GENERAL TOPOLOGY

Infinite Iterated Function Systems: A Multivalued Approach

by

K. LEŚNIAK

Presented by Andrzej LASOTA

Summary. We prove that a compact family of bounded condensing multifunctions has bounded condensing set-theoretic union. Compactness is understood in the sense of the Chebyshev uniform semimetric induced by the Hausdorff distance and condensity is taken w.r.t. the Hausdorff measure of noncompactness. As a tool, we present an estimate for the measure of an infinite union. Then we apply our result to infinite iterated function systems.

1. The space of multifunctions. Let (X, d) be a complete metric space, and let $x_0 \in X$, r > 0, $A, B \subset X$. We denote by $B(x_0, r)$ the open r-ball at x_0 , by $\mathcal{O}_r(A) = \bigcup_{a \in A} B(a, r)$ the r-neighbourhood of A, and by

$$h(A, B) = \inf\{r > 0 : A \subset \mathcal{O}_r(B), B \subset \mathcal{O}_r(A)\}$$

the Hausdorff semimetric. Moreover, we denote by 2^X the family of all nonempty subsets of X, and by $\mathcal{B}(X)$ the family (or hyperspace) of nonempty bounded subsets of X equipped with the Hausdorff semimetric h. The symbol $\varphi : X \to X$ will stand for a multifunction with nonempty bounded values. Such a φ can be identified with a mapping $\varphi : X \to \mathcal{B}(X)$. The image of A under φ is the set $\varphi(A) = \bigcup_{a \in A} \varphi(a)$. The set-theoretic union of multifunctions $\varphi_t : X \to X$, $t \in T$, is $\bigcup_{t \in T} \varphi_t : X \to X$, $(\bigcup_{t \in T} \varphi_t)(x) =$ $\bigcup_{t \in T} \varphi_t(x)$ for $x \in X$. For basic concepts of set-valued analysis see e.g. [HP].

²⁰⁰⁰ Mathematics Subject Classification: 54H25, 47H10, 47H09, 37B99.

Key words and phrases: compactness in Chebyshev's semimetric, Hausdorff measure of noncompactness, condensing multifunction, uniformly Hausdorff upper semicontinuous multifunction, iterated function system, Barnsley–Hutchinson operator, maximal fixed point, attractor.

Let Z be a nonempty set. We introduce the following spaces:

 $\mathcal{BM}(X,X) = \{\varphi : X \multimap X : \varphi(X) \text{ is bounded in } X\},\$

 $\mathcal{B}(Z,\mathcal{B}(X)) = \{\varphi: Z \to \mathcal{B}(X) : \{\varphi(z)\}_{z \in Z} \text{ is bounded in } \mathcal{B}(X)\}.$

The second space is furnished with the Chebyshev semimetric

$$h_{\sup}(\varphi_1, \varphi_2) = \sup_{z \in Z} h[\varphi_1(z), \varphi_2(z)]$$

for $\varphi_1, \varphi_2 : Z \to \mathcal{B}(X)$. We identify $\mathcal{B}(X) = \mathcal{B}(\star, \mathcal{B}(X))$ for \star a singleton and $\mathcal{BM}(X, X) = \mathcal{B}(X, \mathcal{B}(X))$. In particular $\mathcal{BM}(X, X)$ is equipped with the Chebyshev semimetric h_{sup} . Moreover, it is not hard to see the following:

LEMMA 1. If
$$\varphi_1, \varphi_2 : X \multimap X$$
, then

$$\sup_{x \in X} h[\varphi_1(x), \varphi_2(x)] = \sup_{\emptyset \neq A \subset X} h[\varphi_1(A), \varphi_2(A)]$$

Therefore, we have

PROPOSITION 1. The map $j : \mathcal{BM}(X, X) \to \mathcal{B}(2^X, \mathcal{B}(X)), [j(\varphi)](A) = \varphi(A)$ for all $\varphi \in \mathcal{BM}(X, X)$ and $A \in 2^X$, is an isometric embedding, i.e. it is an injection preserving the semimetric h_{sup} .

The operation j is called the *united extension* (see [W]).

LEMMA 2. Let X_1, X_2 be semimetric spaces, with X_1 isometrically embedded in X_2 via $j: X_1 \to X_2$. Then $A \subset X_1$ is (pre)compact if and only if $j(A) \subset X_2$ is.

