

Determinant systems

by

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The purpose of this paper is to explain the algebraical structure of the theory of determinants in Banach spaces. This theory was developed recently in papers [1-10].

In the determinant theory of the linear equation

$$Ax = x_0$$

(in a space X) and the adjoint equation (in a conjugate space \mathcal{E}), written here in the form

$$\xi A = \xi_0,$$

some identities between the determinant and subdeterminants

$$D_0, D_1, D_2, \dots$$

play an especially important part. These identities are assumed here as the basis of an axiomatic definition of $\{D_n\}$ in the case where X and \mathcal{E} are arbitrary linear spaces conjugate in a sense explained in § 1. The sequence $\{D_n\}$ is called a *determinant system* for A . The main problem investigated here is under what conditions A has a determinant system $\{D_n\}$ and what is the connection between A and $\{D_n\}$.

The answer is given by the main theorem (Corollary on p. 201) stating that A has a determinant system $\{D_n\}$ if and only if A is Fredholm, and then $\{D_n\}$ is determined by A uniquely up to a constant factor $\neq 0$. A formula for $\{D_n\}$ is given which explains the connection between $\{D_n\}$ and solutions of the equations under examination. In the case where A is inversible, this formula was earlier applied by Ruston [7] (in another formulation and in a special case).

Leżański's method of interpreting D_n as a $2n$ -linear functional on $\mathcal{E}^n \times X^n$ is used in this paper instead of the more complicated interpretation of Grothendieck and Ruston.

The spaces \mathcal{E} and X play everywhere a completely symmetric role. In order to preserve and to underline this symmetry, the endomorphism

A in X and its adjoint in \mathcal{E} are here considered as a bilinear functional on $\mathcal{E} \times X$.

The first few sections of this paper are only a recapitulation of known facts from Linear Algebra in a form convenient for the further investigation. The definition of determinant systems is given in § 5, the main theorems — in § 6. The last section, § 7, contains a formula for determinant systems in Cartesian products.

No topology is supposed in linear spaces under consideration.

The dimension of linear subspaces of linear spaces is always understood in the algebraic sense.

§ 1. Bilinear functionals. We shall consider a fixed commutative algebraic field F whose elements will be called *scalars* and denoted by a, b, c, α , with indices if necessary. Every mapping into F will be called *functional*.

We shall also consider two fixed linear spaces \mathcal{E} and X (infinitely dimensional, in general) over the field F . The letters ξ, η, ζ (with indices if necessary) will always denote elements of \mathcal{E} , and the letters x, y, z — elements of X .

We suppose that \mathcal{E} and X are *conjugate*, i. e. with every pair $(\xi, x) \in \mathcal{E} \times X$ there is associated a scalar denoted by ξx , in such a way that:

(c₁) the product ξx is a bilinear functional on $\mathcal{E} \times X$, i. e.

$$(c\xi)x = c \cdot (\xi x) = \xi(cx),$$

$$\xi(x_1 + x_2) = \xi x_1 + \xi x_2, \quad (\xi_1 + \xi_2)x = \xi_1 x + \xi_2 x;$$

(c₂) if $\xi x = 0$ for every $\xi \in \mathcal{E}$, then $x = 0$;

(c_{2'}) if $\xi x = 0$ for every $x \in X$, then $\xi = 0$.

If $\xi x = 0$, then ξ, x are said to be *orthogonal*.

Two subspaces X_1, X_2 of X ($\mathcal{E}_1, \mathcal{E}_2$ of \mathcal{E}) are said to be *complementary* if every element $x \in X$ ($\xi \in \mathcal{E}$) can be uniquely represented in the form $x = x_1 + x_2$ where $x_1 \in X_1$ and $x_2 \in X_2$ (in the form $\xi = \xi_1 + \xi_2$ where $\xi_1 \in \mathcal{E}_1$ and $\xi_2 \in \mathcal{E}_2$).

If A is a bilinear functional on $\mathcal{E} \times X$, the value of A at the point $(\xi, x) \in \mathcal{E} \times X$ will be denoted by ξAx .

\mathfrak{A} will denote the class of all bilinear functionals on $\mathcal{E} \times X$ such that the following two conditions are satisfied:

(b) for every fixed $x \in X$ there exists a $y \in X$ such that $\xi Ax = \xi y$ for every $\xi \in \mathcal{E}$;

(b') for every fixed $\xi \in \mathcal{E}$, there exists an $\eta \in \mathcal{E}$ such that $\xi Ax = \eta x$ for every $x \in X$.

On the other hand, it follows from (c₂) that there exists at most one y satisfying (b). The unique element y satisfying (b) for a given x will be denoted by Ax . By definition

$$\xi(Ax) = \xi Ax \quad \text{for every } \xi \in \mathcal{E}.$$

It follows from (c_{2'}) that there exists at most one η satisfying (b'). The unique element η satisfying (b') for a given ξ will be denoted by ξA . By definition

$$(\xi A)x = \xi Ax \quad \text{for every } x \in X.$$

It immediately follows from the definition that \mathfrak{A} is a linear space (over F) with the natural definition of addition and multiplication by scalar. For every $A \in \mathfrak{A}$,

$$A(cx) = c(Ax), \quad A(x_1 + x_2) = Ax_1 + Ax_2$$

and

$$(c\xi)A = c(\xi A), \quad (\xi_1 + \xi_2)A = \xi_1 A + \xi_2 A,$$

i. e. the mapping $y = Ax$ is an endomorphism of X , and the mapping $\eta = \xi A$ is an endomorphism of \mathcal{E} .

For instance, if

$$(1) \quad \xi Ix = \xi x \quad \text{for every } (\xi, x) \in \mathcal{E} \times X,$$

then $I \in \mathfrak{A}$ and $Ix = x$ for every $x \in X$ and $\xi I = \xi$ for every $\xi \in \mathcal{E}$.

Another example of an element K in \mathfrak{A} is given by the following formula:

$$\xi Kx = \xi x_0 \cdot \xi_0 x$$

(i. e., ξKx is the product of the scalars ξx_0 and $\xi_0 x$) where $x_0 \in X$ and $\xi_0 \in \mathcal{E}$ are fixed. This bilinear functional will be denoted by $x_0 \cdot \xi_0$ and called *one-dimensional* because the endomorphisms

$$Kx = x_0 \cdot \xi_0 x \quad \text{and} \quad \xi K = \xi x_0 \cdot \xi_0$$

map X and \mathcal{E} onto their at most one-dimensional subspaces spanned by x_0 and ξ_0 respectively.

The bilinear functional

$$K = \sum_{i=1}^r x_i \cdot \xi_i,$$

i. e. the bilinear functional K defined by the formula

$$\xi Kx = \sum_{i=1}^m \xi x_i \cdot \xi_i x,$$

also belongs to \mathfrak{U} and is called *finitely dimensional* since the endomorphisms

$$Kx = \sum_{i=1}^r x_i \cdot \xi_i x \quad \text{and} \quad \xi K = \sum_{i=1}^r \xi_i x_i \cdot \xi_i$$

map X and \mathfrak{E} onto their finitely dimensional subspaces spanned by x_1, \dots, x_r and ξ_1, \dots, ξ_r respectively.

If $A_1, A_2 \in \mathfrak{U}$, then

$$\xi A_1(A_2 x) = (\xi A_1)A_2 x \quad \text{for every } \xi \in \mathfrak{E} \text{ and } x \in X,$$

and the left (or: right) side of this identity is a bilinear functional in \mathfrak{U} . We shall denote it by $A_1 A_2$. By definition

$$\xi A_1 A_2 x = \xi A_1(A_2 x) = (\xi A_1)A_2 x.$$

It immediately follows from the definition that the endomorphism $y = (A_1 A_2)x$ is the superposition of the endomorphisms $y = A_1 z$ and $z = A_2 x$, i. e.

$$(A_1 A_2)x = A_1(A_2 x).$$

Analogously, the endomorphism $\eta = \xi(A_1 A_2)$ is the superposition of the endomorphisms $\eta = \zeta A_2$ and $\zeta = \xi A_1$, i. e.

$$\xi(A_1 A_2) = (\xi A_1)A_2.$$

Notice that if $K = \sum_{i=1}^r x_i \cdot \xi_i$ is finitely dimensional and $A \in \mathfrak{U}$, then

$$KA = \sum_{i=1}^r x_i \cdot \xi_i A \quad \text{and} \quad AK = \sum_{i=1}^r A x_i \cdot \xi_i.$$

Thus KA and AK are finitely dimensional.

In particular, if $K' = \sum_{j=1}^r x'_j \cdot \xi'_j$, then

$$(2) \quad KK' = \sum_{i=1}^r \sum_{j=1}^r x_i \cdot \xi_i x'_j \cdot \xi'_j = \sum_{i=1}^r \sum_{j=1}^r (\xi_i x'_j) x_i \cdot \xi'_j.$$

The linear space \mathfrak{U} with the multiplication $A_1 A_2$ defined above is a linear (non-commutative) ring. The functional I (see (1)) is the unit of \mathfrak{U} , i. e. $IA = AI = A$ for every $A \in \mathfrak{U}$. Therefore I will be called the *unit on $\mathfrak{E} \times X$* .

The following three conditions are equivalent for every A in \mathfrak{U} :

(i₀) A has an inverse A^{-1} in \mathfrak{U} (i. e. there exists an element $A^{-1} \in \mathfrak{U}$ such that $AA^{-1} = A^{-1}A = I$);

(i₁) the endomorphism $y = Ax$ is a one-to-one mapping of X onto X , and the endomorphism $\eta = \xi A$ is a one-to-one mapping of \mathfrak{E} onto \mathfrak{E} ;

(i₂) the endomorphism $y = Ax$ maps X onto X , and the endomorphism $\eta = \xi A$ maps \mathfrak{E} onto \mathfrak{E} .

A bilinear functional $P \in \mathfrak{U}$ is said to be a *projection* if $PP = P$, i. e. if the endomorphisms $y = Px$ and $\eta = \xi P$ are projections in the ordinary sense. We recall that $y = Px$ is then the projection onto the subspace $X_1 = [Px: x \in X]$ along the subspace $X_2 = [x: Px = 0]$, and X_1, X_2 are complementary. Analogously, $\eta = \xi P$ is the projection onto the subspace $\mathfrak{E}_1 = [\xi P: \xi \in \mathfrak{E}]$ along the subspace $\mathfrak{E}_2 = [\xi: \xi P = 0]$, and $\mathfrak{E}_1, \mathfrak{E}_2$ are complementary.

