{t} F(f(s, t)) \cdot\left(D_{t}^{L} f(s, t)\right)^{-1} \partial_{s}^{L} f(s, t)
$$

whenever $\operatorname{det} D_{t}^{L} f(s, t)$ is nonzero.
By Lemma 4.2, it suffices to show

$$
\begin{equation*}
\left|\int \nabla_{\vec{u}} g(\tilde{\Phi}) \cdot\left(D_{\vec{u}}^{L} \tilde{\Phi}\right)^{-1} \partial_{x_{j}}^{L}(\tilde{\Phi}) a(\vec{u}) \prod_{i=1}^{n} \min \left\{\frac{u_{i} \rho\left(y_{i}\right)}{\rho\left(\xi_{i}\right)}, \frac{\rho\left(\xi_{i}\right)}{u_{i} \rho\left(y_{i}\right)}\right\} d \vec{u}\right| \lesssim 2^{C \varepsilon s} \tag{4.3}
\end{equation*}
$$

where $\nabla_{\vec{u}}=\left(\partial_{u_{1}}, \ldots, \partial_{u_{n}}\right)$. To show (4.3), it is equivalent to show

$$
\left|\int \partial_{u_{k}} g(\tilde{\Phi})\left(\left(D_{\vec{u}}^{L} \tilde{\Phi}\right)^{-1} \partial_{x_{j}}^{L}(\tilde{\Phi})\right)_{k} a(\vec{u}) \prod_{i=1}^{n} \min \left\{\frac{u_{i} \rho\left(y_{i}\right)}{\rho\left(\xi_{i}\right)}, \frac{\rho\left(\xi_{i}\right)}{u_{i} \rho\left(y_{i}\right)}\right\} d \vec{u}\right| \lesssim 2^{C \varepsilon s}
$$

for each $k=1, \ldots, n$, where $(\cdot)_{k}$ denotes the $k$ th component of a vector.
It is not hard to see that the above inequality follows from

$$
\left|\partial_{u_{k}}\left[\left(\left(D_{\vec{u}}^{L} \tilde{\Phi}\right)^{-1} \partial_{x_{j}}^{L}(\tilde{\Phi})\right)_{k} a(\vec{u}) \prod_{i} \min \left\{\frac{u_{i} \rho\left(y_{i}\right)}{\rho\left(\xi_{i}\right)}, \frac{\rho\left(\xi_{i}\right)}{u_{i} \rho\left(y_{i}\right)}\right\}\right]\right| \lesssim 2^{C \varepsilon s},
$$

where $\partial_{u_{k}}$ is understood to be the weak derivative when acting on the minimum function. Since

$$
\left\lvert\,\left(\left.1+\nabla_{\vec{u})} \prod_{i \neq k} \min \left\{\frac{u_{i} \rho\left(y_{i}\right)}{\rho\left(\xi_{i}\right)}, \frac{\rho\left(\xi_{i}\right)}{u_{i} \rho\left(y_{i}\right)}\right\} \right\rvert\, \lesssim 1,\right.\right.
$$

it suffices to show

$$
\left|\partial_{u_{k}}\left[\left(\left(D_{\vec{u}}^{L} \tilde{\Phi}\right)^{-1} \partial_{x_{j}}^{L}(\tilde{\Phi})\right)_{k} a(\vec{u})\right]\right| \lesssim 2^{C \varepsilon s}
$$

Noticing that all functions appearing in the definition of $a$ are smooth and compactly supported, we can easily see that

$$
|a(\vec{u})| \lesssim 1 \quad \text { and } \quad\left|\nabla_{\vec{u}} a(\vec{u})\right| \lesssim 2^{n \varepsilon s} .
$$

Thus it suffices to show that, on the support of $a(\vec{u})$,

$$
\mid\left(1+\partial_{u_{k}}\right) \cdot\left[\left(D_{\vec{u}}^{L}(\tilde{\Phi})^{-1} \partial_{x_{j}}^{L}(\tilde{\Phi})\right]_{k} \mid \lesssim 2^{C \varepsilon s}\right.
$$

By Cramer's rule, it is equivalent to show

$$
\begin{equation*}
\left|\left(1+\partial_{u_{k}}\right) \frac{\operatorname{det}\left(\partial_{u_{1}}^{L}(\tilde{\Phi}), \ldots, \partial_{x_{j}}^{L}(\tilde{\Phi}), \ldots, \partial_{u_{n}}^{L}(\tilde{\Phi})\right)}{\operatorname{det} D_{\vec{u}}^{L}(\tilde{\Phi})}\right| \lesssim 2^{C \varepsilon s} \tag{4.4}
\end{equation*}
$$

where $\left(\partial_{u_{1}}^{L}(\tilde{\Phi}), \ldots, \partial_{x_{j}}^{L}(\tilde{\Phi}), \ldots, \partial_{u_{n}}^{L}(\tilde{\Phi})\right)$ denotes the matrix whose $j^{\prime}$ th column vector is $\partial_{u_{j^{\prime}}}^{L} \tilde{\Phi}$ for $j^{\prime}=1, \ldots, n, j^{\prime} \neq k$ and whose $k$ th column vector is $\partial_{x_{j}}^{L}(\tilde{\Phi})$.

Now we summarize some useful conclusions in the following lemma; see [T] for the proofs.

Lemma 4.3 (see $[\mathrm{T}]$ ). Let $f(t), g(t)$ be a smooth functions from $\mathbb{R}$ to $\mathbb{G}$ and $s(t)$ be a smooth function from $\mathbb{R}$ to $\mathbb{R}$. Then
(a) $\quad\left|\partial_{t} f(t)\right| \sim\left|\partial_{t}^{L} f(t)\right| \quad$ whenever $|f(t)| \lesssim 1$;
(b) $\quad \partial_{t}^{L}(f(t) g(t))=\partial_{t}^{L} g(t)+C[g(t)] \partial_{t}^{L} f(t)$;
(c) $\quad C[t \circ x](t \circ v)=t \circ(C[x] v), \quad C[x]^{-1}=C\left[x^{-1}\right]$;
(d) $\quad|C[x] v| \sim|v| \quad$ whenever $|x| \lesssim 1$;
(e) $\quad X(t \circ x)=t \circ X(x) \quad$ and $\quad \rho(X(x)) \lesssim \rho(x)$;
(f) $\quad \rho\left(\partial_{t}(t \circ x)\right) \sim \rho(t \circ x) \quad$ for $t \lesssim 1$;
(g) $\quad \partial_{t}^{L}(s(t) \circ f(t))=s(t) \circ \partial_{t}^{L} f(t)+\left(s^{\prime}(t) / s(t)\right)(s(t) \circ X[f(t)])$,
where $X(x)$ is the vector field defined by $X(x)=\left.\partial_{t}^{L}(t \circ x)\right|_{t=1}$.
By Lemma 4.3(b),

$$
\begin{equation*}
D_{\vec{u}}^{L}(\tilde{\Phi})=D_{\vec{u}}^{L}\left(\Phi_{\vec{y}}(\vec{u}) x w_{n+1}\right)=C\left[x w_{n+1}\right] D_{\vec{u}}^{L}\left(\Phi_{\vec{y}}(\vec{u})\right) \tag{4.5}
\end{equation*}
$$

Since $\rho\left(x w_{n+1}\right) \lesssim \rho(x)+\rho\left(w_{n+1}\right) \lesssim 1($ cf. [FoSt, p. 9] $)$,

$$
\begin{equation*}
\left|\operatorname{det} D_{\vec{u}}^{L}(\tilde{\Phi})\right|=\left|\operatorname{det} D_{\vec{u}}^{L}\left(\Phi_{\vec{y}}(\vec{u}) x w_{n+1}\right)\right| \sim\left|\operatorname{det} D_{\vec{u}}^{L}\left(\Phi_{\vec{y}}(\vec{u})\right)\right| \gtrsim 2^{-n \varepsilon s} \tag{4.6}
\end{equation*}
$$

on the support of $a(\vec{u})$. On the other hand, since $\tilde{\Phi}$ is smooth and compactly supported in all variables, we can readily see that

$$
\left|\left(1+\partial_{u_{k}}\right) \operatorname{det}\left(\partial_{u_{1}}^{L}(\tilde{\Phi}), \ldots, \partial_{x_{j}}^{L}(\tilde{\Phi}), \ldots, \partial_{u_{n}}^{L}(\tilde{\Phi})\right)\right| \lesssim 1
$$

This inequality together with (4.6) yields (4.4). Thus we have completed the proof of Theorem 1.1.

We make the following remark to demonstrate why we need to pass from the vector-valued integral to a scalar-valued one.

REMARK 4.4. If we worked with the vector-valued integral, instead of (4.3), we need to show

$$
\begin{aligned}
& \mid \iint_{0}^{\infty} \nabla_{\vec{u}} g_{t_{n}}\left(w_{1}^{-1} \Phi_{\vec{y}}(\vec{u}) x\right) \cdot\left(D_{\vec{u}}^{L}\left(w_{1}^{-1} \Phi_{\vec{y}}(\vec{u}) x\right)\right)^{-1} \partial_{x_{j}}^{L}\left(w_{1}^{-1} \Phi_{\vec{y}}(\vec{u}) x\right) h_{t_{n}}\left(u_{n}\left|y_{n}\right|\right) \\
& \left.\times a(\vec{u}) \prod_{i=1}^{n-1} \min \left\{\frac{u_{i} \rho\left(y_{i}\right)}{\rho\left(\xi_{i}\right)}, \frac{\rho\left(\xi_{i}\right)}{u_{i} \rho\left(y_{i}\right)}\right\} \frac{d t_{n}}{t_{n}} d \vec{u} \right\rvert\, \lesssim 2^{C \varepsilon s} .
\end{aligned}
$$

Take a look at the terms depending on $t_{n}$ and observe that if we perform integration by parts in $u_{n}$, the boundary term which depends on $t_{n}$ is

$$
\left.\int_{0}^{\infty} g_{t_{n}}\left(w_{1}^{-1} \Phi_{\vec{y}}(\vec{u}) x\right)\right|_{u_{n}=t_{n} / \rho\left(y_{n}\right)} \frac{d t_{n}}{t_{n}}
$$

which is not bounded in $L^{\infty}(\mathbb{G})$ although $g_{t_{n}} \in L^{\infty}(\mathcal{H})$.

