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A MIXED GAME OF TIMING: PROBLEM OF OPTIMALITY

The present paper is a continuation of paper [2]. Therefore, all notation, Definitions 1-8, Lemmas 1-10, and relations (1)-(41) given therein are binding in what follows.

1. Proof of Theorem 1. Before proving the theorem we formulate some lemmas.

LEMMA 11. If $S \in \{S(\varepsilon)\}_{s>0} \in N_{\lambda}$ ($\|\lambda\| \geqslant 2$), then the strategy S is admissible in the game Γ_{λ} .

This lemma follows easily from Lemmas 5-8 and from the relation $S_{\lambda_1}^*(\varepsilon/2) \in B_{|\lambda_1|}^0(\lambda_1)$.

LEMMA 12. For a strategy $F \in M_{\pi}$ and a family $\{S(\varepsilon)\}_{\varepsilon>0} \in N_{\pi} (\|\pi\| \geqslant 2)$ described by (38) and (41),

- (i) $K(F; y | \pi)$ is a continuous function of the variable y in the interval (a_2, a_{π}) ;
- (ii) $K(D_x(x_1) \cdot F_{\pi_1}^*(\overline{x}_{n,1}); S(\varepsilon) | \pi)$ is a continuous function of the variable x in the interval $\langle b_2, a_{\pi_1} \rangle$ for $\varepsilon > 0$.

Proof. Let $x \in (\bar{b_2}, a_{n_1})$. Then, with the aid of (5), (13), (9), (6), (3) and (4), we get

$$\begin{split} K\big(D_x(x_1)\cdot F_{\pi_1}^*(\overline{x}_{n,1}); \ S(\varepsilon)\,|\,\pi\big) \\ &= (1-a)\int \Big\{ \int\limits_{y>x_1} \big\{P(x) + [1-P(x)][1-2Q(y)]\big\} dT_{b_2}(y) + \\ &+ \int\limits_{y< x} \big[1-2Q(y)]dT_{b_2}(y) \Big\} \, dF_{\pi_1}^*(\overline{x}_{n,1}) + \\ &+ a\int \Big\{P(x) + [1-P(x)]K\left(\overline{x}_{n,1}; \ S_{\pi_1}^*\left(\frac{\varepsilon}{2}\right)\,|\,\pi_1\right) \Big\} \, dF_{\pi_1}^*(\overline{x}_{n,1}), \end{split}$$

whence it follows that statement (ii) of the lemma is true. Statement (i) can be concluded similarly.

LEMMA 13. Under the assumptions of Theorem 1, if w = c and the family $\{S(\varepsilon)\}_{\varepsilon>0}$ is of the form (41), then a < 1.

Proof. Let us assume that a=1. Then for any $\varepsilon>0$ we have $S(\varepsilon)=S_{\pi_1}^*(\varepsilon/2)$.

Hence we infer the validity of the inequalities

(42)
$$K\left(F;\ S_{\pi_1}^*\left(\frac{\varepsilon}{2}\right)|\pi\right) \geqslant v_{\pi}$$

and

(43)
$$K\left(F'; S_{\pi_1}^*\left(\frac{\varepsilon}{2}\right)|\pi\right) \leqslant v_{\pi} + \varepsilon$$

for any positive ε and for all $F' \in A_{\|\pi\|}$, where v_{π} is the value of the game Γ_{π} . Let us put

$$egin{align} F(\overline{x}_n) &= U_{a_2}(x_1) \cdot F_{\pi_1}^*(\overline{x}_{n,1}) & (n = \|\pi\|), \ S_{\pi_1}^*\left(rac{arepsilon}{2}
ight) &= [G^m, \{s_m(y)\}_y] & (m = |\pi|). \ \end{array}$$

By the definition of the strategy $S_{\pi_1}^*(\varepsilon/2)$ it can be concluded, with the help of (7) and (11), that $\operatorname{supp} G^m \subset \langle a_{\pi_1}, 1 \rangle$ and that G^m is a continuous measure.

Further, we put

$$F^{1}(\bar{x}_{n}) = D_{a_{\pi_{1}}}(x_{1}) \cdot F^{*}_{\pi_{1}}(\bar{x}_{n,1}).$$

On account of the definitions of F, $S_{\pi_1}^*(\varepsilon/2)$ and F^1 the following sequence of equalities is valid:

$$\begin{split} K\left(F^{1}(\overline{x}_{n});\ S_{\pi_{1}}^{*}\left(\frac{\varepsilon}{2}\right)|\pi\right) &\stackrel{(5)}{=} \int K\left((a_{\pi_{1}},\overline{x}_{n,1});\ S_{\pi_{1}}^{*}\left(\frac{\varepsilon}{2}\right)|\pi\right) dF_{\pi_{1}}^{*}(\overline{x}_{n,1}) \\ &\stackrel{(3)}{=} \int \int K\left((a_{\pi_{1}},\overline{x}_{n,1});\ s_{m}(y)|\pi\right) dG^{m}(y) dF_{\pi_{1}}^{*}(\overline{x}_{n,1}) \\ &\stackrel{(4)}{=} \int \int \left\{P\left(a_{\pi_{1}}\right) + [1 - P\left(a_{\pi_{1}}\right)]K\left(\overline{x}_{n,1};\ s_{m}(y)|\pi_{1}\right)\right\} dG^{m}(y) dF_{\pi_{1}}^{*}(\overline{x}_{n,1}) \\ &\stackrel{(3)(5)}{=} P\left(a_{\pi_{1}}\right) + [1 - P\left(a_{\pi_{1}}\right)]K\left(F_{\pi_{1}}^{*};\ S_{\pi_{1}}^{*}\left(\frac{\varepsilon}{2}\right)|\pi_{1}\right) \\ &\stackrel{(35)}{=} P\left(a_{\pi_{1}}\right) + [1 - P\left(a_{\pi_{1}}\right)][1 - 2Q\left(a_{\pi_{1}}\right)] \\ &= \int_{a_{2}}^{a_{\pi_{1}}} \left\{P\left(x_{1}\right) + [1 - P\left(x_{1}\right)][1 - 2Q\left(a_{\pi_{1}}\right)]\right\} dU_{a_{2}}(x_{1}) + h, \end{split}$$

where h is a positive number independent of ε .

Analogously it can be shown that

$$K\left(F; S_{\pi_1}^*\left(\frac{\varepsilon}{2}\right)|\pi\right) = \int\limits_{a_2}^{a_{\pi_1}} \left\{P(x_1) + [1-P(x_1)][1-2Q(a_{\pi_1})]\right\} dU_{a_2}(x_1).$$

Therefore

$$K\Big(F^1;\; S^*_{\pi_1}\Big(rac{arepsilon}{2}\Big)|\pi\Big) = K\Big(F;\; S^*_{\pi_1}\Big(rac{arepsilon}{2}\Big)|\pi\Big) + h \quad ext{ for any } arepsilon > 0\,,$$

which contradicts relations (42) and (43).

Thus $\alpha < 1$.

LEMMA 14. Under the assumptions of Theorem 1, if F and $\{S(\varepsilon)\}_{\varepsilon>0}$ take the forms determined by (37)-(41), then

- (i) $a_1 = b_1$ in the case w = g,
- (ii) $a_2 = b_2$ in the case w = c.

The proof is immediate because of the monotonicity of the functions P(t) and Q(t).

LEMMA 15. If the assumptions of Theorem 1 are satisfied in the case w=c and if the strategy F and the family $\{S(\varepsilon)\}_{\varepsilon>0}$ are of the forms given by (38) and (41) with the condition $a_2=b_2=a$, respectively, then

$$(44) K(F; y|\pi) = v_{\pi}$$

for any $y \in \langle a, a_{n_1} \rangle$,

(45)
$$K(D_x(x_1) \cdot F_{\pi_1}^*(\overline{x}_{n,1}); S(\varepsilon) | \pi) = v_{\pi}$$

for any $\varepsilon > 0$ and for all $x \in (a, a_{n_1})$, where v_n is the value of the game Γ_n .

Proof. The assumptions of the lemma imply

(46)
$$K(F; y \mid \pi) \geqslant v_{\pi}, \quad y \in \langle a, a_{\pi} \rangle,$$

$$K(F; S(\varepsilon)|\pi) \leqslant v_{\pi} + \varepsilon \quad (\varepsilon > 0).$$

Assume that for a certain $y_0 \in \langle a, a_{n_1} \rangle$ we have $K(F; y_0 | \pi) > v_{\pi}$. Then, by Lemma 12, there exist a number $\varepsilon_0 > 0$ and a neighbourhood Z_0 of the point y_0 such that

(48)
$$T_a(Z_0) > 0, \quad K(F; y | \pi) > v_{\pi} + \varepsilon_0, y \in Z_0.$$

Hence, in view of the inequality a < 1 (the result of Lemma 13), we can evaluate the following:

$$\begin{split} v_{\pi} + \varepsilon &\geqslant K \big(F; \ S(\varepsilon) \, | \, \pi \big) \\ &\stackrel{(5)(13)}{=} (1-a) \int K(\overline{x}_n; \ S_{|\pi|}^{T_a} \, | \, \pi) \, dF(\overline{x}_n) + a \int K \left(\overline{x}_n; \ S_{\pi_1}^* \left(\frac{\varepsilon}{2} \right) | \, \pi \right) dF(\overline{x}_n) \\ &\stackrel{(9)(5)}{=} (1-a) \int \int K(\overline{x}_n; \ y \, | \, \pi) \, dT_a(y) \, dF(\overline{x}_n) + aK \left(F; \ S_{\pi_1}^* \left(\frac{\varepsilon}{2} \right) | \, \pi \right) \\ &\stackrel{(5)}{=} (1-a) \int K(F; \ y \, | \, \pi) \, dT_a(y) + aK \left(F; \ S_{\pi_1}^* \left(\frac{\varepsilon}{2} \right) | \, \pi \right) \end{split}$$

$$= (1-a) \int_{\mathbf{y} \in Z_0} K(F; \ y \mid \pi) dT_a(y) + (1-a) \int_{\mathbf{y} \notin Z_0} K(F; \ y \mid \pi) dT_a(y) + \\ + \alpha K \left(F; \ S_{\pi_1}^* \left(\frac{\varepsilon}{2} \right) \mid \pi \right) \\ > (1-a) \int_{\mathbf{y} \in Z_0} (v_\pi + \varepsilon_0) dT_a(y) + (1-a) \int_{\mathbf{y} \notin Z_0} v_\pi dT_a(y) + \alpha K \left(F; \ S_{\pi_1}^* \left(\frac{\varepsilon}{2} \right) \mid \pi \right) \\ \geqslant (1-a) v_\pi + a v_\pi + (1-a) \varepsilon_0 T_a(Z_0) = v_\pi + d,$$

where d is a positive number independent of ε .

