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**EXISTENCE OF SOLUTIONS TO
THE (rot, div)-SYSTEM IN L_p -WEIGHTED SPACES**

Abstract. The existence of solutions to the elliptic problem $\operatorname{rot} v = w$, $\operatorname{div} v = 0$ in a bounded domain $\Omega \subset \mathbb{R}^3$, $v \cdot \bar{n}|_S = 0$, $S = \partial\Omega$ in weighted L_p -Sobolev spaces is proved. It is assumed that an axis L crosses Ω and the weight is a negative power function of the distance to the axis. The main part of the proof is devoted to examining solutions of the problem in a neighbourhood of L . The existence in Ω follows from the technique of regularization.

1. Introduction. We consider the elliptic boundary value problem

$$(1.1) \quad \begin{aligned} \operatorname{rot} v &= w && \text{in } \Omega, \\ \operatorname{div} v &= 0 && \text{in } \Omega, \\ v \cdot \bar{n} &= b && \text{on } S, \end{aligned}$$

where $\Omega \subset \mathbb{R}^3$ is a bounded domain, $S = \partial\Omega$, $S \in C^2$, \bar{n} is the unit outward vector normal to S and the dot denotes the scalar product in \mathbb{R}^3 .

For the solvability of problem (1.1), the following compatibility conditions have to be satisfied:

$$(1.2) \quad \int_S b(s) ds = 0,$$

$$(1.3) \quad \operatorname{div} w = 0.$$

Let L be an axis passing through Ω .

Our aim is to prove the existence of solutions to problem (1.1) in weighted Sobolev spaces with the weight equal to a power function of the distance to L . Therefore, we introduce the weighted Sobolev space $V_{p,-\mu}^k(\Omega)$ with the finite

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norm

$$\|u\|_{V_{p,-\mu}^k(\Omega)} = \left(\sum_{|\alpha| \leq k} \int_{\Omega} |D_x^\alpha u(x)|^p \varrho(x)^{p(-\mu-k+|\alpha|)} dx \right)^{1/p} < \infty,$$

where $\varrho(x) = \text{dist}\{x, L\}$, $p \in [1, \infty)$, $\mu \in \mathbb{R}_+$, $k \in \mathbb{N} \cup \{0\}$. Moreover, we introduce the notation

$$H_{-\mu}^k(\Omega) = V_{2,-\mu}^k(\Omega), \quad L_{p,-\mu}(\Omega) = V_{p,-\mu}^0(\Omega).$$

The main result of this paper is the following

THEOREM 1.1. *Assume the compatibility conditions (1.2), (1.3). Assume that $w \in V_{p,-\mu}^k(\Omega)$, $b \in V_{p,-\mu}^{k+1-1/p}(S)$, $\mu \in \mathbb{R}_+$, $\mu \notin \mathbb{Z}$, $k \in \mathbb{N} \cup \{0\}$, $p \in [2, \infty)$, $S \in C^2$. Then there exists a solution to problem (1.1) such that $v \in V_{p,-\mu}^{k+1}(\Omega)$ and*

$$(1.4) \quad \|v\|_{V_{p,-\mu}^{k+1}(\Omega)} \leq c(\|w\|_{V_{p,-\mu}^k(\Omega)} + \|b\|_{V_{p,-\mu}^{k+1-1/p}(S)}),$$

where c does not depend on v, w, b .

To prove Theorem 1.1 we need [4] and the following result.

THEOREM 1.2 (see [7]). *Assume the compatibility conditions (1.2), (1.3). Assume that $w \in H_{-\mu}^k(\Omega)$, $b \in H_{-\mu}^{k+1/2}(S)$, $\mu \in \mathbb{R}_+$, $\mu \notin \mathbb{Z}$, $k \in \mathbb{N} \cup \{0\}$. Then there exists a solution to problem (1.1) such that*

$$(1.5) \quad \|v\|_{H_{-\mu}^{k+1}(\Omega)} \leq c(\|w\|_{H_{-\mu}^k(\Omega)} + \|b\|_{H_{-\mu}^{k+1/2}(S)}),$$

where c does not depend on v, w, b .

The main step in the proofs of Theorems 1.1, 1.2 is to obtain an estimate in weighted spaces in neighbourhoods of points of the axis L because estimates in neighbourhoods at a positive distance to the axis are well known (see [1, 6]). We concentrate on local estimates, and a global estimate follows by applying the idea of regularization (see [7, 3]). Restricting our considerations to neighbourhoods of points of L we showed in [7] that it is sufficient to examine problem (1.1) in neighbourhoods of interior points of $\Omega \cap L$. In this case problem (1.1) can be replaced by the elliptic problem (see [7])

$$(1.6) \quad \begin{aligned} -\Delta u &= f && \text{in } C_{R,a}, \\ u &= 0 && \text{on } \partial C_{R,a}, \end{aligned}$$

where $C_{R,a}$ is an axially symmetric cylinder with axis of symmetry L located in Ω . Introducing the cylindrical coordinates r, φ, z by relations $x_1 = r \cos \varphi$, $x_2 = r \sin \varphi$, $x_3 = z$, where x_1, x_2, x_3 are the Cartesian coordinates such as L is the x_3 -axis we define

$$C_{R,a} = \{x \in \mathbb{R}^3 : r < R, -a < z < a, \varphi \in [0, 2\pi]\}, \quad C_{R,a} \cap S = \emptyset,$$

and the origin of the Cartesian coordinates is at an interior point of $\Omega \cap L$.

Now we describe the proofs of Theorems 1.1 and 1.2 underlining their differences. In [7] we examine problem (1.6) by applying the Fourier transforms and using the norms of weighted spaces also in terms of the Fourier transforms. This is connected with the fact that the L_2 -theory is developed in [7]. In this paper we improve the regularity of solutions from [7] by applying the local regularization method (see [5]) and by using the Paley–Littlewood partition of unity so the methods of this paper are totally different from those in [7].

Up to now Theorem 1.1 has not been applied in proofs of existence of regular solutions to the Navier–Stokes equations (see references in [7]). However, in more delicate proofs based on the L_p -approach Theorem 1.1 will be needed.

