ALGEBRAIC TOPOLOGY

On the Extension of Certain Maps with Values in Spheres by

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Summary. Let *E* be an oriented, smooth and closed *m*-dimensional manifold with $m \ge 2$ and $V \subset E$ an oriented, connected, smooth and closed (m-2)-dimensional submanifold which is homologous to zero in *E*. Let $S^{n-2} \subset S^n$ be the standard inclusion, where S^n is the *n*-sphere and $n \ge 3$. We prove the following extension result: if $h: V \to S^{n-2}$ is a smooth map, then *h* extends to a smooth map $g: E \to S^n$ transverse to S^{n-2} and with $g^{-1}(S^{n-2}) = V$. Using this result, we give a new and simpler proof of a theorem of Carlos Biasi related to the *ambiental bordism* question, which asks whether, given a smooth closed *n*-dimensional manifold $V \subset E$, one can find a compact smooth (m + 1)-dimensional submanifold $W \subset E$ such that the boundary of *W* is *V*.

1. Introduction. The extension problem is whether, given topological spaces X, Y, a subspace $A \subset X$ and a continuous map $f : A \to Y$, one can find a continuous map $g : X \to Y$ such that $g_{|A} = f$. For example, if D^n is the unit *n*-disk, with boundary $\partial(D^n) = S^{n-1}$ = the unit (n-1)-sphere, then the identity map $\mathrm{Id} : S^{n-1} \to S^{n-1}$ cannot be extended to a map $g : D^n \to S^{n-1}$, and this non-extension result has as a consequence the famous Brouwer fixed-point theorem, which asserts that each continuous map $g : D^n \to D^n$ has a fixed point. In fact, this is a particular case of a stronger non-extension result: let M^n be any *n*-dimensional, connected and closed manifold and W^{n+1} an (n + 1)-dimensional compact manifold

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whose boundary is M^n . Then Id : $M^n \to M^n$ cannot be extended to a map $W^{n+1} \to M^n$. More generally, the same is valid if we replace Id : $M^n \to M^n$ by a map of closed manifolds, $g: M^n \to V^n$, which induces an isomorphism in homology, $g_*: H_n(M^n) \to H_n(V^n)$, with any coefficients; for example, if g is a homotopy equivalence. Inspired by this setting, we prove the following extension result.

THEOREM 1. Let E be an oriented, smooth and closed m-dimensional manifold, with $m \ge 2$, and $V \subset E$ an oriented, connected, smooth and closed (m-2)-dimensional submanifold which is homologous (with \mathbb{Z} -coefficients) to zero in E. Let $S^{n-2} \subset S^n$ be the standard inclusion, where $n \ge 3$. Then every smooth map $h: V \to S^{n-2}$ has a smooth extension $g: E \to S^n$ transverse to S^{n-2} and with $g^{-1}(S^{n-2}) = V$.

Theorem 1 gives a method to attack the *ambiental bordism* question, which asks whether, given a smooth closed n-dimensional manifold E and a smooth closed *m*-dimensional submanifold $V \subset E$, one can find a compact smooth (m+1)-dimensional submanifold $W \subset E$ such that the boundary of W is V; in this case, we say that V bounds in E. If $V = S^m$ and E = S^{m+2} , such a W is called a *Seifert surface* for the knot $S^m \to S^{m+2}$. Hirsch considered a related question in his old paper [3]; specifically, he showed that if V is an *m*-dimensional connected closed and oriented manifold which bounds, then there exists an embedding of V into \mathbb{R}^n which is a boundary in \mathbb{R}^n when $n \geq 2m$. In [6], Sato showed that every connected, closed and oriented submanifold $V^m \subset S^{m+2}$ bounds in S^{m+2} . In [1], C. Biasi obtained the following result, which in particular gives Sato's result: denote by i: $V \to E$ the inclusion map and suppose E and V are oriented. Suppose that (V, i) bounds as an element of the oriented cobordism group $\Omega_m(E)$. Then V bounds in E in the following cases: (i) n = m + 2; (ii) $m \leq 3$ and $n \geq m + 2$; (iii) $m = 4, n \ge 6$ and $n \ne 7$ (evidently, [(V, i)] = 0 in $\Omega_m(E)$ is always a necessary condition for V to be a boundary in E). Using Theorem 1, we give a new and simpler proof of case (i).

