

The rigidity theorem for Landsberg hypersurfaces of a Minkowski space

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Abstract. Let M^n be a compact Landsberg hypersurface of a Minkowski space (V^{n+1}, \bar{F}) with constant mean curvature H . Using the Gauss formula for the Chern connection of Finsler submanifolds, we prove that if M is convex, then M is Riemannian with constant curvature.

1. Introduction. Let M be an n -dimensional smooth manifold and $\pi : TM \rightarrow M$ be the natural projection from the tangent bundle. Let (x, Y) be a point of TM with $x \in M$, $Y \in T_x M$ and let (x^i, Y^i) be the local coordinates on TM with $Y = Y^i \partial / \partial x^i$. A *Finsler metric* on M is a function $F : TM \rightarrow [0, \infty)$ with the following properties:

- (i) Regularity: $F(x, Y)$ is smooth in $TM \setminus 0$.
- (ii) Positive homogeneity: $F(x, \lambda Y) = \lambda F(x, Y)$ for $\lambda > 0$.
- (iii) Strong convexity: The fundamental quadratic form $g = g_{ij}(x, Y) dx^i \otimes dx^j$ is positive definite, where $g_{ij} = \frac{1}{2} \partial^2 (F^2) / \partial Y^i \partial Y^j$.

Then (M, F) is called a *Finsler manifold*. The simplest class of Finsler manifolds is the Minkowski spaces. Let V be an n -dimensional real vector space. A *Minkowski norm* on V is a function $F : V \rightarrow [0, \infty)$ with the following properties:

- (i) Regularity: F is smooth in $V \setminus \{0\}$.
- (ii) Positive homogeneity: $F(\lambda Y) = \lambda F(Y)$ for $\lambda > 0$ and $Y \in V$.
- (iii) Strong convexity: For any $Y \in V \setminus \{0\}$, the symmetric bilinear form g_Y is positive definite, where $g_Y(u, v) = \frac{1}{2} \frac{\partial^2}{\partial s \partial t} [F^2(Y + su + tv)] \Big|_{s=t=0}$.

Then (V, F) is called a *Minkowski space*. Let $\{e_i\}$ be an arbitrary basis for V . From the above definition we find that

$$g_{ij}(Y) = g_Y(e_i, e_j) = \frac{1}{2} \frac{\partial^2}{\partial Y^i \partial Y^j} [F^2(Y)].$$

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We see that for any Finsler manifold (M, F) , $F_x(Y) := F(x, Y)$ is a Minkowski norm on T_xM for every point $x \in M$. On the other hand, for a Minkowski space (V, F) , the Finsler metric $F(x, Y) := F(Y) : TV \rightarrow [0, \infty)$ is a function of $Y \in V$ only.

Riemannian submanifolds are important in modern differential geometry and extensively studied. For a compact hypersurface M of the Euclidean space with constant mean curvature, Nomizu and Smyth [NS] proved that if M is convex, then M is a Riemannian sphere. There has been remarkable progress in recent studies on Finsler manifolds. For example, in [BRS], D. Bao, C. Robles and Z. Shen have completely classified strongly convex Randers metrics with constant flag curvature, and the geometry of Ingarden spaces has been described by R. Miron [M].

In this paper, by using the Gauss formula for the Chern connection, we study the Landsberg hypersurfaces of a Minkowski space (V^{n+1}, \bar{F}) and obtain the following

MAIN THEOREM 1.1. *Let M^n be a compact Landsberg hypersurface of a Minkowski space (V^{n+1}, \bar{F}) with constant mean curvature H . If M is convex, then M is Riemannian with constant curvature.*

REMARK. The Main Theorem generalizes the result of Nomizu and Smyth [NS] from the Riemannian to the Finsler case.