Let $\Phi \subset \mathcal{BM}(X, X)$ and let j be as in Proposition 1. Then, by Lemma 2, the family Φ is (pre)compact in $\mathcal{BM}(X, X)$ iff $j(\Phi)$ is (pre)compact in $\mathcal{B}(2^X, \mathcal{B}(X))$. Thus we can speak about h_{\sup} -(pre)compactness with no ambiguity.

2. Hausdorff measure of noncompactness. We recall that the *Hausdorff measure of noncompactness* on a (semi)metric space X is the functional $\beta: 2^X \to [0, \infty]$ defined by

$$\beta(A) = \inf \left\{ r > 0 : \exists x_1, \dots, x_k \in X, \bigcup_{i=1}^k B(x_i, r) \supset A \right\}.$$

Notice that $\beta(A) = \infty$ if and only if A is unbounded. In the case of the hyperspace $\mathcal{B}(X)$ we shall write $B^{\#}(Z,\nu) = \{A \in \mathcal{B}(X) : h(A,Z) < \nu\}$ for the open ν -ball with center $Z \in \mathcal{B}(X)$, and $\beta^{\#} : 2^{\mathcal{B}(X)} \to [0,\infty]$ for the Hausdorff measure of noncompactness. More on measures of noncompactness can be found in [AKPRS].

We have the following (cf. [CV, Remark after Theorem II-4, p. 41] and [D, Chapt. 2, Sect. 7.4, pp. 42–43]):

LEMMA 3 (Estimate for infinite unions). If $\{A_t\}_{t\in T} \subset \mathcal{B}(X)$, then

$$\sup_{t\in T}\beta(A_t) \le \beta\Big(\bigcup_{t\in T}A_t\Big) \le \sup_{t\in T}\beta(A_t) + 2\beta^{\#}(\{A_t\}_{t\in T}).$$

Proof. Let $\nu > \beta^{\#}(\{A_t\}_{t\in T}), \sigma > \sup_{t\in T}\beta(A_t)$. Then there exists a finite family $\{Z_i\}_{i=1}^k \subset \mathcal{B}(X)$ such that $\bigcup_{i=1}^k B^{\#}(Z_i,\nu) \supset \{A_t\}_{t\in T}$. Decompose $T = \bigcup_{i=1}^k T_i$, where $T_i = \{t \in T : A_t \in B^{\#}(Z_i,\nu)\}$. For $t \in T_i$ we have $Z_i \subset \mathcal{O}_{\nu}(A_t), A_t \subset \mathcal{O}_{\nu}(Z_i)$. Further, pick $t_i \in T_i$ in each T_i . Every A_{t_i} can be covered by balls, $A_{t_i} \subset \bigcup_{j \in J(i)} B(x_j^i,\sigma)$, with J(i) finite. As a result we obtain

$$Z_i \subset \mathcal{O}_{\nu}(A_{t_i}) \subset \bigcup_{j \in J(i)} B(x_j^i, \nu + \sigma),$$
$$A_t \subset \mathcal{O}_{\nu}(Z_i) \subset \bigcup_{j \in J(i)} B(x_j^i, \sigma + 2\nu).$$

Since ν , σ were arbitrary, the desired inequality follows.

Hence we infer a generalization of the well known equality $\beta(A_1 \cup A_2) = \max\{\beta(A_1), \beta(A_2)\}.$

PROPOSITION 2. If $\{A_t\}_t \subset \mathcal{B}(X)$ is an h-precompact family, then

$$\beta\Big(\bigcup_t A_t\Big) = \sup_t \beta(A_t).$$

3. Uniform Hausdorff upper semicontinuity. This section deals with the notion of continuity introduced in [L2]. We say that a multifunction $\varphi : X \multimap X$ is uniformly Hausdorff upper semicontinuous if for each $\varepsilon > 0$ and each closed subset A of X,

$$\varphi[\mathcal{O}_{\delta}A] \subset \mathcal{O}_{\varepsilon}\varphi(A) \quad \text{for some } \delta > 0.$$

This type of continuity appears in Section 5 (for more details see [L2]; nontrivial examples can be found in [HP] among those concerned with the differences between upper semicontinuity and Hausdorff upper semicontinuity).

THEOREM 1. Let $\{\varphi_t : X \multimap X\}_{t \in T}$ be an h_{\sup} -precompact family of uniformly Hausdorff upper semicontinuous multifunctions. Then $\bigcup_{t \in T} \varphi_t : X \multimap X$ is again uniformly Hausdorff upper semicontinuous.