## 5. Weak $(1,1)$ estimate I: Reduction to a strong type estimate.

 We turn to the proof of Theorem 1.2. Let us begin with some definitions and notations. A left-invariant quasi-distance $d$ on $\mathbb{G}$ is defined by $d(x, y)=$ $\rho\left(x^{-1} y\right)$. A ball $J:=B\left(x_{J}, 2^{j}\right)$ with center $x_{J}$ and radius $2^{j}$ is a set of the form $J=\left\{x: d\left(x, x_{J}\right)<2^{j}\right\}$ for some $x_{J} \in \mathbb{G}$ and $j \in \mathbb{Z}$. For some $C>1$ (only depending on the constant $B_{0}$ in the quasi-triangle inequality $\left.\rho\left(x y^{-1}\right) \leq B_{0}[\rho(x)+\rho(y)]\right)$, denote by $J_{\triangle}$ the annulus $C J \backslash C^{-1} J$, where $r J:=\left\{x: d\left(x, x_{J}\right)<r 2^{j}\right\}$ for $r>0$. Moreover, let $K(x)=\Omega(x) \rho(x)^{-N}$, $h_{t}(x)=t^{-1} \rho(x) \chi_{\{\rho(x) \leq t\}}(x)$ and $K_{0}=K \chi_{A_{0}}$ with $A_{0}=\{x \in \mathbb{G}: 1 \leq$ $\rho(x) \leq 2\}$. We wish to show that$$
\left|\left\{x \in \mathbb{G}:\left(\int_{0}^{\infty}\left|f *\left(K h_{t}\right)(x)\right|^{2} \frac{d t}{t}\right)^{1 / 2}>\alpha\right\}\right| \lesssim \alpha^{-1}\|f\|_{L^{1}}\left\|K_{0}\right\|_{L \log L}
$$

We may assume that $f \in C_{0}^{\infty}$ and $\alpha=1,\left\|K_{0}\right\|_{L \log L}=1$ by linearity. We perform the standard Calderón-Zygmund decomposition of $f$ at height 1 to obtain $f=g+\sum_{J} b_{J}$, where $\|g\|_{L^{1}} \lesssim\|f\|_{L^{1}}$ and $\|g\|_{L^{\infty}} \lesssim \alpha=1$. The $J$ range over a collection of disjoint balls with $\sum_{J}|J| \lesssim\|f\|_{L^{1}}$ and for each $J$,

$$
\begin{equation*}
\operatorname{supp} b_{J} \subset C J \tag{5.1}
\end{equation*}
$$

and

$$
\begin{equation*}
\left\|b_{J}\right\|_{L^{1}(C J)} \lesssim|J|, \quad \int b_{J}=0 \tag{5.2}
\end{equation*}
$$

Since $f$ is smooth, we may arrange matters so that the $b_{J}$ are smooth. We decompose $K=\sum_{j \in \mathbb{Z}} S_{j} K_{0}$, where

$$
S_{j} K_{0}(x)=2^{-j} \int_{0}^{\infty} \varphi\left(2^{-j} s\right) s^{-N} K_{0}\left(s^{-1} \circ x\right) d s, \quad j \in \mathbb{Z}
$$

(See Section 2 for the definition of $\varphi$ ). In the following, we use $2^{j}$ to denote the radius of $J$, where $j=j(J)$ is an integer. Now we write

$$
\begin{aligned}
&\left(\int_{0}^{\infty}\left|f *\left(K h_{t}\right)(x)\right|^{2} \frac{d t}{t}\right)^{1 / 2} \\
& \leq\left|g *\left(K h_{(\cdot)}\right)(x)\right|_{\mathcal{H}}+\left|\sum_{s \leq C} \sum_{J} b_{J} *\left(h_{(\cdot)} S_{j+s} K_{0}\right)(x)\right|_{\mathcal{H}} \\
&+\left|\sum_{s>C} \sum_{J} b_{J} *\left(h_{(\cdot)} S_{j+s} K_{0}\right)(x)\right|_{\mathcal{H}} \\
&=: I_{1}+I_{2}+I_{3}
\end{aligned}
$$

For the first term, the $L^{2}$ boundedness of $g_{\Omega}$ (Theorem 1.1) and Chebyshev's inequality imply that

$$
\left|\left\{x: I_{1}>1\right\}\right| \leq\|g\|_{L^{2}(\mathbb{G})}^{2} \lesssim\|g\|_{L^{1}(\mathbb{G})} \lesssim\|f\|_{L^{1}(\mathbb{G})} .
$$

The second term is supported in $\bigcup_{J} C J$, thus

$$
\left|\left\{x: I_{2}>1\right\}\right| \leq\left|\bigcup_{J} C J\right| \leq \sum_{J}|C J| \lesssim\|f\|_{L^{1}(\mathbb{G})}
$$

To handle the remaining term, it suffices to show that

$$
\left|\left\{\sum_{s>C}\left(\int_{0}^{\infty}\left|\sum_{J} b_{J} *\left(h_{t} S_{j+s} K_{0}\right)(x)\right|^{2} \frac{d t}{t}\right)^{1 / 2}>1\right\}\right| \lesssim \sum_{J}|J|
$$

Note that $\operatorname{supp}\left(S_{j+s} K_{0}\right) \subset\left\{x \in \mathbb{G}: 2^{j+s-2} \leq \rho(x) \leq 2^{j+s+3}\right\}$. Hence, $b_{J} *\left(h_{t} S_{j+s} K_{0}\right)$ is supported on the annulus $\left(2^{s} J\right)_{\Delta}$ provided that $C$ in the above inequality is large enough (only depending on $B_{0}$ and $C$ in (5.1)). Take a suitable smooth cutoff function $\psi$ such that

$$
\operatorname{supp} \psi \subset\left\{x: C^{-1} / 2<\rho(x)<4 C\right\}
$$

and $\psi \equiv 1$ on $\left\{x: C^{-1}<\rho(x)<2 C\right\}$. Let $\psi_{J}^{s}(x)=\psi\left(2^{-j-s} \circ\left(x_{J}^{-1} x\right)\right)$. Then to finish the proof of Theorem 1.2, it suffices to show that

$$
\begin{equation*}
\left|\left\{\sum_{s>C}\left(\int_{0}^{\infty}\left|\sum_{J} \psi_{J}^{s}(x)\left(b_{J} *\left(h_{t} S_{j+s} K_{0}\right)(x)\right)\right|^{2} \frac{d t}{t}\right)^{1 / 2}>1\right\}\right| \lesssim \sum_{J}|J| . \tag{5.3}
\end{equation*}
$$

Below we show that (5.3) is a consequence of the following proposition:

Proposition 5.1. Suppose $s>C$ and $1<p<2$. Let $\mathcal{J}$ be a non-empty finite collection of disjoint balls such that

$$
\begin{equation*}
\sum_{J}|J| \lesssim 1 \tag{5.4}
\end{equation*}
$$

and

$$
\begin{equation*}
\left\|\sum_{J} \chi_{C 2^{s} J}\right\|_{L^{\infty}(\mathbb{G})} \lesssim 2^{N s} . \tag{5.5}
\end{equation*}
$$

Let $b_{J}$ be a collection of smooth functions satisfying (5.2) and let $\psi_{J}=\psi_{J}^{s}$. Then

$$
\begin{equation*}
\left\|\sum_{J} \psi_{J}\left(b_{J} *\left(h_{t} S_{j+s} F_{J}\right)\right)\right\|_{L^{p}(\mathcal{H})} \lesssim 2^{-\varepsilon s}\left(\sum_{J}|J|\left\|F_{J}\right\|_{L^{2}(\mathbb{G})}^{2}\right)^{1 / 2} \tag{5.6}
\end{equation*}
$$

for all functions $F_{J}$ in $L^{2}(\mathbb{G})$.
The proof of Proposition 5.1 will be postponed until Section 6 . Now let us complete the proof of (5.3) by applying Proposition 5.1. We need the following

Lemma 5.2 ([T, Lemma 9.2]). Let $B \subset B(0, C)$ be any Euclidean ball of radius at least $2^{-\varepsilon s}$, and define the functions $\psi_{J, B}$ by

$$
\psi_{J, B}(x)=\psi_{B}\left(2^{-j-s} \circ\left(x_{J}^{-1} x\right)\right)
$$

where $\psi_{B}$ is any bump function adapted to $B$ (this means that $0 \leq \psi_{B} \leq 1$, $\psi_{B} \in C^{\infty}$ with $\operatorname{supp} \psi_{B} \subset 2 B$ and $\psi_{B} \equiv 1$ on $\left.B\right)$. Then

$$
\left|\left\{\sum_{J} \psi_{J, B}(x)>s^{3} 2^{N s}|B|\right\}\right| \lesssim 2^{-\varepsilon s^{2}}
$$

Applying Lemma 5.2 with a ball of size roughly 1 and a nonnegative cutoff, we obtain

$$
\left|\left\{\sum_{J} \chi_{C 2^{s} J}>s^{3} 2^{N s}|B|\right\}\right| \lesssim 2^{-\varepsilon s^{2}} .
$$

Then we use a sieving argument of Córdoba (see [Cor, p. 11]). For any ball $J \in \mathcal{J}$, define the height $h(J)$ to be the number

$$
h(J)=\#\left\{J^{\prime} \in \mathcal{J}: 2 J \subset 2 J^{\prime}\right\}
$$

where $\# E$ denotes the cardinality of the set $E$.
Define the exceptional set $E_{s}$ by

$$
E_{s}=\bigcup_{h(J) \geq s^{3} 2^{N s}} J
$$

Then $\left|E_{s}\right| \lesssim 2^{-\varepsilon s}$. For each $a=0,1, \ldots, s^{3}-1$, the collection of balls with height between $a 2^{N s}$ and $(a+1) 2^{N s}$ (denoted by $J_{a}$ ) satisfies (5.6), and by
$s^{3}$ applications of (5.5) and the triangle inequality, we obtain

$$
\begin{equation*}
\left\|\sum_{J} \psi_{J}\left(b_{J} *\left(h_{t} S_{j+s} F_{J}\right)\right)\right\|_{L^{p}\left(E_{s}^{c}, \mathcal{H}\right)} \lesssim 2^{-\varepsilon s}\left(\sum_{J}|J|\left\|F_{J}\right\|_{L^{2}(\mathbb{G})}^{2}\right)^{1 / 2} \tag{5.7}
\end{equation*}
$$

for all functions $F_{J}$ in $L^{2}(\mathcal{H})$ (see $[\mathrm{T}]$ ).
We adapt Tao's argument in [T]. By dilation invariance, it suffices to verify (5.3) in the case when $\sum_{J}|J| \sim 1$. In particular, we may assume that (5.4) holds.

For each $s>C$ we decompose $K_{0}$ as $K_{0}=K^{\leq s}+K^{>s}$, where $K^{\leq s}(x)=$ $K_{0}(x) \chi_{\left\{\left|K_{0}\right| इ^{\varepsilon s / 2}\right\}}(x)$. It suffices to show

$$
\begin{align*}
& \left|\left\{\sum_{s>C}\left(\int_{0}^{\infty}\left|\sum_{J} \psi_{J}\left(b_{J} *\left(h_{t} S_{j+s} K^{>s}\right)\right)\right|^{2} \frac{d t}{t}\right)^{1 / 2} \gtrsim 1\right\}\right| \lesssim 1  \tag{5.8}\\
& \left|\left\{\sum_{s>C}\left(\int_{0}^{\infty}\left|\sum_{J} \psi_{J}\left(b_{J} *\left(h_{t} S_{j+s} K^{\leq s}\right)\right)\right|^{2} \frac{d t}{t}\right)^{1 / 2} \gtrsim 1\right\}\right| \lesssim 1
\end{align*}
$$

By Lemma 2.1, (2.5) and (5.2), we have

$$
\begin{aligned}
\left\|\psi_{J}\left(b_{J} *\left(h_{t} S_{j+s} K^{>s}\right)\right)\right\|_{L^{1}(\mathcal{H})} & \lesssim\left\|b_{J}\right\|_{L^{1}(\mathbb{G})}\left\|h_{t} S_{j+s} K^{>s}\right\|_{L^{1}(\mathcal{H})} \\
& \lesssim|J|\left\|K^{>s}\right\|_{L^{1}(\mathbb{G})}
\end{aligned}
$$

Note that

$$
\sum_{s>C}\left\|K^{>s}\right\|_{L^{1}(\mathbb{G})} \lesssim\left\|K_{0}\right\|_{L \log L(\mathbb{G})} \lesssim 1
$$