2. Preliminaries. Let (M^n, F) be an n -dimensional Finsler manifold. F inherits the *Hilbert form*, the *fundamental tensor* and the *Cartan tensor* as follows:

$$\begin{aligned} \omega &= \frac{\partial F}{\partial Y^i} dx^i, & g_Y &= g_{ij}(x, Y) dx^i \otimes dx^j, \\ A_Y &= A_{ijk} dx^i \otimes dx^j \otimes dx^k, & A_{ijk} &:= \frac{F \partial g_{ij}}{2 \partial Y^k}. \end{aligned}$$

It is well known that there exists a unique *Chern connection* ∇ on π^*TM with $\nabla \frac{\partial}{\partial x^i} = \omega_j^i \frac{\partial}{\partial x^j}$ and $\omega_j^i = \Gamma_{ik}^j dx^k$ satisfying

$$\begin{aligned} d(dx^i) - dx^j \wedge \omega_j^i &= - dx^j \wedge \omega_j^i = 0, \\ dg_{ij} - g_{ik} \omega_j^k - g_{jk} \omega_i^k &= 2A_{ijk} \frac{\delta Y^k}{F}, \end{aligned}$$

where $\delta Y^i = dY^i + N_j^i dx^j$, $N_j^i = \gamma_{jk}^i Y^k - \frac{1}{F} A_{jk}^i \gamma_{st}^k Y^s Y^t$ and γ_{jk}^i are the formal Christoffel symbols of the second kind for g_{ij} .

The curvature 2-forms of the Chern connection ∇ are

$$\omega_j^i - \omega_j^k \wedge \omega_k^i = \Omega_j^i = \frac{1}{2} R_{jkl}^i dx^k \wedge dx^l + \frac{1}{F} P_{jkl}^i dx^k \wedge \delta Y^l,$$

where R_{jkl}^i and P_{jkl}^i are the components of the *hh*-curvature tensor and the *hv*-curvature tensor of the Chern connection, respectively.

Let $\varphi : (M^n, F) \rightarrow (\overline{M}^{n+p}, \overline{F})$ be an isometric immersion from a Finsler manifold to a Finsler manifold. We have [S]

$$(2.1) \quad \begin{aligned} F(Y) &= \overline{F}(\varphi_*(Y)), \quad g_Y(U, V) = \overline{g}_{\varphi_*(Y)}(\varphi_*(U), \varphi_*(V)), \\ A_Y(U, V, W) &= \overline{A}_{\varphi_*(Y)}(\varphi_*(U), \varphi_*(V), \varphi_*(W)), \end{aligned}$$

where $Y, U, V, W \in TM$, and \overline{g} and \overline{A} are the fundamental tensor and the Cartan tensor of \overline{M} , respectively.

It can be seen from (2.1) that $\varphi^*(\overline{\omega}) = \omega$, where $\overline{\omega}$ is the Hilbert form of \overline{M} .

In the following we simplify A_Y and g_Y to A and g , respectively.

When \overline{M} is a Minkowski space, the formal Christoffel symbols $\overline{\gamma}_{bc}^a$ of the second kind for \overline{g}_{ab} must vanish and so $\overline{N}_b^a = \overline{\gamma}_{bc}^a \overline{Y}^c - \frac{1}{F} \overline{A}_{bc}^a \overline{\gamma}_{df}^c \overline{Y}^d \overline{Y}^f = 0$; then the horizontal part $(\varphi_*e_i)^H$ of $\varphi_*e_i = u_i^j \varphi_j^A \frac{\partial}{\partial \overline{x}^A}$ can be written as

$$(\varphi_*e_i)^H = u_i^j \varphi_j^A \frac{\delta}{\delta \overline{x}^A} = u_i^j \varphi_j^A \left(\frac{\partial}{\partial \overline{x}^A} - \overline{N}_A^B \frac{\partial}{\partial \overline{Y}^B} \right) = u_i^j \varphi_j^A \frac{\partial}{\partial \overline{x}^A} = \varphi_*e_i,$$

which, together with $\overline{A}(\cdot, \cdot, \overline{Y}) = 0$ and $\varphi_*Y = \overline{Y}$, implies that

$$(2.2) \quad \overline{A}(\cdot, \cdot, \overline{\nabla}_{e_i} \varphi_*\ell) = \overline{A}(\cdot, \cdot, \overline{\nabla}_{\varphi_*e_i} \overline{\ell}) = 0,$$

where $\ell = Y/F$ and $\overline{\ell} = \overline{Y}/\overline{F}$.

