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ARE EC-SPACES AE(METRIZABLE)?

BY

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1. The appealing conjecture that equiconnected spaces are AE(metrizable) remains unanswered. (Recall that a space X is equiconnected (abbrev. EC) provided that there exists a continuous function $\lambda : X \times X \times I \rightarrow X$, where I = [0, 1], such that $\lambda(x, y, 0) = x$, $\lambda(x, y, 1) = y$ and $\lambda(x, x, t) = x$, for all $x, y \in X$ and $t \in I$. (λ is called an equiconnecting function for X.) We will discuss the significance of the preceding conjecture, recall some partial answers and provide a new partial answer, and conclude with some new thoughts which may help with its solution.

The significance of answering the question "are equiconnected spaces *absolute extensor spaces for metrizable spaces* (i.e. AE(metrizable))?" lies in the fact that a positive answer to this question will easily imply the following (for details, see [6]):

(i) linear topological spaces are AE(metrizable),

(ii) compact strongly convex metric spaces are AE(metrizable),

(iii) many groups of homeomorphisms (including the group $H_{\delta}(B^n)$ of homeomorphisms of the euclidean *n*-ball which leave the boundary fixed) are homeomorphic to the Hilbert space ℓ_2 .

Next, let us discuss the known partial answers to the conjecture at hand. Throughout, we will use the terminology of Michael [10].

THEOREM 1.1. If L is an equiconnected metrizable space with dim $L < \infty$ then L is an AE(metrizable).

Proof. This follows from Theorems 2.4 and 3.1 of Dugundji [8].

THEOREM 1.2. Let X be a stratifiable space, L an equiconnected space, A a closed subset of X and $f: A \to L$ a continuous function. If dim $(X-A) < \infty$ then there exists a continuous extension $\overline{f}: X \to L$ of f.

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 $[\]ast$ We thank A. Iwanik for very helpful assistance with Theorem 2.2 in the Appendix. He noted that we failed to prove an earlier and more general version.

C. R. BORGES

Proof. This follows from Theorem 4.2 of [3] and [4].

THEOREM 1.3. Let L be an equiconnected space with an equiconnecting function λ which satisfies the following condition: for each $x \in L$ and each neighborhood U of x there exists a neighborhood V of x such that $\lambda(U \times V \times I) \subset U$. Then L is an AE(stratifiable).

Proof. This follows from Theorems 3.1 and 4.1 of [3] and [4].

THEOREM 1.4. If L is equiconnected then L is an AE(CW-complexes of Whitehead).

Proof. This follows from Theorems 3.2 and 4.3 of [3] and [4].

THEOREM 1.5. Let L be an equiconnected space, X a stratifiable space, A a closed separable metrizable subspace of X and $f: A \to L$ a continuous function. If dim $A < \infty$ then there exists a continuous extension $\overline{f}: X \to L$ of f.

Proof. Say dim A = n. Then, by Theorem IV.8 of [13], there exists an embedding $j : A \to E^{2n+1}$. Since E^{2n+1} is an AE(metrizable) space, continuously extend j to $g : X \to E^{2n+1}$. Then, by Lemma 4.2 of [10], there exists a continuous function $h : X \to F = E^{2n+1} \times I - (E^{2n+1} - j(A)) \times \{0\}$ such that h|A = j = g|A.

We are finally ready to define the map \overline{f} , as follows: By Theorems 3.2 and 4.2 of [3] and [4], let $\hat{f}: F \to L$ be a continuous extension of the map $fj^{-1}: j(A) \to L$. Let $\overline{f} = \widehat{f}h$. (Clearly, $\overline{f}: X \to L$ and $\overline{f}|A = fj^{-1}j = f$.)

Note that if A is not separable then the best embedding result known to us (i.e. Theorem VI.10 of [13]) does not guarantee that A can be embedded in a finite-dimensional AE(metrizable) space.

Theorems 1.2 and 1.5 suggest the following question.

QUESTION 1. Let X be metrizable and A a closed subset of X. Is there a stratifiable space Y such that A is (embedded as) a closed subset of Y, $\dim(Y-A) < \infty$ and the identity function $i : A \to A$ extends to a continuous function $\overline{i} : X \to Y$?