2. Notation. Using the cylindrical coordinates we introduce the weighted spaces

$$V_{p,-\mu}^k(\mathbb{R}^3) = \left\{ u : \left(\sum_{|\alpha| \leq k} \int_{\mathbb{R}^3} |D_x^\alpha u(x)|^p r^{p(-\mu-k+|\alpha|)} dx \right)^{1/p} < \infty \right\}.$$

3. Localization of problem (1.1). We are looking for solutions to problem (1.1) in the form (see [7])

$$(3.1) \quad v = \nabla \varphi + u,$$

where φ is a solution to the problem

$$(3.2) \quad \Delta \varphi = 0, \quad \bar{n} \cdot \nabla \varphi|_S = b$$

and u satisfies

$$(3.3) \quad \begin{aligned} \operatorname{rot} u &= w && \text{in } \Omega, \\ \operatorname{div} u &= 0 && \text{in } \Omega, \\ u \cdot \bar{n}|_S &= 0. \end{aligned}$$

From [2] we know that (3.3)_{2,3} imply the existence of a vector field e such that

$$(3.4) \quad u = \operatorname{rot} e, \quad \operatorname{div} e = 0, \quad e \cdot \bar{\tau}|_S = 0,$$

where $\bar{\tau}$ is a tangent vector to S .

In view of (3.4) problem (3.3) takes the form

$$(3.5) \quad -\Delta e = w, \quad e \cdot \bar{\tau}|_S = 0, \quad \operatorname{div} e|_S = 0.$$

Localizing problems (3.2) and (3.5) by a smooth function from a partition of unity we obtain problem (1.6). The lower order terms which appear in this procedure will be estimated by applying the regularization method.

4. Regularity near the axis L in the L_p -approach. After localization of problems (3.2) and (3.5) to a neighbourhood of an internal point of L or a point where L meets S we can replace them by the problem

$$(4.1) \quad \begin{aligned} -\Delta u &= f && \text{in } \Omega, \\ u &= 0 && \text{on } \partial\Omega, \end{aligned}$$

where $\Omega = C_{R,a}$.

LEMMA 4.1 (local regularity; see [5]). *Let $B_r = \{x_3 \in \mathbb{R} : |x_3| < r\}$, $\xi_i = \xi_i(x')$, $x' = (x_1, x_2)$, $\xi_i \in C_0^\infty(\mathbb{R}^2)$, $i = 1, 2$, $\xi_1 \xi_2 = \xi_1$, $\text{supp } \xi_2 \subset \{x' : c_1 < |x'| < c_2\}$. Then for every $u \in W_p^{l+2}(\mathbb{R}^2 \times B_2)$ the following inequality holds:*

$$(4.2) \quad \|\xi_1 u\|_{W_p^{l+2}(\mathbb{R}^2 \times B_1)} \leq c(\|\xi_2 \Delta u\|_{W_p^l(\mathbb{R}^2 \times B_2)} + \|\xi_2 u\|_{L_{p_1}(\mathbb{R}^2 \times B_2)}),$$

for any $p_1 \in [1, \infty]$, where c does not depend on u .

Let us introduce partitions of unity $\{\zeta_j\}_{j=-\infty}^\infty$, $\{\sigma_j\}_{j=-\infty}^\infty$ such that

$$\text{supp } \zeta_j \subset \{x' : 2^{j-1} < |x'| < 2^{j+1}\},$$

$$\text{supp } \sigma_j \subset \{x' : 2^{j-2} < |x'| < 2^{j+2}\},$$

$\sigma_j, \zeta_j \in C^\infty(\mathbb{R}^2)$, $\zeta_j \sigma_j = \zeta_j$, and for all multiindices α ,

$$|D^\alpha \zeta_j| + |D^\alpha \sigma_j| \leq c_\alpha 2^{-j|\alpha|}.$$

LEMMA 4.2. *Let $\beta \in \mathbb{R}$. Then for any $u \in W_p^{l+2}(\{2^{j-2} < |x'| < 2^{j+2}\} \times \mathbb{R}^1)$ the following inequality holds,*

$$(4.3) \quad \|\zeta_j u\|_{V_{p,\beta}^{l+2}(\mathbb{R}^2 \times \mathbb{R}^1)} \leq c(\|\sigma_j \Delta u\|_{V_{p,\beta}^l(\mathbb{R}^2 \times \mathbb{R}^1)} + \|\sigma_j u\|_{L_{p,\beta-l-2}(\mathbb{R}^2 \times \mathbb{R}^1)}),$$

where c does not depend on u and j .

Proof. Let $K = \{x' : 1 < |x'| < 2\}$, $B = \{x_3 : |x_3| < 2\}$, $K_\mu = \{x' : 2^\mu < |x'| < 2^{\mu+1}\}$, $B_\mu = \{x_3 : |x_3| < 2^{\mu+1}\}$. From (4.2) we have

$$(4.4) \quad \begin{aligned} \sum_{|\alpha|=0}^{l+2} \|D^\alpha(\zeta_j u)\|_{L_p(K \times B)} &\leq c \sum_{|\alpha|=0}^l \|D^\alpha(\sigma_j \Delta u)\|_{L_p(2K \times 2B)} \\ &\quad + c \|\sigma_j u\|_{L_p(2K \times 2B)}, \end{aligned}$$

where $2K = \{x' : 1/2 < |x'| < 4\}$, $2B = \{x_3 : |x_3| < 4\}$. In view of scaling $x \mapsto 2^\mu x$ we obtain

$$(4.5) \quad \begin{aligned} \sum_{|\alpha|=0}^{l+2} 2^{\mu(|\alpha|-2)} \|D^\alpha(\zeta_j u)\|_{L_p(K_\mu \times B_\mu)} \\ \leq c \sum_{|\alpha|=0}^l 2^{\mu|\alpha|} \|D^\alpha \sigma_j \Delta u\|_{L_p(2K_\mu \times 2B_\mu)} + c 2^{-2\mu} \|\sigma_j u\|_{L_p(2K_\mu \times 2B_\mu)}. \end{aligned}$$

Multiplying (4.5) by $2^{(\beta-l)\mu}$, taking the p th power, summing over μ and using that $r \sim 2^\mu$ on the set K_μ , we obtain

$$(4.6) \quad \sum_{|\alpha|=0}^{l+2} \|r^{\beta-l-2+|\alpha|} D^\alpha(\zeta_j u)\|_{L_p(\mathbb{R}^3)} \leq c \sum_{|\alpha|=0}^l \|r^{\beta-l+|\alpha|} D^\alpha(\sigma_j \Delta u)\|_{L_p(\mathbb{R}^3)} + c \|r^{\beta-l-2} \sigma_j u\|_{L_p(\mathbb{R}^3)}.$$

This implies (4.3) and concludes the proof.

