

## Translation equation on monoids

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**Abstract.** We give large classes of solutions of the translation equation on a monoid satisfying the identity condition.

Let  $X$  be a nonempty set and let  $(G, \cdot)$  be a groupoid. By  $F : X \times G \rightarrow X$  we denote an arbitrary solution of the *translation equation*:

$$(1) \quad F(F(\alpha, k), l) = F(\alpha, k \cdot l), \quad \alpha \in X; k, l \in G.$$

This equation appears in several mathematical domains: abstract geometric and algebraic objects, abstract automata, groups of transformations, iterations, representations of groups, dynamical systems and others (see [5]) and therefore has at present a general theory (see [7]).

János Aczél of the University of Waterloo, in a letter to the second author, posed the following problem: what can we say about solutions  $F : X \times \mathbb{N} \rightarrow X$  of the translation equation (1) for which  $F(\alpha, 1) = \alpha$  (the *identity condition*), where  $X$  is an interval and  $(\mathbb{N}, \cdot)$  is the monoid of natural numbers?

We give large classes of solutions of the translation equation on monoids  $G$  satisfying the identity condition  $F(\alpha, 1) = \alpha$ , where 1 denotes the unit element of  $(G, \cdot)$ .

The problem of finding the general solution of the translation equation for  $(G, \cdot) = (\mathbb{N}, \cdot)$  is still open.

REMARK 1. If  $F$  is a solution of (1), then  $G$  acts on  $X$  by means of the mapping  $k \mapsto F(\cdot, k) : X \rightarrow X$ .

DEFINITION 1. A family  $\{E_j\}_{j \in J}$  of nonempty pairwise disjoint subsets of  $G$  is called an *invariant decomposition* of the groupoid  $(G, \cdot)$  if  $G = \bigcup_{j \in J} E_j$  and

$$(2) \quad \forall j \in J \forall k \in G \exists l \in J : (E_j \cdot k \subseteq E_l).$$

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**THEOREM 1.** *Let  $X$  be a nonempty set. Let  $X = \bigcup_{s \in S} X_s$  be a decomposition of  $X$  into a disjoint union of nonempty sets such that for every  $s \in S$  there exists an invariant decomposition  $\{E_{j_s}\}_{j \in J_s}$  of the monoid  $(G, \cdot)$  with  $\text{card } X_s = \text{card } J_s$ . Let  $\bar{g}_s: \{E_{j_s}\}_{j \in J_s} \rightarrow X_s$  be an arbitrary bijection and set  $g_s(k) := \bar{g}_s(E_{j_s})$  for  $k \in E_{j_s}$ . Then the function  $F: X \times G \rightarrow X$  defined by*

$$(3) \quad F(\alpha, k) = \}g_s(g_s^{-1}(\{\alpha\}) \cdot k)\{, \quad \alpha \in X_s, k \in G,$$

*is a solution of the translation equation (1) for which  $F(\alpha, 1) = \alpha$ .*

The symbol  $\}A\{$  in (3) denotes the element of a set  $A$  when  $\text{card } A = 1$ . The proof of Theorem 1 is a simple verification, so it can be omitted.

**REMARK 2.** The decomposition  $\{E_j\}_{j \in J}$  of  $G$  is invariant if and only if the relation

$$a \equiv b \Leftrightarrow \exists j \in J : a, b \in E_j$$

is *right-compatible* with the groupoid operation, i.e.

$$\forall a, b, c \in G : [a \equiv b \Rightarrow a \cdot c \equiv b \cdot c].$$

If the groupoid  $G$  is Abelian, then every equivalence relation  $\equiv$  right-compatible with the groupoid operation is a *congruence* relation, that is,

$$\forall a, b, c, d \in G : [(a \equiv b \wedge c \equiv d) \Rightarrow a \cdot c \equiv b \cdot d].$$

An equivalence relation  $\equiv$  on a groupoid  $G$  is a congruence (respectively: is right-compatible with the groupoid operation) if and only if there exists a function  $h: G \rightarrow G$  such that

$$(4) \quad a \equiv b \Leftrightarrow h(a) = h(b) \text{ and } h(a \cdot b) = h[h(a) \cdot h(b)]$$

(respectively:  $h(a \cdot b) = h[h(a) \cdot h(b)]$  for  $a, b \in G$ ).

