Oscillation of a logistic equation with delay and diffusion

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Abstract. This paper establishes oscillation theorems for a class of functional parabolic equations which arises from logistic population models with delays and diffusion.

1. Introduction. This paper is concerned with a parabolic differential equation with delays which can be used to model the dynamical behavior of a population density governed by a logistic law with time delays and spatial diffusion. Assuming a positive stationary state of the population density, we are interested to seek conditions under which every possible evolution oscillates about it. Similar problems have been dealt with in a few recent studies (see e.g. [2, Chapter 6], [8, 6, 4, 7], [5, Chapter 4] and [3]). The literature is, however, quite limited.

Let $\tau_i(t)$, $1 \leq i \leq n$, be positive continuous functions defined on $[0, \infty)$ such that $\tau = \max_i \{\max_t \tau_i(t)\} < \infty$. Let Ω be a bounded domain in \mathbb{R}^m with a smooth boundary $\partial \Omega$ and let ν be the outward unit normal vector. As usual, let Δ be the Laplacian:

$$\Delta \equiv \frac{\partial^2}{\partial x_1^2} + \ldots + \frac{\partial^2}{\partial x_m^2}$$

Consider the following functional parabolic differential equation:

(1)
$$\frac{\partial u(x,t)}{\partial t} = d(t)\Delta u(x,t) + c(t)u(x,t)\Big\{a(t) - \sum_{i=1}^{n} b_i(t)u(x,t-\tau_i(t))\Big\},$$

where $(x,t) \in \Omega \times (0,\infty)$, a(t), c(t), d(t), $b_1(t)$, ..., $b_n(t)$ are positive, bounded and continuous functions on $[0,\infty)$ and $0 < d_0 \le d(t)$, $0 < b_0 \le c(t)b_i(t)$ for some $i \in \{1,\ldots,n\}$ on $[0,\infty)$. We will consider boundary conditions of the

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^[219]

form

(2)
$$\frac{\partial u(x,t)}{\partial u} = 0, \qquad (x,t) \in \partial \Omega \times (0,\infty),$$

(3)
$$u(x,t) = \phi(x,t), \quad (x,t) \in \Omega \times [-\tau,0],$$

where $\phi(x,t)$ is a non-negative and non-trivial continuous function.

Existence and uniqueness theorems for solutions of (1)-(3) follow from the existence of a unique "heat kernel" $g(x,t,\xi,\mu)$ associated with the differential operator $L[u] = u_t - d(t)u_{xx}$ and the boundary condition (2). By means of this kernel (1)-(3) can be transformed into an integral equation which is well posed and can be solved by the "method of steps". For details, see Kreith and Ladas [7], and [9, 1, 10]. In what follows, by a *solution* of (1)-(3), we mean a function u(x,t) which is continuously differentiable on the closure of $\Omega \times [-\tau, \infty)$ and twice continuously differentiable on $\Omega \times [-\tau, \infty)$.

We will further assume that there is a positive constant u^* such that

(4)
$$\sum_{i=1}^{n} b_i(t) u^* = a(t), \quad t \ge 0,$$

so that $u(x,t) = u^*$ is a stationary solution of (1).

Let u(x,t) be a real continuous function defined on $\overline{\Omega} \times [t_0, \infty)$. Suppose there is some $T \geq t_0$ such that u(x,t) > 0 on $\Omega \times [T,\infty)$. Then u(x,t)is said to be *eventually positive*. An eventually negative u(x,t) is similarly defined. The function u(x,t) is said to be *oscillatory* on $\Omega \times [t_0,\infty)$ if it is neither eventually positive nor eventually negative. Equation (1) is said to be *oscillatory about* u^* if for every positive solution u(x,t) of (1) which satisfies the boundary conditions (2) and (3), the function $u(x,t) - u^*$ is oscillatory on $\Omega \times [-\tau,\infty)$.

2. Non-existence criteria. We first derive a necessary condition for the existence of a solution u(x,t) of (1) such that $u(x,t) - u^*$ is eventually positive.

