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## NONLINEAR MULTIPLE HYBRID PROCEDURES FOR SOLVING SOME CONSTRAINED NONLINEAR OPTIMIZATION PROBLEMS

Abstract. We introduce a new formulation of multiple hybrid procedures which consist in a combination of $k$ arbitrary approximate solutions. The connection between this method and other vector sequence transformations is studied. This connection is also exploited for solving some constrained nonlinear optimization problems. A convergence acceleration result is established and numerical examples are given.

1. Introduction. It is well known that hybrid procedures can be used for solving a system of linear equations [1,6]. Multiple hybrid procedures were defined by Brezinski and Redivo-Zaglia [6] and their acceleration properties have been studied. The nonlinear hybrid procedures studied in [5] are also used for accelerating fixed point iterations. In this paper, we will consider nonlinear multiple hybrid procedures for solving some constrained nonlinear optimization problems. In order to present conveniently our results, let us introduce the setting used throughout this paper. For the vector $x=\left(x_{1}, \ldots, x_{p}\right) \in \mathbb{R}^{p}$, we use the Euclidean norm

$$
\|x\|=\left(\sum_{1 \leq i \leq p} x_{i}^{2}\right)^{1 / 2}
$$

We also denote by $(\cdot, \cdot)$ the corresponding inner product. We use the matrix norm

$$
\|A\|=\sup _{\|x\| \neq 0}\|A x\| /\|x\|
$$

for any $q \times p$ matrix $A$. The paper is organized as follows. Section 2 is devoted to a new formulation of multiple hybrid procedures and the connection

[^0]between this transformation and other vector sequence transformations. In Section 3, we study the convergence acceleration method for solving some constrained nonlinear optimization problems. Some numerical examples are given in Section 4.
2. Nonlinear multiple hybrid procedures. Consider the system of linear equations
\[

$$
\begin{equation*}
A x=b \tag{2.1}
\end{equation*}
$$

\]

Hybrid procedures for solving (2.1) were defined by Abkowicz and Brezinski [1] and by Brezinski and Redivo-Zaglia [6]. Let $x_{1}, \ldots, x_{k}$ be $k$ approximate solutions of (2.1). Multiple hybrid procedures construct a new approximate solution by setting

$$
y_{k}=\sum_{i=1}^{k} \alpha_{i} x_{i} \quad \text { with } \quad \sum_{i=1}^{k} \alpha_{i}=1
$$

where $\alpha_{1}, \ldots, \alpha_{k}$ are chosen to minimize $\left\|\varrho_{k}\right\|$, with

$$
\varrho_{k}=\sum_{i=1}^{k} \alpha_{i} r_{i} \quad \text { and } \quad r_{i}=b-A x_{i} .
$$

Consider the nonlinear system

$$
\begin{equation*}
F(x)=0 \tag{2.2}
\end{equation*}
$$

where $F: \mathbb{R}^{p} \rightarrow \mathbb{R}^{p}$. We suppose that there exists a solution $x^{*}$ of (2.2). Let $x_{n}^{(1)}, \ldots, x_{n}^{(k)}$ be $k$ sequences of vectors of $\mathbb{R}^{p}$ converging to $x^{*}$ with $k \leq p$. We construct a new sequence by setting

$$
\begin{equation*}
t_{n}^{(k)}=\sum_{i=1}^{k} \alpha_{n}^{(i)} x_{n}^{(i)} \quad \text { with } \quad \sum_{i=1}^{k} \alpha_{n}^{(i)}=1 \tag{2.3}
\end{equation*}
$$

We make the following definition:
Definition 2.1. A map $r: \mathbb{R}^{p} \rightarrow \mathbb{R}^{p}$ is said to be a residual function if

$$
\forall x \in \mathbb{R}^{p} \exists \lambda \in \mathbb{R}^{*} \quad r(x)=\lambda F(x)
$$

REmARK 2.1. If we assume that (2.2) has a unique solution $x^{*}$, then

$$
r(x)=0 \Leftrightarrow x=x^{*}
$$

and we get the definition given by Brezinski and Chehab [5].
Let $r^{(1)}, \ldots, r^{(k)}$ be $k$ residual functions, and set

$$
r_{n}^{(i)}=r^{(i)}\left(x_{n}^{(i)}\right), \quad i=1, \ldots, k
$$

Setting

$$
\begin{equation*}
\beta_{n}^{(j)}=1-\sum_{i=1}^{j-1} \alpha_{n}^{(i)}, \quad j=2, \ldots, k \tag{2.4}
\end{equation*}
$$

we obtain from (2.3)

$$
\begin{equation*}
t_{n}^{(k)}=x_{n}^{(1)}+\sum_{j=2}^{k} \beta_{n}^{(j)}\left(x_{n}^{(j)}-x_{n}^{(j-1)}\right) \tag{2.5}
\end{equation*}
$$

We define

$$
\begin{equation*}
\varrho_{n}^{(k)}=r_{n}^{(1)}+\sum_{j=2}^{k} \beta_{n}^{(j)}\left(r_{n}^{(j)}-r_{n}^{(j-1)}\right) \tag{2.6}
\end{equation*}
$$

The coefficients $\beta_{n}^{(2)}, \ldots, \beta_{n}^{(k)}$ are chosen to minimize $\left\|\varrho_{n}^{(k)}\right\|$. We introduce some notations.