A positive answer to the preceding question proves that equiconnected spaces are AE(metrizable) as follows: Let A be a closed subset of a metrizable space X, E an equiconnected space and $f : A \to E$ a continuous function. Continuously extend f to $\overline{f}: Y \to E$, by Theorem 1.2. Note that $\hat{f} = \overline{f} \overline{i}$ is the desired extension.

THEOREM 1.6. If convex subsets of linear topological spaces over the reals, with vector bases which are k_{ω} -spaces, are AE(stratifiable) then equiconnected k_{ω} -spaces are AE(stratifiable).

Proof. Let B be an equiconnected k_{ω} -space. By Theorem 2.1 in the Appendix, B can be embedded as a closed linearly independent subset of a locally convex linear topological space L = M(B); clearly, without loss of generality, we may assume that $\lim B$ (i.e. the linear subspace of L spanned by B) equals L.

Next, note that the space $L_w = \sum_n L_n(B)$, described in the Appendix, is a linear topological space, by Theorem 2.2 in the Appendix; furthermore, B is (embedded as) a closed linearly independent subset of L_w .

Finally, we prove that B is a continuous retract of $(\operatorname{conv} B)_w$ (i.e. the convex hull of B as a subspace of L_w): Using the terminology of Propositions 2.4 and 2.5 in the Appendix, we define a map $r : (\operatorname{conv} B)_w \to B$ by

$$r\left(\sum_{i=1}^{n} t_i b_i\right) = h_n((b_{\mu(1)}, \dots, b_{\mu(n)}), (t_{\mu(1)}, \dots, t_{\mu(n)})),$$

where $(b_1, \ldots, b_n) \in B^n_*$ and $(t_{\mu(1)}, \ldots, t_{\mu(n)})$ means that (t_1, \ldots, t_n) is reordered the same way that (b_1, \ldots, b_n) is reordered by $(b_{\mu(1)}, \ldots, b_{\mu(n)})$ (note that the coordinates of (t_1, \ldots, t_n) may not be distinct). The map r is welldefined, because B is linearly independent.

In order to prove that r is continuous, let us first note that $(\operatorname{conv} B)_w = \sum_n \operatorname{conv}_n B$, with $\operatorname{conv}_n B = L_n(B) \cap \operatorname{conv} B$. Therefore, we need only prove that each $r_n = r |\operatorname{conv}_n B$ is continuous, which we do by using induction. Assuming that r_1, \ldots, r_{n-1} are continuous (clearly, r_1 is continuous), let us prove that r_n is continuous.

It is easily seen that r_n is continuous at each point of $\operatorname{conv}_n B - \operatorname{conv}_{n-1} B = E$. Indeed, pick $q = \sum_{i=1}^n t_i b_i \in E$. Then all $t_i \neq 0$. Let V be any neighborhood of $r(q) = h_n((b_{\mu(1)}, \ldots, b_{\mu(n)}), (t_{\mu(1)}, \ldots, t_{\mu(n)}))$. By continuity of h_n , pick a neighborhood $N = (N_{\mu(1)} \times \ldots \times N_{\mu(n)}) \times (V_{\mu(1)} \times \ldots \times V_{\mu(n)})$ of $((b_{\mu(1)}, \ldots, b_{\mu(n)}), (t_{\mu(1)}, \ldots, t_{\mu(n)}))$ such that $N_{\mu(1)} \times \ldots \times N_{\mu(n)} \subset O_n$ (see Proposition 2.5 in the Appendix), $V_{\mu(1)} \times \ldots \times V_{\mu(n)} \subset P_{n-1}, 0 \notin \bigcup_{i=1}^n V_{\mu(i)}$ and $h_n(N) \subset V$. Then $U = \{\sum_{i=1}^n s_i b'_i \mid b'_i \in N_{\mu(i)} \text{ and } s_i \in V_{\mu(i)}, \text{ for } i = 1, \ldots, n\}$ is a neighborhood of q in L such that $r(U \cap \operatorname{conv}_n B) \subset V$.