Summing up (4.3) with respect to j yields

$$(4.7) \quad \|u\|_{V_{p,\beta}^{l+2}(\mathbb{R}^3)} \leq c \|\Delta u\|_{V_{p,\beta}^l(\mathbb{R}^3)} + c \|u\|_{V_{p,\beta-l-2}^0(\mathbb{R}^3)}.$$

Let

$$P(\partial_{x'}, \partial_{x_3}) = -\Delta, \quad P(\partial_{x'}, \eta) = -\Delta' + \eta^2,$$

where $\Delta' = \partial_{x_1}^2 + \partial_{x_2}^2$. Let us denote by $A(\eta) : V_{p,\beta}^{l+2}(\mathbb{R}^2) \rightarrow V_{p,\beta}^l(\mathbb{R}^2)$ the operator of the problem

$$(4.8) \quad \begin{aligned} P(\partial_{x'}, \eta)u &= f && \text{in } \mathbb{R}^2, \\ u &= 0 && \text{on } S_R^1, \end{aligned}$$

where $S_R^1 = \{x' : |x'| = R\}$.

First, we consider the problem

$$(4.9) \quad \begin{aligned} P(\partial_{x'}, 0)u &= f && \text{in } \mathbb{R}^2, \\ u &= 0 && \text{on } S_R^1. \end{aligned}$$

Passing to the polar coordinates (r, φ) , next to the variable $\tau = -\ln r$ and applying the Fourier transform with respect to τ we have

$$(4.10) \quad \begin{aligned} \bar{P}(\partial_\varphi, \lambda)\tilde{u} &= \widetilde{e^{2\tau} f}, \\ u|_{\varphi=0} &= u|_{\varphi=2\pi}, \\ u_{,\varphi}|_{\varphi=0} &= u_{,\varphi}|_{\varphi=2\pi}, \end{aligned}$$

and

$$\tilde{u}(\lambda, \varphi) = \int_{\mathbb{R}^1} u(\tau, \varphi) e^{-i\lambda\tau} d\tau.$$

On the line $\text{im } \lambda = \beta - 1 \notin \mathbb{Z}$ there is no eigenvalue of problem (4.10). Moreover, $\ker A(\eta)$ and $\text{coker } A(\eta)$ are trivial in the spaces $V_{2,\beta}^0(\mathbb{R}^2)$, $\beta \notin \mathbb{Z}$. Thus the operator $A(\eta)^{-1}$ is defined in $V_{2,\beta}^0(\mathbb{R}^2)$, $\beta \notin \mathbb{Z}$.

LEMMA 4.3. *For any $\eta \in \mathbb{R}^1 \setminus \{0\}$ and any $f \in V_{2,\beta}^0(\mathbb{R}^2)$, $\beta \notin \mathbb{Z}$, the following inequality holds:*

$$(4.11) \quad \sum_{\nu=0}^2 |\eta|^\nu \|\partial_\eta^\gamma A(\eta)^{-1} f\|_{V_{2,\beta}^{2-\nu}(\mathbb{R}^2)} \leq c |\eta|^{-\gamma} \|f\|_{V_{2,\beta}^0(\mathbb{R}^2)}.$$

Proof. We have

$$\partial_\eta^\gamma A(\eta)^{-1} = \sum_{1 \leq q \leq \gamma} \sum_{\alpha_1 + \dots + \alpha_q = \gamma} c_{\alpha_1 \dots \alpha_q} A^{-1} \partial_\eta^{\alpha_1} P A^{-1} \partial_\eta^{\alpha_2} P \dots A^{-1} \partial_\eta^{\alpha_q} P A^{-1},$$

where $c_{\alpha_1 \dots \alpha_q}$ are some constant coefficients. Since

$$\sum_{\nu=0}^2 |\eta|^\nu \|u\|_{V_{2,\beta}^{2-\nu}(\mathbb{R}^2)} \leq c \|P(\partial_{x'}, \eta)u\|_{V_{2,\beta}^0(\mathbb{R}^2)},$$

and

$$\|\partial_\eta^\gamma P(\partial_{x'}, \eta)A(\eta)^{-1} f\|_{V_{2,\beta}^0(\mathbb{R}^2)} \leq c \sum_{\nu=0}^{2-\gamma} |\eta|^\nu \|A(\eta)^{-1} f\|_{V_{2,\beta}^{2-\gamma-\nu}(\mathbb{R}^2)},$$

we obtain

$$\|\partial_\eta^\gamma P(\partial_{x'}, \eta)A(\eta)^{-1} f\|_{V_{2,\beta}^0(\mathbb{R}^2)} \leq c |\eta|^{-\gamma} \|f\|_{V_{2,\beta}^0(\mathbb{R}^2)}.$$

Therefore (4.11) is proved. This concludes the proof.

LEMMA 4.4. *Let the assumptions of Lemma 4.3 be satisfied. Let σ_μ, ζ_ν be the functions introduced after Lemma 4.1. Then for all $\eta \neq 0$ the estimate*

$$(4.12) \quad \|\sigma_\mu A(\eta)^{-1} \zeta_\nu\|_{V_{2,\beta}^0(\mathbb{R}^2) \rightarrow V_{2,\beta}^0(\mathbb{R}^2)} \leq c 2^{-\varepsilon|\mu-\nu|+2\mu}$$

holds for $\beta \notin \mathbb{Z}$ and $\varepsilon > 0$ sufficiently small.

Proof. Observe that the operator $\sigma_\mu A(\eta)^{-1} \zeta_\nu$ maps functions with support in $\text{supp } \zeta_\nu$ to functions with support in $\text{supp } \sigma_\mu$.

First we examine the operator $r^{\pm\varepsilon} A(\eta) r^{\mp\varepsilon}$. Since $A(\eta) = -\Delta' + \eta^2$ and $A(\eta)$ maps $V_{2,\beta}^2(\mathbb{R}^2)$ into $V_{2,\beta}^0(\mathbb{R}^2)$ we have for small ε ,

$$\begin{aligned} \|r^{\pm\varepsilon} A(\eta) r^{\mp\varepsilon} u\|_{V_{2,\beta}^0(\mathbb{R}^2)} &= \|r^{\pm\varepsilon} (-\Delta' + \eta^2) r^{\mp\varepsilon} u\|_{V_{2,\beta}^0(\mathbb{R}^2)} \\ &\leq \|(-\Delta' + \eta^2)u\|_{V_{2,\beta}^0(\mathbb{R}^2)} + \varepsilon \|r^{\mp\varepsilon} r^{\pm\varepsilon-1} \nabla' r \nabla' u\|_{V_{2,\beta}^0(\mathbb{R}^2)} \\ &\quad + \varepsilon(1-\varepsilon) \|r^{\mp\varepsilon} r^{\pm\varepsilon-2} |\nabla' r|^2 u\|_{V_{2,\beta}^0(\mathbb{R}^2)} + \varepsilon \|r^{\mp\varepsilon} r^{\pm\varepsilon-1} \Delta' r u\|_{V_{2,\beta}^0(\mathbb{R}^2)} \\ &\leq \|A(\eta)u\|_{V_{2,\beta}^0(\mathbb{R}^2)} + c\varepsilon \|u\|_{V_{2,\beta-1}^1(\mathbb{R}^2)}. \end{aligned}$$

