## On oscillation of solutions of forced nonlinear neutral differential equations of higher order II

by N. PARHI and R. N. RATH (Berhampur)

Abstract. Sufficient conditions are obtained so that every solution of

$$[y(t) - p(t)y(t - \tau)]^{(n)} + Q(t)G(y(t - \sigma)) = f(t)$$

where  $n \geq 2$ ,  $p, f \in C([0, \infty), \mathbb{R})$ ,  $Q \in C([0, \infty), [0, \infty))$ ,  $G \in C(\mathbb{R}, \mathbb{R})$ ,  $\tau > 0$  and  $\sigma \geq 0$ , oscillates or tends to zero as  $t \to \infty$ . Various ranges of p(t) are considered. In order to accommodate sublinear cases, it is assumed that  $\int_0^\infty Q(t) dt = \infty$ . Through examples it is shown that if the condition on Q is weakened, then there are sublinear equations whose solutions tend to  $\pm \infty$  as  $t \to \infty$ .

**1. Introduction.** In this paper, we study oscillatory and asymptotic behaviour of solutions of

(1) 
$$[y(t) - p(t)y(t-\tau)]^{(n)} + Q(t)G(y(t-\sigma)) = f(t),$$

where  $n \geq 2$ ,  $p, f \in C([0, \infty), \mathbb{R})$ ,  $Q \in C([0, \infty), [0, \infty))$ ,  $G \in C(\mathbb{R}, \mathbb{R})$ ,  $\tau > 0$ and  $\sigma \geq 0$ . In [5], most of the results hold for G satisfying

$$\liminf_{|u|\to\infty} G(u)/u > \lambda > 0.$$

We remove this restriction on G in the present work. In most of our results here we assume

(H<sub>1</sub>) 
$$\int_{0}^{\infty} Q(t) dt = \infty.$$

The technique employed in this paper is motivated by Lemma 2.1 (see Section 2). The results hold true for homogeneous equations associated with (1).

By a solution of (1) we mean a real-valued continuous function y on  $[T_y-\varrho,\infty)$  for some  $T_y \ge 0$ , where  $\varrho = \max\{\tau,\sigma\}$ , such that  $y(t)-p(t)y(t-\tau)$ 

<sup>2000</sup> Mathematics Subject Classification: 34C10, 34C15, 34K40.

 $Key\ words\ and\ phrases:$  oscillation, nonoscillation, neutral equations, asymptotic behaviour.

is *n*-times continuously differentiable and (1) is satisfied for  $t \in [T_y, \infty)$ . A solution of (1) is said to be *oscillatory* if it has arbitrarily large zeros; otherwise, it is called *nonoscillatory*.

## 2. Main results. The following assumptions are needed below:

- (H<sub>2</sub>) G is nondecreasing and uG(u) > 0 for  $u \neq 0$ .
- (H<sub>3</sub>) There exists  $F \in C^n([0,\infty),\mathbb{R})$  such that  $\lim_{t\to\infty} F(t) = 0$  and  $F^{(n)}(t) = f(t)$ .
- (H<sub>4</sub>) For u > 0 and v > 0, there exists  $\alpha > 0$  such that  $G(u) + G(v) \ge \alpha G(u+v)$ .
- $(\tilde{H}_4)$  For x < 0 and y < 0 there exists  $\beta > 0$  such that  $G(x) + G(y) \le \beta G(x+y)$ .

$$(\mathbf{H}_5) \quad G(uv) = G(u)G(v).$$

(H<sub>6</sub>) 
$$\int_{\tau}^{\infty} Q^*(t) dt = \infty$$
, where  $Q^*(t) = \min\{Q(t), Q(t-\tau)\}$ .

Further, p(t) satisfies one of the following conditions:

$$(A_1) \quad 0 \le p(t) \le p_1 < 1,$$

$$(A_2) \quad -1 < -p_2 \le p(t) \le 0,$$

 $(\mathbf{A}_3) \quad -p_3 \le p(t) \le 0,$ 

(A<sub>4</sub>) p(t) changes sign with  $-1 < -p_4 \le p(t) \le p_5 < 1$  such that  $p_4 + p_5 < 1$ , where  $p_4 > 0$  and  $p_5 > 0$ ,

$$(\mathbf{A}_5) \quad 1 \le p(t) \le p_6,$$

$$(\mathbf{A}_6) \quad 0 \le p(t) \le p_7.$$

REMARK 1. The prototype of a function G satisfying  $(H_1)-(\widetilde{H}_4)$  is  $G(u) = |u|^{\gamma} \operatorname{sgn} u, \gamma > 0$  (see [4, p. 292]). Note that  $(H_2)$  and  $(H_5)$  imply that G(-u) = -G(u). Further,  $(H_4)$  and G(-u) = -G(u) imply  $(\widetilde{H}_4)$ .

