

JOANNA RENĆLAWOWICZ and WOJCIECH M. ZAJĄCZKOWSKI (Warszawa)

## WEAK SOLUTIONS TO THE NAVIER–STOKES EQUATIONS IN A Y-SHAPED DOMAIN

*Abstract.* We prove the existence of weak solutions to the Navier–Stokes equations describing the motion of a fluid in a Y-shaped domain.

**1. Introduction.** We consider the inflow-outflow problem in a reverse Y-shaped domain, with one inflow and two outflows. This can be treated as a simple model of the blood flow in veins or arteries. The motion of the fluid is described by the Navier–Stokes equations with boundary slip conditions. The domain  $\Omega \subset \mathbb{R}^3$  is given by  $\Omega = \Omega_1 \cup \Omega_2 \cup \Omega_3$  with the boundary  $\partial\Omega = S = \sum_i S_0^i \cup S_i^i$  where  $\Omega_i$ ,  $i = 1, 2, 3$ , is a cylindrical type domain. To simplify the notation, we often omit the obvious index  $i$  so that  $S_i^i \equiv S_i$ . We denote by  $\bar{n}$  the unit outward vector normal to the boundary  $S$  and by  $\bar{\tau}_j$ ,  $j = 1, 2$ , vectors tangent to  $S$ . We introduce the velocity vector  $v(x, t) = (v^1(x, t), v^2(x, t), v^3(x, t)) \in \mathbb{R}^3$  with  $v_i(x, t) = v(x, t)|_{\Omega_i}$ , the velocity defined on  $\Omega_i$ , and the pressure  $p = p(x, t) \in \mathbb{R}^1$ . The domain  $\Omega$  and the velocity vectors are presented in Figure 1.

The problem reads

$$(1.1) \quad \begin{aligned} v_t + v \cdot \nabla v - \operatorname{div} \mathbb{T}(v, p) &= f && \text{in } \Omega^T = \Omega \times (0, T), \\ \operatorname{div} v &= 0 && \text{in } \Omega^T, \\ v|_{t=0} &= v(0), \\ v \cdot \bar{n}|_{S_0^i} &= 0, \\ v \cdot \bar{n}|_{S_1} &= -a_1, \end{aligned}$$

---

2000 *Mathematics Subject Classification*: 35Q35, 76D03, 76D05.

*Key words and phrases*: Navier–Stokes equations, Y-shaped domain, inflow-outflow problem, slip boundary conditions, weak solutions.

Research supported by KBN grant no. 1 P03A 021 30.

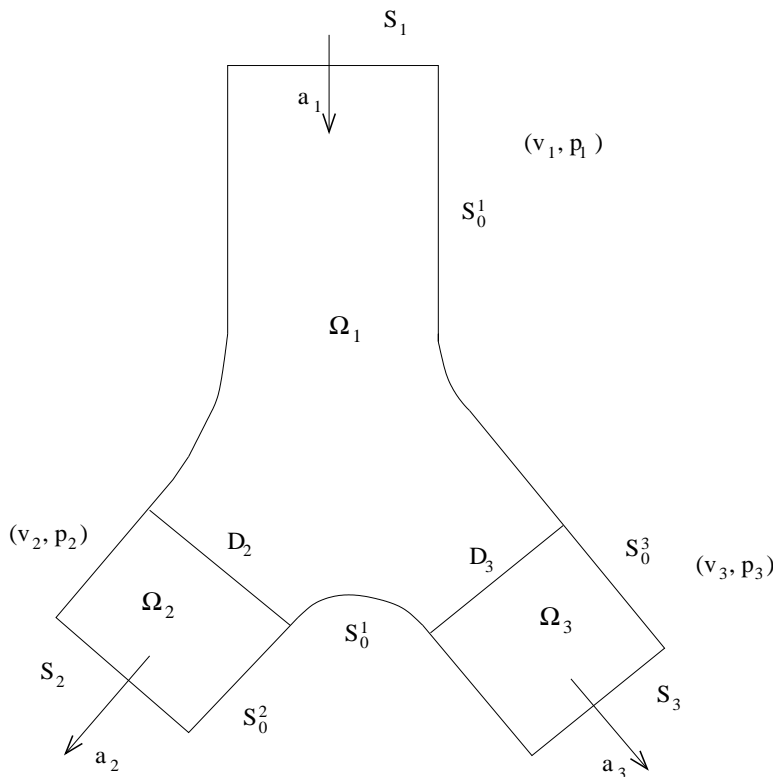


Fig. 1. Y-shaped domain

$$\begin{aligned}
 & v \cdot \bar{n}|_{S_i} = a_i, \quad i = 2, 3, \\
 (1.1) \quad & \nu \bar{n} \cdot \mathbb{D}(v) \cdot \bar{\tau}_j + \gamma v \cdot \bar{\tau}_j = 0, \quad j = 1, 2, \quad \text{on } S_0^i, \\
 [\text{cont.}] \quad & \bar{n} \cdot \mathbb{D}(v) \cdot \bar{\tau}_j = 0, \quad j = 1, 2, \quad \text{on } S_i, \quad i = 1, 2, 3,
 \end{aligned}$$

where  $f = f(x, t) = (f^1(x, t), f^2(x, t), f^3(x, t)) \in \mathbb{R}^3$  is the external force,  $\nu$  is the constant viscosity coefficient,  $\gamma > 0$  is the slip coefficient, and the stress tensor  $\mathbb{T}$  and the dilatation tensor  $\mathbb{D}$  are given as

$$\mathbb{D}(v) = \{v_{,x_j}^i + v_{,x_i}^j\}_{i,j=1,2,3}, \quad \mathbb{T}(v, p) = \nu \mathbb{D}(v) - pI.$$

The inflow  $a_1$  and outflows  $a_2, a_3$  satisfy the compatibility condition

$$\int_{S_1} a_1 = \int_{S_2} a_2 + \int_{S_3} a_3.$$

We set  $\bar{n}_i = \bar{n}|_{\Omega_i}$ . We define the artificial boundaries  $D_i = \Omega_1 \cap \Omega_i, i = 2, 3$ . Then

$$\begin{aligned}
 (1.2) \quad & v_1 = v_i, \\
 & \bar{n}_1 \cdot \mathbb{T}(v_1, p_1) = \bar{n}_1 \cdot \mathbb{T}(v_i, p_i) \quad \text{on } D_i, \quad i = 2, 3, \quad j = 1, 2.
 \end{aligned}$$

In Section 2, we prove some a priori energy type estimates. This is motivated by considerations from [Z1]. Section 3 is devoted to the proof of existence of weak solutions to the problem (1.1) by the Galerkin method (see [L, Chapter 6, Section 7]). The last part is the Appendix where the properties of solutions in the neighborhood of the transmission sections  $D_2$  and  $D_3$  are examined.

