

Periodic solutions of n th order delay Rayleigh equations

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Abstract. A priori bounds are established for periodic solutions of an n th order Rayleigh equation with delay. From these bounds, existence theorems for periodic solutions are established by means of Mawhin's continuation theorem.

In [4], a priori bounds for periodic solutions of the equation

$$(1) \quad x''(t) + \lambda f(x'(t)) + \lambda g(x(t - \tau(t))) = \lambda p(t), \quad \lambda \in (0, 1),$$

are established under relatively simple conditions on f , g and p . Then by means of continuation theorems [1], periodic solutions for the Rayleigh differential equation

$$x''(t) + f(x'(t)) + g(x(t - \tau(t))) = 0$$

are obtained.

In this note, we will be concerned with similar equations of the form

$$(2) \quad x^{(n)}(t) + \lambda f(t, x'(t - \tau_1(t)), \dots, x^{(n-1)}(t - \tau_{n-1}(t))) \\ + \lambda g(t, x(t - \tau_0(t))) = \lambda p(t),$$

and

$$(3) \quad x^{(n)}(t) + f(t, x'(t - \tau_1(t)), \dots, x^{(n-1)}(t - \tau_{n-1}(t))) \\ + g(t, x(t - \tau_0(t))) = p(t)$$

where $\lambda \in (0, 1)$, $n \geq 2$, $\tau_0, \dots, \tau_{n-1}$ and p are T -periodic continuous functions defined on \mathbb{R} with

$$\int_0^T p(t) dt = 0,$$

f is continuous on \mathbb{R}^n , $f(t, 0, \dots, 0) = 0$ for $t \in \mathbb{R}$ and $f(t+T, x_1, \dots, x_{n-1}) = f(t, x_1, \dots, x_{n-1})$ for $(t, x_1, \dots, x_{n-1}) \in \mathbb{R}^n$, and g is continuous on \mathbb{R}^2

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such that $g(t + T, x) = g(t, x)$ for $(t, x) \in \mathbb{R}^2$. To avoid trivial cases, we also assume that the period T is positive.

We will establish a priori bounds for periodic solutions of equation (2) under several conditions imposed on f and g . Once these bounds are obtained, existence of periodic solutions for equation (3) can be demonstrated.

We remark that there are a number of studies which are concerned with the existence of periodic solutions of Rayleigh differential equations (see e.g. [2, 3, 5]). But our conditions are novel and relatively simple as compared to many others. For example, in [3], smoothness in addition to boundedness assumptions are needed for the functions in (1) in order to guarantee a periodic solution.

THEOREM 1. *Suppose there are constants $H \geq 0$, $D > 0$ and $M > 0$ such that*

- (i) $|f(t, x_1, \dots, x_{n-1})| \leq H$ for $(t, x_1, \dots, x_{n-1}) \in \mathbb{R}^n$,
- (ii) $xg(t, x) > 0$ and $|g(t, x)| > H$ for $t \in \mathbb{R}$ and $|x| \geq D$, and
- (iii) $|g(t, x)| \leq M$ for $t \in \mathbb{R}$ and $x \leq -D$.

Then there exist $D_0, \dots, D_{n-1} > 0$ such that for any T -periodic solution $x = x(t)$ of (2),

$$|x^{(j)}(t)| \leq D_j, \quad 0 \leq j \leq n - 1, \quad 0 \leq t \leq T.$$

Proof. Let $x = x(t)$ be a T -periodic solution of (2). In view of (2), and the periodicity of $x(t)$,

$$(4) \quad \int_0^T \{f(t, x'(t - \tau_1(t)), \dots, x^{(n-1)}(t - \tau_{n-1}(t))) + g(t, x(t - \tau_0(t)))\} dt = 0.$$

Note also that

$$(5) \quad \int_0^T |f(t, x'(t - \tau_1(t)), \dots, x^{(n-1)}(t - \tau_{n-1}(t)))| dt \leq TH.$$

Thus,

$$(6) \quad \int_0^T \{g(t, x(t - \tau_0(t))) - H\} dt$$

$$\leq \int_0^T \{g(t, x(t - \tau_0(t))) - |f(t, x'(t - \tau_1(t)), \dots, x^{(n-1)}(t - \tau_{n-1}(t)))|\} dt$$

$$\leq \int_0^T \{g(t, x(t - \tau_0(t))) + f(t, x'(t - \tau_1(t)), \dots, x^{(n-1)}(t - \tau_{n-1}(t)))\} dt = 0.$$