We need the following lemma.

LEMMA 2.1 ([3, p. 19]). Let  $F, G, p \in C([t_0, \infty), \mathbb{R}), t_0 \geq 0$ , be such that  $F(t) = G(t) - p(t)G(t - \tau), t \geq t_0 + \rho, \tau \geq 0, G(t) \neq 0$  for  $t \geq t_0$ ,  $\liminf_{t\to\infty} G(t) = 0$  if G(t) > 0 or  $\limsup_{t\to\infty} G(t) = 0$  if G(t) < 0, and  $\lim_{t\to\infty} F(t) = L$  exists. If p(t) satisfies  $(A_i), i = 1, 2, 5, 6$ , then L = 0.

THEOREM 2.2. Let  $(H_1)$ ,  $(H_2)$  and  $(H_3)$  hold. If p(t) satisfies either  $(A_1)$  or  $(A_2)$ , then every solution of (1) oscillates or tends to zero as  $t \to \infty$ .

*Proof.* Let y(t) be a nonoscillatory solution of (1). Then y(t) > 0 or y(t) < 0 for  $t \ge T_0 > T_y \ge 0$ . Let y(t) > 0 for  $t \ge T_0$ . For  $t \ge T_1 > T_0 + \rho$ , we set

(2) 
$$z(t) = y(t) - p(t)y(t - \tau), \quad w(t) = z(t) - F(t).$$

From (1) it follows that

(3) 
$$w^{(n)}(t) = -Q(t)G(y(t-\sigma)) \le 0$$

for  $t \ge T_1$ . Hence, for large t, each of  $w, w', w'', \ldots, w^{(n-1)}$  is monotonic and of constant sign.

We claim that y(t) is bounded. If not, then there exists a strictly increasing sequence  $\{t_n\} \subset [T_4, \infty)$  satisfying

(4)  $\lim_{n \to \infty} t_n = \infty, \qquad \lim_{n \to \infty} y(t_n) = \infty, \qquad y(t_n) = \max\{y(t) : t \in [T_1, t_n]\}.$ 

From (2) we obtain

(5) 
$$w(t_n) = y(t_n) - p(t_n)y(t_n - \tau) - F(t_n).$$

Assume (A<sub>1</sub>) holds. Then from (5) we get  $w(t_n) > (1-p_1)y(t_n) - F(t_n)$ for *n* large enough such that  $t_n - \tau > T_1$ . Thus  $\lim_{n\to\infty} w(t_n) = \infty$ . Consequently, w(t) > 0 and w'(t) > 0,  $t \ge T_2 > T_1$ . From (3) it follows that  $w^{(n-1)}(t) > 0, t \ge T_3 > T_2$ . On the other hand, for  $0 < \varepsilon < w(T_3), |F(t)| < \varepsilon$ for  $t \ge T_4 > T_3$ . Hence, for  $t \ge T_4, w(t) < y(t) - F(t) < y(t) + \varepsilon$ , which implies that  $0 < w(T_3) - \varepsilon < w(t) - \varepsilon < y(t)$ . Setting  $u(t) = w(t) - \varepsilon, t \ge T_4$ , we obtain  $0 < u(t) < y(t), u'(t) = w'(t) > 0, u^{(n-1)}(t) = w^{(n-1)}(t) > 0$  and  $u^{(n)}(t) = w^{(n)}(t) = -Q(t)G(y(t-\sigma))$ . Integrating from  $T_5$  to t ( $T_4 + \sigma < T_5 < t$ ) and using (H<sub>2</sub>) we obtain

$$u^{(n-1)}(t) = u^{(n-1)}(T_5) - \int_{T_5}^t Q(s)G(y(s-\sigma)) \, ds$$
  
$$< u^{(n-1)}(T_5) - G(u(T_5-\sigma)) \int_{T_5}^t Q(s) \, ds.$$

Hence  $u^{(n-1)}(t) < 0$  for large t by (H<sub>1</sub>), contradicting  $u^{(n-1)}(t) > 0$  for  $t \ge T_4$ . If (A<sub>2</sub>) is satisfied, then from (5) we get  $w(t_n) \ge y(t_n) - F(t_n)$ . Hence  $\lim_{n\to\infty} w(t_n) = \infty$ . Thus w(t) > 0 and w'(t) > 0 for  $t \ge T_2 > T_1$ . Consequently, from (3) it follows that  $w^{(n-1)}(t) > 0$  for  $t \ge T_3 > T_2$ . Since w(t) is increasing, we have, for  $t > T_3 + \tau$ ,