**2. Problem reformulation and a priori estimates.** To obtain energy type estimates we need to work with a function  $v$  which satisfies the homogeneous Dirichlet boundary condition. To reformulate the problem (1.1) we introduce a new function  $\alpha$  satisfying

$$\alpha_1 \cdot \bar{n}_1|_{S_1} = -a_1, \quad \alpha_i \cdot \bar{n}_1|_{S_i} = -a_i, \quad i = 2, 3,$$

and next, we define functions  $u_i$  on  $\Omega_i$  by

$$u_i = v_i - \alpha_i, \quad i = 1, 2, 3.$$

Thus we have

$$\operatorname{div} u_i = -\operatorname{div} \alpha_i, \quad u_i \cdot \bar{n}_i|_{S_i} = 0.$$

Let  $\varphi = (\varphi_1, \varphi_2, \varphi_3)$  be a solution to the problem

$$(2.1) \quad \begin{aligned} \Delta \varphi_i &= -\operatorname{div} \alpha_i && \text{in } \Omega_i, \\ \bar{n}_i \cdot \nabla \varphi_i &= 0 && \text{on } S_i \text{ and } S_0^i, \\ \int_{\Omega_i} \varphi_i dx &= 0, \\ \varphi_1 &= \varphi_i && \text{on } D_i, i = 2, 3, \\ \frac{\partial}{\partial n_1} \varphi_1 &= \frac{\partial}{\partial n_1} \varphi_i && \text{on } D_i, i = 2, 3, \end{aligned}$$

where  $n_i$  is the curvilinear coordinate along the curve tangent to  $\bar{n}_i$ ,  $i = 1, 2, 3$ . We claim

**LEMMA 2.1.** *For every extension function  $\alpha$  such that  $\alpha_i \in H^1(\Omega_i)$ ,  $i = 1, 2, 3$ , there exists a solution  $\varphi = (\varphi_1, \varphi_2, \varphi_3)$  to the problem (2.1) and the following bound holds:*

$$(2.2) \quad \sum_{i=1}^3 \|\nabla \varphi_i\|_{H^2(\Omega_i)} \leq c \sum_{i=1}^3 \|\alpha_i\|_{H^1(\Omega_i)}.$$

For convenience of the reader, we sketch the proof of this technical result in the Appendix.

Therefore, we can define new functions

$$w_i = v_i - \alpha_i - \nabla \varphi_i \equiv v_i - \delta_i$$

satisfying the following system:

$$\begin{aligned}
 & w_{i,t} + w_i \cdot \nabla w_i + w_i \cdot \nabla \delta_i + \delta_i \cdot \nabla w_i - \operatorname{div} \mathbb{T}(w_i, p_i) \\
 & \quad = f_i - \delta_{i,t} - \delta_i \cdot \nabla \delta_i + \nu \operatorname{div} \mathbb{D}(\delta_i) \equiv F_i \quad \text{in } \Omega_i, \\
 & \operatorname{div} w_i = 0 \quad \text{in } \Omega_i, \\
 & w_i \cdot \bar{n}|_{S_i} = 0, \\
 (2.3) \quad & w_i \cdot \bar{n}|_{S_0^i} = 0, \\
 & \nu \bar{n} \cdot \mathbb{D}(w_i) \cdot \bar{\tau}_j + \gamma w_i \cdot \bar{\tau}_j \\
 & \quad = -\nu \bar{n} \cdot \mathbb{D}(\delta_i) \cdot \bar{\tau}_j - \gamma \delta_i \cdot \bar{\tau}_j \equiv B_{0j}^i, \quad j = 1, 2, \quad \text{on } S_0^i, \\
 & \bar{n} \cdot \mathbb{D}(w_i) \cdot \bar{\tau}_j = -\bar{n} \cdot \mathbb{D}(\delta_i) \cdot \bar{\tau}_j \equiv B_{ij}^i, \quad j = 1, 2, \quad \text{on } S_i,
 \end{aligned}$$

and the transmission conditions

$$(2.4) \quad w_1 = w_i \quad \text{and} \quad \frac{\partial}{\partial n_1} w_1 = \frac{\partial}{\partial n_1} w_i \quad \text{on } D_i, \quad i = 2, 3.$$

Now, we introduce weak solutions to (2.3)–(2.4).

DEFINITION 2.1. A *weak solution* to (2.3)–(2.4) is a triple  $(w_1, w_2, w_3)$  satisfying the identities

$$\begin{aligned}
 (2.5) \quad & \sum_{i=1}^3 \left( \int_{\Omega_i^T} w_{i,t} \varphi \, dx \, dt + \int_{\Omega_i^T} H(w_i) \varphi \, dx \, dt + \nu \int_{\Omega_i^T} \mathbb{D}(w_i) \mathbb{D}(\varphi) \, dx \, dt \right. \\
 & \left. + \gamma \sum_{j=1}^2 \int_{S_0^T} w_i \cdot \bar{\tau}_j \varphi \cdot \bar{\tau}_j \, dS_0^i \, dt - \sum_{j=1}^2 \sum_{\sigma=0,i} \int_{S_\sigma^T} B_{\sigma j}^i \varphi \cdot \bar{\tau}_j \, dS_\sigma^i \right) = \sum_{i=1}^3 \int_{\Omega_i^T} F_i \cdot \varphi \, dx \, dt,
 \end{aligned}$$

where  $H(w) = w \cdot \nabla w + w \cdot \nabla \delta + \delta \cdot \nabla w$ , for any sufficiently smooth function  $\varphi$  with  $\operatorname{div} \varphi = 0$ ,  $\varphi \cdot \bar{n}|_S = 0$ .

We introduce some useful notation:

$$\begin{aligned}
 |u|_{p,Q} &= \sum_{i=1}^3 \|u\|_{L_p(Q_i)}, & Q &\in \{\Omega^T, S^T, \Omega, S\}, \quad p \in [1, \infty], \\
 \|u\|_{s,Q} &= \sum_{i=1}^3 \|u\|_{H^s(Q_i)}, & Q &\in \{\Omega, S\}, \quad s \in \mathbb{R}_+ \cup \{0\}, \\
 |u|_{p,q,Q^T} &= \sum_{i=1}^3 \|u\|_{L_q(0,T;L_p(Q_i))}, & Q &\in \{\Omega, S\}, \quad p, q \in [1, \infty],
 \end{aligned}$$

and a space natural for the study of the Navier–Stokes equations:

$$V_2^0(\Omega^T) = \left\{ u : \|u\|_{V_2^0(\Omega^T)} = \operatorname{ess\,sup}_{t \in (0, T)} \|u\|_{L_2(\Omega)} + \left( \int_0^T \|\nabla u\|_{L_2(\Omega)}^2 dt \right)^{1/2} < \infty \right\}.$$

We will need the following result:

LEMMA 2.2 (Korn inequality). *Assume that*

$$(2.6) \quad E_\Omega(w) = \sum_{i,j=1}^3 \int_\Omega (w_{x_j}^i + w_{x_i}^j)^2 dx < \infty$$

and

$$(2.7) \quad \sum_{j=1}^2 |w \cdot \bar{\tau}_j|_{2, S_0}^2 < \infty, \quad w \cdot \bar{n}|_S = 0, \quad \operatorname{div} w|_\Omega = 0.$$

Then there exists a constant  $c$  independent of  $w$  such that

$$(2.8) \quad \|w\|_{H^1(\Omega)}^2 \leq c \left( E_\Omega(w) + \sum_{j=1}^2 |w \cdot \bar{\tau}_j|_{L_2(S_0)}^2 \right) \equiv cE.$$