Conversely,

$$\begin{aligned} \|A(\eta)u\|_{V_{2,\beta}^0(\mathbb{R}^2)} &= \|r^{\mp\epsilon} r^{\pm\epsilon} A(\eta)u\|_{V_{2,\beta}^0(\mathbb{R}^2)} \\ &= \|r^{\mp\epsilon} r^{\pm\epsilon} (-\Delta' + \eta^2)u\|_{V_{2,\beta}^0(\mathbb{R}^2)} \\ &\leq \|r^{\mp\epsilon} (-\Delta' + \eta^2)r^{\pm\epsilon}u\|_{V_{2,\beta}^0(\mathbb{R}^2)} + c\epsilon \|u\|_{V_{2,\beta-1}^1(\mathbb{R}^2)}. \end{aligned}$$

Hence for small ϵ , the norms of the operators $r^{\pm\epsilon} A(\eta)r^{\mp\epsilon}$ and $A(\eta)$ are close to each other because

$$\left| \sup_{\|u\|_{V_{2,\beta}^2(\mathbb{R}^2)} \leq 1} \|r^{\pm\epsilon} A(\eta)r^{\mp\epsilon}u\|_{V_{2,\beta}^0(\mathbb{R}^2)} - \sup_{\|u\|_{V_{2,\beta}^0(\mathbb{R}^2)} \leq 1} \|A(\eta)u\|_{V_{2,\beta}^0(\mathbb{R}^2)} \right| \leq c\epsilon.$$

Therefore for $\beta \pm \epsilon \notin \mathbb{Z}$ and ϵ sufficiently small the operator $A(\eta)$ is an isomorphism from $V_{2,\beta \pm \epsilon}^2(\mathbb{R}^2)$ into $V_{2,\beta \pm \epsilon}^0(\mathbb{R}^2)$. Let $u_\mu = u\sigma_\mu$ and $f_\nu = f\zeta_\nu$. Then we examine the problem

$$(4.13) \quad P(\partial_{x'}, \eta)u = f_\nu.$$

Since the operator $A(\eta)^{-1}$ is defined we have

$$(4.14) \quad u_\mu = \sigma_\mu A^{-1}(\eta)f_\nu.$$

In view of (4.11) we obtain

$$\begin{aligned} \|u_\mu\|_{V_{2,\beta}^2(\mathbb{R}^2)} &\leq c2^{\epsilon\mu} \|u_\mu\|_{V_{2,\beta-\epsilon}^2(\mathbb{R}^2)} \\ &\leq c2^{\epsilon\mu} \|f_\nu\|_{V_{2,\beta-\epsilon}^0(\mathbb{R}^2)} \leq c2^{\epsilon(\mu-\nu)} \|f_\nu\|_{V_{2,\beta}^0(\mathbb{R}^2)}. \end{aligned}$$

Since

$$\|u_\mu\|_{V_{2,\beta}^2(\mathbb{R}^2)} \geq c2^{-2\mu} \|u_\mu\|_{V_{2,\beta}^0(\mathbb{R}^2)}$$

we obtain

$$\|u_\mu\|_{V_{2,\mu}^0(\mathbb{R}^2)} \leq c2^{\epsilon(\mu-\nu)+2\mu} \|f_\nu\|_{V_{2,\beta}^0(\mathbb{R}^2)},$$

where for $\mu > \nu$ we replace ϵ by $-\epsilon$, $\epsilon > 0$ and for $\mu < \nu$ we take ϵ . Then we have

$$(4.15) \quad \|u_\mu\|_{V_{2,\beta}^0(\mathbb{R}^2)} \leq c2^{-\epsilon|\mu-\nu|+2\mu} \|f_\nu\|_{V_{2,\beta}^0(\mathbb{R}^2)}.$$

From (4.15) we derive (4.12). This concludes the proof.

LEMMA 4.5. *Let the assumptions of Lemma 4.4 be satisfied. Then the operator P of the problem*

$$(4.16) \quad \begin{aligned} P(\partial_{x'}, \partial_{x_3})u &= f, \\ u|_{S_R} &= 0 \end{aligned}$$

is an isomorphism

$$(4.17) \quad P : V_{2,\beta}^2(\mathbb{R}^3) \rightarrow V_{2,\beta}^0(\mathbb{R}^3).$$

The lemma follows from the estimate

$$\|u\|_{V_{2,\beta}^2(\mathbb{R}^3)} \leq c\|f\|_{V_{2,\beta}^0(\mathbb{R}^3)}, \quad \beta \notin \mathbb{Z},$$

and the fact that $\ker P$ in $V_{2,\beta}^2(\mathbb{R}^3)$ and $\text{coker } P$ in $V_{2,\beta}^0(\mathbb{R}^3)$ are trivial.

To prove the next lemma we need the following Marcinkiewicz–Mikhlin type result (see [2, Ch. 11, §11]):

LEMMA 4.6. *Let $L_p(\mathbb{R}^d; H)$ be the space of functions with the finite norm*

$$\|f\|_{L_p(\mathbb{R}^d; H)} = \left(\int_{\mathbb{R}^d} \|f(z)\|_H^p dz \right)^{1/p} < \infty,$$

where H is a Hilbert space. Let $M(\xi)$, $\xi \in \mathbb{R}^d$, be a bounded function in \mathbb{R}^d acting as a multiplier. Let for $s = 0, \dots, d$, $i_k \neq i_l$,

$$|\xi|^s \left\| \frac{\partial^s M}{\partial \xi_{i_1} \dots \partial \xi_{i_s}}(\xi) \right\|_{H \rightarrow H} \leq \text{const}.$$

Then $F_{\xi \rightarrow z}^{-1} M(\xi) F_{z \rightarrow \xi}$, where F is the Fourier transform in \mathbb{R}^d , is a continuous operator in $L_p(\mathbb{R}^d; H)$.

LEMMA 4.7. *Let the assumptions of Lemma 4.3 be satisfied. Let $u_\nu \in V_{2,\beta}^2(\mathbb{R}^3)$ be a solution to the problem*

$$P(\partial_{x'}, \partial_{x_3})u_\nu = \zeta_\nu f.$$

Then

$$(4.18) \quad \int_{\mathbb{R}^1} \left(\int_{\mathbb{R}^2} r^{2\beta} |\sigma_\mu(x') u_\nu(x', x_3)|^2 dx' \right)^{p/2} dx_3 \\ \leq c 2^{-p\varepsilon|\mu-\nu|+2\mu p} \int_{\mathbb{R}^1} \left(\int_{\mathbb{R}^2} r^{2\beta} |\zeta_\nu(x') f(x', x_3)|^2 dx' \right)^{p/2} dx_3,$$

where c does not depend on u and f .