(6) 
$$(1-p_2)w(t) \le w(t) + p(t)w(t-\tau)$$
  
=  $y(t) - F(t) - p(t)p(t-\tau)y(t-2\tau) - p(t)F(t-\tau)$   
 $\le y(t) - F(t) - p(t)F(t-\tau).$ 

For  $0 < \varepsilon < (1 - p_2)w(T_3)$ , there exists  $T_4 > T_3$  such that  $|F(t)| < \varepsilon/2$ ,  $t \ge T_4$ . From (6) it follows that

$$(1 - p_2)w(T_3) < (1 - p_2)w(t) \le y(t) + \varepsilon/2 - p(t)\varepsilon/2 < y(t) + \varepsilon$$

for  $t > T_4 + \tau$  because w(t) is increasing and -p(t) < 1. Setting  $u(t) = (1-p_2)w(t) - \varepsilon$  for  $t > T_4 + \tau$ , we obtain  $0 < (1-p_2)w(T_3) - \varepsilon < u(t) < y(t)$ ,  $u'(t) = (1-p_2)w'(t) > 0$ ,  $u^{(n-1)}(t) = (1-p_2)w^{(n-1)}(t) > 0$  and

(7) 
$$u^{(n)}(t) = (1 - p_2)w^{(n)}(t) = -(1 - p_2)Q(t)G(y(t - \sigma)).$$

Integrating (7) from  $T_5$  to  $t (T_4 + 2\rho < T_5 < t)$  we obtain

$$u^{(n-1)}(t) < u^{(n-1)}(T_5) - (1-p_2) \int_{T_5}^t Q(s)G(u(s-\sigma)) ds$$
  
$$< u^{(n-1)}(T_5) - (1-p_2)G(u(T_5-\sigma)) \int_{T_5}^t Q(s) ds,$$

because u is increasing. Hence  $u^{(n-1)}(t) < 0$  for large t, due to (H<sub>1</sub>), a contradiction.

Thus y(t) is bounded. Consequently, whether p(t) satisfies (A<sub>1</sub>) or (A<sub>2</sub>), w(t) is bounded and hence

(8) 
$$(-1)^{n+k}w^{(k)}(t) < 0, \quad k = 1, \dots, n-1,$$

for  $t \ge T_6 > T_1$ . If  $\liminf_{t\to\infty} y(t) = \alpha > 0$ , then  $y(t) > \beta > 0$  for  $t \ge T_7 > T_6$ . Hence from (3) we get

$$w^{(n-1)}(t) < w^{(n-1)}(T_7 + \sigma) - G(\beta) \int_{T_7 + \sigma}^t Q(s) \, ds.$$

Thus, for large t,  $w^{(n-1)}(t) < 0$  by (H<sub>1</sub>), contrary to (8). We conclude that  $\liminf_{t\to\infty} y(t) = 0$ .

Since w(t) is bounded,  $\lim_{t\to\infty} w(t)$  exists due to (8) whether n is odd or even. Hence  $\lim_{t\to\infty} z(t)$  exists. Lemma 2.1 applied to (2) yields  $\lim_{t\to\infty} z(t) = 0$ .

If (A<sub>1</sub>) holds then for  $t \ge T_1, z(t) \ge y(t) - p_1 y(t-\tau)$  implies  $y(t) \le z(t) + p_1 y(t-\tau)$ . Hence  $\limsup_{t\to\infty} y(t) \le \lim_{t\to\infty} z(t) + p_1 \limsup_{t\to\infty} y(t-\tau)$ , that is,  $(1-p_1)\limsup_{t\to\infty} y(t) \le 0$ . Consequently,  $\lim_{t\to\infty} y(t) = 0$ .

