

COMPLEX CONVEXITY AND FIXED POINT THEOREMS IN ORLICZ MODULAR SPACES

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Abstract. In this paper, we prove that every Orlicz modular function space $L_{\Phi, \rho}$ is complex midpoint locally uniformly convex. As a corollary, $L_{\Phi, \rho}$ is also complex strictly convex. Furthermore, we introduce the notions of mean nonexpansive mappings in the modular sense and prove a fixed point theorem in Orlicz modular function spaces.

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1. Introduction. In 1967, the notions of complex extreme points and complex strict convexity have been introduced by E. Thorp and R. Whitley [37]. They proved that the strong maximum modulus theorem for analytic functions with values in a complex Banach space X holds whenever each point of the unit sphere of X is a complex extreme point (see [36]). In 1975, J. Globevnik further introduced the notions of complex strict and uniform convexity of complex normed spaces and proved that the complex space L_1 is complex uniformly convex (see [17]). W. Davis, D. Darling and N. Tomczak-Jaegermann in [14] investigated the complex convexity of quasi-normed linear spaces. P. N. Dowling, Z. B. Hu and D. Mupasiri in [15] studied the complex convexity of Lebesgue–Bochner function spaces. O. Blasco and M. Pavlović in [1] obtained sufficient and necessary conditions for a complex Banach space X which is p -uniformly PL-convex. C. Choi, A. Kamińska and H. J. Lee in [7] obtained criteria for complex extreme points, complex rotundity and complex uniform convexity in Orlicz–Lorentz spaces. H. Hudzik and A. Narloch in [19] considered relationships between monotonicity and complex rotundity, for instance, a point f of the complexification E^C of a real Köthe space E is a complex extreme point if and only if $|f|$ is a point of upper monotonicity in E . H. J. Lee in [26, 27] continued studying relationships between monotonicity and complex convexity in Banach lattices and quasi-Banach lattices respectively. M. M. Czerwińska and A. Kamińska in [12] discussed the complex rotundity and midpoint local uniform convexity in symmetric spaces of measurable operators and they also obtained the concepts of complex midpoint local uniform rotundity and complex local uniform rotundity are equivalent for any complex Banach spaces. Recently, M. M. Czerwińska and A. Parrish in [13] characterized complex extreme points in Marcinkiewicz spaces.

In this work, we prove that any Orlicz modular function space $L_{\Phi, \rho}$ is complex midpoint locally uniformly convex. As a corollary, $L_{\Phi, \rho}$ is also complex strictly convex. Furthermore, we introduce the notions of mean nonexpansive mappings in the modular sense and prove a fixed point theorem in Orlicz modular function spaces.

Before starting with our results, we need to recall some basic concepts and facts of the theory of modular spaces and Orlicz spaces. For basic information concerning fixed point theory for nonexpansive mappings see [18].

Let X be a vector space over the complex field \mathbb{C} . A functional $\rho : X \rightarrow [0, \infty]$ is called a modular provided that for any $f, g \in X$,

- (a) $\rho(f) = 0$ if and only if $f = 0$;
- (b) $\rho(\alpha f) = \rho(f)$ for any $\alpha \in \mathbb{C}$ with $|\alpha| = 1$;
- (c) $\rho(\alpha f + \beta g) \leq \rho(f) + \rho(g)$ for any $\alpha, \beta \geq 0$ with $\alpha + \beta = 1$.

If we replace (c) by

- (c') $\rho(\alpha f + \beta g) \leq \alpha \rho(f) + \beta \rho(g)$ for any $\alpha, \beta \geq 0$ with $\alpha + \beta = 1$,

then the modular ρ is said to be a *convex modular*. A modular space X_ρ is defined by

$$X_\rho = \{f \in X : \rho(\lambda f) \rightarrow 0 \text{ as } \lambda \rightarrow 0\}.$$

Let X_ρ be a modular space, then

$$B(X_\rho) = \{x \in X_\rho : \rho(x) \leq 1\}, \quad \text{and} \quad S(X_\rho) = \{x \in X_\rho : \rho(x) = 1\}$$

denote the closed unit ball and the unit sphere of X_ρ respectively. In the sequel \mathbb{N} , \mathbb{R} and \mathbb{C} denote the set of natural numbers, the set of real numbers and the set of complex numbers, respectively. Let i be the complex number satisfying $i^2 = -1$.