In the following any vector $U \in TM$ will be identified with the corresponding vector $\varphi_*(U) \in T\overline{M}$ and we will use the following convention:

$$\begin{aligned} 1 \leq i, j, \dots \leq n; \quad n+1 \leq \alpha, \beta, \dots \leq n+p; \\ 1 \leq \lambda, \mu, \dots \leq n-1; \quad 1 \leq a, b, \dots \leq n+p. \end{aligned}$$

Let $\varphi : (M^n, F) \rightarrow (\overline{M}^{n+p}, \overline{F})$ be an isometric immersion. Take a \overline{g} -orthonormal frame $\{e_a\}$ for each fibre of $\pi^*T\overline{M}$ and let $\{\omega^a\}$ be its local dual coframe such that $\{e_i\}$ is a frame field for each fibre of π^*TM and ω^n is the Hilbert form, where $\pi : TM \rightarrow M$ denotes the natural projection. Let θ_b^a and ω_j^i denote the Chern connection 1-forms of \overline{F} and F , respectively, i.e., $\overline{\nabla}e_a = \theta_b^a e_b$ and $\nabla e_i = \omega_j^i e_j$, where $\overline{\nabla}$ and ∇ are the Chern connections of \overline{M} and M , respectively. We find that $A(e_i, e_j, e_n) = \overline{A}(e_a, e_b, e_n) = 0$, where $e_n = \frac{Y^i}{F} \frac{\partial}{\partial x^i}$ is the natural dual of the Hilbert form ω^n . Formula (2.2) implies

LEMMA 2.1. *Let $\varphi : (M^n, F) \rightarrow (\overline{M}^{n+p}, \overline{F})$ be an isometric immersion from a Finsler manifold to a Minkowski space. Then $\overline{A}(\cdot, \cdot, \overline{\nabla}_{e_i} e_n) = 0$.*

From $\omega^\alpha = 0$ and the structure equations of \overline{M} , we have $\theta_j^\alpha \wedge \omega^j = 0$, which implies that $\theta_j^\alpha = h_{ij}^\alpha \omega^i$, $h_{ij}^\alpha = h_{ji}^\alpha$. We obtain [L1]

$$(2.3) \quad \omega_i^j = \theta_i^j - \Psi_{jik} \omega^k,$$

where

$$(2.4) \quad \begin{aligned} \Psi_{jik} &= h_{jn}^\alpha \bar{A}_{kia} - h_{kn}^\alpha \bar{A}_{ji\alpha} - h_{in}^\alpha \bar{A}_{kja} \\ &\quad - h_{nn}^\alpha \bar{A}_{iks} \bar{A}_{sj\alpha} + h_{nn}^\alpha \bar{A}_{ijs} \bar{A}_{sk\alpha} + h_{nn}^\alpha \bar{A}_{jks} \bar{A}_{si\alpha}. \end{aligned}$$

In particular,

$$(2.5) \quad \omega_i^n = \theta_i^n - h_{nn}^\alpha \bar{A}_{kia} \omega^k.$$

Using the almost \bar{g} -compatibility, we have

$$(2.6) \quad \theta_\alpha^j = (-h_{ij}^\alpha - 2h_{ni}^\beta \bar{A}_{j\alpha\beta} + 2h_{nn}^\beta \bar{A}_{j\lambda\alpha} \bar{A}_{i\lambda\beta}) \omega^i - 2\bar{A}_{j\alpha\lambda} \omega_n^\lambda.$$

In particular, $\theta_\alpha^n = -h_{ni}^\alpha \omega^i$.

