Liftings of forms to Weil bundles and the exterior derivative

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Abstract. In a previous paper we have given a complete description of linear liftings of *p*-forms on *n*-dimensional manifolds M to *q*-forms on T^AM , where T^A is a Weil functor, for all non-negative integers n, p and q, except the case p = n and q = 0. We now establish formulas connecting such liftings and the exterior derivative of forms. These formulas contain a boundary operator, which enables us to define a homology of the Weil algebra A. We next study the case p = n and q = 0 under the condition that A is acyclic. Finally, we compute the kernels and the images of the boundary operators for the Weil algebras \mathbb{D}_k^r and show that these algebras are acyclic.

Linear liftings of forms to Weil bundles. There is a well known oneto-one correspondence between product preserving bundle functors, which are also called Weil functors or Weil bundles, and Weil algebras ([4], [7], [10]). Consequently, one may try to describe some natural operators transforming sections of a natural bundle into sections of another natural bundle over a Weil bundle (we call natural operators of this kind simply liftings) in terms of the corresponding Weil algebra (see [9] for the general theory of natural operators). In particular, liftings of forms to Weil bundles have been studied by several authors (see for instance [5], [6], [11], [12], [3], [1]).

In this section we briefly recall basic definitions and results of [1], as they are the starting point of the present paper.

We will denote by F_pM the vector space of *p*-forms on a manifold *M*. Let *A* be a Weil algebra and T^A the Weil functor corresponding to *A* (see [9]). Fix non-negative integers *n*, *p* and *q*. A *linear lifting of p-forms to q-forms* on T^A is, by definition, a system of linear maps $L_M : F_pM \to F_q(T^AM)$ indexed by *n*-dimensional manifolds and satisfying for all such manifolds *M* and *N*, every embedding $f : M \to N$ and every $\omega \in F_pN$ the condition

(1)
$$L_M(f^*\omega) = (T^A f)^* (L_N(\omega)).$$

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If s is a non-negative integer, then we will use the symbol C_sA to denote the vector space of skew-symmetric s-linear maps $G : A \times \cdots \times A \to A^*$ (where A^* denotes the vector space of linear functions $A \to \mathbb{R}$) satisfying

(2)
$$G(a_1, \ldots, a_{s-1}, bc)(d) = G(a_1, \ldots, a_{s-1}, b)(cd) + G(a_1, \ldots, a_{s-1}, c)(bd)$$

for all $a_1, \ldots, a_{s-1}, b, c, d \in A$ whenever $s \ge 1$.

Suppose $p \ge q$ and $D \in C_{p-q}A$. There is a unique linear lifting $D^{p,q}$ of p-forms to q-forms on T^A such that

(3)
$$D_U^{p,q}(\omega)(X)(Y_1,\ldots,Y_q)$$

= $D(X^{i_{q+1}},\ldots,X^{i_p})(((T^A\omega_{i_1\ldots i_p})(X))Y_1^{i_1}\ldots Y_q^{i_q})$

for every open subset U of \mathbb{R}^n , every $\omega \in F_p U$, every $X \in T^A U$ and all $Y_1, \ldots, Y_q \in A^n$, where the coordinates $\omega_{i_1 \ldots i_p} : U \to \mathbb{R}$ for $i_1, \ldots, i_p \in \{1, \ldots, n\}$ are such that $\omega(x)(y_1, \ldots, y_p) = \omega_{i_1 \ldots i_p}(x)y_1^{i_1} \ldots y_p^{i_p}$ for every $x \in U$ and all $y_1, \ldots, y_p \in \mathbb{R}^n$ (formula (3) makes sense, because $T^A \mathbb{R}^n = A^n$ and $T^A U$ is an open subset of the vector space A^n , so $D_U^{p,q}(\omega)(X)$ can be interpreted as a skew-symmetric q-linear map $A^n \times \cdots \times A^n \to \mathbb{R}$).

If $p+1 \ge q$ and $E \in C_{p-q+1}A$, then $E^{p+1,q} \circ d$ (where d denotes the exterior derivative) is another linear lifting of p-forms to q-forms on T^A . The main theorem of [1] states that every linear lifting of p-forms to q-forms on T^A is of the form specified in the table below for almost all n, p and q, where $D \in C_{p-q}A$ and $E \in C_{p-q+1}A$ are uniquely determined.

	$0 \leq p \leq n-1$	p = n	$n+1 \le p$
q = 0	$D^{p,0}$		0
$1 \leq q \leq p$	$D^{p,q} + E^{p+1,q} \circ d$	$D^{n,q}$	0
q = p + 1	$E^{p+1,p+1} \circ d$	0	0
$p+2 \leq q$	0	0	0

The case p = n and q = 0 was omitted in [1], because it is more difficult than the others. In what follows we prove Theorem 2, which covers this unusual case.