It is also easily seen that r_n is continuous at each point w in the boundary of $\operatorname{conv}_{n-1}B$ (as a subspace of $\operatorname{conv}_n B$). Indeed, let $w = \sum_{i=1}^j t_i b_i$, with all $t_i \neq 0$ and j < n-1. Let V be any neighborhood of $y = r_j(w) = h_j((b_{\mu(1)}, \ldots, b_{\mu(j)}), (t_{\mu(1)}, \ldots, t_{\mu(j)}))$. Pick any $\overline{b} = (b_{\mu(1)}, \ldots, b_{\mu(j)}), b_{j+1}, \ldots, b_n) \in O_n$. Letting $\overline{t} = (t_{\mu(1)}, \ldots, t_{\mu(j)}, 0, \ldots, 0)$, pick a neighborhood $(N_{\mu(1)} \times \ldots \times N_{\mu(n)}) \times (V_{\mu(1)} \times \ldots \times V_{\mu(n)})$ of $(\overline{b}, \overline{t})$ in $L^n \times \mathbb{R}^n$ such that $h((N_{\mu(1)} \times \ldots \times N_{\mu(n)}) \times ((V_{\mu(1)} \times \ldots \times V_{\mu(n)}) \cap P_{n-1})) \subset V$ (see Proposition 2.4 in the Appendix). Then, letting $M = \{\sum_{i=1}^n s_i b'_i \mid b'_i \in N_{\mu(i)} \text{ and } s_i \in V_{\mu(i)}, \text{ for } i = 1, \ldots, n\}$, we find that M is a neighborhood of w such that $r_n(M \cap \operatorname{conv}_n B) \subset V$. This shows that r_n is continuous at w.

From the preceding two paragraphs we finally conclude that r_n is continuous, which completes the proof.

Theorem 1.6 raises some interesting questions.

QUESTION 2. When is a closed convex subset of a linear topological space L a continuous retract of L?

From Dugundji's Extension Theorem one immediately sees that closed convex subsets of a metrizable locally convex linear topological space L are continuous retracts of L. The answer in general appears quite difficult. The results of [7] may help answer this question for completely metrizable linear topological spaces.

2. Appendix. Michael [11] has proved that every metric space can be embedded isometrically as a closed, *linearly independent* subset of a normed linear space, while Arens and Eells [1] have proved that any Tikhonov space can be embedded as a closed, but not linearly independent, subset of a locally convex linear space. Fortunately, a modification of their embedding along the lines of Michael's technique yields the stronger and quite useful result that follows.

THEOREM 2.1. Every Tikhonov space X can be embedded as a closed, linearly independent subset of a locally convex linear topological space M(X). If X is metric then M(X) is a normed linear space and the embedding is isometric.

Proof. Let (Y, τ) be a Tikhonov space and let $X = Y \cup \{x_0\}$, for some $x_0 \notin Y$. The topology of X is the one generated by $\tau \cup \{\{x_0\}\}$; clearly, X is also a Tikhonov space.

Using the same construction of [1], let M(X) be the set of all real-valued functions m on X such that m(y) = 0 for all but finitely many $y \in Y$ and $\sum_{y \in X} m(y) = 0$; for convenience, letting $m(y) = \lambda_y$ for $m(y) \neq 0$, m is represented as a linear combination $m = \sum_{\lambda_y \neq 0} \lambda_y y$ with $\sum_{\lambda_y \neq 0} \lambda_y = 0$. It is proved in [1] that

(i) M(X), with the usual addition and scalar multiplication of realvalued functions, can be given a topology \mathcal{L}_0 such that $(M(X), \mathcal{L}_0)$ is a locally convex linear topological space,

(ii) X is embedded as a closed subspace of M(X) by the map $\psi : X \to M(X)$ defined by $\psi(x) = x - x_0$; furthermore, $B = \{x - x_0 \mid x \in X - \{x_0\}\}$ is a vector base for M(X).

From (ii) we immediately see that $\psi(Y) = \{x - x_0 \mid x \in Y\}$ is linearly independent (indeed, $\psi(Y) = B$); furthermore, $\psi(Y)$ is a closed subset of M(X), since $\psi(Y)$ is a closed subset of $\psi(X)$. This completes the proof.