Then by (5.4) and the triangle inequality,

$$
\sum_{s>C}\left\|\sum_{J} \psi_{J}\left(b_{J} *\left(h_{t} S_{j+s} K^{>s}\right)\right)\right\|_{L^{1}(\mathcal{H})} \lesssim \sum_{j>C}|J|\left\|K^{>s}\right\|_{L^{1}(\mathbb{G})} \lesssim 1
$$

which implies (5.8) by Chebyshev's inequality.
As for (5.9), applying the estimate (5.7) with $F_{J}=K^{\leq s}$ for all $J$, we have, for each $s$,

$$
\begin{aligned}
\left\|\left\|\left.\sum_{J} \psi_{J}\left(b_{J} *\left(h_{t} S_{j+s} K^{\leq s}\right)\right)\right|_{\mathcal{H}}\right\|_{L^{p}\left(E_{s}^{c}\right)}\right. & \lesssim 2^{-\varepsilon s}\left(\sum_{J}|J|\left\|K^{\leq s}\right\|_{L^{2}(\mathbb{G})}^{2}\right)^{1 / 2} \\
& \lesssim 2^{-\varepsilon s / 2}
\end{aligned}
$$

Summing this over $s>C$ yields

$$
\left\|\sum_{s>C}\left(\int_{0}^{\infty}\left|\sum_{J} \psi_{J}\left(b_{J} *\left(h_{t} S_{j+s} K^{\leq s}\right)\right)\right|^{2} \frac{d t}{t}\right)^{1 / 2}\right\|_{L^{p}\left(\left(\bigcup_{s>C} E_{s}\right)^{c}\right)} \lesssim 1
$$

Thus (5.9) follows from Chebyshev's inequality and the fact $\left|\bigcup_{s>C} E_{s}\right| \lesssim 1$. This completes the derivation of (5.3) from Proposition 5.1.
6. Weak $(1,1)$ estimate II: Proof of Proposition 5.1 (I). The following sections are devoted to proving Proposition 5.1. To get (5.6), by duality, it suffices to show

$$
\left(\sum_{J}|J|^{-1}\left\|\int_{0}^{\infty} S_{j+s}^{*}\left[\left(\tilde{b}_{J}\right) *\left(\psi_{J} g_{t}\right) h_{t}\right] \frac{d t}{t}\right\|_{L^{2}(\mathbb{G})}^{2}\right)^{1 / 2} \lesssim 2^{-\varepsilon s}\left\|g_{t}\right\|_{L^{p^{\prime}}(\mathcal{H})}
$$

for all test functions $g_{t} \in L^{p^{\prime}}(\mathcal{H})$, where $S_{j+s}^{*}$ denotes the adjoint of $S_{j+s}$ and $\tilde{b}_{J}(x)=b_{J}(-x)$. By the $T T^{*}$ method, we need to show

$$
\begin{array}{r}
\left\|\sum_{J}|J|^{-1} \psi_{J}\left(b_{J} * S_{j+s}\left[\int_{0}^{\infty} S_{j+s}^{*}\left(\left[\tilde{b}_{J} *\left(\psi_{J} g_{t_{1}}\right)\right] h_{t_{1}}\right) \frac{d t_{1}}{t_{1}} h_{t_{2}}\right]\right)\right\|_{L^{p}(\mathcal{H})}  \tag{6.1}\\
\lesssim 2^{-\varepsilon s}\left\|g_{t}\right\|_{L^{p^{\prime}}(\mathcal{H})} .
\end{array}
$$

Define the self-adjoint operators $T_{J}$ and $T$ by

$$
T_{J} f_{t}(x)=\frac{b_{J}}{|J|} *\left(S_{0}\left(\int_{0}^{\infty} S_{0}^{*}\left[\left(\tilde{b}_{J} * f_{t_{1}}\right) h_{t_{1}}\right] \frac{d t_{1}}{t_{1}}\right) h_{t_{2}}\right)(x)
$$

and $T=2^{-N s} \sum_{J} \psi_{J} T_{J} \psi_{J}$, respectively, where $\psi_{J}$ denotes the multiplier defined by

$$
\psi_{J} f(x):=\psi_{J}(x) f(x) .
$$

Then the desired estimate (6.1) takes the form

$$
\begin{equation*}
\left\|T f_{t}\right\|_{L^{p}(\mathcal{H})} \lesssim 2^{-\varepsilon s}\left\|f_{t}\right\|_{L^{p^{\prime}}(\mathcal{H})} \tag{6.2}
\end{equation*}
$$

since $S_{j+s} S_{j+s}^{*}=2^{-N(s+j)} S_{0} S_{0}^{*}$. Let $d_{J}: B(0, C) \rightarrow C J$ denote the map

$$
\begin{equation*}
d_{J}(v)=x_{J}\left(2^{j} \circ v\right) . \tag{6.3}
\end{equation*}
$$

Define the smooth functions $c_{J}$ supported on the ball $B(0, C)$ by $c_{J}(v)=$ $|J|^{-1} b_{J}\left(d_{J}(v)\right)$. Then by (5.2),

$$
\left\|c_{J}\right\|_{L^{1}(B(0, C))} \lesssim 1 \quad \text { and } \quad \int_{B(0, C)} c_{J}=0 .
$$

Note that

$$
S_{0} S_{0}^{*} F(x)=\int \bar{\varphi}(u) F(u \circ x) d u
$$

where $\bar{\varphi}(u)=\int \varphi(v) \varphi(u v) v^{-(N-1)} d v$ is a bump function adapted to $\{u \sim 1\}$. Then $T_{J}$ takes the form

$$
\begin{aligned}
T_{J} F_{t_{1}}\left(t_{2}, x\right)=\iiint \int & c_{J}(v) \bar{\varphi}(u) c_{J}(w) F_{t_{1}}\left(d_{J}(w) u \circ\left(d_{J}(v)^{-1} x\right)\right) \\
& \times h_{t_{1}}\left(u \circ\left(d_{J}(v)^{-1} x\right)\right) h_{t_{2}}\left(d_{J}(v)^{-1} x\right) d v d u d w \frac{d t_{1}}{t_{1}} .
\end{aligned}
$$

We need to define a slightly larger and noncancellative version of $T_{J}$. For each $J$, let $\psi_{J}^{+}$be a slight enlargement of $\psi_{J}$ which is positive on the support
of $\psi_{J}$. Also, applying Lemma 4.1, we may find functions $c_{J}^{1}, \ldots, c_{J}^{n}$ supported on $B(0, C)$ such that

$$
\begin{equation*}
c_{J}=\sum_{i=1}^{n} \partial_{x_{i}} c_{J}^{i}, \quad\left\|c_{J}^{i}\right\|_{L^{1}(\mathbb{G})} \lesssim 1 . \tag{6.4}
\end{equation*}
$$

Define $c_{J}^{+}=\left|c_{J}\right|+\sum_{i=1}^{n}\left|c_{J}^{i}\right|$. Then $c_{J}^{+}$is a nonnegative function on $B(0, C)$ with

$$
\begin{equation*}
\left\|c_{J}^{+}\right\|_{L^{1}(\mathbb{G})} \lesssim 1 . \tag{6.5}
\end{equation*}
$$

Finally, we choose $\varphi^{+}$to be any enlargement of $\bar{\varphi}$ which is strictly positive on the support of $\bar{\varphi}$, and satisfies $\varphi^{+}(u)=\varphi^{+}\left(u^{-1}\right) u^{2-N}$. We then define the self-adjoint operator $T_{J}^{+}$by

$$
\begin{aligned}
T_{J}^{+} F_{t_{1}}\left(t_{2}, x\right)=\iiint & c_{J}^{+}(v) \varphi^{+}(u) c_{J}^{+}(w) F_{t_{1}}\left(d_{J}(w) u \circ\left(d_{J}(v)^{-1} x\right)\right) \\
& \times h_{t_{1}}\left(u \circ\left(d_{J}(v)^{-1} x\right)\right) h_{t_{2}}\left(d_{J}(v)^{-1} x\right) d v d u d w \frac{d t_{1}}{t_{1}},
\end{aligned}
$$

and

$$
T^{+}=2^{-N s} \sum_{J} \psi_{J}^{+} T_{J}^{+} \psi_{J}^{+}
$$

where $\psi_{J}^{+}$denotes the multiplier defined by $\psi_{J}^{+} f(x):=\psi_{J}^{+}(x) f(x)$. Clearly, for all $J$ and non-negative $F$, we have the pointwise bounds

$$
\begin{equation*}
T_{J} F_{t_{1}}\left(t_{2}, x\right) \leq T_{J}^{+} F_{t_{1}}\left(t_{2}, x\right) \quad \text { and } \quad T F_{t_{1}}\left(t_{2}, x\right) \leq T^{+} F_{t_{1}}\left(t_{2}, x\right) \tag{6.6}
\end{equation*}
$$

Before estimating (6.2), we first show

$$
\begin{equation*}
\left\|T^{+} F_{t}\right\|_{L^{p}(\mathcal{H})} \lesssim\left\|F_{t}\right\|_{L^{q}(\mathcal{H})} \quad \text { for all } 1 \leq p \leq q \leq \infty . \tag{6.7}
\end{equation*}
$$

By interpolation and duality, it suffices to verify (6.7) for $q=\infty$. By Hölder's inequality and (5.5), we have

$$
\begin{aligned}
& \left\|\sum_{J} \psi_{J}^{+} T_{J}^{+} \psi^{+} F_{t_{1}}\right\|_{L^{p}(\mathcal{H})}=\left\|\left(\int_{0}^{\infty}\left|\sum_{J}\left(\psi_{J}^{+} T_{J}^{+} \psi^{+} F_{t_{1}}\right)\left(t_{2}, \cdot\right)\right|^{2} \frac{d t_{2}}{t_{2}}\right)^{1 / 2}\right\|_{L^{p}(\mathbb{G})} \\
& \leq\left\|\sum_{J}\left|\psi_{J}^{+}\right|\left(\int_{0}^{\infty}\left|\left(T_{J}^{+} \psi^{+} F_{t_{1}}\right)\left(t_{2}, \cdot\right)\right|^{2} \frac{d t_{2}}{t_{2}}\right)^{1 / 2}\right\|_{L^{p}(\mathbb{G})} \\
& \lesssim\left\|\left(\sum_{J}\left|\chi_{C 2^{s} J}\right|\right)^{1 / p^{\prime}}\right\|_{L^{\infty}(\mathbb{G})}\left\|\left\{\sum_{J}\left(\int_{0}^{\infty}\left|\left(T_{J}^{+} \psi^{+} F_{t_{1}}\right)\left(t_{2}, \cdot\right)\right|^{2} \frac{d t_{2}}{t_{2}}\right)^{p / 2}\right\}^{1 / p}\right\|_{L^{p}(\mathbb{G})} \\
& \lesssim 2^{N s / p^{\prime}}\left(\sum_{J}\left\|T_{J}^{+} \psi_{J}^{+} F_{t_{1}}\right\|_{L^{p}(\mathcal{H})}^{p}\right)^{1 / p} .
\end{aligned}
$$

By Hölder's and Minkowski's inequalities, using $\sum|J| \lesssim 1$ and (5.5) we get

$$
\begin{aligned}
& \sum_{J}\left\|T_{J}^{+} \psi_{J}^{+} F_{t}\right\|_{L^{p}(\mathcal{H})}^{p} \lesssim\left\|F_{t_{1}}\right\|_{L^{\infty}(\mathcal{H})}^{p} \sum_{J} \| \iiint c_{J}^{+}(v) \varphi^{+}(u) c_{J}^{+}(w) \\
& \times \psi_{J}^{+}\left(d_{J}(w) u \circ\left(d_{J}(v)^{-1} x\right)\right) d v d u d w \|_{L^{p}(\mathbb{G}, d x)}^{p} \\
& \lesssim\left\|F_{t_{1}}\right\|_{L^{\infty}(\mathcal{H})}^{p} \sum_{J}\left\|\psi_{J}^{+}\right\|_{L^{p}(\mathbb{G})}^{p} \lesssim 2^{N s}\left\|F_{t_{1}}\right\|_{L^{\infty}(\mathcal{H})}^{p}
\end{aligned}
$$

Now combining these two estimates yields (6.7).
To finish the proof of Theorem 1.2 , we must obtain an attenuation factor $2^{-2 \varepsilon s}$ for (6.2). To this end, we want to iterate $T m+1$ times with $m=2^{2 n-3}$, as in the $L^{2}$ case. But symmetry considerations require iterating one more time, i.e., iterating $m+2$ times is sufficient for our purpose (see Remark 6.3 below). Now we turn to the details.