For instance, if x_1, \dots, x_r and ξ_1, \dots, ξ_r are normed biorthogonal, i. e. $\xi_i x_j = \delta_{ij}$ where δ_{ij} is the Kronecker symbol, then the bilinear functional $P \in \mathfrak{U}$ defined by the formula

$$P = I - \sum_{i=1}^r x_i \cdot \xi_i$$

is a projection, called an *r-dimensional projection*. In fact, we then have:

$$Px = x \text{ if } x \text{ is orthogonal to } \xi_1, \dots, \xi_r,$$

$$Px = 0 \text{ if } x \text{ is a linear combination of } x_1, \dots, x_r,$$

i. e. the endomorphism $y = Px$ is a projection of X onto the subspace orthogonal to ξ_1, \dots, ξ_r and along the r -dimensional subspace spanned by x_1, \dots, x_r . Analogously,

$$\xi P = \xi \text{ if } \xi \text{ is orthogonal to } x_1, \dots, x_r,$$

$$\xi P = 0 \text{ if } \xi \text{ is a linear combination of } \xi_1, \dots, \xi_r,$$

i. e. the endomorphism $\eta = \xi P$ is a projection of \mathfrak{E} onto the subspace orthogonal to x_1, \dots, x_r and along the r -dimensional subspace spanned by ξ_1, \dots, ξ_r .

The functional $I \in \mathfrak{U}$ is the only 0-dimensional projection.

§ 2. Quasi-inverse. Let \mathfrak{U} be any algebraic ring (non-commutative, in general). An element $B \in \mathfrak{U}$ is said to be a *quasi-inverse* of an element $A \in \mathfrak{U}$ if

$$(3) \quad ABA = A \quad \text{and} \quad BAB = B.$$

It immediately follows from the definition that if B is a quasi-inverse of A , then A is also a quasi-inverse of B .

We shall consider only the case where \mathfrak{U} has a unit element denoted by I .

Observe that if A has a right (left) inverse B , then B is a quasi-inverse of A , and then every quasi-inverse of A is a right (left) inverse of A . Consequently, if A has the inverse A^{-1} , then A^{-1} is the only quasi-inverse of A .

If

$$(4) \quad \begin{matrix} A, L, \\ B, \mathcal{L} \end{matrix}$$

are elements in \mathfrak{A} such that

$$(5) \quad A\mathcal{L} = 0 = \mathcal{L}A, \quad BL = 0 = LB,$$

$$(6) \quad AB + L\mathcal{L} = I, \quad BA + \mathcal{L}L = I,$$

then B is a quasi-inverse of A , \mathcal{L} is a quasi-inverse of L , and

$$(7) \quad (A+L)(B+\mathcal{L}) = I = (B+\mathcal{L})(A+L),$$

i. e. $B+\mathcal{L} = (A+L)^{-1}$.

In fact, (7) follows immediately from (5) and (6). Equalities (3) can be obtained from (6) by the right or left multiplication by A or B , on account of (5). In the same way we obtain the analogues of (3) for L, \mathcal{L} .

Observe that hypotheses (5), (6) remain unchanged if we commute rows or columns in the matrix (4).

Suppose now that A, L, \mathcal{L} are elements in \mathfrak{A} such that

$$(8) \quad A\mathcal{L} = 0 = \mathcal{L}A,$$

and that \mathcal{L} is a quasi inverse of L , i. e.

$$(9) \quad L\mathcal{L}L = L, \quad \mathcal{L}L\mathcal{L} = \mathcal{L}.$$

Then the elements

$$(10) \quad A_0 = A+L, \quad P = I-L\mathcal{L}, \quad Q = I-\mathcal{L}L$$

satisfy the equations

$$(11) \quad A = PA_0 = A_0Q,$$

$$(12) \quad PP = P, \quad QQ = Q.$$

Moreover, if the inverse A_0^{-1} exists, then the element

$$(13) \quad B = A_0^{-1} - \mathcal{L}$$

is a quasi-inverse of A . More exactly, elements (4) then satisfy conditions (5) and (6).

The proof can be obtained by a simple calculation. Only the proof of the second part of (5) is a little more difficult and will be quoted here. We have

$$BL = A_0^{-1}L - \mathcal{L}L = A_0^{-1}(L - A_0\mathcal{L}L) = A_0^{-1}(L - (A+L)\mathcal{L}L) = 0$$

on account of (8), (9). By the same method we prove $LB = 0$.

In the sequel of this paper, \mathfrak{A} will always be the ring defined in § 1 with the unit I defined by (1).

Let A, B be any bilinear functionals in \mathfrak{A} . Let

$$X_1 = [Ax: x \in X], \quad \mathcal{E}_1 = [\xi A: \xi \in \mathcal{E}],$$

$$X_0 = [Bx: x \in X], \quad \mathcal{E}_0 = [\xi B: \xi \in \mathcal{E}].$$

Then the following three conditions are equivalent:

(q₀) B is a quasi-inverse of A (i. e. (3) hold);

(q) $AB y = y$ for every $y \in X_1$ and $BA x = x$ for every $x \in X_0$;

(q') $\eta = \eta BA$ for every $\eta \in \mathcal{E}_1$ and $\xi = \xi AB$ for every $\xi \in \mathcal{E}_0$.

The condition (q) can also be formulated as follows: the mapping $x = By$, considered as a mapping defined only on X_1 , is the inverse of the mapping $y = Ax$, considered as a mapping defined only on X_0 . Similarly, (q') can be formulated in the form: the mapping $\xi = \eta B$, considered as a mapping defined only on \mathcal{E}_1 , is the inverse of the mapping $\eta = \xi A$, considered as a mapping defined only on \mathcal{E}_0 .

Suppose now that (4) are bilinear functionals in \mathfrak{A} such that conditions (5), (6) are satisfied. To formulate their fundamental property it will be convenient to denote them as follows:

$$\begin{matrix} A_{0,0}, A_{0,1}, \\ A_{1,0}, A_{1,1}. \end{matrix}$$

Conditions (5), (6) can be now written in the form:

$$(14) \quad A_{i,j}A_{1-i,1-j} = 0,$$

$$(15) \quad A_{i,j}A_{i,1-j} + A_{1-i,j}A_{1-i,1-j} = I, \quad A_{i,1-j}A_{i,j} + A_{1-i,1-j}A_{1-i,j} = I$$

where $i, j = 0, 1$. Let

$$X_{i,j}^0 = [x: A_{i,j}x = 0], \quad X_{i,j}^1 = [A_{i,j}x: x \in X],$$

$$\mathcal{E}_{i,j}^0 = [\xi: \xi A_{i,j} = 0], \quad \mathcal{E}_{i,j}^1 = [\xi A_{i,j}: \xi \in \mathcal{E}]$$

for $i, j = 0, 1$.

Suppose that (14), (15) hold. Then the following equalities express the fundamental property of $A_{i,j}$:

$$(16) \quad X_{i,j}^{1-k} = X_{1-i,1-j}^k \quad \text{and} \quad \mathcal{E}_{i,j}^{1-k} = \mathcal{E}_{1-i,1-j}^k \quad \text{for } i, j, k = 0, 1.$$

By symmetry, it suffices to prove only that

$$X_{i,j}^0 = X_{1-i,1-j}^1.$$

Suppose $x \in X_{i,j}^0$, i. e. $A_{i,j}x = 0$. Then, multiplying the second equality (15) by x , we obtain $x = A_{1-i,1-j}(A_{1-i,j}x)$, which implies $x \in X_{1-i,1-j}^1$. Suppose now that $x \in X_{1-i,1-j}^1$, i. e. $x = A_{1-i,1-j}y$ ($y \in X$). Then, multiplying (14) by y , we infer that $A_{i,j}x = 0$, i. e. $x \in X_{i,j}^0$.

The following theorem immediately results from the above consideration (see (7), (q₀), (q), (q') and (16)):

THEOREM I. Suppose that (4) are bilinear functionals in \mathfrak{A} satisfying conditions (5) and (6). Then B is a quasi-inverse of A and:

(e₀) x satisfies the equation

$$Ax = 0$$

if and only if x is of the form $x = Ly$ where $y \in X$;

(e'₀) ξ satisfies the equation

$$\xi A = 0$$

if and only if ξ is of the form $\xi = \eta L$ where $\eta \in \mathfrak{E}$;

(e) the equation

$$(17) \quad Ax = x_0$$

has a solution x if and only if $Lx_0 = 0$; then $x = Bx_0$ is the only solution of (17) such that $Lx = 0$;

(e') the equation

$$(17') \quad \xi A = \xi_0$$

has a solution ξ if and only if $\xi_0 L = 0$; then $\xi = \xi_0 B$ is the only solution of (17') such that $\xi L = 0$.

§ 3. Fredholm functionals. A subspace X_1 of X is said to be of *codimension* r if there exist r linearly independent elements $\zeta_1, \dots, \zeta_r \in \mathfrak{E}$ such that X_1 is the set of all elements x orthogonal to ζ_1, \dots, ζ_r , i. e.

$$X_1 = [x: \zeta_i x = 0 \text{ for } i = 1, \dots, r].$$

Then there exists an r -dimensional subspace X_2 complementary to X_1 . Every complementary subspace X_2 is spanned by some elements y_1, \dots, y_r such that

$$(18) \quad \zeta_i y_j = \delta_{i,j},$$

and every element $x \in X$ can then be uniquely represented in the form

$$x = x' + a_1 y_1 + \dots + a_r y_r \quad \text{where} \quad x' \in X_1.$$

The whole space X is of codimension 0.

By symmetry, a subspace \mathfrak{E}_1 of \mathfrak{E} is said to be of *codimension* r if there exist r linearly independent elements $z_1, \dots, z_r \in X$ such that \mathfrak{E}_1 is the set of all elements ξ orthogonal to z_1, \dots, z_r , i. e.

$$\mathfrak{E}_1 = [\xi: \xi z_i = 0 \text{ for } i = 1, \dots, r].$$

Then there exists an r -dimensional subspace \mathfrak{E}_2 complementary to \mathfrak{E}_1 . Every complementary subspace \mathfrak{E}_2 is spanned by some elements η_1, \dots, η_r such that

$$(18') \quad \eta_i z_j = \delta_{i,j},$$

and every element $\xi \in \mathfrak{E}$ can then be uniquely represented in the form

$$\xi = \xi' + a_1 \eta_1 + \dots + a_r \eta_r \quad \text{where} \quad \xi' \in \mathfrak{E}'.$$

The whole space \mathfrak{E} is of codimension 0.