We define the following matrices by giving their columns:

$$
\Delta_{n, k}^{1}=\left[x_{n}^{(2)}-x_{n}^{(1)}, \ldots, x_{n}^{(k)}-x_{n}^{(k-1)}\right], \quad \Delta_{n, k}^{2}=\left[\Delta^{2} x_{n}^{(1)}, \ldots, \Delta^{2} x_{n}^{(k-1)}\right]
$$

where $\Delta^{2} x_{n}^{(i)}=\Delta\left(\Delta x_{n}^{(i)}\right)$ and $\Delta x_{n}^{(i)}=x_{n}^{(i+1)}-x_{n}^{(i)}$; morever,

$$
R_{n, k}=\left[r_{n}^{(1)}, \ldots, r_{n}^{(k-1)}\right], \quad \Delta R_{n, k}=\left[r_{n}^{(2)}-r_{n}^{(1)}, \ldots, r_{n}^{(k)}-r_{n}^{(k-1)}\right]
$$

$$
\left(\Delta R_{n, k}\right)^{\dagger}=\left(\left(\Delta R_{n, k}\right)^{T} \Delta R_{n, k}\right)^{-1}\left(\Delta R_{n, k}\right)^{T}, \quad \text { the pseudo-inverse of } \Delta R_{n, k}
$$

We also set

$$
\beta_{n, k}=\left(\beta_{n}^{(2)}, \ldots, \beta_{n}^{(k)}\right)^{T} \in \mathbb{R}^{k-1}
$$

The following theorem shows that $\left(t_{n}^{(k)}\right)_{n}$ defined by (2.3) is well defined, and gives a new formula for it.

THEOREM 2.1. If $\operatorname{rank}\left(\Delta R_{n, k}\right)=k-1$, then there exists a unique vector $\beta_{n, k}$ which solves

$$
\begin{equation*}
\left(\Delta R_{n, k}\right)^{T} \Delta R_{n, k} \beta_{n, k}=-\left(\Delta R_{n, k}\right)^{T} r_{n}^{(1)} \tag{2.7}
\end{equation*}
$$

and

$$
\begin{equation*}
t_{n}^{(k)}=x_{n}^{(1)}-\Delta_{n, k}^{1}\left(\Delta R_{n, k}\right)^{\dagger} r_{n}^{(1)} \tag{2.8}
\end{equation*}
$$

Proof. Using the previous notations and (2.6), we have

$$
\varrho_{n}^{(k)}=r_{n}^{(1)}+\Delta R_{n, k} \beta_{n, k}
$$

Then

$$
\begin{aligned}
\left\|\varrho_{n}^{(k)}\right\|^{2} & =\left\|r_{n}^{(1)}\right\|^{2}+2\left(r_{n}^{(1)}, \Delta R_{n, k} \beta_{n, k}\right)+\left\|\Delta R_{n, k} \beta_{n, k}\right\|^{2} \\
& =\left\|r_{n}^{(1)}\right\|^{2}+2\left(\left(\Delta R_{n, k}\right)^{T} r_{n}^{(1)}, \beta_{n, k}\right)+\left(\left(\Delta R_{n, k}\right)^{T} \Delta R_{n, k} \beta_{n, k}, \beta_{n, k}\right)
\end{aligned}
$$

Therefore, the vector $\beta_{n, k}$ minimizing $\left\|\varrho_{n}^{(k)}\right\|^{2}$ is such that

$$
\left(\Delta R_{n, k}\right)^{T} \Delta R_{n, k} \beta_{n, k}=-\left(\Delta R_{n, k}\right)^{T} r_{n}^{(1)}
$$

By the previous notations and (2.5), we have

$$
t_{n}^{(k)}=x_{n}^{(1)}+\Delta_{n, k}^{1} \beta_{n, k}
$$

On the other hand, it is well known that the hypothesis $\operatorname{rank}\left(\Delta R_{n, k}\right)=k-1$ implies that $\left(\Delta R_{n, k}\right)^{T} \Delta R_{n, k}$ is nonsingular. Then we finally have

$$
\beta_{n, k}=-\left(\Delta R_{n, k}\right)^{\dagger} r_{n}^{(1)} \quad \text { and } \quad t_{n}^{(k)}=x_{n}^{(1)}-\Delta_{n, k}^{1}\left(\Delta R_{n, k}\right)^{\dagger} r_{n}^{(1)}
$$

Remark 2.2. (1) Consider the optimization problem

$$
\begin{equation*}
\text { find } x^{*} \in \mathbb{R}^{p} \quad \text { such that } \quad f\left(x^{*}\right)=\min _{x \in \mathbb{R}^{p}} f(x) \tag{2.9}
\end{equation*}
$$

where $f$ is a convex function from $\mathbb{R}^{p}$ to $\mathbb{R}$. Problem (2.9) is equivalent to (2.2) with $F=\nabla f$, the gradient of $f$.

If we set $x_{n+i}=x_{n+i-1}-\lambda_{n, i} \nabla f\left(x_{n+i-1}\right), x_{n}^{(i)}=x_{n+i-1}$, where $x_{0} \in \mathbb{R}^{p}, n=0,1, \ldots, i=1, \ldots, k-1$ and $\lambda_{n, i}$ is the solution of $\min _{\lambda \in \mathbb{R}^{*}} f\left(x_{n+i-1}-\lambda \nabla f\left(x_{n+i-1}\right)\right)$, then:

- For $k=3$ and $r_{n}^{(i)}=-\lambda_{n, i} \nabla f\left(x_{n+i-1}\right), i=1,2$, we obtain (see [11]) $t_{n}^{(k)}=\varepsilon_{2}^{(n)}$, the vector $\varepsilon$-algorithm [3, 4].
- For $k=p$ and $r_{n}^{(i)}=-\nabla f\left(x_{n+i-1}\right), i=1, \ldots, p$, we get the modified Henrici transformation used in [12] for solving (2.9):

$$
t_{n}^{(p)}=x_{n}-\Delta X_{n}\left(\Delta F^{\prime}\left(x_{n}\right)\right)^{-1} \nabla f\left(x_{n}\right)
$$

where $\Delta F^{\prime}\left(x_{n}\right)$ is the $p \times p$ matrix whose columns are

$$
\nabla f\left(x_{n+1}\right)-\nabla f\left(x_{n}\right), \ldots, \nabla f\left(x_{n+p}\right)-\nabla f\left(x_{n+p-1}\right)
$$