EC-SPACES

For any linear topological space (L, \mathcal{T}) over a field F and nonempty subset B of L, and $n \in \omega$, let $L_n(B) = \{\sum_{i=1}^n r_i b_i | b_i \in B \text{ and } r_i \in F\}$. Also, let $\lim B = \bigcup \{L_n(B) | n \in \omega\}$ be the linear subspace of L spanned by B. For any linear topological space (L, τ) and vector base B for L, let L_w denote the set L with the weak topology over $\{L_n(B) | n \in \omega\}$, i.e. $L_w = \sum_n L_n(B)$ or, equivalently, L_w has the quotient topology generated by the natural map $q : \bigvee_n L_n(B) \to L$, where $\bigvee_n L_n(B)$ denotes the disjoint topological union of $\{(L_n(B), \tau | L_n(B)) | n \in \omega\}$; note that each $L_n(B) \subset L_w$ retains its original topology as a subspace of L.

For compact metric spaces, a different proof of the following result is essentially contained in the proof of Proposition VIII.5.2 of [2].

Let us first recall that a Hausdorff space which is a union of an increasing sequence $\{X_n\}$ of compact subspaces is said to be a k_{ω} -space if the natural map $q : \bigvee_n X_n \to X$, from the disjoint topological union of the X_n , is a quotient map (i.e. $X = \sum_n X_n$). From results of [12], one immediately sees that finite products and quotient images of k_{ω} -spaces are k_{ω} -spaces.

THEOREM 2.2. Let L be a linear topological space over the real (or complex) numbers with a vector base B which is a k_{ω} -space. Then L_w is a linear topological space.

Proof. Since B and \mathbb{R} are k_{ω} -spaces, one immediately finds that each $L_n(B)$ is a k_{ω} -space (since the natural map $m : \prod_{i=1}^n (\mathbb{R} \times B) \to L_n(B)$, defined by $m((t_1, b_1), \ldots, (t_n, b_n)) = t_1 b_1 + \ldots + t_n b_n$, is a quotient (indeed, open and continuous) map). Therefore, from the following diagram

where the map ψ is also addition on each $L_n(B) \times L_m(B)$, we conclude that addition in L_w is continuous, because $q \times q$ is a quotient map.

Similarly, the fact that q is a quotient map and \mathbb{R} is locally compact implies that scalar multiplication is continuous (because $q \times 1 : (\bigvee_n L_n(B)) \times \mathbb{R} \to L_w \times \mathbb{R}$ is a quotient map, by Theorem XII.4.1 of [9]). Consequently, L_w is a linear topological space, which completes the proof.

The work that follows is needed for the proof of Theorem 1.6 and consists of refinements of the work in [3]. For convenience, let us recall that

(i) for any set X and $n = 1, 2, ..., X^{n+1} = \prod_{i=1}^{n} X_i$

(ii) for $(x_1, \ldots, x_{n+1}) = x \in X^{n+1}, \hat{x} = (x_1, \ldots, x_n) \in X^n$,

(iii) if $(t_1, \ldots, t_{n+1}) = t \in P_n$ (the unit *n*-simplex in E^{n+1}) and $t_{n+1} \neq 1$ then $(t_1/(1 - t_{n+1}), \ldots, t_n/(1 - t_{n+1})) = \hat{t} \in P_{n-1}$, for $n = 1, 2, \ldots$, (iv) if $\lambda : L \times L \times I \to L$ is an equiconnecting function then $h_1 : L \times \{1\} \to L$ is defined by $h_1(x, 1) = x$ and, for $n = 2, 3, \ldots, h_n : L^n \times P_{n-1} \to L$ is defined by

$$h_{n+1}(x,t) = \begin{cases} x_{n+1} & \text{if } t_{n+1} = 1, \\ \lambda(h_n(\hat{x},\hat{t}), x_{n+1}, t_{n+1}) & \text{if } t_{n+1} \neq 1. \end{cases}$$

The following lemma is needed for the next very crucial proposition.

LEMMA 2.3. A function $f : X \to Y$ is continuous at $x \in X$ iff each net $\{x_{\nu}\}_{\nu \in \Gamma}$ in X which converges to x has a subnet $\{x_{\alpha}\}_{\alpha \in \Lambda}$ such that $\lim_{\alpha} f(x_{\alpha}) = f(x)$.