*Proof.* We have

$$\begin{aligned} E_\Omega(w) &= 2 \sum_{i,j=1}^3 \left( \int_\Omega (w_{x_j}^i)^2 dx + \int_\Omega w_{x_j}^i \cdot w_{x_i}^j dx \right) \\ &= 2 \sum_{i,j=1}^3 \left( \int_\Omega (w_{x_j}^i)^2 dx + \int_\Omega (w_{x_j}^i \cdot w^j)_{x_i} dx \right) \\ &= 2 \sum_{i,j=1}^3 \left( \int_\Omega (w_{x_j}^i)^2 dx + \int_S w_{x_j}^i \cdot w^j \cdot n_i dS \right) \\ &= 2 \sum_{i,j=1}^3 \left( \int_\Omega (w_{x_j}^i)^2 dx - \int_S w^i \cdot w^j \cdot n_{i,x_j} dS \right), \end{aligned}$$

where  $\int_\Omega f$  denotes  $\sum_{i=1}^3 \int_{\Omega_i} f_i$ . This implies

$$(2.9) \quad |\nabla w|_{2, \Omega}^2 \leq cE.$$

For a non-axially symmetric function  $w$  we can use the results in [Z2] to find that

$$(2.10) \quad |w|_{2, \Omega}^2 \leq \delta |\nabla w|_{2, \Omega}^2 + M(\delta) E_\Omega(w)$$

so that (2.9) and (2.10) yield (2.8). ■

We will show the following a priori estimate for  $w$ .

LEMMA 2.3. Assume that  $a_1 \in L_6(0, T; L_3(S_1))$ ,  $\nabla \alpha \in L_2(0, T; L_3(\Omega))$  and  $w_i(0) \in L_2(\Omega_i)$ ,  $i = 1, 2, 3$ . Let

$$\Gamma^2(t) = |f|_{6/5, \Omega}^2 + |\alpha_t|_{6/5, \Omega}^2 + |\nabla \alpha_t|_{6/5, \Omega}^2 + |\alpha|_{2, S_0}^2 + |\nabla \alpha|_{2, \Omega}^2 (1 + |\alpha|_{W_3^1(\Omega)}^2)$$

with

$$\int_0^T \Gamma^2(t) dt < \infty.$$

Then

$$(2.11) \quad |w|_{V_2^0(\Omega^t)}^2 \leq ce^{c(|a_1|_{3,6,S_1^t}^6 + |\nabla \alpha|_{3,2,\Omega^t}^2)} \left( \int_0^t \Gamma^2(t') dt' + |w(0)|_{2,\Omega}^2 \right).$$

*Proof.* With  $\varphi = w$  and  $w \cdot \bar{n}|_S = 0$  we get by definition of weak solutions

$$(2.12) \quad \sum_{i=1}^3 \left( \frac{1}{2} \frac{d}{dt} |w_i|_{2,\Omega_i}^2 + \int_{\Omega_i} |\delta_i \cdot \nabla w_i \cdot w_i + w_i \cdot \nabla \delta_i \cdot w_i| dx + \nu |\mathbb{D}(w_i)|_{2,\Omega_i}^2 + \gamma |w_i \cdot \bar{\tau}_j|_{2,S_0^i}^2 \right) = \sum_{i=1}^3 \left( \sum_{j=1}^2 \sum_{\sigma=0,i} S_\sigma^i \int B_{\sigma j}^i w_i \cdot \bar{\tau}_j dS_\sigma^i + \int_{\Omega_i} F_i \cdot w_i dx \right).$$

Now, we analyze the second term on the l.h.s. We have

$$\begin{aligned} \int_{\Omega_i} \delta_i \cdot \nabla w_i \cdot w_i dx &= \int_{\Omega_i} (\alpha_i + \nabla \varphi_i) \cdot \nabla w_i \cdot w_i dx \\ &= \int_{\Omega_i} \alpha_i \cdot \nabla w_i \cdot w_i dx + \int_{\Omega_i} \nabla \varphi_i \cdot \nabla w_i \cdot w_i dx \equiv I_1 + I_2 \end{aligned}$$

so that

$$\begin{aligned} I_1(w_i) &= \frac{1}{2} \int_{\Omega_i} \alpha_i \cdot \nabla (w_i^2) dx \\ &= \frac{1}{2} \int_{\Omega_i} \operatorname{div}(\alpha_i w_i^2) dx - \frac{1}{2} \int_{\Omega_i} \operatorname{div} \alpha_i \cdot w_i^2 dx \equiv I_1^a + I_1^b. \end{aligned}$$

Next, we calculate

$$\begin{aligned} I_1^a(w_1) &= -\frac{1}{2} \int_{S_1} a_1 w_1^2 dS_1 + \frac{1}{2} \int_{D_2} \alpha \cdot \bar{n}_1 w_2^2 dD_2 + \frac{1}{2} \int_{D_3} \alpha \cdot \bar{n}_1 w_3^2 dD_3, \\ I_1^a(w_i) &= \frac{1}{2} \int_{S_i} a_i w_i^2 dS_i - \frac{1}{2} \int_{D_i} \alpha \cdot \bar{n}_1 w_i^2 dD_i, \quad i = 2, 3. \end{aligned}$$

Thus,

$$\sum_{i=1}^3 I_1^a(w_i) = \frac{1}{2} \left( - \int_{S_1} a_1 w_1^2 dS_1 + \int_{S_2} a_2 w_2^2 dS_2 + \int_{S_3} a_3 w_3^2 dS_3 \right),$$

and we can estimate

$$-\sum_{i=1}^3 I_1^a(w_i) \leq \varepsilon_1^a \|w_1\|_{1,\Omega_1}^2 + c(1/\varepsilon_1^a) |a_1|_{3,S_1}^6 |w_1|_{2,\Omega_1}^2.$$

For  $I_1^b$  we have

$$\left| \sum_{i=1}^3 I_1^b(w_i) \right| \leq \varepsilon_1^b |w|_{6,\Omega}^2 + c(1/\varepsilon_1^b) |\nabla \alpha|_{3,\Omega}^2 |w|_{2,\Omega}^2$$

so

$$\left| \sum_{i=1}^3 I_1(w_i) \right| \leq \varepsilon_1 (|w|_{6,\Omega}^2 + \|w\|_{1,\Omega}^2) + c(1/\varepsilon_1) (|a_1|_{3,S_1}^6 + |\nabla \alpha|_{3,\Omega}^2) |w|_{2,\Omega}^2.$$

Also we obtain

$$\sum_{i=1}^3 I_2(w_i) = \frac{1}{2} \sum_{i=1}^3 \int \nabla \varphi_i \cdot \nabla (w_i^2) = -\frac{1}{2} \sum_{i=1}^3 \int \Delta \varphi_i w_i^2 = \frac{1}{2} \sum_{i=1}^3 \int \operatorname{div} \alpha_i w_i^2.$$

Consequently,

$$\left| \sum_{i=1}^3 I_2(w_i) \right| \leq \varepsilon_2 |w|_{6,\Omega}^2 + c(1/\varepsilon_2) |\nabla \alpha|_{3,\Omega}^2 |w|_{2,\Omega}^2.$$

