# ON COMPACT SYMPLECTIC AND KÄHLERIAN SOLVMANIFOLDS WHICH ARE NOT COMPLETELY SOLVABLE 

By

## ALEKSY TRALLE (WROCŁAW)

We are interested in the problem of describing compact solvmanifolds admitting symplectic and Kählerian structures. This was first considered in $[3,4]$ and $[7]$. These papers used the Hattori theorem concerning the cohomology of solvmanifolds, hence the results obtained covered only the completely solvable case. Our results do not use the assumption of complete solvability. We apply our methods to construct a new example of a compact symplectic non-Kählerian solvmanifold.

1. Introduction. Recently, there has been an interest in examples of compact symplectic manifolds with no Kähler structures ( $[1,5,7,8,10,15$, $16]$ and others). With the exception of $[7,16]$ and the surgery technique of [8], known examples are nilmanifolds coming from the following general theorem proved by C. Benson and C. Gordon [3]:

Let $M$ be a compact $K(\Gamma, 1)$-manifold where $\Gamma$ is a discrete, finitely generated, torsion free, nilpotent group. If $M$ admits a Kähler structure, then $\Gamma$ is abelian and $M$ is diffeomorphic to a torus.

This theorem implies that any non-toral symplectic $K(\Gamma, 1)$-manifold with nilpotent $\Gamma$ yields the desired example.

Motivated by this, the authors of $[3,4,7]$ raised the same question for aspherical manifolds and, in particular, for solvmanifolds.

The case of solvmanifolds, however, differs essentially from that of nilmanifolds for several reasons. In general, the Nomizu theorem concerning the cohomology of a nilmanifold is not available, therefore, the minimal model of a solvmanifold cannot be used directly. Moreover, the known examples of symplectic and Kählerian solvmanifolds show that all possible cohomology types, Kählerian and non-Kählerian, may occur (see [4, 7]).

[^0]Key words and phrases: solvmanifold, Kähler structure, symplectic structure.

In [4] and [7], the authors investigated the case of a solvmanifold $G / \Gamma$ of a completely solvable Lie group $G$ and established the necessary conditions for the existence of Kählerian structures on such manifolds. The key to the proof of the cited results is the Nomizu-Hattori theorem [11] regarding the cohomology of $G / \Gamma$ which allowed the authors to establish the rational model $\left(\bar{A}^{*}(G / \Gamma), d\right)=\left(\Lambda L(G)^{*}, \delta\right)$. For arbitrary Lie groups, the NomizuHattori theorem does not hold (see [19] and [26]) and the technique of [4] is not available. Moreover, there are many types of solvmanifolds which are not completely solvable [26], e.g. solvmanifolds of $(R)$-type, $(E)$-type, mixed types etc.

We attack the problem in a different manner. The main results of this article are the following three theorems. Theorem 1 is the main algebraic tool. It shows that for any compact solvmanifold $G / \Gamma$ (completely solvable or not) the existence of a Kählerian structure implies some strong algebraic conditions on the cohomology complex $\left(\Lambda L(G)^{*}, \delta\right)$ of the Lie algebra $L(G)$. The most interesting feature of this result is the fact that although $\left(\Lambda L(G)^{*}, \delta\right)$ is not a rational model of $G / \Gamma$ in the non-completely solvable case, Theorem 1 is strong enough to obtain results analogous to [7] in the general case. In particular, Theorem 2 yields a new example of a compact symplectic non-Kählerian manifold $M^{8}$ (it is 8-dimensional). Theorem 3 describes algebraic properties of rational models of some aspherical Kählerian manifolds provided that these models admit a structure of a twisted tensor product. In particular, these results hold for any solvmanifold which has a free model represented as a twisted tensor product (in the spirit of [20]). Unfortunately, the author does not know which solvmanifolds admit free twisted tensor products as rational models except those considered in Corollary 1 to Theorem 3. It is worth mentioning that applications of rational homotopy theory to geometry are limited presently to the nilpotent space situation and are not directly applicable to the solvmanifold case. Therefore, Theorem 3 can be viewed as a step along the lines of the original twisted models of Sullivan.

Theorem 1. Let $M=G / \Gamma$ be a compact solvmanifold carrying a Kählerian structure. Then the cochain complex $\left(\Lambda L(G)^{*}, \delta\right)$ of the Lie algebra $L(G)$ satisfies the following property: all triple Massey products and higher order Massey products of the pair $\left(\Lambda L(G)^{*}, H^{*}\left(\Lambda L(G)^{*}\right)\right)$ vanish as cohomology classes in $H^{*}\left(\Lambda L(G)^{*}\right)$ (that is, there is a choice of cochains in $\Lambda L(G)^{*}$ representing all triple Massey products and higher order Massey products so that these cochains are exact).

Remark. This condition is stronger than saying simply that all Massey products vanish, since, for instance, a triple Massey product $\langle[a],[b],[c]\rangle$ is defined with an indeterminacy lying in the ideal generated by $[a]$ and $[c]$.

Theorem 2. Let $L(G)$ be a Lie algebra defined as follows:

$$
\begin{equation*}
L(G)=\operatorname{Span}\left(A, B, X_{1}, X_{2}, X_{3}, X_{4}, X_{5}, X_{6}\right) \tag{1}
\end{equation*}
$$

$$
\begin{aligned}
{\left[A, X_{1}\right] } & =X_{1}, \quad\left[A, X_{2}\right]=-X_{2}, \quad\left[A, X_{3}\right]=X_{3}, \quad\left[A, X_{4}\right]=-X_{4}, \\
\text { (2) } \quad\left[A, X_{5}\right] & =\alpha X_{6}, \quad\left[A, X_{6}\right]=-\alpha X_{5}, \quad \alpha \in \mathbb{R}, \\
{\left[B, X_{3}\right] } & =X_{1}, \quad\left[B, X_{4}\right]=X_{2}
\end{aligned}
$$

(the other brackets are assumed to be zero). Let $G$ be a simply connected Lie group corresponding to $L(G)$. Then:
(i) $G$ is a solvable non-nilpotent and not completely solvable Lie group;
(ii) $G$ contains a lattice $\Gamma$ for some particular $\alpha$;
(iii) the homogeneous space $G / \Gamma$ is a compact symplectic solvmanifold with no Kähler structure.

To formulate Theorem 3, we introduce the notion of the twisted tensor product of graded commutative differential algebras. Here and in the sequel we use traditional notations of rational homotopy theory and solvmanifolds. Nevertheless, some of them are explained in the next section.

Let $(\mathcal{R}, \bar{d})$ and $(\mathcal{S}, \delta)$ be graded commutative differential algebras. Introduce the tensor product $\mathcal{R} \otimes \mathcal{S}$ of $\mathcal{R}$ and $\mathcal{S}$ as graded algebras and define the "twisted" derivation $d$ by the formula

$$
\begin{aligned}
& d(r \otimes 1)=\bar{d}(r) \otimes 1, \quad r \in \mathcal{R} \\
& d(1 \otimes s)=1 \otimes \delta(s)+\sum_{i \geq 0}(-1)^{(i+1) \operatorname{deg}(s)} \sum_{\xi \geq 1} \phi_{i}^{\xi}(s) \otimes r_{i+1}^{\xi}, \quad s \in \mathcal{S}
\end{aligned}
$$

here $\phi_{i}^{\xi}$ is a derivation of $(\mathcal{S}, \delta)$ decreasing the degree by $i$, that is,

$$
\phi_{i}^{\xi}(x y)=\phi_{i}^{\xi}(x) y+(-1)^{i \operatorname{deg}(x)} x \phi_{i}^{\xi}(y)
$$

and $\left\{r_{i+1}^{\xi}, \xi=1,2, \ldots\right\}$ constitute a basis of $\mathcal{R}^{i+1}$. By definition, the graded differential algebra $(\mathcal{R} \otimes \mathcal{S}, d)$ is called the twisted tensor product of $(\mathcal{R}, \bar{d})$ and $(\mathcal{S}, \delta)$. In the sequel we denote the twisted tensor product by $(\mathcal{R}, \bar{d}) \otimes_{\tau}$ $(\mathcal{S}, \delta)$.

Remark. Twisted tensor products could be considered in a more general framework [12, 20].

Theorem 3. Let $F \rightarrow E \rightarrow T^{k}$ be a fiber bundle with the fiber $F$ of homotopy type $K(\pi, 1)$ with nilpotent $\pi$ over the homotopy torus $T^{k}$. Assume that the total space $E$ of the bundle admits a model $\left(A^{*}(E), d\right)$ which can be represented as a twisted tensor product

$$
\left(A^{*}(E), d\right)=(\Lambda X, \bar{d}=0) \otimes_{\tau}(\Lambda Y, \delta),
$$

where $X$ and $Y$ are finite-dimensional vector spaces of elements of degree 1, and $(\Lambda Y, \delta)$ is a minimal differential algebra. Then if $E$ admits a Kählerian structure, the model $\left(A^{*}(E), d\right)$ has the following properties:
(i) $\left(A^{*}(E), d\right)$ is a Lefschetz algebra;
(ii) for the bigrading $\Lambda^{i j}=\Lambda^{i} X \otimes \Lambda^{j} Y$ the following equalities hold:

$$
H^{1}\left(A^{*}\right)=\Lambda^{1,0}, \quad H^{n-1}\left(A^{*}\right)=\Lambda^{k, l-1}, \quad k=\operatorname{dim} X, l=\operatorname{dim} Y ;
$$

(iii) the Lefschetz element $\omega \in \Lambda^{2}(X \oplus Y)$ can be chosen in the form

$$
\omega=\omega^{2,0}+\omega^{0,2}
$$

and $\omega^{2,0}$ and $\omega^{0,2}$ are non-degenerate 2-forms on $X^{*}$ and $Y^{*}$, which are closed and non-exact with respect to $d$ and $\delta$.
(iv) $\operatorname{dim} X$ and $\operatorname{dim} Y$ are even and $X^{*}$ and $Y^{*}$ are $\omega$-orthogonal.