LEMMA 1. Suppose (1)–(3) has a solution u(x,t) such that $u(x,t) - u^*$ is eventually positive. Then the first order delay differential inequality

(5)
$$y'(t) \le -\sum_{i=1}^{n} u^* c(t) b_i(t) y(t - \tau_i(t))$$

has an eventually positive solution.

Proof. Suppose there is a positive number t_1 such that $u(x,t) - u^* > 0$ on $\Omega \times [t_1, \infty)$. For convenience, let $w(x,t) = u(x,t) - u^*$. Then from (1) and (4), we have

(6)
$$\frac{\partial w(x,t)}{\partial t} = d(t)\Delta w(x,t) - c(t)[w(x,t) + u^*]\sum_{i=1}^n b_i(t)w(x,t - \tau_i(t)).$$

Integrate both sides of (6) with respect to x over Ω to obtain

(7)
$$\frac{d}{dt} \int_{\Omega} w(x,t) dx = d(t) \int_{\Omega} \Delta w(x,t) dx$$
$$-c(t) \int_{\Omega} [w(x,t) + w^*] \sum_{i=1}^{n} b_i(t) w(x,t - \tau_i(t)) dx.$$

By the Green formula and the boundary condition (2), we obtain

(8)
$$\int_{\Omega} \Delta w(x,t) \, dx = \int_{\partial \Omega} \frac{\partial w(x,t)}{\partial \nu} \, ds = 0$$

Pick a number $t_2 > t_1 + \tau$. Then w(x,t) > 0 and $w(x,t-\tau_i(t)) > 0$ for $(x,t) \in \Omega \times [t_2,\infty)$. In view of (7) and (8), we have

$$\frac{d}{dt} \int_{\Omega} w(x,t) dx \le -c(t) \int_{\Omega} u^* \sum_{i=1}^n b_i(t) w(x,t-\tau_i(t)) dx, \quad t \ge t_2$$

We have thus shown that

$$y(t) = \int_{\Omega} w(x,t) \, dx, \quad t \ge t_2,$$

is an eventually positive solution of (5). The proof is complete.

Next we derive a necessary condition for the existence of a positive solution u(x,t) of (1) such that $u(x,t) - u^*$ is eventually negative.

LEMMA 2. Suppose (1)–(3) has a positive solution u(x,t) such that $u(x,t) - u^*$ is eventually negative. Then for any $\mu \in (0,1)$, the first order delay differential inequality

(9)
$$y'(t) \le -\sum_{i=1}^{n} u^* \mu c(t) b_i(t) y(t - \tau_i(t))$$

has an eventually positive solution.

Proof. Suppose there is a positive number t_1 such that $u(x,t) - u^* < 0$ for $(x,t) \in \Omega \times [t_1,\infty)$. Let

$$p(x,t) = \ln\left(\frac{u(x,t)}{u^*}\right) < 0, \quad (x,t) \in \Omega \times [t_1,\infty).$$

We assert that

$$y(t) = \int_{\Omega} -p(x,t) \, dx$$

is an eventually positive solution of (9). To prove this, note first that from (1) and (4) we have

(10)
$$\frac{\partial p(x,t)}{\partial t} = d(t)e^{-p(x,t)}\Delta e^{p(x,t)} + c(t)\left\{a(t) - \sum_{i=1}^{n} b_{i}(t)u^{*}e^{p(x,t-\tau_{i}(t))}\right\}$$
$$= d(t)e^{-p(x,t)}\Delta e^{p(x,t)} - u^{*}c(t)\sum_{i=1}^{n} b_{i}(t)\left\{e^{p(x,t-\tau_{i}(t))} - 1\right\}.$$

Integrate the above equality with respect to x over \varOmega to obtain

(11)
$$\frac{d}{dt} \int_{\Omega} p(x,t) \, dx = d(t) \int_{\Omega} e^{-p(x,t)} \Delta e^{p(x,t)} \, dx$$
$$- u^* c(t) \sum_{i=1}^n b_i(t) \int_{\Omega} \left\{ e^{p(x,t-\tau_i(t))} - 1 \right\} \, dx.$$