A homology of the algebra A. If $p \ge q - 1 \ge 0$ and $F \in C_{p-q+1}A$ then $d \circ F^{p,q-1}$ is a linear lifting of p-forms to q-forms on T^A , and so it is of the form specified in the above table with some D and E determined by F. In the next section we will establish explicit formulas for $d \circ F^{p,q-1}$. They will contain a boundary operator, which we now define. For every positive integer s and every $G \in C_s A$ we define the skewsymmetric (s-1)-linear map $\partial_s G : A \times \cdots \times A \to A^*$ by

$$(\partial_s G)(a_1, \dots, a_{s-1})(b) = G(a_1, \dots, a_{s-1}, b)(1)$$

for all $a_1, \ldots, a_{s-1}, b \in A$. We will have $\partial_s G \in C_{s-1}A$ once we check that

$$(\partial_s G)(a_1, \dots, a_{s-2}, bc)(d) = (\partial_s G)(a_1, \dots, a_{s-2}, b)(cd) + (\partial_s G)(a_1, \dots, a_{s-2}, c)(bd)$$

for all $a_1, \ldots, a_{s-2}, b, c, d \in A$ whenever $s \ge 2$. By (2) and the skew-symmetry of G,

$$\begin{aligned} (\partial_s G)(a_1, \dots, a_{s-2}, bc)(d) &= G(a_1, \dots, a_{s-2}, bc, d)(1) \\ &= G(a_1, \dots, a_{s-2}, b, d)(c) + G(a_1, \dots, a_{s-2}, c, d)(b) \\ &= G(a_1, \dots, a_{s-2}, b, c)(d) + G(a_1, \dots, a_{s-2}, b, d)(c) \\ &+ G(a_1, \dots, a_{s-2}, c, b)(d) + G(a_1, \dots, a_{s-2}, c, d)(b) \\ &= G(a_1, \dots, a_{s-2}, b, cd)(1) + G(a_1, \dots, a_{s-2}, c, bd)(1) \\ &= (\partial_s G)(a_1, \dots, a_{s-2}, b)(cd) + (\partial_s G)(a_1, \dots, a_{s-2}, c)(bd), \end{aligned}$$

which is the desired conclusion. Therefore we have defined the linear map $\partial_s: C_s A \to C_{s-1} A$ for every positive integer s.

It will be convenient to put $C_{-1}A = \mathbb{R}$, $\partial_0 : C_0A \ni G \mapsto G(1) \in C_{-1}A$ (this definition makes sense, because $C_0A = A^*$) and $\partial_{-1} = 0$.

If $s \ge 1$ and $G \in C_s A$, then by (2),

$$G(a_1, \dots, a_{s-1}, 1)(1) = G(a_1, \dots, a_{s-1}, 1 \cdot 1)(1)$$

= $G(a_1, \dots, a_{s-1}, 1)(1) + G(a_1, \dots, a_{s-1}, 1)(1),$

and so $G(a_1, \ldots, a_{s-1}, 1)(1) = 0$ for all $a_1, \ldots, a_{s-1} \in A$. From this we deduce that $\partial_{s-1}\partial_s = 0$ for every $s \ge 0$.

Thus we have constructed a chain complex and we define the homology vector spaces of the algebra A by the usual formula $H_s A = \ker \partial_s / \operatorname{im} \partial_{s+1}$ for every $s \geq -1$. We will call A acyclic if $H_s A = \{0\}$ for all $s \geq -1$.

As a curiosity, it is worth pointing out that the above construction works not only for a Weil algebra, but also for any algebra with unit, even noncommutative and non-associative.

Formulas for $d \circ F^{p,q-1}$. Since constant coefficients in formulas we want to derive depend on the choice of constant coefficients in some definitions, we now make the following convention. If m and s are non-negative integers, V is an open subset of \mathbb{R}^m , $\alpha \in F_s V$ and the coordinates $\alpha_{i_1...i_s} : V \to \mathbb{R}$ for $i_1, \ldots, i_s \in \{1, \ldots, m\}$ are such that $\alpha(x)(y_1, \ldots, y_s) = \alpha_{i_1...i_s}(x)y_1^{i_1} \ldots y_s^{i_s}$ for every $x \in V$ and all $y_1, \ldots, y_s \in \mathbb{R}^m$, then $\alpha = \alpha_{i_1 \ldots i_s} dx^{i_1} \wedge \cdots \wedge dx^{i_s}$ and

$$d\alpha = \frac{\partial \alpha_{i_1\dots i_s}}{\partial x^j} \, dx^j \wedge dx^{i_1} \wedge \dots \wedge dx^{i_s}.$$

We are now in a position to formulate a theorem containing the promised formulas for $d \circ F^{p,q-1}$, where $F \in C_{p-q+1}A$.

THEOREM 1. Let
$$p - q + 1 \ge 0$$
 and $F \in C_{p-q+1}A$.
If $q = 0$, then
(4) $0 = (-1)^{p-1} (\partial_{p+1}F)^{p,0} + F^{p+1,0} \circ d$.
If $1 \le q \le p$, then
(5) $q(d \circ F^{p,q-1}) = (p - q + 1)(-1)^{p-1} (\partial_{p-q+1}F)^{p,q} + (p + 1)(F^{p+1,q} \circ d)$.
If $q = p + 1$, then
(6) $d \circ F^{p,p} = F^{p+1,p+1} \circ d$.