In the case of a congruence relation, the function  $h$  is a homomorphism of  $G$  onto the groupoid  $h(G)$  with the operation  $c \# d = h(c \cdot d)$ . This means that the equivalence relation  $\equiv$  is a congruence in the groupoid  $(G, \cdot)$  if and only if there exists a homomorphism  $H$  of  $G$  into a groupoid  $T$  such that  $a \equiv b \Leftrightarrow H(a) = H(b)$  (see [2, pp. 35–37]). This yields a method of constructing invariant decompositions (see Remark 4, due to Andrzej Schinzel).

**REMARK 3.** If the groupoid  $G$  is a group, then its invariant decompositions are sets of right cosets of some subgroup (see [1, pp. 34–35]). Moreover, if the group  $G$  is Abelian then invariant decompositions are determined by quotient groups.

**REMARK 4** (by A. Schinzel). By Remark 2 all congruences  $\equiv$  in the monoid  $(\mathbb{N}, \cdot)$  are obtained by the following

CONSTRUCTION  $C_1$

- 1° Take an arbitrary Abelian semigroup  $(T, +)$  with neutral element 0.
- 2° Take an arbitrary function  $\phi : P \rightarrow T$ , where  $P$  is the set of all prime numbers. Define a homomorphism  $H : (\mathbb{N}, \cdot) \rightarrow (T, +)$  by setting, for  $a = \prod_{p \in P} p^{\alpha(p)} \in \mathbb{N}$ , where  $\alpha(p)$  are nonnegative integers,

$$H(a) := \sum_{p \in P} \alpha(p)\phi(p).$$

- 3° For  $a, b \in \mathbb{N}$  define:  $a \equiv b \Leftrightarrow H(a) = H(b)$ , that is,

$$\prod_{p \in P} p^{\alpha(p)} \equiv \prod_{p \in P} p^{\beta(p)} \Leftrightarrow \sum_{p \in P} \alpha(p)\phi(p) = \sum_{p \in P} \beta(p)\phi(p),$$

where  $\alpha(p), \beta(p)$  are nonnegative integers.

To describe all congruence relations means to describe all semigroups and, in consequence, to solve the association equation

$$F(F(a, b), c) = F(a, F(b, c)), \quad \text{where } F : G \times G \rightarrow G.$$

EXAMPLE 1 (by A. Schinzel). Let  $T := 2^{\mathbb{N}}$  be the monoid with the union operation. If we define  $\phi(p) := \{p\}$  we get the congruence relation

$$a \equiv b \Leftrightarrow a \text{ and } b \text{ have the same prime factors;}$$

this means that components of the invariant decomposition of  $\mathbb{N}$  are sets of natural numbers having the same prime factors.

REMARK 5. To obtain the same invariant decomposition as in Example 1, it is possible to take  $\mathbb{N}$  with a suitable operation in place of  $2^{\mathbb{N}}$ . The function  $h : \mathbb{N} \rightarrow \mathbb{N}$  such that  $h(a)$  equals the product of the prime factors of  $a$  for  $a > 1$  and  $h(1) = 1$  satisfies (4), hence  $h$  is a homomorphism of  $(\mathbb{N}, \cdot)$  into  $\mathbb{N}$  with the operation  $a \# b = h(a \cdot b)$ .

REMARK 6. When the monoid  $(G, \cdot)$  is the group then Theorem 1 yields all solutions of the translation equation (1) satisfying  $F(\alpha, 1) = \alpha$ . In this case the invariant decompositions consist of right cosets of some subgroup  $G_s$  of  $G$  (see Remark 3) and  $\bar{g}_s$  is equal to  $g_s$  and  $g_s : G/G_s \rightarrow X_s$ . Also the general solution of the translation equation (1) satisfying  $F(\alpha, 1) = \alpha$  has been given in [4] by the following

CONSTRUCTION  $C_2$

- 1° Let  $X = \bigcup_{s \in S} X_s$  be a disjoint union of nonempty sets (fibres)  $X_s$  such that for every  $s \in S$  there exists a subgroup  $G_s \leq G$  and a bijection  $g_s : G/G_s \rightarrow X_s$ , where  $G/G_s$  is the set of right cosets of  $G_s$  in  $G$ .
- 2° Then  $F(\alpha, k) = g_s(g_s^{-1}(\alpha) \cdot k)$ ,  $\alpha \in X_s, k \in G$ .