Corollary 1. Let $F \rightarrow E \rightarrow T^{k}$ be a fiber bundle with the base and the fiber as in Theorem 3. Assume that the $\pi_{1}\left(T^{k}\right)$-action on $H^{*}(F)$ is nilpotent. Then, if $E$ is endowed with a Kählerian structure, there exists a free graded differential algebra $\left(A^{*}(E), d\right)$ which has the structure of the free tensor product given by Theorem 3 and possesses algebraic properties (i)-(iv).

In particular, let $M=G / \Gamma$ be a compact solvmanifold carrying a Kählerian structure. Assume that the corresponding Mostow bundle satisfies the nilpotency condition for the $\pi_{1}(G / N \Gamma)$-action on $H^{*}(N \Gamma / \Gamma)$. There exists a free graded differential algebra $\left(A^{*}(G / \Gamma), d\right)$ which is a free rational model for $G / \Gamma$ and has the properties (i)-(iv) of Theorem 3.

Remark. The definition of the Mostow bundle is given is Section 5. We included the solvmanifold case into the formulation of the corollary, although the author does not know whether there are solvmanifolds non-diffeomorphic to nilmanifolds whose Mostow bundle satisfies the nilpotency condition. So far, the last part of the corollary may be trivial. However, at the end of the paper we describe (very briefly) what the $\pi_{1}\left(T^{k}\right)$-action on $H^{*}(F)$ looks like in the solvmanifold case. This suggests that for non-abelian fibers the nilpotency condition may appear.

To illustrate the usefulness of Theorem 3 we also show that it generalizes the Benson-Gordon theorem [4].

Corollary 2. If $G$ is completely solvable and $G / \Gamma$ is a solvmanifold that admits a Kähler structure, then
(i) there is an abelian complement $\mathcal{A}$ in $L(G)$ of the derived algebra $\mathcal{N}=[L(G), L(G)] ;$
(ii) $\mathcal{A}$ and $\mathcal{N}$ are even-dimensional;
(iii) the center of $L(G)$ intersects $\mathcal{N}$ trivially;
(iv) the Kählerian form is cohomologous to a left-invariant symplectic form $\omega=\omega_{0}+\omega_{1}$, where $\mathcal{N}=\operatorname{ker}\left(\omega_{0}\right)$ and $\mathcal{A}=\operatorname{ker}\left(\omega_{1}\right)$;
(v) both $\omega_{0}$ and $\omega_{1}$ are closed but non-exact in $L(G)$ and also in $\mathcal{N}$ and $\mathcal{A}$;
(vi) the adjoint action of $\mathcal{A}$ on $\mathcal{N}$ is by infinitesimal symplectomorphisms.

Remark. (i) Corollary 2 follows from the proof of Theorem 3.
(ii) The properties (i)-(iv) stated in Theorem 3 are the algebraic properties established in [4] for $\left(\Lambda L(G)^{*}, \delta\right)$ in the completely solvable case.
2. Preliminaries. This work is situated, in fact, in the framework of rational homotopy theory. Since there are many books and research articles devoted to this topic, we assume that the reader is familiar with it and refer to $[6,9,14,23]$.

In the sequel we consider the category $\mathbb{R}$-DGA of graded differential algebras over the field of real numbers (although the algebraic results are valid for an arbitrary field of zero characteristic). By definition, a model of a manifold $M$ is a free graded differential algebra $A^{*}(M)$ such that there exists either a homomorphism

$$
\alpha: A^{*}(M) \rightarrow \Omega_{\mathrm{DR}}(M)
$$

or a homomorphism

$$
\beta: \Omega_{\mathrm{DR}}(M) \rightarrow A^{*}(M)
$$

inducing isomorphism in cohomology. Of course, $A^{*}(M)$ need not be minimal and therefore is not unique. We use the notion of the minimal model in the usual sense. The cohomology functor for $\mathbb{R}$-DGA is denoted by $H^{*}$. By definition we call a free finitely-graded differential algebra $A=\bigoplus_{i=0}^{n} A^{i}$ oriented if $H^{n}(A) \neq 0$.

Definition. (i) A finitely-graded free differential algebra $(A, d)=$ $\left(\bigoplus_{i=0}^{2 n} A^{i}, d\right)$ is called symplectic if there exists an element $[\omega] \in H^{2}(A)$ such that $[\omega]^{n} \neq 0, \omega \in A^{2}$.
(ii) An algebra $(A, d)$ satisfying (i) is called Lefschetz, or satisfies the hard Lefschetz condition, if all homomorphisms

$$
L_{\omega^{r}}: H^{n-r} \rightarrow H^{n+r}, \quad L_{\omega^{r}}([h])=\left[\omega^{r}\right][h], \quad r \geq 1
$$

are isomorphisms. The element $\omega \in A^{2}$ is called Lefschetz.
Observe that symplectic algebras satisfying Poincaré duality are models of compact symplectic manifolds and Lefschetz algebras are those of compact Kählerian manifolds. This fact will play the crucial role in Section 5.

One of the ingredients of proofs in this article is the Thomas theorem concerning the models of Serre fibrations [24] and [25], therefore, we reproduce its exact formulation (see [24] for the proof).
(*)

$$
F \rightarrow E \rightarrow B
$$

be a Serre fibration with $B$ and $F$ of finite cohomology type. As usual, the fundamental group $\pi_{1}(B)$ acts on $H^{*}(F)$ via a representation $\pi_{1}(B) \rightarrow$ $\operatorname{Aut}\left(H^{*}(F)\right)$ (see, e.g., $\left.[21]\right)$. We assume that $E, F$ and $B$ are path-connected. Recall that by definition an action of a group $G$ on an abelian group $C$ is called nilpotent if $G$ acts on $C$ by automorphisms and the inductively defined sequence
$\Gamma_{0} C=C \supset \Gamma_{1} C \supset \ldots \supset \Gamma_{n+1} C=\left\{g c-c: g \in G, \quad c \in \Gamma_{n} C\right\} \supset \ldots$
vanishes for some $n \geq 1,(\{\ldots\}$ denotes the $\mathbb{Z} G$-submodule in $C$ generated by $g c-c$ ).

Thomas theorem. Let (*) be a Serre fibration satisfying the above assumptions. Suppose that $\pi_{1}(B)$ acts nilpotently on $H^{*}(F)$. Then there exists a model $\left(A^{*}(E), d\right)$ which is a twisted tensor product

$$
\left(A^{*}(E), d\right)=\left(\mathcal{M}_{B}, d_{B}\right) \otimes_{\tau}\left(\mathcal{M}_{F}, d_{F}\right)
$$

of the minimal models $\left(\mathcal{M}_{B}, d_{B}\right)$ and $\left(\mathcal{M}_{F}, d_{F}\right)$ of $B$ and $F$ respectively. The twisting $\tau$ is of the form (3).

In the sequel we denote the vector space dual to the vector space $X$ by $X^{*}$.

Following [4], we consider as solvmanifolds only homogeneous spaces $G / \Gamma$, where $G$ is a solvable simply connected Lie group and $\Gamma$ is a lattice in $G$, that is, a discrete co-compact subgroup (see $[2,18]$ for the general theory of solvmanifolds).

We introduce nilmanifolds as homogeneous spaces $N / \Gamma$, where $N$ is a simply connected nilpotent Lie group and $\Gamma$ a lattice in $N$.

To compare our results with [4, 7], we recall the definition of a completely solvable Lie group: a Lie group $G$ is completely solvable if all endomorphisms ad $V: L(G) \rightarrow L(G), V \in L(G)$, possess only real eigenvalues. Of course, there are many solvable Lie groups which are not completely solvable (see e.g. $[2,26])$.

To prove the main results we need the following fact, which is well known and can be found in explicit form in [10]:

Proposition. The minimal model of any compact nilmanifold $N / \Gamma$ is of the form

$$
\left(\mathcal{M}_{N / \Gamma}, d\right) \simeq\left(\Lambda L(N)^{*}, \delta\right)
$$

where $\delta$ is a standard derivation determining the cohomology of $L(N)$ :
(4) $\delta \alpha\left(X_{0}, \ldots, X_{k}\right)=\sum_{i<j}(-1)^{i+j-1} \alpha\left(\left[X_{i}, X_{j}\right], X_{0}, \ldots, \widehat{X}_{i}, \widehat{X}_{j}, \ldots, X_{k}\right)$,
$X_{0}, \ldots, X_{k} \in L(N), \alpha \in \Lambda^{k} L(N)^{*}$.

Definition ([6]). (i) Let $(A, d)$ be a free graded commutative differential algebra. We call it formal if there exists a quasi-isomorphism

$$
\varrho:(A, d) \rightarrow\left(H^{*}(A, d), 0\right)
$$

where $\left(H^{*}(A, d), 0\right)$ denotes the cohomology algebra considered as a graded differential algebra with zero derivation.
(ii) We say that a graded commutative differential algebra is a formal consequence of its cohomology algebra if the minimal model $\left(\mathcal{M}_{A}, d\right)$ of $\left(A, d_{A}\right)$ is formal.

Remark. We slightly generalized the notion of formality, extending it to free (not necessarily minimal) algebras. This terminology is a bit more convenient for us. On the other hand, it is important to distinguish the notions of formality and that of being a formal consequence. In general a graded differential algebra may have the formal minimal model, but nevertheless, there may be no quasiisomorphisms between the original algebra and its cohomology (compare e.g. the main theorem in [6] concerning the de Rham algebra of any Kählerian manifold).

The classical theorem of Deligne-Griffiths-Morgan-Sullivan [6] will be used in the proofs of Theorem 1 and Theorem 2. We reproduce it here.

DGMS-Theorem. For any compact Kählerian manifold its de Rham algebra is a formal consequence of its cohomology algebra.

In Section 4 we use the notions of the Massey product and the higher order Massey product referring to [13] for the definition.

A free graded algebra over a graded vector space $X$ is denoted by $\Lambda X$, the degree of an element $x \in X$ is denoted by $\operatorname{deg}(x)$.
3. Proof of Theorem 1. Recall that for introducing Massey products one needs a pair $\left(A, H^{*}(A)\right)$ (a differential graded algebra $A$ together with its cohomology algebra). It is important for us to stress this fact, since in the sequel we will change algebras without changing cohomologies and, therefore, Massey products will also vary for different pairs. For this reason, we will use a slightly different terminology considering Massey products of the pair $\left(A, H^{*}(A)\right)$.