We quote the following propositions:

PROPOSITION 2.2 (Gauss equations, [L1, Theorem 3.1]). *Let $\varphi : (M^n, F) \rightarrow (\bar{M}^{n+p}, \bar{F})$ be an isometric immersion from a Finsler manifold to a Finsler manifold. Then*

$$\begin{aligned} P_{ik\lambda}^j &= \bar{P}_{ik\lambda}^j + \Psi_{jik;\lambda} - 2\Psi_{sik} A_{js\lambda} - 2h_{ik}^\alpha \bar{A}_{j\lambda\alpha}, \\ R_{ikl}^j &= \bar{R}_{ikl}^j - h_{ik}^\alpha h_{jl}^\alpha + h_{il}^\alpha h_{jk}^\alpha + \Psi_{jik|l} - \Psi_{jil|k} \\ &\quad + \Psi_{sik} \Psi_{jsl} - \Psi_{sil} \Psi_{jsk} - 2h_{ik}^\alpha h_{nl}^\beta \bar{A}_{j\alpha\beta} + 2h_{il}^\alpha h_{nk}^\beta \bar{A}_{j\alpha\beta} \\ &\quad + 2h_{ik}^\alpha h_{nn}^\beta \bar{A}_{js\alpha} \bar{A}_{ls\beta} - 2h_{il}^\alpha h_{nn}^\beta \bar{A}_{js\alpha} \bar{A}_{ks\beta} - h_{nn}^\alpha \bar{A}_{sl\alpha} \bar{P}_{iks}^j \\ &\quad + h_{nn}^\alpha \bar{A}_{ska} \bar{P}_{ils}^j + h_{nl}^\alpha \bar{P}_{ik\alpha}^j - h_{nk}^\alpha \bar{P}_{il\alpha}^j, \end{aligned}$$

where “;” and “|” denote the vertical and the horizontal covariant differentials with respect to the Chern connection ∇ respectively.

PROPOSITION 2.3 (Codazzi equations, [L1, Theorem 3.2]). *Let $\varphi : (M^n, F) \rightarrow (\bar{M}^{n+p}, \bar{F})$ be an isometric immersion from a Finsler manifold to a Finsler manifold. Then*

$$\begin{aligned} h_{ij;\lambda}^\alpha &= -\bar{P}_{ij\lambda}^\alpha, \\ h_{ij|k}^\alpha - h_{ik|j}^\alpha &= -\bar{R}_{ijk}^\alpha + h_{nj}^\beta \bar{P}_{ik\beta}^\alpha - h_{nk}^\beta \bar{P}_{ij\beta}^\alpha \\ &\quad - h_{lk}^\alpha \Psi_{lij} + h_{lj}^\alpha \Psi_{lik} - h_{nn}^\beta \bar{A}_{l\beta} \bar{P}_{ikl}^\alpha + h_{nn}^\beta \bar{A}_{lk\beta} \bar{P}_{ijl}^\alpha. \end{aligned}$$

PROPOSITION 2.4 ([L2, Theorem 4.4]). *An isometric immersion $\varphi : (M, F) \rightarrow (\bar{M}, \bar{F})$ is minimal if and only if*

$$\int_{SM} \langle V, \mathcal{H} \rangle dV_{SM} = 0$$

for any vector $V \in \Gamma(TM)^\perp$, where

$$(2.7) \quad \mathcal{H} = \sum_i \left\{ B(e_i, e_i) + \sum_\alpha [2\bar{C}(e_\alpha, e_i, B(e_i, Fe_n)) + (\bar{\nabla}_{Fe_n^H} \bar{C})(e_i, e_i, e_\alpha) + 2\bar{C}(\bar{\nabla}_{Fe_n^H} e_i, e_i, e_\alpha)] e_\alpha \right\},$$

$\bar{C} = \bar{A}/\bar{F}, e_i^H$ and denotes the horizontal part of e_i .

DEFINITION 2.5. M^n is called of constant mean curvature if $H = |\mathcal{H}| =$ constant.