Let

$$G_+(t) = \max\{g(t, x(t - \tau_0(t))) - H, 0\}, \quad t \in \mathbb{R},$$

$$G_-(t) = \max\{H - g(t, x(t - \tau_0(t))), 0\}, \quad t \in \mathbb{R}.$$

Then G_+ and G_- are nonnegative and continuous on \mathbb{R} ,

$$(7) \quad g(t, x(t - \tau_0(t))) - H = G_+(t) - G_-(t), \quad t \in \mathbb{R},$$

and in view of (ii) and (iii),

$$G_-(t) = |G_-(t)| \leq H + M, \quad t \in \mathbb{R}.$$

In view of (6) and (7), we have

$$\int_0^T G_+(t) dt \leq \int_0^T G_-(t) dt \leq M_1$$

where $M_1 = (H + M)T$. In view of (7), we have

$$\int_0^T |g(t, x(t - \tau_0(t))) - H| dt \leq 2M_1,$$

which implies

$$(8) \quad \int_0^T |g(t, x(t - \tau_0(t)))| dt \leq 2M_1 + TH.$$

By integrating (2), in view of (5) and (8), we see that

$$\begin{aligned} \int_0^T |x^{(n)}(t)| dt &\leq \int_0^T |f(t, x'(t - \tau_1(t)), \dots, x^{(n-1)}(t - \tau_{n-1}(t)))| dt \\ &\quad + \int_0^T |g(t, x(t - \tau_0(t)))| dt + \int_0^T |p(t)| dt \\ &\leq TH + 2M_1 + TH + T \max_{0 \leq t \leq T} |p(t)|. \end{aligned}$$

Since $x^{(n-2)}(0) = x^{(n-2)}(T)$, there exists $t_1 \in [0, T]$ such that $x^{(n-1)}(t_1) = 0$. Thus

$$|x^{(n-1)}(t)| = \left| \int_{t_1}^t x^{(n)}(s) ds \right| \leq \int_0^T |x^{(n)}(s)| ds \leq D_{n-1}, \quad t \in [0, T],$$

where $D_{n-1} = TH + 2M_1 + TH + T \max_{0 \leq t \leq T} |p(t)| > 0$. Next we will show that when $n > 2$, we have $|x^{(j)}(t)| \leq D_j$ for $1 \leq j \leq n - 2$ and $0 \leq t \leq T$. Indeed, since $x^{(n-3)}(0) = x^{(n-3)}(T)$, there exists $t_2 \in [0, T]$ such

that $x^{(n-2)}(t_2) = 0$. As a consequence,

$$|x^{(n-2)}(t)| = \left| \int_{t_2}^t x^{(n-1)}(s) ds \right| \leq \int_0^T |x^{(n-1)}(s)| ds \leq TD_{n-1} \equiv D_{n-2}.$$

The rest of the proof follows by induction. To complete our proof, we will show that $|x(t)| \leq D_0, t \in [0, T]$, for some $D_0 > 0$. Indeed, in view of (4),

$$f(t_3, x'(t_3 - \tau_1(t_3)), \dots, x^{(n-1)}(t_3 - \tau_{n-1}(t_3))) + g(t_3, x(t_3 - \tau_0(t_3))) = 0$$

for some $t_3 \in [0, T]$. Hence by (i),

$$|g(t_3, x(t_3 - \tau_0(t_3)))| = |f(t_3, x'(t_3 - \tau_1(t_3)), \dots, x^{(n-1)}(t_3 - \tau_{n-1}(t_3)))| \leq H.$$

But then by (ii), $|x(t_3 - \tau_0(t_3))| < D$. Since $x(t)$ is T -periodic, there exists $t_4 \in [0, T]$ such that $|x(t_4)| < D$. Finally,

$$|x(t)| = \left| x(t_4) + \int_{t_4}^t x'(s) ds \right| \leq D + \int_0^T |x'(s)| ds \leq D + TD_1$$

for $t \in [0, T]$. The proof is complete.

Having the a priori bounds just obtained, we may follow the standard procedures as explained in various places of [1] and the continuation theorem on page 40 of [1] to show the existence of a periodic solution of (3). For completeness, a brief sketch is included.

Let X be the Banach space of all functions $x = x(t) \in C^{(n-1)}(\mathbb{R})$ such that $x(t + T) = x(t)$ for all t , endowed with the norm

$$\|x\| = \sum_{j=0}^{n-1} \max_{0 \leq t \leq T} |x^{(j)}(t)|.$$

Also let Y be the Banach space of all continuous functions of the form $y = y(t)$ defined on \mathbb{R} such that $y(t + T) = y(t)$ for all t , and endowed with the norm $\|y\|_0 = \max_{0 \leq t \leq T} |y(t)|$. Now let $L : X \cap C^{(n)}(\mathbb{R}) \rightarrow Y$ be the operator defined by $(Lx)(t) = x^{(n)}(t)$ for $t \in \mathbb{R}$, and let $N : X \rightarrow Y$ be defined by

$$(Nx)(t) = -f(t, x'(t - \tau_1(t)), \dots, x^{(n-1)}(t - \tau_{n-1}(t))) - g(t, x(t - \tau_0(t))) + p(t)$$

for $t \in \mathbb{R}$. Let $\text{Im } L$ and $\text{Ker } L$ be respectively the image and kernel of the operator L . Clearly, $\text{Ker } L = \mathbb{R}$. Furthermore, if we define the projections $P : X \rightarrow \text{Ker } L$ and $Q : Y \rightarrow Y/\text{Im } L$ by

$$(Px)(t) = \frac{1}{T} \int_0^T x(t) dt, \quad (Qy)(t) = \frac{1}{T} \int_0^T y(t) dt, \quad t \in \mathbb{R},$$

then $\text{Ker } L = \text{Im } P$ and $\text{Ker } Q = \text{Im } L$. Furthermore, L is a Fredholm operator of index zero. The operator N is continuous and maps bounded subsets

of X into bounded subsets of Y , thus for any bounded open subset Ω of X , $N(\overline{\Omega})$ is bounded. This shows that $(I - Q)N(\overline{\Omega})$ is bounded. Since the inverse K of $L|_{\text{dom } L \cap \text{ker } P}$ is compact, $K(I - Q)N(\overline{\Omega})$ is relatively compact, and so L -compact on the closure of Ω (see e.g. [1, pp. 166–187]).