If (A<sub>2</sub>) holds then  $y(t) \leq z(t)$  for  $t \geq T_1$ . Hence  $\lim_{t\to\infty} y(t) = 0$ . If y(t) < 0 for  $t \geq t_0$ , then we set x(t) = -y(t) for  $t \geq t_0$  to obtain

$$[x(t) - p(t)x(t-\tau)]^{(n)} + Q(t)\widetilde{G}(x(t-\sigma)) = \widetilde{f}(t),$$

where  $\tilde{f}(t) = -f(t)$  and  $\tilde{G}(u) = -G(-u)$ . If  $\tilde{F}(t) = -F(t)$ , then (H<sub>2</sub>) and (H<sub>3</sub>) are satisfied for  $\tilde{G}$  and  $\tilde{F}$  respectively. Hence  $\lim_{t\to\infty} x(t) = 0$ , that is,  $\lim_{t\to\infty} y(t) = 0$ . Thus the theorem is proved.

As a consequence of Theorem 2.2 we get the following.

COROLLARY 2.3. Under the assumptions of Theorem 2.2, every nonoscillatory solution of (1) tends to zero as  $t \to \infty$  and hence every unbounded solution of (1) oscillates.

REMARK 2. Theorem 2.2 remains true if  $f(t) \equiv 0$ .

For sublinear G, that is, G satisfying  $\int_0^{\pm c} du/G(u) < \infty$ , c > 0, or  $\liminf_{|u|\to 0} G(u)/u > \mu > 0$ , condition (H<sub>1</sub>) cannot be relaxed e.g. to

 $\int_0^\infty t^{n-1}Q(t)\,dt=\infty$  used in [5]. This follows from the example given below.

EXAMPLE. Consider

(9)  $[y(t) - py(t-1)]'' + \frac{3}{8}(t-1)^{-1/2}(t^{-3/2} - p(t-1)^{-3/2})y^{1/3}(t-1) = 0$ with either  $0 and <math>t \ge t_0 > \max\{2, (1 - (2p)^{2/3})^{-1}\}$ , or  $-1 and <math>t > t_0 > 2$ . In the first case (H<sub>1</sub>) fails because from the inequality

 $Q(t) = \frac{3}{8}[t^{-3/2}(t-1)^{-1/2} - p(t-1)^{-2}] < \frac{3}{8}[t^{-3/2} - p(t-1)^{-2}]$ 

it follows that  $\int_{t_0}^{\infty} Q(t) dt < \infty$ . However,

$$Q(t) > \frac{3p}{8} [2(t-1)^{-2} - (t-1)^{-2}] = \frac{3p}{8} (t-1)^{-2}$$

implies that

$$\int_{t_0}^t sQ(s) \, ds > \frac{3p}{8} \int_{t_0}^t s(s-1)^{-2} \, ds > \ln[(t-1)/(t_0-1)].$$

Hence  $\int_{t_0}^{\infty} Q(t) dt = \infty$ . Similarly in the second case  $\int_{t_0}^{\infty} Q(t) dt < \infty$  and  $\int_{t_0}^{t} sQ(s) ds > \frac{3}{8} \int_{t_0}^{t} ds/s$  implies that  $\int_{t_0}^{\infty} tQ(t) dt = \infty$ . In both cases, (9) admits a solution  $y(t) = t^{3/2}$  which is nonoscillatory and unbounded.

In the following theorem, p(t) is allowed to change sign.

THEOREM 2.4. Let  $(H_1)$ ,  $(H_2)$  and  $(H_3)$  hold. Let p(t) be  $\tau$ -periodic and  $(A_4)$  be satisfied. Then every solution of (1) oscillates or tends to zero as  $t \to \infty$ .

*Proof.* Let y(t) be a nonoscillatory solution of (1). Proceeding as in the proof of Theorem 2.2 we conclude that there is a sequence  $\{t_n\}$  satisfying (4). Then (5) and (A<sub>4</sub>) yield

$$w(t_n) \ge y(t_n) - p_5 y(t_n - \tau) F(t_n) \ge (1 - p_5) y(t_n) - F(t_n)$$

Hence  $\lim_{n\to\infty} w(t_n) = \infty$ . Thus w(t) > 0 and w'(t) > 0 for  $t \ge T_2 > T_1$ . From (3) it follows that  $w^{(n-1)}(t) > 0$  for  $t \ge T_3 > T_2$ . Since w(t) is increasing and positive and  $p(t) = p(t - \tau)$ , we obtain