Since

(12)
$$\frac{\partial}{\partial\nu} \{e^{\pm p(x,t)}\} = \pm e^{\pm p(x,t)} \frac{\partial p(x,t)}{\partial\nu}, \quad (x,t) \in \partial\Omega \times [t_1,\infty),$$

(13)
$$\left. \frac{\partial p(x,t)}{\partial \nu} \right|_{\partial \Omega} = \frac{1}{u(x,t)} \frac{\partial u(x,t)}{\partial \nu} \Big|_{\partial \Omega} = 0,$$

and

$$e^{p(x,t)}\Delta e^{-p(x,t)} = |\nabla p(x,t)|^2 - \Delta p(x,t), \quad (x,t) \in \Omega \times [t_1,\infty),$$

we obtain

(14)
$$\int_{\Omega} e^{-p(x,t)} \Delta e^{p(x,t)} dx = \int e^{p(x,t)} \Delta e^{-p(x,t)} dx$$
$$= \int_{\Omega} |\nabla p(x,t)|^2 dx - \int_{\Omega} \Delta p(x,t) dx$$
$$= \int_{\Omega} |\nabla p(x,t)|^2 dx - \int_{\partial\Omega} \frac{\partial p(x,t)}{\partial \nu} ds$$
$$= \int_{\Omega} |\nabla p(x,t)|^2 dx.$$

From (11) we also obtain

222

(15)
$$\frac{d}{dt} \int_{\Omega} -p(x,t) dx$$
$$= -d(t) \int_{\Omega} |\nabla p(x,t)|^2 dx + u^* c(t) \sum_{i=1}^n b_i(t) \int_{\Omega} \{e^{p(x,t-\tau_i(t))} - 1\} dx$$
$$\leq u^* c(t) \sum_{i=1}^n b_i(t) \int_{\Omega} \{e^{p(x,t-\tau_i(t))} - 1\} dx.$$

To complete the proof, it suffices to show that for any $\mu \in (0,1)$, there is some T_0 such that

$$e^{p(x,t-\tau_i(t))} - 1 \le \mu p(x,t-\tau_i(t)), \quad t \ge T_0.$$

In order to do this, pick $t_2 > t_1 + \tau$ so that p(x,t) < 0 and $p(x,t-\tau_i(t)) < 0$ for $(x,t) \in \Omega \times [t_2,\infty)$. For $(x,t) \in \Omega \times [t_2,\infty)$, consider the positive functional V defined by

$$V[p](t) = u^* \int_{\Omega} \int_{0}^{p(x,t)} (e^y - 1) \, dy \, dx.$$

By (10) and (12)–(14), the derivative of V with respect to (1) satisfies

$$\begin{split} \frac{dV}{dt} &= u^* \int_{\Omega} (e^{p(x,t)} - 1) \frac{\partial p(x,t)}{\partial t} \, dx \\ &= u^* d(t) \int_{\Omega} \Delta e^{p(x,t)} \, dx - u^* d(t) \int_{\Omega} e^{-p(x,t)} \Delta e^{p(x,t)} \, dx \\ &- (u^*)^2 c(t) \sum_{i=1}^n b_i(t) \int_{\Omega} \{e^{p(x,t)} - 1\} \{e^{p(x,t-\tau_i(t))} - 1\} \, dx \\ &\leq -u^* d(t) \int_{\Omega} |\nabla p(x,t)|^2 \, dx \\ &- (u^*)^2 c(t) \sum_{i=1}^n b_i(t) \int_{\Omega} \{e^{p(x,t)} - 1\} \{e^{p(x,t-\tau_i(t))} - 1\} \, dx. \end{split}$$