Below we show that, to get (6.2), it suffices to prove

$$
\begin{equation*}
\left\|T^{m+2} F_{t}\right\|_{L^{p}(\mathcal{H})} \lesssim 2^{-\varepsilon s}\left\|F_{t}\right\|_{L^{p^{\prime}}(\mathcal{H})} \tag{6.8}
\end{equation*}
$$

for $1 \leq p<2$ and some $\varepsilon>0$. Indeed, by (6.8) and $m-2$-fold application of (6.7) for $q=p$ and replacing $T^{+}$by $T$ (see (6.6)), we get

$$
\begin{equation*}
\left\|T^{2 m} F_{t}\right\|_{L^{p}(\mathcal{H})} \lesssim\left\|T^{m+2} F_{t}\right\|_{L^{p}(\mathcal{H})} \lesssim 2^{-\varepsilon s}\left\|F_{t}\right\|_{L^{p^{\prime}}(\mathcal{H})} \tag{6.9}
\end{equation*}
$$

By the $T T^{*}$ method and the self-adjointness of $T$, it is easy to see that (6.9) implies

$$
\begin{equation*}
\left\|T^{m} F_{t}\right\|_{L^{p}(\mathcal{H})} \lesssim 2^{-\varepsilon^{\prime} s}\left\|F_{t}\right\|_{L^{2}(\mathcal{H})} \tag{6.10}
\end{equation*}
$$

for some $\varepsilon^{\prime}>0$. On the other hand, by repeated application of (6.7) and (6.6),

$$
\begin{equation*}
\left\|T^{m} F_{t}\right\|_{L^{p}(\mathcal{H})} \lesssim\left\|F_{t}\right\|_{L^{q}(\mathcal{H})} \quad \text { for all } q \geq p \geq 1 \tag{6.11}
\end{equation*}
$$

By interpolation between (6.10) and (6.11), we thus obtain

$$
\begin{equation*}
\left\|T^{m} F_{t}\right\|_{L^{p}(\mathcal{H})} \lesssim 2^{-\varepsilon^{\prime \prime} s}\left\|F_{t}\right\|_{L^{p^{\prime}}(\mathcal{H})} \tag{6.12}
\end{equation*}
$$

for some small $\varepsilon^{\prime \prime}>0$. Iterating this argument $2^{2 n-4}-1$ times we thus obtain

$$
\left\|T^{2} F_{t}\right\|_{L^{p}(\mathcal{H})} \lesssim 2^{-\theta s}\left\|F_{t}\right\|_{L^{p^{\prime}}(\mathcal{H})}
$$

for some $\theta>0$, and (6.2) follows from this easily (see the process of deriving (6.12) from (6.9)).

Thus, we only need to show (6.8). Applying (6.7) $m+2$ times for $p=$ $q=2$, we see that $T^{m+2}$ is bounded on $L^{2}(\mathcal{H})$. By interpolation and duality, it suffices to prove (6.8) for $p=1$. By expanding $T^{m}$, we thus only need to
show that

$$
\begin{equation*}
\left\|2^{-N m s} \sum_{J_{1}, \ldots, J_{m} \in \mathcal{J}} T\left(\bigotimes_{i=1}^{m} \psi_{J_{i}} T_{J_{i}} \psi_{J_{i}}\right) T F_{t_{m}}\right\|_{L^{1}(\mathcal{H})} \lesssim 2^{-\varepsilon s}\left\|F_{t_{m}}\right\|_{L^{\infty}(\mathcal{H})} \tag{6.13}
\end{equation*}
$$

here, $\bigotimes_{i=1}^{m} Q_{i}$ denotes the composition of the operators $Q_{1}, \ldots, Q_{m}$, defined by $\bigotimes_{i=1}^{m} Q_{i}(f):=Q_{m}\left(\cdots\left(Q_{2}\left(Q_{1} f\right)\right) \cdots\right)$. The balls $\left\{J_{1}, \ldots, J_{m}\right\}$ may have different sizes. We shall extract a subsequence of $n$ ball, whose sizes increase monotonically. First we need the following definition:

Definition 6.1. Let $\mathbf{J}=\left(J_{1}, \ldots, J_{m}\right)$ be an $m$-tuple of balls $(m \geq n)$ and $\mathbf{k}=\left\{k_{1}, \ldots, k_{n}\right\}$ be a strictly increasing $n$-tuple of integers in $\{1, \ldots, m\}$. We say that $\mathbf{J}$ is ascending with respect to $\mathbf{k}$ if

$$
j_{k_{q}} \leq j_{l} \quad \text { for all } k_{q} \leq l \leq k_{n}
$$

we then write $\mathbf{J} \nearrow \mathbf{k}$. Similarly, we say that $\mathbf{J}$ is descending with respect to k if

$$
j_{k_{q}} \leq j_{l} \quad \text { for all } k_{1} \leq l \leq k_{q}
$$

and write $\mathbf{J} \searrow \mathbf{k}$, where $2^{j_{i}}$ is the radius of $J_{i}(i=1, \ldots, m)$.
The following lemma is due to Tao.
Lemma 6.2 ([T, Lemma 10.2]). If $m=2^{2 n-3}$ and $\mathbf{J} \in \mathcal{J}^{m}$, then there exists a sequence $\mathbf{k}$ such that either $\mathbf{J} \nearrow \mathbf{k}$ or $\mathbf{J} \searrow \mathbf{k}$.

For all $\mathbf{k}=\left\{k_{1}, \ldots, k_{n}\right\} \subset\{1, \ldots, m\}$, we say $\mathbf{k}<\mathbf{k}^{\prime}$ if $k_{1}<k_{1}^{\prime}$, or $k_{j}=k_{j}^{\prime}$ for $j=1, \ldots, i-1$, but $k_{i}<k_{i}^{\prime}(i=2, \ldots, n)$. This defines an order on $\mathbf{k}$. Thus, when $m=2^{2 n-3}$, for all $\mathbf{J} \in \mathcal{J}^{m}$ we can choose a largest sequence $\mathbf{k}:=\mathbf{k}_{\max }(\mathbf{J})$ with respect to this order so that either $\mathbf{J} \nearrow \mathbf{k}$ or $\mathbf{J} \searrow \mathbf{k}$. Clearly, Lemma 6.2 implies that $\mathbf{k}_{\max }(\mathbf{J})$ is well-defined. Since the number of choices of $\mathbf{k}$ is finite, it suffices to show that

$$
\begin{align*}
& 2^{-N m s}\left\|_{\substack{\mathbf{J}=\left(J_{1}, \ldots, J_{m}\right) \in \mathcal{J}^{m} \\
\mathbf{k}_{\max }(\mathbf{J})=\mathbf{k}}} T\left(\bigotimes_{i=1}^{m} \psi_{J_{i}} T_{J_{i}} \psi_{J_{i}}\right) T F_{t_{m}}\right\|_{L^{1}(\mathcal{H})}  \tag{6.14}\\
& \lesssim 2^{-\varepsilon s}\left\|F_{t_{m}}\right\|_{L^{\infty}(\mathcal{H})}
\end{align*}
$$

for each $\mathbf{k}$.
Fix k. Using the following discussion we can reduce to the case when $k_{1}=1$ and $k_{n}=m$. Since

$$
\mathbf{k}_{\max }\left(J_{1}, \ldots, J_{m}\right)=\mathbf{k}
$$

is independent of the choices of $J_{i}$ for $k_{n}<i \leq m$, we may write

$$
\mathbf{k}_{\max }\left(J_{1}, \ldots, J_{k_{n}}\right)=\mathbf{k} \quad \text { instead of } \quad \mathbf{k}_{\max }\left(J_{1}, \ldots, J_{m}\right)=\mathbf{k}
$$

Then the left hand side of (6.14) can be rewritten as

$$
2^{-N\left(m-k_{n}\right) s}\left\|_{\substack{J_{1}, \ldots, J_{k_{n}} \in \mathcal{J} \\ \mathbf{k}_{\max }\left(J_{1}, \ldots, J_{k_{n}}\right)=\mathbf{k}}} T\left(\bigotimes_{i=1}^{k_{n}} \psi_{J_{i}} T_{J_{i}} \psi_{J_{i}}\right) T T^{m-k_{n}} F_{t_{m}}\right\|_{L^{1}(\mathcal{H})} .
$$

By (6.7), $T$ is bounded on $L^{\infty}(\mathcal{H})$, and it is sufficient to show that

$$
\begin{aligned}
& 2^{-N\left(m-k_{n}\right) s} \| \sum_{\substack{J_{1}, \ldots, J_{k_{n}} \in \mathcal{J} \\
\mathbf{k}_{\max }\left(J_{1}, \ldots, J_{k_{n}}\right)=\mathbf{k}}} T\left(\bigotimes_{i=1}^{k_{n}} \psi_{J_{i}} T_{J_{i}} \psi_{J_{i}}\right) T F_{t_{m}} \|_{L^{1}(\mathcal{H})} \\
& \lesssim 2^{-\varepsilon s}\left\|F_{t_{m}}\right\|_{L^{\infty}(\mathcal{H})}
\end{aligned}
$$

Using a similar argument to the above, the desired estimate can be further reduced to

$$
\begin{array}{r}
2^{-N\left(k_{n}-k_{1}+1\right) s}\left\|T^{k_{1}-1} \sum_{\substack{J_{k_{1}}, \ldots, J_{k_{n}} \in \mathcal{J} \\
\mathbf{k}_{\max }\left(J_{k_{1}}, \ldots, J_{k_{n}}\right)=\mathbf{k}}} T\left(\bigotimes_{i=k_{1}}^{k_{n}} \psi_{J_{i}} T_{J_{i}} \psi_{J_{i}}\right) T F_{t_{m}}\right\|_{L^{1}(\mathcal{H})} \\
\lesssim 2^{-\varepsilon s}\left\|F_{t_{m}}\right\|_{L^{\infty}(\mathcal{H})}
\end{array}
$$

The left hand side is majorized by

$$
2^{-N\left(k_{n}-k_{1}+1\right) s}\left\|\left(T^{+}\right)^{k_{1}-1} \sum_{\substack{J_{k_{1}}, \ldots, J_{k_{n}} \in \mathcal{J} \\ \mathbf{J} / \mathbf{k} \text { or } \mathbf{J} \backslash \mathbf{k}}}\left|T\left(\bigotimes_{i=k_{1}}^{k_{n}} \psi_{J_{i}} T_{J_{i}} \psi_{J_{i}}\right) T F_{t_{m}}\right|\right\|_{L^{1}(\mathcal{H})} .
$$

By (6.7), $T^{+}$is bounded on $L^{1}(\mathcal{H})$, so we may discard the $\left(T^{+}\right)^{k_{1}-1}$ operator. Relabelling $\mathbf{J}$ and $\mathbf{k}$, and reducing $m$ to $k_{n}-k_{1}+1$, we only need to show that

$$
\begin{equation*}
\left\|2^{-N m s} \sum_{\substack{J_{1}, \ldots, J_{m} \in \mathcal{J} \\ \mathbf{J} / \not \mathbf{k} \text { or } \mathbf{J} \backslash \mathbf{k}}}\left|T\left(\bigotimes_{i=1}^{m} \psi_{J_{i}} T_{J_{i}} \psi_{J_{i}}\right) T F_{t_{m}}\right|\right\|_{L^{1}(\mathcal{H})} . \tag{6.15}
\end{equation*}
$$

for all $n \leq m \leq 2^{2 n-3}$ and all $\mathbf{k}$ with $k_{1}=1$ and $k_{n}=m$.
REMARK 6.3. Recall that in the estimates of the $L^{2}$ case, we iterate $L$ $n+1$ times (see Section 3) because of an extra integral in the variable $t$. Here we need to iterate $T m+2$ times in (6.8) in order to guarantee that the left hand side of (6.15) is symmetric in the sense that the case $\mathbf{J} \nearrow \mathbf{k}$ is dual to $\mathbf{J} \searrow \mathbf{k}$. Thus we only need to prove (6.15) for $\mathbf{J} \nearrow \mathbf{k}$.