$$(1 - p_4)w(t) < w(t) - p_4w(t - \tau) < w(t) + p(t)w(t - \tau)$$
  
=  $y(t) - F(t) - p(t)p(t - \tau)y(t - 2\tau) - p(t)F(t - \tau)$   
=  $y(t) - F(t) - p^2(t)y(t - 2\tau) - p(t)F(t - \tau)$   
<  $y(t) - F(t) - p(t)F(t - \tau)$ 

for  $t \ge T_4 > T_3 + \rho$ . Then proceeding as in the proof of Theorem 2.2 we arrive at a contradiction. Hence y(t) is bounded. Consequently,  $\lim_{t\to\infty} z(t)$  exists. Applying the argument of the proof of Theorem 2.2, we may show

that  $\liminf_{t\to\infty} y(t) = 0$ . As Lemma 2.1 cannot be applied here to show that  $\limsup_{t\to\infty} y(t) = 0$ , we proceed as follows: observe that

$$\lim_{t \to \infty} z(t) = \limsup_{t \to \infty} [y(t) - p(t)y(t - \tau)] \ge \limsup_{t \to \infty} [y(t) - p_5 y(t - \tau)]$$
$$\ge \limsup_{t \to \infty} y(t) + \liminf_{t \to \infty} [-p_5 y(t - \tau)]$$
$$= \limsup_{t \to \infty} y(t) - p_5 \limsup_{t \to \infty} y(t - \tau)$$
$$= (1 - p_5) \limsup_{t \to \infty} y(t)$$

and

$$\lim_{t \to \infty} z(t) = \liminf_{t \to \infty} [y(t) - p(t)y(t - \tau)] \le \liminf_{t \to \infty} [y(t) + p_4 y(t - \tau)]$$
$$\le \liminf_{t \to \infty} y(t) + \limsup_{t \to \infty} [p_4 y(t - \tau)] = p_4 \limsup_{t \to \infty} y(t - \tau)$$
$$= p_4 \limsup_{t \to \infty} y(t),$$

since  $\liminf_{t\to\infty} y(t) = 0$ . Combining the above inequalities we get

$$0 \le (1 - p_5 - p_4) \limsup_{t \to \infty} y(t) \le 0,$$

because  $p_4 + p_5 < 1$ . Hence  $\lim_{t\to\infty} y(t) = 0$ . If y(t) < 0 for  $t \ge T_0$ , we obtain  $\lim_{t\to\infty} y(t) = 0$  in a similar manner. Thus the theorem is proved.

THEOREM 2.5. Suppose that  $(H_1)-(\widetilde{H}_4)$  hold and Q is decreasing. If  $p(t) \equiv -1$ , then every solution of (1) oscillates or tends to zero as  $t \to \infty$ .

Proof. Proceeding as in the previous proofs we show that w(t) is monotonic and hence  $\lim_{t\to\infty} w(t) = \ell$ , where  $-\infty \leq \ell \leq \infty$ . If  $-\infty \leq \ell < 0$ then z(t) < 0 for large t, a contradiction. If  $\ell = 0$ , then z(t) > y(t) implies that  $\lim_{t\to\infty} y(t) = 0$ . Suppose  $0 < \ell \leq \infty$ . Then  $w^{(n-1)}(t) > 0$  for large tand hence  $\lim_{t\to\infty} w^{(n-1)}(t)$  exists and is finite. Further,  $z(t) > \lambda > 0$  for  $t \geq T_2 > T_1$ . Integrating (3) from  $T_2$  to s ( $s > T_2$ ) and then taking the limit as  $s \to \infty$ , we obtain

(10) 
$$\int_{T_2}^{\infty} Q(t)G(y(t-\sigma)) dt < \infty.$$

On the other hand, for  $T_3 > T_2 + \varrho$ ,  $\int_{T_3}^{\infty} Q(t)G(z(t-\sigma)) dt \ge G(\lambda) \int_{T_3}^{\infty} Q(t) dt$ implies  $\int_{T_3}^{\infty} Q(t)G(z(t-\sigma)) dt = \infty$  due to (H<sub>1</sub>). Hence

$$\int_{T_3}^{\infty} Q(t) [G(y(t-\sigma)) + G(y(t-\sigma-\tau))] dt = \infty$$

by (H<sub>4</sub>). Consequently, using (10), we obtain  $\int_{T_3}^{\infty} Q(t)G(y(t-\sigma-\tau)) dt = \infty$ ,

that is,

$$\infty = \int_{T_3-\tau}^{\infty} Q(s+\tau)G(y(s-\sigma))\,ds < \int_{T_3-\tau}^{\infty} Q(s)G(y(s-\sigma))\,ds < \infty,$$

a contradiction. Hence  $\ell = 0$  is the only possibility. The proof of the theorem is thus complete.