Note that from (1),

$$\begin{aligned} \frac{d}{dt} \int_{\Omega} u(x,t) \, dx &= \int_{\Omega} \frac{\partial u(x,t)}{\partial t} \, dx \\ &= \int_{\Omega} d(t) \Delta u(x,t) \, dx \\ &+ \int_{\Omega} u(x,t) c(t) \sum_{i=1}^{n} b_i(t) (u^* - u(x,t - \tau_i(t))) \, dx \end{aligned}$$

$$= \int_{\Omega} u(x,t)c(t) \sum_{i=1}^{n} b_i(t)(u^* - u(x,t-\tau_i(t))) \, dx \ge 0,$$

thus

$$\int_{\Omega} \left(u(x,t) - u(x,t - \tau_i(t)) \right) dx \ge 0,$$

which implies

$$\begin{split} &\int_{\Omega} \{e^{p(x,t)} - 1\} \{e^{p(x,t-\tau_i(t))} - 1\} \, dx \\ &= \int_{\Omega} \{e^{p(x,t)} - 1\}^2 \, dx + \int_{\Omega} \{e^{p(x,t)} - 1\} \{e^{p(x-\tau_i(t))} - e^{p(x,t)}\} \, dx \\ &= \int_{\Omega} \{e^{p(x,t)} - 1\}^2 \, dx + \frac{1}{(u^*)^2} \int_{\Omega} (u(x,t) - u^*)(u(x,t-\tau_i(t)) - u(x,t)) \, dx \\ &\geq \int_{\Omega} \{e^{p(x,t)} - 1\}^2 \, dx, \end{split}$$

by the first mean value theorem for integrals. As a consequence, we see that

(16)
$$\frac{dV}{dt} \leq -u^* d(t) \int_{\Omega} |\nabla p(x,t)|^2 dx$$
$$-(u^*)^2 c(t) \sum_{i=1}^n b_i(t) \int_{\Omega} \{e^{p(x,t)} - 1\}^2 dx$$
$$= -u^* d(t) \int_{\Omega} |\nabla p(x,t)|^2 dx$$
$$-(u^*)^2 c(t) \sum_{i=1}^n b_i(t) \int_{\Omega} \{u(x,t) - u^*\}^2 dx$$

for $t \ge t_2$. Integrate both sides of (16), and recall the assumptions that $0 < d_0 \le d(t)$ and $0 < b_0 \le b_i(t)c(t)$, to obtain

$$V(t_2) \ge V(t) + u^* d_0 \int_{t_2}^t \int_{\Omega} |\nabla p(x,t)|^2 \, dx \, dy$$
$$+ (u^*)^2 b_0 \int_{t_2}^t \int_{\Omega} \{u(x,y) - u^*\}^2 \, dx \, dy.$$

Hence, by writing $\{\int_{\Omega} |\cdot|^2 dx\}^{1/2} = \|\cdot\|$, we have

$$\int_{t_2}^{\infty} \int_{\Omega} \{u(x,y) - u^*\}^2 \, dx \, dy = \int_{t_2}^{\infty} \|u(x,y) - u^*\|^2 \, dy < \infty$$

224

and

$$\int_{t_2}^{\infty} \int_{\Omega} |\nabla p(x,y)|^2 \, dx \, dy = \int_{t_2}^{\infty} \|\nabla p(x,y)\|^2 \, dy < \infty,$$

so that $||u(x,y) - u^*|| \in L_1(0,\infty)$ and $||\nabla p(x,t)||^2 \in L_1(0,\infty)$. But from the assumption that $u(x,t) < u^*$ for $(x,t) \in \Omega \times [t_1,\infty)$ we have

$$\frac{1}{(u^*)^2} \|\nabla u(x,t)\|^2 \le \|\nabla p(x,t)\|^2,$$

so that $\|\nabla u(x,t)\|^2 \in L_1(0,\infty)$. Now

,

$$(17) \quad \frac{d}{dt} \|\nabla u(x,t)\|^{2}$$

$$= \left(\frac{\partial u(x,t)}{\partial t}, -\Delta u(x,t)\right)$$

$$= -d(t) \|\Delta u(x,t)\|^{2}$$

$$+ \left(\nabla \left\{ c(t)u(x,t) \left[a(t) - \sum_{i=1}^{n} b_{i}(t)u(x,t - \tau_{i}(t))\right] \right\}, \nabla u(x,t) \right)$$

$$\leq -d_{0} \|\Delta u(x,t)\|^{2} + ca \|\nabla u(x,t)\|^{2}$$

$$+ u^{*}c \sum_{i=1}^{n} b_{i} \|\nabla u(x,t - \tau_{i}(t))\| \|\nabla u(x,t)\|,$$

where $|a(t)| \leq a$, $|c(t)| \leq c$, $|b_i(t)| \leq b_i$ for $t \geq 0$ (recall that a(t), c(t) and $b_i(t)$ are bounded).