Lemma 1. Let

$$
\begin{equation*}
\psi:\left(A, d_{A}\right) \rightarrow\left(B, d_{B}\right) \tag{6}
\end{equation*}
$$

be a morphism in $\mathbb{R}-\mathrm{DG} A$, inducing a monomorphism in cohomology. Then the following implication holds: if $\left(B, d_{B}\right)$ is a formal consequence of its cohomology algebra, then all triple Massey products and higher order Massey products of the pair $\left(A, H^{*}(A)\right)$ vanish as cohomology classes in $H^{*}(A)$ (that
is, there is a choice of cochains in A representing all triple Massey products and higher order Massey products so that these cochains are exact).

Proof. Consider, first, triple Massey products (of course, we could proceed with Massey products of an arbitrary order, but we prefer to accomplish the proof separately for triple and then for quadruple Massey products presenting all essential moments of the proof but avoiding clumsy notation).

Note that for each morphism $\varphi:\left(A, d_{A}\right) \rightarrow\left(B, d_{B}\right)$,

$$
\varphi^{*}\langle[a],[b],[c]\rangle=\left\langle\varphi^{*}[a], \varphi^{*}[b], \varphi^{*}[c]\right\rangle,
$$

where the right-hand side of this identity is considered as a cohomology class in $H^{*}\left(B, d_{B}\right)$ and the right-hand product $\langle,$,$\rangle is taken with respect to the$ pair $\left(B, H^{*}(B)\right)$. Indeed, the cohomology class $[y]$ representing the triple Massey product is determined by the following procedure: if

$$
d_{A} x^{12}=\bar{a} b, \quad d_{A} x^{23}=\bar{b} c, \quad x^{12}, x^{23} \in A,
$$

then

$$
y=\bar{a} x^{23}+\bar{x}^{12} c
$$

(here and in the sequel $\bar{x}$ denotes $(-1)^{p} x$ for $x \in A^{p}$ ). We take an arbitrary cocycle $y$ obtained by this procedure and fix it. We do not care about the indeterminacy lying in $([a],[c])$. Then

$$
\varphi(y)=\overline{\varphi(a)} \varphi\left(x^{23}\right)+\overline{\varphi\left(x^{12}\right)} \varphi(c)
$$

and

$$
\begin{aligned}
\varphi\left(d_{A} x^{12}\right) & =d_{B} \varphi\left(x^{12}\right)=\overline{\varphi(a)} \varphi(b) \\
\varphi\left(d_{A} x^{23}\right) & =d_{B} \varphi\left(x^{23}\right)=\overline{\varphi(b)} \varphi(c)
\end{aligned}
$$

so that $\varphi(y)$ represents, by definition, a triple Massey product

$$
\langle[\varphi(a)],[\varphi(b)],[\varphi(c)]\rangle
$$

of the pair $\left(B, H^{*}(B)\right)$. Finally,

$$
\varphi^{*}[y]=\left\langle\left[\varphi^{*}[a], \varphi^{*}[b], \varphi^{*}[c]\right\rangle\right.
$$

as expected.
Now, let us prove the lemma for triple Massey products. Let $\left(\mathcal{M}_{B}, d\right)$ be the minimal model of $\left(B, d_{B}\right)$ and $\varrho$ be the corresponding quasi-isomorphism

$$
\varrho:\left(\mathcal{M}_{B}, d\right) \rightarrow\left(B, d_{B}\right) .
$$

Assume that there exists a non-zero cohomology class $[y] \in H^{*}\left(A, d_{A}\right)$ represented as a triple Massey product $[y]=\langle[a],[b],[c]\rangle$. We have already shown that $\psi^{*}[y]=\left\langle\psi^{*}[a], \psi^{*}[b], \psi^{*}[c]\right\rangle$. Since $\psi^{*}$ is injective, $\psi^{*}[y]$ represents a non-zero cohomology class in $H^{*}(B)$ which is represented as a triple Massey product of the pair $\left(B, H^{*}(B)\right)$. Since $\varrho^{*}$ is an isomorphism, there exist
cocycles $a_{M}, b_{M}, c_{M} \in \mathcal{M}_{B}$ such that

$$
\varrho^{*}\left[a_{M}\right]=\psi^{*}[a], \quad \varrho^{*}\left[b_{M}\right]=\psi^{*}[b], \quad \varrho^{*}\left[c_{M}\right]=\psi^{*}[c] .
$$

Recall that

$$
\psi^{*}[a] \psi^{*}[b]=0, \quad \psi^{*}[b] \psi^{*}[c]=0
$$

which implies $\varrho^{*}\left[a_{M}\right] \varrho^{*}\left[b_{M}\right]=0, \varrho^{*}\left[b_{M}\right] \varrho^{*}\left[c_{M}\right]=0$ and

$$
\left[a_{M}\right]\left[b_{M}\right]=0, \quad\left[b_{M}\right]\left[c_{M}\right]=0
$$

Hence,

$$
d z^{12}=\bar{a}_{M} b_{M}, \quad d z^{23}=\bar{b}_{M} c_{M}
$$

for cochains $z^{12}, z^{23} \in \mathcal{M}_{B}$. Take

$$
y_{M}=\bar{a}_{M} z^{23}+\bar{z}^{12} c_{M},
$$

which is a cocycle representing the triple Massey product $\left\langle\left[a_{M}\right],\left[b_{M}\right],\left[c_{M}\right]\right\rangle$ of the pair $\left(\mathcal{M}_{B}, H^{*}\left(\mathcal{M}_{B}\right) \simeq H^{*}(B)\right)$. Thus,

$$
\begin{aligned}
\varrho^{*}\left[y_{M}\right] & =\varrho^{*}\left\langle\left[a_{M}\right],\left[b_{M}\right],\left[c_{M}\right]\right\rangle=\left\langle\varrho^{*}\left[a_{M}\right], \varrho^{*}\left[b_{M}\right], \varrho^{*}\left[c_{M}\right]\right\rangle \\
& =\left\langle\psi^{*}[a], \psi^{*}[b], \psi^{*}[c]\right\rangle=\psi^{*}[y] \neq 0 .
\end{aligned}
$$

But, since $\left(\mathcal{M}_{B}, d\right)$ is formal, $\left[y_{M}\right]$ must vanish as a cohomology class in $H^{*}\left(\mathcal{M}_{B}\right)$ because of the following general fact proved in [6] (p. 262): if $\left(\mathcal{M}_{B}, d\right)$ is formal, one can make uniform choices so that the cochains representing all Massey products and higher order Massey products are exact. This contradiction implies $\langle[a],[b],[c]\rangle=0$ in $H^{*}(A)$.

Consider now quadruple Massey products. Recall the procedure of constructing the corresponding cohomology classes. Again, we assume that all cohomology classes representing triple Massey products of the pair $\left(A, H^{*}(A)\right)$ vanish (this is the condition under which quadruple Massey products are well-defined, sometimes this condition is called "simultaneous vanishing"). Assume that $[w] \in H^{*}(A)$ is a quadruple Massey product:

$$
[w]=\langle[a],[b],[c],[u]\rangle
$$

Again, we begin with the general observation that $\varphi^{*}[w]=\left\langle\varphi^{*}[a], \varphi^{*}[b]\right.$, $\left.\varphi^{*}[c], \varphi^{*}[u]\right\rangle$ for each $\mathbb{R}$-DG $A$-morphism $\varphi$. Indeed, the construction of the quadruple Massey product is carried out as follows: one takes cochains $x^{12}, x^{23}, x^{34} \in A$ such that

$$
d_{A} x^{12}=\bar{a} b, \quad d_{A} x^{23}=\bar{b} c, \quad d_{A} x^{34}=\bar{c} u
$$

and cochains $x^{13}, x^{24} \in A$ such that

$$
d_{A} x^{13}=\bar{a} x^{23}+\bar{x}^{12} c, \quad d_{A} x^{24}=\bar{b} x^{34}+\bar{x}^{23} u
$$

and forms a cocycle

$$
w=\bar{a} x^{24}+\bar{x}^{12} x^{34}+\bar{x}^{13} u
$$

Again, as in the previous case,

$$
\begin{gathered}
\varphi d_{A} x^{12}=d_{B} \varphi\left(x^{12}\right)=\overline{\varphi(a)} \varphi(b), \quad \varphi d_{A} x^{23}=d_{B} \varphi\left(x^{23}\right)=\overline{\varphi(b)} \varphi(c), \\
\varphi d_{A} x^{34}=d_{B} \varphi\left(x^{34}\right)=\overline{\varphi(c)} \varphi(u) \\
\varphi d_{A} x^{13}=d_{B} \varphi\left(x^{13}\right)=\overline{\varphi(a)} \varphi\left(x^{23}\right)+\overline{\varphi\left(x^{12}\right)} \varphi(c), \\
\varphi d_{A} x^{24}=d_{B} \varphi\left(x^{24}\right)=\overline{\varphi(b)} \varphi\left(x^{34}\right)+\overline{\varphi\left(x^{23}\right)} \varphi(u),
\end{gathered}
$$

which means that

$$
\varphi(w)=\overline{\varphi(a)} \varphi\left(x^{24}\right)+\overline{\varphi\left(x^{12}\right)} \varphi\left(x^{34}\right)+\overline{\varphi\left(x^{13}\right)} \varphi(u)
$$

represents the corresponding quadruple Massey product of the pair $\left(B, H^{*}(B)\right)$. Finally,

$$
\varphi^{*}[w]=\left\langle\left[\varphi^{*}[a], \varphi^{*}[b], \varphi^{*}[c], \varphi^{*}[u]\right\rangle .\right.
$$

Again, take the minimal model $\left(\mathcal{M}_{B}, d\right)$ and cocycles $\left[a_{M}\right],\left[b_{M}\right],\left[c_{M}\right]$ and $\left[u_{M}\right]$ in $\mathcal{M}_{B}$ such that $\varrho^{*}\left[a_{M}\right]=\psi^{*}[a], \varrho^{*}\left[b_{M}\right]=\psi^{*}[b], \varrho^{*}\left[c_{M}\right]=\psi^{*}[c], \varrho^{*}\left[u_{M}\right]$ $=\psi^{*}[u]$. Since $\varrho^{*}$ is an isomorphism, the identities involving cohomology classes in $H^{*}(A)$ are transferred to $H^{*}\left(\mathcal{M}_{B}\right)$ :

$$
\left[a_{M}\right]\left[b_{M}\right]=0, \quad\left[b_{M}\right]\left[c_{M}\right]=0, \quad\left[c_{M}\right]\left[u_{M}\right]=0
$$