2. Proofs. Homology and cohomology will be understood with \mathbb{Z} -coefficients. To simplify notation, if $X \subset Y$ and $\alpha \in H_r(X)$, we use the same notation $\alpha \in H_r(Y)$ for the image of α under the homomorphism induced by the inclusion $X \to Y$. If W is an *n*-dimensional, oriented and closed manifold, we will denote by $\mu_W \in H_n(W)$ its fundamental homology class.

To prove Theorem 1, denote by $\eta \to V$ and $\nu \to S^{n-2}$ the normal bundles of V in E and S^{n-2} in S^n , and by $D(\eta)$, $D(\nu)$, $S(\eta)$ and $S(\nu)$ the associated disk bundles and sphere bundles. The symbols D_P , D_L and D_A will be used to denote, respectively, the Poincaré, Lefschetz and Alexander duality isomorphisms, with the convention that the domains of these

maps are the cohomology \mathbb{Z} -modules. Denote by $D(\eta)_* \subset D(\eta)$ the subset of non-zero vectors, and by $U_\eta \in H^2(D(\eta), D(\eta)_*)$ the Thom class of η . By excision, U_η can be considered as lying in $H^2(E, E - V)$, and $D_L : H^s(D(\eta), S(\eta)) \cong H^s(D(\eta), D(\eta)_*) \to H_{m-s}(D(\eta))$ can be seen as an isomorphism $D_L : H^s(E, E - V) \to H_{m-s}(E)$; in this setting, the inclusion map $i : V \to E$ can be viewed as the zero section. Write $j : E \to (E, E - V)$ for the inclusion map. Let $e \in H^2(V)$ be the Euler class of η .

We assert that $j_*i_*(\mu_V) = D_A(e)$ in $H_{m-2}(E, E - V)$. In fact, a basic property of Thom classes (sometimes used as their definition) is that $U_\eta = D_L^{-1}i_*(\mu_V)$ (see, for example, [2, Chapter 6, Section 11]). Also, the composite homomorphism

$$D_A(ji)^* D_L^{-1} : H_{m-2}(E) \to H^2(E, E-V) \to H^2(V) \to H_{m-2}(E, E-V)$$

coincides with $j_*: H_{m-2}(E) \to H_{m-2}(E, E-V)$; this follows from the fact that the duality isomorphisms are essentially the cap product with the fundamental homology classes. The Euler class e is given by $e = (ji)^*(U_\eta)$, and thus $D_A(e) = D_A(ji)^* D_L^{-1} i_*(\mu_V) = j_* i_*(\mu_V)$, which shows the assertion.

Since by hypothesis $\mu_V = 0$ in $H_{m-2}(E)$, we get e = 0, and we assert that this implies that η is a trivial vector bundle. In fact, it is well known that the 2-dimensional oriented vector bundles over V are in one-to-one correspondence with the homotopy classes of maps from V into a classifying space BSO(2), [V, BSO(2)]. A model for BSO(2) is the complex projective space $\mathbb{C}P^{\infty} = \lim_{n} \mathbb{C}P^{n}$ (with the weak topology). $\mathbb{C}P^{\infty}$ is an Eilenberg-MacLane space of type ($\mathbb{Z}, 2$), and so $[V, \mathbb{C}P^{\infty}]$ is in one-to-one correspondence with $H^2(V,\mathbb{Z})$; choosing a generator $\alpha \in H^2(\mathbb{C}P^\infty,\mathbb{Z}) \cong \mathbb{Z}$, this correspondence can be given by $[f] \in [V, \mathbb{C}P^{\infty}] \mapsto f^*(\alpha) \in H^2(V, \mathbb{Z})$. On the other hand, it is also well known that the Euler class of the oriented 2-dimensional universal vector bundle over $\mathbb{C}P^{\infty}$ (which is the complex canonical line bundle) is either α or $-\alpha$. If $f \in [V, \mathbb{C}P^{\infty}]$ classifies $\eta \to V$, then the naturality of the Euler classes show that, up to sign, $f^*(\alpha)$ is the Euler class e of η . It follows that $f^*(\alpha) = 0$ and thus f is homotopic to a constant map, so that η is a trivial bundle. This outline follows from bundle theory and the material of [2, Chapter 7, Sections 13 and 14]; alternatively, see 8, Part III.