Integrate both sides of (17) from $t = t_2$ to $t = T > t_2$ to obtain

$$(18) \qquad \|\nabla u(x,T)\|^{2} - \|\nabla u(x,t_{2})\| + d_{0} \int_{t_{2}}^{T} \|\Delta u(x,t)\|^{2} dt$$

$$\leq ca \int_{t_{2}}^{T} \|\nabla u(x,t)\|^{2} dt + u^{*}c \sum_{i=1}^{n} b_{i} \int_{t_{2}}^{T} \|\nabla u(x,t-\tau_{i}(t))\| \|\nabla u(x,t)\| dt$$

$$\leq ca \int_{t_{2}}^{T} \|\nabla u(x,t)\|^{2} dt$$

$$+ u^{*}c \sum_{i=1}^{n} b_{i} \Big\{ \int_{t_{2}}^{T} \|\nabla u(x,t-\tau_{i}(t))\|^{2} dt \Big\}^{1/2} \Big\{ \int_{t_{2}}^{T} \|\nabla u(x,t)\|^{2} dt \Big\}^{1/2}.$$

We may now infer from $\|\nabla u(x,t)\|^2 \in L_1(0,\infty)$ and the above inequality that $\|\Delta u(x,t)\|^2 \in L_1(0,\infty)$ and $\|\nabla u(x,t)\|^2$ is bounded on (t_2,∞) .

In a similar fashion, we obtain

$$\begin{split} \int_{t_2}^T \left| \frac{d}{dt} \| \nabla u(x,t) \|^2 \right| dt \\ &\leq d_0 \int_{t_2}^T \| \Delta u(x,t) \|^2 \, dt + ca \int_{t_2}^T \| \nabla u(x,t) \|^2 \, dt \\ &+ u^* c \sum_{i=1}^n b_i \Big\{ \int_{t_2}^T \| \nabla u(x,t-\tau_i(t)) \|^2 \, dt \Big\}^{1/2} \Big\{ \int_{t_2}^T \| \nabla u(x,t) \|^2 \, dt \Big\}^{1/2}. \end{split}$$

Since $\|\nabla u(x,t)\|^2 \in L_1(0,\infty)$ and $\|\Delta u(x,t)\|^2 \in L_1(0,\infty)$, we may deduce the fact that $(d/dt)\|\nabla u(x,t)\|^2 \in L_1(0,\infty)$.

We now make a few more deductions. First, from $\|\nabla u(x,t)\|^2 \in L_1(0,\infty)$ and $(d/dt)\|\nabla u(x,t)\|^2 \in L_1(0,\infty)$, by integrating $(d/dt)\|\nabla u(x,t)\|^2$ from a large but fixed number to infinity, we see that as t tends to infinity, $\|\nabla u(x,t)\|^2$ tends to a constant which must be zero, i.e.

(19)
$$\lim_{t \to \infty} \int_{\Omega} |\nabla u(x,t)|^2 dt = \lim_{t \to \infty} \|\nabla u(x,t)\|^2 = 0.$$

Furthermore, since

$$\begin{aligned} \frac{1}{2} \frac{d}{dt} \|u(x,t) - u^*\|^2 \\ &= \int_{\Omega} (u(x,t) - u^*) \frac{\partial u(x,t)}{\partial t} dx \\ &= d(t) \int_{\Omega} (u(x,t) - u^*) \Delta u(x,t) dx \\ &- \int_{\Omega} (u(x,t) - u^*) c(t) u(x,t) u(x,t) \sum_{i=1}^n b_i(t) (u(x,t - \tau_i(t)) - u^*) dx, \end{aligned}$$