(for example, $[a][b]=0 \Rightarrow \psi^{*}[a] \psi^{*}[b]=\varrho^{*}\left[a_{M}\right] \varrho^{*}\left[b_{M}\right]=0$ ). Hence

$$
d z^{12}=\bar{a}_{M} b, \quad d z^{23}=\bar{b}_{M} c_{M}, \quad d z^{34}=\bar{c}_{M} u_{M}, \quad z^{12}, z^{23}, z^{34} \in \mathcal{M}_{B}
$$

Since $\langle[a],[b],[c]\rangle=0$ and $\langle[b],[c],[u]\rangle=0$ as cohomology classes in $H^{*}(A)$ ("vanish simultaneously"), the same is valid for their images under $\psi^{*}$ and $\varrho^{*}$ (see the corresponding identity for arbitrary $\varphi^{*}$ ). Therefore,

$$
\left\langle\left[a_{M}\right],\left[b_{M}\right],\left[c_{M}\right]\right\rangle=0, \quad\left\langle\left[b_{M}\right],\left[c_{M}\right],\left[u_{M}\right]\right\rangle=0
$$

as cohomology classes in $H^{*}\left(\mathcal{M}_{B}\right)$ and there exist cochains $z^{13}, z^{24} \in \mathcal{M}_{B}$ such that

$$
d z^{13}=\bar{a}_{M} z^{32}+\bar{z}^{12} c_{M}, \quad d z^{24}=\bar{b}_{M} z^{34}+\bar{z}^{23} u_{M}
$$

Hence, the quadruple Massey product is well-defined with respect to the pair $\left(\mathcal{M}_{B}, H^{*}\left(\mathcal{M}_{B}\right)\right)$ :

$$
\left[w_{M}\right]=\left\langle\left[a_{M}\right],\left[b_{M}\right],\left[c_{M}\right],\left[u_{M}\right]\right\rangle
$$

and

$$
\begin{aligned}
\varrho^{*}\left\langle\left[a_{M}\right],\left[b_{M}\right],\left[c_{M}\right],\left[u_{M}\right]\right\rangle & =\left\langle\varrho^{*}\left[a_{M}\right], \varrho^{*}\left[b_{M}\right], \varrho^{*}\left[c_{M}\right], \varrho^{*}\left[u_{M}\right]\right\rangle \\
& =\left\langle\psi^{*}[a], \psi^{*}[b], \psi^{*}[c], \psi^{*}[u]\right\rangle \\
& =\psi^{*}\langle[a],[b],[c],[u]\rangle \neq 0
\end{aligned}
$$

if we assume that $\langle[a],[b],[c],[u]\rangle \neq 0$, since $\psi^{*}$ is an injection. However, $\left(\mathcal{M}_{B}, d\right)$ is formal and $\left\langle\left[a_{M}\right],\left[b_{M}\right],\left[c_{M}\right],\left[u_{M}\right]\right\rangle$ must vanish as a cohomology
class in $H^{*}\left(\mathcal{M}_{B}\right)$ (again, appeal to the remark on p. 262 in [6]). This contradiction completes the proof. The same argument is obviously valid for Massey products of arbitrary orders.

Proof of Theorem 1. Let $\Omega_{\mathrm{DR}}(G / \Gamma)$ be the de Rham algebra of $G / \Gamma$. Consider $\left(\Lambda L(G)^{*}, \delta\right)$ as the algebra of all left-invariant differential forms on $G$ :

$$
\left(\Lambda L(G)^{*}, \delta\right) \simeq\left(\Omega_{\mathrm{DR}}^{\operatorname{inv}}(G), d\right)
$$

Since $\Gamma$ is a lattice in $G$ and $G$ is simply connected, the natural projection $G \rightarrow G / \Gamma$ is a covering with a discrete fiber $\Gamma$. Therefore, this covering determines the injection

$$
\left(\Omega_{\mathrm{DR}}^{\mathrm{inv}}(G), d\right) \rightarrow \Omega_{\mathrm{DR}}(G / \Gamma)
$$

Thus, finally

$$
\left(\Lambda L(G)^{*}, \delta\right) \rightarrow \Omega_{\mathrm{DR}}(G / \Gamma)
$$

is injective. It is known that this morphism induces a monomorphism on cohomology (see [19]), and the proof follows from the DGMS-theorem and Lemma 1.
4. The solvmanifold $M^{8}$. In this section we prove Theorem 2. The proof will consist of the three lemmas below.

Lemma 2. The Lie group $G$ determined by (1)-(2) is the semidirect product

$$
G=\mathbb{R}^{2} \times_{\varphi} \mathbb{R}^{6}
$$

where $\varphi: \mathbb{R}^{2} \rightarrow \mathrm{GL}\left(\mathbb{R}^{6}\right)$ is the homomorphism defined by the formula

$$
\varphi(t, x)=\left(\begin{array}{cccccc}
e^{t} & 0 & x e^{t} & 0 & 0 & 0 \\
0 & e^{-t} & 0 & x e^{-t} & 0 & 0 \\
0 & 0 & e^{t} & 0 & 0 & 0 \\
0 & 0 & 0 & e^{-t} & 0 & 0 \\
0 & 0 & 0 & 0 & \cos \alpha t & \sin \alpha t \\
0 & 0 & 0 & 0 & -\sin \alpha t & \cos \alpha t
\end{array}\right)
$$

for $(t, x) \in \mathbb{R}^{2}$.
Proof. Observe that $L(G)=\mathcal{A} \times{ }_{\varphi_{*}} \mathcal{N}$, where $\mathcal{A}=\operatorname{Span}(A, B), \mathcal{N}=$ $\operatorname{Span}\left(X_{1}, \ldots, X_{6}\right)$ and $\varphi_{*}: \mathcal{A} \rightarrow \operatorname{End}(\mathcal{N})$ is defined by the rule

$$
\varphi_{*}(A)=\left(\begin{array}{cccccc}
1 & 0 & 0 & 0 & 0 & 0 \\
0 & -1 & 0 & 0 & 0 & 0 \\
0 & 0 & 1 & 0 & 0 & 0 \\
0 & 0 & 0 & -1 & 0 & 0 \\
0 & 0 & 0 & 0 & 0 & 1 \\
0 & 0 & 0 & 0 & -1 & 0
\end{array}\right), \quad \varphi_{*}(B)=\left(\begin{array}{cccccc}
0 & 0 & 1 & 0 & 0 & 0 \\
0 & 0 & 0 & 1 & 0 & 0 \\
0 & 0 & 0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 & 0 & 0
\end{array}\right)
$$

Indeed, since $\mathcal{A}$ and $\mathcal{N}$ are abelian, $\operatorname{End}(\mathcal{N})=\operatorname{Der}(\mathcal{N})$ and since $\left[\varphi_{*}(A), \varphi_{*}(B)\right]=0$, the linear mapping determined by the above matrices is a homomorphism of the Lie algebras $\mathcal{A}$ and $\operatorname{Der}(\mathcal{N})$, which means that $L(G)=\mathcal{A} \times \varphi_{*} \mathcal{N}$.

From (2), $L(G)$ is solvable but non-nilpotent $\left(\left[A, X_{1}\right]=X_{1}\right.$ contradicts the nilpotency condition, while the solvability follows from the inclusion $[L(G), L(G)] \subset \mathcal{N}$ and the commutativity of $\mathcal{N})$.

Now, computing the exponential mapping from the standard formula

$$
\varphi(\exp t A)=e^{\varphi_{*}(t A)}, \quad \varphi(\exp t B)=e^{\varphi_{*}(t B)}
$$

one obtains the expression for $\varphi(t, x)$. The lemma is proved.
Remark. We have also proven that $G$ is solvable, non-nilpotent and not completely solvable, since ad $A$ possesses an imaginary eigenvalue (see the expression of ad $\left.A=\varphi_{*}(A)\right)$.

Lemma 3. Let $S \in \mathrm{SL}(2, \mathbb{Z})$ be a matrix with two distinct real eigenvalues, say, $\lambda$ and $\lambda^{-1}$. Let $P \in \mathrm{GL}(2, \mathbb{R})$ be a matrix such that

$$
P S P^{-1}=\left(\begin{array}{cc}
\lambda & 0 \\
0 & \lambda^{-1}
\end{array}\right)
$$

Put $a_{0}=\ln \lambda$. If one takes $\alpha=2 \pi / a_{0}$ in (2), then the set

$$
\Gamma=\left(\left(a_{0} \mathbb{Z}\right) \times \mathbb{Z}\right) \times_{\varphi} L, \quad L=\left(P\left(m_{1}, m_{2}\right), P\left(n_{1}, n_{2}\right),\left(q_{1}, q_{2}\right)\right)
$$

is a lattice in an appropriate Lie group $G$.
Proof. It is enough to prove that $L$ is invariant under $\varphi\left(\left(a_{0} \mathbb{Z}\right) \times \mathbb{Z}\right)$. From Lemma 2 one obtains by straightforward calculation

$$
\varphi\left(a_{0} p_{1}, p_{2}\right)=\left(\begin{array}{ccc}
P S^{p_{1}} P^{-1} & p_{2} P S^{p_{1}} P^{-1} & 0 \\
0 & P S^{p_{1}} P^{-1} & 0 \\
0 & 0 & E_{2}
\end{array}\right)
$$

Applying the latter linear transformation to $L$, one obtains $\varphi\left(a_{0} p_{1}, p_{2}\right)(L) \subset$ $L$ (the calculation is straightforward). The lemma is proved.

Lemma 4. Under the assumptions of Theorem 2, the pair

$$
\left(\left(\Lambda L(G)^{*}, \delta\right), H^{*}\left(\Lambda L(G)^{*}, \delta\right)\right)
$$

has a non-vanishing quadruple Massey product. The graded differential algebra $\left(\Lambda L(G)^{*}, \delta\right)$ is cohomologically symplectic.