A bilinear functional $A \in \mathfrak{A}$ is said to be *Fredholm of order* r if

(f) the subspace $X_1 = [Ax: x \in X]$ is of codimension r ,

and

(f') the subspace $\mathfrak{E}_1 = [\xi A: \xi \in \mathfrak{E}]$ is of codimension r .

In other words, $A \in \mathfrak{A}$ is Fredholm of order r if:

(f₁) the equation $Ax = 0$ has exactly r linearly independent solutions z_1, \dots, z_r ;

(f'₁) the equation $\xi A = 0$ has exactly r linearly independent solutions ζ_1, \dots, ζ_r ;

(f₂) the equation $Ax = x_0$ has a solution x if and only if $\zeta_i x_0 = 0$ for $i = 1, \dots, r$;

(f'₂) the equation $\xi A = \xi_0$ has a solution ξ if and only if $\xi_0 z_r = 0$ for $i = 1, \dots, r$.

In particular, A is Fredholm of order 0 if and only if $y = Ax$ is a one-to-one mapping of X onto itself and $\eta = \xi A$ is a one-to-one mapping of \mathfrak{E} onto itself, i. e. if A has an inverse A^{-1} in the ring \mathfrak{A} (see (i₀), (i₁)). For instance, I is Fredholm of order 0.

If the spaces X and \mathfrak{E} are finitely dimensional, then they have the same dimension and, by a known theorem of Linear Algebra, every bilinear functional on $\mathfrak{E} \times X$ is Fredholm.

If $X = X' \times X''$ and $\mathfrak{E} = \mathfrak{E}' \times \mathfrak{E}''$, where \mathfrak{E}' , X' are conjugate and \mathfrak{E}'' , X'' are conjugate, then so are \mathfrak{E} , X . If X' , X'' are bilinear functionals on $\mathfrak{E}' \times X$, $\mathfrak{E}'' \times X''$ respectively, then

$$(19) \quad \xi Ax = \xi' A' x' + \xi'' A'' x'' \quad \text{for} \quad \xi = (\xi', \xi'') \in \mathfrak{E} \quad \text{and} \quad x = (x', x'') \in X$$

is a bilinear functional on $\mathcal{E} \times X$. We shall denote the functional A by (A', A'') . If A' and A'' are Fredholm of orders r' and r'' respectively, then $A = (A', A'')$ is Fredholm of order $r = r' + r''$.

Let \mathcal{E}, X be some conjugate spaces. Every bilinear functional X of the form $A = I - K$ where K is finitely dimensional, is Fredholm. In fact, X and \mathcal{E} can then be represented in the form $X = X' \times X''$, $\mathcal{E} = \mathcal{E}' \times \mathcal{E}''$ where \mathcal{E}', X' are conjugate, \mathcal{E}'', X'' are conjugate, X', \mathcal{E}' are finitely dimensional, and $A = (A', I'')$, I'' being the unit on \mathcal{E}'', X'' .

If A_1 has the inverse A_1^{-1} , and A_2 is Fredholm, then $A_1 A_2$ and $A_2 A_1$ are Fredholm (of the same order as A_2).

Consequently, every bilinear functional of the form

$$(I - K)A_0 \quad \text{or} \quad A_0(I - K),$$

where A_0 has the inverse and K is finitely dimensional, is Fredholm.

Conversely, if A is Fredholm, then A can be represented in the form

$$(20) \quad A = (I - K_1)A_0 = A_0(I - K_2)$$

where A_0 has the inverse A_0^{-1} , and K_1, K_2 are finitely dimensional. Moreover, we can always assume that

$$P = I - K_1 \quad \text{and} \quad Q = I - K_2$$

are r -dimensional projections ($r =$ the order of A).

In fact, let z_1, \dots, z_r and ζ_1, \dots, ζ_r satisfy (f_1) and (f'_1) , and let y_1, \dots, y_r and η_1, \dots, η_r satisfy (18) and $(18')$. Let

$$L = \sum_{i=1}^r y_i \cdot \eta_i, \quad \bar{L} = \sum_{i=1}^r z_i \cdot \zeta_i,$$

$$K_1 = LL = \sum_{i=1}^r y_i \cdot \zeta_i, \quad K_2 = \bar{L}L = \sum_{i=1}^r z_i \cdot \eta_i$$

(see (2), (18), (18')). Then A, L, \bar{L} satisfy (8) and (9). Consequently (see (10), (11), (12)), P and Q are projections and the bilinear functional

$$A_0 = A + L$$

satisfies (20). A_0 has the inverse A_0^{-1} since (see $(i_0), (i_2)$) the endomorphism $y = A_0 x$ maps X onto itself, and $\eta = \xi A_0$ maps \mathcal{E} onto itself. In fact, if $y = x' + a_1 y_1 + \dots + a_r y_r$ where $x' \in X_1$, i. e. $x' = Ax$ for some $x \in X$, then $y = A_0((I - K_2)x + \sum_{i=1}^r a_i z_i)$. The proof of an analogous statement for $\eta = \xi A_0$ is similar.

Every Fredholm functional $A \in \mathcal{U}$ has a quasi-inverse, viz.

$$(21) \quad B = A_0^{-1} - \mathcal{E}$$

is a quasi-inverse of A (see (13)).

If A_1, A_2 are Fredholm, so is $A_1 A_2$. In fact, $A_1 = B_1(I - K_1)$, $A_2 = B_2(I - K_2)$, where B_1, B_2 have inverses and K_1, K_2 are finitely dimensional. Hence $A_1 A_2 = B_1(I - K_1)B_2(I - K_2)$. However, $(I - K_1)B_2$ is Fredholm, i. e. $(I - K_1)B_2 = B_3(I - K_3)$, where B_3 has an inverse and K_3 is finitely dimensional. Hence $A_1 A_2 = A_0(I - K)$ where $A_0 = B_1 B_3$ has an inverse and $K = K_2 + K_3 - K_3 K_2$ is finitely dimensional.

Example. Let $X' = \mathcal{E}'' = (c) =$ the space of all convergent sequences and $X'' = \mathcal{E}' = (l) =$ the space of all absolutely convergent series. Then \mathcal{E}', X' and \mathcal{E}'', X'' are conjugate and, consequently, so are $\mathcal{E} = \mathcal{E}' \times \mathcal{E}'', X = X' \times X''$. The bilinear functional

$$\xi' A' x' = \sum_{n=1}^{\infty} a_{n+1} a_n \quad \text{for} \quad \xi' = (a_n) \in \mathcal{E}' \quad \text{and} \quad x' = (a_n) \in X'$$

is not Fredholm on $\mathcal{E}' \times X'$, and the bilinear functional

$$\xi'' A'' x'' = \sum_{n=1}^{\infty} a_n a_{n+1} \quad \text{for} \quad \xi'' = (a_n) \in \mathcal{E}'' \quad \text{and} \quad x'' = (a_n) \in X''$$

is not Fredholm on $\mathcal{E}'' \times X''$; however, the bilinear functional $A = (A', A'')$ (see (19)) is Fredholm on $\mathcal{E} \times X$. The bilinear functionals $A_1 = (A', I'')$ and $A_2 = (I', A'')$ (where I' and I'' are units on $\mathcal{E}' \times X'$ and $\mathcal{E}'' \times X''$ respectively) are not Fredholm but $A_1 A_2 = (A', A'')$ is Fredholm. The order of $A = (A', A'')$ is 1. The order of $A^n = A A \dots A$ (n times) is n .

§ 4. Relativization to a subring. It is sometimes convenient to consider only a special subring \mathfrak{B} instead of the whole ring \mathcal{U} . We shall always assume that \mathfrak{B} satisfies the following conditions:

- (r₁) I belongs to \mathfrak{B} ; every finite dimensional $K \in \mathcal{U}$ also belongs to \mathfrak{B} ;
- (r₂) if $A \in \mathfrak{B}$ has an inverse A^{-1} in \mathcal{U} , then A^{-1} also belongs to \mathfrak{B} .

Thus the notions of inverses in \mathcal{U} and \mathfrak{B} coincide, and, for every $A \in \mathfrak{B}$, each of the conditions $(i_0), (i_1), (i_2)$ is equivalent to the existence of the inverse of A in \mathfrak{B} .

Observe that if $A \in \mathfrak{B}$ is Fredholm and B is a quasi-inverse of A , then $B \in \mathfrak{B}$ also. This immediately follows from (21). Observe that $B \in \mathfrak{B}$ also in the case where \mathfrak{B} is only an algebraical subring (non-linear, in general) satisfying (r_2) and the following condition:

- (r₀) I belongs to \mathfrak{B} ; if $K \in \mathcal{U}$ is finitely dimensional and $A \in \mathfrak{B}$, then $A + K \in \mathfrak{B}$.