Therefore $v_{\pi} + \varepsilon > v_{\pi} + d$ for any $\varepsilon > 0$, which is impossible. Thus condition (44) is valid.

Now, let $x \in \langle a, a_{n_1} \rangle$. From the ε -optimality of the strategy $S(\varepsilon)$ it follows that for any $\varepsilon > 0$

$$K(D_x(x_1) \cdot F_{\pi_1}^*(\overline{x}_{n,1}); S(\varepsilon) | \pi) \leqslant v_\pi + \varepsilon.$$

We show that the left-hand side of this inequality does not depend on ϵ .

Indeed, we have

$$\begin{split} K \big(D_x(x_1) \cdot F_{\pi_1}^*(\overline{x}_{n,1}); \ S(\varepsilon) \, | \, \pi \big) \\ &\stackrel{(5)(13)}{=} (1-a) \int K(\overline{x}_n; \ S_{|\pi|}^{T_a} | \, \pi) \, d \, \{ D_x(x_1) \cdot F_{\pi_1}^*(\overline{x}_{n,1}) \} \, + \\ &\quad + a \int \Big\{ P(x) + [1-P(x)] K \Big(\overline{x}_{n,1}; \ S_{\pi_1}^* \Big(\frac{\varepsilon}{2} \Big) | \, \pi_1 \Big) \Big\} \, dF_{\pi_1}^*(\overline{x}_{n,1}) \\ &= (1-a) K \big(D_x(x_1) \cdot F_{\pi_1}^*(\overline{x}_{n,1}); \ S_{|\pi|}^{T_a} | \, \pi \big) + \\ &\quad + a \Big\{ P(x) + [1-P(x)] K \Big(F_{\pi_1}^*; \ S_{\pi_1}^* \Big(\frac{\varepsilon}{2} \Big) | \, \pi_1 \Big) \Big\} \\ \stackrel{(35)}{=} (1-a) K \big(D_x(x_1) \cdot F_{\pi_1}^*(\overline{x}_{n,1}); \ S_{|\pi|}^{T_a} | \, \pi \big) + \\ &\quad + a \{ P(x) + [1-P(x)] [1-2Q(a_{\pi_1})] \}, \end{split}$$

which is of course independent of ε .

Therefore, for any $\varepsilon > 0$ and for all $x \in \langle a, a_{\pi_1} \rangle$ we get

$$K(D_x(x_1) \cdot F_{\pi_1}^*(\overline{x}_{n,1}); S(\varepsilon) | \pi) \leqslant v_{\pi}.$$

Suppose that for a certain $x_0 \in \langle a, a_{\pi_1} \rangle$ we have

$$K(D_{x_0}(x_1) \cdot F_{n_1}^*(\bar{x}_{n,1}); S(\varepsilon) | \pi) < v_{\pi}.$$

Then, by Lemma 12, there exist a number $\varepsilon_1 > 0$ and a neighbourhood Z_1 of the point x_0 such that $U_a(Z_1) > 0$ and

$$K(D_x(x_1) \cdot F_{\pi_1}^*(\overline{x}_{n,1}); S(\varepsilon) | \pi) < v_\pi - \varepsilon_1, \quad x \in Z_1.$$

Hence

$$\begin{split} K(F;\;S(\varepsilon)\,|\,\pi) &= \int\limits_a^{a_{n_1}} K\big(D_x(x_1)\cdot F_{n_1}^{\star}(\overline{x}_{n,1});\;S(\varepsilon)\,|\,\pi\big) d\,U_a(x) \\ &< \int\limits_{x\notin Z_1} v_{\pi}d\,U_a(x) + \int\limits_{x\in Z_1} (v_{\pi}-\varepsilon_1)\,d\,U_a(x) = v_{\pi}-\varepsilon_1\,U_a(Z_1), \end{split}$$

which contradicts the assumption of the optimality of the strategy F. Therefore, equality (45) holds.

LEMMA 16. If the assumptions of Theorem 1 are satisfied in the case w=g and if the strategy F and the family $\{S(\varepsilon)\}_{\varepsilon>0}$ are of the forms given by (37) and (39), (40), respectively, then under the condition $a_1=b_1=b$ the equalities

(49)
$$P(b) + [1 - P(b)][1 - 2Q(a_{\tau_1})] = v_{\tau_1},$$

$$(50) 1-2Q(b) = v_r$$

are valid.

Proof. Using the optimality of the strategies F and $S(\varepsilon)$ we conclude that

$$\begin{split} v_{\tau} \leqslant & \lim_{\boldsymbol{y} \to a_{\tau_{1}}^{-}} K(F; \ \boldsymbol{y} \mid \tau) \stackrel{\text{(5)(6)}}{=} P(b) + [1 - P(b)][1 - 2Q(\boldsymbol{a}_{\tau_{1}})] \\ \stackrel{\text{(35)}}{=} P(b) + [1 - P(b)]K\left(F_{\tau_{1}}^{*}; \ S_{\tau_{1}}^{*}\left(\frac{\varepsilon}{2}\right) \mid \tau\right) \\ \stackrel{\text{(5)(4)(3)}}{=} K(F; \ S(\varepsilon) \mid \tau) \leqslant v_{\tau} + \varepsilon. \end{split}$$

Considering that ε is an arbitrary positive number we get equality (49). Now we prove (50). Under the assumption b=0, equalities (49) and (50) would imply the relation $Q(a_{\tau_1})=0$, which contradicts inequality (29). Therefore we have b>0.

Hence, reasoning analogously as above, we get

$$\begin{split} v_{\tau} &\leqslant \lim_{y \to b^{-}} K(F; \ y \,|\, \tau) \stackrel{\text{(5)(6)}}{=} 1 - 2Q(b) \\ &= \lim_{\varepsilon \to 0^{+}} \int \big[1 - 2Q(y) \big] dH_{\langle b, b + \delta(\varepsilon) \rangle}(y) \stackrel{\text{(5)(4)(3)}}{=} \lim_{\varepsilon \to 0^{+}} K \big(D_{a_{\tau_{1}}}(x_{1}) \cdot F_{\tau_{1}}^{*}(\overline{x}_{n,1}); \ S(\varepsilon) \,|\, \tau \big) \\ &\leqslant \lim_{\varepsilon \to 0^{+}} (v_{\tau} + \varepsilon) \,= \, v_{\tau}, \end{split}$$

which implies (50).

Proof of Theorem 1. First we consider the case w = c.

By Lemmas 13 and 14 it can be concluded that the strategy F and the family $\{S(\varepsilon)\}_{\varepsilon>0}$ are of the forms

$$F(\bar{x}_n) = U_a(x_1) \cdot F_{\pi_1}^*(\bar{x}_{n,1}) \quad (\|\pi\| = n),$$

$$S(\varepsilon) = \left[(1-a) S_{|\pi|}^{T_a} + a S_{\pi_1}^* \left(\frac{\varepsilon}{2} \right) \right] \quad (\varepsilon > 0),$$

where supp $U_a = \sup T_a = \langle a, a_{\pi_1} \rangle$, and a and a are certain numbers such that $0 \leq a < a_{\pi_1}$ and $0 \leq a < 1$.