Below we prove (6.15) for $\mathbf{J} \nearrow \mathbf{k}$. Since $T$ is bounded on $L^{\infty}(\mathcal{H})$, it suffices to show

$$
\begin{equation*}
\left\|2^{-N m s} \sum_{J_{1}, \ldots, J_{m} \in \mathcal{J}: \mathbf{J} / \mathbf{k}}\left|T\left(\bigotimes_{i=1}^{m} \psi_{J_{i}} T_{J_{i}} \psi_{J_{i}}\right) F_{t_{m}}\right|\right\|_{L^{1}(\mathcal{H})} \lesssim 2^{-\varepsilon s}\left\|F_{t_{m}}\right\|_{L^{\infty}(\mathcal{H})} \tag{6.16}
\end{equation*}
$$

for all $n \leq m \leq 2^{2 n-3}$ and all $\mathbf{k}$ such that $k_{1}=1, k_{n}=m$.
Next, we shall remove the $t$ integral in the $\mathcal{H}$ norm on the left hand side of (6.16). Then the problem reduces to estimating a scalar-valued integral. To be more precise, we will use the following conclusion:

Lemma 6.4.

$$
\begin{equation*}
\left\|T^{+} F_{t_{0}}\right\|_{L^{1}(\mathcal{H})} \lesssim \sup _{J \in \mathcal{J}, w \in B(0, C)}\left\|\int_{0}^{\infty} h_{t_{0}}\left(\left|d_{J}(w)^{-1} \cdot\right|\right) F_{t_{0}} \psi_{J}^{+} \frac{d t_{0}}{t_{0}}\right\|_{L^{1}(\mathbb{G})} \tag{6.17}
\end{equation*}
$$

Proof. We first show that (6.17) is a consequence of (5.5) and the inequality

$$
\begin{equation*}
\left\|\left(T_{J}^{+} \psi_{J}^{+} F_{t_{0}}\right)(\cdot, \cdot)\right\|_{L^{1}(\mathcal{H})} \lesssim \sup _{w \in B(0, C)}\left\|\int_{0}^{\infty} h_{t_{0}}\left(d_{J}(w)^{-1} \cdot\right) \psi_{J}^{+} F_{t_{0}} \frac{d t_{0}}{t_{0}}\right\|_{L^{1}(\mathbb{G})} . \tag{6.18}
\end{equation*}
$$

In fact, the above estimate together with (5.5) yields

$$
\begin{aligned}
\| T^{+} & F_{t_{0}} \|_{L^{1}(\mathcal{H})} \lesssim 2^{-N s}\left(\sum_{J}\left\|\psi_{J}^{+}\right\|_{L^{\infty}(\mathbb{G})} \cdot\left\|T_{J}^{+}\left(\psi_{J}^{+} F_{t_{0}}\right)\right\|_{L^{1}(\mathcal{H})}\right) \\
& \lesssim 2^{-N s} \sum_{J}\left\|\chi_{C^{s} s}\right\|_{L^{\infty}(\mathbb{G})} \sup _{w \in B(0, C)}\left\|\int_{0}^{\infty} h_{t_{0}}\left(\left|d_{J}(w)^{-1} \cdot\right|\right) F_{t_{0}} \psi_{J}^{+} \frac{d t_{0}}{t_{0}}\right\|_{L^{1}(\mathbb{G})} \\
& \lesssim \sup _{J \in \mathcal{J}, w \in B(0, C)}\left\|\int_{0}^{\infty} h_{t_{0}}\left(\left|d_{J}(w)^{-1} \cdot\right|\right) F_{t_{0}} \psi_{J}^{+} \frac{d t_{0}}{t_{0}}\right\|_{L^{1}(\mathbb{G})} .
\end{aligned}
$$

Let us turn to the proof of (6.18). For any $G_{s} \in L^{\infty}(\mathcal{H})$ with $\left\|G_{s}\right\|_{L^{\infty}(\mathcal{H})}$ $\leq 1$, we write $\left|\left\langle\left(T_{J}^{+} \psi_{J}^{+} F_{t_{0}}\right)(\cdot, s), G(\cdot, s)\right\rangle_{L^{1}(\mathcal{H})}\right|$ as

$$
\begin{aligned}
& \mid \iiint \int c_{J}^{+}(v) \varphi^{+}(u) c_{J}^{+}(w)\left\langle F_{t_{0}}\left(d_{J}(w) u \circ\left(d_{J}(v)^{-1} x\right)\right), h_{t_{0}}\left(u \circ\left(d_{J}(v)^{-1} x\right)\right)\right\rangle_{\mathcal{H}} \\
& \quad \times \psi_{J}^{+}\left(d_{J}(w) u \circ\left(d_{J}(v)^{-1} x\right)\right)\left\langle h_{s}\left(d_{J}(v)^{-1} x\right), G_{s}(x)\right\rangle_{\mathcal{H}} d x d u d v d w \mid .
\end{aligned}
$$

Now we use the change of variables $x=d_{J}(v) \frac{1}{u} \circ\left(d_{J}(w)^{-1} y\right.$ ) (so $d x=$ $u^{-N} d y$ ) and $u \sim 1$ to deduce

$$
\begin{aligned}
& \left|\left\langle\left(T_{J}^{+} \psi_{J}^{+} F_{t_{0}}\right)(\cdot, s), G(\cdot, s)\right\rangle_{L^{1}(\mathcal{H})}\right| \\
& \quad \lesssim \mid \iiint \int c_{J}^{+}(v) \varphi^{+}(u) c_{J}^{+}(w) \psi_{J}^{+}(y)\left\langle F_{t_{0}}(y), h_{t_{0}}\left(d_{J}(w)^{-1} y\right)\right\rangle_{\mathcal{H}} \\
& \left.\quad \times\left\langle h_{s}\left(\frac{1}{u} \circ\left(d_{J}(w)^{-1} y\right)\right), G_{s}\left(d_{J}(v) \frac{1}{u} \circ\left(d_{J}(w)^{-1} y\right)\right)\right\rangle_{\mathcal{H}} d y d u d v d w \right\rvert\,
\end{aligned}
$$

$$
\begin{aligned}
& \lesssim \iiint \int c_{J}^{+}(v) \varphi^{+}(u) c_{J}^{+}(w) \psi_{J}^{+}(y) \mid\left\langle F_{t_{0}}(y),\right. \\
& \left., h_{t_{0}}\left(d_{J}(w)^{-1} y\right)\right\rangle\left._{\mathcal{H}}\right|^{\prime} \\
& \\
& \times\left\|h_{s}\right\|_{L^{\infty}(\mathcal{H})}\left\|G_{s}\right\|_{L^{\infty}(\mathcal{H})} d y d u d v d w \\
& \lesssim \sup _{w \in B(0, C)}\left\|\left\langle h_{t_{0}}\left(d_{J}(w)^{-1} \cdot\right), \psi_{J}^{+} F_{t_{0}}\right\rangle_{\mathcal{H}}\right\|_{L^{1}(\mathbb{G})}\left\|c_{J}^{+}\right\|_{L^{1}(\mathbb{G})}^{2}\left\|\psi^{+}\right\|_{L^{\infty}(\mathbb{G})}\left\|\varphi^{+}\right\|_{L^{1}(\mathbb{G})} \\
& \lesssim \sup _{w \in B(0, C)}\left\|\int_{0}^{\infty} h_{t_{0}}\left(d_{J}(w)^{-1} \cdot\right) \psi_{J}^{+} F_{t_{0}} \frac{d t_{0}}{t_{0}}\right\|_{L^{1}(\mathbb{G})}
\end{aligned}
$$

where (6.5) is used in the last inequality. By duality, we finally obtain (6.18).

REmARK 6.5. From the pointwise inequality (6.6), we see that Lemma 6.4 still holds on replacing $T^{+}$by $T$.

Applying Lemma 6.4 to the function

$$
F\left(t_{0}, \cdot\right)=\left[\left(\bigotimes_{i=1}^{m} \psi_{J_{i}} T_{J_{i}} \psi_{J_{i}}\right) F_{t_{m}}\right]\left(t_{0}, \cdot\right)
$$

and $J=J_{0}$, we see that to show (6.16), it suffices to verify

$$
\begin{array}{r}
2^{-N m s} \sum_{\mathbf{J} \in \mathcal{J}^{m}: \mathbf{J} / \mathbf{k}}\left\|\left\langle\left[\left(\bigotimes_{i=1}^{m} \psi_{J_{i}} T_{J_{i}} \psi_{J_{i}}\right) F_{t_{m}}\right]\left(t_{0}, \cdot\right) \psi_{J_{0}}^{+}(\cdot), h_{t_{0}}\left(d_{J_{0}}\left(w_{0}\right)^{-1} \cdot\right)\right\rangle_{\mathcal{H}}\right\|_{L^{1}(\mathbb{G})}  \tag{6.19}\\
\lesssim 2^{-\varepsilon s}\left\|F_{t_{m}}\right\|_{L^{\infty}(\mathcal{H})}
\end{array}
$$

uniformly in $J_{0}$ and $w_{0} \in B(0, C)$ for all $n \leq m \leq 2^{2 n-3}$ and all $\mathbf{k}$ with $k_{1}=1$ and $k_{n}=m$.

Fix $m$ and $\mathbf{k}$. By duality, it suffices to prove that the quantity

$$
\begin{equation*}
\sum_{\mathbf{J} / \mathbf{k}}\left|\left\langle\int_{0}^{\infty}\left[\left(\bigotimes_{i=1}^{m} \psi_{J_{i}} T_{J_{i}} \psi_{J_{i}}\right) F_{t_{m}}\right]\left(t_{0}, \cdot\right) h_{t_{0}}\left(d_{J_{0}}\left(w_{0}\right)^{-1} \cdot\right) \psi_{J_{0}}^{+} \frac{d t_{0}}{t_{0}}, G\right\rangle\right| \tag{6.20}
\end{equation*}
$$

is $\lesssim 2^{-\varepsilon s} 2^{N m s}$ for all functions $F_{t}$ in the unit ball of $L^{\infty}(\mathcal{H})$ and $G$ in the unit ball of $L^{\infty}(\mathbb{G})$.