Proof. To simplify the proof, note that (4) and (6) may be interpreted as special cases of (5), because the coefficients of the terms which do not make sense vanish in these special cases.

If s is a positive integer, u is a non-negative integer and $G \in C_s A$, then by induction on u we deduce from (2) that

(7)
$$G(a_1, \dots, a_{s-1}, b_1 \dots b_u)(c)$$

= $\sum_{v=1}^u G(a_1, \dots, a_{s-1}, b_v)(b_1 \dots b_{v-1}b_{v+1} \dots b_u c)$

for all $a_1, \ldots, a_{s-1}, b_1, \ldots, b_u, c \in A$. From (7) we conclude immediately that if $f : \mathbb{R}^n \to \mathbb{R}$ is a polynomial, then

(8)
$$G(a_1, \dots, a_{s-1}, (T^A f)(X))(c) = G(a_1, \dots, a_{s-1}, X^j) \left(\left(\left(T^A \frac{\partial f}{\partial x^j} \right)(X) \right) c \right)$$

for every $X \in A^n$. Actually, (8) still holds when $f: U \to \mathbb{R}$ is a smooth map on an open subset U of \mathbb{R}^n and $X \in T^A U$ (this is due to the fact that T^A has a finite order; see [1]).

If $q \geq 1$, *m* is a non-negative integer, *V* is an open subset of \mathbb{R}^m and $\alpha \in F_{q-1}V$, then we write $\alpha^{y_1\dots y_{q-1}}: V \ni x \mapsto \alpha(x)(y_1,\dots,y_{q-1}) \in \mathbb{R}$ for $y_1,\dots,y_{q-1} \in \mathbb{R}^m$. In this notation we have

(9)
$$(d\alpha)(x)(y_1,\ldots,y_q) = \frac{1}{q} \sum_{u=1}^{q} (-1)^{u-1} (d(\alpha^{y_1\ldots y_{u-1}y_{u+1}\ldots y_q}))(x)(y_u)$$

for every $x \in V$ and all $y_1, \ldots, y_q \in \mathbb{R}^m$, as is easy to verify.

292

Let U be an open subset of \mathbb{R}^n and $\omega \in F_pU$. By (3), if $q \ge 1$ then

$$F_U^{p,q-1}(\omega)(X)(Y_1,\ldots,Y_{q-1})$$

= $F(X^{i_q},\ldots,X^{i_p})(((T^A\omega_{i_1\ldots i_p})(X))Y_1^{i_1}\ldots Y_{q-1}^{i_{q-1}})$

for every $X \in T^A U$ and all $Y_1, \ldots, Y_{q-1} \in A^n$. Hence (9) gives

$$(10) \quad q(d(F_U^{p,q-1}(\omega)))(X)(Y_1,\ldots,Y_q) = \sum_{u=1}^q (-1)^{u-1} \bigg(\sum_{t=q}^p F(X^{i_q},\ldots,X^{i_{t-1}},Y_u^{i_t},X^{i_{t+1}},\ldots,X^{i_p}) \\ (((T^A\omega_{i_1\ldots i_p})(X))Y_1^{i_1}\ldots Y_{u-1}^{i_{u-1}}Y_{u+1}^{i_u}\ldots Y_q^{i_{q-1}}) \\ + F(X^{i_q},\ldots,X^{i_p}) \bigg(\bigg(\bigg(T^A \frac{\partial \omega_{i_1\ldots i_p}}{\partial x^j} \bigg)(X) \bigg) Y_1^{i_1}\ldots Y_{u-1}^{i_{u-1}}Y_{u+1}^{i_u}\ldots Y_q^{i_{q-1}}Y_u^j \bigg) \bigg)$$

for every $X \in T^A U$ and all $Y_1, \ldots, Y_q \in A^n$. But, by the skew-symmetry of F and ω ,

$$(11) \qquad \sum_{u=1}^{q} (-1)^{u-1} \sum_{t=q}^{p} F(X^{i_{q}}, \dots, X^{i_{t-1}}, Y^{i_{t}}_{u}, X^{i_{t+1}}, \dots, X^{i_{p}}) \\ (((T^{A}\omega_{i_{1}\dots i_{p}})(X))Y^{i_{1}}_{1}\dots Y^{i_{u-1}}_{u-1}Y^{i_{u}}_{u+1}\dots Y^{i_{q-1}}_{q}) \\ = (p-q+1) \sum_{u=1}^{q} (-1)^{u-1} \\ \times F(X^{i_{q}}, \dots, X^{i_{p-1}}, Y^{i_{p}}_{u})(((T^{A}\omega_{i_{1}\dots i_{p}})(X))Y^{i_{1}}_{1}\dots Y^{i_{u-1}}_{u-1}Y^{i_{u}}_{u+1}\dots Y^{i_{q-1}}_{q}) \\ = (p-q+1)(-1)^{p-1} \\ \times \sum_{u=1}^{q} F(X^{i_{q+1}}, \dots, X^{i_{p}}, Y^{i_{u}}_{u})(((T^{A}\omega_{i_{1}\dots i_{p}})(X))Y^{i_{1}}_{1}\dots Y^{i_{u-1}}_{u-1}Y^{i_{u+1}}_{u+1}\dots Y^{i_{q}}_{q}).$$