THEOREM 2.6. Let  $(H_2)-(H_6)$  hold. If p(t) satisfies  $(A_3)$ , then every solution of (1) oscillates or tends to zero as  $t \to \infty$ . (Observe that  $(H_6) \Rightarrow (H_1)$ and it is not necessary to assume Q(t) to be decreasing in Theorem 2.6. However, if Q(t) is decreasing then  $(H_6)$  and  $(H_1)$  are equivalent.)

*Proof.* Using the notations of previous proofs, setting  $\lim_{t\to\infty} w(t) = \ell$ , we show that  $-\infty \leq \ell < 0$  is not possible and  $\ell = 0$  implies  $\lim_{t\to\infty} y(t) = 0$ . Assume, if possible, that  $0 < \ell \leq \infty$ . Hence  $z(t) > \lambda > 0$  and  $w^{(n-1)}(t) > 0$ for  $t \geq T_2 > T_1 > T_0 + \varrho$ . If  $t \geq T_3 > T_2 + \varrho$ , then using (H<sub>2</sub>), (H<sub>4</sub>), (H<sub>5</sub>) and (H<sub>6</sub>) we deduce from (3) that

$$0 = w^{(n)}(t) + Q(t)G(y(t-\sigma)) + G(-p(t-\sigma))[w^{(n)}(t-\tau) + Q(t-\tau)G(y(t-\tau-\sigma))] \geq w^{(n)}(t) + G(p_3)w^{(n)}(t-\tau) + \alpha Q^*(t)G(z(t-\sigma)) \geq w^{(n)}(t) + G(p_3)w^{(n)}(t-\tau) + \alpha G(\lambda)Q^*(t).$$

Integrating the above inequality and using  $(H_6)$  we get

$$w^{(n-1)}(t) + G(p_3)w^{(n-1)}(t-\tau) < 0$$

for large t, a contradiction. The case y(t) < 0 for  $t \ge T_0$  may be dealt with similarly. Thus the theorem is proved.

The following example shows that condition  $(H_6)$  cannot be weakened for sublinear G.

EXAMPLE. Consider (9) with p(t) = -3/2 for  $t \ge 2$ . We have

$$Q(t) = (t-1)^{-1/2} \left[\frac{3}{8}t^{-3/2} + \frac{9}{16}(t-1)^{-3/2}\right]$$

and Q(t) is decreasing. Further,  $Q(t) < \frac{15}{16}(t-1)^{-2}$  for  $t \geq 2$  implies that  $\int_2^{\infty} Q(t) dt < \infty$ . However,  $tQ(t) > \frac{3}{8}t^{-1/2}(t-1)^{-1/2} > 3/(8t)$ , so  $\int_2^{\infty} tQ(t) dt = \infty$ . Equation (9) admits a positive unbounded solution  $y(t) = t^{3/2}$ .

REMARK 3. In the literature there are a few papers dealing with the case  $p(t) \ge 1$  (see [1, 2, 5, 6]). In the following some results in this direction are obtained.

THEOREM 2.7. Suppose that n is odd and  $(H_1)$  and  $(H_2)$  hold. If p(t) satisfies  $(A_3)$  then every nonoscillatory solution of

(11) 
$$[y(t) - p(t)y(t-\tau)]^{(n)} + Q(t)G(y(t-\sigma)) = 0$$

tends to  $+\infty$  or  $-\infty$  as  $t \to \infty$ .

*Proof.* Proceeding as in the proof of Theorem 2.2, we deduce that

$$\lim_{t \to \infty} z^{(n-1)}(t) = \lambda, \qquad -\infty \le \lambda < \infty.$$

Suppose that  $-\infty < \lambda < \infty$ .