Since η and ν are trivial bundles, $P := D(\eta)$ and $T := D(\nu)$ are trivial disk (smooth) bundles over V and S^{n-2} , respectively. Moreover, P and T can be considered as tubular neighbourhoods of V in E and S^{n-2} in S^n , respectively. Set $M := E - \operatorname{int}(P)$, $A := S(\eta) = \partial(M) = \partial(P)$, N := $S^n - \operatorname{int}(T)$ and $B := S(\nu) = \partial(N) = \partial(T)$. By Proposition 4.3 of [1], there exists a cross section $r : V \to A$ such that $r_*(\mu_V) = 0$ in $H_{m-2}(M)$. Note that, since S^1 is a Lie group, any (smooth) bundle $X \to B$ with fibre S^1 has the following property: for any (smooth) sections $s_1, s_2 : B \to X$, there exists a (smooth) bundle isomorphism $g : X \to X$ inducing the identity on B and such that $s_2 = gs_1$.

Consequently, there exists a (smooth) bundle isomorphism $g: A \to V \times S^1$ such that g(r(v)) = (v, 1) for every $v \in V$, where $1 \in S^1$. Let $G: P \to V \times D^2$ be a (smooth) bundle isomorphism such that $G_{|A} = g$ and G(v) = (v, 0) for every $v \in V$, where 0 is the centre of D^2 . We identify T with $S^{n-2} \times D^2$ in the standard way; then $B = S^{n-2} \times S^1$ and $N = D^{n-1} \times S^1$, with $\partial(D^{n-1}) = S^{n-2}$. Let $H: V \times D^2 \to S^{n-2} \times D^2 = T$ be defined by H(v,w) = (h(v),w). Then $HG: P \to T$ is transverse to S^{n-2} and $(HG)^{-1}(S^{n-2}) = V$. Thus an extension of $f := (H_{|V \times S^1})g: A \to B$ to a smooth map $M \to N$ gives an extension as stated in Theorem 1. To obtain this extension, the first step is to find a continuous extension $M \to N$.

Since N is an Eilenberg-MacLane space of type $(\mathbb{Z}, 1)$, a continuous extension $M \to N$ of f exists if and only if $\delta(if)^*(\theta) = 0$ in $H^2(M, A)$, where $i: B \to N$ is the inclusion map, $\delta: H^1(A) \to H^2(M, A)$ is the coboundary homomorphism and θ is a generator of $H^1(N) \cong \mathbb{Z}$ (see [7, Theorem 12, p. 428]). The diagram

$$\begin{array}{c|c} H^1(A) & \xrightarrow{D_P} H_{m-2}(A) \\ & \delta & \downarrow & k_* \\ H^2(M,A) & \xrightarrow{D_L} H_{m-2}(M) \end{array}$$

where $k : A \to M$ is the inclusion, is commutative (see [4, p. 379]). It follows that $\delta(if)^*(\theta) = 0$ if and only if $k_*(D_P(if)^*(\theta)) = 0$.