REMARK 7. Construction  $C_3$  mentioned below, quoted from [3], includes the general form of invariant decompositions for the subsemigroup  $G^+$  of positive elements of the group  $(G, +, \leq)$ , linearly ordered and Abelian.

Before the presentation of the construction of the decompositions, we need two definitions.

DEFINITION 2. A subset  $A$  of  $G$  is called *bounded* if  $\exists z \in G^+ \forall a \in A : (a < z \text{ and } a > -z)$ , and *unbounded* if it is not bounded.

DEFINITION 3. Let  $A, B$  be subsets of  $G$  and  $A \subseteq B \subseteq G$ . We say that:

(a)  $A$  is an *initial interval* of  $B$  if

$$\forall a_0 \in A : \{a \in B : a \leq a_0\} \subseteq A,$$

(b)  $A$  is a *final interval* of  $B$  if

$$\forall a_0 \in A : \{a \in B : a_0 \leq a\} \subseteq A.$$

All  $G^+$ -invariant decompositions of the semigroup  $G^+$  of positive elements of a linearly ordered, Abelian group  $G$  are obtained by

CONSTRUCTION  $C_3$

1° Take a family  $\{G_s\}_{s \in S}$  of distinct, bounded subgroups of  $G$  forming a chain, i.e.  $G_s \subset G_t$  or  $G_t \subset G_s$  for  $s, t \in S$ , and an unbounded subgroup  $G^*$  such that  $G^* \supseteq \bigcup_{s \in S} G_s$ .

2° Let  $\Phi$  be a function from the family  $\{G_s\}_{s \in S}$  onto a family of initial intervals of  $G^+$  such that

(a)  $\Phi(G_s)$  is a union of intersections with  $G^+$  of cosets of  $C(G_s)$  in  $G$ , where  $C(G_s)$  denotes the smallest convex subgroup containing  $G_s$  (the convexity of  $C(G_s)$  means that together with every positive element  $a$  the subgroup  $C(G_s)$  contains all elements  $x \in G^+$  with  $x \leq a$ ),

(b) if  $G_s \subset G_t$ , then  $\Phi(G_s) \subset \Phi(G_t)$ .

3° Every nonempty set

$$W \cap \left[ \Phi(G_s) \setminus \bigcup_{G_t \subsetneq G_s} \Phi(G_t) \right], \quad W \in G_s, \quad s \in S,$$

is a component of the decomposition.

4° The sets

$$V \cap \left[ G^+ \setminus \bigcup_{s \in S} \Phi(G_s) \right], \quad V \in G/G^*,$$

are the remaining components.

If we assume additionally that  $(G, +, \leq)$  is an Archimedean group, then Construction  $C_3$  is reduced to the following result from the paper [6].

Every  $G^+$ -invariant decomposition of the semigroup  $G^+$  of positive elements of a linearly ordered, Archimedean group is of the following form:

- (a) there exists a right-closed or right-open interval  $[0, x_0]$  such that every element belonging to  $[0, x_0]$  is a component of the decomposition (this interval may be empty),
- (b) the remaining components are the intersections with  $G^+ \setminus [0, x_0]$  of cosets of some subgroup  $G^*$  in  $G$ .

Using Construction  $C_3$  and Theorem 1 we can obtain examples of solutions for the semigroup  $G^+$  of positive elements of a linearly ordered, Abelian group  $(G, +, \leq)$ .