§ 5. Determinant systems. Let \mathfrak{B} satisfy the conditions $(r_1), (r_2)$ mentioned in § 4, and let $A \in \mathfrak{B}$. By a *determinant system* for A in \mathfrak{B} we shall understand every infinite sequence

$$(22) \quad D_0, D_1, D_2, \dots$$

such that:

(d₁) D_n is $2n$ -linear functional on $\underbrace{\mathcal{E} \times \mathcal{E} \times \dots \times \mathcal{E}}_{n \text{ times}} \times \underbrace{X \times X \times \dots \times X}_{n \text{ times}}$, the value of D_n at a point $(\xi_1, \dots, \xi_n, x_1, \dots, x_n)$ of this Cartesian product being denoted by $D_n(\xi_1, \dots, \xi_n; x_1, \dots, x_n)$; in particular D_0 is a scalar;

(d₂) for $n = 2, 3, \dots$, $D_n(\xi_1, \dots, \xi_n; x_1, \dots, x_n)$ is skew symmetric in ξ_1, \dots, ξ_n and in x_1, \dots, x_n , i. e. for every permutation $p = (p_1, \dots, p_n)$ of numbers $1, \dots, n$

$$D_n(\xi_{p_1}, \dots, \xi_{p_n}; x_1, \dots, x_n) = \text{sgn } p \cdot D_n(\xi_1, \dots, \xi_n; x_1, \dots, x_n) = D_n(\xi_1, \dots, \xi_n; x_{p_1}, \dots, x_{p_n})$$

where $\text{sgn } p = 1$ if the permutation p is even, and $\text{sgn } p = -1$ if p is odd;

(d₃) for $n = 1, 2, \dots$, $D_n(\xi_1, \dots, \xi_n; x_1, \dots, x_n)$, interpreted as a function of ξ_i and x_j only, belongs to \mathfrak{B} ;

(d₄) there exists an integer $r \geq 0$ such that D_r does not vanish identically;

(d₅) the following identities hold for $n = 0, 1, 2, \dots$:

$$(D_n) \quad D_{n+1}(\xi_0 A, \xi_1, \dots, \xi_n; x_0, x_1, \dots, x_n) = \sum_{i=0}^n (-1)^i \xi_0 x_i \cdot D_n(\xi_1, \dots, \xi_n; x_0, \dots, x_{i-1}, x_{i+1}, \dots, x_n),$$

$$(D'_n) \quad D_{n+1}(\xi_0, \xi_1, \dots, \xi_n; A x_0, x_1, \dots, x_n) = \sum_{i=0}^n (-1)^i \xi_i x_0 \cdot D_n(\xi_0, \dots, \xi_{i-1}, \xi_{i+1}, \dots, \xi_n; x_1, \dots, x_n).$$

It follows immediately from (d₅) that

$$D_n(\xi_1, \dots, \xi_n; x_1, \dots, x_n) = 0$$

if either $\xi_i = \xi_j$ or $x_i = x_j$ for $i \neq j$.

The least integer r such that D_r does not vanish identically is called the *order* of the determinant system (22).

If X and \mathcal{E} are m -dimensional spaces over F with the usual definition of the product ξx , then every $A \in \mathfrak{U}$ has a determinant system. Viz. fix a coordinate system in X and the corresponding coordinate system in \mathcal{E} .

Then, in the summation notation from the Tensor Calculus, if $x = (a^1, \dots, a^m)$ and $\xi = (a_1, \dots, a_m)$, then $\xi x = a_i a^i$, and there exists a scalar square matrix $\{c_j^i\}$ such that $\xi A x = a_i c_j^i a^j$. Let D_0 be the algebraical determinant of $\{c_j^i\}$. If $0 < n \leq m$, i_1, \dots, i_n are different positive integers $\leq m$ and j_1, \dots, j_n are different positive integers $\leq m$, let $b_{i_1, \dots, i_n; j_1, \dots, j_n}^{i_1, \dots, i_n}$ denote the corresponding algebraical minor of the matrix $\{c_j^i\}$ (i. e. the determinant obtained from $\{c_j^i\}$ by omitting the rows with indexes j_1, \dots, j_n and the columns with indexes i_1, \dots, i_n , and multiplied respectively by ± 1); otherwise let $b_{i_1, \dots, i_n; j_1, \dots, j_n}^{i_1, \dots, i_n} = 0$. For $n = 1, 2, \dots$ let

$$D_n(\xi_1, \dots, \xi_n; x_1, \dots, x_n) = a_{j_1} \dots a_{j_n} b_{i_1, \dots, i_n; j_1, \dots, j_n}^{i_1, \dots, i_n} a^{j_1} \dots a^{j_n}$$

where $\xi_k = (a_1, \dots, a_m)$ and $x_k = (a^1, \dots, a^m)$. The sequence (22) so defined is a determinant system for A .

An example of a determinant system (under some hypotheses on A) in the case where X and \mathcal{E} are Banach spaces was given by Leżański [3] (see also Sikorski [9]) and (under more restrictive hypotheses on A) by Ruston [6] and Grothendieck [1].

Observe that if (22) is a determinant system for A , and $c \neq 0$, then

$$cD_0, cD_1, cD_2, \dots$$

is also a determinant system for A .

If (22) is a determinant system for A , and $c \neq 0$, then

$$D_0, \frac{1}{c} D_1, \frac{1}{c^2} D_2, \dots$$

is a determinant system for cA .

If (22) is a determinant system for A , and $B \in \mathfrak{B}$ has the inverse B^{-1} , then

$$D_n(\xi_1 B^{-1}, \dots, \xi_n B^{-1}; x_1, \dots, x_n) \quad (n = 0, 1, 2, \dots)$$

is a determinant system for AB , and

$$D_n(B^{-1} \xi_1, \dots, B^{-1} \xi_n; B^{-1} x_1, \dots, B^{-1} x_n) \quad (n = 0, 1, 2, \dots)$$

is a determinant system for BA .

The unit I always has a determinant system. In fact, let

$$\theta_0 = 1 \quad \text{and} \quad \theta_n \begin{pmatrix} \xi_1, \dots, \xi_n \\ x_1, \dots, x_n \end{pmatrix} = \begin{vmatrix} \xi_1 x_1, \dots, \xi_1 x_n \\ \dots \dots \dots \\ \xi_n x_1, \dots, \xi_n x_n \end{vmatrix} \quad \text{for } n = 1, 2, \dots$$

Then $\theta_0, \theta_1, \theta_2, \dots$ is a determinant system for I .

It follows immediately from the last two remarks that if A has the inverse A^{-1} , then the formulas

$$(23) \quad \mathcal{D}_0 = 1, \quad \mathcal{D}_n \begin{pmatrix} \xi_1, \dots, \xi_n \\ x_1, \dots, x_n \end{pmatrix} = \theta_n \begin{pmatrix} \xi_1 A^{-1}, \dots, \xi_n A^{-1} \\ x_1, \dots, x_n \end{pmatrix}$$

$$= \theta_n \begin{pmatrix} \xi_1, \dots, \xi_n \\ A^{-1}x_1, \dots, A^{-1}x_n \end{pmatrix} = \begin{vmatrix} \xi_1 A^{-1}x_1, \dots, \xi_1 A^{-1}x_n \\ \dots \dots \dots \\ \xi_n A^{-1}x_1, \dots, \xi_n A^{-1}x_n \end{vmatrix} \quad \text{for } n = 1, 2, \dots$$

define a determinant system $\mathcal{D}_0, \mathcal{D}_1, \mathcal{D}_2, \dots$ for A .

We quote also the following example of a determinant system (a slight generalization of a definition in Ruston [7]). Suppose X and \mathcal{E} are complex Banach spaces, A is an open set of complex numbers, \mathfrak{B} is an algebra of continuous bilinear functionals on $\mathcal{E} \times X$. Let $A(\lambda)$ be a holomorphic function of a complex variable $\lambda \in A$ with values in \mathfrak{B} . Suppose that, for every $\lambda \in A$ except an isolated set of points $\lambda_1, \lambda_2, \dots$, the inverse $A(\lambda)^{-1}$ exists. Let $\mathcal{D}_n(\lambda)$ be the $2n$ -linear functional defined by (23) where A is replaced by $A(\lambda)$. $\mathcal{D}_n(\lambda)$ is a holomorphic function of $\lambda \in A - (\lambda_1, \lambda_2, \dots)$ with values in the Banach space of all $2n$ -linear continuous functionals on $\mathcal{E} \times \dots \times \mathcal{E} \times X \times \dots \times X$. Suppose that, for every k , there exists an integer $r_k > 0$ such that all $\mathcal{D}_n(\lambda)$ have at most a pole of order $\leq r_k$ at the point λ_k , and one of them has a pole exactly of order r_k . Let $D_0(\lambda)$ be a complex-valued holomorphic function in A such that $D_0(\lambda)$ has a zero of order r_k for $\lambda = \lambda_k$ ($k = 1, 2, \dots$) and $D_0(\lambda) \neq 0$ otherwise. Then all $D_n(\lambda) = D_0(\lambda)\mathcal{D}_n(\lambda)$ ($n = 1, 2, \dots$) are holomorphic in the whole A and, for every $\lambda \in A$, $D_0(\lambda), D_1(\lambda), D_2(\lambda), \dots$ is a determinant system for $A(\lambda)$.

Some criterions for $A(\lambda) = I + \lambda T$ (where $T \in \mathfrak{B}$) to satisfy the hypotheses mentioned above (in the case where A is the whole plane) were given by Ruston [7].

6. Fundamental theorems. Let X and \mathcal{E} be conjugate and let \mathfrak{B} satisfy the hypotheses mentioned in § 4.

THEOREM II. *If a bilinear functional $A \in \mathfrak{B}$ has in \mathfrak{B} a determinant system (8) of order r , then A is Fredholm of order r .*

More exactly:

If $\eta_1, \dots, \eta_r \in \mathcal{E}$ and $y_1, \dots, y_r \in X$ are such that

$$D_r \begin{pmatrix} \eta_1, \dots, \eta_r \\ x_1, \dots, x_r \end{pmatrix} \neq 0,$$

then there exist elements $\xi_1, \dots, \xi_r \in \mathcal{E}$ and $z_1, \dots, z_r \in X$ such that

$$(24) \quad \xi_i x = \frac{D_r \begin{pmatrix} \eta_1, \dots, \eta_r \\ y_1, \dots, y_{i-1}, x, y_{i+1}, \dots, y_r \end{pmatrix}}{D_r \begin{pmatrix} \eta_1, \dots, \eta_r \\ y_1, \dots, y_r \end{pmatrix}} \quad \text{for every } x \in X$$

and

$$(24') \quad \xi z_i = \frac{D_r \begin{pmatrix} \eta_1, \dots, \eta_{i-1}, \xi, \eta_{i+1}, \dots, \eta_r \\ y_1, \dots, y_r \end{pmatrix}}{D_r \begin{pmatrix} \eta_1, \dots, \eta_r \\ y_1, \dots, y_r \end{pmatrix}} \quad \text{for every } \xi \in \mathcal{E}.$$

The elements ξ_1, \dots, ξ_r are linearly independent and are solutions of the equation

$$(25) \quad \xi A = 0.$$

The elements z_1, \dots, z_r are linearly independent and are solutions of the equation

$$(25') \quad Ax = 0.$$

Conversely, every solution ξ of (25) is a linear combination of ξ_1, \dots, ξ_r , and every solution x of (25') is a linear combination of z_1, \dots, z_r .