Let $y \in (a, a_{\pi_1})$. Then

$$\begin{split} v_{\pi} &\stackrel{(44)(5)}{=} \int\limits_{a}^{a_{\pi_{1}}} K(D_{x}(x_{1}) \cdot F_{\pi_{1}}^{*}(\overline{x}_{n,1}); \ y \mid \pi) dU_{a}(x) \\ &\stackrel{(5)(6)}{=} \int\limits_{a}^{y} \left\{ P(x) + [1 - P(x)] K(F_{\pi_{1}}^{*}(\overline{x}_{n,1}); \ y \mid \pi_{1}) \right\} dU_{a}(x) + \\ &+ \int\limits_{y}^{a_{\pi_{1}}} [1 - 2Q(y)] dU_{a}(x) \\ &\stackrel{(5)(6)}{=} \int\limits_{a}^{y} \left\{ P(x) + [1 - P(x)] [1 - 2Q(y)] \right\} dU_{a}(x) + \int\limits_{y}^{a_{\pi_{1}}} [1 - 2Q(y)] dU_{a}(x) \\ &= 1 - 2Q(y) + \int\limits_{a}^{y} 2Q(y) P(x) dU_{a}(x). \end{split}$$

The above transformation and (5) lead to the identity

(51)
$$K(F_{\pi}^{*}; y | \pi) = 1 - 2Q(y) + \int_{a_{\pi}}^{y} 2Q(y)P(x)dU_{\pi}(x), \quad a_{\pi} \leq y < a_{\pi_{1}}$$

(it is sufficient to repeat the transformation for $U_a = U_{\pi}$ defined by (24) beginning with the second component of the sequence of equalities) and to the equation

(52)
$$\int_{a}^{y} P(x_{1}) dU_{a}(x_{1}) = \frac{v_{\pi} - 1}{2Q(y)} + 1.$$

Integrating by parts we see that $U_a(x_1)$ must be absolutely continuous in the interval (a, a_{x_1}) , and then, differentiating with respect to y, we get

$$rac{dU_a(x_1)}{dx_1} = rac{(v_\pi - 1)Q'(x_1)}{2P(x_1)Q^2(x_1)}, \quad a < x_1 < a_{\pi_1}.$$

Further, relation (52) is valid for y = a, which yields

$$(53) v_n = 1 - 2Q(a),$$

whence

$$rac{d\,U_a(x_1)}{dx_1} = rac{Q\,(a)Q'\,(x_1)}{P\,(x_1)Q^2\,(x_1)}\,, ~~ a < x_1 < a_{\pi_1}.$$

Since U_a is a probability measure, we have

$$\int\limits_{a}^{a_{\pi_{1}}} rac{Q(a)Q'(x_{1})}{P(x_{1})Q^{2}(x_{1})} dx_{1} = 1.$$

Thus, in view of (31), $a=a_{\pi}$. Hence, using (24) and (53), we conclude that $F=F_{\pi}^*$ and

$$v_n = 1 - 2Q(a_n).$$

Now we show that $S(\varepsilon) = S_{\pi}^{*}(\varepsilon)$ for any $\varepsilon > 0$. Assuming $x \in \langle a_{\pi}, a_{\pi_{1}} \rangle$ we have

$$\begin{split} v_n &\stackrel{(45)}{=} K\left(D_x(x_1) \cdot F_{\pi_1}^*(\bar{x}_{n,1}); \ S(\varepsilon) | \pi\right) \\ &\stackrel{(9)(13)}{=} (1-a) \int\limits_{a_n}^{a_{\pi_1}} K\left(D_x(x_1) \cdot F_{\pi_1}^*(\bar{x}_{n,1}); \ y | \pi\right) dT_a(y) + \\ &+ aK\left(D_x(x_1) \cdot F_{\pi_1}^*(\bar{x}_{n,1}); \ S_{\pi_1}^*\left(\frac{\varepsilon}{2}\right) | \pi\right) \\ &\stackrel{(3)-(6)}{=} (1-a) \int\limits_{a_n}^{x} [1-2Q(y)] dT_a(y) + \\ &+ (1-a) \int\limits_{x}^{a_{\pi_1}} \{P(x) + [1-P(x)][1-2Q(y)]\} dT_a(y) + \\ &+ a\left\{P(x) + [1-P(x)]K\left(F_{\pi_1}^*; \ S_{\pi_1}^*\left(\frac{\varepsilon}{2}\right) | \pi_1\right)\right\} \\ &\stackrel{(35)}{=} (1-a) \int\limits_{a_n}^{a_{\pi_1}} [1-2Q(y)] dT_a(y) + (1-a) \int\limits_{x}^{a_{\pi_1}} 2Q(y)P(x) dT_a(y) + \\ &+ a\{1-2Q(a_{\pi_1})[1-P(x)]\}. \end{split}$$

The above transformation leads to the identities

$$\begin{split} (55) \qquad & K \big(D_x(x_1) \cdot F_{\pi_1}^*(\overline{x}_{n,1}); \ S_\pi^*(\varepsilon) \, | \, \pi \big) = (1 - a_\pi) \int\limits_{a_\pi}^{a_{\pi_1}} \left[1 - 2Q(y) \right] dT_\pi(y) \, + \\ & + (1 - a_\pi) \int\limits_x^{a_{\pi_1}} 2Q(y) P(x) \, dT_\pi(y) + a_\pi \{ 1 - 2Q(a_{\pi_1}) [1 - P(x)] \}, \qquad a_\pi \leqslant x < a_\pi \} \end{split}$$

(it is sufficient to repeat that transformation for $T_a = T_{\pi}$, $\alpha = a_{\pi}$ and $S(\varepsilon) = S_{\pi}^*(\varepsilon)$, beginning with the second component of the sequence

of equalities) and

$$\begin{aligned} (56) \qquad v_{\pi} &= (1-a) \int\limits_{a_{\pi}}^{a_{\pi_{1}}} [1-2Q(y)] dT_{a}(y) + \\ &+ (1-a) \int\limits_{x}^{a_{\pi_{1}}} 2Q(y) P(x) dT_{a}(y) + a \{1-2Q(a_{\pi_{1}})[1-P(x)]\}, \\ &a \leqslant x < a_{\pi_{1}}. \end{aligned}$$

Putting $x = a_{\pi_1}$ in the last identity we get

$$v_{\pi} = (1-a) \int_{a_{\pi}}^{a_{\pi_{1}}} [1-2Q(y)] dT_{a}(y) + a \{1-2Q(a_{\pi_{1}})[1-P(a_{\pi_{1}})]\}.$$

Hence identity (56) can be transformed to the following form:

$$\int\limits_{x}^{a_{\pi_{1}}}Q(y)\,dT_{a}(y)\,=\,\frac{a}{1-a}\,\frac{Q(a_{\pi_{1}})[P(a_{\pi_{1}})-P(x)]}{P(x)},\quad \, a_{\pi}\leqslant x < a_{\pi_{1}}.$$

Integrating by parts we see that $T_a(y)$ must be absolutely continuous in the interval (a_n, a_{n_1}) , and then, differentiating with respect to x, we have

$$rac{dT_a(y)}{dy} = rac{lP'(y)}{Q(y)P^2(y)}, \quad a_\pi < y < a_{\pi_1},$$

where

$$l=P(a_{\pi_1})Q(a_{\pi_1})rac{a}{1-a}$$
 .

Since T_a is a probability measure, we obtain

$$\int_{a_{\pi}}^{a_{\pi_1}} dT_a(y) = 1.$$

Summarizing, equations (25), (26) and (34) imply $a = a_{\pi}$ and $T_a = T_{\pi}$, which means that $S(\varepsilon) = S_{\pi}^{*}(\varepsilon)$ for any $\varepsilon > 0$.

Thus Theorem 1 has been proved in the case w = c.

Now we consider the case w=g. By Lemma 14 the strategy F and the family $\{S(\varepsilon)\}_{\varepsilon>0}$ are of the forms

$$egin{align} F(\overline{x}_n) &= D_b(x_1) \cdot F_{ au_1}^*(\overline{x}_{n,1}) & (\| au\| = n), \ & S(arepsilon) &= \left[H_{\langle b,b+\delta(arepsilon)
angle}, \left\{ S_{ au_1}^*\left(rac{arepsilon}{2}
ight)
ight\}_{r_1}
ight] & (arepsilon > 0). \end{split}$$

Comparing the left-hand sides of equations (49) and (50) we get

$$Q(a_{\tau_1}) = \frac{Q(b)}{1 - P(b)},$$

which, in view of (21), gives $b = a_r$ and

$$(57) v_{\tau} = 1 - 2Q(a_{\tau}).$$

Therefore, $F = F_{\tau}^*$, and if $\delta(\varepsilon) = \delta_{\tau}(\varepsilon)$, $H_{\langle b,b+\delta(\varepsilon)\rangle} = H_{\tau}^*(\varepsilon)$, then, finally, $S(\varepsilon) = S_{\tau}^*(\varepsilon)$.

Thus Theorem 1 is valid also in the case w = g.

At the end of this section we give a lemma which will be used in the proof of optimality.

LEMMA 17. The following equalities are valid:

(58)
$$K(F_{\pi}^*; y|\pi) = v_{\pi}, \quad a_{\pi} \leqslant y < a_{\pi_1},$$

$$(59) K(D_x(x_1) \cdot F_{\pi_1}^*(\overline{x}_{n,1}); \ S_{\pi}^*(\varepsilon) | \pi) = v_{\pi}, \varepsilon > 0, \ a_{\pi} \leqslant x < a_{\pi_1}.$$

Proof. Equality (58) follows immediately from (51) and (24), and equality (59) is a simple consequence of (55) and (25).

2. Proof of optimality of strategies F_{λ}^* and $S_{\lambda}^*(\varepsilon)$. In this section we show that the strategies F_{λ}^* and $S_{\lambda}^*(\varepsilon)$ are optimal for player A and ε -optimal for player B, respectively, and the number v_{λ} given by (54) and (57) is the value of the game Γ_{λ} .

LEMMA 18. The following inequalities are valid:

- (i) $K(F_{1|g}^*; S|1|g) \geqslant v_{1|g} \text{ for all } S \in B_1^0(1|g),$
- (ii) $K(F; S_{1|g}^*(\varepsilon)|1|g) \leqslant v_{1|g}$ for all $F \in A_1$ $(\varepsilon > 0)$,
- (iii) $K(F_{n|c}^*; S|n|c) \geqslant v_{n|c}$ for all $S \in B_0^0(n|c)$ $(n \geqslant 1)$,
- (iv) $K(F; S_{n|c}^*(\varepsilon)|n|c) \leqslant v_{n|c}$ for all $F \in A_n$ $(\varepsilon > 0, n \geqslant 1)$.