(2) Consider the vector sequence defined by $x_{n+i}=x_{n+i-1}-\lambda F\left(x_{n+i-1}\right)$, with $x_{0} \in \mathbb{R}^{p}, \lambda>0, i=1, \ldots, p$ and $n=0,1, \ldots$ If we set

$$
x_{n}^{(i)}=x_{n+i-1}, \quad r_{n}^{(i)}=-\lambda F\left(x_{n+i-1}\right)
$$

then we have $r_{n}^{(i)}=\Delta x_{n}^{(i)}, r_{n}^{(i+1)}-r_{n}^{(i)}=\Delta^{2} x_{n}^{(i)}$ and $\Delta R_{n, k}=\Delta_{n, k}^{2}$. We obtain the $R R E$ (reduced rank extrapolation; see [13])

$$
\begin{equation*}
t_{n}^{(k)}=x_{n}-\Delta_{n, k}^{1}\left(\Delta_{n, k}^{2}\right)^{\dagger} \Delta x_{n} \tag{2.10}
\end{equation*}
$$

3. Nonlinearly constrained optimization problems. Let us now apply the vector sequence transformation (2.8) to the solution of the constrained optimization problem

$$
\left\{\begin{array}{l}
\min f(x)  \tag{3.1}\\
\text { subject to } g(x) \leq 0
\end{array}\right.
$$

where the functions $f: \mathbb{R}^{p} \rightarrow \mathbb{R}$ and $g: \mathbb{R}^{p} \rightarrow \mathbb{R}^{q}$ (with $g(x)=\left(g_{i}(x)\right)_{1 \leq i \leq q}$ and $q \leq p$ ) are convex and twice continuously differentiable. The Lagrangian is defined by

$$
L(x, \lambda)=f(x)+\sum_{i=1}^{q} \lambda^{i} g_{i}(x)
$$

where $x \in \mathbb{R}^{p}$ and $\lambda=\left(\lambda^{1}, \ldots, \lambda^{q}\right) \in \mathbb{R}^{q}$.

It is well known that if a vector $x^{*}$ is a solution of (3.1), then there exists a multiplier $\lambda^{*} \in \mathbb{R}_{+}^{q}$ such that

$$
\begin{equation*}
L\left(x^{*}, \lambda\right) \leq L\left(x^{*}, \lambda^{*}\right) \leq L\left(x, \lambda^{*}\right) \quad \forall x \in \mathbb{R}^{p} \forall \lambda \in \mathbb{R}_{+}^{q} \tag{3.2}
\end{equation*}
$$

We denote by $J_{g}$ the Jacobian matrix of $g$, and we set $T\left(x_{n}\right)=t_{n}^{(p)}$.
Consider problem (3.2) and let $x_{0} \in \mathbb{R}^{p}$ and $\lambda_{0} \in \mathbb{R}_{+}^{q}$ be given vectors. Assuming that $\left(x_{n}, \lambda_{n}\right)=\left(x_{n}^{1}, \ldots, x_{n}^{p}, \lambda_{n}^{1}, \ldots, \lambda_{n}^{q}\right) \in \mathbb{R}^{p} \times \mathbb{R}_{+}^{q}$ is given, we consider the problem

$$
L\left(x^{*}, \lambda^{*}\right) \leq L\left(x, \lambda^{*}\right) \quad \forall x \in \mathbb{R}^{p}
$$

One can obtain $x_{n+1}$ such that

$$
L\left(x_{n+1}, \lambda_{n}\right) \leq L\left(x_{n}, \lambda_{n}\right)
$$

Then we apply the gradient method [8] to $\min _{x \in \mathbb{R}^{p}} L\left(x, \lambda_{n}\right)$, where $x_{n}$ is considered as an initial point, and we define the vector sequence $\left(y_{n}^{(m)}\right)_{m}$ by

$$
\begin{aligned}
& y_{n}^{(1)}=x_{n} \\
& \text { for } m=1, \ldots, \text { do } \\
& \qquad r_{n}^{(m)}=\alpha\left(\nabla f\left(y_{n}^{(m)}\right)+\left(J_{g}\left(y_{n}^{(m)}\right)\right)^{T} \lambda_{n}\right) \\
& \qquad y_{n}^{(m+1)}=y_{n}^{(m)}-r_{n}^{(m)} \\
& \text { end do }
\end{aligned}
$$

where $\alpha>0$. Then the sequence $\left(T\left(y_{n}^{(m)}\right)\right)_{m}$ defined by $(2.8)$ for $\left(y_{n}^{(m)}\right)_{m}$ converges to a limit denoted by $x_{n+1}$.