The equation

$$(26) \quad \xi A = \xi_0$$

has a solution ξ if and only if $\xi_0 z_i = 0$ for $i = 1, \dots, r$. The equation

$$(26') \quad Ax = x_0$$

has a solution x if and only if $\xi_i x_0 = 0$ for $i = 1, \dots, r$.

The bilinear functional B defined by the formula

$$\xi Bx = \frac{D_{r+1} \begin{pmatrix} \xi, \eta_1, \dots, \eta_r \\ x, y_1, \dots, y_r \end{pmatrix}}{D_r \begin{pmatrix} \eta_1, \dots, \eta_r \\ y_1, \dots, y_r \end{pmatrix}}$$

is a quasi-inverse of A . If ξ_0 is orthogonal to all z_1, \dots, z_r , then $\xi_0 B$ is the only solution of (26), orthogonal to y_1, \dots, y_r . Analogously, if x_0 is orthogonal to ζ_1, \dots, ζ_r , then Bx_0 is the only solution of (26'), orthogonal to η_1, \dots, η_r .

In fact, the conditions $\zeta_i \in \mathcal{E}$ and $z_i \in X$ ($i = 1, \dots, r$) follow directly from (d₃). It follows immediately from the definition (24) that $\zeta_i y_j = \delta_{ij}$. Thus ζ_1, \dots, ζ_r are linearly independent, and so are y_1, \dots, y_r . Similarly, (24') implies that $\eta_i z_j = \delta_{ij}$. Thus z_1, \dots, z_r are linearly independent, and so are η_1, \dots, η_r .

Let L and \bar{L} be defined as in § 3:

$$L = \sum_{i=1}^r y_i \cdot \eta_i, \quad \bar{L} = \sum_{i=1}^r z_i \cdot \zeta_i.$$

The identity (D_{r-1}) (see p. 190) and the skew symmetry (d₂) imply $\zeta_i A x = 0$ for every $x \in X$, i. e. (see (c₂)) $\zeta_i A = 0$ for $i = 1, \dots, r$. Similarly (D'_{r-1}) , (d₂) and (c₂) imply $A z_i = 0$ for $i = 1, \dots, r$. Hence $A\bar{L} = 0 = \bar{L}A$.

The skew symmetry (d₂) implies that $B y_i = 0$ and $\eta_i B = 0$ for $i = 1, \dots, r$. Hence $BL = 0 = LB$.

Setting in (D_n) $n = r$ and replacing $\xi_0, \xi_1, \dots, \xi_r, x_0, x_1, \dots, x_r$ by $\xi, \eta_1, \dots, \eta_r, x, y_1, \dots, y_r$ respectively, we obtain, on account of the skew symmetry (d₂), $AB = I - LL$. Analogously we obtain, from (D'_r) on account of (d₂), $BA = I - \bar{L}\bar{L}$.

Since (see (2)) $L\bar{L}L = L$ and $\bar{L}LL = \bar{L}$, all the hypotheses of Theorem I are satisfied. Theorem II immediately follows from Theorem I.

THEOREM III. *If $A \in \mathfrak{B}$ is Fredholm, then A has a determinant system in \mathfrak{B} . This system is determined by A uniquely up to a scalar factor $\neq 0$.*

Let r be the order of A .

Consider first the case where $r = 0$, i. e. A has the inverse A^{-1} . It follows from § 5 that A then has a determinant system, viz. the system D_0, D_1, D_2, \dots defined by (23). Conversely, if D_0, D_1, D_2, \dots is any determinant system of A , then it follows from the identities (D_n) , (D'_n) for $\{D_n\}$ and $\{D'_n\}$, by induction on n , that (Ruston [7])

$$D_n = D_0 \cdot D_n \quad \text{for } n = 0, 1, 2, \dots$$

This completes the proof of Theorem II in the case $r = 0$.

Suppose now that $r > 0$. Let $X_1, X_2, \mathcal{E}_1, \mathcal{E}_2, y_1, \dots, y_r, z_1, \dots, z_r, \eta_1, \dots, \eta_r, \zeta_1, \dots, \zeta_r$ and B have the same meaning as in § 3, i. e. X_1, \mathcal{E}_1 are defined in (f) and (f'); z_1, \dots, z_r and ζ_1, \dots, ζ_r satisfy (f₁), (f₂),

(f'₁), (f'₂); y_1, \dots, y_r and η_1, \dots, η_r satisfy (18) and (18'); X_2 and \mathcal{E}_2 are subspaces spanned by y_1, \dots, y_r and η_1, \dots, η_r respectively; and B is a quasi-inverse of A .

Let

$$(27) \quad D_n = 0 \quad \text{for } n = 0, \dots, r-1,$$

$$(28) \quad D_r \begin{pmatrix} \xi_1, \dots, \xi_r \\ x_1, \dots, x_r \end{pmatrix} = \begin{vmatrix} \xi_1 z_1, \dots, \xi_1 z_r \\ \dots \dots \dots \\ \xi_r z_1, \dots, \xi_r z_r \end{vmatrix} \cdot \begin{vmatrix} \zeta_1 x_1, \dots, \zeta_1 x_r \\ \dots \dots \dots \\ \zeta_r x_1, \dots, \zeta_r x_r \end{vmatrix},$$

and for $k = 1, 2, \dots$ let

$$(29) \quad D_{r+k} \begin{pmatrix} \xi_1, \dots, \xi_{r+k} \\ x_1, \dots, x_{r+k} \end{pmatrix} = \sum_{p, q} \text{sgn } p \cdot \text{sgn } q \cdot \begin{vmatrix} \xi_{p_1} B x_{q_1}, \dots, \xi_{p_1} B x_{q_k} \\ \dots \dots \dots \\ \xi_{p_k} B x_{q_1}, \dots, \xi_{p_k} B x_{q_k} \end{vmatrix} \cdot D_r \begin{pmatrix} \xi_{p_{k+1}}, \dots, \xi_{p_{k+r}} \\ x_{q_{k+1}}, \dots, x_{q_{k+r}} \end{pmatrix}$$

where Σ is extended over all permutations $p = (p_1, \dots, p_{r+k})$ and $q = (q_1, \dots, q_{r+k})$ of the integers $1, \dots, r+k$, such that

$$p_1 < p_2 < \dots < p_k, \quad p_{k+1} < p_{k+2} < \dots < p_{r+k},$$

$$q_1 < q_2 < \dots < q_k, \quad q_{k+1} < q_{k+2} < \dots < q_{r+k}.$$

Of course, if the field F of scalars has the characteristic zero, then (29) can also be written in the form

$$D_{r+k} \begin{pmatrix} \xi_1, \dots, \xi_{r+k} \\ x_1, \dots, x_{r+k} \end{pmatrix} = \sum_{p, q} \frac{\text{sgn } p \cdot \text{sgn } q}{(k!)^2 (r!)^2} \begin{vmatrix} \xi_{p_1} B x_{q_1}, \dots, \xi_{p_1} B x_{q_k} \\ \dots \dots \dots \\ \xi_{p_k} B x_{q_1}, \dots, \xi_{p_k} B x_{q_k} \end{vmatrix} \cdot D_r \begin{pmatrix} \xi_{p_{k+1}}, \dots, \xi_{p_{k+r}} \\ x_{q_{k+1}}, \dots, x_{q_{k+r}} \end{pmatrix}$$

where Σ is extended over all permutations $p = (p_1, \dots, p_{r+k})$ and $q = (q_1, \dots, q_{r+k})$ of the integers $1, \dots, r+k$.

We shall prove that the sequence

$$(30) \quad D_0, D_1, D_2, \dots$$

defined by (27), (28) and (29) is a determinant system for A . It is evident that (30) satisfies conditions (d_1) , (d_2) , (d_3) . It follows from (28) and (18), (18') that

$$\mathcal{D}_r \begin{pmatrix} \eta_1, \dots, \eta_r \\ y_1, \dots, y_r \end{pmatrix} = 1,$$

i. e. (d_4) is also satisfied.

It follows immediately from (27) that identities (D_n) and (D'_n) hold for $n = 0, \dots, n-2$. They also hold for $n = r-1$. In fact, the right side is then equal to zero by (27) and so is the left side on account of (28). More exactly, if either one of the points ξ_1, \dots, ξ_2 belongs to \mathcal{E}_1 (i. e. is of the form ξA) or one of the points x_1, \dots, x_r belongs to X_1 (i. e. is of the form Ax), then

$$(31) \quad \mathcal{D}_r \begin{pmatrix} \xi_1, \dots, \xi_r \\ x_1, \dots, x_r \end{pmatrix} = 0$$

since points in E_1 are orthogonal to all z_1, \dots, z_r and points in X_1 are orthogonal to all ξ_1, \dots, ξ_r .

Since the ξ 's and the x 's play a symmetric role everywhere, in order to prove (d₅) it suffices to prove only (D_n) for $n = r + k$, $k \geq 0$.