Let D, D_0, \dots, D_{n-1} be as in Theorem 1, and let Ω be the subset of X consisting of the functions of the form $x = x(t)$ such that $\|x\| < \overline{D}$, where \overline{D} is a fixed number which satisfies $\overline{D} > \max\{D_0, D_1, \dots, D_{n-1}\} + D$. For any $\lambda \in (0, 1)$ and any $x = x(t)$ in the domain of L which also belongs to $\partial\Omega$, we must have $Lx \neq \lambda Nx$. For otherwise in view of $\|x\| < \overline{D}$, x belongs to the interior of Ω , contrary to the assumption that $x \in \partial\Omega$. Next, note that a function $x = x(t) \in \text{Ker } L \cap \partial\Omega$ must be the constant function $x(t) \equiv \overline{D}$ or $x(t) \equiv -\overline{D}$. Hence

$$\begin{aligned} (QN)(x) &= \frac{1}{T} \int_0^T [-f(t, x'(t - \tau_1(t)), \dots, x^{(n-1)}(t - \tau_{n-1}(t)))] dt \\ &\quad + \frac{1}{T} \int_0^T [-g(t, x(t - \tau_0(t)) + p(t)] dt \\ &= \frac{1}{T} \int_0^T [-f(t, 0, \dots, 0) - g(t, x(t - \tau_0(t)))] dt \\ &= -\frac{1}{T} \int_0^T g(t, x(t - \tau_0(t))) dt = -\frac{1}{T} \int_0^T g(t, x) dt \neq 0. \end{aligned}$$

Finally, consider the mapping

$$H(x, s) = sx + (1 - s) \frac{1}{T} \int_0^T g(t, x) dt, \quad 0 \leq s \leq 1.$$

Since for every $s \in [0, 1]$ and $x \in \text{Ker } L \cap \partial\Omega$, we have

$$xH(x, s) = sx^2 + (1 - s)x \frac{1}{T} \int_0^T g(t, x) dt > 0,$$

$H(x, s)$ is an admissible homotopy. This shows that

$$\begin{aligned} \text{deg}\{QNx, \Omega \cap \text{Ker } L, 0\} &= \text{deg}\left\{-\frac{1}{T} \int_0^T g(t, x) dt, \Omega \cap \text{Ker } L, 0\right\} \\ &= \text{deg}\{-x, \Omega \cap \text{Ker } L, 0\} \\ &= \text{deg}\{-x, \Omega \cap \mathbb{R}, 0\} \neq 0. \end{aligned}$$

We have thus verified all the assumptions of the continuation theorem [1, p. 40]. Under the assumptions of Theorem 1, equation (3) thus has a T -periodic solution.

THEOREM 2. *Suppose the assumptions of Theorem 1 hold. Then equation (3) has a T -periodic solution.*

As an example, consider the equation

$$\begin{aligned} x'''(t) + \exp\{-\sin^2 t - (x'(t - \cos t))^2 - (x''(t - \sin t))^2\} \\ + (1 + \cos^2 t) \arctan(x(t - \sin t)) \\ = \sin t + \exp(-\sin^2 t). \end{aligned}$$

Take

$$\begin{aligned} f(t, x_1, x_2) &= \exp(-\sin^2 t - x_1^2 - x_2^2) - \exp(-\sin^2 t), \\ g(t, x) &= (1 + \cos^2 t) \arctan x, \end{aligned}$$

$\tau_0(t) = \sin t$, $\tau_1(t) = \cos t$, $\tau_2(t) = \sin t$, and $p(t) = \sin t$ and $T = 2\pi$. It is then easy to verify that all the assumptions of Theorem 1 are satisfied with $H = 1$, $D > \pi/4$ and $M = \pi$. Hence this equation has a 2π -periodic solution.

We remark that by symmetric arguments, we can establish the following existence theorem.

THEOREM 3. *Suppose there are constants $H \geq 0$, $D > 0$ and $M > 0$ such that (i) $|f(t, x_1, \dots, x_{n-1})| \leq H$ for $(t, x_1, \dots, x_{n-1}) \in \mathbb{R}^n$, (ii) $xg(t, x) > 0$ and $|g(t, x)| > H$ for $t \in \mathbb{R}$ and $|x| \geq D$, and (iii) $|g(t, x)| \leq M$ for $t \in \mathbb{R}$ and $x \geq D$. Then (3) has a T -periodic solution.*

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(1234)