A map $\Phi : R \rightarrow [0, \infty]$ is said to be an *Orlicz function* if Φ is vanishing at zero, even, convex and continuous, and satisfies $\lim_{u \rightarrow 0} \frac{\Phi(u)}{u} = 0$ and $\lim_{u \rightarrow \infty} \frac{\Phi(u)}{u} = \infty$. For every Orlicz function Φ , its complementary function $\Psi : R \rightarrow [0, \infty]$ is defined by the formula

$$\Psi(v) = \sup\{u|v| - \Phi(u) : u \geq 0\},$$

the complementary function Ψ is also an Orlicz function.

For an Orlicz function Φ , we define

$$a_\Phi = \max\{u \geq 0 : \Phi(u) = 0\}, \quad b_\Phi = \max\{u \geq 0 : \Phi(u) < \infty\}.$$

Let (T, Σ, μ) be a Σ -finite, atomless measure space with a complete μ -measure. L° is the family of all Σ -measurable functions defined on T . For a given Orlicz function Φ , the *Orlicz modular* is defined by the formula

$$\rho(f) = \int_T \Phi(|f(t)|) d\mu \quad \forall f \in L^\circ.$$

Let $\text{supp}(f) = \{t \in T : |f(t)| \neq 0\}$. The Orlicz space L_Φ is generated by an Orlicz function Φ by the formula

$$L_\Phi = \{f \in L^\circ : \rho(cf) < \infty, \text{ for some } c > 0 \text{ depending on } f\}.$$

L_Φ is usually equipped with the Luxemburg norm

$$\|f\|_\Phi = \inf\{\varepsilon > 0 : \rho(\frac{f}{\varepsilon}) \leq 1\}$$

or with the equivalent one

$$\|f\|_\Phi^\circ = \sup\left\{\int_T |f(t)g(t)| d\mu : g \in L_\Psi, \rho(g) \leq 1\right\}$$

called the *Orlicz norm*.

Indeed, Orlicz spaces and their kinds of generalizations belong to modular spaces. For the sake of simplicity, we define $L_{\Phi, \rho} = (L_\Phi, \rho)$ and $L_\Phi = (L_\Phi, \|\cdot\|_\Phi)$.

Let X_ρ be a modular space. Then

- (1) We say that (f_n) is ρ -convergent to f if $\rho(f_n - f) \rightarrow 0$ as $n \rightarrow \infty$. We write $f_n \rightarrow f(\rho)$.
- (2) A sequence (f_n) is said to be ρ -Cauchy if $\rho(f_n - f_m) \rightarrow 0$ as $n, m \rightarrow \infty$.
- (3) X_ρ is said to be *complete* if any ρ -Cauchy sequence is ρ -convergent.
- (4) A subset $C \subset X_\rho$ is called ρ -closed if f belongs to C for any sequence $\{f_n\} \subset C$ with $f_n \rightarrow f(\rho)$.
- (5) A subset $C \subset L_{\Phi, \rho}$ is called ρ -bounded if

$$\delta_\rho(C) = \sup\{\rho(f - g) : f, g \in C\} < +\infty,$$

where $\delta_\rho(C)$ is said to be the ρ -diameter of C .

- (6) We say the modular ρ has *Fatou property* if

$$\rho(f) \leq \liminf_{n \rightarrow \infty} \rho(f_n)$$

whenever $f_n \rightarrow f(\rho)$.