Since

$$(d\omega)_{i_1\dots i_{p+1}} = \frac{1}{p+1} \sum_{u=1}^{p+1} (-1)^{u-1} \frac{\partial \omega_{i_1\dots i_{u-1}i_{u+1}\dots i_{p+1}}}{\partial x^{i_u}}$$

for all $i_1, \ldots, i_{p+1} \in \{1, \ldots, n\}$, (3) and the skew-symmetry of F give

(12)
$$(p+1)(F_U^{p+1,q}(d\omega))(X)(Y_1,\ldots,Y_q)$$

= $\sum_{u=1}^{p+1} (-1)^{u-1} F(X^{i_{q+1}},\ldots,X^{i_{p+1}}) \left(\left(\left(T^A \frac{\partial \omega_{i_1\ldots i_{u-1}i_{u+1}\ldots i_{p+1}}}{\partial x^{i_u}} \right)(X) \right) Y_1^{i_1}\ldots Y_q^{i_q} \right)$

J. Dębecki

$$=\sum_{u=1}^{q} (-1)^{u-1} F(X^{i_{q}}, \dots, X^{i_{p}}) \left(\left(\left(T^{A} \frac{\partial \omega_{i_{1} \dots i_{p}}}{\partial x^{j}} \right)(X) \right) Y_{1}^{i_{1}} \dots Y_{u-1}^{i_{u-1}} Y_{u+1}^{i_{u}} \dots Y_{q}^{i_{q-1}} Y_{u}^{j} \right) \\= (-1)^{p} \sum_{u=q+1}^{p+1} F(X^{i_{q+1}}, \dots, X^{i_{p}}, X^{j}) \left(\left(\left(T^{A} \frac{\partial \omega_{i_{1} \dots i_{p}}}{\partial x^{j}} \right)(X) \right) Y_{1}^{i_{1}} \dots Y_{q}^{i_{q}} \right)$$

for every $X \in T^A U$ and all $Y_1, \ldots, Y_q \in A^n$. But, by (8),

(13)
$$(-1)^{p} \sum_{u=q+1}^{p+1} F(X^{i_{q+1}}, \dots, X^{i_{p}}, X^{j}) \left(\left(\left(T^{A} \frac{\partial \omega_{i_{1}\dots i_{p}}}{\partial x^{j}} \right)(X) \right) Y_{1}^{i_{1}} \dots Y_{q}^{i_{q}} \right)$$
$$+ (p-q+1)(-1)^{p} F(X^{i_{q+1}}, \dots, X^{i_{p}}, (T^{A} \omega_{i_{1}\dots i_{p}})(X))(Y_{1}^{i_{1}} \dots Y_{q}^{i_{q}}).$$
Combining (10)–(13) and applying (7) and (3) we obtain

$$\begin{aligned} &(q(d(F_U^{p,q-1}(\omega))) - (p+1)(F_U^{p+1,q}(d\omega)))(X)(Y_1,\ldots,Y_q) \\ &= (p-q+1)(-1)^{p-1} \\ &\times \sum_{u=1}^q F(X^{i_{q+1}},\ldots,X^{i_p},Y_u^{i_u})(((T^A\omega_{i_1\ldots i_p})(X))Y_1^{i_1}\ldots Y_{u-1}^{i_{u-1}}Y_{u+1}^{i_{u+1}}\ldots Y_q^{i_q}) \\ &- (p-q+1)(-1)^p F(X^{i_{q+1}},\ldots,X^{i_p},(T^A\omega_{i_1\ldots i_p})(X))(Y_1^{i_1}\ldots Y_q^{i_q}) \\ &= (p-q+1)(-1)^{p-1}F(X^{i_{q+1}},\ldots,X^{i_p},((T^A\omega_{i_1\ldots i_p})(X))Y_1^{i_1}\ldots Y_q^{i_q}) (1) \\ &= (p-q+1)(-1)^{p-1}(\partial_{p-q+1}F)_U^{p,q}(\omega)(X)(Y_1,\ldots,Y_q) \end{aligned}$$

for every $X \in T^A U$ and all $Y_1, \ldots, Y_q \in A^n$. This establishes (5), and the proof is complete.

The case p = n and q = 0. Let L be a linear lifting of n-forms to 0-forms on T^A . One may ask if there exists a $D \in C_n A$ such that $L = D^{n,0}$ and, if this is so, whether such a D is unique or not. The following proposition answers the latter question.

PROPOSITION 1. Let $D, \widetilde{D} \in C_n A$. Then $D^{n,0} = \widetilde{D}^{n,0}$ if and only if $\partial_n D = \partial_n \widetilde{D}$.