Next, we consider the expression

$$\int_{\Omega_i} w_i \cdot \nabla \delta_i \cdot w_i = \int_{\Omega_i} w_i \cdot \nabla \alpha \cdot w_i + \int_{\Omega_i} w_i \cdot \nabla (\nabla \varphi_i) \cdot w_i \equiv I_3 + I_4$$

with

$$\begin{aligned} \left| \sum_{i=1}^3 I_3(w_i) \right| &\leq \varepsilon_3 |w|_{6,\Omega}^2 + c(1/\varepsilon_3) |\nabla \alpha|_{3,\Omega}^2 |w|_{2,\Omega}^2, \\ \left| \sum_{i=1}^3 I_4(w_i) \right| &\leq \varepsilon_4 |w|_{6,\Omega}^2 + c(1/\varepsilon_4) |\nabla \alpha|_{3,\Omega}^2 |w|_{2,\Omega}^2. \end{aligned}$$

We sum (2.12) over  $i = 1, 2, 3$ , and use the above estimates. Then, we use the imbedding inequality

$$\|u\|_{6,\Omega} \leq c \|u\|_{W_2^1(\Omega)},$$

and the Korn inequality (2.8):

$$\|w\|_{H^1(\Omega)} \leq c \left( \int_{\Omega_i} \mathbb{D}(w)^2 + \sum_{j=1}^2 |w \cdot \bar{\tau}_j|_{2,S_0}^2 \right),$$

to obtain

$$\begin{aligned}
(2.13) \quad & \frac{1}{2} \frac{d}{dt} |w|_{2,\Omega}^2 + |w|_{H^1(\Omega)}^2 \\
& \leq cA |w|_{2,\Omega}^2 + \int_{\Omega} F \cdot w + \sum_{i=1}^3 \sum_{j=1}^2 \sum_{\sigma=0,i} \int_{S_{\sigma}^i} B_{\sigma,j}^i w_i \cdot \bar{\tau}_j dS_{\sigma}^i \\
& \equiv cA |w|_{2,\Omega}^2 + J,
\end{aligned}$$

where  $A = |a_1|_{3,S_1}^6 + |\nabla \alpha|_{3,\Omega}^2$ . We now deal with the r.h.s. of the above inequality. The last two terms have the form

$$\begin{aligned}
J = & \sum_{i=1}^3 \sum_{j=1}^2 \int_{\Omega_i} (f_i - \delta_{i,t} - \delta_i \cdot \nabla \delta_i) w_i dx + \nu \int_{\Omega_i} \operatorname{div} \mathbb{D}(\delta_i) \cdot w_i dx \\
& - \int_{S_0^i} (\nu \bar{n}_i \mathbb{D}(\delta_i) \bar{\tau}_j w_i \cdot \bar{\tau}_j + \gamma \delta_i \cdot \bar{\tau}_j \cdot w_i \cdot \bar{\tau}_j) dS_0^i - \int_{S_i} \nu \bar{n}_i \mathbb{D}(\delta_i) \bar{\tau}_j w_i \cdot \bar{\tau}_j dS_i.
\end{aligned}$$

To simplify we only study the second term of  $J$ :

$$\begin{aligned}
\int_{\Omega_1} \operatorname{div} \mathbb{D}(\delta_1) \cdot w_1 &= \sum_{\sigma=0,1} \sum_{j=1}^2 \int_{S_{\sigma}^1} \bar{n}_1 \mathbb{D}(\delta_1) \bar{\tau}_j w_1 \cdot \bar{\tau}_j - \int_{\Omega_1} \mathbb{D}(\delta_1) \cdot \mathbb{D}(w_1) \\
&+ \sum_{k=2,3} \sum_{j=1}^2 \int_{D_k} \bar{n}_1 \mathbb{D}(\delta_k) \bar{\tau}_j w_k \cdot \bar{\tau}_j, \\
\int_{\Omega_i} \operatorname{div} \mathbb{D}(\delta_i) \cdot w_i &= \sum_{\sigma=0,i} \sum_{j=1}^2 \int_{S_{\sigma}^i} \bar{n}_i \mathbb{D}(\delta_i) \bar{\tau}_j w_i \cdot \bar{\tau}_j - \int_{\Omega_i} \mathbb{D}(\delta_i) \cdot \mathbb{D}(w_i) \\
&+ \sum_{j=1}^2 \int_{D_i} \bar{n}_i \mathbb{D}(\delta_i) \bar{\tau}_j w_i \cdot \bar{\tau}_j \\
&= \sum_{\sigma=0,i} \sum_{j=1}^2 \int_{S_{\sigma}^i} \bar{n}_i \mathbb{D}(\delta_i) \bar{\tau}_j w_i \cdot \bar{\tau}_j - \int_{\Omega_i} \mathbb{D}(\delta_i) \cdot \mathbb{D}(w_i) \\
&- \sum_{j=1}^2 \int_{D_i} \bar{n}_1 \mathbb{D}(\delta_i) \bar{\tau}_j w_i \cdot \bar{\tau}_j, \quad i = 2, 3,
\end{aligned}$$

to obtain

$$\begin{aligned}
J &= \sum_{i=1}^3 \left( \int_{\Omega} (f_i - \delta_{i,t} - \delta_i \cdot \nabla \delta_i) \cdot w_i - \gamma \int_{S_0^i} \delta_i \cdot \bar{\tau}_j \cdot w_i \cdot \bar{\tau}_j dS_0^i - \nu \int_{\Omega} \mathbb{D}(\delta_i) \cdot \mathbb{D}(w_i) \right) \\
&\equiv \sum_{i=1}^3 (J_1^i + J_2^i + J_3^i) \equiv J_1 + J_2 + J_3.
\end{aligned}$$



Then

$$|J_1| \leq \varepsilon_5 |w|_{6,\Omega}^2 + c(1/\varepsilon_5)(|f|_{6/5,\Omega}^2 + |\delta_t|_{6/5,\Omega}^2 + |\delta \cdot \nabla \delta|_{6/5,\Omega}^2),$$

where

$$\begin{aligned} |\delta_t|_{6/5,\Omega} &\leq |\alpha_t|_{6/5,\Omega} + |\nabla \varphi_t|_{6/5,\Omega} \leq |\alpha_t|_{6/5,\Omega} + \left| \int_{\Omega} \nabla G \nabla \alpha_t \right|_{6/5,\Omega} \\ &\leq c(|\alpha_t|_{6/5,\Omega} + |\nabla \alpha_t|_{6/5,\Omega}), \end{aligned}$$

and  $G$  is the Green function for the problem for  $\varphi$ . Similarly,

$$|\delta \cdot \nabla \delta|_{6/5,\Omega} \leq |\delta|_{3,\Omega} |\nabla \delta|_{2,\Omega} \leq c|\alpha|_{W_3^1(\Omega)} |\nabla \alpha|_{2,\Omega}.$$

We examine  $J_2$  and  $J_3$  to get

$$\begin{aligned} |J_2| &\leq \varepsilon_6 |w|_{H^1(\Omega)}^2 + c(1/\varepsilon_6) \left( |\alpha|_{2,S_0}^2 + \sum_{j=1}^2 |\bar{\tau}_j \cdot \nabla \varphi|_{2,S_0}^2 \right) \\ &\leq \varepsilon_6 |w|_{H^1}^2 + c(1/\varepsilon_6) (|\alpha|_{2,S_0}^2 + |\nabla \alpha|_{2,\Omega}^2), \\ |J_3| &\leq \varepsilon_7 |w|_{H^1(\Omega)}^2 + c(1/\varepsilon_7) |\mathbb{D}(\delta)|_{2,\Omega}^2 \\ &\leq \varepsilon_7 |w|_{H^1(\Omega)}^2 + c(1/\varepsilon_7) (|\nabla \alpha|_{2,\Omega} + |\nabla \nabla \varphi|_{2,\Omega})^2 \\ &\leq \varepsilon_7 |w|_{H^1(\Omega)}^2 + c(1/\varepsilon_7) |\nabla \alpha|_{2,\Omega}^2. \end{aligned}$$