Proof. We have

$$u_\nu = F_{\eta \rightarrow x_3}^{-1} A(\eta)^{-1} F_{x_3 \rightarrow \eta} \zeta_\nu f,$$

where F is the Fourier transform in \mathbb{R}^1 .

By Lemma 4.6 $F_{\eta \rightarrow x_3}^{-1} M(\eta) F_{x_3 \rightarrow \eta}$, where $M(\eta) = \sigma_\mu A(\eta)^{-1} \zeta_\nu$, is a continuous operator in $L_p(\mathbb{R}^1; V_{2,\beta}^0(\mathbb{R}^2))$. Then by (4.12) we obtain (4.18). This concludes the proof.

LEMMA 4.8. *Let the assumptions of Lemma 4.3 be satisfied. Let u_ν be defined in the assumptions of Lemma 4.7. Then for $p \geq 2$ we have*

$$(4.19) \quad \int_{\mathbb{R}^3} r^{p(\beta-1)-2} |\zeta_\mu(x') u_\nu(x', x_3)|^p dx' dx_3 \\ \leq c 2^{-\varepsilon|\mu-\nu|p} \int_{\mathbb{R}^3} r^{p(\beta+1)-2} |\zeta_\nu(x') f(x', x_3)|^p dx' dx_3,$$

where c does not depend on u and f .

Proof. By the Hölder inequality the r.h.s. of (4.18) is estimated by

$$(4.20) \quad c 2^{-p\varepsilon|\mu-\nu|+2\mu p} \int_{\mathbb{R}^1} dx_3 \left[|\text{supp } \zeta_\nu|^{(p-2)/p} \left(\int_{\mathbb{R}^2} r^{p\beta} |\zeta_\nu f|^p dx' \right)^{2/p} \right]^{p/2} \\ \leq c 2^{-p\varepsilon|\mu-\nu|+2\mu p} \int_{\mathbb{R}^1} dx_3 2^{\nu(p-2)} \int_{\mathbb{R}^2} r^{p\beta} |\zeta_\nu f|^p dx' \\ \leq c 2^{-p\varepsilon|\mu-\nu|+2\mu p} \int_{\mathbb{R}^1} dx_3 \int_{\mathbb{R}^2} r^{p(\beta+1)-2} |\zeta_\nu f|^p dx',$$

where we used that on $\text{supp } \zeta_\nu$ we have $r \in (2^{\nu-1}, 2^{\nu+1})$.

Divide \mathbb{R}^1 into segments Q_j of length 2^μ each. By $2Q_j$ we denote a segment with length $2^{\mu+1}$ which contains Q_j .

By the Hölder inequality we have

$$\int_{2Q_j} \int_{\mathbb{R}^2} |\sigma_\mu u_\nu| dx' dx_3 \leq \int_{2Q_j} |\text{supp } \sigma_\mu|^{1/2} \left(\int_{\mathbb{R}^2} |\sigma_\mu u_\nu|^2 dx' \right)^{1/2} dx_3 \\ \leq c \int_{2Q_j} 2^\mu dx_3 \left(\int_{\mathbb{R}^2} |\sigma_\mu u_\nu|^2 dx' \right)^{1/2} \equiv I_1,$$

where we used that

$$(4.21) \quad \text{supp } \sigma_\mu \subset \{x' \in \mathbb{R}^2 : 2^{\mu-2} < |x'| < 2^{\mu+2}\}.$$

Continuing,

$$I_1 \leq c \int_{2Q_j} 2^{\mu-\beta\mu} \left(\int_{\mathbb{R}^2} r^{2\beta} |\sigma_\mu u_\nu|^2 dx' \right)^{1/2} dx_3 \equiv I_2,$$

where we used (4.21) again. Continuing,

$$\left(\int_{2Q_j} \int_{\mathbb{R}^2} |\sigma_\mu u_\nu| dx' dx_3 \right)^p \leq 2^{(1-\beta)\mu p} \left[\int_{2Q_j} dx_3 \left(\int_{\mathbb{R}^2} r^{2\beta} |\sigma_\mu u_\nu|^2 dx' \right)^{1/2} \right]^p \\ \leq c 2^{(1-\beta)\mu p} \left(\int_{2Q_j} 1^{p'} dx_3 \right)^{p/p'} \left(\int_{2Q_j} dx_3 \left(\int_{\mathbb{R}^2} r^{2\beta} |\sigma_\mu u_\nu|^2 dx' \right)^{p/2} \right) \equiv I_3,$$

where $1/p + 1/p' = 1$, $p/p' = p - 1$. Hence, we have

$$I_3 = c 2^{(1-\beta)\mu p + \mu(p-1)} \int_{2Q_j} dx_3 \left(\int_{\mathbb{R}^3} r^{2\beta} |\sigma_\mu u_\nu|^2 dx' \right)^{p/2}.$$

Therefore, we get

$$(4.22) \quad \left(\int_{2Q_j} \int_{\mathbb{R}^2} |\sigma_\mu u_\nu| dx' dx_3 \right)^p \leq c 2^{-\mu p(\beta-2)-\mu} \int_{2Q_j} dx_3 \left(\int_{\mathbb{R}^2} r^{2\beta} |\sigma_\mu u_\nu|^2 dx' \right)^{p/2}.$$

From Lemma 4.1 for $|\mu - \nu| > 3$ we obtain the inequality

$$(4.23) \quad \int_{Q_j} \int_{\mathbb{R}^2} |\zeta_\mu u_\nu|^p dx' dx_3 \leq c 2^{3\mu(1-p)} \left(\int_{2Q_j} \int_{\mathbb{R}^2} |\sigma_\mu u_\nu| dx' dx_3 \right)^p$$

by a scaling argument.

From (4.22) and (4.23) and for $|\mu - \nu| > 3$ we obtain

$$(4.24) \quad \int_{\mathbb{R}^3} |\zeta_\mu u_\nu|^p dx' dx_3 \leq c 2^{2\mu - \mu p(\beta-1)} \int_{\mathbb{R}} \left(\int_{\mathbb{R}^2} r^{2\beta} |\sigma_\mu u_\nu|^2 dx' \right)^{p/2} dx_3.$$

In the case $|\mu - \nu| \leq 3$ we have to add on the r.h.s. of (4.22) the expression

$$c 2^{2\mu p} \int_{2Q_j} \int_{\mathbb{R}^2} |\zeta_\nu f|^p dx' dx_3.$$

Hence, in this case, we have to add the same term on the r.h.s. of (4.24). Using (4.18) we obtain (4.19). This concludes the proof.