Proof. Consider the dual base in $L(G)^{*}$, which we denote by

$$
\left\{a, b, x_{1}, x_{2}, x_{3}, x_{4}, x_{5}, x_{6}\right\}
$$

From (4) (which is valid for any $\left.\left(\Lambda L(G)^{*}, \delta\right)\right)$ the following formulas hold:

$$
\delta a=\delta b=0
$$

$$
\begin{gathered}
\delta x_{1}=-a x_{1}-b x_{3}, \quad \delta x_{2}=a x_{2}-b x_{4}, \quad \delta x_{3}=a x_{3}, \quad \delta x_{4}=-a x_{4}, \\
\\
\delta x_{5}=a x_{6}, \quad \delta x_{6}=-a x_{5} .
\end{gathered}
$$

The element

$$
\omega=a b+x_{3} x_{4}+x_{1} x_{3}+x_{2} x_{4}+x_{5} x_{6}
$$

shows that $\left(\Lambda L(G)^{*}, \delta\right)$ is symplectic, since $\omega^{4} \neq 0$ (it is proportional to $\left.a b x_{1} x_{2} x_{3} x_{4} x_{5} x_{6}\right)$. The latter product cannot be exact, since a straightforward computation shows that

$$
\begin{aligned}
\delta\left(\mu a x_{1} x_{2} x_{3} x_{4} x_{5} x_{6}+\nu b x_{1} x_{2} x_{3} x_{4} x_{5} x_{6}\right. & \\
& \left.+\sum_{i j} \gamma_{i j} a b x_{1} \ldots \widehat{x}_{i} \ldots \widehat{x}_{j} \ldots x_{6}\right)=0
\end{aligned}
$$

(the vanishing of $\delta$ on the first two terms follows from the fact that all $\delta x_{j}$ contain either $a$ or $b$, and the vanishing of $\delta$ on the sum of the other terms can be verified directly).

A calculation of the same kind shows that $\delta \omega=0$ and thus $\Lambda L(G)^{*}$ is symplectic.

The pair $\left(\left(\Lambda L(G)^{*}, \delta\right), H^{*}\left(\Lambda L(G)^{*}\right)\right)$ has a non-vanishing quadruple Massey product. To prove this, use a straightforward generalization of the argument in [7]. We reproduce it here for the convenience of the reader. To simplify notations, we denote the Chevalley-Eilenberg complex $\left(\Lambda L(G)^{*}, \delta\right)$ by the symbol $(A, \delta)$. If all the triple Massey products in $(A, \delta)$ vanish, one can form a quadruple Massey product as follows. Let $\left[\lambda_{1}\right] \in H^{p}(A),\left[\lambda_{2}\right] \in H^{q}(A),\left[\lambda_{3}\right] \in H^{r}(A),\left[\lambda_{4}\right] \in H^{s}(A)$ and assume that

$$
\left\langle\left[\lambda_{1}\right],\left[\lambda_{2}\right],\left[\lambda_{3}\right]\right\rangle=0, \quad\left\langle\left[\lambda_{2}\right],\left[\lambda_{3}\right],\left[\lambda_{4}\right]\right\rangle=0 .
$$

Then one can define the quadruple Massey product $\left\langle\left[\lambda_{1}\right],\left[\lambda_{2}\right],\left[\lambda_{3}\right],\left[\lambda_{4}\right]\right\rangle$, which vanishes if and only if there exist $f_{1} \in A^{p+q-1}, f_{2} \in A^{q+r-1}, f_{3} \in$ $A^{r+s-1}, \mu_{1} \in A^{p+q+r-2}, \mu_{2} \in A^{q+r+s-2}$ such that

$$
\begin{gather*}
\lambda_{1} \wedge \lambda_{2}=\delta f_{1}  \tag{5}\\
\lambda_{2} \wedge \lambda_{3}=\delta f_{2}  \tag{6}\\
\lambda_{3} \wedge \lambda_{4}=\delta f_{3}  \tag{7}\\
\lambda_{1} \wedge f_{2}+(-1)^{p+1} f_{1} \wedge \lambda_{3}=\delta \mu_{1}  \tag{8}\\
\lambda_{2} \wedge f_{3}+(-1)^{q+1} f_{2} \wedge \lambda_{4}=\delta \mu_{2}  \tag{9}\\
{\left[(-1)^{p+1} \lambda \wedge \mu_{2}+(-1)^{q+1} \mu_{1} \wedge \lambda_{4}+f_{1} \wedge f_{3}\right]=0} \tag{10}
\end{gather*}
$$

Take $\lambda_{1}=x_{3} \wedge x_{4}, \lambda_{2}=\lambda_{3}=\lambda_{4}=b$. One can check that the triple Massey products $\left\langle\left[x_{3} \wedge x_{4}\right],[b],[b]\right\rangle$ and $\langle[b],[b],[b]\rangle$ vanish. Therefore, one can define the following quadruple Massey product:

$$
\left\langle\left[x_{3}\right] \wedge\left[x_{4}\right],[b],[b],[b]\right\rangle .
$$

Assume that it vanishes. Then one can rewrite (5)-(10) as follows:

$$
\begin{gather*}
x_{3} \wedge x_{4} \wedge b=\delta f_{1} \\
0=\delta f_{2} \\
0=\delta f_{3} \\
x_{3} \wedge x_{4} \wedge f_{2}-f_{1} \wedge b=\delta \mu_{1} \\
b \wedge f_{3}+f_{2} \wedge b=\delta \mu_{2} \\
{\left[-x_{3} \wedge x_{4} \wedge \mu_{2}+\mu_{1} \wedge b+f_{1} \wedge f_{3}\right]=0}
\end{gather*}
$$

Observe that

$$
\delta\left(x_{1} \wedge x_{4}\right)=\left(-a \wedge x_{1}-b \wedge x_{3}\right) \wedge x_{4}-x_{1} \wedge a \wedge x_{4}=-b \wedge x_{3} \wedge x_{4}
$$

and from ( $5^{\prime}$ ) one obtains

$$
\begin{equation*}
\delta f_{1}=-\delta\left(x_{1} \wedge x_{4}\right) \Rightarrow f_{1}=-x_{1} \wedge x_{4}+f_{1}^{\prime}, \delta f_{1}^{\prime}=0 \tag{11}
\end{equation*}
$$

Substituting (11) to (4') we have

$$
\begin{equation*}
x_{3} \wedge x_{4} \wedge f_{2}+x_{1} \wedge x_{4} \wedge b+f_{1}^{\prime} \wedge b=\delta \mu_{1} \tag{12}
\end{equation*}
$$

which implies

$$
\left[x_{3} \wedge x_{4}\right] \cdot\left[f_{2}\right] \in[b] \cdot H^{2}(A)
$$

A straightforward calculation shows that

$$
H^{2}(A)=\left\{[a \wedge b],\left[x_{3} \wedge x_{4}\right],\left[x_{1} \wedge x_{4}+x_{2} \wedge x_{3}\right],\left[x_{5} \wedge x_{6}\right]\right\}
$$

which implies
(13)

$$
f_{2}=t \cdot b, \quad t \in \mathbb{R}
$$

From (1'),

$$
\left[x_{3} \wedge x_{4}\right] \cdot[b]=0 \Rightarrow\left[x_{3} \wedge x_{4}\right] \cdot\left[f_{2}\right]=0
$$

and therefore, from (12),

$$
\left[b \wedge x_{1} \wedge x_{4}\right]=[b] \cdot\left[f_{1}^{\prime}\right]
$$

The latter equality implies

$$
\begin{equation*}
f_{1}^{\prime}=\frac{1}{2}\left(x_{1} \wedge x_{4}+x_{2} \wedge x_{3}\right)+p \cdot a \wedge b+q \cdot x_{3} \wedge x_{4} \tag{14}
\end{equation*}
$$

To prove (14) observe that

$$
\begin{aligned}
\delta\left(x_{1} \wedge x_{2}\right) & =\left(-a \wedge x_{1}-b \wedge x_{3}\right) \wedge x_{2}-x_{1} \wedge\left(a \wedge x_{2}-b \wedge x_{4}\right) \\
& =b \wedge x_{2} \wedge x_{3}-b \wedge x_{1} \wedge x_{4}
\end{aligned}
$$

and thus

$$
\left[b \wedge x_{1} \wedge x_{4}\right]=\left[b \wedge x_{2} \wedge x_{3}\right] .
$$

From (14) and (12),
(15) $f_{1}=-x_{1} \wedge x_{4}+\frac{1}{2}\left(x_{1} \wedge x_{4}+x_{2} \wedge x_{3}\right)+p \cdot a \wedge b+q \cdot x_{3} \wedge x_{4}$

$$
=\frac{1}{2}\left(x_{2} \wedge x_{3}-x_{1} \wedge x_{4}\right)+p \cdot a \wedge b+q \cdot x_{3} \wedge x_{4}, \quad p, q \in \mathbb{R}
$$

From (13), ( $7^{\prime}$ ) and ( $9^{\prime}$ ) one obtains

$$
\begin{equation*}
f_{2}-f_{3}=s \cdot b, \quad s \in \mathbb{R} \tag{16}
\end{equation*}
$$

To prove this equality, one should notice that $\left[f_{2}\right],\left[f_{3}\right] \in H^{1}(A)=\operatorname{Span}(a, b)$ and $\left.\left[f_{2}-f_{3}\right)\right] \wedge[b]=0\left(\right.$ from $\left.\left(9^{\prime}\right)\right)$. Thus, (16) is the only possibility for $f_{2}$ and $f_{3}$. Since $f_{3}=(t-s) \cdot b$, one obtains

$$
\begin{equation*}
\delta \mu_{2}=0 \tag{17}
\end{equation*}
$$

A straightforward calculation shows that

$$
\begin{equation*}
f_{1} \wedge f_{3}=\delta\left((t-s) \cdot x_{2} \wedge\left(q \cdot x_{3}-\frac{1}{2} \cdot x_{1}\right)\right) \tag{18}
\end{equation*}
$$