The above estimates yield

$$\begin{aligned} |J| &\leq \varepsilon |w|_{H^1(\Omega)} + c(1/\varepsilon) [ |f|_{6/5,\Omega}^2 + |\alpha_t|_{6/5,\Omega}^2 + |\nabla \alpha_t|_{6/5,\Omega}^2 + |\alpha|_{2,S_0}^2 \\ &\quad + |\nabla \alpha|_{2,\Omega}^2 (1 + |\alpha|_{W_3^1(\Omega)}^2) ] \\ &= \varepsilon |w|_{H^1(\Omega)} + c(1/\varepsilon) \Gamma^2(t). \end{aligned}$$

Then from (2.13) we obtain

$$(2.14) \quad \frac{1}{2} \frac{d}{dt} |w|_{2,\Omega}^2 + |w|_{H^1(\Omega)}^2 \leq c(A|w|_{2,\Omega}^2 + \Gamma^2(t)).$$

If we set  $A(t) = |a_1|_{3,6,S_1^+}^6 + |\nabla \alpha|_{3,2,\Omega^+}^2$ , this can be rewritten as

$$(2.15) \quad \frac{d}{dt} (|w|_{2,\Omega}^2 e^{-cA(t)}) + |w|_{H^1(\Omega)}^2 e^{-cA(t)} \leq c\Gamma^2(t) e^{-cA(t)}$$

and integrated in time:

$$\begin{aligned} |w(t)|_{2,\Omega}^2 + e^{cA(t)} \int_0^t |w(t')|_{H^1(\Omega)}^2 e^{-cA(t')} dt' \\ \leq ce^{cA(t)} \left( \int_0^t \Gamma^2(t') e^{-cA(t')} dt' + |w(0)|_{2,\Omega}^2 \right). \end{aligned}$$

We can estimate the r.h.s. and simplify as follows:

$$|w(t)|_{2,\Omega}^2 + \int_0^t |w(t')|_{H^1(\Omega)}^2 dt' \leq ce^{cA(t)} \left( \int_0^t \Gamma^2(t') dt' + |w(0)|_{2,\Omega}^2 \right).$$

Omitting the first term on the l.h.s. we get

$$(2.16) \quad \int_0^t |w(t')|_{H^1(\Omega)}^2 dt' \leq ce^{cA(t)} \left( \int_0^t \Gamma^2(t') dt' + |w(0)|_{2,\Omega}^2 \right).$$

On the other hand, we can omit the second term in (2.15) to obtain

$$(2.17) \quad \frac{d}{dt} (|w|_{2,\Omega}^2 e^{-cA(t)}) \leq c\Gamma^2(t),$$

and integrate in time to get the estimate for  $|w|_{2,\Omega}$ . Together with (2.16) this gives the result. ■

We have  $v = w + \delta = w + \alpha + \nabla\varphi$  where

$$\begin{aligned} |\delta|_{V_2^0(\Omega^T)}^2 &\leq |\delta|_{2,\infty,\Omega^T}^2 + \int_0^T \|\delta(t')\|_{1,\Omega}^2 dt' \\ &\leq |\alpha|_{2,\infty,\Omega^T}^2 + |\nabla\alpha|_{2,\infty,\Omega^T}^2 + \int_0^T \|\alpha(t')\|_{1,\Omega}^2 dt'. \end{aligned}$$

Thus, we have the following corollary:

LEMMA 2.4. *Let the assumptions of Lemma 2.3 be satisfied and*

$$(2.18) \quad \Lambda(T) = c(|\alpha|_{2,\infty,\Omega^T}^2 + |\nabla\alpha|_{2,\infty,\Omega^T}^2) + \int_0^T \|\alpha(t')\|_{1,\Omega}^2 dt' < \infty.$$

Then

$$(2.19) \quad |v|_{V_2^0(\Omega^T)}^2 \leq ce^{c(|a_1|_{3,6,S_1^T}^6 + |\nabla\alpha|_{3,2,\Omega^T}^2)} \left( \int_0^T \Gamma^2(t') dt' + |v(0)|_{2,\Omega}^2 \right) + \Lambda(T).$$

**3. Weak solutions to (2.3).** In this section, we follow the ideas from [L, Chapter 6, Section 7]. We will use the Galerkin method to prove the existence of weak solutions to the problem (2.3). Namely, we introduce the sequence of approximating functions  $w_N$  given as

$$w^N(x, t) = \sum_{k=1}^N C_{kN}(t) a^k(x),$$

where  $\{a^k\}_{k=1}^\infty$  is a system of orthogonal functions in  $L_2(\Omega) \cap J_2^0(\Omega)$ . Here,  $J_2^0(\Omega) = \{f \in H^1(\Omega) : \operatorname{div} f = 0\}$  and  $\{a^k\}_{k=1}^\infty$  is a fundamental system in  $H^1(\Omega)$  with  $\sup_{x \in \Omega} |a^k(x)| < \infty$ ,  $\sup_{x \in \partial\Omega} |a^k(x)| < \infty$ . The coefficients

$C_{kN}(0)$  are defined by

$$C_{kN}|_{t=0} = (w_0, a_k), \quad k = 1, \dots, N,$$

and the functions  $w^N$  satisfy the following system with test functions  $a^k$ :

$$\begin{aligned} \sum_{i=1}^3 \left\{ \int_{\Omega_i} \left( \frac{1}{2} \frac{d}{dt} w_i^N a^k + w_i^N \cdot \nabla w_i^N a^k + \delta_i \cdot \nabla w_i^N \cdot w_i^N + w_i^N \cdot \nabla \delta_i \cdot w_i^N \right. \right. \\ \left. \left. + \nu \mathbb{D}(w_i^N) \mathbb{D}(a^k) \right) dx + \gamma \int_{S_0^i} w_i^N \cdot \bar{\tau}_j a^k \bar{\tau}_j dS_0^i \right\} \\ = \sum_{i=1}^3 \left( \sum_{j=1}^2 \sum_{\sigma=0, i} \int_{S_\sigma^i} B_{\sigma j}^i a^k \cdot \bar{\tau}_j dS_\sigma^i + \int_{\Omega_i} F_i \cdot a^k dx \right) \end{aligned}$$

for  $k = 1, \dots, N$ . Thus,  $w^N$  would be a weak solution to (2.3).