To prove the next lemma we need a result on operators in Banach spaces. Let $\mathcal{E}_0(\mathbb{R}^3), \mathcal{E}_1(\mathbb{R}^3)$ be Banach spaces of functions defined on \mathbb{R}^3 , closed under pointwise multiplication with functions from $C_0^\infty(\mathbb{R}^2 \setminus \{0\})$. Let $\{\zeta_j\}_{j=-\infty}^\infty$ be the partition of unity described above.

Assume that there exist p and q , $1 \leq p \leq q \leq \infty$, such that for all $u \in \mathcal{E}_0$, $v \in \mathcal{E}_1$ the following inequalities hold:

$$(4.25) \quad \|u\|_{\mathcal{E}_0} \leq c \left(\sum_{j=-\infty}^\infty \|\zeta_j u\|_{\mathcal{E}_0}^q \right)^{1/q},$$

$$(4.26) \quad \|v\|_{\mathcal{E}_1} \geq c \left(\sum_{j=-\infty}^\infty \|\zeta_j v\|_{\mathcal{E}_1}^p \right)^{1/p},$$

where $\|\cdot\|_{\mathcal{E}_i}$ is the norm of \mathcal{E}_i , $i = 0, 1$.

LEMMA 4.9. *Let $\theta : \mathcal{E}_1 \rightarrow \mathcal{E}_0$ be a linear operator defined on functions with compact supports such that for some $\varepsilon > 0$ and all $\mu, \nu \in \mathbb{Z}$,*

$$(4.27) \quad \|\zeta_\mu \theta \zeta_\nu v\|_{\mathcal{E}_0} \leq c e^{-\varepsilon|\mu-\nu|} \|\zeta_\nu v\|_{\mathcal{E}_1}$$

for all $v \in \mathcal{E}_1(\mathbb{R}^3)$. Then for any $v \in \mathcal{E}_1(\mathbb{R}^3)$ with compact support,

$$(4.28) \quad \|\theta v\|_{\mathcal{E}_0(\mathbb{R}^3)} \leq c \|v\|_{\mathcal{E}_1(\mathbb{R}^3)},$$

where c does not depend on v .

Proof. From (4.25),

$$\begin{aligned} \|\theta v\|_{\mathcal{E}_0(\mathbb{R}^3)} &= \left\| \theta \left(\sum_{\nu=-\infty}^{\infty} \zeta_{\nu} v \right) \right\|_{\mathcal{E}_0(\mathbb{R}^3)} \leq c \left(\sum_{\mu=-\infty}^{\infty} \left\| \sum_{\nu=-\infty}^{\infty} \xi_{\mu} \theta \xi_{\nu} v \right\|_{\mathcal{E}_0(\mathbb{R}^3)}^q \right)^{1/q} \\ &\leq c \left[\sum_{\mu=-\infty}^{\infty} \left(\sum_{\nu=-\infty}^{\infty} \|\xi_{\mu} \theta \xi_{\nu} v\|_{\mathcal{E}_0(\mathbb{R}^3)} \right)^q \right]^{1/q}. \end{aligned}$$

Applying (4.27) yields

$$\|\theta v\|_{\mathcal{E}_0(\mathbb{R}^3)} \leq c \sum_{\mu=-\infty}^{\infty} \left(\sum_{\nu=-\infty}^{\infty} e^{-\varepsilon|\mu-\nu|} \|\zeta_{\nu} v\|_{\mathcal{E}_1(\mathbb{R}^3)} \right)^q \Big]^{1/q}.$$

Since the operator of discrete convolution with the kernel $\{e^{-|j|\varepsilon}\}_{j=-\infty}^{\infty}$ is continuous from l_p to l_q for $q \geq p$, we have

$$\|\theta v\|_{\mathcal{E}_0(\mathbb{R}^3)} \leq c \left(\sum_{\nu=-\infty}^{\infty} \|\zeta_{\nu} v\|_{\mathcal{E}_1(\mathbb{R}^3)}^p \right)^{1/p}.$$

Using now (4.26) we obtain (4.28). This concludes the proof.

LEMMA 4.10. *Let the assumptions of Lemma 4.4 be satisfied. Let $u \in V_{2,\beta}^2(\mathbb{R}^3)$ be a solution of problem (4.16). Then for $p \geq 2$ the inequality*

$$(4.29) \quad \int_{\mathbb{R}^3} r^{p(\beta-1)-2} |u(x', x_3)|^p dx' dx_3 \leq c \int_{\mathbb{R}^3} r^{p(\beta+1)-2} |f(x', x_3)|^p dx' dx_3$$

is valid, where c does not depend on u and f .

Proof. We apply Lemma 4.9 to the inequality of Lemma 4.8 with $q = p$, $\mathcal{E}_0 = V_{p,\beta-1-2/p}^0(\mathbb{R}^3)$, $\mathcal{E}_1 = V_{p,\beta+1-2/p}^0(\mathbb{R}^3)$ and $\theta : V_{2,\beta}^0(\mathbb{R}^3) \rightarrow V_{2,\beta}^2(\mathbb{R}^3)$ is the inverse to the operator of problem (4.16). Then (4.19) becomes the inequality (4.27). Then Lemma 4.9 implies (4.28), which is exactly (4.29). This concludes the proof.

LEMMA 4.11. *Let the assumptions of Lemma 4.4 hold. Let $f \in V_{2,\varkappa}^l(\mathbb{R}^3) \cap V_{p,\varkappa}^l(\mathbb{R}^3)$, $p \geq 2$. Then for solutions $u \in V_{2,\varkappa}^{l+2}(\mathbb{R}^3)$ of problem (4.16) the following inequality is valid:*

$$(4.30) \quad \|u\|_{V_{p,\varkappa}^{l+2}(\mathbb{R}^3)} \leq c \|f\|_{V_{p,\varkappa}^l(\mathbb{R}^3)},$$

where c does not depend on u and f .