Proof. From a lemma proved in [1] it follows that if L and \tilde{L} are two linear liftings of *n*-forms to 0-forms on T^A such that

$$L_{\mathbb{R}^n}(dx^1 \wedge \dots \wedge dx^n) = \widetilde{L}_{\mathbb{R}^n}(dx^1 \wedge \dots \wedge dx^n),$$

then $L = \widetilde{L}$. By (3) and the skew-symmetry of D,

(14)
$$D_{\mathbb{R}^n}^{n,0}(dx^1 \wedge \dots \wedge dx^n)(X)$$

= $D(X^1, \dots, X^n)(1) = \begin{cases} (\partial_n D)(X^1, \dots, X^{n-1})(X^n) & \text{if } n \ge 1, \\ \partial_0 D & \text{if } n = 0, \end{cases}$

for every $X \in A^n$, and a similar formula holds for D. Combining these with the above-mentioned lemma completes the proof.

The problem of the existence of a $D \in C_n A$ such that $L = D^{n,0}$ is more difficult. We will solve it under the condition that $H_{n-1}A = \{0\}$.

We define $S_{n-1}A$ to be the set of skew-symmetric *n*-linear functions $C : A \times \cdots \times A \to \mathbb{R}$ with the properties that

(15)
$$C(a_1, \ldots, a_{n-2}, bc, d) = C(a_1, \ldots, a_{n-2}, b, cd) + C(a_1, \ldots, a_{n-2}, c, bd)$$

for all $a_1, \ldots, a_{n-2}, b, c, d \in A$ whenever $n \ge 2$ and

(16)
$$C(a_1, \dots, a_{n-1}, 1) = 0$$

for all $a_1, \ldots, a_{n-1} \in A$ whenever $n \ge 1$ (note that if $n \ge 2$, then (16) is a consequence of (15) with b = 1 and c = 1).

Let $C \in S_{n-1}A$. If $n \ge 1$, then we define the skew-symmetric (n-1)-linear map $\overline{C} : A \times \cdots \times A \to A^*$ by

$$C(a_1, \ldots, a_{n-1})(b) = C(a_1, \ldots, a_{n-1}, b)$$

for $a_1, \ldots, a_{n-1}, b \in A$. If n = 0, then we put $\overline{C} = C$ (in this case $C \in \mathbb{R}$). Let $\overline{S_{n-1}A}$ denote the image of the linear injection $S_{n-1}A \ni C \mapsto \overline{C} \in \ker \partial_{n-1}$.

PROPOSITION 2. $\overline{S_{n-1}A} = \ker \partial_{n-1}$.

Proof. The case $n \leq 1$ is trivial. Suppose that $n \geq 2$ and $G \in \ker \partial_{n-1}$. The *n*-linear function $C : A \times \cdots \times A \to \mathbb{R}$ given by $C(a_1, \ldots, a_{n-1}, b) = G(a_1, \ldots, a_{n-1})(b)$ for all $a_1, \ldots, a_{n-1}, b \in A$ is skew-symmetric in the first n-1 variables. If we show that it is skew-symmetric in the last two variables as well, we will have $G = \overline{C}$ and the proof will be completed. But the fact that $\partial_{n-1}G = 0$ and (2) yield

$$0 = G(a_1, \dots, a_{n-2}, bc)(1) = G(a_1, \dots, a_{n-2}, b)(c) + G(a_1, \dots, a_{n-2}, c)(b)$$

for all $a_1, \ldots, a_{n-2}, b, c \in A$, which is the desired conclusion.

LEMMA 1. For every linear lifting L of n-forms to 0-forms on T^A there is a unique $C \in S_{n-1}A$ such that

(17)
$$L_{\mathbb{R}^n}(dx^1 \wedge \dots \wedge dx^n)(X) = C(X^1, \dots, X^n)$$

for every $X = (X^1, \ldots, X^n) \in A^n$.

Proof. From (1) with $f : \mathbb{R}^n \ni x \mapsto (t_1 x^1, \dots, t_n x^n) \in \mathbb{R}^n$, where $t_1, \dots, t_n \in \mathbb{R} \setminus \{0\}$, we have

$$t_1 \dots t_n L_{\mathbb{R}^n} (dx^1 \wedge \dots \wedge dx^n) (X) = L_{\mathbb{R}^n} (dx^1 \wedge \dots \wedge dx^n) (t_1 X^1, \dots, t_n X^n)$$

for every $X \in A^n$. By continuity, the same is true for all $t_1, \ldots, t_n \in \mathbb{R}$. The homogeneous function theorem (see [9]) now shows that there is an *n*-linear function $C: A \times \cdots \times A \to \mathbb{R}$ satisfying (17).

From (1) with $f : \mathbb{R}^n \ni x \mapsto (x^{\sigma(1)}, \dots, x^{\sigma(n)}) \in \mathbb{R}^n$, where σ is a permutation of $\{1, \dots, n\}$, we have

 $\operatorname{sgn} \sigma L_{\mathbb{R}^n}(dx^1 \wedge \dots \wedge dx^n)(X) = L_{\mathbb{R}^n}(dx^1 \wedge \dots \wedge dx^n)(X^{\sigma(1)}, \dots, X^{\sigma(n)})$

for every $X \in A^n$. Hence, by (17), C is skew-symmetric.