For each $\mathbf{J} \in \mathcal{J}^{m}$ and $\mathbf{J} \nearrow \mathbf{k}$, we expand the inner product in (6.20) as

$$
\begin{array}{r}
\int \cdots \int F_{t_{m}}\left(x_{m}\right) G\left(x_{0}\right) \psi_{J_{0}}^{+}\left(x_{0}\right) \prod_{i=1}^{m}\left(\psi_{J_{i}}\left(x_{i-1}\right) c_{J_{i}}\left(v_{i}\right) \bar{\varphi}\left(u_{i}\right) c_{J_{i}}\left(w_{i}\right) \psi_{J_{i}}\left(x_{i}\right)\right) \\
\times \\
\times \prod_{j=0}^{m-1} R_{j} h_{t_{m}}\left(u_{m} \circ\left(d_{J_{m}}\left(v_{m}\right)^{-1} x_{m-1}\right)\right) \frac{d t_{m}}{t_{m}} d \vec{w} d \vec{u} d \vec{v} d x_{0}
\end{array}
$$

where $\vec{v}=\left(v_{1}, \ldots, v_{m}\right), \vec{w}=\left(w_{1}, \ldots, w_{m}\right)$ range over $B(0, C)^{m}$, and $\vec{u}=$ $\left(u_{1}, \ldots, u_{m}\right)$ ranges over $\left[C^{-1}, C\right]^{m}, d \vec{w}=\prod_{i=1}^{m} d w_{i}, d \vec{v}=\prod_{i=1}^{m} d v_{i}, x_{0}$
ranges over $\mathbb{G}$, and $x_{1}, \ldots, x_{m}$ are defined recursively by

$$
\begin{equation*}
x_{i}=d_{J_{i}}\left(w_{i}\right)\left(u_{i} \circ\left(d_{J_{i}}\left(v_{i}\right)^{-1} x_{i-1}\right)\right) \quad \text { for } i=1, \ldots, m \tag{6.21}
\end{equation*}
$$

Moreover, $R_{j}(j=0, \ldots, m-1)$ is defined by

$$
R_{0}:=\min \left\{\frac{\rho\left(d_{J_{1}}\left(v_{1}\right)^{-1} x_{0}\right)}{\rho\left(d_{J_{0}}\left(w_{0}\right)^{-1} x_{0}\right)}, \frac{\rho\left(d_{J_{0}}\left(w_{0}\right)^{-1} x_{0}\right)}{\rho\left(d_{J_{1}}\left(v_{1}\right)^{-1} x_{0}\right)}\right\}
$$

and

$$
R_{j}:=\min \left\{\frac{\rho\left(u_{j} \circ\left(d_{J_{j}}\left(v_{j}\right)^{-1} x_{j-1}\right)\right)}{\rho\left(d_{J_{j+1}}\left(v_{j+1}\right)^{-1} x_{j}\right)}, \frac{\rho\left(d_{J_{j+1}}\left(v_{j+1}\right)^{-1} x_{j}\right)}{\rho\left(u_{j} \circ\left(d_{J_{j}}\left(v_{j}\right)^{-1} x_{j-1}\right)\right)}\right\}
$$

for $j=1, \ldots, m-1$.
We define new variables $\vec{\tau}=\left(\tau_{1}, \ldots, \tau_{n}\right)$ by $\tau_{q}=u_{k_{q}}$ and $y=v_{1}$, since only these variables are actively used below. As in the proof of Theorem 1.1, we shall decompose the $\mathbf{J} \nearrow \mathbf{k}$ portion of (6.20) into

$$
\begin{align*}
\sum_{\mathbf{J} \in \mathcal{J}^{m}: \mathbf{J} / \mathbf{k}} \mid \int \cdots \int & F_{t_{m}}\left(x_{m}\right) G\left(x_{0}\right) \psi_{J_{0}}^{+}\left(x_{0}\right) \prod_{i=1}^{m}\left(\psi_{J_{i}}\left(x_{i-1}\right) c_{J_{i}}\left(v_{i}\right) \bar{\varphi}\left(u_{i}\right)\right.  \tag{6.22}\\
& \left.\times c_{J_{i}}\left(w_{i}\right) \psi_{J_{i}}\left(x_{i}\right)\right) \prod_{j=0}^{m-1} R_{j} \eta\left(2^{\delta s} 2^{-M_{n}} \operatorname{det} D_{\vec{\tau}}^{L}\left(x_{m}\right)\right) \\
& \left.\times h_{t_{m}}\left(u_{m} \circ\left(d_{J_{m}}\left(v_{m}\right)^{-1} x_{m-1}\right)\right) \frac{d t_{m}}{t_{m}} d \vec{w} d \vec{u} d \vec{v} d x_{0} \right\rvert\,
\end{align*}
$$

and

$$
\begin{align*}
\sum_{\mathbf{J} \in \mathcal{J}^{m}: \mathbf{J} / \mathbf{k}} \mid \int & \cdots \int F_{t_{m}}\left(x_{m}\right) G\left(x_{0}\right) \psi_{J_{0}}^{+}\left(x_{0}\right) \prod_{i=1}^{m}\left(\psi_{J_{i}}\left(x_{i-1}\right) c_{J_{i}}\left(v_{i}\right) \bar{\varphi}\left(u_{i}\right)\right.  \tag{6.23}\\
& \left.\times c_{J_{i}}\left(w_{i}\right) \psi_{J_{i}}\left(x_{i}\right)\right) \prod_{j=0}^{m-1} R_{j}\left[1-\eta\left(2^{\delta s} 2^{-M_{n}} \operatorname{det} D_{\vec{\tau}}^{L}\left(x_{m}\right)\right)\right] \\
& \left.\times h_{t_{m}}\left(u_{m} \circ\left(d_{J_{m}}\left(v_{m}\right)^{-1} x_{m-1}\right)\right) \frac{d t_{m}}{t_{m}} d \vec{w} d \vec{u} d \vec{v} d x_{0} \right\rvert\,
\end{align*}
$$

where $M_{n}=\sum_{i=1}^{n} \alpha_{i}\left(j_{k_{i}}+s\right)$ (recall that $2^{j_{k_{i}}}$ is the radius of $\left.J_{k_{i}}\right)$ and $\delta>0$ is a small constant to be chosen later, and $\eta$ is a bump function which equals 1 near the identity.

The degenerate portion (6.22), as in the $L^{2}$ case, can be majorized by the corresponding portion of the singular integral. Thus it suffices to verify that the nondegenerate portion $(6.23) \lesssim 2^{-\varepsilon s} 2^{N m s}$.
7. Weak $(1,1)$ estimate III: Nondegenerate portion of the integral. To finish the proof of Proposition 5.1, we only need to show (6.24). Define

$$
\tilde{T}_{J}^{+} F(x)=\iiint c_{J}^{+}(v) \varphi^{+}(u) c_{J}^{+}(w) F\left(d_{J}(w) u \circ\left(d_{J}(v)^{-1} x\right)\right) d w d u d v
$$

and

$$
\tilde{T}^{+}=2^{-N s} \sum_{J} \psi_{J}^{+} \tilde{T}_{J}^{+} \psi_{J}^{+}
$$

where $c_{J}^{+}$and $\varphi^{+}$are as in the definition of $T_{J}^{+}$in Section 6. In $[\mathrm{T}]$, the following estimate is proved:

$$
\begin{equation*}
\left\|\tilde{T}^{+} F\right\|_{L^{p}(\mathbb{G})} \lesssim\|F\|_{L^{q}(\mathbb{G})} \quad \text { for all } 1 \leq p \leq q \leq \infty \tag{7.1}
\end{equation*}
$$

Therefore, to show (6.24), it is sufficient to show that

$$
\begin{aligned}
\sum_{\mathbf{J} \in \mathcal{J}^{m}: \mathbf{J} / \mathbf{k}} \mid \int \cdots \int F_{t_{m}}\left(x_{m}\right) & G\left(x_{0}\right) \psi_{J_{0}}^{+}\left(x_{0}\right) \prod_{i=1}^{m}\left(\psi_{J_{i}}\left(x_{i-1}\right) c_{J_{i}}\left(v_{i}\right) \bar{\varphi}\left(u_{i}\right) c_{J_{i}}\left(w_{i}\right)\right. \\
& \left.\times \psi_{J_{i}}\left(x_{i}\right)\right) \prod_{j=0}^{m-1} R_{j}\left(1-\eta\left(2^{\delta s} 2^{-M_{n}} \operatorname{det} D_{\vec{\tau}}^{L}\left(x_{m}\right)\right)\right) \\
& \left.\times h_{t_{m}}\left(u_{m} \circ\left(d_{J_{m}}\left(v_{m}\right)^{-1} x_{m-1}\right)\right) \frac{d t_{m}}{t_{m}} d \vec{w} d \vec{u} d \vec{v} d x_{0} \right\rvert\, \\
\lesssim & 2^{-\varepsilon s} 2^{N m s}\left\langle\left(\tilde{T}^{+}\right)^{m} 1,1\right\rangle .
\end{aligned}
$$

By expanding out $\tilde{T}^{+}$, we rewrite the above estimate as

$$
\begin{align*}
& \mid \int \cdots \int F_{t_{m}}\left(x_{m}\right) G\left(x_{0}\right) \psi_{J_{0}}^{+}\left(x_{0}\right) \prod_{i=1}^{m}\left(\psi_{J_{i}}\left(x_{i-1}\right) c_{J_{i}}\left(v_{i}\right) \bar{\varphi}\left(u_{i}\right) c_{J_{i}}\left(w_{i}\right)\right.  \tag{7.2}\\
& \left.\quad \times \psi_{J_{i}}\left(x_{i}\right)\right) \prod_{j=0}^{m-1} R_{j} h_{t_{m}}\left(u_{m} \circ\left(d_{J_{m}}\left(v_{m}\right)^{-1} x_{m-1}\right)\right) \\
& \left.\quad \times\left(1-\eta\left(2^{\delta s} 2^{-M_{n}} \operatorname{det} D_{\vec{\tau}}^{L}\left(x_{m}\right)\right)\right) \frac{d t_{m}}{t_{m}} d \vec{w} d \vec{u} d \vec{v} d x_{0} \right\rvert\, \\
& \quad \lesssim 2^{-\varepsilon s} \iiint \int \prod_{i=1}^{m} \psi_{J_{i}}^{+}\left(x_{i-1}\right) c_{J_{i}}^{+}\left(v_{i}\right) \varphi^{+}\left(u_{i}\right) c_{J_{i}}^{+}\left(w_{i}\right) \psi_{J_{i}}^{+}\left(x_{i}\right) d x_{0} d \vec{w} d \vec{u} d \vec{v} .
\end{align*}
$$

Fix all the frozen variables. Removing all the factors in the above expression which do not depend on the variables $y:=v_{1}$ and $\vec{\tau}$, we reduce (7.2) to

$$
\begin{align*}
& \iint G\left(x_{0}\right)\left(\int_{0}^{\infty} F_{t_{m}}\left(x_{m}\right) h_{t_{m}}\left(u_{m} \circ\left(d_{J_{m}}\left(v_{m}\right)^{-1} x_{m-1}\right)\right) \frac{d t_{m}}{t_{m}}\right) c_{J_{1}}(y)  \tag{7.3}\\
& \quad \times a(y, \vec{\tau})\left(\prod_{i=0}^{m-1} R_{i}\right)\left(1-\eta\left(2^{\delta s} 2^{-M_{n}} \operatorname{det} D_{\vec{\tau}}^{L}\left(x_{m}\right)\right)\right) d y d \vec{\tau} \\
& \quad \lesssim 2^{-\varepsilon s} \iint c_{J_{1}}^{+}\left(v_{1}\right) a^{+}(y, \vec{\tau}) d y d \vec{\tau}
\end{align*}
$$

where

$$
\begin{aligned}
a(y, \vec{\tau}) & =\prod_{l=1}^{m} \psi_{J_{l}}\left(x_{l-1}\right) \psi_{J_{l}}\left(x_{l}\right)\left(1-\eta\left(2^{\delta s} 2^{-M_{n}} \operatorname{det} D_{\overrightarrow{\tilde{\tau}}}^{L}\left(x_{m}\right)\right)\right) \prod_{q=1}^{n} \bar{\varphi}\left(\vec{\tau}_{q}\right) \psi_{J_{0}}^{+}\left(x_{0}\right) \\
a^{+}(y, \vec{\tau}) & =\prod_{l=1}^{m} \psi_{J_{l}}^{+}\left(x_{l-1}\right) \psi_{J_{l}}^{+}\left(x_{l}\right) \prod_{q=1}^{n} \varphi^{+}\left(\vec{\tau}_{q}\right)
\end{aligned}
$$