Proof. The first two inequalities are a particular case of the result of paper [1], the next two were proved in [3].

THEOREM 2. For every vector λ the strategies F_{λ}^* and $S_{\lambda}^*(\varepsilon)$ satisfy the inequalities

(60)
$$K(F_{\lambda}^*; S | \lambda) \geqslant v_{\lambda}$$

for any $S \in B^0_{|\lambda|}(\lambda)$ and

(61)
$$K(F; S_{\lambda}^{*}(\varepsilon) | \lambda) \leqslant v_{\lambda} + \varepsilon$$

for any $F \in A_{||\lambda||}$ and for all $\varepsilon > 0$.

Proof. We prove by induction with respect to the number $n = ||\lambda||$. Step 1. If n = 1, the theorem follows immediately from Lemma 18.

Step 2. Assume that for some $n \ge 1$ and for every $(\bar{k}_r | w) = \lambda'$ such that $\|\lambda'\| = n$ inequalities (60) and (61) are satisfied for $\lambda = \lambda'$.

Step 3. Let us fix in an arbitrary way a vector $(\bar{k}_r|w) = \lambda$ such that $\|\lambda\| = n+1$. We show, under the inductive hypothesis, that inequalities (60) and (61) hold for the vector λ fixed above.

At first we consider the case w = g.

Let $S = [G^m, \{s_m(y)\}_y] = [G^m, \{S_{m-1}(v_1)\}_{v_1}] \in B_m^0(\tau)$ $(m = |\tau|)$ according to the notation given in the Remark in Section 2 of paper [2]. We investigate, using the statement of Step 2, the expression $K(F_{\tau}^*; s_m(y)|\tau)$.

(i) If $y < a_{\tau}$, we have

$$K(F_{\tau}^*; s_m(y)|\tau) \stackrel{\text{(5)(4)}}{=} 1 - 2Q(y) > 1 - 2Q(a_{\tau}) \stackrel{\text{(57)}}{=} v_{\tau}.$$

(ii) If $y = a_{\tau}$, we have

$$K(F_{\tau}^*; s_m(y)|\tau) \stackrel{(5)(4)}{=} 1 - Q(a_{\tau}) - Q(a_{\tau})[1 - P(a_{\tau})] > 1 - 2Q(a_{\tau}) \stackrel{(57)}{=} v_{\tau}.$$

(iii) If $y > a_{\tau}$, we have

$$egin{aligned} Kig(F_{ au}^*;\ s_m(y) | auig) &\stackrel{ ext{(5)(4)}}{=} P(a_{ au}) + [1 - P(a_{ au})] Kig(F_{ au_1}^*;\ S_{m-1}(a_{ au}) | au_1ig) \\ &\geqslant P(a_{ au}) + [1 - P(a_{ au})] v_{ au_1} &\stackrel{ ext{(21)(57)}}{=} v_{ au}. \end{aligned}$$

Summarizing cases (i)-(iii), we get

$$K(F_{\tau}^*; s_m(y)|\tau) \geqslant v_{\tau}, \quad 0 \leqslant y \leqslant 1,$$

whence, by (5) and (19), for every $S \in B_m^0(\tau)$ we obtain

(62)
$$K(F_{\tau}^*; S | \tau) \geqslant v_{\tau}.$$

Now we prove inequality (61) in the case w = g for the vector τ fixed in Step 3. For simplification we introduce the following notation: $b = a_{\tau} + \delta_{\tau}(\varepsilon)$ and $H = H_{\tau}^{*}(\varepsilon)$.

Analogously as before we estimate the expression $K(\bar{x}_{n+1}; S^*_{\tau}(\varepsilon)|\tau)$ for $\bar{x}_{n+1} \in \bar{X}_{n+1}$ and $\varepsilon > 0$.

(i) If $x_1 \leqslant a_{\tau}$, we have

$$\begin{split} K(\overline{x}_{n+1}; \ S_{\tau}^{*}(\varepsilon) | \tau) &\stackrel{(3)(4)}{=} P(x_{1}) + [1 - P(x_{1})] K\left(\overline{x}_{n+1,1}; \ S_{\tau_{1}}^{*}\left(\frac{\varepsilon}{2}\right) | \tau_{1}\right) \\ & \leqslant P(x_{1}) + [1 - P(x_{1})] \left(v_{\tau_{1}} + \frac{\varepsilon}{2}\right) \\ & \stackrel{(57)}{\leqslant} P(a_{\tau}) + [1 - P(a_{\tau})][1 - 2Q(a_{\tau_{1}})] + \varepsilon \stackrel{(21)(57)}{=} v_{\tau} + \varepsilon. \end{split}$$

(ii) If
$$x_1 \in (a_\tau, b)$$
, we have

$$\begin{split} &K\left(\overline{x}_{n+1};\ S_{\tau}^{*}(\varepsilon) \mid \tau\right) \\ &\stackrel{(3)(4)}{=} \int\limits_{a_{\tau}}^{x_{1}} \left[1-2Q(y)\right] dH(y) + \\ &+ \int\limits_{x_{1}}^{b} \left\{P(x_{1}) + [1-P(x_{1})]K\left(\overline{x}_{n+1,1}; S_{\tau_{1}}^{*}\left(\frac{\varepsilon}{2}\right) \mid \tau_{1}\right)\right\} dH(y) \\ &\leqslant \int\limits_{a_{\tau}}^{x_{1}} \left[1-2Q(a_{\tau})\right] dH(y) + \int\limits_{x_{1}}^{b} \left\{P(b) + [1-P(b)]K\left(\overline{x}_{n+1,1}; S_{\tau_{1}}^{*}\left(\frac{\varepsilon}{2}\right) \mid \tau_{1}\right)\right\} dH(y) \\ &\leqslant \int\limits_{a_{\tau}}^{x_{1}} \left[1-2Q(a_{\tau})\right] dH(y) + \int\limits_{x_{1}}^{b} \left\{P(b) + [1-P(b)]\left[1-2Q(a_{\tau_{1}}) + \frac{\varepsilon}{2}\right]\right\} dH(y) \\ &\leqslant \int\limits_{a_{\tau}}^{x_{1}} \left[1-2Q(a_{\tau})\right] dH(y) + \int\limits_{x_{1}}^{b} \left\{1-2Q(a_{\tau_{1}})\left[1-P(a_{\tau}) - \frac{\varepsilon}{4}\right] + \frac{\varepsilon}{2}\right\} dH(y) \\ &\leqslant \int\limits_{a_{\tau}}^{x_{1}} \left[1-2Q(a_{\tau})\right] dH(y) + \int\limits_{x_{1}}^{b} \left\{1-2Q(a_{\tau_{1}})[1-P(a_{\tau})] + \varepsilon\right\} dH(y) \\ &\leqslant \int\limits_{a_{\tau}}^{x_{1}} \left[1-2Q(a_{\tau})\right] dH(y) + \varepsilon \stackrel{(57)}{=} v_{\tau} + \varepsilon. \end{split}$$

(iii) If $x_1 \geqslant b$, we have

$$K(\overline{x}_{n+1}; S_{\tau}^*(\varepsilon) \mid \tau) \stackrel{(3)(4)}{=} \int\limits_{a_{\tau}}^{b} [1 - 2Q(y)] dH(y) \leqslant \int\limits_{a_{\tau}}^{b} [1 - 2Q(a_{\tau})] dH(y) \stackrel{(57)}{=} v_{\tau}.$$

Summarizing, for any $x_{n+1} \in \overline{X}_{n+1}$ we have

$$K(\bar{x}_{n+1}; S_{\tau}^*(\varepsilon) | \tau) \leqslant v_{\tau} + \varepsilon \quad (\varepsilon > 0),$$

which, by (5), implies finally

(63)
$$K(F; S_{\tau}^{*}(\varepsilon)|\tau) \leqslant v_{\tau} + \varepsilon$$

for any $F \in A_{n+1}$ and for all $\varepsilon > 0$.

Thus, under the inductive hypothesis, inequalities (60) and (61) have been proved in the case w = g.

Now we consider the case w = c.

Let $S = [G^m, \{s_m(y)\}_y] \in B_m^0(\pi)$ $(m = |\pi|)$. We investigate, using the statement of Step 2, the expression $K(F_{\pi}^*; s_m(y)|\pi)$.

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(i) If $y < a_{\pi}$, we have

$$K(F_{\pi}^*; \ s_m(y) \mid \pi) \stackrel{\text{(5)(4)}}{=} 1 - 2Q(y) > 1 - 2Q(a_{\pi}) \stackrel{\text{(54)}}{=} v_{\pi}.$$

(ii) If $y \in \langle a_{\pi}, a_{\pi_1} \rangle$, we have

$$K(F_{\pi}^{*}; s_{m}(y) | \pi) \stackrel{(5)(4)(6)}{=} K(F_{\pi}^{*}; y | \pi) \stackrel{(58)}{=} v_{\pi}.$$

(iii) If $y \geqslant a_{\pi_1}$, we have

$$K(F_{\pi}^{*}; s_{m}(y) | \pi) \stackrel{(5)(4)}{=} \int_{a_{\pi}}^{a_{\pi_{1}}} \{P(x_{1}) + [1 - P(x_{1})]K(F_{\pi_{1}}^{*}; s_{m}(y) | \pi_{1})\} dU_{\pi}(x_{1})$$

$$\geqslant \int_{a_{\pi}}^{(54)} \{P(x_1) + [1 - P(x_1)][1 - 2Q(a_{\pi_1})]\} dU_{\pi}(x_1) \stackrel{(23)(24)}{=} 1 - 2Q(a_{\pi}) \stackrel{(54)}{=} v_{\pi}.$$

Therefore for all $y \in \langle 0, 1 \rangle$ we get

$$K(F_{\pi}^*; s_m(y)|\pi) \geqslant v_{\pi},$$

which, by (5) and (19), implies

$$(64) K(F_{\pi}^*; S \mid \pi) \geqslant v_{\pi}$$

for all strategies $S \in B_m^0(\pi)$.