Thus, one can rewrite ( $8^{\prime}$ ) and ( $10^{\prime}$ ) as follows
$\left(8^{\prime \prime}\right) \quad(t+q) \cdot b \wedge x_{3} \wedge x_{4}-\frac{1}{2} b \wedge\left(x_{2} \wedge x_{3}-x_{1} \wedge x_{4}\right)=\delta \mu_{1}$,

$$
-\left[x_{3} \wedge x_{4}\right] \wedge\left[\mu_{2}\right]+\left[\mu_{1} \wedge b\right]=0
$$

One can check that

$$
b \wedge x_{3} \wedge x_{4}=\delta\left(-x_{1} \wedge x_{4}\right), \quad b \wedge\left(x_{2} \wedge x_{3}-x_{1} \wedge x_{1}\right)=\delta\left(x_{1} \wedge x_{2}\right)
$$

These equations together with ( $8^{\prime \prime}$ ) imply that there exists a closed element $\mu_{1}^{\prime}$ such that

$$
\mu_{1}=-(t+q) x_{1} \wedge x_{4}-\frac{1}{2} x_{1} \wedge x_{2}+\mu_{1}^{\prime}
$$

The latter equation implies

$$
\left[\mu_{1} \wedge b\right]=-(t+q) \cdot\left[x_{1} \wedge x_{4} \wedge b\right]-\frac{1}{2}\left[x_{1} \wedge x_{2} \wedge b\right]+\left[\mu_{1}^{\prime}\right] \wedge[b] .
$$

Therefore, one can rewrite ( $10^{\prime \prime}$ ) as follows:

$$
\left[-x_{3} \wedge x_{4}\right] \wedge\left[\mu_{2}\right]-(t+q) \cdot\left[x_{1} \wedge x_{4} \wedge b\right]-\frac{1}{2}\left[x_{1} \wedge x_{2} \wedge b\right]+\left[\mu_{1}^{\prime}\right] \wedge[b]=0
$$

So, the cohomology class $\left[x_{1} \wedge x_{2} \wedge b\right]$ satisfies the condition

$$
\left[x_{1} \wedge x_{2} \wedge b\right] \in[b] \cdot H^{2}(A)+\left[x_{3} \wedge x_{4}\right] \cdot H^{1}(A)
$$

which is generated by $\left[b \wedge x_{1} \wedge x_{4}\right],\left[a \wedge x_{3} \wedge x_{4}\right],\left[b \wedge x_{5} \wedge x_{6}\right]$. This is impossible because the cohomology classes $\left[x_{1} \wedge x_{2} \wedge b\right],\left[b \wedge x_{1} \wedge x_{4}\right],\left[b \wedge x_{5} \wedge x_{6}\right],[a \wedge$ $\left.x_{3} \wedge x_{4}\right]$ are linearly independent (this may be verified directly). The proof is complete.

Proof of Theorem 2. Lemma 2 implies (i); (ii) follows from Lemma 3 and the remark after Lemma 2. To prove (iii), we use again the isomorphism between the graded differential algebra $\left(\Lambda L(G)^{*}, \delta\right)$ and the algebra of left-invariant differential forms on $G$. The inequality $\omega^{4} \neq 0$ in case of left-invariant differential forms implies the non-degeneracy of the appropri-
ate matrix of the 2-form $\omega$. Since $G \rightarrow G / \Gamma$ is a covering, the matrix of the differential form induced by $\omega$ on $G / \Gamma$ remains the same and, therefore, remains non-degenerate. Thus, $\omega$ determines a symplectic structure on $G / \Gamma$. Since Lemma 4 implies that the pair $\left(\left(\Lambda L(G)^{*}, \delta\right), H^{*}\left(\Lambda L(G)^{*}\right)\right)$ has a non-zero quadruple Massey product, the proof follows from Theorem 1 and the DGMS-theorem (see Section 2).
5. Proof of Theorem 3 and corollaries. Let $(\Lambda X \otimes \Lambda Y, d)$ satisfy the conditions of Theorem 3. In the sequel we assume $X$ and $Y$ to be finitedimensional and fix the bases $x_{1}, \ldots, x_{k}, y_{1}, \ldots, y_{l}$ of $X$ and $Y$ respectively. We begin with

Lemma 5. Let $(\Lambda X \otimes \Lambda Y, d)$ satisfy the conditions of Theorem 3. Suppose that $(\Lambda X \otimes \Lambda Y, d)$ is oriented. Then, necessarily, the derivation $d$ is of the form

$$
d y_{j}=x^{(j)}+y_{s_{j} t_{j}}+\sum_{s \neq j} \widetilde{x}_{s} y_{s}+\bar{x}_{j} y_{j}, \quad j=1, \ldots, l,
$$

where

$$
\begin{equation*}
\sum_{j=1}^{l} \bar{x}_{j}=0 \tag{13}
\end{equation*}
$$

$$
x^{(j)} \in \Lambda^{2} X, \quad y_{s_{j} t_{j}} \in \Lambda^{2} Y, \quad \operatorname{deg}\left(\widetilde{x}_{s}\right)=1, \quad \operatorname{deg}\left(y_{s}\right)=1, \quad \operatorname{deg}\left(\bar{x}_{j}\right)=1
$$

Proof. Since $H^{n}(\Lambda X \otimes \Lambda Y, d) \neq 0$ and since $(\Lambda X \otimes \Lambda Y)$ is the exterior algebra,

$$
\operatorname{dim} H^{n}(\Lambda X \otimes \Lambda Y)=\operatorname{dim} Z^{n}(\Lambda X \otimes \Lambda Y)=\Lambda^{n}(X \oplus Y)=1
$$

Suppose that $\Lambda^{n-1}(X \oplus Y) \neq Z^{n-1}(\Lambda(X \oplus Y))$, so that there exists $v \in$ $\Lambda^{n-1}(X \oplus Y)$ with $d v \neq 0, d v \in \Lambda^{n}(X \oplus Y)$. By the previous remark $d v=\alpha u$, where $u$ is a generator in $\Lambda^{n}(X \oplus Y)$ corresponding to the non-zero cohomology class, which is a contradiction.

Thus

$$
\begin{equation*}
\Lambda^{n-1}(X \oplus Y)=\Lambda^{k-1, l}+\Lambda^{k, l-1}=Z^{n-1}(X \oplus Y) \tag{14}
\end{equation*}
$$

Therefore

$$
u_{i}=x_{1} \ldots \widehat{x}_{i} \ldots x_{k} y_{1} \ldots y_{l} \in \Lambda^{k-1, l}, \quad i=1, \ldots, k
$$

are cocycles (here and in the sequel $\widehat{x}_{i}$ denotes the absence of $x_{i}$ ). Calculating $d u_{i}$ explicitly one obtains

$$
\begin{aligned}
& d u_{i}=x_{1} \ldots \widehat{x}_{i} \ldots x_{k}\left((-1)^{j-1} \sum_{j=1}^{l} y_{1} \ldots y_{j-1} d y_{j} y_{j+1} \ldots y_{l}\right) \\
&= x_{1} \ldots \widehat{x}_{i} \ldots x_{k}\left\{( - 1 ) ^ { j - 1 } \sum _ { j = 1 } ^ { l } y _ { 1 } \ldots y _ { j - 1 } \left(x^{(j)}+y_{s_{j} t_{j}}\right.\right. \\
&\left.\left.+\sum_{s \neq j} \widetilde{x}_{s} y_{s}+\bar{x}_{j} y_{j}\right) y_{j+1} \ldots y_{l}\right\} \\
&= \sum_{j=1}^{l}(-1)^{j-1}\left\{x_{1} \ldots \widehat{x}_{i} \ldots x_{k} y_{1} \ldots y_{j-1} x^{(j)} y_{j+1} \ldots y_{l}\right. \\
&+x_{1} \ldots \widehat{x}_{i} \ldots x_{k} y_{1} \ldots y_{j-1} y_{s_{j} t_{j}} y_{j+1} \ldots y_{l} \\
&+x_{1} \ldots \widehat{x}_{i} \ldots x_{k} y_{1} \ldots y_{j-1}\left(\sum_{s \neq j} \widetilde{x}_{s} y_{s}\right) y_{j+1} \ldots y_{l} \\
&\left.+x_{1} \ldots \widehat{x}_{i} \ldots x_{k} y_{1} \ldots y_{j-1} \bar{x}_{j} y_{j} y_{j+1} \ldots y_{l}\right\}=0
\end{aligned}
$$

Observe that

$$
\begin{aligned}
x_{1} \ldots \widehat{x}_{i} \ldots x_{k} y_{1} \ldots y_{j-1} x^{(j)} y_{j+1} \ldots y_{l} \in \Lambda^{k+1, l} & =\{0\}, \\
x_{1} \ldots x_{i} \ldots x_{k} y_{1} \ldots y_{j-1} y_{s_{j} t_{j}} y_{j+1} \ldots y_{l} \in \Lambda^{k-1, l+1} & =\{0\}, \\
x_{1} \ldots \widehat{x}_{i} \ldots x_{k} y_{1} \ldots y_{j-1}\left(\sum_{s \neq j} \widetilde{x}_{s} y_{s}\right) y_{j+1} \ldots y_{l} & =0 .
\end{aligned}
$$

The first two equalities are obvious, the third follows, since $s \in\{1, \ldots, j-1$, $j+1, \ldots, l\}$. Finally,

$$
x_{1} \ldots \widehat{x}_{i} \ldots x_{k}\left(\sum_{j=1}^{l} \bar{x}_{j}\right) y_{1} \ldots y_{j-1} y_{j} y_{j+1} \ldots y_{l}=0
$$

which means that

$$
\sum_{j=1}^{l} \bar{x}_{j} \in \operatorname{Ann}_{\Lambda^{1,0}}\left(x_{1} \ldots \widehat{x}_{i} \ldots x_{k}\right)
$$

Since the above argument is valid for all $i$,

$$
\sum_{j=1}^{l} \bar{x}_{j} \in \bigcap_{i=1}^{k} \operatorname{Ann}_{\Lambda^{1,0}}\left(x_{1} \ldots \widehat{x}_{i} \ldots x_{k}\right)
$$

Since the sum of $\bar{x}_{j}$ is of degree $1,(13)$ follows. Lemma 5 is proved.