PROPOSITION 2.6 ([L2, Theorem 5.2]). Let M^n be a hypersurface of a Minkowski space $\bar{V}^{n+1} = (V^{n+1}, \bar{F})$. If M is Landsberg, then $h_{in}^{n+1} \bar{A}_{jn+1} = 0$ and $\Psi_{ijk} = 0$.

It follows from Lemma 2.1 that

$$(2.8) \quad \bar{A}(\cdot, \cdot, e_j) \omega_n^j(e_i) + \bar{A}(\cdot, \cdot, e_\lambda) \Psi_{\lambda ni} + \bar{A}(\cdot, \cdot, e_{n+1}) h_{ni}^{n+1} = 0.$$

Combining (2.8) and Proposition 2.5 immediately yields

PROPOSITION 2.7. Let M^n be a Landsberg hypersurface of a Minkowski space (V^{n+1}, \bar{F}) . Then $h_{ni}^{n+1} \bar{A}_{jn+1n+1} = h_{ni}^{n+1} \bar{A}_{n+1n+1n+1} = 0$.

PROPOSITION 2.8. If M^n is a Landsberg hypersurface of a Minkowski space \bar{V}^{n+1} with constant mean curvature, then $\sum_i h_{ii}^{n+1} =$ constant.

Proof. It follows from Propositions 2.5 and 2.6 and the first formula of Proposition 2.3 that

$$h_{nn|j}^{n+1} \bar{A}_{in+1n+1} \omega^j + h_{nn}^{n+1} \bar{A}_{in+1n+1;\lambda} \omega_n^\lambda + h_{nn}^{n+1} \bar{A}_{in+1n+1;n+1} h_{nj}^{n+1} \omega^j = 0,$$

which gives

$$(2.9) \quad h_{nn}^{n+1} \bar{A}_{in+1n+1;\lambda} = 0.$$

It follows from (2.9) and $\bar{A}_{abc;d} = \bar{A}_{abd;c}$ that

$$(2.10) \quad (\bar{\nabla}_{Fe_n^H} \bar{C})(e_i, e_i, e_{n+1}) = \bar{C}_{iin+1;\lambda} \theta_n^\lambda (Fe_n^H) + \bar{C}_{iin+1;n+1} \theta_n^{n+1} (Fe_n^H) = 0.$$

From Propositions 2.6 and 2.7 we can deduce that $\bar{C}(\bar{\nabla}_{Fe_n^H} e_i, e_i, e_{n+1}) = 0$. Therefore by (2.10) and (2.7), we have $H = B(e_i, e_i) = \sum_i h_{ii}^{n+1} e_{n+1}$. Since we are assuming that H is constant, it follows that $\sum_i h_{ii}^{n+1} =$ constant. ■

PROPOSITION 2.9. If a hypersurface M^n of a Minkowski space \bar{V}^{n+1} is a Landsberg manifold, then

$$\begin{aligned} h_{ij;\lambda;\mu}^{n+1} &= h_{ij;\mu;\lambda}^{n+1}, \\ h_{ij|k;\lambda}^{n+1} &= h_{ij;\lambda|k}^{n+1} - h_{sj}^{n+1} P_{ik\lambda}^s - h_{is}^{n+1} P_{jk\lambda}^s + h_{ij|k}^{n+1} \bar{A}_{n+1n+1\lambda}, \\ h_{ij|k|l}^{n+1} &= h_{ij|k|l}^{n+1} + h_{sj}^{n+1} R_{ikl}^s + h_{is}^{n+1} R_{jkl}^s. \end{aligned}$$

Proof. For a hypersurface (M^n, F) of a Minkowski space (V^{n+1}, \bar{F}) , we have

$$(2.11) \quad h_{ij|k}^{n+1} \omega^k + h_{ij;\lambda}^{n+1} \omega_n^\lambda = dh_{ij}^{n+1} - h_{kj}^{n+1} \omega_i^k - h_{ik}^{n+1} \omega_j^k + h_{ij}^{n+1} \theta_{n+1}^{n+1}.$$