Now, taking into account relations (62)-(64), one can see that in order to complete the inductive proof of Theorem 2 it suffices to show that the inequality

(65)
$$K(F; S_{\pi}^{*}(\varepsilon) | \pi) \leq v_{\pi} + \varepsilon$$

is valid for any $F \in A_{n+1}$ and for all $\varepsilon > 0$.

In view of Lemma 18 (iii) we can restrict our investigation only to the case $r \ge 2$ ($\pi = (\bar{k}_r | c)$).

Inequality (65) is equivalent, by (5), to

(66)
$$K(\overline{x}_{n+1}; S_{\pi}^{*}(\varepsilon) | \pi) \leqslant v_{\pi} + \varepsilon$$

for any $\varepsilon > 0$ and for all $\overline{x}_{n+1} \in \overline{X}_{n+1}$.

To prove this inequality we use the forthcoming Lemmas 19-23. At first we introduce the following new notation, taking $\pi_i = (\bar{k}_{r,i}|c)$:

$$T(V) = \sum_{i=1}^{k_r} \prod_{j=1}^{i-1} \alpha_{n_{j-1}} (1 - \alpha_{n_{i-1}}) T_{n_{i-1}}(V)$$

$$\text{for } V \in \mathcal{B}(\langle 0, 1 \rangle) \; (\prod_{j=1}^{0} (\cdot) = 1),$$

$$p = \alpha_n \alpha_{n_1} \dots \alpha_{n_{k_r-1}},$$

$$t_s = \alpha_n \alpha_{n_1} \dots \alpha_{n_{s-1}} (1 - \alpha_{n_s}) l_{n_s} \quad (1 \leqslant s < k_r),$$

where T_{n_i} , a_{n_i} and l_{n_i} $(i = 0, 1, ..., k_r - 1)$ are determined by (25)-(27).

We define the auxiliary strategies $S^{j}_{\pi}(\varepsilon)$ and $S^{j}_{\pi_{1}}(\varepsilon)$ ($\varepsilon > 0$) for every $j = 0, 1, \ldots, \|\pi\|$ as follows:

$$S_{\pi_j}^j(\varepsilon) = \begin{cases} D_1 & \text{if } j = \|\pi\|, \\ S_{\pi_j}^*(\varepsilon) & \text{if } j < \|\pi\|, \end{cases}$$

$$S_{\pi_i}^j(\varepsilon) = \begin{cases} [(1 - \alpha_{\pi_i}) S_{|\pi_i|}^{T_{\pi_i}} + \alpha_{\pi_i} S_{\pi_{i+1}}^j(\varepsilon/2)] \\ & \text{if } \sum_{n=0}^{2k-1} k_{r-n} \leqslant i < \sum_{n=0}^{2k} k_{r-n} \text{ for some } k \geqslant 0 \text{ } (\sum_{n=0}^{-1} (\cdot) = 0), \\ S_{\pi_{i+1}}^j(\varepsilon/2) & \text{otherwise.} \end{cases}$$

By Lemmas 5-7 it is easy to conclude that the strategies $S_{\pi}^{j}(\varepsilon)$ and $S_{\pi_{1}}^{j}$ are admissible in the game $\Gamma_{\pi_{i}}$.

Let us associate with every noisy action of player A in the game Γ_n a point in which this action is taken under the condition that player A uses the strategy F_n^* . Now, the strategy $S_n^j(\varepsilon)$ can be interpreted in the following manner. Player B, applying the strategy $S_n^j(\varepsilon)$ $(0 \le j \le ||\pi||)$, behaves according to the strategy $S_n^*(\varepsilon)$ if all noisy actions of player A belonging to the group of j initial actions were taken not later than in the associated points.

For strategies $S_{\pi}^{j}(\varepsilon)$ and $S_{\pi_{1}}^{j}(\varepsilon)$ we obtain, with the aid of (3), (4), (9) and (13), the following equalities:

$$(68) \quad K(\overline{x}_{n+1}; \ S_{\pi}^{*}(\varepsilon) | \pi)$$

$$= 1 - \prod_{i=1}^{j} [1 - P(x_{i})] + \prod_{i=1}^{j} [1 - P(x_{i})] K(\overline{x}_{n+1,j}; \ S_{\pi}^{j}(\varepsilon) | \pi_{j})$$

$$\text{if } 0 \leq x_{1} \leq \ldots \leq x_{i} \leq a_{\pi} \ (0 \leq j \leq ||\pi||),$$

$$\begin{split} (69) \qquad K \big(\overline{x}_{n+1}; \; S_{n_1}^*(\varepsilon) \, | \, \pi \big) \\ &= 1 - \prod_{i=1}^j \; [1 - P(x_i)] + \prod_{i=1}^j \; [1 - P(x_i)] K \big(\overline{x}_{n+1,j}; \; S_{n_1}^j(\varepsilon) \, | \, \pi_j \big) \\ & \qquad \qquad \text{if} \; \; 0 \leqslant x_1 \leqslant \ldots \leqslant x_i \leqslant a_n, \; (0 \leqslant j \leqslant \|\pi\|), \end{split}$$

$$\begin{split} 70) \qquad K\big(\overline{x}_{n+1,1}; \,\, S_{n_1}^{*}(\varepsilon) \,|\, \pi_1 \big) \\ &= \, 1 - \prod_{i=2}^{j} \, [1 - P(x_i)] + \prod_{i=2}^{j} \, [1 - P(x_i)] K\big(\overline{x}_{n+1,j}; \,\, S_{n_1}^{j}(\varepsilon) \,|\, \pi_j \big) \\ & \quad \text{if} \,\, 0 \leqslant x_2 \leqslant \ldots \leqslant x_i \leqslant a_{n_1} \,\, (0 \leqslant j \leqslant \|\pi\|) \,. \end{split}$$

In the forthcoming lemmas we use the additional notation:

$$\pi_{kr} = (\bar{k}_{r,k_r}|c).$$

LEMMA 19. For any $\varepsilon>0$ and for all $\overline{x}_{n+1}\in \overline{X}_{n+1}$ satisfying $x_1>a_{n_kr}$ the inequality

$$Kig(\overline{x}_{n+1};\ S_{\pi}^{ullet}(arepsilon) | \piig) \leqslant Kig(\overline{x}_{n+1}^{(1)};\ S_{\pi}^{ullet}(arepsilon) | \piig) + rac{arepsilon}{2}$$

is valid, where $\bar{x}_{n+1}^{(1)} = (a_{n_{kr}}, \bar{x}_{n+1,1})$.

Proof. By (3), (4), (9) and (13) we have

(71)
$$K(\overline{x}_{n+1}; S_{\pi}^*(\varepsilon)|\pi)$$

$$=\int_{a_{r}}^{a_{n_{kr}}}\left[1-2Q(y)\right]dT(y)+pK\left(\overline{x}_{n+1};\ S_{\pi_{kr}}^{*}\left(\frac{\varepsilon}{2^{k_{r}}}\right)|\pi\right),$$

where T and p are given by (67).

For simplification we write

$$egin{align} a &= a_{n_{kr}}, \quad b &= a_{n_{kr}} + \delta_{n_{kr}} \left(rac{arepsilon}{2^{k_r}}
ight), \ & H &= H^*_{\langle a,b
angle}, \quad arepsilon_r &= rac{arepsilon}{2^{k_r+1}}, \quad c &= \min(x_1,b), \ & s^*(y) &= [D_y, \{S^*_{k_r,k_r+1|c}(arepsilon_r)\}_{r_1}]. \end{split}$$

One can easily check, by (3) and (4), that

(72)
$$K(\bar{x}_{n+1,1}; s^*(y) | \pi_1) = 1 - 2Q(y), \quad a < y < x_1.$$

Since $x_1 > a_{n_{kr}}$, we have

$$K\left(\overline{x}_{n+1}; S_{\pi_{kr}}^*\left(\frac{\varepsilon}{2^{k_r}}\right) | \pi\right)$$

$$\stackrel{\text{(3)(4)}}{=} \int_{a}^{c} [1 - 2Q(y)] dH(y) + \int_{c}^{b} \{P(x_{1}) + [1 - P(x_{1})]K(\bar{x}_{n+1,1}; s^{*}(y) | \pi_{1})\} dH(y)$$

$$\leq \int_{0}^{c} \{P(a) + [1 - P(a)][1 - 2Q(y)]\} dH(y) +$$

$$+ \int_{c}^{b} \{P(b) + [1 - P(b)]K(\overline{x}_{n+1,1}; s^{*}(y) | \pi)\} dH(y)$$

$$\leq \int_{a}^{c} \{P(a) + [1 - P(a)][1 - 2Q(y)]\} dH(y) + \\ + \int_{c}^{b} \{P(a) + [1 - P(a)]K(\overline{x}_{n+1,1}; \ s^{*}(y) | \pi_{1}) + \varepsilon_{r}\} dH(y) \\ \leq \int_{a}^{(72)} \int_{a}^{b} \{P(a) + [1 - P(a)]K(\overline{x}_{n+1,1}; \ s^{*}(y) | \pi_{1})\} dH(y) + \frac{\varepsilon}{2}$$

$$\leq \int_{a}^{(3)(4)} K(\overline{x}_{n+1}^{(1)}; \ S_{\pi_{kr}}^{*}\left(\frac{\varepsilon}{2^{k_{r}}}\right) | \pi\right) + \frac{\varepsilon}{2}.$$

Hence we conclude that the assertion of the lemma is true because of the validity of (71) for $\bar{x}_{n+1} = \bar{x}_{n+1}^{(1)}$.