We have

$$\begin{aligned} & \mathcal{D}_{r+k+1} \left(\begin{matrix} \xi_0, \xi_1, \dots, \xi_{r+k} \\ x_0, x_1, \dots, x_{r+k} \end{matrix} \right) \\ &= \sum_{p', q} \text{sgn } p' \cdot \text{sgn } q \cdot \begin{vmatrix} \xi_0 Bx_{q_0}, \dots, \xi_0 Bx_{q_k} \\ \xi_{p_1} Bx_{q_0}, \dots, \xi_{p_1} Bx_{q_k} \\ \vdots \\ \xi_{p_k} Bx_{q_0}, \dots, \xi_{p_k} Bx_{q_k} \end{vmatrix} \cdot \mathcal{D}_r \left(\begin{matrix} \xi_{p_{k+1}}, \dots, \xi_{p_{k+r}} \\ x_{q_{k+1}}, \dots, x_{q_{k+r}} \end{matrix} \right) + \\ &+ \sum_{p'', q} \text{sgn } p'' \cdot \text{sgn } q \cdot \begin{vmatrix} \xi_{p_0} Bx_{q_0}, \dots, \xi_{p_0} Bx_{q_k} \\ \xi_{p_1} Bx_{q_0}, \dots, \xi_{p_1} Bx_{q_k} \\ \vdots \\ \xi_{p_k} Bx_{q_0}, \dots, \xi_{p_k} Bx_{q_k} \end{vmatrix} \cdot \mathcal{D}_r \left(\begin{matrix} \xi_0, \xi_{p_{k+2}}, \dots, \xi_{p_{k+r}} \\ x_{q_{k+1}}, x_{q_{k+2}}, \dots, x_{q_{k+r}} \end{matrix} \right) \end{aligned}$$

where p', p'', q denote arbitrary permutations (of the integers $0, 1, \dots, r+k$) of the form:

$$\begin{aligned} \mathfrak{p}' &= (0, p_1, \dots, p_k, p_{k+1}, \dots, p_{k+r}), & p_1 &< \dots < p_k, \quad p_{k+1} < \dots < p_{k+r}; \\ \mathfrak{p}'' &= (p_0, p_1, \dots, p_k, 0, p_{k+2}, \dots, p_{k+r}), & p_0 &< \dots < p_k, \quad p_{k+2} < \dots < p_{k+r}; \\ \mathfrak{q} &= (q_0, q_1, \dots, q_k, q_{k+1}, \dots, q_{k+r}), & q_0 &< \dots < q_k, \quad q_{k+1} < \dots < q_{k+r}. \end{aligned}$$

It follows from (31) that

$$\begin{aligned}
& \mathcal{D}_{r+k+1} \left(\begin{matrix} \xi_0 A, & \xi_1, & \dots, & \xi_{r+k} \\ x_0, & x_1, & \dots, & x_{r+k} \end{matrix} \right) \\
&= \sum_{p,q} \text{sgn } p' \cdot \text{sgn } q \cdot \left| \begin{matrix} \xi_0 A B x_{q_0}, \dots, \xi_0 A B x_{q_k} \\ \xi_{p_1} B x_{q_0}, \dots, \xi_{p_k} B x_{q_k} \\ \vdots \\ \xi_{p_k} B x_{q_0}, \dots, \xi_{p_k} B x_{q_k} \end{matrix} \right| \cdot \mathcal{D}_r \left(\begin{matrix} \xi_{p_{k+1}}, \dots, \xi_{p_{k+r}} \\ x_{q_{k+1}}, \dots, x_{q_{k+r}} \end{matrix} \right) \\
&= \sum_{p',q} \sum_{j=0}^k (-1)^j \cdot \text{sgn } p \cdot \text{sgn } q \cdot \xi_0 A B x_{q_j} \cdot \\
&\quad \cdot \left| \begin{matrix} \xi_{p_1} B x_{q_0}, \dots, \xi_{p_1} B x_{q_{j-1}}, \xi_{p_1} B x_{q_{j+1}}, \dots, \xi_{p_1} B x_{q_k} \\ \vdots \\ \xi_{p_k} B x_{q_0}, \dots, \xi_{p_k} B x_{q_{j-1}}, \xi_{p_k} B x_{q_{j+1}}, \dots, \xi_{p_k} B x_{q_k} \end{matrix} \right| \cdot \mathcal{D}_r \left(\begin{matrix} \xi_{p_{k+1}}, \dots, \xi_{p_{k+r}} \\ x_{q_{k+1}}, \dots, x_{q_{k+r}} \end{matrix} \right) \\
&= \sum_{i=0}^{r+k} (-1)^i \cdot \xi_0 A B x_i \cdot \sum_{p,q,i} \text{sgn } p \cdot \text{sgn } q \cdot i \cdot \\
&\quad \cdot \left| \begin{matrix} \xi_{p_1} B x_{q_{i,1}}, \dots, \xi_{p_1} B x_{q_{i,k}} \\ \vdots \\ \xi_{p_k} B x_{q_{i,1}}, \dots, \xi_{p_k} B x_{q_{i,k}} \end{matrix} \right| \cdot \mathcal{D}_r \left(\begin{matrix} \xi_{p_{k+1}}, \dots, \xi_{p_{k+r}} \\ x_{q_{i,k+1}}, \dots, x_{q_{i,k+r}} \end{matrix} \right)
\end{aligned}$$

where $p = (p_1, \dots, p_{k+r})$ is any permutation of the integers $1, \dots, k+r$ such that $p_1 < \dots < p_k$, $p_{k+1} < \dots < p_{k+r}$, and $q_i = (q_{i,1}, \dots, q_{i,k+r})$ is any permutation of the integers $0, \dots, i-1, i+1, \dots, k+r$ such that $q_{i,1} < \dots < q_{i,k}$, $q_{i,k+1} < \dots < q_{i,k+r}$. The factor $(-1)^j$ is now replaced by $(-1)^i$ since if $q_j = i$, p is the permutation obtained from p' by omitting the integer 0 , and q_i is the permutation obtained from q by omitting the integer i , then the corresponding ± 1 -coefficients satisfy the equality

$$(-1)^j \cdot \operatorname{sgn} p' \cdot \operatorname{sgn} q = (-1)^i \cdot \operatorname{sgn} p \cdot \operatorname{sgn} q_i.$$

The sum $\sum_{p,q}$ being equal to

$$\mathcal{D}_{r+k} \left(\begin{matrix} \xi_1, \dots, \dots, \dots, \dots, \xi_{r+k} \\ x_0, \dots, x_{i-1}, x_{i+1}, \dots, x_{r+k} \end{matrix} \right),$$

we obtain

$$\begin{aligned} \mathcal{D}_{r+k+1} \left(\begin{matrix} \xi_0 A, \xi_1, \dots, \xi_{r+k} \\ x_0, x_1, \dots, x_{r+k} \end{matrix} \right) \\ = \sum_{i=0}^{r+k} (-1)^i \cdot \xi_0 A B x_i \cdot \mathcal{D}_{r+k} \left(\begin{matrix} \xi_1, \dots, \xi_{r+k} \\ x_0, \dots, x_{i-1}, x_{i+1}, \dots, x_{r+k} \end{matrix} \right). \end{aligned}$$

Thus, in order to complete the proof of (D_{r+k}) we have to prove that

$$\begin{aligned} (32) \quad \sum_{i=k}^{r+k} (-1)^i \cdot \xi_0 A B x_i \cdot \mathcal{D}_{r+k} \left(\begin{matrix} \xi_1, \dots, \xi_{r+k} \\ x_0, \dots, x_{i-1}, x_{i+1}, \dots, x_{r+k} \end{matrix} \right) \\ = \sum_{i=0}^{r+k} (-1)^i \cdot \xi_0 x_i \cdot \mathcal{D}_{r+k} \left(\begin{matrix} \xi_1, \dots, \xi_{r+k} \\ x_0, \dots, x_{i-1}, x_{i+1}, \dots, x_{r+k} \end{matrix} \right). \end{aligned}$$

Every point $x \in X$ can be represented in the form

$$x = x' + a_1 y_1 + \dots + a_r y_r$$

where $x' \in X_1$ (see § 2). The left and the right sides of (32) are linear in each of the variables x_0, x_1, \dots, x_{r+k} . Therefore, in order to prove (32) it suffices to show that this equality holds if each of points x_0, x_1, \dots, x_{r+k} is either equal to one of the points y_1, \dots, y_r or belongs to X_1 . The proof is based on the following remark, which follows directly from (29) and (31):

$$(33) \quad \mathcal{D}_{r+k} \left(\begin{matrix} \xi_1, \dots, \xi_{r+k} \\ x_1, \dots, x_{r+k} \end{matrix} \right) = 0$$

whenever more than k points among x_1, \dots, x_{r+k} belong to X_1 .

Consider first the case where each of points y_1, \dots, y_r appears at most once in the sequence x_0, x_1, \dots, x_{r+k} . Then at least $k+1$ points among x_0, x_1, \dots, x_{r+k} belong to X_1 .

If $x_i \in X_1$, then $A B x_i = x_i$ (see (q)) and consequently

$$\begin{aligned} (34) \quad (-1)^i \cdot \xi_0 A B x_i \cdot \mathcal{D}_{r+k} \left(\begin{matrix} \xi_1, \dots, \xi_{r+k} \\ x_0, \dots, x_{i-1}, x_{i+1}, \dots, x_{r+k} \end{matrix} \right) \\ = (-1)^i \cdot \xi_0 x_i \cdot \mathcal{D}_{r+k} \left(\begin{matrix} \xi_1, \dots, \xi_{r+k} \\ x_0, \dots, x_{i-1}, x_{i+1}, \dots, x_{r+k} \end{matrix} \right). \end{aligned}$$

If $x_i = y_j$, then equality (34) also holds since then

$$(35) \quad \mathcal{D}_{r+k} \left(\begin{matrix} \xi_1, \dots, \xi_{r+k} \\ x_0, \dots, x_{i-1}, x_{i+1}, \dots, x_{r+k} \end{matrix} \right) = 0$$

on account of (33).

Suppose now that an element y_j appears in the sequence x_0, x_1, \dots, x_{r+k} at least twice, i. e. $x_{i_1} = y_j = x_{i_2}$ ($i_1 \neq i_2$). Then, by the skew symmetry of \mathcal{D}_{r+k} ,

$$\begin{aligned} (-1)^{i_1} \cdot \xi_0 A B x_{i_1} \cdot \mathcal{D}_{r+k} \left(\begin{matrix} \xi_1, \dots, \xi_{r+k} \\ x_0, \dots, x_{i_1-1}, x_{i_1+1}, \dots, x_{r+k} \end{matrix} \right) + \\ + (-1)^{i_2} \cdot \xi_0 A B x_{i_2} \cdot \mathcal{D}_{r+k} \left(\begin{matrix} \xi_0, \dots, \xi_{r+k} \\ x_0, \dots, x_{i_2-1}, x_{i_2+1}, \dots, x_{r+k} \end{matrix} \right) = 0, \end{aligned}$$

and analogously

$$\begin{aligned} (-1)^{i_1} \cdot \xi_0 x_{i_1} \cdot \mathcal{D}_{r+k} \left(\begin{matrix} \xi_1, \dots, \xi_{r+k} \\ x_0, \dots, x_{i_1-1}, x_{i_1+1}, \dots, x_{r+k} \end{matrix} \right) + \\ + (-1)^{i_2} \cdot \xi_0 x_{i_2} \cdot \mathcal{D}_{r+k} \left(\begin{matrix} \xi_1, \dots, \xi_{r+k} \\ x_0, \dots, x_{i_2-1}, x_{i_2+1}, \dots, x_{r+k} \end{matrix} \right) = 0. \end{aligned}$$

If $i_1 \neq i \neq i_2$, then (34) holds. In fact, (35) is then satisfied by the skew symmetry, since y_j appears twice in the sequence $x_0, \dots, x_{i-1}, x_{i+1}, \dots, x_r$. This proves (32).