Proof. The "only if" part is well-known (indeed, $\lim_{\nu} f(x_{\nu}) = f(x)$).

The "if" part: Suppose that f is not continuous at x. Then there exists a net $\{x_{\nu}\}_{\nu\in\Gamma}$ in X such that $\lim_{\nu} x_{\nu} = x$ but $\{f(x_{\nu})\}_{\nu\in\Gamma}$ does not converge to f(x). Hence, there exists a neighborhood V of f(x) and a subnet $\{f(x_{\beta})\}_{\beta\in\Theta}$ of $\{f(x_{\nu})\}_{\nu\in\Gamma}$ such that $\{f(x_{\beta}) \mid \beta \in \Theta\} \cap V = \emptyset$. Since $\lim_{\beta} x_{\beta} = x$, by hypothesis there exists a subnet $\{x_{\alpha}\}_{\alpha\in\Lambda}$ of $\{x_{\beta}\}_{\beta\in\Theta}$ (hence, a subnet of $\{x_{\nu}\}_{\nu\in\Gamma}$) such that $\lim_{\alpha} f(x_{\alpha}) = f(x)$, a contradiction (since $\{f(x_{\alpha}) \mid \alpha \in \Lambda\} \cap V = \emptyset$).

PROPOSITION 2.4. If $\lambda : L \times L \times I \to L$ is an equiconnecting function then the functions h_1, h_2, \ldots are continuous and satisfy conditions (a), (b) and (d) of Definition 2.2 of [3].

Proof. Clearly h_1 is continuous (and $h_2 = \lambda$). By induction, let us assume that h_j is continuous for $j \leq n$ and let us prove that $h_{n+1}: L^{n+1} \times P_n \to L$ is continuous. (First note that we already know from the proof of Theorem 3.1 in [3] that each h_{n+1} is continuous in the second variable.) Let us prove that h_{n+1} is continuous at each $(x,t) \in L^{n+1} \times P_n$ by considering two cases.

Case 1: $t = (t_1, \ldots, t_{n+1})$ with $t_{n+1} \neq 1$. Pick a neighborhood N_t of t in P_n such that, for each $s \in N_t$, $s_{n+1} \neq 1$. Then, letting $h'_{n+1} = h_{n+1}|L^{n+1} \times N_t$, we find that $h'_{n+1}(x,s) = \lambda(h_n(\hat{x},\hat{s}), x_{n+1}, s_{n+1})$. Since h_n and λ are continuous, we immediately conclude that h'_{n+1} is continuous. This proves that h_{n+1} is continuous at any $(x,t) \in L^{n+1} \times P_n$ such that $t_{n+1} \neq 1$.

Case 2: $t = (0, \ldots, 0, 1)$. Then $h_{n+1}(x, t) = x_{n+1}$. Let $\{(x_{\alpha}, t_{\alpha})\}_{\alpha \in \Gamma}$ be a net in $L^{n+1} \times P_n$ which converges to (x, t); say $(x_{\alpha}, t_{\alpha}) = ((x_1^{\alpha}, \ldots, x_{n+1}^{\alpha}), (t_1^{\alpha}, \ldots, t_{n+1}^{\alpha}))$.

Next, let us recall that

$$h_{n+1}(x_{\alpha}, t_{\alpha}) = \begin{cases} x_{n+1}^{\alpha} & \text{if } t_{n+1}^{\alpha} = 1, \\ \lambda(h_n((x_1^{\alpha}, \dots, x_n^{\alpha}), \hat{t}_{\alpha}), x_{n+1}^{\alpha}, t_{n+1}^{\alpha}) & \text{if } t_{n+1}^{\alpha} \neq 1, \end{cases}$$

where

$$\hat{t}_{\alpha} = \left(\frac{t_1^{\alpha}}{1 - t_{n+1}^{\alpha}}, \cdots, \frac{t_n^{\alpha}}{1 - t_{n+1}^{\alpha}}\right)$$

and note the following:

(i) If there exists a subnet $\{(x_{\beta}, t_{\beta})\}_{\beta \in \Theta}$ of $\{(x_{\alpha}, t_{\alpha})\}_{\alpha \in \Gamma}$ such that $h_{n+1}(x_{\beta}, t_{\beta}) = x_{n+1}^{\beta}$, for each $\beta \in \Theta$, then $\lim_{\beta} h_{n+1}(x_{\beta}, t_{\beta}) = \lim_{\beta} x_{n+1}^{\beta} = x_{n+1}$.