In order to determine $\lambda_{n+1}$, we consider the problem

$$
L\left(x^{*}, \lambda\right) \leq L\left(x^{*}, \lambda^{*}\right) \quad \forall \lambda \in \mathbb{R}_{+}^{q}
$$

One can obtain $\lambda_{n+1}$ such that

$$
L\left(x_{n+1}, \lambda_{n}\right) \leq L\left(x_{n+1}, \lambda_{n+1}\right)
$$

Then we can take $\lambda_{n+1}$ as the first iteration of the gradient method applied to $\max _{\lambda \in \mathbb{R}_{+}^{q}} L\left(x_{n+1}, \lambda\right)$, where $\lambda_{n}$ is considered as an initial point. Then we have

$$
\lambda_{n+1}=P\left(\lambda_{n}+\varrho g\left(x_{n+1}\right)\right)
$$

where $\varrho>0$ and $P$ is the projection onto $\mathbb{R}_{+}^{q}$ defined by

$$
P(x)=\left(\max \left(x^{i}, 0\right)\right)_{1 \leq i \leq q} \quad \forall x \in \mathbb{R}^{q}
$$

The corresponding algorithm is as follows:

## Algorithm 1.

(a) Choose $x_{0} \in \mathbb{R}^{p}, T\left(y_{0}^{(-1)}\right)=x_{0}, \lambda_{0} \in \mathbb{R}_{+}^{q}, \alpha>0, \varepsilon>0$ and $\varrho>0$
(b) for $n=0,1, \ldots$, do
(b1) Set $y_{n}^{(1)}=x_{n}$
for $i=1, \ldots, p$, do

$$
\begin{aligned}
& r_{n}^{(i)}=\alpha\left(\nabla f\left(y_{n}^{(i)}\right)+\left(J_{g}\left(y_{n}^{(i)}\right)\right)^{T} \lambda_{n}\right) \\
& y_{n}^{(i+1)}=y_{n}^{(i)}-r_{n}^{(i)}
\end{aligned}
$$

end do
(b2) for $i=1, \ldots$, do
$r_{n}^{(p+i)}=\alpha\left(\nabla f\left(y_{n}^{(p+i)}\right)+\left(J_{g}\left(y_{n}^{(p+i)}\right)\right)^{T} \lambda_{n}\right)$
$y_{n}^{(p+i+1)}=y_{n}^{(p+i)}-r_{n}^{(p+i)}$
solve the linear system $\left(\Delta R_{n, p}\right)^{T} \Delta R_{n, p} \beta_{n, p}=\left(\Delta R_{n, k}\right)^{T} r_{n}^{(i)}$
compute $T\left(y_{n}^{(i)}\right)=y_{n}^{(i)}-\Delta_{n, p}^{1} \beta_{n, p}$
if $\left\|T\left(y_{n}^{(i)}\right)-T\left(y_{n}^{(i-1)}\right)\right\| \leq \varepsilon$ then
set $x_{n+1}=T\left(y_{n}^{(i)}\right)$
stop
end if
end do
(b3) Computation of $\lambda_{n+1}$
for $i=1, \ldots, q$, do
$\lambda_{n+1}^{i}=\max \left(\lambda_{n}^{i}+\varrho g_{i}\left(x_{n+1}\right), 0\right)$.
end do
if $\left\|x_{n+1}-x_{n}\right\| \leq \varepsilon$ then
set $x^{*}=x_{n+1}$
stop
end if
end do.
As mentioned above, the following theorem shows that $\left(T\left(y_{n}^{(m)}\right)\right)_{m}$ converges to $x_{n+1}$ faster than $\left(y_{n}^{(m)}\right)_{m}$. Furthermore, we shall see that the vector sequence $\left(x_{n}\right)_{n}$ obtained by this procedure converges to the solution of (3.1).

We suppose that $g(x)=C x-d$, and $\left\{x \in \mathbb{R}^{p}: g(x)<0\right\} \neq \emptyset$, where $C \in M_{q, p}(\mathbb{R})$ and $d \in \mathbb{R}^{q}$. This case occurs frequently in practice.

Let us now study the convergence and acceleration of the sequence transformation $\left(T\left(y_{n}^{(m)}\right)\right)_{m}$. We denote by $\nabla^{2} f$ the Hessian of $f$. The following theorem shows the acceleration of convergence obtained by $\left(T\left(y_{n}^{(m)}\right)\right)_{m}$.

Theorem 3.1. Let $f: \mathbb{R}^{p} \rightarrow \mathbb{R}$ be of class $C^{2}$ and convex. Suppose that there exist constants $m, \varrho, M, \varepsilon>0$ such that

$$
\begin{gather*}
m\|x-y\|^{2} \leq\left(\nabla f(x)-\nabla f(y)-\frac{\varrho}{2} C^{T} C(x-y), x-y\right) \quad \forall x, y \in \mathbb{R}^{p}  \tag{3.3}\\
\forall n \exists N \exists \gamma_{n}>0 \forall m \geq N \quad\left|\operatorname{det}\left(\frac{r_{n}^{m}}{\left\|r_{n}^{m}\right\|}, \ldots, \frac{r_{n}^{m+p-1}}{\left\|r_{n}^{m+p-1}\right\|}\right)\right| \geq \gamma_{n} \\
\left\|\nabla^{2} f(x)-\nabla^{2} f(y)\right\| \leq M\|x-y\| \quad \forall(x, y) \in \mathbb{R}^{p} \times \mathbb{R}^{p}
\end{gather*}
$$

Then:

1) The sequence $\left(T\left(y_{n}^{(m)}\right)\right)_{m}$ is defined for $m \geq N$ and $n \geq 0$.
2) For all $n \geq 0$ there exists a unique $x_{n+1} \in \mathbb{R}^{p}$ such that

$$
\lim _{m \rightarrow \infty} \frac{\left\|T\left(y_{n}^{(m)}\right)-x_{n+1}\right\|}{\left\|y_{n}^{(m)}-x_{n+1}\right\|}=0
$$

3) The sequence $\left(x_{n}\right)_{n \in \mathbb{N}}$ converges to the solution $x^{*}$ of problem (3.1).