Since $d_{J_{m}}\left(w_{m}\right)$ is independent of $y$ and $\vec{\tau}$, we may set

$$
\begin{aligned}
f\left(x_{m}\right) & =\int_{0}^{\infty} F_{t_{m}}\left(x_{m}\right) h_{t_{m}}\left(u_{m} \circ\left(d_{J_{m}}\left(v_{m}\right)^{-1} x_{m-1}\right)\right) \frac{d t_{m}}{t_{m}} \\
& =\int_{0}^{\infty} F_{t_{m}}\left(x_{m}\right) h_{t_{m}}\left(d_{J_{m}}\left(w_{m}\right)^{-1} x_{m}\right) \frac{d t_{m}}{t_{m}}
\end{aligned}
$$

By Cauchy-Schwarz's inequality, we can easily see $\|f\|_{L^{\infty}(\mathbb{G})} \leq 1$.
To show (7.3), by (6.4) and integration by parts, it suffices to verify that

$$
\begin{align*}
I_{1}+I_{2}+I_{3}:= & \left|\iint c_{J_{1}}^{i}(y) \partial_{y_{i}} f\left(x_{m}\right) a(y, \vec{\tau}) \prod_{\varsigma=0}^{m-1} R_{\varsigma} d y d \vec{\tau}\right|  \tag{7.4}\\
& +\left|\iint c_{J_{1}}^{i}(y) f\left(x_{m}\right) \partial_{y_{i}} a(y, \vec{\tau}) \prod_{\varsigma=0}^{m-1} R_{\varsigma} d y d \vec{\tau}\right| \\
& +\left|\iint c_{J_{1}}^{i}(y) f\left(x_{m}\right) a(y, \vec{\tau})\left(\partial_{y_{i}} \prod_{\varsigma=0}^{m-1} R_{\varsigma}\right) d y d \vec{\tau}\right| \\
\lesssim & 2^{-\varepsilon s} \iint c_{J_{1}}^{+}\left(v_{1}\right) a^{+}(y, \vec{\tau}) d y d \vec{\tau}
\end{align*}
$$

for each $i=1, \ldots, n$. The desired estimate for $I_{2}$ follows from Lemma 13.1 in $[\mathrm{T}]$ and the obvious bound $\prod_{\varsigma=0}^{m-1} R_{\varsigma} \leq 1$. To estimate $I_{1}$ and $I_{3}$, the estimates for the derivatives of homogeneous norms are required.

We give an explicit estimate for the Euclidean derivative of the homogeneous norm which is new on general homogeneous groups.

Theorem 7.1. The homogeneous norm $\rho$ satisfies the estimate

$$
\begin{equation*}
\left|\partial_{x_{i}} \rho(x)\right| \lesssim \rho(x)^{-\alpha_{i}+1} \tag{7.5}
\end{equation*}
$$

where $\alpha_{i}$ is given by (1.3).

Proof. The homogeneity of $\rho$ implies that

$$
\rho\left(r^{\alpha_{1}} x_{1}, \ldots, r^{\alpha_{n}} x_{n}\right)=r \rho\left(x_{1}, \ldots, x_{n}\right)
$$

Taking the derivative in $x_{i}$, we have

$$
r^{\alpha_{i}} \partial_{x_{i}} \rho(r \circ x)=r \partial_{x_{i}} \rho(x),
$$

which shows that $\partial x_{i} \rho(x)$ is homogeneous of order $-\alpha_{i}+1$. Since the homogeneous norm is $C^{\infty}$ away from the origin (see [FoSt]), we know that $\partial_{x_{i}} \rho(x) \lesssim 1$ for $x \in \Sigma$. Then (7.5) follows by a dilation argument.

Using the above theorem, we next show the following
LEMMA 7.2. For $y=v_{1}$ and $x_{\varsigma-1}(\varsigma=1, \ldots, m)$ defined by (6.21), the following estimates hold:

$$
\begin{align*}
& \left|\partial_{y_{i}}\left[\rho\left(d_{J_{\varsigma}}\left(v_{\varsigma}\right)^{-1} x_{\varsigma-1}\right)\right]\right| \lesssim 2^{-\varepsilon s} \rho\left(d_{J_{\varsigma}}\left(v_{\varsigma}\right)^{-1} x_{\varsigma-1}\right)  \tag{a}\\
& \quad \text { for } \varsigma=1, \ldots, m \text { and } i=1, \ldots, n
\end{align*}
$$

$$
\begin{align*}
& \left|\partial_{\vec{\tau}_{q}}\left[\rho\left(d_{J_{\varsigma}}\left(v_{\varsigma}\right)^{-1} x_{\varsigma-1}\right)\right]\right| \lesssim \rho\left(d_{J_{\varsigma}}\left(v_{\varsigma}\right)^{-1} x_{\varsigma-1}\right)  \tag{b}\\
& \quad \text { for } \varsigma=1, \ldots, m \text { and } q=1, \ldots, n .
\end{align*}
$$

Proof. Since $x_{\varsigma-1} \in\left(2^{s} J_{\varsigma}\right)_{\Delta}$, we see that

$$
\rho\left(d_{J_{\varsigma}}\left(v_{\varsigma}\right)^{-1} x_{\varsigma-1}\right) \approx 2^{s+j_{\varsigma}} .
$$

For (a), we only need to show that

$$
\begin{equation*}
\left|\partial_{y_{i}}\left[\left(d_{J_{\varsigma}}\left(v_{\varsigma}\right)^{-1} x_{\varsigma-1}\right)_{k}\right]\right| \lesssim 2^{-\varepsilon s} 2^{\left(s+j_{\varsigma}\right) \alpha_{k}} \tag{7.6}
\end{equation*}
$$

where $(x)_{k}$ denotes the $k$ th component of $x \in \mathbb{R}^{n}$. Indeed, let

$$
z=\left(d_{J_{\varsigma}}\left(v_{\varsigma}\right)^{-1} \cdot x_{\varsigma-1}\right)
$$

Since $\rho$ is regular, by the chain rule, this estimate together with (7.5) yields

$$
\left|\partial_{y_{i}}\left[\rho\left(d_{J_{\varsigma}}\left(v_{\varsigma}\right)^{-1} x_{\varsigma-1}\right)\right]\right|=\left|\sum_{m=1}^{n} \frac{\partial \rho(z)}{\partial z_{m}} \frac{\partial z_{m}}{y_{i}}\right| \lesssim 2^{-\varepsilon s} 2^{s+j_{\varsigma}}
$$

which gives (a). Now we prove the inequality (7.6). Since

$$
\left|2^{-s-j_{\varsigma}} \circ\left(d_{J_{\varsigma}}\left(v_{\varsigma}\right)^{-1} x_{\varsigma-1}\right)\right| \sim \rho\left(2^{-s-j_{\varsigma}} \circ\left(d_{J_{\varsigma}}\left(v_{\varsigma}\right)^{-1} x_{\varsigma-1}\right)\right) \lesssim 1
$$

by Lemma 4.3(a), we have

$$
\left|\partial_{y_{i}}\left(2^{-s-j_{\varsigma}} \circ\left(d_{J_{\varsigma}}\left(v_{\varsigma}\right)^{-1} x_{\varsigma-1}\right)\right)\right| \sim\left|\partial_{y_{i}}^{L}\left(2^{-s-j_{\varsigma}} \circ\left(d_{J_{\varsigma}}\left(v_{\varsigma}\right)^{-1} x_{\varsigma-1}\right)\right)\right| .
$$

Applying Lemma 4.3(b), (g), we get

$$
\begin{aligned}
\left|\partial_{y_{i}}^{L}\left(2^{-s-j_{\varsigma}} \circ\left(d_{J_{\varsigma}}\left(v_{\varsigma}\right)^{-1} x_{\varsigma-1}\right)\right)\right| & =\left|\partial_{y_{i}}^{L}\left(\left(2^{-s-j_{\varsigma}} u_{\varsigma-1}\right) \circ\left(d_{J_{\varsigma-1}}\left(v_{\varsigma-1}\right)^{-1} x_{\varsigma-2}\right)\right)\right| \\
& =\cdots \\
& =\left|\partial_{y_{i}}^{L}\left(\left(2^{-s-j_{\varsigma}} u_{\varsigma-1} \ldots u_{1}\right) \circ\left(d_{J_{1}}(y)^{-1} x_{0}\right)\right)\right|
\end{aligned}
$$

Using the fact $j_{1} \leq j_{\varsigma}$ arising from $\mathbf{J} \nearrow \mathbf{k}$ and $u_{l} \sim 1$ for $l=1, \ldots, m$, and then applying Lemma 4.3(b), (c), (d), we have

$$
\begin{aligned}
\left|\partial_{y_{i}}\left(2^{-s-j_{\varsigma}} \circ\left(d_{J_{\varsigma}}\left(v_{\varsigma}\right)^{-1} x_{\varsigma-1}\right)\right)\right| & \lesssim\left|\partial_{y_{i}}^{L}\left(2^{-s-j_{\varsigma}} \circ\left(d_{J_{1}}(y)^{-1} x_{0}\right)\right)\right| \\
& \lesssim\left|\partial_{y_{i}}^{L}\left(2^{-s-j_{1}} \circ\left(d_{J_{1}}(y)^{-1} x_{0}\right)\right)\right| \\
& \lesssim\left|C\left[2^{-j_{1}-s} \circ\left(x_{J_{1}}^{-1} x_{0}\right)\right]\left(2^{-s} \circ \partial_{y_{i}}^{L}\left(y^{-1}\right)\right)\right| \\
& \lesssim\left|\left(2^{-s} \circ \partial_{y_{i}}^{L}\left(y^{-1}\right)\right)\right| \lesssim 2^{-\alpha_{1} s},
\end{aligned}
$$

where we use $d_{J_{1}}(y)^{-1}=\left(2^{j_{1}} \circ y^{-1}\right) x_{J}^{-1}$ in the third inequality, and in the last inequality we use the fact that $y^{-1}$ depends on $y$ polynomially. Hence, by (1.3),

$$
\begin{aligned}
2^{-\left(s+j_{\varsigma}\right) \alpha_{k}}\left|\partial_{y_{i}}\left(d_{J_{\varsigma}}\left(v_{\varsigma}\right)^{-1} x_{\varsigma-1}\right)_{(k)}\right| & =\left|\partial_{y_{i}}\left(2^{-\left(s+j_{\varsigma}\right) \alpha_{k}}\left(d_{J_{\varsigma}}\left(v_{\varsigma}\right)^{-1} x_{\varsigma-1}\right)\right)_{(k)}\right| \\
& \leq\left|\partial_{y_{i}}\left(2^{-s-j_{i}} \circ\left(d_{J_{\varsigma}}\left(v_{\varsigma}\right)^{-1} x_{\varsigma-1}\right)\right)\right| \leq 2^{-\alpha_{1} s},
\end{aligned}
$$

which implies (7.6) .
The proof of (b) is similar. We may assume that $k_{q} \leq \varsigma$ (otherwise (b) is trivial). By the chain rule, it suffices to show

$$
\begin{equation*}
\left|\partial_{\vec{\tau}_{q}}\left[\left(d_{J_{\varsigma}}\left(v_{\varsigma}\right)^{-1} x_{\varsigma-1}\right)_{k}\right]\right| \lesssim 2^{\left(s+j_{\varsigma}\right) \alpha_{k}} \tag{7.7}
\end{equation*}
$$