EXAMPLE 2. Let  $\mathbb{Z}$  denote the set of integers and  $G := \{ax + b : a, b \in \mathbb{Z}\}$  be the group of linear polynomials with ordinary addition and with linear order defined as follows:

$$(ax + b \leq cx + d) \Leftrightarrow (a < c) \text{ or } (a = c \text{ and } b \leq d).$$

The semigroup of positive elements is

$$G^+ := \{ax + b : a > 0, b \in \mathbb{Z}\} \cup \mathbb{Z}^+,$$

where  $\mathbb{Z}^+ := \{a \in \mathbb{Z} : a \geq 0\}$ . According to Construction  $C_3$ , take the chain of bounded subgroups  $\{0\} \subset \mathbb{Z}$  and the unbounded subgroup  $G^* := G$ . Define  $\Phi(\{0\}) := \mathbb{Z}^+$  and  $\Phi(\mathbb{Z}) := \mathbb{Z}^+ \cup (\mathbb{Z} + x)$ , where  $\mathbb{Z} + x \in G/\mathbb{Z}$ . Every element of  $\mathbb{Z}^+$  is a component of the decomposition. The sets  $\mathbb{Z} + x$ ,  $G^+ \setminus (\mathbb{Z}^+ \cup (\mathbb{Z} + x))$  are also components.

Let now  $X := [0, \infty[$ ,  $S := [0, 1[$ ,  $X_s := \{s + j : j = 0, 1, 2, \dots\}$  and  $J_s := \mathbb{N} \cup \{0\}$  for  $s \in S$ . Moreover,  $E_{0s} := \mathbb{Z} + x$ ,  $E_{1s} := G^+ \setminus (\mathbb{Z}^+ \cup (\mathbb{Z} + x))$  and  $E_{js} := \{j - 2\}$  for  $j \in \{2, 3, 4, \dots\}$  and  $s \in S$ . Assume that  $\bar{g}_s(E_{js}) := s + j$  for  $j \in \mathbb{N} \cup \{0\}$  and for  $s \in S$ . We get the following solution  $F : X \times G^+ \rightarrow X$  of the translation equation:

$$F(\alpha, w) = \begin{cases} \alpha & \text{if } \alpha \in [0, 1[ \text{ and } w \in \mathbb{Z}^+ \text{ or } \alpha \in [1, 2[ \text{ and } w \in G^+, \\ \alpha + 1 & \text{if } \alpha \in [0, 1[ \text{ and } w \in G^+ \setminus \mathbb{Z}^+, \\ \alpha - E(\alpha) & \text{if } \alpha \in X \setminus [0, 2[ \text{ and } w \in \mathbb{Z} + x, \\ \alpha - E(\alpha) + 1 & \text{if } \alpha \in X \setminus [0, 2[ \text{ and } w \in G^+ \setminus (\mathbb{Z}^+ \cup (\mathbb{Z} + x)), \\ \alpha + w & \text{if } \alpha \in X \setminus [0, 2[ \text{ and } w \in \mathbb{Z}^+, \end{cases}$$

where  $E(\alpha)$  denotes the integer part of  $\alpha$ .

In what follows  $(\mathbb{N}, \cdot)$  and  $(\mathbb{Q}_+, \cdot)$  denote the monoid of natural numbers and the group of positive rational numbers respectively.

Using Theorem 1 we can obtain examples of solutions for  $(G, \cdot) = (\mathbb{N}, \cdot)$ .

EXAMPLE 3. Let  $X := ]1/4, 1]$  and take  $S := ]1/2, 1]$ ,  $X_s := ]s/2, s]$ ,  $J_s := \{1, 2\}$  for  $s \in S$ . Moreover,  $E_{1s} := \{1, 3, 5, \dots\}$ ,  $E_{2s} := \{2, 4, 6, \dots\}$  for

$s \in S$ . Define  $\bar{g}_s(E_{1s}) := s/2$ ,  $\bar{g}_s(E_{2s}) := s$  for  $s \in S$ . We get the following solution:

$$F(\alpha, k) = \begin{cases} 2\alpha & \text{for } \alpha \in ]1/4, 1/2], k \in \{2, 4, 6, \dots\}, \\ \alpha & \text{for } \alpha \in ]1/2, 1], k \in \mathbb{N} \text{ or } \alpha \in ]1/4, 1/2], k \in \{1, 3, 5, \dots\}. \end{cases}$$