If $n \ge 2$, then put $U = \{x \in \mathbb{R}^n : x^{n-1} > 0\}$ and

$$f: U \ni x \mapsto \left(x^1, \dots, x^{n-2}, \frac{1}{2}(x^{n-1})^2, x^n\right) \in \mathbb{R}^n,$$

$$g: U \ni x \mapsto \left(x^1, \dots, x^{n-1}, x^{n-1}x^n\right) \in \mathbb{R}^n.$$

Since $f^*(dx^1 \wedge \cdots \wedge dx^n) = g^*(dx^1 \wedge \cdots \wedge dx^n)$, from (1) we have

(18)
$$L_{\mathbb{R}^n}(dx^1 \wedge \dots \wedge dx^n)(X^1, \dots, X^{n-2}, \frac{1}{2}(X^{n-1})^2, X^n)$$

= $L_{\mathbb{R}^n}(dx^1 \wedge \dots \wedge dx^n)(X^1, \dots, X^{n-1}, X^{n-1}X^n)$

for $X \in T^A U$. In the same manner, with U replaced by $\{x \in \mathbb{R}^n : x^{n-1} < 0\}$, we can see that (18) also holds for $X \in T^A \{x \in \mathbb{R}^n : x^{n-1} < 0\}$, and so, by continuity, for every $X \in A^n$. The polarization of (18) with respect to X^{n-1} and (17) now show that (15) holds.

If n = 1, then from (1) with $f : \mathbb{R} \ni x \mapsto 2x - 1 \in \mathbb{R}$ we have $2L_{\mathbb{R}}(dx)(1) = L_{\mathbb{R}}(dx)(1)$, so $L_{\mathbb{R}}(dx)(1) = 0$. Hence, by (17), C satisfies (16).

The uniqueness of C is evident. This completes the proof.

Lemma 1 enables us to formulate the following proposition.

PROPOSITION 3. Let L be a linear lifting of n-forms to 0-forms on T^A and $C \in S_{n-1}A$ be such that (17) holds. Then there exists a $D \in C_nA$ such that $L = D^{n,0}$ if and only if $\overline{C} \in \operatorname{im} \partial_n$.

Proof. If $D \in C_n A$, then (17) and (14) show that $\overline{C} = \partial_n D$ if and only if $L_{\mathbb{R}^n}(dx^1 \wedge \cdots \wedge dx^n) = D_{\mathbb{R}^n}^{n,0}(dx^1 \wedge \cdots \wedge dx^n)$, which is equivalent to $L = D^{n,0}$, because of the above-mentioned lemma of [1]. This completes the proof.

Propositions 1–3 give the following theorem.

THEOREM 2. If $H_{n-1}A = \{0\}$, then for every linear lifting L of n-forms to 0-forms on T^A there is a $D \in C_nA$ such that $L = D^{n,0}$, and so the vector space of linear liftings of n-forms to 0-forms on T^A is isomorphic to $C_nA/\ker \partial_n$.

Thus Theorem 2 gives a classification of linear liftings of *n*-forms to 0forms on T^A under the condition that A is acyclic. Clearly, ker $\partial_{-1} = \mathbb{R}$ and im $\partial_0 = \mathbb{R}$. However, computing ker ∂_s and im ∂_{s+1} for all $s \geq -1$ and an arbitrary Weil algebra A seems difficult. In the next section we will solve this problem for some special (but important) Weil algebras.

ker ∂_s and im ∂_{s+1} for the algebras \mathbb{D}_k^r . Let r and k be non-negative integers. We will denote by \mathbb{D}_k^r the Weil algebra of r-jets at 0 of smooth

functions $\mathbb{R}^k \to \mathbb{R}$. It is worth pointing out that each Weil algebra A is a factor algebra of \mathbb{D}_k^r for some r and k (see [8]), so the chain complex CA is isomorphic to a subcomplex of $C\mathbb{D}_k^r$.

If r = 0 or k = 0, then $\mathbb{D}_k^r = \mathbb{R}$, and it is a simple matter to check that $H_s \mathbb{R} = \{0\}$ for every $s \ge -1$.

From now on we make the assumption that $r \ge 1$ and $k \ge 1$.

We will denote by x^i for $i \in \{1, \ldots, k\}$ the *r*-jet at 0 of the projection $\mathbb{R}^k \ni x \mapsto x^i \in \mathbb{R}$ and write $x^{\alpha} = (x^1)^{\alpha^1} \dots (x^k)^{\alpha^k}$ and $|\alpha| = \alpha^1 + \dots + \alpha^k$ for $\alpha \in \mathbb{N}^k$, where \mathbb{N} stands for the set of non-negative integers.