we have

$$\begin{aligned} \left| \frac{1}{2} \frac{d}{dt} \| u(x,t) - u^* \|^2 \right| \\ &\leq d \int_{\Omega} |u(x,t) - u^*| \cdot |\Delta u(x,t)| \, dx \\ &+ c \sum_{i=1}^n b_i u^* \int_{\Omega} |u(x,t) - u^*| \cdot |u(x,t-\tau_i(t)) - u^*| \, dx \end{aligned}$$

and

$$\begin{split} \int_{t_3}^T \left| \frac{1}{2} \frac{d}{dt} \| u(x,t) - u^* \|^2 \right| dt \\ &\leq d \Big\{ \int_{t_3}^T \| \Delta u(x,t) \|^2 \, dt \Big\}^{1/2} \Big\{ \int_{t_3}^T \| u(x,t) - u^* \|^2 \, dt \Big\}^{1/2} \\ &+ c u^* \sum_{i=1}^n b_i \Big\{ \int_{t_3}^T \| u(x,t) - u^* \|^2 \, dt \Big\}^{1/2} \\ &\times \Big\{ \int_{t_3}^T \| u(x,t - \tau_i(t)) - u^* \|^2 \, dt \Big\}^{1/2}. \end{split}$$

As a consequence, we have

$$\frac{d}{dt}\|u(x,t)-u^*\| \in L_1(0,\infty),$$

in view of the previously shown facts that $\|\Delta u(x,t)\|^2 \in L_1(0,\infty)$ and $\|u(x,t) - u^*\|^2 \in L_1(0,\infty)$. By integrating $(d/dt)\|u(x,t) - u^*\|$ from a large but fixed number to infinity, we see that as t tends to infinity, $\|u(x,t) - u^*\|$ tends to a constant which must be zero, i.e.

(20)
$$\lim_{t \to \infty} \|u(x,t) - u^*\| = 0.$$

Next, from $u(x,t) < u^*$ for $t > t_2$ and the boundedness of $\|\nabla u(x,t)\|$ on (t_2,∞) , we see that $\|u(x,t) - u^*\|_{\infty}$ and $\|\nabla u(x,t)\|_{\infty}$ are bounded (where $\|w\|_{\infty} = \operatorname{ess\,sup} |w(x)|$); then from the inequality

$$\|w\|_{\sigma} \leq \|w\|_{\infty}^{(\sigma-2)/\sigma} \|w\|_2^{2/\sigma} \quad \text{for all } \sigma \geq 2$$

and (19) as well as (20), we obtain

(21)
$$\lim_{t \to \infty} \|u(x,t) - u^*\|_{\sigma} = \lim_{t \to \infty} \|\nabla u(x,t)\|_{\sigma} = 0, \quad \sigma > m.$$

Next, from the Sobolev inequality, we obtain

(22)
$$||u(x,t) - u^*||_{\infty}$$

 $\leq M(\Omega,m,\sigma) \{ ||u(x,t) - u^*||_{\sigma} + ||\nabla(u(x,t) - u^*)||_{\sigma} \},$

where $M(\Omega, m, \sigma)$ is some positive constant.

Finally, from (21) and (22), we see that $||u(x,t) - u^*||_{\infty} \to 0$ as $t \to \infty$, so that

$$\lim_{t\to\infty} u(x,t) = u^* \quad \text{uniformly in } x\in \overline{\Omega},$$

which implies

(23) $\lim_{t \to \infty} p(x,t) = 0 \quad \text{uniformly in } x \in \overline{\Omega}.$

Now for any $t > t_2$ and $t_3 > t_2$,

$$e^{p(x,t-\tau_i(t))} - e^{p(x,t_3)} = \{p(x,t-\tau_i(t)) - p(x,t_3)\}e^{p(x,\eta_i(t))}$$

where $e^{p(x,\eta_i(t))} \to 1$ as $t \to \infty$. Thus for any $\mu \in (0,1)$, we can find t_4 such that

$$\mu < e^{p(x,\eta_i(t))} < 1, \quad t \ge t_4$$

which implies

$$e^{p(x,t-\tau_i(t))} - 1 \le \mu p(x,t-\tau_i(t)), \quad t \ge t_4$$

as required. The proof is complete.