With  $(f, g) = \int_{\Omega} f g dx$  and  $(f, g)_S = \int_S f g dS$  this can be rewritten as

$$\begin{aligned} \sum_{i=1}^3 \{ (w_{i,t}^N, a^k) + (w_i^N \cdot \nabla w_i^N, a^k) + (\delta_i \cdot \nabla w_i^N, a^k) + (w_i^N \cdot \nabla \delta_i, a^k) \\ + \nu (\mathbb{D}(w_i^N), \mathbb{D}(a^k)) + \gamma (w_i^N \cdot \bar{\tau}_j, a^k \cdot \bar{\tau}_j)_{S_0^i} \} \\ = \sum_{i=1}^3 \left[ \sum_{j=1}^2 \sum_{\sigma=0, i} (B_{\sigma j}^i, a^k \cdot \bar{\tau}_j)_{S_\sigma^i} + (F_i, a^k) \right], \quad k = 1, \dots, N. \end{aligned}$$

Thus,

$$\begin{aligned} (3.1) \quad \left( \frac{d}{dt} w^N, a^k \right) + (w^N \cdot \nabla w^N, a^k) + (\delta \cdot \nabla w^N, a^k) + (w^N \cdot \nabla \delta, a^k) \\ + \nu (\mathbb{D}(w^N), \mathbb{D}(a^k)) + \gamma (w^N \cdot \bar{\tau}_j, a^k \cdot \bar{\tau}_j)_{S_0} \\ = \sum_{i=1}^3 \sum_{j=1}^2 \sum_{\sigma=0, i} (B_{\sigma j}^i, a^k \cdot \bar{\tau}_j)_{S_\sigma^i} + (F, a^k), \quad k = 1, \dots, N. \end{aligned}$$

The above equations are in fact a system of ordinary differential equations for the functions  $C_{kN}(t)$ . The properties of the sequence  $a^k$  imply

$$|w^N(\cdot, t)|_{2, \Omega}^2 = \sum_{k=1}^N C_{kN}^2(t).$$

On the other hand, we can obtain a priori bounds for the approximate solutions  $w^N$  of the same form as in (2.11):

$$\begin{aligned} (3.2) \quad |w^N|_{V_2^0(\Omega^T)}^2 = \sup_{0 \leq t \leq T} |w^N|_{2, \Omega} + \int_0^T |\nabla w^N|_{2, \Omega} dt' \\ \leq c e^{c(|a_1|_{3,6, S_1^T}^6 + |\nabla \alpha|_{3,2, \Omega^T}^2)} \left( \int_0^T \Gamma^2(t') dt' + |w(0)|_{2, \Omega}^2 \right) \leq C. \end{aligned}$$

Therefore,  $\sup_{0 \leq t \leq T} |C_{kN}(t)|$  is bounded on  $[0, T]$  and  $w^N$  are well defined for all times  $t$ .

Define now  $\psi_{N,k} \equiv (w^N(x, t), a^k(x))$ . This sequence is uniformly bounded by (3.2). We can also show that it is equicontinuous. Namely, we integrate (3.1) with respect to  $t$  from  $t$  to  $t + \Delta t$  to obtain

$$\begin{aligned}
& |\psi_{N,k}(t + \Delta t) - \psi_{N,k}(t)| \\
& \leq \sup_{x \in \Omega} |a^k(x)| \int_t^{t+\Delta t} (|w^N \cdot \nabla w^N|_{2,\Omega} + |\delta \cdot \nabla w^N|_{2,\Omega} |w^N \cdot \nabla \delta|_{2,\Omega} + |F|_{2,\Omega}) dt' \\
& \quad + \nu |\nabla a^k|_{2,\Omega} \int_t^{t+\Delta t} |\nabla w^N|_{2,\Omega} dt' \\
& \quad + \gamma \sup_{x \in S} |a^k(x)| \int_t^{t+\Delta t} \left( |w^N \cdot \bar{\tau}_j|_{2,S_0} + \sum_{i=1}^3 \sum_{j=1}^2 \sum_{\sigma=0,i} |B_{\sigma j}|_{2,S_\sigma^i} \right) dt' \\
& \leq \sup_{x \in \Omega} |a^k(x)| \sqrt{\Delta t} \left( \sup_{x \in \Omega} |w^N|_{2,\Omega} (|\nabla w^N|_{2,\Omega^T} + |\nabla \delta|_{2,\Omega^T}) \right. \\
& \quad \left. + \sup_{x \in \Omega} |\delta|_{2,\Omega} |\nabla w^N|_{2,\Omega^T} \right) \\
& \quad + \sup_{x \in \Omega} |a^k(x)| \int_t^{t+\Delta t} |F|_{2,\Omega} dt' + \nu |\nabla a^k|_{2,\Omega} \sqrt{\Delta t} |\nabla w^N|_{2,\Omega^T} \\
& \quad + \gamma \sup_{x \in S} |a^k(x)| \left( \sqrt{\Delta t} |\nabla w^N|_{2,\Omega^T} + \int_t^{t+\Delta t} \sum_{j=1}^2 |B_j|_{2,S} \right) dt' \\
& \leq C(k) \left( \sqrt{\Delta t} + \int_t^{t+\Delta t} (|F|_{2,\Omega} + \sum_{j=1}^2 |B_j|_{2,S}) dt' \right).
\end{aligned}$$

We can see that for given  $k$  and  $N \geq k$  the r.h.s. tends to zero as  $\Delta t \rightarrow 0$  uniformly in  $N$ . Thus, one can choose a subsequence  $N_m$  such that  $\psi_{N_m,k}$  converges as  $m \rightarrow \infty$  uniformly to some continuous function  $\psi_k$  for any given  $k$ . Since the limit function  $w$  is defined as

$$w(x, t) = \sum_{k=1}^{\infty} \psi_k(t) a^k(x),$$

we conclude that  $(w^{N_m} - w, \psi)$  tends to zero as  $m \rightarrow \infty$  uniformly with respect to  $t \in [0, T]$  for any  $\psi \in J_2^0(\Omega)$ , and  $w(x, t)$  is continuous in  $t$  in the weak topology. Moreover, estimate (3.2) remains true for the limit function  $w$ .

We will show that  $\{w^{N_m}\}$  converges strongly in  $L_2(\Omega^T)$ . To this end, we need to apply the following version of the Friedrichs lemma: for any  $\varepsilon > 0$ , there exists  $N_\varepsilon$  such that for any  $u \in W_2^1(\Omega)$ ,

$$\|u\|_{2,\Omega}^2 \leq \sum_{k=1}^{N_\varepsilon} (u, a^k) + \varepsilon \|\nabla u\|_{2,\Omega}^2.$$

This in terms of  $u = w^{N_m} - w^{N_l}$  reads

$$\|w^{N_m} - w^{N_l}\|_{2,\Omega^T}^2 \leq \sum_{k=1}^{N_\varepsilon} \int_0^T (w^{N_m} - w^{N_l}, a^k) dt + \varepsilon \|\nabla w^{N_m} - \nabla w^{N_l}\|_{2,\Omega^T}^2.$$

By (3.2), we have

$$\|\nabla w^{N_m} - \nabla w^{N_l}\|_{2,\Omega^T}^2 \leq 2C^2$$

for some constant  $C$ . The above integral, for given  $N_\varepsilon$ , can be arbitrarily small provided  $m$  and  $l$  are sufficiently large, so it tends to zero as  $m, l \rightarrow \infty$ . Therefore,  $\{w^{N_m}\}$  converges strongly in  $L_2(\Omega^T)$ .