Proof. 1) Assume that the vector $\lambda_{n}$ is given and consider the function $\Phi_{n}: \mathbb{R}^{p} \rightarrow \mathbb{R}$ defined by

$$
\Phi_{n}(x)=f(x)+\left(\lambda_{n}, g(x)\right) \quad \forall x \in \mathbb{R}^{p} .
$$

We have

$$
\begin{align*}
\nabla \Phi_{n}(x) & =\nabla f(x)+C^{T} \lambda_{n}  \tag{3.6}\\
\nabla^{2} \Phi_{n}(x) & =\nabla^{2} f(x) \tag{3.7}
\end{align*}
$$

By the hypothesis (3.3), we have
$m\|x-y\|^{2} \leq(\nabla f(x)-\nabla f(y), x-y)-\frac{\varrho}{2}\|C(x-y)\|^{2} \quad \forall(x, y) \in \mathbb{R}^{p} \times \mathbb{R}^{p}$, and then, by (3.6), we deduce

$$
m\|x-y\|^{2} \leq\left(\nabla \Phi_{n}(x)-\nabla \Phi_{n}(y), x-y\right) \quad \forall(x, y) \in \mathbb{R}^{p} \times \mathbb{R}^{p}
$$

This relation implies (see [7]) the sufficient condition for the existence and uniqueness of the solution of the problem $\min _{x \in \mathbb{R}^{p}} \Phi_{n}(x)$, denoted by $x_{n+1}$, and for all $x, y \in \mathbb{R}^{p}$, we have

$$
m\|y\|^{2} \leq\left(\nabla^{2} \Phi_{n}(x) y, y\right) \quad \forall(x, y) \in \mathbb{R}^{p} \times \mathbb{R}^{p}
$$

Therefore, using (3.4), (3.5) and (3.7), we deduce that $\nabla^{2} \Phi_{n}\left(x_{n+1}\right)$ is regular,

$$
\left\|\nabla^{2} \Phi_{n}(x)-\nabla^{2} \Phi_{n}(y)\right\| \leq M\|x-y\| \quad \forall(x, y) \in \mathbb{R}^{p} \times \mathbb{R}^{p}
$$

and

$$
\forall n \geq 0 \exists N>0 \exists \gamma_{n} \forall m \geq N
$$

$$
\left|\operatorname{det}\left(\frac{\nabla \Phi_{n}\left(y_{n}^{(m)}\right)}{\left\|\nabla \Phi_{n}\left(y_{n}^{(m)}\right)\right\|}, \ldots, \frac{\nabla \Phi_{n}\left(y_{n}^{(m+p-1)}\right)}{\left\|\nabla \Phi_{n}\left(y_{n}^{(m+p-1)}\right)\right\|}\right)\right| \geq \gamma_{n}
$$

Then, for all $n \geq 0$, the sequence $T\left(y_{n}^{(m)}\right)$ is defined for $m \geq N$ and (see [13])

$$
\lim _{m \rightarrow \infty} \frac{\left\|T\left(y_{n}^{(m)}\right)-x_{n+1}\right\|}{\left\|y_{n}^{(m)}-x_{n+1}\right\|}=0
$$

Now we will prove the convergence of the sequence $\left(x_{n}\right)_{n}$ to the solution of problem (3.1).

The sufficient condition for the existence of the solution of (3.1) is given by (3.3) and the hypothesis $\left\{x \in \mathbb{R}^{p}: g(x)<0\right\} \neq \emptyset$ (see [7]). It is well known that if $x^{*}$ is a solution to (3.1) with corresponding multipliers $\lambda^{*} \in$ $\mathbb{R}_{+}^{p}$, then $x^{*}$ also satisfies

$$
\begin{equation*}
L\left(x^{*}, \lambda\right) \leq L\left(x^{*}, \lambda^{*}\right) \leq L\left(x, \lambda^{*}\right) \quad \forall(x, \lambda) \in \mathbb{R}^{p} \times \mathbb{R}_{+}^{q} \tag{3.8}
\end{equation*}
$$

Using (3.3), we have
$m\left\|x_{n+1}-x^{*}\right\|^{2} \leq\left(\nabla f\left(x_{n+1}\right)-\nabla f\left(x^{*}\right)-\frac{\varrho}{2} C^{T} C\left(x_{n+1}-x^{*}\right), x_{n+1}-x^{*}\right)$.
By (3.8), we have $L\left(x^{*}, \lambda^{*}\right)=\min _{x \in \mathbb{R}^{p}} L\left(x, \lambda^{*}\right)$, thus

$$
\nabla f\left(x^{*}\right)=-C^{T} \lambda^{*}
$$

On the other hand, $\Phi_{n}\left(x_{n+1}\right)=\min _{x \in \mathbb{R}^{p}} \Phi_{n}(x)$ implies

$$
\nabla f\left(x_{n+1}\right)=-C^{T} \lambda_{n}
$$

Thus, we deduce

$$
\begin{aligned}
& m\left\|x_{n+1}-x^{*}\right\|^{2} \leq\left(-C^{T}\left(\lambda_{n}-\lambda^{*}\right)-\frac{\varrho}{2} C^{T} C\left(x_{n+1}-x^{*}\right), x_{n+1}-x^{*}\right) \\
& \quad \leq-\frac{1}{2 \varrho}\left(2 \varrho C^{T}\left(\lambda_{n}-\lambda^{*}\right)+\varrho^{2} C^{T} C\left(x_{n+1}-x^{*}\right), x_{n+1}-x^{*}\right) \\
& \quad \leq-\frac{1}{2 \varrho}\left(\varrho^{2}\left(C^{T} C\left(x_{n+1}-x^{*}\right), x_{n+1}-x^{*}\right)+2 \varrho\left(C^{T}\left(\lambda_{n}-\lambda^{*}\right), x_{n+1}-x^{*}\right)\right)
\end{aligned}
$$