3. Oscillation criteria. In the last section, we have established necessary conditions for the existence of eventually positive or negative solutions. These conditions are related to delay differential inequalities. In order to obtain oscillation theorems, we only need conditions under which these inequalities do not have eventually positive solutions. Such a technique for obtaining oscillation theorems is standard (see for example [2, Chapter 6] or [7]). For illustration, we now mention several examples.

LEMMA 3 (Ladas and Stavroulakis [8]; see also [2, p. 199]). Let $\sigma_1, \ldots, \sigma_k$ be positive constants and let $q_1(t), \ldots, q_k(t)$ be positive continuous functions on $[t_0, \infty)$. Suppose

$$\liminf_{t \to \infty} \int_{t-\sigma_i/2}^t q_i(s) \, ds > 0, \qquad 1 \le i \le k,$$

and

$$\liminf_{t \to \infty} \int_{t-\sigma_i}^t q_i(s) \, ds > \frac{1}{e} \quad \text{for at least one } i \in \{1, \dots, k\}.$$

Then the differential inequality

$$x'(t) + \sum_{i=1}^{k} q_i(t)x(t - \sigma_i) \le 0$$

has no eventually positive solutions.

In view of Lemmas 1, 2 and 3, we obtain the following oscillation theorem.

THEOREM 1. Suppose τ_1, \ldots, τ_n are positive constants and a(t), c(t), d(t), $b_1(t), \ldots, b_n(t)$ are bounded functions on $[0, \infty)$ such that for $t \ge 0$, $0 < d_0 \le d(t)$ and $0 < b_0 \le c(t)b_i(t)$ for some $i \in \{1, \ldots, n\}$. Suppose u^* is a positive constant such that (4) holds. If

$$\liminf_{t \to \infty} \int_{t-\tau_i/2}^t c(s)b_i(s) \, ds > 0, \qquad 1 \le i \le n,$$

and

$$\liminf_{t \to \infty} \int_{t-\tau_i}^t c(s)b_i(s) \, ds > \frac{1}{e} \quad \text{for at least one } i \in \{1, \dots, n\}$$

Then equation (1) is oscillatory about u^* .

A result of Hunt and Yorke [6] states that if $\tau_i(t)$ and $q_i(t)$, $1 \le i \le n$, are positive continuous functions on $[0, \infty)$ such that

(24)
$$\max_{i} \max_{t} \tau_{i}(t) < \infty,$$

and if

$$\liminf_{t \to \infty} \sum_{i=1}^{n} q_i(t) \tau_i(t) > \frac{1}{e},$$

then all solutions of

(25)
$$x'(t) + \sum_{i=1}^{n} q_i(t)x(t - \tau_i(t)) = 0$$

must oscillate. Another result in [5, Corollary 3.2.2] states that under the same assumptions on $\tau_i(t)$ and $q_i(t)$ as above, a necessary and sufficient condition for all solutions of (25) to oscillate is that the inequality

$$x'(t) + \sum_{i=1}^{n} q_i(t)x(t - \tau_i(t)) \le 0$$

does not have any eventually positive solution. In view of these two results and our Lemmas 1 and 2, we obtain the following result.

THEOREM 2. Suppose a(t), c(t), d(t), $b_1(t)$,..., $b_n(t)$ and $\tau_1(t)$,..., $\tau_n(t)$ are positive bounded continuous functions on $[0, \infty)$ such that (24) holds and for $t \ge 0$, $0 < d_0 \le d(t)$ and $0 < b_0 \le c(t)b_i(t)$ for some $i \in \{1, \ldots, n\}$. Suppose u^* is a positive constant such that (4) holds. If

$$\liminf_{t \to \infty} c(t) \sum_{i=1}^n b_i(t) \tau_i(t) u^* > \frac{1}{e},$$

then equation (1) is oscillatory about u^* .

Other results can be obtained from corresponding oscillation theorems for equation (25), which can be found, among others, in [5, Section 3.4].

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