Proof. From (4.7) with $\beta = \varkappa$ we have

$$\|u\|_{V_{p,\varkappa}^{l+2}(\mathbb{R}^3)} \leq c (\|f\|_{V_{p,\varkappa}^l(\mathbb{R}^3)} + \|u\|_{V_{p,\varkappa-l-2}^0(\mathbb{R}^3)}).$$

From Lemma 4.10 and from the assumption that $f \in V_{p,\varkappa-l}^0$ we have $p(\beta+1) - 2 = p(\varkappa - l)$, so $\beta = \varkappa - l - 1 + 2/p$, so $p(\beta - 1) - 2 = p(\varkappa - l - 2)$. Hence,

$$\|u\|_{V_{p,\kappa-l-2}^0(\mathbb{R}^3)} \leq c\|f\|_{V_{p,\kappa-l}^0(\mathbb{R}^3)} \leq c\|f\|_{V_{p,\kappa}^l(\mathbb{R}^3)}.$$

Thus (4.30) holds. This concludes the proof.

THEOREM 4.1. *Let $\text{Im } \lambda = \beta - 1 \notin \mathbb{Z}$. Let $f \in V_{p,\beta}^l(\mathbb{R}^3)$, $l \in \mathbb{N}$, $p \in (1, \infty)$, $\beta \in \mathbb{R}$. Then there exists a solution to problem (4.1) such that $u \in V_{p,\beta}^{l+2}(\mathbb{R}^3)$ and*

$$(4.31) \quad \|u\|_{V_{p,\beta}^{l+2}(\mathbb{R}^3)} \leq c\|f\|_{V_{p,\beta}^l(\mathbb{R}^3)},$$

where c does not depend on u and f .

Proof. Let $\{f_\nu\}$ be a sequence of smooth functions with compact support in $\mathbb{R}^3 \setminus L$ which converges to f in $V_{p,\beta}^l(\mathbb{R}^3)$. By Lemma 4.5 there exists a solution $u_\nu \in V_{2,\beta}^{l+2}(\mathbb{R}^3)$ to problem (4.1) with r.h.s. f_ν . From (4.30) the sequence $\{u_\nu\}$ converges in $V_{p,\beta}^{l+2}(\mathbb{R}^3)$. This concludes the proof.

5. Existence in a bounded domain

Proof of Theorem 1.1. To prove Theorem 1.1 we introduce a partition of unity (see [7]). We distinguish four types of subdomains: $\Omega^{(1)}$ —near an interior point of $\Omega \cap L$, $\Omega^{(2)}$ —near the point where L meets S , $\Omega^{(3)}$ —near an interior point of Ω but at a positive distance from L , $\Omega^{(4)}$ —near a point of S at a positive distance from L . With each subdomain $\Omega^{(k)}$, $k = 1, 2, 3, 4$, we connect a smooth function $\zeta^{(k)}$ which is equal to 1 in $\bar{w}^{(k)} \subset \Omega^{(k)}$ and vanishes outside of $\Omega^{(k)}$.

We shall restrict our considerations to problem (3.2) only, because problem (3.5) can be treated in the same way.

Let us extend the boundary condition (3.2)₂ by introducing a function \tilde{b} such that

$$(5.1) \quad \bar{n} \cdot \nabla \tilde{b} = b.$$

Then the function

$$(5.2) \quad u = \varphi - \tilde{b}$$

is a solution to the problem

$$(5.3) \quad \begin{aligned} \Delta u &= f && \text{in } \Omega, \\ \bar{n} \cdot \nabla u|_S &= 0, \end{aligned}$$

where $f = -\Delta \tilde{b}$. Multiplying (5.3)₁ by $\zeta^{(1)}$ and defining $u^{(1)} = u\zeta^{(1)}$, $f^{(1)} = f \cdot \zeta^{(1)}$ we obtain, instead of (5.3), the problem

$$(5.4) \quad \begin{aligned} \Delta u^{(1)} &= f^{(1)} + 2\nabla \zeta^{(1)} \nabla u + \Delta \zeta^{(1)} u, \\ u^{(1)}|_{\partial\Omega^{(1)}} &= 0. \end{aligned}$$

Multiplying (5.3) by $\zeta^{(2)}$ we obtain

$$(5.5) \quad \begin{aligned} \Delta u^{(2)} &= f^{(2)} + 2\nabla\zeta^{(2)}\nabla u + \Delta\zeta^{(2)}u && \text{in } \Omega^{(2)} \times (0, T), \\ \bar{n} \cdot \nabla u^{(2)} &= u\bar{n} \cdot \nabla\zeta^{(2)} && \text{on } S \cap \bar{\Omega}^{(2)}. \end{aligned}$$

Let us introduce a local coordinate system $y = \{y_1, y_2, y_3\}$ with the origin at the point where L meets S and such that $y_3 > 0$ describes points inside Ω . Let $S^{(2)} = S \cap \bar{\Omega}^{(2)}$ be described by the relation

$$(5.6) \quad y_3 = F(y_1, y_2).$$

Introducing new coordinates

$$(5.7) \quad \begin{aligned} z_i &= y_i, & i &= 1, 2, \\ z_3 &= y_3 - F(y_1, y_2), \end{aligned}$$

we define a mapping $z = \Phi(y)$.

If problem (3.2) is formulated in coordinates $x = \{x_1, x_2, x_3\}$ we can pass to coordinates $y = \{y_1, y_2, y_3\}$ by a rotation and a translation. We denote this mapping by $y = Y(x)$. Hence

$$(5.8) \quad \begin{aligned} z &= (\Phi \circ Y)(x) \equiv \Psi(x), \\ \hat{\Omega}^{(2)} &= \Psi(\Omega^{(2)}), & \hat{S}^{(2)} &= \Psi(S^{(2)}). \end{aligned}$$

Introducing the notation

$$\begin{aligned} \tilde{u}^{(2)}(z) &= u^{(2)}(\Psi^{-1}(z)), & \tilde{u}(z) &= u(\Psi^{-1}(z)), \\ \nabla_{\Psi} &= \frac{\partial z}{\partial x} \Big|_{x=\Psi^{-1}(z)} \cdot \nabla_z = \Psi_x|_{x=\Psi^{-1}(z)} \cdot \nabla_z, \\ \bar{n}_z &= (0, 0, 1), & \bar{n}_{\Psi} &= (F_{y_1}, F_{y_2}, -1)|_{y=\Phi^{-1}(z)}, \end{aligned}$$

we can express problem (5.5) in the form

$$(5.9) \quad \begin{aligned} \nabla_z^2 \tilde{u}^{(2)} &= (\nabla_z^2 - \nabla_{\Psi}^2) \tilde{u}^{(2)} + 2\nabla_{\Psi} \tilde{\zeta}^{(2)} \nabla_{\Psi} \tilde{u} + \nabla_{\Psi}^2 \tilde{\zeta}^{(2)} \tilde{u} && \text{in } \hat{\Omega}^{(2)}, \\ \bar{n}_z \cdot \nabla_z \tilde{u}^{(2)} &= (\bar{n}_z - \bar{n}_{\Psi}) \cdot \nabla_z \tilde{u}^{(2)} + \bar{n}_{\Psi} \cdot \nabla_z \tilde{\zeta}^{(2)} \tilde{u} && \text{on } \hat{S}^{(2)}. \end{aligned}$$