EXAMPLE 4. Let  $X, S, \{X_s\}, J_s$  for  $s \in S$  be as in Example 3. We take  $E_{1s} := \{1\}$ ,  $E_{2s} := \mathbb{N} \setminus \{1\}$  for  $s \in S$ . The functions  $\bar{g}_s$  are defined as in Example 2. We get the following solution:

$$F(\alpha, k) = \begin{cases} 2\alpha & \text{for } \alpha \in ]1/4, 1/2], k \in \mathbb{N} \setminus \{1\}, \\ \alpha & \text{for } \alpha \in ]1/2, 1], k \in \mathbb{N} \text{ or } \alpha \in ]1/4, 1/2], k = 1. \end{cases}$$

EXAMPLE 5. Let  $X := [0, \infty[$ ,  $S := [0, 1[$ ,  $X_s := \{s + j : j = 0, 1, 2, \dots\}$ ,  $J_s := \mathbb{N} \cup \{0\}$  for  $s \in S$ . Moreover,  $E_{0s} := \{2, 4, 6, \dots\}$  and  $E_{js} := \{2j - 1\}$  for  $j \in \mathbb{N}$  and  $s \in S$ . Define  $\bar{g}_s(E_{js}) := s + j$  for  $j \in \mathbb{N} \cup \{0\}$  and  $s \in S$ . We get the following solution:

$$F(\alpha, k) = \begin{cases} \alpha - E(\alpha) & \text{for } \alpha \in X \setminus [0, 1[ \text{ and } k \in \{2, 4, 6, \dots\}, \\ & \text{or } \alpha \in [0, 1[ \text{ and } k \in \mathbb{N}, \\ \alpha + E(\alpha)(k - 1) - (k - 1)/2 & \text{for } \alpha \in X \setminus [0, 1[ \text{ and } k \in \{1, 3, 5, \dots\}, \end{cases}$$

where  $E(\alpha)$  denotes the integer part of  $\alpha$ .

REMARK 8. If we define  $\phi : P \rightarrow T = 2^{\mathbb{N}}$  by  $\phi(p) := \emptyset$  for  $p \neq 2$  and  $\phi(2) := \{1\}$ , where  $T = 2^{\mathbb{N}}$  denotes the monoid described in Example 1, then by Construction  $C_1(3^\circ)$  in Remark 4 we get the congruence equivalent to the invariant decomposition from Example 3, which means that  $E_1 := \{1, 3, 5, \dots\}$ ,  $E_2 := \{2, 4, 6, \dots\}$ .

Similarly, if we define  $\phi : P \rightarrow T = 2^{\mathbb{N}}$  by  $\phi(p) := \mathbb{N}$  for all  $p \in P$ , then by Construction  $C_1(3^\circ)$  we get the congruence equivalent to the invariant decomposition from Example 4, which means that  $E_1 := \{1\}$ ,  $E_2 := \mathbb{N} \setminus \{1\}$ .

To obtain the invariant decomposition from Example 5, it is sufficient to consider the semigroup  $(T, \cdot) := (2^{\mathbb{R} \setminus \{0\}}, \cdot)$ , where the operation is defined by  $A \cdot B := \{a \cdot b : a \in A, b \in B\}$  for  $A, B \in 2^{\mathbb{R} \setminus \{0\}}$ , and to define  $\phi : P \rightarrow T = 2^{\mathbb{R} \setminus \{0\}}$  by  $\phi(p) := \{p\}$  for  $p \neq 2$  and  $\phi(2) := \mathbb{R} \setminus \{0\}$ .

REMARK 9. If the solution of equation (1) is trivial, that is,  $F(\alpha, k) := \alpha$  for every  $(\alpha, k) \in X \times \mathbb{N}$ , where  $X$  denotes an arbitrary nonempty set, then the invariant decomposition of  $\mathbb{N}$  has exactly one element  $\{\mathbb{N}\}$ , the set  $X$  is decomposed into singletons and  $\bar{g}_s(\mathbb{N}) := s$ .