Let C be a ρ -bounded subset of X_ρ . Then

(a) The ρ -Chebyshev radius of C with respect to f is defined by

$$r_\rho(f, C) = \sup\{\rho(f - g) : g \in C\}.$$

(b) The ρ -Chebyshev radius of C is defined by

$$R_\rho(C) = \inf\{r_\rho(f, C) : f \in C\}.$$

(c) The ρ -Chebyshev center of C is defined by

$$Z_\rho(C) = \{f \in C : r_\rho(f, C) = R_\rho(C)\}.$$

We say that $f \in C$ is a ρ -diametral point if $r_\rho(f, C) = \delta_\rho(C)$. The set C is said to be ρ -diametral if each $f \in C$ is a ρ -diametral point.

We say that X_ρ has ρ -normal structure if every nonempty ρ -bounded, ρ -closed, convex subset C of X_ρ , not reduced to a single point, is not a ρ -diametral set.

We say that X_ρ has property (R) provided that every decreasing sequence (C_n) of nonempty ρ -bounded, ρ -closed, convex subset of X_ρ has nonempty intersection provided $C_n \neq \emptyset$ for any $n \in \mathbb{N}$.

For more details on Orlicz spaces we refer to [11, 8, 10, 9, 16, 6, 5, 20, 21, 29, 35] and for more details on modular spaces one can consult [23, 24, 25, 28, 30, 31, 32, 33, 34].

Let C be a subset of X_ρ and let $T : C \rightarrow C$ be a mapping. If there exists $k \in [0, 1)$ such that

$$\rho(T(f) - T(g)) \leq k\rho(f - g)$$

for any $f, g \in C$, then the mapping T is said to be ρ -contractive [23]. If the inequality

$$\rho(T(f) - T(g)) \leq \rho(f - g)$$

holds for any $f, g \in C$, then the mapping T is said to be ρ -nonexpansive. $f \in C$ is called a fixed point of T provided that $T(f) = f$. The family of the fixed points of T is said to be the fixed point set and is denoted by $\text{Fix } T$. A subset $D \subset X_\rho$ is called T -invariant if $T(D) \subset D$.

2. Main results. We first show the notions of complex extreme points and complex strongly extreme points of Banach spaces to the modular spaces. For more details on these notions we refer to [3, 4, 2].

DEFINITION 2.1 ([2]). Let X_ρ be a modular space. A point $x \in S(X_\rho)$ is said to be a complex extreme point of $B(X_\rho)$ if for any $y \in X_\rho$ with $y \neq 0$

$$\sup_{|\lambda| \leq 1} \rho(x + \lambda y) > 1.$$

X_ρ is said to be complex strictly convex if every element of $S(X_\rho)$ is a complex extreme point of $B(X_\rho)$.

DEFINITION 2.2 ([2]). Let X_ρ be a modular space. A point $x \in S(X_\rho)$ is said to be a *complex strongly extreme point* of $B(X_\rho)$ if $\Delta_{c,\rho}(x, \varepsilon) > 0$ for every $\varepsilon > 0$, where

$$\Delta_{c,\rho}(x, \varepsilon) = \inf \left\{ 1 - |\lambda| : \lambda \in \mathbb{C}, 0 < |\lambda| \leq 1, \right. \\ \left. \text{and } \exists y \in X_\rho : \rho\left(x \pm \frac{y}{\lambda}\right) \leq \frac{1}{|\lambda|}, \rho\left(x \pm i\frac{y}{\lambda}\right) \leq \frac{1}{|\lambda|}, \rho(y) \geq \varepsilon \right\}.$$

X_ρ is said to be *complex midpoint locally uniformly convex* if every element of $S(X_\rho)$ is a complex strongly extreme point of $B(X_\rho)$.