If  $\liminf_{t\to\infty} y(t) > 0$ , then  $y(t) > \beta > 0$  for  $t \ge T_3 > T_2$ . Hence

$$\int_{T_3+\sigma}^{\infty} Q(t)G(y(t-\sigma))\,dt > G(\beta) \int_{T_3+\sigma}^{\infty} Q(t)\,dt$$

implies that  $\int_{T_3+\sigma}^{\infty} Q(t)G(y(t-\sigma)) dt = \infty$  by (H<sub>1</sub>). On the other hand, integrating  $z^{(n)}(t) + Q(t)G(y(t-\sigma)) = 0$ , we obtain  $\int_{T_3+\sigma}^{\infty} Q(t)G(y(t-\sigma)) dt = z^{(n-1)}(T_3+\sigma) - \lambda < \infty$ , a contradiction. Hence  $\liminf_{t\to\infty} y(t) = 0$ .

Thus there exists a sequence  $\{t_n\} \subset [T_2, \infty)$  such that  $t_n \to \infty$  and  $y(t_n) \to 0$  as  $n \to \infty$ . As  $z(t_n) = y(t_n) - p(t_n)y(t_n - \tau) < y(t_n)$ , we have  $\limsup_{n\to\infty} z(t_n) \leq 0$ . Similarly,  $z(t_n + \tau) = y(t_n + \tau) - p(t_n + \tau)y(t_n) > -p_6y(t_n)$  implies that  $\liminf_{n\to\infty} z(t_n + \tau) \geq 0$ .

If z(t) > 0 for  $t \ge T_2$ , then  $\lim_{t\to\infty} z(t) = \mu$ , where  $0 \le \mu \le \infty$ . If  $0 < \mu \le \infty$  then z(t) > a > 0 for  $t \ge T_4 > T_2$ . Hence  $0 \ge \limsup_{n\to\infty} z(t_n) \ge a > 0$ , a contradiction. Thus  $\mu = 0$ .

If z(t) < 0 for  $t \ge T_2$ , then  $\lim_{t\to\infty} z(t) = \mu$ , where  $-\infty \le \mu \le 0$ . If  $-\infty \le \mu < 0$ , then z(t) < b < 0 for large t. Hence  $0 \le \liminf_{n\to\infty} z(t_n+\tau) \le b < 0$ , a contradiction. Thus  $\mu = 0$ .

Consequently,  $(-1)^{n+k}z^{(k)}(t) < 0$ , k = 0, 1, ..., n-1, for large t, and  $\lim_{t\to\infty} z^{(k)}(t) = 0$ , k = 0, 1, ..., n-1. Since n is odd, z'(t) < 0 for large t. Hence z(t) > 0 for  $t \ge T_2$ . From (2) we obtain  $y(t) > y(t-\tau)$ . Hence  $\lim_{t\to\infty} y(t) > 0$ , a contradiction. Thus  $\lambda = -\infty$ . This implies that  $\lim_{t\to\infty} y(t) = \infty$ . Thus the proof of the theorem is complete.

REMARK 4 (see [5]). The conclusion of Theorem 2.7 holds for G with  $\liminf_{|u|\to\infty} G(u)/u > \lambda > 0$  provided (H<sub>1</sub>) is replaced by  $\int_0^\infty t^{n-1}Q(t) dt = \infty$ .

COROLLARY 2.8. Let the conditions of Theorem 2.7 be satisfied. Then every bounded solution of (11) oscillates.

THEOREM 2.9. Suppose that p(t) satisfies (A<sub>6</sub>). Let (H<sub>2</sub>) and (H<sub>3</sub>) hold. If, for every sequence  $\{\sigma_i\} \subset (0, \infty)$  such that  $\lim_{i\to\infty} \sigma_i = \infty$  and for every  $\gamma > 0$  such that the intervals  $(\sigma_i - \gamma, \sigma_i + \gamma), i = 1, 2, \dots, are nonoverlapping,$ 

$$\sum_{i=1}^{\infty} \int_{\sigma_i - \gamma}^{\sigma_i + \gamma} Q(t) \, dt = \infty,$$

then every unbounded solution of (1) oscillates or tends to  $\pm \infty$  as  $t \to \infty$ , and every bounded solution of (1) oscillates or tends to zero as  $t \to \infty$ .

*Proof.* Proceeding as in the proof of Theorem 2.7 we obtain

$$\lim_{t \to \infty} w^{(n-1)}(t) = -\infty \quad \text{or} \quad \lim_{t \to \infty} w^{(n-1)}(t) = \lambda.$$

If the former holds, then  $\lim_{t\to\infty} w(t) = -\infty$ . Since  $w(t) > -p_7 y(t-\tau) - F(t)$ , we have  $\lim_{t\to\infty} y(t) = \infty$ .