Now, we assert that $D_P(if)^*(\theta) = \pm r_*(\mu_V)$. In fact, set $f' = H_{|V \times S^1}$: $V \times S^1 \to B$. By the Künneth formula for cohomology, $(if')^*(\theta) = u_1 \times u_2$, where $u_1 \in H^0(V)$ and $u_2 \in H^1(S^1)$ are generators. Moreover, $\mu_{V \times S^1} = \mu_V \times \mu_{S^1}$. By property 21 in [7, p. 255], with α a generator of $H_0(S^1)$, we obtain

$$D_P(if')^*(\theta) = (if')^*(\theta) \cap \mu_{V \times S^1} = (u_1 \cap \mu_V) \times (u_2 \cap \mu_{S^1}) = \mu_V \times \alpha.$$

Thus, since g(r(v)) = (v, 1), by the Künneth formula for homology, we deduce that $D_P(if')^*(\theta) = \pm (gr)_*(\mu_V)$. It follows that $D_P(if)^*(\theta) = \pm r_*(\mu_V)$, because $g: A \to V \times S^1$ is a homeomorphism and f = f'g. Since $k_*(r_*(\mu_V))$ = 0, we obtain $\delta(if)^*(\theta) = 0$, and consequently we get the required continuous extension $M \to N$ of f. This extension can be slightly modified to give a map $M \to N$ which is smooth in a collar neighbourhood of A in M. This last map can be approximated, without changing its values in a smaller collar neighbourhood of A in M, by a smooth map $M \to N$. Together with $HG: P \to T$, this gives the desired smooth map $E \to S^n$ (for the approximation theorems for smooth maps used here and in the next corollary, see for example [5] and [9]). COROLLARY (C. Biasi, [1]). Let E be an oriented, smooth and closed mdimensional manifold with $m \ge 2$, $V \subset E$ an oriented, pathwise connected, smooth and closed (m - 2)-dimensional submanifold, and $i : V \to E$ the inclusion map. If (V, i) bounds as an element of the oriented cobordism group $\Omega_{m-2}(E)$, then V bounds in E.

Proof. Consider S^3 as the one-point compactification $\{(x, y, z) \in \mathbb{R}^3 \mid$ $x^2+y^2+z^2 < 1 \cup \{\infty\}$ and $S^1 = \{(x, y, z) \in \mathbb{R}^3 \mid x^2+y^2 = 1/4, z=0\} \subset S^3$, and let $h: V \to S^1$ be a constant map. Let $j: W^{m-1} \to E$ be a map that realizes the cobordism of (V,i) in $\Omega_{m-2}(E)$ and let $k: V \to W^{m-1}$ be the inclusion map. Since i = jk and $\mu_V = 0$ in $H_{m-2}(W^{m-1})$, $\mu_V = 0$ in $H_{m-2}(E)$. Evidently, the inclusion $S^1 \to S^3$ has the properties of the standard inclusion $S^{n-2} \to S^n$ used in Theorem 1, hence this theorem applies to $h: V \to S^1$; as in its proof, denote by P a closed tubular neighbourhood of V in E and by T the closed tubular neighbourhood of S^1 in S^3 given by the product of S^1 and an orthogonal 2-disk of radius 1/4. In the same way, set M = E - int(P), $A = \partial(M) = \partial(P)$, $N = S^3 - int(T)$ and $B = \partial(N) = \partial(T)$. As we have seen, $h: V \to S^1$ extends to a smooth map $F: E \to S^3$ transverse to S^1 and with $F^{-1}(S^1) = V$. Consider the Seifert surface $D \subset S^3$ for S^1 , $D = \{(x, y, z) \in \mathbb{R}^3 \mid x^2 + y^2 \le 1/4, z = 0\}.$ Because of the construction of F in the proof of Theorem 1, it is transverse to D at every point in $F^{-1}(D) \cap P$. Then there exists an ε -approximation $F': E \to S^3$ for F which is smooth, transverse to D and with $F'_{|P} = F_{|P}$. Then $F'_{|P|}^{-1}(S^1) = V$, and for ε sufficiently small the points of E - P cannot be mapped by F' into S^1 . The Thom transversality theorem then implies that $F'^{-1}(D) = W$ is an (m-1)-dimensional submanifold of E whose boundary is $F'^{-1}(S^1) = V$, and the proof is finished.

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