For $s \geq 1$ we denote by Z_s the set of $(i_1, \ldots, i_s, \alpha) \in \{1, \ldots, k\}^s \times \mathbb{N}^k$ with the properties that $i_1 < \cdots < i_s$, and either $|\alpha| < r$ or $|\alpha| = r$ and $i_s < \max\{l \in \{1, \ldots, k\} : \alpha^l > 0\}$. Moreover, let Z_0 denote the set of $\alpha \in \mathbb{N}^k$ such that $|\alpha| \leq r$. In [2] it is proved that the map $I_s : C_s \mathbb{D}_k^r \to \mathbb{R}^{Z_s}$ given by $I_s(D)(i_1, \ldots, i_s, \alpha) = D(x^{i_1}, \ldots, x^{i_s})(x^{\alpha})$ for every $D \in C_s \mathbb{D}_k^r$ and every $(i_1, \ldots, i_s, \alpha) \in Z_s$ is an isomorphism of vector spaces for every non-negative integer s.

For $s \geq 1$ we denote by W_s the set of $(i_1, \ldots, i_s, \alpha) \in \{1, \ldots, k\}^s \times \mathbb{N}^k$ such that $i_1 < \cdots < i_s, |\alpha| \leq r, \alpha \neq 0$ and $i_s < \max\{l \in \{1, \ldots, k\} : \alpha^l > 0\}$. Moreover, let W_0 denote the set of $\alpha \in \mathbb{N}^k$ such that $|\alpha| \leq r$ and $\alpha \neq 0$. Of course, $W_s \subset Z_s$ for every non-negative integer s.

Suppose now that $s \ge 1$.

For $(i_1, \ldots, i_{s-1}, \beta) \in W_{s-1}$ we put $i_s = \max\{l \in \{1, \ldots, k\} : \beta^l > 0\}$ and $\alpha = \beta - e_{i_s}$, where e_1, \ldots, e_k is the standard basis of the module \mathbb{Z}^k . It is easily seen that $(i_1, \ldots, i_s, \alpha) \in Z_s \setminus W_s$. Writing $\varphi_s(i_1, \ldots, i_{s-1}, \beta) = (i_1, \ldots, i_s, \alpha)$ we get $\varphi_s : W_{s-1} \to Z_s \setminus W_s$.

For $(i_1, \ldots, i_s, \alpha) \in Z_s \setminus W_s$ we put $\beta = \alpha + e_{i_s}$. It is easily seen that $(i_1, \ldots, i_{s-1}, \beta) \in W_{s-1}$. Writing $\psi_s(i_1, \ldots, i_s, \alpha) = (i_1, \ldots, i_{s-1}, \beta)$ we get $\psi_s : Z_s \setminus W_s \to W_{s-1}$.

LEMMA 2. $\psi_s \circ \varphi_s = \mathrm{id}_{W_{s-1}}$ and $\varphi_s \circ \psi_s = \mathrm{id}_{Z_s \setminus W_s}$.

Proof. The proof is immediate.

If $(i_1, \ldots, i_s) \in \mathbb{N}^s$ and $i_u \neq i_v$ for all $u, v \in \{1, \ldots, s\}$ such that $u \neq v$, then we will write $P(i_1, \ldots, i_s) = (i_{\sigma(1)}, \ldots, i_{\sigma(s)})$ and $\operatorname{sgn}(i_1, \ldots, i_s) = \operatorname{sgn} \sigma$, where σ is the permutation of $\{1, \ldots, s\}$ such that $i_{\sigma(1)} < \cdots < i_{\sigma(s)}$.

LEMMA 3. If $B \in \mathbb{R}^{Z_s}$, then $B \in I_s(\ker \partial_s)$ if and only if

(19)
$$B(i_1, \dots, i_s, \alpha) = -\frac{1}{\alpha^{i_s} + 1} \sum_{\substack{j \in \{l \in \{1, \dots, k\} : \alpha^l > 0\} \\ j \neq i_1, \dots, i_s}} \alpha^j \operatorname{sgn}(i_1, \dots, i_{s-1}, j) \times B(P(i_1, \dots, i_{s-1}, j), \alpha + e_{i_s} - e_j)}$$

for every $(i_1, \ldots, i_s, \alpha) \in Z_s \setminus W_s$. Furthermore, the right hand side of (19) contains only $B(i_1, \ldots, i_s, \alpha)$ such that $(i_1, \ldots, i_s, \alpha) \in W_s$.

Proof. Since every $D \in C_s \mathbb{D}_k^r$ is skew-symmetric, the first assertion of our lemma may be reformulated as follows: if $D \in C_s \mathbb{D}_k^r$, then $D \in \ker \partial_s$ if and only if

(20)
$$D(x^{i_1}, \dots, x^{i_s})(x^{\alpha}) = -\frac{1}{\alpha^{i_s} + 1} \sum_{\substack{j \in \{l \in \{1, \dots, k\} : \alpha^l > 0\}\\j \neq i_s}} \alpha^j D(x^{i_1}, \dots, x^{i_{s-1}}, x^j)(x^{\alpha + e_{i_s} - e_j})$$

for every $(i_1, \ldots, i_s, \alpha) \in Z_s \setminus W_s$.