Therefore

$$
\begin{aligned}
& m\left\|x_{n+1}-x^{*}\right\|^{2} \\
& \quad \leq-\frac{1}{2 \varrho}\left(\left\|\lambda_{n}-\lambda^{*}+\varrho C\left(x_{n+1}-x^{*}\right)\right\|^{2}-\left\|\lambda_{n}-\lambda^{*}\right\|^{2}\right) \\
& \quad \leq-\frac{1}{2 \varrho}\left(\left\|\lambda_{n}+\varrho\left(C x_{n+1}-d\right)-\lambda^{*}-\varrho\left(C x^{*}-d\right)\right\|^{2}-\left\|\lambda_{n}-\lambda^{*}\right\|^{2}\right)
\end{aligned}
$$

Using (3.8), we have $L\left(x^{*}, \lambda^{*}\right)=\max _{\lambda \in \mathbb{R}_{+}^{q}} L\left(x^{*}, \lambda\right)$, thus

$$
\lambda^{*}=P\left(\lambda^{*}+\varrho\left(C x_{n+1}-d\right)\right)
$$

and since $\lambda_{n+1}=P\left(\lambda_{n}+\varrho\left(C x_{n+1}-d\right)\right.$ ), we finally obtain

$$
\begin{equation*}
m\left\|x_{n+1}-x^{*}\right\|^{2} \leq-\frac{1}{2 \varrho}\left(\left\|\lambda_{n+1}-\lambda^{*}\right\|^{2}-\left\|\lambda_{n}-\lambda^{*}\right\|^{2}\right) \tag{3.9}
\end{equation*}
$$

which proves that the sequence $\left(\left\|\lambda_{n}-\lambda^{*}\right\|\right)_{n}$ is decreasing, hence convergent, which gives $\lim _{k \rightarrow \infty} x_{n+1}=x^{*}$.

Remarks 3.1. (1) The assumption (3.4) is the uniform invertibility hypothesis [13]. In [10, Prop. 4], a characterization of this hypothesis is given using the matrix $\nabla^{2} f\left(x_{n+1}\right)$.
(2) It suffices to take $\alpha \in] 0,1 / M\left[\right.$ in order to have $I-\alpha \nabla^{2} f\left(x_{n+1}\right)$ regular.

Now we propose another version of Algorithm 1 where the vector sequence $\left(y_{n}^{(m)}\right)_{m}$ is computed by the gradient method with an optimal step.

Algorithm 2. We replace (b1) and (b2) by ( $\mathrm{b}^{\prime} 1$ ) and ( $\mathrm{b}^{\prime} 2$ ), where ( $\mathrm{b}^{\prime} 1$ ) and $\left(\mathrm{b}^{\prime} 2\right)$ are defined by:
$\left(\mathrm{b}^{\prime} 1\right)$ Set $y_{n}^{(1)}=x_{n}$
for $i=1, \ldots, p$, do
compute $s_{n}^{(i)}=\left(\nabla f\left(y_{n}^{(i)}\right)+\left(J_{g}\left(y_{n}^{(i)}\right)\right)^{T} \lambda_{n}\right)$
compute $\alpha_{n}^{(i)}$ by $\min _{\alpha \in \mathbb{R}^{+}} L\left(y_{n}^{i}+\alpha s_{n}^{i}, \lambda_{n}\right)$
set $r_{n}^{i}=\alpha_{n}^{(i)} s_{n}^{(i)}, y_{n}^{(i+1)}=y_{n}^{(i)}-r_{n}^{(i)}$
end do
$\left(\mathrm{b}^{\prime} 2\right)$ for $i=1, \ldots$, do
compute $s_{n}^{(p+i)}=\left(\nabla f\left(y_{n}^{(p+i)}\right)+\left(J_{g}\left(y_{n}^{(p+i)}\right)\right)^{T} \lambda_{n}\right)$
compute $\alpha_{n}^{(p+i)}$ by $\min _{\alpha \in \mathbb{R}^{+}} L\left(y_{n}^{(p+i)}+\alpha s_{n}^{(p+i)}, \lambda_{n}\right)$
set $r_{n}^{(p+i)}=\alpha_{n}^{(p+i)} s_{n}^{(p+i)}, y_{n}^{(p+i+1)}=y_{n}^{(p+i)}-r_{n}^{(p+i)}$
solve the linear system $\left(\Delta R_{n, p}\right)^{T} \Delta R_{n, p} \beta_{n, p}=\left(\Delta R_{n, k}\right)^{T} r_{n}^{(i)}$
compute $t_{n}^{(p)}=T\left(y_{n}^{(i)}\right)=y_{n-}^{(i)} \Delta_{n, p}^{1} \beta_{n, p}$
if $\left\|T\left(y_{n}^{(i)}\right)-T\left(y_{n-1}^{(i)}\right)\right\| \leq \varepsilon$ then
set $x_{n+1}=T\left(y_{n}^{(i)}\right)$
stop
end if
end do.
The following theorem shows that $T\left(y_{n}^{(m)}\right)_{m}$ given by Algorithm 2 converges to $x_{n+1}$ faster than $\left(y_{n}^{(m)}\right)_{m}$. We denote by $G\left(u_{1}, \ldots, u_{p}\right)=$ $\operatorname{det}\left(\left(u_{i}, u_{j}\right)\right)_{1 \leq i, j \leq p}$ the Gram determinant corresponding to the $p$-tuple $\left(u_{1}, \ldots, u_{p}\right)$. We obtain the following result.