REMARK 10. The function  $F(\alpha, k) := k \cdot \alpha$  for  $(\alpha, k) \in X \times \mathbb{N}$  and  $X := ]0, \infty[$  is a solution of the translation equation (1). This solution is not of the form (3) (see Remark 11).

**THEOREM 2.** *Let  $X \subset \mathbb{R}$  be an arbitrary interval. Suppose that a solution  $F : X \times \mathbb{N} \rightarrow X$  of the translation equation (1) satisfying  $F(\alpha, 1) = \alpha$  for  $\alpha \in X$  can be extended to a solution  $\bar{F} : X \times \mathbb{Q}_+ \rightarrow X$  of this equation. Then there exists a family  $\{X_s\}_{s \in S}$  of disjoint sets such that  $\bigcup_{s \in S} X_s = X$  and for every  $s \in S$  there exists a subgroup  $\mathbb{Q}_s \leq \mathbb{Q}_+$  and a bijection  $g_s : \mathbb{Q}_+/\mathbb{Q}_s \rightarrow X_s$  for which*

$$(5) \quad F(\alpha, k) = g_s(g_s^{-1}(\alpha) \cdot k), \quad \alpha \in X_s, k \in \mathbb{N}.$$

*Proof.* This follows immediately from Construction  $C_2$ .

**THEOREM 3.** *Let  $X \subset \mathbb{R}$  be an arbitrary interval. A function  $F : X \times \mathbb{N} \rightarrow X$  is a solution of the translation equation (1) such that for every  $\alpha \in X$  the function  $F(\alpha, \cdot)$  is increasing and for every  $k \in \mathbb{N}$  the function  $F(\cdot, k)$  is increasing and surjective if and only if there exists a family  $\{X_s\}_{s \in S}$  of disjoint sets such that  $\bigcup_{s \in S} X_s = X$  and there exists a family of increasing bijections  $g_s : \mathbb{Q}_+ \rightarrow X_s, s \in S$ , such that*

$$(6) \quad F(\alpha, k) = g_s(g_s^{-1}(\alpha) \cdot k), \quad \alpha \in X_s, k \in \mathbb{N}.$$

We present two proofs of this theorem. The first one is a corollary from Theorem 2 and the other proof is direct.

*Proof I* (of the “only if” part of Theorem 3, using Theorem 2). Note that the assumptions about  $F : X \times \mathbb{N} \rightarrow X$  imply that  $F(\alpha, 1) = \alpha$  and  $F$  can be extended to a solution  $\bar{F} : X \times \mathbb{Q}_+ \rightarrow X$  of (1). Indeed, since  $F(F(\alpha, 1), 1) = F(\alpha, 1)$ , by injectivity of  $F(\cdot, 1)$  we get  $F(\alpha, 1) = \alpha$ . We can put

$$(7) \quad \bar{F}(\alpha, k/l) := \beta \quad \text{such that} \quad F(\alpha, k) = F(\beta, l),$$

for every  $\alpha \in X$  and  $k/l \in \mathbb{Q}_+$ . The existence and uniqueness of  $\beta$  result from the assumption that  $F(\cdot, l)$  is surjective and injective, so  $\bar{F}$  is correctly defined. One can verify easily that  $\bar{F}$  is a solution of the translation equation. Indeed, let

$$\bar{F}\left(\bar{F}\left(\alpha, \frac{k}{l}\right), \frac{m}{n}\right) =: \gamma \quad \text{and} \quad \bar{F}\left(\alpha, \frac{k \cdot m}{l \cdot n}\right) =: \delta.$$

If we set  $\bar{F}(\alpha, k/l) =: \beta$ , then by definition (7),  $F(\alpha, k) = F(\beta, l)$  and  $F(\beta, m) = F(\gamma, n)$  and  $F(\alpha, k \cdot m) = F(\delta, l \cdot n)$ . Hence

$$F(\gamma, n \cdot l) = F(\beta, m \cdot l) = F(\alpha, k \cdot m) = F(\delta, n \cdot l),$$

so  $\gamma = \delta$ .