THEOREM 2.3. *Let X_ρ be a modular space. If $x \in S(X_\rho)$ is a complex strongly extreme point of $B(X_\rho)$, then x is a complex extreme point of $B(X_\rho)$.*

Proof. Suppose that $x \in S(X_\rho)$ is not a complex extreme point of the closed unit ball $B(X_\rho)$. Then there exists $z \in X_\rho \setminus \{0\}$ such that

$$\sup_{|\lambda| \leq 1} \rho(x + \lambda z) \leq 1.$$

Hence, we have

$$\rho(x \pm z) \leq 1, \quad \rho(x \pm iz) \leq 1.$$

Letting $\varepsilon_0 = \rho(z) > 0$, we obtain $\Delta_{c,\rho}(x, \varepsilon_0) = 0$ which is a contradiction. ■

The next result is an immediate corollary of the previous theorem.

COROLLARY 2.4. *Let X_ρ be a modular space, if X_ρ is complex midpoint locally uniformly convex, it is also complex strictly convex.*

In order to prove that every Orlicz modular function space $L_{\Phi,\rho}$ is complex midpoint locally uniformly convex, we have first to recall a useful result ([4, p. 187]).

LEMMA 2.5. *For any $\varepsilon > 0$, there exists $\delta \in (0, \frac{1}{2})$ such that if $u, v \in \mathbb{C}$ and*

$$|v| \geq \frac{\varepsilon}{8} \max_e |u + ev|,$$

then

$$|u| \leq \frac{1 - 2\delta}{4} \Sigma_e |u + ev|,$$

where

$$\max_e |u + ev| = \max\{|u + v|, |u - v|, |u + iv|, |u - iv|\}, \\ \Sigma_e |u + ev| = |u + v| + |u - v| + |u + iv| + |u - iv|.$$

THEOREM 2.6. *Let $L_{\Phi,\rho}$ be an Orlicz modular function space. Then $L_{\Phi,\rho}$ is complex midpoint locally uniformly convex.*

Proof. Suppose that $x_0 \in S(L_{\Phi,\rho})$ is not a complex strongly extreme point of the unit ball $B(L_{\Phi,\rho})$, by Definition 2.2, then there exists $\varepsilon_0 > 0$ such that $\Delta_{c,\rho}(x_0, \varepsilon_0) = 0$. That is, there exist $\lambda_n \in \mathbb{C}$ with $|\lambda_n| \rightarrow 1$ and $y_n \in L_{\Phi,\rho}$ satisfying $\rho(y_n) \geq \varepsilon_0$, such that

$$\rho\left(x_0 \pm \frac{y_n}{\lambda_n}\right) \leq \frac{1}{|\lambda_n|}, \quad \rho\left(x_0 \pm i\frac{y_n}{\lambda_n}\right) \leq \frac{1}{|\lambda_n|}$$

for each $n \in \mathbb{N}$. Setting $z_n = y_n/\lambda_n$, we have

$$\rho(z_n) = \rho\left(\frac{y_n}{\lambda_n}\right) \geq \rho(y_n) \geq \varepsilon_0$$

and

$$\rho(x_0 \pm z_n) \leq \frac{1}{|\lambda_n|}, \quad \rho(x_0 \pm iz_n) \leq \frac{1}{|\lambda_n|}.$$

For the above $\varepsilon_0 > 0$, by Lemma 2.5, there exists $\delta_0 \in (0, \frac{1}{2})$, such that if $u, v \in \mathbb{C}$ and

$$|v| \geq \frac{\varepsilon_0}{8} \max_e |u + ev|,$$

then

$$|u| \leq \frac{1 - 2\delta_0}{4} \Sigma_e |u + ev|.$$

For every $n \in \mathbb{N}$, we define

$$\begin{aligned} A_n &= \left\{ t \in T : |z_n(t)| \geq \frac{\varepsilon_0}{8} \max_e |x_0(t) + ez_n(t)| \right\}, \\ z_n^{(1)} : z_n^{(1)}(t) &= z_n(t) \ (t \notin A_n), \quad z_n^{(1)}(t) = 0 \ (t \in A_n), \\ z_n^{(2)} : z_n^{(2)}(t) &= 0 \ (t \notin A_n), \quad z_n^{(2)}(t) = z_n(t) \ (t \in A_n). \end{aligned}$$