Differentiating (2.11), we obtain

$$(2.12) \quad \left\{ h_{ij|k|l}^{n+1} - \frac{1}{2} h_{sj}^{n+1} R_{ikl}^s - \frac{1}{2} h_{is}^{n+1} R_{jkl}^s - \frac{1}{2} h_{ij;\lambda}^{n+1} R_{nkl}^\lambda \right. \\ \left. + 2h_{ij}^{n+1} h_{sk}^{n+1} h_{nl}^{n+1} \bar{A}_{sn+1n+1} - 2h_{ij}^{n+1} h_{sk}^{n+1} h_{nn}^{n+1} \bar{A}_{stn+1} \bar{A}_{tln+1} \right\} \omega^k \wedge \omega^l \\ + \left\{ h_{ij|k;\lambda}^{n+1} - h_{ij;\lambda|k}^{n+1} + h_{ij;\mu}^{n+1} P_{nk\lambda}^\mu + h_{is}^{n+1} P_{jk\lambda}^s + h_{sj}^{n+1} P_{ik\lambda}^s - h_{ij|k}^{n+1} \bar{A}_{n+1n+1\lambda} \right. \\ \left. + 2h_{ij}^{n+1} h_{sk}^{n+1} \bar{A}_{sn+1\lambda} \right\} \omega^k \wedge \omega_n^\lambda + h_{ij;\lambda;\mu}^{n+1} \omega_n^\lambda \wedge \omega_n^\mu = 0.$$

We obtain the conclusion immediately from (2.12), Propositions 2.5 and 2.6, and the first formula of Proposition 2.3. ■

3. Landsberg hypersurfaces of a Minkowski space. Let M^n be a Landsberg hypersurface with constant mean curvature of a Minkowski space \bar{V}^{n+1} . By Proposition 2.7, we have

$$(3.1) \quad \sum_i h_{ii|j}^{n+1} \omega^j + \sum_i h_{ii;\lambda}^{n+1} \omega_n^\lambda = 2 \sum_{ij} h_{ij}^{n+1} A_{ij\lambda} \omega_n^\lambda.$$

It follows from (3.1) that

$$(3.2) \quad \sum_i h_{ii|j}^{n+1} = 0 \quad \text{and} \quad \sum_i h_{ii;\lambda}^{n+1} = 2 \sum_{ik} h_{ik}^{n+1} A_{ik\lambda}.$$

Differentiating the first formula of (3.2), we obtain

$$\sum_i h_{ii|j|k}^{n+1} \omega^k + \sum_i h_{ii;j;\lambda}^{n+1} \omega_n^\lambda = 2 \sum_{ik} h_{ij|l}^{n+1} A_{ik\lambda} \omega_n^\lambda,$$

which implies that

$$(3.3) \quad \sum_i h_{ii|j|k}^{n+1} = 0.$$

DEFINITION 3.1. M is called *convex* if the second fundamental form h_{ij}^{n+1} of M is positive semi-definite.

Define $\delta Y^i = dY^i + N_j^i dx^j$. The pull-back of the Sasaki metric $g_{ij} dx^i \otimes dx^j + g_{ij} \delta Y^i \otimes \delta Y^j$ from $TM \setminus \{0\}$ to the sphere bundle SM is a Riemannian metric

$$\hat{g} = g_{ij} dx^i \otimes dx^j + \delta_{ab} \omega_n^a \otimes \omega_n^b.$$

We now quote two lemmas:

LEMMA 3.2 ([Mo, Lemma 2.2]). For $X = \sum_i x_i \omega^i \in \Gamma(\pi^* T^* M)$, $\text{div}_{\hat{g}} X = \sum_i x_{i|i} + \sum_{\mu,\lambda} x_\mu P_{\lambda\lambda\mu}^n$.