On account of the above-mentioned result of [2], if $D \in C_s \mathbb{D}_k^r$, then $D \in \ker \partial_s$ if and only if $(\partial_s D)(x^{i_1}, \ldots, x^{i_{s-1}})(x^\beta) = 0$ for every $(i_1, \ldots, i_{s-1}, \beta) \in Z_{s-1}$. Applying (8) we can rewrite this as

(21)
$$\sum_{j \in \{l \in \{1, \dots, k\} : \beta^l > 0\}} \beta^j D(x^{i_1}, \dots, x^{i_{s-1}}, x^j)(x^{\beta - e_j}) = 0.$$

But (20) is equivalent to (21) with $(i_1, \ldots, i_{s-1}, \beta) = \psi_s(i_1, \ldots, i_s, \alpha)$, which means that (20) holds if and only if (21) holds for $(i_1, \ldots, i_{s-1}, \beta) \in W_{s-1}$, because of Lemma 2. Consequently, the first assertion of our lemma will be proved as soon as we can show that (20) implies (21) with $(i_1, \ldots, i_{s-1}, \beta) \in Z_{s-1} \setminus W_{s-1}$.

Since $Z_0 \setminus W_0 = \{0\}$, this is true if s = 1. Therefore we can assume that $s \ge 2$. It is easy to see that for every $(i_1, \ldots, i_{s-1}, \beta) \in Z_{s-1} \setminus W_{s-1}$ and every $j \in \{l \in \{1, \ldots, k\} : \beta^l > 0\} \setminus \{i_1, \ldots, i_{s-1}\}$, either $\beta - e_j = 0$, or $\beta - e_j \neq 0$ and $\max\{i_1, \ldots, i_{s-1}, j\} = i_{s-1} \ge \max\{l \in \{1, \ldots, k\} : (\beta - e_j)^l > 0\}$, and so $(P(i_1, \ldots, i_{s-1}, j), \beta - e_j) \in Z_s \setminus W_s$. Hence (20) and the skew-symmetry of D give

$$D(x^{i_1}, \dots, x^{i_{s-1}}, x^j)(x^{\beta - e_j}) = -\frac{1}{\beta^{i_{s-1}} + 1} \times \sum_{\substack{h \in \{l \in \{1, \dots, k\} : \beta^l > 0\} \\ h \neq i_1, \dots, i_{s-1}, j}} \beta^h D(x^{i_1}, \dots, x^{i_{s-2}}, x^h, x^j)(x^{\beta + e_{i_{s-1}} - e_h - e_j}).$$

Substituting this into (21) and using the skew-symmetry of D we see that the left hand side of (21) equals

$$-\frac{1}{\beta^{i_{s-1}}+1}\sum_{\substack{j,h\in\{l\in\{1,\dots,k\}:\beta^{l}>0\}\\j,h\neq i_{1},\dots,i_{s-1}\\j\neq h}}\beta^{h}\beta^{j}D(x^{i_{1}},\dots,x^{i_{s-2}},x^{h},x^{j})(x^{\beta+e_{i_{s-1}}-e_{h}-e_{j}}),$$

which vanishes because of the skew-symmetry of D. This proves the first assertion of our lemma.

To prove the second one it suffices to notice that for every $(i_1, \ldots, i_s, \alpha) \in Z_s \setminus W_s$ and every $j \in \{l \in \{1, \ldots, k\} : \alpha^l > 0\} \setminus \{i_1, \ldots, i_s\}$ we have $\max\{i_1, \ldots, i_{s-1}, j\} < i_s = \max\{l \in \{1, \ldots, k\} : (\alpha + e_{i_s} - e_j)^l > 0\}$, and so $(P(i_1, \ldots, i_{s-1}, j), \alpha + e_{i_s} - e_j) \in W_s$. This completes the proof.

Note that Lemma 3 gives a description of ker ∂_s . Namely, any $B \in I_s(\ker \partial_s)$ may be defined arbitrarily on W_s first, and then by (19) on $Z_s \setminus W_s$ (the same is true for s = 0 when the right hand side of (19) vanishes). In particular, we have the following corollary.

COROLLARY. For every $s \ge 0$ the map ker $\partial_s \ni D \mapsto I_s(D)|_{W_s} \in \mathbb{R}^{W_s}$ is an isomorphism of vector spaces.

Finally, from Lemmas 2 and 3 and the above-mentioned result of [2] we obtain the following theorem which states that the algebras \mathbb{D}_k^r are acyclic.

THEOREM 3. $H_s \mathbb{D}_k^r = \{0\}$ for every $s \geq -1$.

Proof. dim ker $\partial_{s-1} = \operatorname{card} W_{s-1} = \operatorname{card} Z_s - \operatorname{card} W_s = \dim C_s \mathbb{D}_k^r - \operatorname{dim} \ker \partial_s = \operatorname{dim} \operatorname{im} \partial_s$ for every $s \ge 1$.

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J. Dębecki

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