We summarize the above convergence properties of the sequence  $\{w^{N_m}\}$ :

- (i)  $w^{N_m} \rightarrow w$  strongly in  $L_2(\Omega^T)$  for some  $w$ ,
- (ii)  $w^{N_m} \rightarrow w$  weakly in  $L_2(\Omega)$  uniformly with respect to  $t \in [0, T]$ ,
- (iii)  $\nabla w^{N_m} \rightarrow \nabla w$  weakly in  $L_2(\Omega^T)$ .

For given  $\Phi^k = \sum_{j=1}^k d_j(t) a^j(x)$ , the sequence  $\{w^{N_m}\}$  satisfies the identities

$$\int_{\Omega} \left( \frac{d}{dt} w^{N_m} \Phi^k + (w^{N_m} \cdot \nabla w^{N_m} + \delta \cdot \nabla w^{N_m} + w^{N_m} \cdot \nabla \delta) \Phi^k + \nu \mathbb{D}(w^{N_m}) \mathbb{D}(\Phi^k) \right) dx + \gamma \int_{S_0} w^{N_m} \cdot \bar{\tau}_j \Phi^k \cdot \bar{\tau}_j dS_0 = \sum_{i=1}^3 \sum_{j=1}^2 \sum_{\sigma=0,i} \int_{S_\sigma^i} B_{\sigma j} \Phi^k \cdot \bar{\tau}_j dS_\sigma^i + \int_{\Omega} F \Phi^k dx.$$

Then we can pass to the limit as  $m \rightarrow \infty$  to obtain the identity for  $w$ . The conditions  $\operatorname{div} w^N = 0$ ,  $w^N \cdot \bar{n}|_{S^T} = 0$  stay true for the limit function  $w$  as well.

It remains to consider the limit  $\lim_{t \rightarrow 0} w(x, t)$ . We note that the  $w^{N_m}$  satisfy the relation (2.12) (if we use the test function  $w^{N_m}$ ). This yields

$$|w^{N_m}|_{2,\Omega} \leq |w_0|_{2,\Omega} + \int_0^t (|F|_{2,\Omega} + |B|_{2,S}) dt'.$$

In the limit  $m \rightarrow \infty$  we obtain

$$|w|_{2,\Omega} \leq |w_0|_{2,\Omega} + \int_0^t (|F|_{2,\Omega} + |B|_{2,S}) dt',$$

which implies

$$\overline{\lim}_{t \rightarrow 0} |w|_{2, \Omega} \leq |w_0|_{2, \Omega}.$$

On the other hand, since  $w^{N_m}$  tends to  $w$  as  $m \rightarrow \infty$ , we have  $|w^{N_m} - w_0|_{2, \Omega} \rightarrow 0$ . Therefore,  $|w^{N_m} - w_0| \rightarrow 0$  weakly in  $L_2(\Omega)$  as  $t \rightarrow 0$  and

$$|w_0|_{2, \Omega} \leq \underline{\lim}_{t \rightarrow 0} |w|_{2, \Omega}.$$

We conclude that the limit  $\lim_{t \rightarrow 0} |w|_{2, \Omega}$  exists and is equal to  $|w_0|_{2, \Omega}$  where the convergence is strong, in the  $L_2(\Omega)$  norm.

Consequently, we have proved the following result.

**THEOREM 1.** *Let the assumptions of Lemma 2.3 be satisfied. Then there exists a weak solution  $w$  to problem (2.3) such that  $w$  is weakly continuous with respect to  $t$  in  $L_2(\Omega)$  norm and  $w$  converges to  $w_0$  as  $t \rightarrow 0$  strongly in  $L_2(\Omega)$  norm.*

**4. Appendix: sketch of proof of Lemma 2.1.** We discuss the properties of the functions  $\varphi_i$ ,  $i = 1, 2, 3$ , solving problem (2.1). To this end, we need the notion of a regularizer and a partition of unity for the domain  $\Omega$ . Namely, let us define two collections of open subsets  $\{\omega^{(k)}\}$  and  $\{\Omega^{(k)}\}$ ,  $k \in \mathcal{M} \cup \mathcal{N}$ , such that  $\overline{\omega^{(k)}} \subset \Omega^{(k)} \subset \Omega$ ,  $\bigcup_k \omega^{(k)} = \bigcup_k \Omega^{(k)} = \Omega$ ,  $\overline{\Omega^{(k)}} \cap S = \emptyset$  for  $k \in \mathcal{M}$  and  $\overline{\Omega^{(k)}} \cap S \neq \emptyset$  for  $k \in \mathcal{N}$ . We assume that at most a finite number of  $\Omega^{(k)}$  have nonempty intersection.

We will treat in more detail only the local problem on some sufficiently small subset  $\Omega^N \subset \Omega$  such that  $\Omega^N \cap D_2 \neq \emptyset$  and  $\Omega^N \cap S_0^i \neq \emptyset$ ,  $i = 1, 2$ . The case of a domain that intersects  $D_3$  is analogous and subsets that lie entirely (i.e. with their closures) in one of  $\Omega^i$ ,  $i = 1, 2, 3$ , are much easier to treat.

First, we straighten the boundary  $(S_0^1 \cup S_0^2) \cap \Omega^N$  and by the reflection technique we transform the problem on  $\Omega^N$  to an equivalent problem on some subset  $\Omega^M$  where  $\Omega^M \cap D_2 \neq \emptyset$  and  $\text{int}\{\Omega^M\} \cap S_0^i \neq \emptyset$ ,  $i = 1, 2$  (see Figure 2.)

The system (2.1) now reads

$$\begin{aligned} -\Delta \varphi_1 &= \text{div } \alpha_1 && \text{in } \Omega^M \cap \Omega_1, \\ -\Delta \varphi_2 &= \text{div } \alpha_2 && \text{in } \Omega^M \cap \Omega_2, \\ \frac{\partial \varphi_1}{\partial n_1} \Big|_{D_2} &= \frac{\partial \varphi_2}{\partial n_1} \Big|_{D_2}. \end{aligned}$$

Here, we denote in fact by  $\varphi$  the new function  $\varphi\zeta$  where  $\zeta$  is a smooth function with compact support in  $\Omega^M$ . In the new coordinates the local problem on

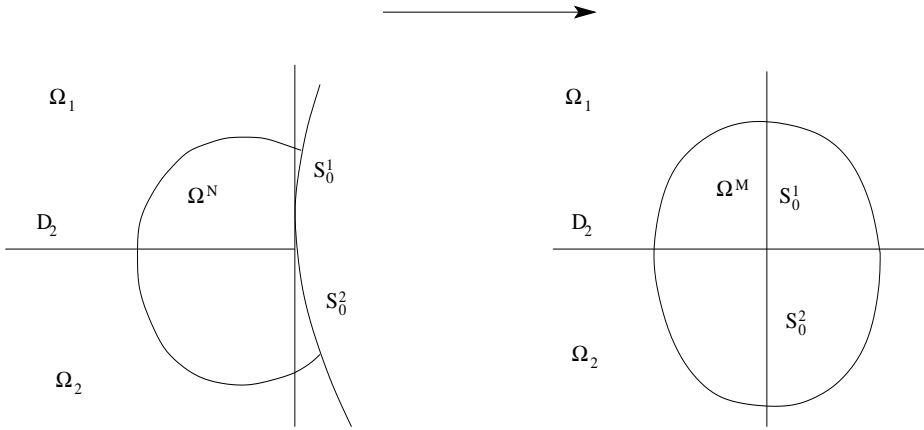


Fig. 2. Transformation from  $\Omega^N$  to  $\Omega^M$

$\Omega^M$  takes the following form in a half-space:

$$\begin{aligned}
 (4.1) \quad & -\Delta\varphi_1 = \operatorname{div} \alpha_1 \quad \text{for } x_3 > 0, \\
 & -\Delta\varphi_2 = \operatorname{div} \alpha_2 \quad \text{for } x_3 < 0, \\
 & \left. \frac{\partial\varphi_1}{\partial x_3} \right|_{x_3=0} = \left. \frac{\partial\varphi_2}{\partial x_3} \right|_{x_3=0},
 \end{aligned}$$

and it is completed with the conditions at infinity:

$$\begin{aligned}
 (4.2) \quad & \varphi_1 \rightarrow 0 \quad \text{as } x_3 \rightarrow \infty, \\
 & \varphi_2 \rightarrow 0 \quad \text{as } x_3 \rightarrow -\infty.
 \end{aligned}$$