Therefore, by Theorem 2, we have the form (5) of the solution  $F : X \times \mathbb{N} \rightarrow X$ . Since the functions  $F(\alpha, \cdot)$  are injective for every  $\alpha \in X$ , by Construction  $C_2$  we get  $\mathbb{Q}_s = \{1\} \leq \mathbb{Q}_+$  for every  $s \in S$ , which yields (6).

We will verify that the bijections  $\{g_s\}_{s \in S}$  are increasing. Let  $k/l < k_1/l_1$  and

$$g_s(k/l) =: \alpha, \quad g_s(k_1/l_1) =: \beta.$$

By (6) and by definition of  $\bar{F}$  we get

$$\bar{F}\left(\alpha, \frac{k_1 l}{k l_1}\right) = g_s\left(\frac{k}{l} \cdot \frac{k_1 l}{k l_1}\right) = g_s\left(\frac{k_1}{l_1}\right) = \beta, \quad \text{whence} \quad F(\alpha, k_1 l) = F(\beta, k l_1).$$

Since  $k l_1 < l k_1$ , by assumptions we have

$$F(\alpha, k l_1) < F(\alpha, k_1 l) = F(\beta, k l_1) \quad \text{and} \quad \alpha < \beta.$$

Since the “if” part is evident, the first proof is complete.

*Proof II* (of the “only if” part of Theorem 3). We define the following relation in  $X$ :

$$\forall \alpha, \beta \in X : \quad \alpha \sim_F \beta \Leftrightarrow \exists k, l \in \mathbb{N} : F(\alpha, k) = F(\beta, l).$$

It is to verify that it is an equivalence relation. Indeed, evidently it is symmetric and reflexive. Let now  $\alpha \sim_F \beta$  and  $\beta \sim_F \gamma$ . Then

$$\exists k, l, k_1, l_1 \in \mathbb{N} : \quad F(\alpha, k) = F(\beta, l) \quad \text{and} \quad F(\beta, k_1) = F(\gamma, l_1).$$

Hence

$$F(\alpha, k \cdot k_1) = F(\beta, l \cdot k_1) = F(\gamma, l \cdot l_1), \quad \text{so} \quad \alpha \sim_F \gamma.$$

We denote by  $\{X_s\}_{s \in S}$  the set of equivalence classes. Fix  $s \in S$  and  $\alpha_0 \in X_s$ . We define  $h_s : X_s \rightarrow \mathbb{Q}_+$  by

$$h_s(\alpha) := k/l, \quad \text{where} \quad F(\alpha_0, k) = F(\alpha, l).$$

The function  $h_s$  is correctly defined. Indeed, if

$$F(\alpha_0, k) = F(\alpha, l) \quad \text{and} \quad F(\alpha_0, k_1) = F(\alpha, l_1),$$

then

$$F(\alpha_0, l \cdot k_1) = F(\alpha, l \cdot l_1) = F(\alpha_0, l_1 \cdot k).$$

Since  $F(\alpha_0, \cdot)$  is injective,  $l \cdot k_1 = l_1 \cdot k$ , whence  $k_1/l_1 = k/l$ .

We will show that  $h_s : X_s \rightarrow \mathbb{Q}_+$  is a bijection. If  $h_s(\alpha) = h_s(\beta) = k/l$  then  $F(\alpha, l) = F(\alpha_0, k) = F(\beta, l)$  and by injectivity of  $F(\cdot, l)$  we get  $\alpha = \beta$ . To prove the surjectivity, take  $m/n \in \mathbb{Q}_+$ . Let  $F(\alpha_0, m) = \beta$ . By the surjectivity of  $F(\cdot, n)$ , we have  $F(\alpha_0, m) = \beta = F(\alpha, n)$  for some  $\alpha$ , so  $h_s(\alpha) = m/n$ .