Suppose that the latter holds. Proceeding as in the proof of Theorem 2.7 and using (H<sub>3</sub>), we have  $\lim_{t\to\infty} w(t) = 0$ . Hence  $(-1)^{n+k}w^{(k)}(t) < 0$ ,  $k = 0, 1, \ldots, n-1$ , for  $t \ge T_2 > T_1$  and  $\lim_{t\to\infty} w^{(k)}(t) = 0$ ,  $k = 0, 1, \ldots, n-1$ .

If y(t) is unbounded, then there exists a sequence  $\{t_n\} \subset [T_2, \infty)$  such that  $t_n \to \infty$  and  $y(t_n) \to \infty$  as  $n \to \infty$ . Let  $\mu > 0$ . Then  $y(t_n) > \mu$  for  $n \ge N_1 > 0$ . From the continuity of y it follows that there exists  $\delta_n > 0$  with  $\liminf_{n\to\infty} \delta_n > 0$  such that  $y(t) > \mu$  for  $t \in (t_n - \delta_n, t_n + \delta_n)$ . Then choosing n large enough such that  $\delta_n > \delta > 0$  for  $n \ge N > N_1$ , we obtain

$$\begin{split} & \int_{T_2}^{\infty} Q(t) G(y(t-\sigma)) \, dt \geq \sum_{n=N}^{\infty} \int_{t_n-\delta_n+\sigma}^{t_n+\delta_n+\sigma} Q(t) G(y(t-\sigma)) \, dt \\ & > G(\mu) \sum_{n=N}^{\infty} \int_{t_n-\delta_n+\sigma}^{t_n+\delta_n+\sigma} Q(t) \, dt \\ & > G(\mu) \sum_{n=N}^{\infty} \int_{t_n-\delta+\sigma}^{t_n+\delta+\sigma} Q(t) \, dt. \end{split}$$

From the hypothesis it follows that  $\int_{T_2}^{\infty} Q(t)G(y(t-\sigma)) dt = \infty$ . Integrating (3) yields

$$\int_{T_2} Q(t)G(y(t-\sigma)) \, dt = w^{(n-1)}(T_2) < \infty,$$

a contradiction.

 $\sim$ 

If y(t) is bounded, then we claim  $\limsup_{t\to\infty} y(t) = 0$ . If not, then  $\limsup_{t\to\infty} y(t) = \alpha, \alpha > 0$ . Then there exists a sequence  $\{t_n\}$  such that  $y(t_n) > \beta > 0$  for large n. Proceeding as above we arrive at a contradiction. Hence our claim holds. Consequently,  $\lim_{t\to\infty} y(t) = 0$ . The case y(t) < 0for  $t \ge T_0$  may be dealt with similarly. Thus the theorem is proved. Acknowledgements. The authors are grateful to the referee for various suggestions to improve the quality of the paper.

## References

- M. P. Chen, Z. C. Wang, J. S. Yu and B. G. Zhang, Oscillation and asymptotic behaviour of higher order neutral differential equations, Bull. Inst. Math. Acad. Sinica 22 (1994), 203–217.
- Q. Chuanxi and G. Ladas, Oscillations of higher order neutral differential equations with variable coefficients, Math. Nachr. 150 (1991), 15–24.
- [3] I. Győri and G. Ladas, Oscillation Theory of Delay-Differential Equations with Applications, Clarendon Press, Oxford, 1991.
- [4] T. H. Hildebrandt, Introduction to the Theory of Integration, Academic Press, New York, 1963.
- [5] N. Parhi and R. N. Rath, On oscillation of solutions of forced nonlinear neutral differential equations of higher order, Czechoslovak Math. J., in press.
- [6] D. Q. Tang, Oscillation of higher order nonlinear neutral functional-differential equation, Ann. Differential Equations 12 (1996), 83–88.

Department of Mathematics Berhampur University Berhampur 760007, Orissa, India E-mail: parhi2002@rediffmail.com Department of Mathematics Khallikote (Autonomous) College Berhampur 760001, Orissa, India E-mail: radhanathmath@yahoo.co.in

Reçu par la Rédaction le 29.3.2001 Révisé le 5.11.2002

(1248)