Theorem 3.2. Let $f: \mathbb{R}^{p} \rightarrow \mathbb{R}$ be of class $C^{2}$ and suppose that there exist constants $m, \varrho, \varepsilon>0$ such that

$$
\begin{align*}
& m\|x-y\|^{2} \leq\left(\nabla f(x)-\nabla f(y)-\frac{\varrho}{2} C^{T} C(x-y), x-y\right), \forall x, y \in \mathbb{R}^{p}  \tag{3.10}\\
& \forall n \exists N \exists \gamma_{n}>0 \forall m \geq N \quad G\left(\frac{r_{n}^{(m)}}{\left\|r_{n}^{(m)}\right\|}, \ldots, \frac{r_{n}^{(m+p-1)}}{\left\|r_{n}^{(m+p-1)}\right\|}\right) \geq \gamma_{n} \tag{3.11}
\end{align*}
$$

Then:

1) The sequence $\left(T\left(y_{n}^{(m)}\right)\right)_{m}$ is defined for $m \geq N$ and $n \geq 0$.
2) For all $n \geq 0$ there exists a unique $x_{n+1} \in \mathbb{R}^{p}$ such that

$$
\lim _{m \rightarrow \infty} \frac{\left\|T\left(y_{n}^{(m)}\right)-x_{n+1}\right\|}{\left\|y_{n}^{(m)}-x_{n+1}\right\|}=0
$$

3) The sequence $\left(x_{n}\right)_{n \in \mathbb{R}}$ converges to the solution $x^{*}$ of problem (3.1).

Proof. As in Theorem 3.1, the probem $\min _{x \in \mathbb{R}^{p}} \Phi_{n}(x)$ has a unique solution denoted by $x_{n+1}$. Using (3.10), (3.11), (3.6), and (3.7), we have

$$
\begin{gathered}
m\|y\|^{2} \leq\left(\nabla^{2} \Phi_{n}(x) y, y\right) \quad \forall(x, y) \in \mathbb{R}^{p} \times \mathbb{R}^{p} \\
m\|x-y\|^{2} \leq\left(\nabla \Phi_{n}(x)-\nabla \Phi_{n}(y), x-y\right) \quad \forall(x, y) \in \mathbb{R}^{p} \times \mathbb{R}^{p}
\end{gathered}
$$

$$
\forall n \geq 0 \exists N>0 \exists \gamma_{n}>0 \forall m \geq N G\left(\frac{\nabla \Phi_{n}\left(y_{n}^{m}\right)}{\left\|\nabla \Phi_{n}\left(y_{n}^{m}\right)\right\|}, \ldots, \frac{\nabla \Phi_{n}\left(y_{n}^{m+p-1}\right)}{\left\|\nabla \Phi_{k}\left(y_{n}^{m+p-1}\right)\right\|}\right) \geq \gamma_{n}
$$

Then for all $n \geq 0$, the sequence $T\left(y_{n}^{m}\right)$ is defined for $m \geq N$ and we have (see [12])

$$
\lim _{m \rightarrow \infty} \frac{\left\|T\left(y_{n}^{m}\right)-x_{n+1}\right\|}{\left\|y_{n}^{m}-x_{n+1}\right\|}=0
$$

The end of the proof is the same as in Theorem 3.1.
4. Numerical experiments. In this section, we report on some numerical experiments. We compare the nonlinear multiple hybrid procedures NLM given by Algorithms 1 and 2 with the gradient method GM and the gradient method with optimal step GMO [2, 7]. This comparison will be summarized in tables which give the number of iterations, iter., and the associated residual norms for each method. The stopping criterion is given by res. $=\left\|x_{k}-x^{*}\right\|$, where $x^{*}$ is the solution of problem (3.1). To solve the linear system in Algorithms 1 and 2, we use Gaussian elimination.

Example 1. The first example has been used in [15]. We consider the following problem:

$$
\left\{\begin{array}{l}
\text { Minimize } \frac{1}{2} x_{1}^{2}+\frac{1}{2} x_{2}^{2}-2 x_{1} x_{2}-x_{1}-2 x_{2} \\
\text { subject to }\left\{\begin{array}{l}
x_{1}+x_{2} \leq 1, \\
x_{1} \geq 0 \text { and } x_{2} \geq 0
\end{array}\right.
\end{array}\right.
$$

For this function, we can see that $x^{*}=(1 / 3,2 / 3)$. For different initial points $x_{0}$ we obtain the following tables:

Table 1. $x_{0}=(0.5,1)$

| iter | GM | NLMH |
| ---: | :---: | :---: |
| 0 | $1.414213562373089 \mathrm{E}-002$ | $1.414213562373089 \mathrm{E}-002$ |
| 1 | $7.071067811865560 \mathrm{E}-003$ | $1.138360651264128 \mathrm{E}-016$ |
| 4 | $8.838834764831656 \mathrm{E}-004$ |  |
| 10 | $1.381067932011570 \mathrm{E}-005$ |  |
| 20 | $1.348699145788843 \mathrm{E}-008$ |  |
| 25 | $4.214691149978832 \mathrm{E}-010$ |  |
| 30 | $1.430201717150080 \mathrm{E}-011$ |  |

Table 2. $x_{0}=(0.6,0.9)$

| iter | GM | NLMH |
| :---: | :---: | :---: |
| 0 | $1.414213562373018 \mathrm{E}-003$ | $1.414213563273018 \mathrm{E}-003$ |
| 1 | $5.656854249492542 \mathrm{E}-004$ | $1.159106867033638 \mathrm{E}-015$ |
| 5 | $1.448154687869300 \mathrm{E}-005$ |  |
| 10 | $1.482910400262855 \mathrm{E}-007$ |  |
| 15 | $1.518500241054302 \mathrm{E}-009$ |  |
| 20 | $1.554941226978357 \mathrm{E}-011$ |  |
| 25 | $1.602622606765867 \mathrm{E}-013$ |  |
| 30 | $4.399650097552470 \mathrm{E}-014$ |  |