LEMMA 3.3 ([N, Theorem 1]). *All Landsberg spaces of nonzero constant flag curvature are Riemannian.*

Proof of Main Theorem. According to Propositions 2.2, 2.3, and 2.6–2.8,

$$(3.4) \quad R_{jkl}^i = h_{ik}^{n+1}h_{jl}^{n+1} - h_{il}^{n+1}h_{jk}^{n+1},$$

$$(3.5) \quad h_{ij;\lambda}^{n+1} = 0,$$

$$(3.6) \quad h_{ij|k}^{n+1} = h_{ik|j}^{n+1},$$

$$(3.7) \quad h_{ij|k|l}^{n+1} = h_{ij|l|k}^{n+1} + h_{sj}^{n+1}R_{ikl}^s + h_{is}^{n+1}R_{jkl}^s.$$

Let $\omega = dS = S_{|i}\omega^i + S_{;i}\omega_n^i$. Then ω is a global section on π^*T^*M . By (3.5), i.e., $S_{;i} = 0$, and Lemma 3.1, we have

$$(3.8) \quad \operatorname{div}_{\widehat{g}}\omega = 2 \sum_{i,j,k} (h_{ij|k}^{n+1})^2 + 2 \sum_{i,j,k} h_{ij}^{n+1}h_{ij|k|k}^{n+1}.$$

It can be seen from (3.3)–(3.8) that

$$(3.9) \quad \begin{aligned} \operatorname{div}_{\widehat{g}}\omega &= 2 \sum_{i,j,k} (h_{ij|k}^{n+1})^2 + 2 \sum_{i,j,k,s} h_{ij}^{n+1} \{h_{kk|i|j}^{n+1} + h_{si}^{n+1}R_{kjk}^s + h_{ks}^{n+1}R_{ijk}^s\} \\ &= 2 \sum_{i,j,k} (h_{ij|k}^{n+1})^2 + 2 \sum_{i,j,k,l} \{h_{ij}^{n+1}h_{ki}^{n+1}h_{jk}^{n+1}h_{ll}^{n+1} - 2(h_{ij}^{n+1}h_{kl}^{n+1})^2\}. \end{aligned}$$

Let λ_i be the eigenvalues of the second fundamental tensor h_{ij}^{n+1} of M . It is easy to see from (3.9) that

$$(3.10) \quad \frac{1}{2} \operatorname{div}_{\widehat{g}}\omega = \sum_{i,j,k} (h_{ij|k}^{n+1})^2 + \frac{1}{2} \sum_{i,j} (\lambda_i - \lambda_j)^2 \lambda_i \lambda_j.$$

Since M is convex, i.e., $\lambda_i \lambda_j \geq 0$ for all i, j , the right hand side of (3.10) is nonnegative. Because of the compactness of M , we infer that h_{ij}^{n+1} is constant and $h_{ij}^{n+1} = 0$ for all $i \neq j$ on M . Differentiating $h_{na}^{n+1} = 0$ yields $h_{aa}^{n+1} = h_{nn}^{n+1}$ for all $a = 1, \dots, n - 1$, i.e., $h_{ii}^{n+1} = H$ for all i . It is easy to see from (3.4) that

$$(3.11) \quad R_{ikl}^j = H(\delta_{il}\delta_{jk} - \delta_{ik}\delta_{jl}).$$

On the other hand, let $x = \bar{x}^a \partial / \partial \bar{x}^a$ be the position vector field of the Minkowski space V^{n+1} with respect to the origin. By a simple direct computation, we get $\bar{\nabla}_Z x = Z$ for all $Z = z^a \partial / \partial \bar{x}^a$ on V^{n+1} , which, together with Lemma 2.1, implies that $\nabla_{e_i} x^2 = 2\langle e_i, x \rangle$ and $\nabla_{e_i} \langle e_i, x \rangle = \theta_i^j \langle e_j, x \rangle + h_{ii}^{n+1} \langle e_{n+1}, x \rangle + 1$. As M is compact, there exists a point $P \in M$ such that $h_{ii}^{n+1}(P) > 0$ for all i , so $H > 0$. Thus by (3.11), M is a Landsberg space with nonzero constant flag curvature H , which together with Lemma 3.2 finishes the proof of Main Theorem.

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