(ii) If there exists a subnet $\{(x_{\gamma}, t_{\gamma})\}_{\gamma \in \Lambda}$ of $\{(x_{\alpha}, t_{\alpha})\}_{\alpha \in \Gamma}$ such that $h_{n+1}(x_{\gamma}, t_{\gamma}) = \lambda(h_n((x_1^{\gamma}, \ldots, x_n^{\gamma}), \hat{t}_{\gamma}), x_{n+1}^{\gamma}, t_{n+1}^{\gamma})$, for each $\gamma \in \Lambda$, then let us pick a convergent subnet $\{\hat{t}_{\beta}\}_{\beta \in \Theta}$ of $\{\hat{t}_{\gamma}\}_{\gamma \in \Lambda}$ in P_{n-1} ; say, $\lim_{\beta} \hat{t}_{\beta} = (t_1, \ldots, t_n) \in P_{n-1}$. It follows that

$$\lim_{\beta} h_{n+1}(x_{\beta}, t_{\beta}) = \lim_{\beta} \lambda(h_n(\hat{x}_{\beta}, \hat{t}_{\beta}), x_{n+1}^{\beta}, t_{n+1}^{\beta})$$
$$= \lambda(h_n(\hat{x}, (t_1, \dots, t_n)), x_{n+1}, 1) = x_{n+1}$$

(because, by inductive hypothesis, we know that h_n is continuous).

We immediately conclude from (i) and (ii) that any net $\{(x_{\alpha}, t_{\alpha})\}_{\alpha \in \Lambda}$ which converges to (x, t) has a subnet $\{(x_{\beta}, t_{\beta})\}_{\beta \in \Theta}$ such that $\lim_{\beta} h_{n+1}(x_{\beta}, t_{\beta}) = x_{n+1} = h_{n+1}(x, t)$. By Lemma 2.3, h_{n+1} is continuous at (x, t).

Cases 1 and 2 show that h_{n+1} is continuous. The fact that the h_n satisfy conditions (a), (b) and (d) of Definition 2.2 of [3] is proved in Theorem 3.1 of [3] (of course, the continuity of the h_n is much more stronger than (b)).

For any space X and positive integer n, let X_*^n denote the subspace of the cartesian product X^n which consists of all points in X^n with distinct coordinates. It is clear that if X is Hausdorff then X_*^n is an open subspace of X^n . Let T denote the relation on X^n defined by $(x_1, \ldots, x_n)T(y_1, \ldots, y_n)$ if and only if there exists $\sigma \in S_n$ (the symmetric group on $\{1, \ldots, n\}$) such that $(y_1, \ldots, y_n) = (x_{\sigma(1)}, \ldots, x_{\sigma(n)})$. It is well-known that the quotient map $\nu_n : X^n \to X^n/T$ is an open and closed (i.e. clopen) map. Let $\mu_n = \nu_n |X_*^n$; since X_*^n is an open inverse set under ν_n , we immediately see that μ_n is also clopen.

For metric spaces, the following result is essentially due to V. Klee, by very different methods (cf. Ex. A on p. 271 of [2]).

PROPOSITION 2.5. Let X be a Hausdorff space. For n = 1, 2, ... there exists a clopen subspace O_n of X_*^n such that

- (i) $\mu_n | O_n$ is a homeomorphism,
- (ii) $\mu_n(O_n) = \mu_n(X_*^n),$
- (iii) $(x_1, ..., x_n) \in O_n$ implies that $(x_1, ..., x_{n-1}) \in O_{n-1}$.