We introduce new functions  $u_i = \varphi_i - \tilde{\varphi}_i$  where  $\tilde{\varphi}_i$  satisfy the first two equations of the system (4.1). Therefore, we consider the equivalent problem

$$\begin{aligned}
 & -\Delta u_1 = 0 \quad \text{for } x_3 > 0, \\
 & -\Delta u_2 = 0 \quad \text{for } x_3 < 0, \\
 & \left. \frac{\partial u_1}{\partial x_3} - \frac{\partial u_2}{\partial x_3} \right|_{x_3=0} = \left. \frac{\partial \tilde{\varphi}_2}{\partial x_3} - \frac{\partial \tilde{\varphi}_1}{\partial x_3} \right|_{x_3=0} \equiv -\psi_1, \\
 & u_1 - u_2|_{x_3=0} = \tilde{\varphi}_2 - \tilde{\varphi}_1 \equiv \psi_2, \\
 & u_1 \rightarrow 0 \quad \text{as } x_3 \rightarrow \infty, \\
 & u_2 \rightarrow 0 \quad \text{as } x_3 \rightarrow -\infty.
 \end{aligned}$$

Applying the Fourier transform (with respect to  $x' = (x_1, x_2)$ ), i.e.

$$\tilde{u}(\xi, x_3) = \int_{\mathbb{R}^2} e^{-i\xi x'} u(x', x_3) dx',$$

where  $\xi = (\xi_1, \xi_2)$  and  $\xi \cdot x' = \xi_1 x_1 + \xi_2 x_2$ , we obtain the problem

$$(4.3) \quad \begin{aligned} \xi^2 \tilde{u}_1 - \frac{\partial^2 \tilde{u}_1}{\partial x_3^2} &= 0 \quad \text{for } x_3 > 0, \\ \xi^2 \tilde{u}_2 - \frac{\partial^2 \tilde{u}_2}{\partial x_3^2} &= 0 \quad \text{for } x_3 < 0, \\ \frac{\partial \tilde{u}_1}{\partial x_3} - \frac{\partial \tilde{u}_2}{\partial x_3} \Big|_{x_3=0} &= -\tilde{\psi}_1, \\ \tilde{u}_1 - \tilde{u}_2 \Big|_{x_3=0} &= \tilde{\psi}_2, \\ \tilde{u}_1 &\rightarrow 0 \quad \text{as } x_3 \rightarrow \infty, \\ \tilde{u}_2 &\rightarrow 0 \quad \text{as } x_3 \rightarrow -\infty. \end{aligned}$$

We can easily find the solutions

$$\tilde{u}_1 = c_1 e^{-|\xi|x_3}, \quad \tilde{u}_2 = c_2 e^{|\xi|x_3},$$

where

$$c_1 + c_2 = \tilde{\psi}_1, \quad c_1 - c_2 = \tilde{\psi}_2,$$

thus

$$c_1 = \frac{1}{2} (\tilde{\psi}_1 + \tilde{\psi}_2), \quad c_2 = \frac{1}{2} (\tilde{\psi}_1 - \tilde{\psi}_2).$$

We want to use  $\tilde{u}_i$  to estimate the  $H^2$  norm of  $u_i$ . By way of example, we examine  $\tilde{u}_1$ . We observe that

$$\begin{aligned} \int_0^\infty |\tilde{u}_1|^2 &= \int_0^\infty c_1^2 e^{-2|\xi|x_3} dx_3 \leq \frac{c}{|\xi|}, \\ \left\| \frac{d}{dx_3} \tilde{u}_1 \right\|_{L_2}^2 &= \int_0^\infty \left| \frac{d}{dx_3} \tilde{u}_1 \right|^2 = c_1^2 \int_0^\infty |\xi|^2 e^{-2|\xi|x_3} dx_3 \leq c|\xi|, \\ \left\| \frac{d^2}{dx_3^2} \tilde{u}_1 \right\|_{L_2}^2 &\leq c|\xi|^3. \end{aligned}$$

Consequently,

$$\begin{aligned} \sum_{i=1}^2 \|u_i\|_{H^2}^2 &= \int \left( [(1 + \xi^2)\tilde{u}]^2 + \left| \frac{d^2}{dx_3^2} \tilde{u} \right|^2 \right) d\xi \\ &\leq \int \left( (1 + \xi^2)^2 \frac{|\tilde{\psi}|^2}{|\xi|} + |\xi|^3 |\tilde{\psi}|^2 \right) d\xi_1 d\xi_2 \\ &\leq c \|\tilde{\psi}\|_{H^{3/2}(\mathbb{R}^2)}^2 \leq c \|\tilde{\alpha}\|_{H^1(\mathbb{R}^3)}. \end{aligned}$$

Hence, by the regularizer technique and the a priori estimate on  $\varphi$ ,

$$\sum_{i=1}^3 \int_{\Omega_i} |\nabla \varphi_i|^2 \leq c \sum_{i=1}^3 \int_{\Omega_i} |\nabla \alpha_i|^2$$

we deduce the statement of Lemma 2.1 and the estimate (2.2).



## References

- [L] O. A. Ladyzhenskaya, *Mathematical Theory of Viscous Incompressible Flow*, Nauka, Moscow 1970 (in Russian).
- [Z1] W. M. Zajączkowski, *Global regular nonstationary flow for the Navier–Stokes equations in a cylindrical pipe*, Topol. Methods Nonlinear Anal. 26 (2005), 221–286.
- [Z2] —, *Global existence of axially symmetric solutions to Navier–Stokes equations with large angular component of velocity*, Colloq. Math. 100 (2004), 243–263.

Joanna Renclawowicz  
Institute of Mathematics  
Polish Academy of Sciences  
Śniadeckich 8  
00-956 Warszawa, Poland  
E-mail: jr@impan.gov.pl

Wojciech M. Zajączkowski  
Institute of Mathematics  
Polish Academy of Sciences  
Śniadeckich 8  
00-956 Warszawa, Poland  
E-mail: wz@impan.gov.pl  
and  
Institute of Mathematics and Cryptology  
Military University of Technology  
Kaliskiego 2  
00-908 Warszawa, Poland

*Received on 2.3.2006;*  
*revised version on 5.4.2006*

(1810)