Now, we will show that  $h_s$  is an increasing function. Let  $\alpha < \beta$  and

$$h_s(\alpha) = k/l, \quad h_s(\beta) = k_1/l_1.$$

We have  $F(\alpha_0, k) = F(\alpha, l)$  and  $F(\alpha_0, k_1) = F(\beta, l_1)$ . Since  $F(\cdot, ll_1)$  is increasing, we obtain

$$F(\alpha_0, k l_1) = F(\alpha, ll_1) < F(\beta, ll_1) = F(\alpha_0, k_1 l),$$

therefore  $k l_1 < k_1 l$  and  $k/l < k_1/l_1$ .



Let now  $\alpha \in X_s$ ,  $k \in \mathbb{N}$ . Let  $h_s(\alpha) = K/L$  and  $\beta := F(\alpha, k)$ . Hence

$$h_s(\alpha) \cdot k = K \cdot k/L.$$

We will show

$$h_s(\beta) = K \cdot k/L.$$

Indeed, we have  $F(\beta, L) = F(\alpha, kL)$ ,  $F(\alpha_0, K) = F(\alpha, L)$  and

$$F(\alpha_0, Kk) = F(\alpha, Lk) = F(\beta, L),$$

therefore  $h_s(\beta) = K \cdot k/L$ , and so

$$F(\alpha, k) = \beta = h_s^{-1}(K \cdot k/L) = h_s^{-1}(h_s(\alpha) \cdot k).$$

Putting  $g_s = h_s^{-1}$  we have the form (6), which was to be shown.

REMARK 11. If  $F : X \times \mathbb{N} \rightarrow X$  satisfies the assumptions of Theorem 3, then  $F$  cannot be obtained by means of Theorem 1.

Indeed, otherwise let  $g_s(1) =: \alpha_0$  for some  $s \in S$ . Then  $X_s = \{F(\alpha_0, k) : k \in \mathbb{N}\} = g_s(\mathbb{N})$  and  $\alpha_0 \in X_s$ . Let  $\bar{F} : X \times \mathbb{Q}_+ \rightarrow X$  be an extension of the solution  $F$ . Since  $\bar{F}(\alpha_0, 1/2) < F(\alpha_0, k)$  for  $k \in \mathbb{N}$ , we have  $\bar{F}(\alpha_0, 1/2) \notin X_s$ . Let  $\bar{F}(\alpha_0, 1/2) \in X_t$ ,  $t \neq s$ . Hence

$$F(\bar{F}(\alpha_0, 1/2), 2) = F(\alpha_0, 1) = \alpha_0,$$

so  $\alpha_0 \in X_t$ , which contradicts the relation  $X_t \cap X_s = \emptyset$ .

REMARK 12. Let  $X := [0, \infty[$  and define  $F : X \times \mathbb{N} \rightarrow X$  by

$$F(\alpha, k) = \begin{cases} \alpha, & \alpha \in X, k = 1, \\ 1, & \alpha \in [0, 1], k \in \mathbb{N} \setminus \{1\}, \\ k\alpha, & \alpha \in X \setminus [0, 1], k \in \mathbb{N} \setminus \{1\}. \end{cases}$$

Then  $F$  is a solution of (1) which cannot be extended to a solution  $\bar{F} : X \times \mathbb{Q}_+ \rightarrow X$  and is not of the form (3).

Indeed, for every solution  $\bar{F} : X \times \mathbb{Q}_+ \rightarrow X$  of (1) satisfying  $\bar{F}(\alpha, 1) = \alpha$ , all functions  $\bar{F}(\cdot, k)$  ought to be bijections. But

$$F(1/2, 2) = 1 = F(3/4, 2),$$

therefore  $F$  cannot be extended to a solution  $\bar{F} : X \times \mathbb{Q}_+ \rightarrow X$ .

Moreover, by Theorem 1,  $\text{card } X_s = \text{card } J_s$  for  $s \in S$ . It is easy to see that for the solution  $F$  one of the elements of the family  $\{X_s\}_{s \in S}$  is the set  $X_n = [0, 1]$  for some  $n \in S$ . This implies the following contradiction:

$$c = \text{card } [0, 1] = \text{card } J_n \leq \text{card } \mathbb{N} = \aleph_0.$$

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