Using Lemma 4.3(a), (b), (g), (e), we have

$$
\begin{aligned}
\left|\partial_{\vec{\tau}_{q}}\left(2^{-s-j_{\varsigma}} \circ\left(d_{J_{\varsigma}}\left(v_{\varsigma}\right)^{-1} x_{\varsigma-1}\right)\right)\right| & \sim\left|\partial_{\tilde{\tau}_{q}}^{L}\left(2^{-s-j_{\varsigma}} \circ\left(d_{J_{\varsigma}}\left(v_{\varsigma}\right)^{-1} x_{\varsigma-1}\right)\right)\right| \\
& \sim\left|\partial_{\vec{\tau}_{q}}^{L}\left(2^{-s-j_{\varsigma}} \circ\left(\vec{\tau}_{q} \circ d_{J_{q}}\left(v_{q}\right)^{-1} x_{q-1}\right)\right)\right| \\
& \lesssim\left|\left.\right|_{q} ^{-1}\left(\vec{\tau}_{q} \circ X\left[2^{-s-j_{q}} \circ\left(d_{J_{q}}\left(v_{q}\right)^{-1} x_{q-1}\right)\right]\right)\right| \\
& \sim\left|X\left[2^{-s-j_{q}} \circ\left(d_{J_{q}}\left(v_{q}\right)^{-1} x_{q-1}\right)\right]\right| \\
& \sim \rho\left(2^{-s-j_{q}} \circ\left(d_{J_{q}}\left(v_{q}\right)^{-1} x_{q-1}\right)\right) \lesssim 1,
\end{aligned}
$$

which, by (1.3), implies (7.7).
Let us continue to estimate $I_{1}$ and $I_{3}$ in (7.4). We consider $I_{3}$ first. To begin, we prove that

$$
\begin{equation*}
\left|\partial_{y_{i}}\left(R_{\varsigma}\right)\right| \lesssim 2^{-\varepsilon s} \quad \text { for } i=1, \ldots, n \text { and } \varsigma=0,1, \ldots, m-1 . \tag{7.8}
\end{equation*}
$$

When $\varsigma=0$, if $\rho\left(d_{J_{1}}\left(v_{1}\right)^{-1} x_{0}\right) \leq \rho\left(d_{J_{0}}\left(w_{0}\right)^{-1} x_{0}\right)$, then by Lemma 7.2(a),

$$
\left|\partial_{y_{i}}\left(R_{0}\right)\right| \lesssim \frac{\left|\partial_{y_{i}}\left[\rho\left(d_{J_{1}}\left(v_{1}\right)^{-1} x_{0}\right)\right]\right|}{\rho\left(d_{J_{0}}\left(w_{0}\right)^{-1} x_{0}\right)} \lesssim 2^{-\varepsilon s} .
$$

If $\rho\left(d_{J_{0}}\left(w_{0}\right)^{-1} x_{0}\right) \leq \rho\left(d_{J_{1}}\left(v_{1}\right)^{-1} x_{0}\right)$, the proof is similar.

Next we estimate $\partial_{y_{i}}\left(R_{\varsigma}\right)$ for $\varsigma=1, \ldots, m-1$. If $\rho\left(u_{\varsigma} \circ\left(d_{J_{\varsigma}}\left(v_{\varsigma}\right)^{-1} x_{\varsigma-1}\right)\right) \leq$ $\rho\left(d_{J_{\varsigma+1}}\left(v_{\varsigma+1}\right)^{-1} x_{\varsigma}\right)$, then by Lemma $7.2(\mathrm{a})$, we have

$$
\begin{aligned}
\left|\partial_{y_{i}}\left(R_{\varsigma}\right)\right| \leq & \left|\frac{\partial_{y_{i}}\left[\rho\left(u_{\varsigma} \circ\left(d_{J_{\varsigma}}\left(v_{\varsigma}\right)^{-1} x_{\varsigma-1}\right)\right)\right] \rho\left(d_{J_{\varsigma+1}}\left(v_{\varsigma+1}\right)^{-1} x_{\varsigma}\right)}{\rho\left(d_{J_{\varsigma+1}}\left(v_{\varsigma+1}\right)^{-1} x_{\varsigma}\right)^{2}}\right| \\
& +\left|\frac{\rho\left(u_{\varsigma} \circ\left(d_{J_{\varsigma}}\left(v_{\varsigma}\right)^{-1} x_{\varsigma-1}\right)\right) \partial_{y_{i}}\left[\rho\left(d_{J_{\varsigma+1}}\left(v_{\varsigma+1}\right)^{-1} x_{\varsigma}\right)\right]}{\rho\left(d_{J_{\varsigma+1}}\left(v_{\varsigma+1}\right)^{-1} x_{\varsigma}\right)^{2}}\right| \\
& \lesssim \frac{\left|\partial_{y_{i}}\left[\rho\left(u_{\varsigma} \circ\left(d_{J_{\varsigma}}\left(v_{\varsigma}\right)^{-1} x_{\varsigma-1}\right)\right)\right]\right|+\left|\partial_{y_{i}}\left[\rho\left(d_{J_{\varsigma+1}}\left(v_{\varsigma+1}\right)^{-1} x_{\varsigma}\right)\right]\right|}{\rho\left(d_{J_{\varsigma+1}}\left(v_{\varsigma+1}\right)^{-1} x_{\varsigma}\right)} \lesssim 2^{-\varepsilon s} .
\end{aligned}
$$

The case when $\rho\left(d_{J_{\varsigma+1}}\left(v_{\varsigma+1}\right)^{-1} x_{\varsigma}\right) \leq \rho\left(u_{\varsigma} \circ\left(d_{J_{\varsigma}}\left(v_{\varsigma}\right)^{-1} x_{\varsigma-1}\right)\right)$ can be treated similarly. Thus (7.8) is proved. From (7.8) and $R_{\varsigma} \leq 1(\varsigma=0, \ldots, m-1)$, we have

$$
\begin{equation*}
\left|\partial_{y_{i}} \prod_{\varsigma=0}^{m-1} R_{\varsigma}\right| \lesssim 2^{-\varepsilon s} \tag{7.9}
\end{equation*}
$$

From (7.9) and $\|f\|_{L^{\infty}(\mathbb{G})} \leq 1$, the estimate for $I_{3}$ follows easily.
Finally, we estimate $I_{1}$. It suffices to show that

$$
\begin{equation*}
\left|\int \partial_{y_{i}} f\left(x_{m}\right) a(y, \vec{\tau}) \prod_{\varsigma=0}^{m-1} R_{\varsigma} d \vec{\tau}\right| \lesssim 2^{-\varepsilon s} \int a^{+}(y, \vec{\tau}) d \vec{\tau} \tag{7.10}
\end{equation*}
$$

uniformly in $y$. Fix $y$. By Lemma 4.2, we can rewrite the left hand side as

$$
\left|\int \nabla_{\vec{\tau}} f\left(x_{m}\right) \cdot\left(D_{\vec{\tau}}^{L} x_{m}\right)^{-1} \partial_{y_{i}}^{L} x_{m} a(y, \vec{\tau}) \prod_{\varsigma=0}^{m-1} R_{\varsigma} d \vec{\tau}\right|
$$

Integrating by parts, we see that this is equal to

$$
\left|\int f\left(x_{m}\right) \nabla_{\vec{\tau}} \cdot\left(\left(D_{\vec{\tau}}^{L} x_{m}\right)^{-1} \partial_{y_{i}}^{L} x_{m} a(y, \vec{\tau}) \prod_{\varsigma=0}^{m-1} R_{\varsigma}\right) d \vec{\tau}\right| .
$$

Thus to show (7.10), it suffices to prove the pointwise bound

$$
\left\|\left(1+\nabla_{\vec{\tau}}\right)\left(\prod_{\varsigma=0}^{m-1} R_{\varsigma}\right)\right\|\left\|\left(1+\nabla_{\vec{\tau}}\right)\left(\left(D_{\vec{\tau}}^{L} x_{m}\right)^{-1} \partial_{y_{i}}^{L} x_{m} a(y, \vec{\tau})\right)\right\| \lesssim 2^{-\varepsilon s} a^{+}(y, \vec{\tau}),
$$

where $\|(1+\nabla) f\|:=|\nabla f|+|f|$. The estimate

$$
\left\|\left(1+\nabla_{\vec{\tau}}\right)\left(\left(D_{\vec{\tau}}^{L} x_{m}\right)^{-1} \partial_{y_{i}}^{L} x_{m} a(y, \vec{\tau})\right)\right\| \lesssim 2^{-\varepsilon s} a^{+}(y, \vec{\tau})
$$

is shown in [T, p. 1583]. Thus it suffices to show

$$
\left\|\left(1+\nabla_{\vec{\tau}}\right)\left(\prod_{\varsigma=0}^{m-1} R_{\varsigma}\right)\right\| \lesssim 1
$$

From the obvious fact $\left|R_{\varsigma}\right| \lesssim 1$, we reduce the proof to

$$
\begin{equation*}
\left|\partial_{\tau_{q}}\left(R_{\varsigma}\right)\right| \lesssim 1 \tag{7.11}
\end{equation*}
$$

for each $\varsigma=0, \ldots, m-1$ and $q=1, \ldots, n$.
We first estimate $\partial_{\tau_{q}}\left(R_{0}\right)$. If $\rho\left(d_{J_{1}}\left(v_{1}\right)^{-1} x_{0}\right) \leq \rho\left(d_{J_{0}}\left(w_{0}\right)^{-1} x_{0}\right)$, then by Lemma 7.2(b), we get

$$
\left|\partial_{\tau_{q}}\left(R_{0}\right)\right|=\frac{\left|\partial_{\tau_{q}}\left[\rho\left(d_{J_{1}}\left(v_{1}\right)^{-1} x_{0}\right)\right]\right|}{\rho\left(d_{J_{0}}\left(w_{0}\right)^{-1} x_{0}\right)} \lesssim 1 .
$$

If $\rho\left(d_{J_{0}}\left(w_{0}\right)^{-1} x_{0}\right) \leq \rho\left(d_{J_{1}}\left(v_{1}\right)^{-1} x_{0}\right)$, the estimate is similar.
Next we estimate $\partial_{\tau_{q}}\left(R_{\varsigma}\right)$ for $\varsigma=1, \ldots, m-1$. If $\rho\left(u_{\varsigma} \circ\left(d_{J_{\varsigma}}\left(v_{\varsigma}\right)^{-1} x_{\varsigma-1}\right)\right) \leq$ $\rho\left(d_{J_{\varsigma}+1}\left(v_{\varsigma}+1\right)^{-1} x_{\varsigma}\right)$, then by Lemma $7.2(\mathrm{~b})$, we have

$$
\left.\begin{align*}
&\left|\partial_{\tau_{q}}\left(R_{\varsigma}\right)\right| \leq\left.\left.\left\lvert\, \frac{\partial_{\tau_{q}}\left[\rho\left(u_{\varsigma} \circ\left(d_{J_{\varsigma}}\left(v_{\varsigma}\right)^{-1} x_{\varsigma-1}\right)\right)\right] \rho\left(d _ { J _ { \varsigma + 1 } } \left(v_{\varsigma}+1\right.\right.}{}\right.\right)^{-1} x_{\varsigma}\right)  \tag{7.12}\\
& \rho\left(d_{\varsigma_{\varsigma+1}}\left(v_{\varsigma+1}\right)^{-1} x_{\varsigma}\right)^{2}
\end{align*} \right\rvert\,
$$

The case $\rho\left(d_{J_{\varsigma}+1}\left(v_{\varsigma+1}\right)^{-1} x_{\varsigma}\right) \leq \rho\left(u_{\varsigma} \circ\left(d_{J_{\varsigma}}\left(v_{\varsigma}\right)^{-1} x_{\varsigma}-1\right)\right)$ can be verified in a similar way. Thus (7.11) is proved. This ends the proof of Proposition 5.1 and, therefore, Theorem 1.2.

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