Let $\tilde{\eta}^{(2)}$ be a function such that

$$(5.10) \quad \frac{\partial}{\partial z_3} \tilde{\eta}^{(2)} \Big|_{z_3=0} = (\bar{n}_z - \bar{n}_{\Psi}) \cdot \nabla_z \tilde{u}^{(2)} + \tilde{u} \bar{n}_{\Psi} \cdot \nabla_z \tilde{\zeta}^{(2)}.$$

Then the function

$$(5.11) \quad \tilde{\psi}^{(2)} = \tilde{u}^{(2)} - \tilde{\eta}^{(2)}$$

is a solution to the problem

$$\begin{aligned}
 \nabla_z^2 \tilde{\psi}^{(2)} &= \Delta \tilde{\eta}^{(2)} + (\nabla_z^2 - \nabla_{\Psi}^2) \tilde{u}^{(2)} + 2\nabla_{\Psi} \tilde{\zeta}^{(2)} \nabla_{\Psi} \tilde{u} \\
 &\quad + \nabla_{\Psi}^2 \tilde{\zeta}^{(2)} \tilde{u} \equiv \tilde{F}^{(2)} \quad \text{in } \hat{\Omega}^{(2)}, \\
 (5.12) \quad \frac{\partial}{\partial z_3} \tilde{\psi}^{(2)} \Big|_{z_3=0} &= 0, \\
 \tilde{\psi}^{(2)} \Big|_{\partial \hat{\Omega}^{(2)} \setminus \{z: z_3=0\}} &= 0,
 \end{aligned}$$

where

$$\hat{\Omega}^{(2)} = \{z \in \mathbb{R}^3 : (z_1^2 + z_2^2)^{1/2} < R, 0 < z_3 < a, \varphi_z \in [0, 2\pi]\},$$

$\varphi_z = \arctg(\frac{z_2}{z_1})$. After reflection with respect to the plane $z_3 = 0$ problem (5.12) assumes the form

$$\begin{aligned}
 (5.13) \quad -\nabla_z^2 \tilde{\psi}'^{(2)} &= \tilde{F}'^{(2)}, \\
 \tilde{\psi}'^{(2)} \Big|_{\partial \hat{\Omega}'^{(2)}} &= 0,
 \end{aligned}$$

where η' means that $\eta'(z', z_3) = \eta(z', z_3)$ for $z_3 > 0$, $z' = (z_1, z_2)$ and $\eta'(z', z_3) = \eta(z', -z_3)$ for $z_3 < 0$, and

$$\hat{\Omega}'^{(2)} = \{z \in \mathbb{R}^3 : (z_1^2 + z_2^2)^{1/2} < R, -a < z_3 < a, \varphi_z \in [0, 2\pi]\}.$$

Applying Lemma 4.11 we obtain for solutions to problems (5.4) and (5.13) the estimate

$$\begin{aligned}
 (5.14) \quad \|u^{(k)}\|_{V_{p,-\mu}^{l+2}(\Omega)} &\leq c \|f^{(k)}\|_{V_{p,-\mu}^l(\Omega)} \\
 &\quad + c(\|\nabla u\|_{V_{p,-\mu}^l(\Omega \cap \Omega^{(k)})} + \|u\|_{V_{p,-\mu}^l(\Omega \cap \Omega^{(k)})}),
 \end{aligned}$$

where $k = 1, 2$ and in the case of problem (5.13) we used that $\text{diam } \Omega^{(2)}$ is sufficiently small.

In the case of the subdomains $\Omega^{(3)}$ and $\Omega^{(4)}$ we obtain problems similar to (5.4) and (5.9). Then instead of (5.14) we get

$$(5.15) \quad \|u^{(k)}\|_{W_p^{l+2}(\Omega)} \leq c \|f^{(k)}\|_{W_p^l(\Omega)} + c(\|\nabla u\|_{W_p^l(\Omega^{(k)})} + \|u\|_{W_p^l(\Omega^{(k)})}).$$

Moreover, for solutions to problem (5.3) we have

$$(5.16) \quad \|u\|_{W_p^{l+2}(\Omega)} \leq c \|f\|_{W_p^l(\Omega)}.$$

Let $\mu \in (0, 1)$. Then summing up inequalities (5.14) and (5.15) and applying the Hardy inequality with estimate (5.16) to the last two terms on the r.h.s. of (5.15) we obtain

$$(5.17) \quad \|u\|_{V_{p,-\mu}^{l+2}(\Omega)} \leq c \|f\|_{V_{p,-\mu}^l(\Omega)}.$$

Now let $\mu \in (1, 2)$. Then the last two terms on the r.h.s. of (5.14) can be estimated in view of the Hardy inequality and (5.17). Repeating the other arguments we obtain (5.17) for $\mu \in (1, 2)$.

Continuing the above considerations and assuming that $u \in V_{p,-\mu}^{l+2}(\Omega)$, $\mu \in (k-1, k)$ we obtain (5.17) for $\mu \in (k, k+1)$, $k \in \mathbb{N}$.

Repeating the above considerations for problem (3.5) we obtain by (3.1) the following estimate for solutions to problem (1.1):

$$(5.18) \quad \|v\|_{V_{p,-\mu}^{l+1}(\Omega)} \leq c(\|w\|_{V_{p,-\mu}^l(\Omega)} + \|b\|_{V_{p,-\mu}^{l+1-1/p}(S)}).$$

This holds for smooth functions vanishing sufficiently fast near L .

To prove Theorem 1.1 we use Theorem 1.2. Let (w_ν, b_ν) be a sequence of smooth functions with compact support in $\bar{\Omega} \setminus L$ which converges to $(w, b) \in V_{p,-\mu}^k(\Omega) \times V_{p,-\mu}^{k+1-1/p}(S)$. In view of Theorem 1.2 we have the existence of an approximate solution of the problem

$$(5.19) \quad \begin{aligned} \operatorname{rot} v_\nu &= w_\nu, \\ \operatorname{div} v_\nu &= 0, \\ \bar{n} \cdot v_\nu &= b_\nu. \end{aligned}$$

By Theorem 1.2 there exists a solution to problem (5.19) such that $v_\nu \in H_{-\mu}^{l+2}(\Omega)$ with r.h.s. equal to w_ν and b_ν . Using estimate (5.18) we find that the sequence converges in $V_{p,-\mu}^{l+2}(\Omega)$ and (1.4) holds. This concludes the proof.

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