Example 2. This example is taken from [15]. We consider the following problem:

$$
\left\{\begin{array}{l}
\text { Minimize } x_{1}^{2}+x_{2}^{2}+x_{3}^{2}+x_{4}^{2}-2 x_{1}-x_{2}-3 x_{4} \\
\text { subject to }\left\{\begin{array}{l}
2 x_{1}+x_{2}+x_{3}+4 x_{4} \leq 7, \\
x_{1}+x_{2}+2 x_{3}+x_{4} \leq 6, \\
x_{i} \geq 0 \text { pour } i=1,2,3,4
\end{array}\right.
\end{array}\right.
$$

For $x_{0}=(2,2,1,0)$ we obtain the results shown in Fig. 1.
Example 3. This example was taken from [8]. We consider the problem

$$
\left\{\begin{array}{l}
\text { Minimize } \sum_{1 \leq i \leq n} f_{i}^{2}(x) \\
\text { subject to } C x \leq d
\end{array}\right.
$$

where

- $n$ is any positive multiple of $2, x=\left(x_{i}\right)_{1 \leq i \leq n}$,
- for $i=1, \ldots, n / 2, f_{2 i-1}(x)=10\left(x_{2 i}-x_{2 i-1}^{2}\right), f_{2 i}(x)=1-x_{2 i-1}$,


Fig. 1

- $C$ is the $n \times n$ matrix given by

$$
C=\left(\begin{array}{ccccc}
1 & 1 & 1 & \ldots & 1 \\
0 & 1 & 1 & \ldots & 1 \\
0 & 0 & 1 & \ldots & 1 \\
\ldots & \ldots & \ldots & \ldots & \ldots \\
0 & 0 & 0 & \ldots & 1
\end{array}\right)
$$

- $d=(n, n-1, n-2, \ldots, 2,1)$.

For this problem, we used two values of $n$ :

- $n=10, x_{0}=(1,1,2,3,-1,1,0,2,-3,1)($ Table 3),
- $n=20, x_{0}=(1,1,2,3,-1,1,0,2,-3,1,1,1,2,3,-1,1,0,2,-3,1)$
(Table 4).

Table 3

| iter | GM | NLMH |
| :---: | :---: | :---: |
| 0 | $5.196152423125231 \mathrm{E}-000$ | $5.196152423125231 \mathrm{E}-000$ |
| 1 | $1.848869271451412 \mathrm{E}-000$ | $4.551452613214589 \mathrm{E}-001$ |
| 10 | $4.874501256871418 \mathrm{E}-001$ | $8.691254803654878 \mathrm{E}-002$ |
| 20 | $4.701452178321422 \mathrm{E}-001$ | $2.574512014583601 \mathrm{E}-002$ |
| 30 | $4.110214567852103 \mathrm{E}-001$ | $1.461420568972214 \mathrm{E}-003$ |
| 40 | $3.661204568912511 \mathrm{E}-001$ | $4.401257896542451 \mathrm{E}-004$ |
| 45 | $3.601025321642539 \mathrm{E}-001$ | $3.261250458792152 \mathrm{E}-010$ |

Table 3 (cont.)

| iter | GM | NLMH |
| :---: | :---: | :---: |
| 50 | $3.591204520121544 \mathrm{E}-001$ | $1.182507890125461 \mathrm{E}-016$ |
| 90 | $1.123654825613125 \mathrm{E}-001$ |  |
| 100 | $1.084536218962116 \mathrm{E}-001$ |  |
| 190 | $6.801245612561215 \mathrm{E}-002$ |  |
| 200 | $7.151452105682512 \mathrm{E}-003$ |  |
| 210 | $8.831258976521252 \mathrm{E}-004$ |  |

Table 4

| iter | GM | NLMH |
| :---: | :---: | :---: |
| 0 | $7.348469228123105 \mathrm{E}-000$ | $7.348469228123105 \mathrm{E}-000$ |
| 1 | $1.831287965412451 \mathrm{E}-000$ | $3.920124563214528 \mathrm{E}-001$ |
| 10 | $2.172014508963212 \mathrm{E}-001$ | $3.041789156325469 \mathrm{E}-002$ |
| 20 | $2.084567825946129 \mathrm{E}-001$ | $2.421576824563154 \mathrm{E}-002$ |
| 30 | $2.045862587165234 \mathrm{E}-001$ | $2.075862143654152 \mathrm{E}-002$ |
| 40 | $1.764589253156015 \mathrm{E}-001$ | $4.452136589456201 \mathrm{E}-003$ |
| 50 | $1.701452879653223 \mathrm{E}-001$ | $1.391254368245631 \mathrm{E}-004$ |
| 60 | $1.665239015846152 \mathrm{E}-001$ | $1.282458964321145 \mathrm{E}-004$ |
| 70 | $1.614528635248963 \mathrm{E}-001$ | $1.204568124351238 \mathrm{E}-004$ |
| 80 | $1.541502589673541 \mathrm{E}-001$ | $1.091254362154786 \mathrm{E}-004$ |
| 83 | $1.531452689354611 \mathrm{E}-001$ | $9.554218961254518 \mathrm{E}-005$ |
| 85 | $1.530125647856918 \mathrm{E}-001$ | $7.661254897314051 \mathrm{E}-007$ |
| 86 | $1.521456924056314 \mathrm{E}-001$ | $1.102578965314256 \mathrm{E}-007$ |
| 87 | $1.520456243654213 \mathrm{E}-001$ | $6.891452865432897 \mathrm{E}-011$ |
| 88 | $1.520412365478127 \mathrm{E}-001$ | $4.401789546243154 \mathrm{E}-013$ |
| 89 | $1.520411356245634 \mathrm{E}-001$ | $2.184579652301457 \mathrm{E}-015$ |
| 100 | $1.445628397025648 \mathrm{E}-002$ |  |
| 150 | $7.431546289378564 \mathrm{E}-002$ |  |
| 200 | $7.082154839147325 \mathrm{E}-003$ |  |
|  |  |  |

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