Proof. By induction, assume that the subspaces O_1, \ldots, O_{n-1} have been found so that (i)–(iii) are satisfied, and let us define O_n : Let \mathcal{S} be the collection of all open subsets S of X_*^n such that $\mu_n | S$ is one-to-one (therefore, a homeomorphism, because μ_n is an open map) and S satisfies (iii). Note that $\mathcal{S} \neq \emptyset$. (Pick $(x_1, \ldots, x_n) \in X_*^n$ such that $(x_1, \ldots, x_n) \in O_{n-1}$ and open neighborhoods N_k of x_k , $k = 1, \ldots, n$, such that $N_i \cap N_j = \emptyset$ whenever $i \neq j$, and $N_1 \times \ldots \times N_{n-1} \in O_{n-1}$. Then $N_1 \times \ldots \times N_n \in \mathcal{S}$.) Partially order \mathcal{S} by inclusion and let \mathcal{N} be a nest in \mathcal{S} . Clearly, $\bigcup \mathcal{N} \in \mathcal{S}$; therefore, by Zorn's Lemma, let O_n be a maximal element of \mathcal{S} . Clearly, O_n satisfies (iii), and O_n satisfies (i) because O_n is open (so $\mu_n | O_n$ is an open one-to-one map).

 O_n satisfies (ii): Suppose not. Then there exists $x = (x_1, \ldots, x_n) \in X_n^*$ such that $x \in O_n^- - O_n$ and $\mu_n(x) \notin \mu_n(O_n)$. (Simply pick $y \in \mu_n(X_n^*) - \mu_n(O_n)$ such that $y \in \mu_n(O_n)^-$. Then $\mu^{-1}(y) \cap O_n^- \neq \emptyset$, because μ_n is a closed map.) It follows that $(x_1, \ldots, x_{n-1}) \in O_{n-1}$. Pick a net $\{x_\beta = (x_{\beta 1}, \ldots, x_{\beta n})\}_{\beta \in \Lambda}$ in O_n such that $\lim_\beta x_\beta = x$. Then $\lim_\beta \hat{x}_\beta = \hat{x} = (x_1, \ldots, x_{n-1})$. Since O_{n-1} is a closed subspace of X_n^{n-1} , we get $\hat{x} \in O_{n-1}$. Since $(x_1, \ldots, x_{n-1}) \in O_{n-1}$, there exist open neighborhoods N_i of x_i , $i = 1, \ldots, n$, such that $N_1 \times \ldots \times N_{n-1} \subset O_{n-1}$ and $N_i \cap N_j = \emptyset$ whenever $i \neq j$. Therefore, for each $(z_1, \ldots, z_n) \in (N_1 \times \ldots \times N_n) \cap O_n, (z_1, \ldots, z_{n-1}) \in O_{n-1}$. Hence, letting $O_n' = O_n \cup (N_1 \times \ldots \times N_n)$, we conclude that $O_n' \in S$ and O_n is a proper subset of O_n' , which contradicts the maximality of O_n ; hence, O_n satisfies (ii).

In order to complete the proof, we need only show that O_n is also a closed subspace of X_*^n : Suppose not. Pick $(z_1, \ldots, z_n) \in X_*^n$ such that $(z_1, \ldots, z_n) \in O_n^- - O_n$. Pick an open neighborhood $N_1 \times \ldots \times N_n$ of (z_1, \ldots, z_n) such that $N_i \cap N_j = \emptyset$ whenever $i \neq j$. Letting $O'_n = O_n \cup (N_1 \times \ldots \times N_n)$, we easily deduce that $\mu_n | O'_n$ is a one-to-one map; however, since O_n satisfies (ii), this is impossible, a contradiction which completes the proof.

DEFINITION 2.6. For each $(x_1, \ldots, x_n) \in X^n_*$, $(x_{\mu(1)}, \ldots, x_{\mu(n)})$ will denote the point of O_n such that $\mu_n(x_1, \ldots, x_n) = \mu_n(x_{\mu(1)}, \ldots, x_{\mu(n)})$. This defines a function $p: X^n_* \to O_n$ by $p(x_1, \ldots, x_n) = (x_{\mu(1)}, \ldots, x_{\mu(n)})$.

LEMMA 2.7. The function $p: X_*^n \to O_n$ is an open continuous map.

Proof. Simply note that $p(N_1 \times \ldots \times N_n) = N_{\mu(1)} \times \ldots \times N_{\mu(n)}$, for any open subsets N_1, \ldots, N_n of X such that $N_i \cap N_j = \emptyset$ whenever $i \neq j$.

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