Suppose now that D_0, D_1, D_2, \dots is any determinant system for A . We shall prove that there exists a scalar $c \neq 0$ such that

$$(36) \quad D_n = c D_n \quad \text{for} \quad n = 0, 1, 2, \dots$$

where $\{D_n\}$ is defined by (27), (28), (29).

It follows from Theorem II that r is the order of $\{D_n\}$, i. e.

$$(37) \quad D_n = 0 \quad \text{for} \quad n = 0, \dots, r-1$$

and $D_r \neq 0$. It follows from (d_2) , (D'_{r-1}) , (D_{r-1}) and from (37) that

$$(38) \quad D_r \left(\begin{matrix} \xi_1, \dots, \xi_r \\ x_1, \dots, x_r \end{matrix} \right) = 0$$

if either one of the points x_1, \dots, x_r belongs to X_1 (i. e. is of the form Ax) or one of the points ξ_1, \dots, ξ_r belongs to \mathcal{E}_1 (i. e. is of the form ξA).

Every point $x_i \in X$ can be uniquely represented in the form $x_i = x'_i + x''_i$ where $x'_i \in X_1$ and $x''_i \in X_2$ and, analogously, every point $\xi_i \in \mathcal{E}$ can be uniquely represented in the form $\xi_i = \xi'_i + \xi''_i$ where $\xi'_i \in \mathcal{E}_1$ and $\xi''_i \in \mathcal{E}_2$. Property (38) implies that for arbitrary $x_i \in X$ and $\xi_i \in \mathcal{E}$ ($i = 1, \dots, r$),

$$(39) \quad D_r \begin{pmatrix} \xi_1, \dots, \xi_r \\ x_1, \dots, x_r \end{pmatrix} = D_r \begin{pmatrix} \xi'_1, \dots, \xi'_r \\ x'_1, \dots, x'_r \end{pmatrix},$$

i. e. D_r is completely determined by its values on subspaces \mathcal{E}_2 and X_2 . The same is true for \mathcal{D}_r , i. e.

$$(40) \quad \mathcal{D}_r \begin{pmatrix} \xi_1, \dots, \xi_r \\ x_1, \dots, x_r \end{pmatrix} = \mathcal{D}_r \begin{pmatrix} \xi'_1, \dots, \xi'_r \\ x'_1, \dots, x'_r \end{pmatrix}.$$

Since \mathcal{E}_2 and X_2 are r -dimensional, all $2r$ -linear functionals defined on $\underbrace{\mathcal{E}_2 \times \dots \times \mathcal{E}_2}_r \times \underbrace{X_2 \times \dots \times X_2}_r$ and skew symmetric in $\xi'_1, \dots, \xi'_r \in \mathcal{E}_2$ and $x'_1, \dots, x'_r \in X_2$ differ only by a scalar factor. In particular, there exists a scalar $c \neq 0$ (since $D_r \neq 0 \neq \mathcal{D}_r$) such that

$$D_r \begin{pmatrix} \xi'_1, \dots, \xi'_r \\ x'_1, \dots, x'_r \end{pmatrix} = c \cdot \mathcal{D}_r \begin{pmatrix} \xi'_1, \dots, \xi'_r \\ x'_1, \dots, x'_r \end{pmatrix}$$

for $\xi'_1, \dots, \xi'_r \in \mathcal{E}_2$ and $x'_1, \dots, x'_r \in X_2$. This proves, by (39) and (40), that

$$D_r \begin{pmatrix} \xi_1, \dots, \xi_r \\ x_1, \dots, x_r \end{pmatrix} = c \cdot \mathcal{D}_r \begin{pmatrix} \xi_1, \dots, \xi_r \\ x_1, \dots, x_r \end{pmatrix}$$

for arbitrary $\xi_1, \dots, \xi_r \in \mathcal{E}$ and $x_1, \dots, x_r \in X$. This and (27), (37) imply that (36) is true for $n = 0, \dots, r$.

We shall prove, by induction with respect to k , that (36) is true for $n = r+k$, $k = 0, 1, 2, \dots$. The case $k = 0$ was just proved.

Suppose that (36) is true for $n = r+k$. We shall prove that it is true for $n+1 = r+k+1 > r$, i. e.

$$(41) \quad D_{n+1} \begin{pmatrix} \xi_0, \xi_1, \dots, \xi_n \\ x_0, x_1, \dots, x_n \end{pmatrix} = c \cdot \mathcal{D}_{n+1} \begin{pmatrix} \xi_0, \xi_1, \dots, \xi_n \\ x_0, x_1, \dots, x_n \end{pmatrix}.$$

Since D_{n+1} and \mathcal{D}_{n+1} are linear in all variables, it suffices to prove (41) only in the case where each of the points x_0, x_1, \dots, x_n either belongs to X_1 or is equal to one of the points y_1, \dots, y_r .

If the sequence x_0, x_1, \dots, x_n contains one point of the form λx (i. e. belonging to X_1), then (41) holds. This follows from the induction hypothesis and from the identity (D'_n) for D_{n+1} and for \mathcal{D}_{n+1} (see also (d_2)).

If the sequence x_0, x_1, \dots, x_n contains exclusively points y_1, \dots, y_r , one of them appears at least twice. Hence, by the skew symmetry (d_2) , both sides of (41) are equal to 0.

COROLLARY. $A \in \mathfrak{B}$ has a determinant system in \mathfrak{B} if and only if A is Fredholm. The determinant system (22) of A is determined by A uniquely up to a constant factor $c \neq 0$, viz. if the order of A is zero, then

$$(42_0) \quad D_n = D_0 \cdot \mathcal{D}_n \quad \text{for } n = 0, 1, 2, \dots$$

where \mathcal{D}_n are given by (23), and if the order of A is positive, then

$$(42) \quad D_n = c \cdot \mathcal{D}_n \quad \text{for } n = 0, 1, 2, \dots$$

where $c \neq 0$ and \mathcal{D}_n are defined by (27), (28), (29).

If $A \in \mathfrak{A}$ has a determinant system in \mathfrak{A} and $A \in \mathfrak{B}$, then A has also a determinant system in \mathfrak{B} (viz. the same determinant system has this property).

§ 7. Determinant systems in product spaces. Suppose that the spaces \mathcal{E}' , X' are conjugate, and \mathcal{E}'' , X'' are conjugate. Let $\mathcal{E} = \mathcal{E}' \times \mathcal{E}''$ and $X = X' \times X''$. For every point $x \in X$, x' and x'' always denote such points in X' and X'' respectively that $x = (x', x'')$. Analogously, if $\xi \in \mathcal{E}$, then ξ' and ξ'' always denote such points in \mathcal{E}' and \mathcal{E}'' respectively that $\xi = (\xi', \xi'')$.

THEOREM IV. If

$$(43) \quad D'_0, D'_1, D'_2, \dots$$

is a determinant system for a bilinear functional A' on $\mathcal{E}' \times X'$, and

$$(44) \quad D''_0, D''_1, D''_2, \dots$$

is a determinant system for a bilinear functional A'' on $\mathcal{E}'' \times X''$, then the formulas

$$(45) \quad D_n \begin{pmatrix} \xi_1, \dots, \xi_n \\ x_1, \dots, x_n \end{pmatrix} = \sum_{s=0}^n \sum_{p,q} \text{sgn } p \cdot \text{sgn } q \cdot D'_s \begin{pmatrix} \xi'_{p_1}, \dots, \xi'_{p_s} \\ x'_{q_1}, \dots, x'_{q_s} \end{pmatrix} \cdot D''_{n-s} \begin{pmatrix} \xi''_{p_{s+1}}, \dots, \xi''_{p_n} \\ x''_{q_{s+1}}, \dots, x''_{q_n} \end{pmatrix}$$

(where $\sum_{p,q}$ is extended over all the permutations $p = (p_1, \dots, p_n)$ and $q = (q_1, \dots, q_n)$ of the integers $1, \dots, n$, such that

$$p_1 < p_2 < \dots < p_s, \quad p_{s+1} < p_{s+2} < \dots < p_n,$$

$$q_1 < q_2 < \dots < q_s, \quad q_{s+1} < q_{s+2} < \dots < q_n$$

define a determinant system (in \mathcal{A})

$$(46) \quad D_0, D_1, D_2, \dots$$

for the bilinear functional $A = (A', A'')$ on $\mathcal{E} \times X$ (see definition (19)).

It is evident that (46) has the properties (d_1) , (d_2) and (d_3) . It also has the property (d_4) since if r' and r'' are orders of (43) and (44) respectively, and points $x'_1, \dots, x'_{r'} \in X'$, $x''_{r'+1}, \dots, x''_{r'+r''} \in X''$, $\xi'_1, \dots, \xi'_{r'} \in \mathcal{E}$, $\xi'_{r'+1}, \dots, \xi'_{r'+r''}$ are such that

$$(47) \quad D_{r'} \begin{pmatrix} \xi'_1, \dots, \xi'_{r'} \\ x'_1, \dots, x'_{r'} \end{pmatrix} \neq 0, \quad D''_{r''} \begin{pmatrix} \xi'_{r'+1}, \dots, \xi'_{r'+r''} \\ x''_{r'+1}, \dots, x''_{r'+r''} \end{pmatrix} \neq 0,$$

then $D_{r'+r''} \begin{pmatrix} \xi'_1, \dots, \xi'_{r'+r''} \\ x'_1, \dots, x'_{r'+r''} \end{pmatrix}$ is different from zero for

$$x_i = (x'_i, 0), \quad \xi_i = (\xi'_i, 0) \quad (i = 1, \dots, r'),$$

$$x_{r'+i} = (0, x''_{r'+i}), \quad \xi_i = (0, \xi'_{r'+i}) \quad (i = 1, \dots, r''),$$

since its value is then equal to the product of scalars (47).

We have to prove that (46) satisfies the identities (D_n) and (D'_n) . Since ξ 's and x 's play a symmetric role everywhere, it suffices to prove only (D_n) .