LEMMA 20. For every $\bar{x}_{n+1} \in \bar{X}_{n+1}$ such that $x_1 < a_n$ the inequality

$$Kig(ar{x}_{n+1};\; S^{ullet}_{oldsymbol{\pi}}(arepsilon) | \piig) \leqslant Kig(ar{x}_{n+1}^{(2)};\; S^{ullet}_{oldsymbol{\pi}}(arepsilon) | \piig) \quad \ (arepsilon>0)$$

is valid, where $\overline{x}_{n+1}^{(2)}$ is the vector obtained from \overline{x}_{n+1} by putting the number a_n in place of all its components smaller than a_n .

Proof. It is easy to check using (68) that $K(\overline{x}_{n+1}; S_{\pi}^{*}(\varepsilon)|\pi)$ considered as a function of variables x_1, x_2, \ldots, x_j $(j = \max\{i: x_i < a_n\})$ is an increasing function on the set $0 \le x_1 \le \ldots \le x_j < a_n$ with respect to each variable. This implies the assertion of the lemma.

LEMMA 21. Under the inductive hypothesis the inequality

$$K(\bar{x}_{n+1}; S_{\pi}^{*}(\varepsilon) | \pi) \leqslant v_{\pi} + \frac{\varepsilon}{2} \quad (\varepsilon > 0)$$

is valid if the vector \overline{x}_{n+1} satisfies $a_{\pi_1} < x_1 \leqslant a_{\pi_{kr}}$.

Proof. Let us assume that $a_{n_s} < x_1 \le a_{n_{s+1}}$ for some s $(1 \le s < k_r - 1)$. Then, using (67), we evaluate

$$\begin{split} K\big(\overline{x}_{n+1}; \ S_{\pi}^{\bullet}(\varepsilon) \,|\, \pi\big) \\ &\stackrel{(3)(4)(13)(9)}{=} \int\limits_{a_{\pi}}^{a_{\pi_{1}}} \left[1 - 2Q(y)\right] dT(y) + \int\limits_{a_{\pi_{1}}}^{x_{1}} \left[1 - 2Q(y)\right] dT(y) + \\ &+ \int\limits_{x_{1}}^{a_{\pi_{kr}}} \left\{P\left(x_{1}\right) + \left[1 - P\left(x_{1}\right)\right] K\left(\overline{x}_{n+1,1}; \ y \,|\, \pi_{1}\right)\right\} dT(y) + \\ &+ p \left\{P\left(x_{1}\right) + \left[1 - P\left(x_{1}\right)\right] K\left(\overline{x}_{n+1,1}; \ S_{\pi_{kr}}^{\bullet}\left(\frac{\varepsilon}{2^{k_{r}}}\right) \,|\, \pi_{1}\right)\right\} \\ &= \int\limits_{a_{\pi}}^{\varepsilon} \int\limits_{a_{\pi}}^{a_{\pi_{1}}} \left[1 - 2Q(y)\right] dT(y) - \int\limits_{a_{\pi_{1}}}^{x_{1}} 2P\left(x_{1}\right) Q\left(y\right) dT(y) + \\ \end{split}$$

$$+ \int_{a_{n_1}}^{x_1} \{P(x_1) + [1 - P(x_1)][1 - 2Q(y)]\} dT(y) + \\ + \int_{x_1}^{a_{n_{kr}}} \{P(x_1) + [1 - P(x_1)]K(\overline{x}_{n+1,1}; y | \pi_1)\} dT(y) + \\ + p \left\{P(x_1) + [1 - P(x_1)]K(\overline{x}_{n+1,1}; S_{n_{kr}}^*(\frac{\varepsilon}{2^{k_r}}) | \pi_1)\right\}.$$

From (34) and (67) it follows that

$$\int_{a_{n_1}}^{a_{n_{kr}}} dT(y) + p = a_n.$$

Hence, taking into account the inductive hypothesis, we obtain $K(\overline{x}_{n+1};\ S_{\pi}^*(\varepsilon)|\pi)$

$$\begin{split} = \int\limits_{a_{\pi}}^{a_{\pi_{1}}} \left[1 - 2Q(y)\right] dT(y) - \int\limits_{a_{\pi_{1}}}^{x} 2P(x_{1})Q(y) dT(y) + a_{\pi}P(x_{1}) + \\ + \left[1 - P(x_{1})\right] \left\{ \int\limits_{a_{\pi_{1}}}^{x_{1}} \left[1 - 2Q(y)\right] dT(y) + \int\limits_{x_{1}}^{a_{\pi_{kr}}} K(\overline{x}_{n+1,1}; \ y \mid \pi_{1}) dT(y) + \\ + pK\left(\overline{x}_{n+1,1}; \ S_{\pi_{kr}}^{*}\left(\frac{\varepsilon}{2^{k_{r}}}\right) \mid \pi_{1}\right) \right\} \end{split}$$

$$\begin{array}{l} ^{(3)(4)(9)(13)} \int\limits_{a_{\pi}}^{a_{\pi_{1}}} \left[1-2Q(y)\right] dT(y) - \int\limits_{a_{\pi_{1}}}^{x_{1}} 2P(x_{1})Q(y) dT(y) + \\ + a_{\pi} \left\{ P(x_{1}) + \left[1-P(x_{1})\right] K \left(\overline{x}_{n+1,1}; \ S_{\pi_{1}}^{*} \left(\frac{\varepsilon}{2}\right) | \pi_{1} \right) \right\} \\ \leqslant \int\limits_{a_{\pi}}^{a_{\pi_{1}}} \left[1-2Q(y)\right] dT(y) - \sum\limits_{i=1}^{s-1} \int\limits_{a_{\pi_{i}}}^{a_{\pi_{i+1}}} 2P(x_{1})Q(y) dT(y) - \\ - \int\limits_{a_{\pi_{s}}}^{x_{1}} 2P(x_{1})Q(y) dT(y) + a_{\pi} \left\{ P(x_{1}) + \left[1-P(x_{1})\right] \left[1-2Q(a_{\pi_{1}})\right] \right\} + \frac{\varepsilon}{2} \\ = \int\limits_{a_{\pi}}^{a_{\pi_{1}}} \left[1-2Q(y)\right] dT(y) + 2P(x_{1}) \left\{ -\frac{t_{1}}{P(a_{\pi_{1}})} + \frac{t_{1}}{P(a_{\pi_{2}})} - \\ - \frac{t_{2}}{P(a_{\pi_{2}})} + \frac{t_{2}}{P(a_{\pi_{3}})} - \dots - \frac{t_{s}}{P(a_{\pi_{s}})} + \frac{t_{s}}{P(x_{1})} \right\} + \\ + a_{\pi} \left\{ 1-2Q(a_{\pi_{1}}) \left[1-P(x_{1})\right] \right\} + \frac{\varepsilon}{2}. \end{array}$$

Let us consider the function

$$E(x,j) = 2P(x) \left\{ -\frac{t_1}{P(a_{n_1})} + \frac{t_1}{P(a_{n_2})} - \dots - \frac{t_j}{P(a_{n_j})} + \frac{t_j}{P(x)} \right\} +$$
 $+ a_n \{1 - 2Q(a_{n_1})[1 - P(x)]\}$

defined on the set $\langle a_{n_j}, a_{n_{j+1}} \rangle \times \{1, 2, ..., s\}$. Since

$$-\frac{t_1}{P(a_{n_1})} + a_n Q(a_{n_1}) \stackrel{(26)(27)(67)}{=} -\frac{a_n P(a_{n_1}) Q(a_{n_1})}{1 - P(a_{n_1})} < 0$$

and

$$\frac{t_{i}}{P(a_{n_{i}})} - \frac{t_{i+1}}{P(a_{n_{i+1}})} \stackrel{(26)(27)(67)}{=} - a_{\pi} a_{n_{1}} \dots a_{n_{i}} \frac{P(a_{n_{i+1}})Q(a_{n_{i+1}})}{1 - P(a_{n_{i+1}})} < 0,$$

E(x, j) is a decreasing function of the variable x in the interval $\langle a_{n_j}, a_{n_{j+1}} \rangle$ for every fixed j = 1, 2, ..., s and, consequently,

$$E(x_1, s) \leqslant E(a_{n_s}, s) = E(a_{n_s}, s-1) < E(a_{n_{s-1}}, s-1)$$

= ... = $E(a_{n_s}, 1) < E(a_{n_1}, 1)$.