Lemma 6. Under the conditions of Lemma 5 we have the inclusion

$$
\begin{equation*}
d\left(\Lambda^{k-2, l}\right) \subset \Lambda^{k, l-1} \tag{15}
\end{equation*}
$$

Proof. Take the element $y_{1} \ldots y_{l}$. Then

$$
\begin{aligned}
d\left(y_{1} \ldots y_{l}\right)= & \sum_{i=1}^{l}(-1)^{i-1} y_{1} \ldots d y_{i} \ldots y_{l} \\
= & \sum_{i=1}^{l}(-1)^{i-1} y_{1} \ldots y_{i-1}\left(x^{(i)}+y_{s_{i} t_{i}}+\sum_{s \neq i} \widetilde{x}_{s} y_{s}+\bar{x}_{i} y_{i}\right) y_{i+1} \ldots y_{l} \\
= & \sum_{i=1}^{l}(-1)^{i-1} y_{1} \ldots y_{i-1} \bar{x}^{(i)} y_{i+1} \ldots y_{l} \\
& +\sum_{i=1}^{l}(-1)^{i-1} y_{1} \ldots y_{i-1} \bar{x}_{i} y_{i} y_{i+1} \ldots y_{l} \\
= & \sum_{i=1}^{l}(-1)^{i-1} y_{1} \ldots y_{i-1} x^{(i)} y_{i+1} \ldots y_{l} \in \Lambda^{2, l},
\end{aligned}
$$

because

$$
\begin{aligned}
y_{1} \ldots y_{i-1} y_{s_{i} t_{i}} y_{i+1} \ldots y_{l} \in \Lambda^{0, l+1} & =\{0\} \\
y_{1} \ldots y_{i-1}\left(\sum_{s \neq i} \widetilde{x}_{s} y_{s}\right) y_{i+1} \ldots y_{l} & =0
\end{aligned}
$$

and

$$
\sum_{i=1}^{l}(-1)^{2(i-1)} \bar{x}_{i} y_{1} \ldots y_{i-1} y_{i} y_{i+1} \ldots y_{l}=\left(\sum_{i=1}^{l} \bar{x}_{i}\right) y_{1} \ldots y_{l}=0
$$

from Lemma 5. Lemma 6 is proved.
Lemma 7. Let $(\Lambda X \otimes \Lambda Y, d)$ satisfy the conditions of Lemma 5. Assume in addition that the Poincaré duality holds. If

$$
\begin{equation*}
H^{1}(\Lambda X \otimes \Lambda Y, d)=\Lambda^{1,0} \tag{16}
\end{equation*}
$$

then

$$
\begin{equation*}
H^{n-1}(\Lambda X \otimes \Lambda Y, d)=\Lambda^{k-1, l} \tag{17}
\end{equation*}
$$

Proof. From the Poincaré duality

$$
\operatorname{dim} H^{n-1}(\Lambda X \otimes \Lambda Y)=k
$$

From (14),

$$
Z^{n-1}(\Lambda X \otimes \Lambda Y)=\Lambda^{k-1, l}+\Lambda^{k, l-1}
$$

and by comparing the degrees (the calculation is straightforward, although it is necessary to use the minimality of $(\Lambda Y, \delta)$ which guarantees that $y_{s_{j} t_{j}}$
do not contain expressions with $y_{j}$ ):

$$
d\left(\Lambda^{k-1, l-1}\right) \subset \Lambda^{k, l-1}, \quad d\left(\Lambda^{k, l-2}\right) \subset \Lambda^{k, l-1} .
$$

From Lemma 6 (formula (15)), $d\left(\Lambda^{k-2, l}\right) \subset \Lambda^{k, l-1}$ and therefore, the subspace $B^{n-1}$ of coboundaries is contained in $\Lambda^{k, l-1}$. Thus,

$$
\operatorname{dim} H^{n-1}(\Lambda X \otimes \Lambda Y)=\operatorname{dim}\left(\Lambda^{k-1, l}+\Lambda^{k, l-1}\right)-\operatorname{dim} B^{n-1}=k
$$

Therefore, since $\operatorname{dim} \Lambda^{k, l-1}=l, \operatorname{dim} \Lambda^{k-1, l}=k$, the assumption $B^{n-1} \neq$ $\Lambda^{k, l-1}$ would imply

$$
\operatorname{dim} H^{n-1}=\operatorname{dim} Z^{n-1}-\operatorname{dim} B^{n-1}=k+l-\operatorname{dim} B^{n-1}>k
$$

Thus

$$
\begin{equation*}
B^{n-1}=\Lambda^{k, l-1} \tag{18}
\end{equation*}
$$

and Lemma 7 is proved.
Proof of Theorem 3. Since there exists a model $\left(A^{*}(E), d\right)$ which admits a structure of a twisted tensor product, it remains to prove that this algebra possesses the algebraic properties (i)-(iv) stated in Theorem 3. The first property follows from the existence of a Kählerian structure on $E$.

Suppose that $(\Lambda X \otimes \Lambda Y, d)$ satisfies the conditions of Lemma 7 and $d y_{j}$ are linearly independent. Then (16) holds, since $\left.d\right|_{X}=0$ and $\left.d\right|_{Y}$ is one-to-one. If some $d y_{j}$ are linearly dependent, by the obvious base change one can assume that for the new basis vectors $\bar{y}_{j}, d \bar{y}_{j}=0$ and thus $\bar{y}_{j} \in X$. Therefore one can assume the linear independence of $d y_{j}$ without loss of generality and (17) follows. Now, the condition (ii) follows from Lemma 7.

To prove (iii)-(iv), take $y^{*} \in Y^{*}$ and observe that

$$
\left(i\left(y^{*}\right) \omega\right) \omega^{m-1}=\frac{1}{m} i\left(y^{*}\right) \omega^{m} \in \Lambda^{k, l-1}
$$

since $\omega^{m} \in \Lambda^{n}=\Lambda^{k+l}$. From (18), $i\left(y^{*}\right) \omega^{m}$ is a coboundary. Therefore, $i\left(y^{*}\right) \omega \notin \Lambda^{1,0}$ because otherwise the hard Lefschetz condition and Lemma 7 would give a contradiction. Thus there exists $\bar{y}^{*} \in Y^{*}$ such that $\omega\left(y^{*}, \bar{y}^{*}\right) \neq$ 0 and therefore $\left.\omega\right|_{Y^{*} \times Y^{*}}$ is non-degenerate. Observe that using non-degeneracy, one can choose $X^{*}$ to be $\omega$-orthogonal to $Y^{*}$. Using the appropriate identifications of exterior algebra elements and alternating forms one obtains the form of the Lefschetz element, that is, (iii) and, as a consequence, (iv). Theorem 3 is proved.

Proof of Corollary 1. Observe that the assumptions of Corollary 1 imply the possibility of applying the Thomas theorem to the fibration $F \rightarrow E \rightarrow T^{k}$. Since, obviously,

$$
\mathcal{M}_{T^{k}}=(\Lambda X, 0), \quad X=\operatorname{Span}\left(x_{1}, \ldots, x_{k}\right), \quad \operatorname{deg}\left(x_{i}\right)=1, \quad i=1, \ldots, k
$$

and

$$
\mathcal{M}_{F}=(\Lambda Y, \delta), \quad Y=\operatorname{Span}\left(y_{1}, \ldots, y_{r}\right), \quad \operatorname{deg}\left(y_{j}\right)=1, \quad j=1, \ldots, r
$$

the rational model $\left(A^{*}(E), d\right)$ is a twisted tensor product

$$
\left(A^{*}(E), d\right)=\left(\Lambda X \otimes_{\tau} \Lambda Y, d\right)
$$

where $d$ satisfies the assumptions of Theorem 3 .
Coming back to the solvmanifold case, let $N$ be the nilradical of $G$. From the Mostow theorem [16], $N \cap \Gamma$ is a lattice in $N$. The latter fact is equivalent to the closedness of $N \Gamma$ in $G$. Therefore, one can construct the Mostow bundle

$$
\Gamma N / \Gamma=N / N \cap \Gamma \rightarrow G / \Gamma \rightarrow G / \Gamma N .
$$

It is well known that $G / \Gamma N$ is a torus and since $\Gamma \cap N$ is a lattice, the fiber of the considered fibration is a compact nilmanifold and thus has the homotopy type of $K(\pi, 1)$ with nilpotent $\pi$. Since we assumed the nilpotency of the $\pi_{1}(G / \Gamma N)$-action on the cohomology of the fiber, the conditions of Theorem 3 are satisfied and there exists a free graded differential algebra, which is a rational model of $G / \Gamma$ and satisfies the algebraic properties (i)(iv) proved in Theorem 3. This model of course can be represented in the form $\mathcal{M}_{G / \Gamma N} \otimes_{\tau} \mathcal{M}_{N / N \cap \Gamma}$.

Proof of Corollary 2. Analyzing the proof of Theorem 3 one can notice that conditions (ii)-(iv) are valid for any twisted tensor product of the form given in Theorem 3 and satisfying the Lefschetz condition. Following [4] we assign to $G / \Gamma$ a model $\bar{A}^{*}(G / \Gamma)$ which possesses properties (i)-(iv) of $A^{*}(G / \Gamma)$, although this new model in general differs from the latter. We observe that for completely solvable Lie groups,

$$
H^{*}(G / \Gamma) \simeq H^{*}(L(G))=H^{*}\left(\Lambda L(G)^{*}, \delta\right)
$$

by Hattori's theorem [11]. Since

$$
\left(\Lambda L(G)^{*}, \delta\right) \simeq\left(\Omega_{\mathrm{DR}}^{\mathrm{inv}}(G), d\right)
$$

the cohomology class of a Kählerian form has a representative $\omega \in$ $\left(\Lambda^{2} L(G)^{*}, \delta\right)$. Since $\omega^{m} \neq 0$ and $\omega$ is an alternating 2-form on $L(G)$, it is non-degenerate. Therefore, $\left(\Lambda L(G)^{*}, \delta\right)$ can be taken as a model of $G / \Gamma$.