It is easy to see that $z_n = z_n^{(1)} + z_n^{(2)}$ for each $n \in \mathbb{N}$, and

$$\begin{aligned} \rho(z_n^{(1)}) &= \int_{T \setminus A_n} \Phi(|z_n(t)|) d\mu \leq \int_{T \setminus A_n} \Phi\left(\frac{\varepsilon_0}{8} \max_e |x_0(t) + ez_n(t)|\right) d\mu \\ &\leq \frac{\varepsilon_0}{8} \int_{T \setminus A_n} \Phi\left(\max_e |x_0(t) + ez_n(t)|\right) d\mu \\ &\leq \frac{\varepsilon_0}{8} \sum_e \rho(x_0 + ez_n) \leq \frac{\varepsilon_0}{2|\lambda_n|} < \frac{3\varepsilon_0}{4} \end{aligned}$$

for n large enough since $|\lambda_n| \rightarrow 1$ as $n \rightarrow \infty$. Consequently, we deduce that

$$\rho(z_n^{(2)}) > \frac{\varepsilon_0}{4}$$

which shows that $\mu(A_n) > 0$. Furthermore, we have

$$\begin{aligned} 1 &= \rho(x_0) = \int_{A_n} \Phi(|x_0(t)|) d\mu + \int_{T \setminus A_n} \Phi(|x_0(t)|) d\mu \\ &\leq \int_{A_n} \Phi\left(\frac{1 - 2\delta_0}{4} \Sigma_e |x_0(t) + ez_n(t)|\right) d\mu + \int_{T \setminus A_n} \Phi\left(\frac{1}{4} \Sigma_e |x_0(t) + ez_n(t)|\right) d\mu \\ &\leq (1 - 2\delta_0) \int_{A_n} \Phi\left(\frac{1}{4} \Sigma_e |x_0(t) + ez_n(t)|\right) d\mu + \int_{T \setminus A_n} \Phi\left(\frac{1}{4} \Sigma_e |x_0(t) + ez_n(t)|\right) d\mu \\ &= \int_T \Phi\left(\frac{1}{4} \Sigma_e |x_0(t) + ez_n(t)|\right) d\mu - 2\delta_0 \int_{A_n} \Phi\left(\frac{1}{4} \Sigma_e |x_0(t) + ez_n(t)|\right) d\mu \\ &\leq \frac{1}{4} \Sigma_e \int_T \Phi(|x_0(t) + ez_n(t)|) d\mu - 2\delta_0 \int_{A_n} \Phi\left(\frac{1}{4} \Sigma_e |x_0(t) + ez_n(t)|\right) d\mu \\ &\leq \frac{1}{|\lambda_n|} - 2\delta_0 \int_{A_n} \Phi\left(\frac{1}{4} \Sigma_e |x_0(t) + ez_n(t)|\right) d\mu. \end{aligned}$$

Notice that

$$\int_{A_n} \Phi\left(\frac{1}{4}\Sigma_e|x_0(t) + ez_n(t)|\right) d\mu \geq \int_{A_n} \Phi(|z_n(t)|) d\mu = \rho(z_n^{(2)}) > \frac{\varepsilon_0}{4}.$$

Hence,

$$1 = \rho(x_0) \leq \frac{1}{|\lambda_n|} - 2\delta_0 \int_{A_n} \Phi\left(\frac{1}{4}\Sigma_e|x_0(t) + ez_n(t)|\right) d\mu < \frac{1}{|\lambda_n|} - \frac{\delta_0\varepsilon_0}{2}.$$

Since $|\lambda_n| \rightarrow 1$ as $n \rightarrow \infty$, letting $n \rightarrow \infty$ we get a contradiction

$$1 = \rho(x_0) < \frac{1}{|\lambda_n|} - \frac{\delta_0\varepsilon_0}{2} < 1,$$

which completes the proof. ■

Combining Corollary 2.4 and Theorem 2.6 we obtain immediately the following result.