Now, returning again to the previous evaluations, we get

$$\begin{split} &K\left(\overline{x}_{n+1};\ S_{\pi}^{*}(\varepsilon)\,|\,\pi\right)\\ &\leqslant \int\limits_{a_{\pi}}^{a_{\pi_{1}}}\left[1-2Q(y)\right]dT(y)+E(x_{1},s)+\frac{\varepsilon}{2}\\ &<\int\limits_{a_{\pi}}^{a_{\pi_{1}}}\left[1-2Q(y)\right]dT(y)+E(a_{\pi_{1}},1)+\frac{\varepsilon}{2}\\ &\stackrel{\text{\tiny (47)(18)(19)}}{=}\left(1-a_{\pi}\right)\int\limits_{a_{\pi}}^{a_{\pi_{1}}}\left[1-2Q(y)\right]dT_{\pi}(y)+a_{\pi}\{1-2Q(a_{\pi_{1}})[1-P(a_{\pi_{1}})]\}+\frac{\varepsilon}{2}\\ &\stackrel{\text{\tiny (55)(59)}}{=}v_{\pi}+\frac{\varepsilon}{2}. \end{split}$$

The lemma has been proved.

LEMMA 22. If the vector $\overline{x}_{n+1} \in \overline{X}_{n+1}$ satisfies $x_1 \geqslant a_{\pi}$, $x_j < a_{\pi_1}$, $x_{j+1} \geqslant a_{\pi_1}$ for some $j, 2 \leqslant j \leqslant n+1$ $(x_{n+2}=1)$, then, under the inductive hypothesis, the inequality

$$Kig(\overline{x}_{n+1};\;S^*_\pi(arepsilon)\,|\,\piig)\leqslant Kig(\overline{x}_{n+1}^{(3)};\;S^*_\pi(arepsilon)\,|\,\piig)+rac{arepsilon}{2} \qquad (arepsilon>0)$$

holds, where $\overline{x}_{n+1}^{(3)}$ is the vector obtained from \overline{x}_{n+1} by putting the value a_{π_1} in place of the components x_2, x_3, \ldots, x_i .

Proof. Let \overline{x}_{n+1} be the vector satisfying the assumption of the lemma. Then for $y \in (x_i, a_n)$ we have

$$K(\overline{x}_{n+1,j}; \ y \mid \pi_j) = egin{cases} 1 - 2Q(y) & ext{if } 2 \leqslant j < n+1, \ -1 & ext{if } j = n+1, \ w_{n+1} = g, \ -Q(y) & ext{if } j = n+1, \ w_{n+1} = c, \end{cases}$$

which implies the following inequality:

(73)
$$K(\overline{x}_{n+1,j}; y | \pi_j) \leq 1 - 2Q(y), \quad x_j < y < a_{\pi_1} (j = 2, 3, ..., n+1).$$

Now we introduce the notation

$$egin{aligned} E_j(x_1,\,\ldots,\,x_{j-1}) &= \int\limits_{a_{m{\pi}}}^{x_{j-1}} K(\overline{x}_{n+1};\;y\,|\,m{\pi}) dT(y) + \int\limits_{x_{j-1}}^{a_{m{\pi}_1}} \left\{1 - \prod\limits_{i=1}^{j-1} \left[1 - P(x_i)
ight] + \prod\limits_{i=1}^{j-1} \left[1 - P(x_i)
ight] \left\{1 - 2Q(y)
ight] \right\} dT(y) + a_{m{\pi}} \left\{1 - \prod\limits_{i=1}^{j-1} \left[1 - P(x_i)
ight] \right\}, \end{aligned}$$

where T is given in (67) and j = 2, 3, ..., n+1.

As is easy to see, the expression $E_j(x_1, ..., x_{j-1})$ depends only on the variables $x_1, x_2, ..., x_{j-1}$.

Now, using the definition of the strategy $S_{\pi}^{*}(\varepsilon)$, we evaluate the following:

$$\begin{split} K\left(\overline{x}_{n+1}; \ S_{\pi}^{*}(\varepsilon) \mid \pi\right) \\ &\stackrel{(3)(4)(6)(9)(13)}{=} \int\limits_{a_{\pi}}^{x_{j-1}} K(\overline{x}_{n+1}; \ y \mid \pi) dT(y) + \int\limits_{x_{j-1}}^{a_{\pi_{1}}} \left\{1 - \prod\limits_{i=1}^{j-1} \left[1 - P(x_{i})\right] + \right. \\ &+ \prod\limits_{i=1}^{j-1} \left[1 - P(x_{i})\right] K(\overline{x}_{n+1,j-1}; \ y \mid \pi_{j-1}) \right\} dT(y) + a_{\pi} K\left(\overline{x}_{n+1}; \ S_{\pi_{1}}^{*}\left(\frac{\varepsilon}{2}\right) \mid \pi\right) \\ \stackrel{(4)(69)}{=} \int\limits_{a_{\pi}}^{x_{j-1}} K(\overline{x}_{n+1}; \ y \mid \pi) dT(y) + \int\limits_{x_{j-1}}^{a_{\pi_{1}}} \left\{1 - \prod\limits_{i=1}^{j-1} \left[1 - P(x_{i})\right]\right\} dT(y) + \\ &+ \prod\limits_{i=1}^{j-1} \left[1 - P(x_{i})\right] \left\{ \int\limits_{x_{j-1}}^{x_{j}} \left[1 - 2Q(y)\right] dT(y) + \\ &+ \int\limits_{x_{j}}^{*} \left\{P(x_{j}) + \left[1 - P(x_{j})\right] K(\overline{x}_{n+1,j}; \ y \mid \pi_{j})\right\} dT(y) \right\} + \\ &+ a_{\pi} \left\{1 - \prod\limits_{i=1}^{j} \left[1 - P(x_{i})\right] + \prod\limits_{i=1}^{j} \left[1 - P(x_{i})\right] K\left(\overline{x}_{n+1,j}; \ S_{\pi_{1}}^{j}\left(\frac{\varepsilon}{2}\right) \mid \pi_{j}\right) \right\} \end{split}$$

$$\leq \int\limits_{a_{n}}^{s_{j-1}} K(\overline{x}_{n+1}; \ y \, | \, n) \, dT(y) + \int\limits_{x_{j-1}}^{a_{n_{1}}} \left\{ 1 - \prod_{i=1}^{j-1} \left[1 - P(x_{i}) \right] \right\} \, dT(y) + \\ + \prod\limits_{i=1}^{j-1} \left[1 - P(x_{i}) \right] \left\{ \int\limits_{x_{j-1}}^{x_{j}} \left[1 - 2Q(y) \right] dT(y) + \\ + \int\limits_{j}^{a_{n_{1}}} \left\{ P(x_{j}) + \left[1 - P(x_{j}) \right] \left[1 - 2Q(y) \right] \right\} dT(y) \right\} + \\ + a_{n} \left\{ 1 - \prod\limits_{i=1}^{j} \left[1 - P(x_{i}) \right] + \prod\limits_{i=1}^{j} \left[1 - P(x_{i}) \right] K\left(\overline{x}_{n+1,j}; \ S_{n_{1}}^{j} \left(\frac{\varepsilon}{2}\right) \mid \pi_{j} \right) \right\} \\ \stackrel{\text{(26)}}{=} E_{j}(x_{1}, \dots, x_{j-1}) + \prod\limits_{i=1}^{j-1} \left[1 - P(x_{i}) \right] \left\{ 2(1 - a_{n}) l_{n} P(x_{j}) \left\{ \frac{1}{P(x_{j})} - \frac{1}{P(a_{n_{1}})} \right\} + \\ + a_{n} P(x_{j}) + a_{n} \left[1 - P(x_{j}) \right] K\left(\overline{x}_{n+1,j}; \ S_{n_{1}}^{j} \left(\frac{\varepsilon}{2}\right) \mid \pi_{j} \right) \right\} \\ \stackrel{\text{(26)}}{=} E_{j}(x_{1}, \dots, x_{j-1}) + \\ + \prod\limits_{i=1}^{j-1} \left[1 - P(x_{i}) \right] \left\{ 2(1 - a_{n}) l_{n} + a_{n} K\left(\overline{x}_{n+1,j}; \ S_{n_{1}}^{j} \left(\frac{\varepsilon}{2}\right) \mid \pi_{j} \right) \right\} \\ \stackrel{\text{(26)}}{=} E_{j}(x_{1}, \dots, x_{j-1}) + \\ + P(x_{j}) \left[-2a_{n}Q(a_{n_{1}}) + a_{n} - a_{n} K\left(\overline{x}_{n+1,j}; \ S_{n_{1}}^{j} \left(\frac{\varepsilon}{2}\right) \mid \pi_{j} \right) \right] \right\} \\ \leqslant E_{j}(x_{1}, \dots, x_{j-1}) + \prod\limits_{i=1}^{j-1} \left[1 - P(x_{i}) \right] \left\{ 2(1 - a_{n}) l_{n} + \\ + a_{n} K\left(\overline{x}_{n+1,j}; \ S_{n_{1}}^{j} \left(\frac{\varepsilon}{2}\right) \mid \pi_{j} \right) \right\} \right\} \\ + P(x_{j}) \left[-2a_{n}Q(a_{n_{1}}) + a_{n} + a_{n} \frac{\varepsilon}{2} - a_{n} K\left(\overline{x}_{n+1,j}; \ S_{n_{1}}^{j} \left(\frac{\varepsilon}{2}\right) \mid \pi_{j} \right) \right] \right\}.$$