By definition (45), we have

$$\begin{aligned} & D_{n+1} \begin{pmatrix} \xi_0, \xi_1, \dots, \xi_n \\ x_0, x_1, \dots, x_n \end{pmatrix} \\ &= \sum_{s=0}^n \sum_{p', q'} \text{sgn } p' \cdot \text{sgn } q' \cdot D'_s \begin{pmatrix} \xi'_0, \xi'_{p_1}, \dots, \xi'_{p_s} \\ x'_{q_0}, x'_{q_1}, \dots, x'_{q_s} \end{pmatrix} \cdot D''_{n-s} \begin{pmatrix} \xi''_{p_{s+1}}, \dots, \xi''_{p_n} \\ x''_{q_{s+1}}, \dots, x''_{q_n} \end{pmatrix} + \\ &+ \sum_{s=0}^n \sum_{p'', q''} \text{sgn } p'' \cdot \text{sgn } q'' \cdot D'_s \begin{pmatrix} \xi'_{p_1}, \xi'_{p_2}, \dots, \xi'_{p_s} \\ x'_{q_0}, x'_{q_1}, \dots, x'_{q_{s-1}} \end{pmatrix} \cdot D''_{n-s+1} \begin{pmatrix} \xi''_0, \xi''_{p'_{s+1}}, \dots, \xi''_{p'_n} \\ x''_{q_s}, x''_{q_{s+1}}, \dots, x''_{q_n} \end{pmatrix} \end{aligned}$$

where p', p'', q', q'' are any permutations of numbers $0, 1, \dots, n$ such that

$$(48) \quad p' = (0, p_1, \dots, p_n), \quad p_1 < \dots < p_s, \quad p_{s+1} < \dots < p_n,$$

$$(49) \quad p'' = (p_1, \dots, p_s, 0, p_{s+1}, \dots, p_n), \quad p_1 < \dots < p_s, \quad p_{s+1} < \dots < p_n,$$

$$(50) \quad q' = (q_0, \dots, q_n), \quad q_0 < \dots < q_s, \quad q_{s+1} < \dots < q_n,$$

$$(51) \quad q'' = (q_0, \dots, q_n), \quad q_0 < \dots < q_{s-1}, \quad q_s < \dots < q_n.$$

By (D_s) and (D_{n-s}) ,

$$\begin{aligned} & D_{n+1} \begin{pmatrix} \xi_0 A, \xi_1, \dots, \xi_n \\ x_0, x_1, \dots, x_n \end{pmatrix} \\ &= \sum_{s=0}^n \sum_{p', q'} (-1)^j \cdot \text{sgn } p' \cdot \text{sgn } q' \cdot \xi'_0 A' x'_{q'_j} \cdot D'_s \begin{pmatrix} \xi'_{p_1}, \dots, \xi'_{p_s} \\ x'_{q_0}, \dots, x'_{q_{j-1}}, x'_{q_{j+1}}, \dots, x'_{q_s} \end{pmatrix} \cdot \\ &\quad \cdot D''_{n-s} \begin{pmatrix} \xi''_{p_{s+1}}, \dots, \xi''_{p_n} \\ x''_{q_{s+1}}, \dots, x''_{q_n} \end{pmatrix} + \\ &+ \sum_{s=0}^n \sum_{p'', q''} (-1)^j \cdot \text{sgn } p'' \cdot \text{sgn } q'' \cdot \xi'_0 A'' x''_{q''_{s+j}} \cdot D'_s \begin{pmatrix} \xi'_{p_1}, \dots, \xi'_{p_s} \\ x'_{q_0}, \dots, x'_{q_{s-1}} \end{pmatrix} \cdot \\ &\quad \cdot D''_{n-s} \begin{pmatrix} \xi''_{p_{s+1}}, \dots, \xi''_{p_n} \\ x''_{q_s}, \dots, x''_{q_{s+j-1}}, x''_{q_{s+j+1}}, \dots, x''_{q_n} \end{pmatrix} \\ &= \sum_{i=0}^n (-1)^i \cdot \xi'_0 A' x'_i \cdot \sum_{s=0}^n \sum_{p'_0, q'_i} \text{sgn } p'_0 \cdot \text{sgn } q'_i \cdot D'_s \begin{pmatrix} \xi'_{p_1}, \dots, \xi'_{p_s} \\ x'_{q_{i,1}}, \dots, x'_{q_{i,s}} \end{pmatrix} \cdot \\ &\quad \cdot D''_{n-s} \begin{pmatrix} \xi''_{p_{s+1}}, \dots, \xi''_{p_n} \\ x''_{q_{i,s-1}}, \dots, x''_{q_{i,n}} \end{pmatrix} + \\ &+ \sum_{i=1}^n (-1)^i \cdot \xi'_0 A'' x''_i \cdot \sum_{s=0}^n \sum_{p''_0, q''_i} \text{sgn } p''_0 \cdot \text{sgn } q''_i \cdot D'_s \begin{pmatrix} \xi'_{p_1}, \dots, \xi'_{p_s} \\ x'_{q_{i,1}}, \dots, x'_{q_{i,s}} \end{pmatrix} \cdot \\ &\quad \cdot D''_{n-s} \begin{pmatrix} \xi''_{p_{s+1}}, \dots, \xi''_{p_n} \\ x''_{q_{i,s+1}}, \dots, x''_{q_{i,n}} \end{pmatrix}. \end{aligned}$$

In the last formula, $p'_0 = (p_1, \dots, p_n)$ and $p''_0 = (p_1, \dots, p_n)$ are permutations (of the integers $1, \dots, n$) obtained from p' and p'' respectively (see (48) and (49)) by omitting the number zero; consequently

$$p_1 < \dots < p_s \quad \text{and} \quad p_{s+1} < \dots < p_n.$$

Similarly $q'_i = (q_{i,1}, \dots, q_{i,n})$ and $q''_i = (q_{i,1}, \dots, q_{i,n})$ are permutations (of numbers $0, \dots, i-1, i+1, \dots, n$) obtained respectively from q' and q'' (see (50) and (51)) by omitting the number i ; consequently

$$q_{i,1} < \dots < q_{i,s} \quad \text{and} \quad q_{i,s+1} < \dots < q_{i,n}.$$

The factor $(-1)^j$ is now replaced by $(-1)^i$ since if $q_j = i$, then the corresponding ± 1 -coefficients at $\xi'_0 A' x'_{q'_j}$, $\xi'_0 A'' x''_{q''_j}$ satisfy the equality

$$(-1)^j \cdot \text{sgn } p' \cdot \text{sgn } q' = (-1)^i \cdot \text{sgn } p'_0 \cdot \text{sgn } q'_i;$$

analogously, if $q_{s+j} = i$, then the corresponding ± 1 -coefficients at $\xi''_0 A'' x''_{q''_{s+j}}$, $\xi''_0 A' x'_i$ satisfy the equality

$$(-1)^j \cdot \text{sgn } p'' \cdot \text{sgn } q'' = (-1)^i \cdot \text{sgn } p''_0 \cdot \text{sgn } q''_i.$$

Consequently we have

$$\begin{aligned} D_{n+1} \begin{pmatrix} \xi_0 A, \xi_1, \dots, \xi_n \\ x_0, x_1, \dots, x_n \end{pmatrix} \\ = \sum_{i=0}^n (-1)^i \cdot \xi'_0 A' x'_i \cdot D_n \begin{pmatrix} \xi_1, \dots, \xi_n \\ x_0, \dots, x_{i-1}, x_{i+1}, \dots, x_n \end{pmatrix} + \\ + \sum_{i=0}^n (-1)^i \cdot \xi''_0 A'' x''_i \cdot D_n \begin{pmatrix} \xi_1, \dots, \xi_n \\ x_0, \dots, x_{i-1}, x_{i+1}, \dots, x_n \end{pmatrix} \\ = \sum_{i=0}^n (-1)^i \cdot \xi_0 A x_i \cdot D_n \begin{pmatrix} \xi_1, \dots, \xi_n \\ x_0, \dots, x_{i-1}, x_{i+1}, \dots, x_n \end{pmatrix} \end{aligned}$$

since $\xi'_0 A' x'_i + \xi''_0 A'' x''_i = \xi_0 A x_i$ by the definition (19) of A .

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On Leżański endomorphisms

by

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This paper is a supplement to my paper [5]⁽¹⁾.

An endomorphism T of a complex Banach space X is said to be a *Leżański endomorphism* provided the functional

$$(1) \quad F_0(K) = \text{trace } KT \quad (K \in \mathfrak{R}_0)$$

is continuous on the space \mathfrak{R}_0 of all finitely dimensional endomorphisms K in X (with respect to the usual norm of K), i. e. if it satisfies the hypotheses of Leżański's [1], [2] determinant theory of the linear equation

$$(2) \quad x + \lambda T x = x_0.$$

In [5] I quoted an example of a Leżański endomorphism T (in the space L) which was not compact (= completely continuous). However, the endomorphism T^2 was compact. The subject of this paper is to prove that this is true for every Leżański endomorphism. More precisely:

THEOREM. *If T is a Leżański endomorphism in X , then T^2 (and, consequently, T^n for $n = 2, 3, \dots$) is the limit (in the norm) of a sequence of finitely dimensional endomorphisms.*

Let F be any continuous linear extension of F_0 (see (1)) over the space \mathfrak{R} of all linear continuous endomorphisms (with the usual norm) in X . Let $D_0(\lambda)$ be the Leżański determinant of (2), determined by F . $D_0(\lambda)$ is an entire function of λ and, for small λ ,

$$(3) \quad D_0(\lambda) = \exp \left(\frac{\sigma_1 \lambda}{1} - \frac{\sigma_2 \lambda^2}{2} + \frac{\sigma_3 \lambda^3}{3} - \frac{\sigma_4 \lambda^4}{4} + \dots \right)$$

where

$$(4) \quad \sigma_n = F(T^{n-1}) \quad \text{for } n = 1, 2, \dots$$

⁽¹⁾ Errata to [5]. In footnote (4) on p. 106 instead of " \mathfrak{R}^* is identical with \mathfrak{R}_* " we should have " K_* is identical with the class of all T satisfying (*)".

Errata to [4]. The lines 18-30 on p. 46 should be omitted.