COROLLARY 2.7. *Let $L_{\Phi,\rho}$ be an Orlicz modular function space. Then $L_{\Phi,\rho}$ is complex strictly convex.*

Now we study the problem of existence of fixed points for mean nonexpansive mappings in the modular sense in Orlicz modular function spaces. Before we state the fixed point theorem, we have to introduce the concept of mean nonexpansive mappings in the modular sense.

DEFINITION 2.8. Let C be a subset of X_ρ and let $T : C \rightarrow C$ be a mapping. We say that T is a *mean nonexpansive mapping in the modular sense* provided that

$$\rho(T(f) - T(g)) \leq a\rho(f - g) + b\rho(f - T(g)),$$

where $a, b \geq 0$ and $a + b \leq 1$.

Next, we generalize the results for nonexpansive mappings in the modular sense ([22, Theorem 3.10]) to mean nonexpansive mappings in the modular sense.

THEOREM 2.9. *Let $C \subset L_{\Phi,\rho}$ be a nonempty, ρ -closed, ρ -bounded, convex subset and let $T : C \rightarrow C$ be a mean nonexpansive mapping in the modular sense. Then there exists $D \subset C$, which is nonempty, ρ -closed, convex and T -invariant, such that*

$$\delta_\rho(D) \leq \frac{1}{2}\delta_\rho(C) + \frac{1}{2}R_\rho(C).$$

Proof. If $R_\rho(C) = \delta_\rho(C)$ then we can take $D = C$. Assume therefore that $R_\rho(C) < \delta_\rho(C)$. Let

$$\gamma = \frac{1}{2}\delta_\rho(C) + \frac{1}{2}R_\rho(C).$$

Since $R_\rho(C) < \gamma$, there exists $f \in C$ such that $r_\rho(f, C) \leq \gamma$. Define the family

$$\mathfrak{F} = \{E \subset C : T(E) \subset E, f \in E, E \text{ is } \rho\text{-closed and convex}\}$$

and observe that $\mathfrak{F} \neq \emptyset$ since $C \in \mathfrak{F}$. Let $D = \bigcap_{E \in \mathfrak{F}} E$ and notice that $D \subset C$, $f \in D$, D is also ρ -closed and convex and $T(D) \subset D$. Let us define the ρ -balls for all $\alpha > 0$ by

$$B_\rho(g, \alpha) = \{h \in L_{\Phi,\rho} : \rho(g - h) \leq \alpha\}, \quad g \in L_{\Phi,\rho}.$$

Then we observe that every ρ -ball $B_\rho(g, \alpha)$ is convex and ρ -closed by Fatou's lemma. Let \mathfrak{G} be a family of all ρ -balls which contain $T(D) \cup \{f\}$. The convex hull of $T(D) \cup \{f\}$ is denoted by $\text{conv}(T(D) \cup \{f\})$. It is not difficult to see that

$$\text{conv}(T(D) \cup \{f\}) = \bigcap_{B \in \mathfrak{G}} B \cap D$$

and the set $\text{conv}(T(D) \cup \{f\})$ is ρ -closed, convex and contains f . We will prove that it is also T -invariant. Indeed, let $F = \text{conv}(T(D) \cup \{f\})$ and notice that $F \subset D$. Then

$$T(F) \subseteq T(D) \subseteq F$$

which implies $F = D$. Let

$$D_r = \{h \in D : r_\rho(h, D) \leq r\},$$

then $f \in D_r$ since $r_\rho(f, C) \leq r$. Notice that

$$D_r = \bigcap_{g \in D} B_\rho(g, r) \cap D.$$

Hence, D_r is convex and ρ -closed. Let us prove that D_r is T -invariant. Take $h \in D_r$, then $h \in D$. In view of the definition of D_r , we have $D \subset B_\rho(h, r)$. For any $z \in T(D) \subset D$, there exists $g \in D$ such that $T(g) = z$. Then