Further, we investigate, using relation (70) and the inductive assumption, the coefficient which stands at $P(x_j)$ in the last expression:

$$\begin{split} &-2a_{n}Q(a_{n_{1}})+a_{n}+a_{n}\frac{\varepsilon}{2}-a_{n}K\left(\overline{x}_{n+1,j};\ S_{n_{1}}^{j}\left(\frac{\varepsilon}{2}\right)|\ \pi_{j}\right)\\ &\geqslant -2a_{n}Q(a_{n_{1}})+a_{n}+a_{n}\frac{\varepsilon}{2}-a_{n}\left\{1-\left[1-P(a_{n_{1}})\right]^{j-1}+\right.\\ &\left.+\left[1-P(a_{n_{1}})\right]^{j-1}K\left(\overline{x}_{n+1,j};\ S_{n_{1}}^{j}\left(\frac{\varepsilon}{2}\right)|\ \pi_{j}\right)\right\}\\ &\stackrel{(70)}{=}-2a_{n}Q(a_{n_{1}})+a_{n}+a_{n}\frac{\varepsilon}{2}-a_{n}K\left((a_{n_{1}},\ldots,a_{n_{1}},\overline{x}_{n+1,j});\ S_{n_{1}}^{*}\left(\frac{\varepsilon}{2}\right)|\ \pi_{1}\right)\\ &\geqslant -2a_{n}Q(a_{n_{1}})+a_{n}+a_{n}\frac{\varepsilon}{2}-a_{n}\left(v_{n_{1}}+\frac{\varepsilon}{2}\right)\stackrel{(37)}{=}0\,. \end{split}$$

Therefore, the above-investigated coefficient is non-negative. Consequently, returning to the previous evaluations, we have

$$\begin{split} &K(\overline{x}_{n+1};\ S_{\pi}^{*}(\varepsilon)\,|\,\pi)\\ \leqslant &E_{j}(x_{1},\ldots,x_{j-1}) + \prod_{i=1}^{j-1}\left[1 - P(x_{i})\right] \Big\{2(1 - a_{n})l_{n} + a_{n}K\left(\overline{x}_{n+1,j};\ S_{\pi_{1}}^{j}\left(\frac{\varepsilon}{2}\right)\,|\,\pi_{j}\right) + \\ &+ P(a_{\pi_{1}})\left[-2a_{\pi}Q(a_{\pi_{1}}) + a_{\pi} + a_{\pi}\frac{\varepsilon}{2} - a_{\pi}K\left(\overline{x}_{n+1,j};\ S_{\pi_{1}}^{j}\left(\frac{\varepsilon}{2}\right)\,|\,\pi_{j}\right)\right]\Big\}\\ &= K((x_{1},\ldots,x_{j-1},\,a_{\pi_{1}},\,x_{j+1},\,\ldots,\,x_{n+1});\ S_{\pi}^{*}(\varepsilon)\,|\,\pi) + \\ &+ a_{\pi}P(a_{\pi_{1}})\prod_{i=1}^{j-1}\left[1 - P(x_{i})\right]\frac{\varepsilon}{2}, \end{split}$$

where the last equality is obtained analogously as in evaluating the expression $K(\bar{x}_{n+1}; S_{\pi}^*(\varepsilon)|\pi)$ in the initial part of the proof.

Now, repeating step by step the procedure outlined above for the components $x_{j-1}, x_{j-2}, \ldots, x_2$, we get finally

$$K\big(\overline{x}_{n+1};\ S_{\pi}^{*}(\varepsilon)\,|\,\pi\big)\leqslant K\big(\overline{x}_{n+1}^{(3)};\ S_{\pi}^{*}(\varepsilon)\,|\,\pi\big)+a_{\pi}P(a_{\pi_{1}})\sum_{s=2}^{j}\prod_{i=1}^{s-1}\left[1-P(x_{i})\right]\frac{\varepsilon}{2}.$$

However, the second term of the right-hand side of this inequality can be estimated as follows:

$$\begin{aligned} a_n P(a_{n_1}) & \sum_{s=2}^j \prod_{i=1}^{s-1} \left[1 - P(x_i) \right] \frac{\varepsilon}{2} \\ & \leqslant a_n P(a_{n_1}) \sum_{s=2}^\infty \left[1 - P(a_n) \right]^{s-1} \frac{\varepsilon}{2} = a_n P(a_{n_1}) \frac{1 - P(a_n)}{P(a_n)} \frac{\varepsilon}{2} \\ & \stackrel{(27)}{=} \frac{Q(a_n)}{Q(a_{n_1})} \frac{\varepsilon}{2} \stackrel{(30)}{<} \frac{\varepsilon}{2} \end{aligned}$$

Summarizing, we have

$$Kig(\overline{x}_{n+1};\ S^*_\pi(arepsilon)\,|\,\piig)\leqslant Kig(\overline{x}_{n+1}^{(3)};\ S^*_\pi(arepsilon)\,|\,\piig)\,+\,rac{arepsilon}{2} \qquad (arepsilon>0)\,,$$

which completes the proof of Lemma 22.

LEMMA 23. If the vector $\overline{x}_{n+1} \in \overline{X}_{n+1}$ satisfies $a_n \leqslant x_1 \leqslant a_{n_1}$ and $x_2 \geqslant a_{n_1}$, then under the inductive hypothesis the inequality

$$Kig(\overline{x}_{n+1};\; S^{ullet}_{\pi}(arepsilon)\!\mid\!\piig)\!\leqslant v_{\pi}\!+rac{arepsilon}{2}$$

is valid for any $\varepsilon > 0$.

Proof. Using the definition of the strategy $S_{\pi}^{*}(\varepsilon)$ and the assumption of the lemma we obtain

$$\begin{split} K\left(\overline{x}_{n+1};\ S_{\pi}^{*}(\varepsilon)\,|\,\pi\right) \\ \stackrel{(3)(4)(6)(9)(13)}{=} (1-a_{\pi}) \int_{a_{\pi}}^{a_{\pi_{1}}} K(\overline{x}_{n+1};\ y\,|\,\pi) dT_{\pi}(y) + \\ &\quad + a_{\pi} \Big\{ P(x_{1}) + [1-P(x_{1})] K\left(\overline{x}_{n+1,1};\ S_{\pi_{1}}^{*}\left(\frac{\varepsilon}{2}\right)|\,\pi_{1}\right) \Big\} \\ \stackrel{(54)}{\leq} (1-a_{\pi}) \int_{a_{\pi}}^{a_{\pi_{1}}} K(\overline{x}_{n+1};y\,|\,\pi) dT_{\pi}(y) + a_{\pi} \{P(x_{1}) + [1-P(x_{1})][1-2Q(a_{\pi_{1}})]\} + \frac{\varepsilon}{2} \\ \stackrel{(6)}{=} (1-a_{\pi}) \Big\{ \int_{a_{\pi}}^{x_{1}} [1-2Q(y)] dT_{\pi}(y) + \int_{x_{1}}^{a_{\pi_{1}}} \{P(x_{1}) + [1-P(x_{1})][1-2Q(y)]\} dT_{\pi}(y) \Big\} \\ + [1-P(x_{1})][1-2Q(y)] dT_{\pi}(y) \Big\} + a_{\pi} \{1-2Q(a_{\pi_{1}})[1-P(x_{1})]\} + \frac{\varepsilon}{2} \end{split}$$

$$\begin{split} &= (1-a_{\pi}) \int\limits_{a_{\pi}}^{a_{\pi_{1}}} \left[1-2Q(y)\right] dT_{\pi}(y) + \\ &+ (1-a_{\pi}) \int\limits_{x_{1}}^{a_{\pi_{1}}} 2Q(y)P(x_{1}) dT_{\pi}(y) + a_{\pi}\{1-2Q(a_{\pi_{1}})[1-P(x_{1})]\} + \frac{\varepsilon}{2} \\ &\stackrel{55)}{=} K(D_{x_{1}} \cdot F_{\pi_{1}}^{*}(\overline{x}_{n+1,1}); \ S_{\pi}^{*}(\varepsilon) |\pi) + \frac{\varepsilon}{2} \stackrel{(59)}{=} v_{\pi} + \frac{\varepsilon}{2}. \end{split}$$

This completes the proof of the lemma.

Now, summarizing the results of Lemmas 19-23 we infer that the inductive hypothesis (Step 2) implies inequality (66).

Hence, by (5), we get finally

$$K(F; S_{\pi}^*(\varepsilon) | \pi) \leqslant v_{\pi} + \varepsilon$$

for any $\varepsilon > 0$ and for all $F \in A_{n+1}$. This inequality, together with (62)-(64), completes the inductive proof of Theorem 2.

We end our reasonings with a conclusion being equivalent to Theorem 2:

For an arbitrary vector λ the game Γ_{λ} has the value equal to $v_{\lambda} = 1 - 2Q(a_{\lambda})$, F_{λ}^{*} is the optimal strategy for player A and $S_{\lambda}^{*}(\varepsilon)$ is the ε -optimal strategy for player B for any $\varepsilon > 0$.

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MIESZANA GRA CZASOWA: PROBLEM OPTYMALNOŚCI

STRESZCZENIE

Niniejsza praca jest kontynuacją pracy [2]. Jest ona dalszym ciągiem rozważań dotyczących modelu gry czasowej na zbiorze $\langle 0,1\rangle$, w której gracz A dysponuje dowolną skończoną liczbą akcji cichych i głośnych, a gracz B — jedną akcją głośną. W szczególności dowodzi się twierdzenia o jednoznaczności strategii optymalnych, sformułowanego w [2], oraz wykazuje się, że znalezione tam strategie są optymalne.