Take $\mathcal{N}=[L(G), L(G)]$ and decompose $L(G)^{*}$ as a vector space sum $L(G)^{*}=\mathcal{A}^{*} \oplus \mathcal{N}^{*}$, where

$$
\mathcal{A}^{*}=\left\{\theta \in L(G)^{*}: \theta(\mathcal{N})=0\right\}, \quad \mathcal{N}^{*}=\left\{\alpha \in L(G)^{*}: \alpha(\mathcal{A})=0\right\}
$$

(here $\mathcal{A}$ is an arbitrary complement to $\mathcal{N}$ ). Now, taking into account the equalities (the first follows from (4))

$$
\delta \beta(U, V)=-\beta([X, Y]), \quad \mathcal{N}=[L(G), L(G)]
$$

we have $\delta\left(\Lambda \mathcal{A}^{*}\right)=0$. Since $\mathcal{N}$ is contained in the nilradical of $L(G)$, the ideal $\mathcal{N}$ is nilpotent and therefore $\left(\Lambda \mathcal{N}^{*},\left.\delta\right|_{\Lambda \mathcal{N}^{*}}\right)$ is a minimal graded differential algebra. Therefore,

$$
\left(\bar{A}^{*}(G / \Gamma)=\left(\Lambda L(G)^{*}, \delta\right)=\left(\Lambda \mathcal{A}^{*}, \delta=0\right) \otimes_{\tau}\left(\Lambda \mathcal{N}^{*},\left.\delta\right|_{\Lambda \mathcal{N}^{*}}\right)\right.
$$

(that is, the model for $G / \Gamma$ can be represented as a twisted tensor product satisfying the condition (ii) of Theorem 3, the Lefschetz condition and the conditions of Lemmas 5-7 (the latter is guaranteed by the minimality of the second term in the twisted tensor product). Finally, $\left(\bar{A}^{*}(G / \Gamma), d\right)$ has the properties (i)-(iv) of Theorem 3 and as a consequence, the properties (ii), (iv) and (v) of Corollary 2.

Remark. These properties were proved in [4] directly for the particular case of $\left(\Lambda L(G)^{*}, \delta\right)$ with completely solvable $G$.

To finish the proof it is enough to repeat the argument in [4] (parts (i), (iii) and (vi). Here, of course, the proof is based on the particular choice of $\left(\bar{A}^{*}(G / \Gamma), d\right)$. For example, the commutativity of $\mathcal{A}$ follows from (v) of Theorem 2 and the formula

$$
\begin{aligned}
0 & =\delta \omega(A, B, V) \\
& =-\omega([A, B], V)+\omega([A, V], B)-\omega([B, V], A), \quad A, B \in \mathcal{A}, V \in \mathcal{N}
\end{aligned}
$$

(see the proof in [4] for details). The corollary is proved.
Remark. There are examples of solvmanifolds for which the associated Mostow bundle satisfies the nilpotency condition for $\pi_{1}(G / N \Gamma)$. Consider the semidirect product $G=\mathbb{R}^{2} \times_{\varphi} \mathbb{R}^{4}$ determined by the homomorphism $\varphi: \mathbb{R}^{2} \rightarrow \mathrm{GL}\left(\mathbb{R}^{4}\right)$ of the form

$$
\varphi(x, t)=\left(\begin{array}{cccc}
\cos \pi 2 t & \sin \pi 2 t & x \cos \pi t & x \sin \pi t \\
-\sin \pi 2 t & \cos \pi 2 t & -x \sin \pi t & x \cos \pi t \\
0 & 0 & \cos \pi 2 t & \sin \pi 2 t \\
0 & 0 & -\sin \pi 2 t & \cos \pi 2 t
\end{array}\right)
$$

One can show by exactly the same method as in the proof of Theorem 2 that $G$ is a solvable non-nilpotent Lie group possessing a lattice. The corresponding Mostow bundle is of the form $T^{4} \rightarrow G / \Gamma \rightarrow T^{2}$. The action of $\pi_{1}\left(T^{2}\right)$ on $H^{*}\left(T^{4}\right)$ is nilpotent. To prove this, it is enough to combine several observations. First, since the generators of the fundamental group of the base can be represented as submanifolds in $T^{2}$, one can reduce the study of their action to the action of the same elements on the cohomology of the fiber in the corresponding portion of the Mostow bundle over $S^{1}$. Since the Mostow bundle is a smooth Steenrod fiber bundle [22] with structure group $N \Gamma / H$ ( $H$ is a maximal normal subgroup contained in $\Gamma$ ), its portions over $S^{1}$ can be reduced to bundles with discrete structure group (say, introducing a connection in the corresponding principal fiber bundles
and using the holonomy theorem). But for Steenrod fiber bundles with discrete groups the fundamental group of the base acts on the cohomology of the fiber via the representation in the structure group of the bundle acting on the fiber [22]. Calculating now this action for our particular Mostow bundle, one can notice that a non-trivial action may come only from the elements of the lattice $\Gamma$ generating non-trivial classes in $N \Gamma / H$. But $\varphi(m, n)$ is a unipotent matrix for all $(m, n) \in \mathbb{Z}^{2}$, which implies the nilpotency of the action on $H^{*}(N / N \cap \Gamma)$. Thus, we have constructed a solvmanifold for which the corresponding Mostow bundle satisfies the nilpotency condition. However, this example is not very interesting, since the total space of this bundle is diffeomorphic to a nilmanifold. The author failed to construct an example of a "pure" solvmanifold with the required property. The above argument might work for non-abelian fibers, since the torsion in $\Gamma \cap N /[\Gamma \cap N, \Gamma \cap N]=(\Gamma \cap N)_{\text {ab }}$ might "kill" some generators in cohomology, e.g. in $H^{1}(N / N \cap \Gamma) \simeq(\Gamma \cap N)_{\mathrm{ab}} \otimes \mathbb{Q}$.

On the other hand, an example in [17] shows that there are solvmanifolds whose Mostow bundles do not satisfy the nilpotency condition.

Acknowledgements. This work was supported by the Polish KBN. The author is grateful to Martin Saralegi for the opportunity of reading the preprint [7] before its publication and to the referee for valuable advice and improvements. The final version of this paper was finished during the author's stay in Mathematisches Forschungsinstitut (Oberwolfach). The Volkswagen-Stiftung research grant "Research in Pairs" is greatly appreciated.

## REFERENCES

[1] E. Abbena, An example of an almost Kähler manifold which is not Kählerian, Boll. Un. Mat. Ital. (6) 3-A (1984), 383-392.
[2] L. Auslander, An exposition of the structure of solvmanifolds, Bull. Amer. Math. Soc. 79 (1973), 227-285.
[3] C. Benson and C. S. Gordon, Kähler and symplectic structures on nilmanifolds, Topology 27 (1988), 513-518.
[4] —, —, Kähler structures on compact solvmanifolds, Proc. Amer. Math. Soc. 108 (1990), 971-980.
[5] L. A. Cordero, M. Fernandez and A. Gray, Symplectic manifolds with no Kähler structure, Topology 25 (1986), 375-380.
[6] P. Deligne, P. Griffiths, J. Morgan and D. Sullivan, Real homotopy theory of Kähler manifolds, Invent. Math. 29 (1975), 245-274.
[7] M. Fernández, M. de León and M. Saralegui, A six-dimensional compact symplectic solvmanifold without Kähler structures, Osaka J. Math. 33 (1996), 19-35.
[8] R. Gompf, Some new symplectic 4-manifolds, Turkish J. Math. 18 (1994), 7-15.
[9] S. Halperin, Lectures on Minimal Models, Hermann, 1982.
[10] K. Hasegawa, Minimal models of nilmanifolds, Proc. Amer. Math. Soc. 106 (1989), 67-71.
[11] A. Hattori, Spectral sequence in the de Rham cohomology of fibre bundles, J. Fac. Sci. Univ. Tokyo Sect. 18 (1960), 289-331.
[12] K. Hess, Twisted tensor products of DGA's and the Adams-Hilton model for the total space of a fibration, in: London Math. Soc. Lecture Note Ser. 175, Cambridge Univ. Press, 1992, 29-51.
[13] D. Kraines, Massey higher products, Trans. Amer. Math. Soc. 124 (1966), 431-449.
[14] D. Lehmann, Théorie homotopique des formes différentielles (d'après D. Sullivan), Astérisque 45 (1977).
[15] G. Lupton and J. Oprea, Symplectic manifolds and formality, J. Pure Appl. Algebra 91 (1994), 193-207.
[16] D. McDuff, Examples of symplectic simply connected manifolds with no Kähler structure, J. Differential Geom. 20 (1984), 267-277.
[17] C. McCord and J. Oprea, Rational Lusternik-Schnirelmann category and the Arnold conjecture for nilmanifolds, Topology 32 (1993), 701-717.
[18] G. D. Mostow, Factor spaces of solvable groups, Annals of Math. 60 (1954), 1-27.
[19] M. Raghunathan, Discrete Subgroups of Lie Groups, Springer, 1972.
[20] M. Schlessinger and J. Stasheff, Deformation theory and rational homotopy type, preprint (1992), 44 pp .
[21] J.-P. Serre, Homologie singulière des espaces fibrés, Ann. of Math. 54 (1951), 425505.
[22] N. Steenrod, The Topology of Fiber Bundles, Princeton Univ. Press, 1951.
[23] D. Tanré, Homotopie Rationnelle: Modèles de Chen, Quillen, Sullivan, Springer, 1983.
[24] J.-C. Thomas, Homotopie rationnelle des fibrés de Serre, Université des Sciences et Techniques de Lille I, 1980.
[25] -, Rational homotopy of Serre fibrations, Ann. Inst. Fourier (Grenoble) 31 (3) (1981), 71-90.
[26] E. Vinberg, V. Gorbatsevich and O. Shvartsman, Discrete Subgroups of Lie Groups, Itogi Nauki i Tekhniki. Sovremennye Problemy Matematiki 21 (1988), 5115 (in Russian).

Institute of Mathematics
University of Wrocław
Pl. Grunwaldzki 2/4
50-384 Wrocław, Poland
E-mail: tralle@sus.univ.szczecin.pl


[^0]:    1991 Mathematics Subject Classification: 53C15, 55P62.