$$\begin{aligned} \rho(T(h) - z) &= \rho(T(h) - T(g)) \leq a\rho(h - g) + b\rho(h - T(g)) \\ &\leq ar + b\rho(h - T(g)) \leq (a + b)r \leq r \end{aligned}$$

which implies $T(D) \subset B_\rho(T(h), r)$. On the other hand, f belongs to $B_\rho(T(h), r)$ since $r_\rho(f, C) \leq r$ and $T(h) \in D$. Thus

$$D = F \subset B_\rho(T(h), r),$$

which implies $r_\rho(T(h), D) \leq r$. Then $T(h) \in D_r$, we obtain $T(D_r) \subseteq D_r$. Consequently, $D_r \in \mathfrak{F}$ and by the definition of D , we have $D = D_r$. Hence, $\delta_\rho(D) \leq r$ which shows that D is the desired set. ■

THEOREM 2.10. *Suppose that $L_{\Phi, \rho}$ has property (R) and ρ -normal structure. Let $C \subset L_{\Phi, \rho}$ be a nonempty, ρ -closed, ρ -bounded, convex subset and let $T : C \rightarrow C$ be a mean nonexpansive mapping in the modular sense. Then the mapping T has a fixed point in C .*

Proof. Let \mathfrak{A} be a family of all nonempty, ρ -closed, convex and T -invariant subsets of C . Define $\delta_0 : \mathfrak{A} \rightarrow \mathbb{R}^+$ by the formula

$$\delta_0(A) = \inf\{\delta_\rho(B) : B \in \mathfrak{A}, B \subset A\}.$$

Let $\varepsilon_n > 0$ for each $n \in \mathbb{N}$ and $\varepsilon_n \rightarrow 0$ as $n \rightarrow \infty$. Then we can find a decreasing sequence $\{A_n\}$ satisfying $A_n \in \mathfrak{A}$ and $\delta_\rho(A_{n+1}) \leq \delta_0(A_n) + \varepsilon_n$. Since $L_{\Phi, \rho}$ has property (R), we have $A_0 = \bigcap_{n \in \mathbb{N}} A_n \neq \emptyset$. Clearly, $A_0 \in \mathfrak{A}$. It remains to show that A_0 has only one point. Indeed, by Theorem 2.9, there exists $D \in \mathfrak{A}$ with $D \subset A_0$ such that

$$\delta_\rho(D) \leq \frac{1}{2}(\delta_\rho(A_0) + R_\rho(A_0)). \quad (1)$$

Since $D \subset A_n$ for each $n \in \mathbb{N}$, it follows that $\delta_0(A_n) \leq \delta_\rho(D)$. Hence,

$$\delta_\rho(D) \leq \delta_\rho(A_0) \leq \delta_\rho(A_{n+1}) \leq \delta_0(A_n) + \varepsilon_n \leq \delta_\rho(D) + \varepsilon_n,$$

which implies that

$$\delta_\rho(D) \leq \delta_\rho(A_0) \leq \delta_\rho(D) + \varepsilon_n.$$

Letting $n \rightarrow \infty$, we obtain $\delta_\rho(D) = \delta_\rho(A_0)$. By combining with inequality (1), it follows that

$$\delta_\rho(A_0) \leq R_\rho(A_0).$$

Since always $\delta_\rho(A_0) \geq R_\rho(A_0)$, we obtain $\delta_\rho(A_0) = R_\rho(A_0)$. Since $L_{\Phi, \rho}$ has ρ -normal structure, we deduce that A_0 is reduced to a single point. Since A_0 is T -invariant, this point is a fixed point for T . ■

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