Proof. Fix $\varepsilon > 0$ and closed $A \subset X$. By h_{\sup} -precompactness choose a finite $\varepsilon/3$ -net $\{\varphi_{t_i}\}_{i=1}^k$, i.e., for each t there is i such that

$$h_{\sup}(\varphi_t, \varphi_{t_i}) < \varepsilon/3.$$

Since $\varphi_{t_1}, \ldots, \varphi_{t_k}$ are uniformly Hausdorff upper semicontinuous, for each *i* there is $\delta_{t_i} > 0$ such that $\varphi_{t_i}[\mathcal{O}_{\delta_{t_i}}(A)] \subset \mathcal{O}_{\varepsilon/3} \varphi_{t_i}(A)$. Hence

$$\varphi_t[\mathcal{O}_{\delta_{t_i}}(A)] \subset \mathcal{O}_{\varepsilon/3}\varphi_{t_i}[\mathcal{O}_{\delta_{t_i}}(A)] \subset \mathcal{O}_{\varepsilon/3}\mathcal{O}_{\varepsilon/3}[\varphi_{t_i}(A)]$$
$$\subset \mathcal{O}_{3\varepsilon/3}\varphi_t(A) \subset \mathcal{O}_{\varepsilon}\Big[\bigcup_t \varphi_t(A)\Big].$$

Putting $\delta = \min\{\delta_{t_i} : i = 1, \dots, k\}$ we get $\bigcup_t \varphi_t[\mathcal{O}_{\delta}(A)] \subset \mathcal{O}_{\varepsilon}[\bigcup_t \varphi_t(A)]$.

Similarly to Theorem 1 one can prove

PROPOSITION 3. The subspace of $\mathcal{BM}(X, X)$ consisting of bounded uniformly Hausdorff upper semicontinuous multifunctions is closed in the h_{sup} semimetric.

So the h_{sup} -limit of a sequence of uniformly Hausdorff upper semicontinuous maps is again a map of the same kind.

4. Compact families of condensing maps. We say that a multifunction $\varphi : X \multimap X$ is:

• a β -contraction if there exists L < 1 such that

$$\beta[\varphi(A)] \le L \cdot \beta(A)$$

for all $A \subset X$ with $\beta(A) < \infty$;

• a β -condensing map if

$$\beta[\varphi(A)] < \beta(A)$$

for all $A \subset X$ with $\beta(A) < \infty$ and $\beta[\varphi(A)] > 0$.

Observe that every β -contraction is β -condensing.

We define, for every $A \subset X$, the evaluation map $ev_A : \mathcal{BM}(X, X) \to \mathcal{B}(X)$ by $ev_A(\varphi) = \varphi(A)$ for all $\varphi \in \mathcal{BM}(X, X)$. From Lemma 1 we obtain:

LEMMA 4. For every $A \subset X$ the evaluation map $ev_A : \mathcal{BM}(X, X) \to \mathcal{B}(X)$ is nonexpansive, i.e.,

$$h[\operatorname{ev}_A(\varphi_1), \operatorname{ev}_A(\varphi_2)] \le h_{\sup}(\varphi_1, \varphi_2).$$

Recall that the Hausdorff measure of noncompactness $\beta : \mathcal{B}(X) \to [0, \infty)$ is nonexpansive, i.e., $|\beta(A_1) - \beta(A_2)| \leq h(A_1, A_2)$; so, in particular, it is continuous (e.g. [AKPRS]). Now we can state the main result.

THEOREM 2 (on compact unions of condensing maps). Let

 $\{\varphi_t : X \multimap X\}_{t \in T} \subset \mathcal{BM}(X, X)$

be an h_{\sup} -compact family of bounded β -condensing multifunctions. Then $\bigcup_{t \in T} \varphi_t : X \multimap X$ is also a bounded β -condensing map.

Proof. Boundedness is obvious (just take a finite net of multifunctions). To verify β -condensity, fix $A \subset X$ with $\beta(A) < \infty$. Since $\{\varphi_t\}_{t \in T}$ is $h_{\text{sup-compact}}$, the family $\{\varphi_t(A)\}_{t \in T} \subset \mathcal{B}(X)$ is h-compact (Lemma 4). By continuity of β the function $t \mapsto \beta[\varphi_t(A)]$ attains its maximum at some t_0 . Finally,

$$\beta \Big[\bigcup_{t \in T} \varphi_t(A) \Big] = \sup_{t \in T} \beta [\varphi_t(A)] = \beta [\varphi_{t_0}(A)] < \beta(A)$$

when the left hand side is > 0; the first equality follows from Proposition 2.

As one might expect, compactness cannot be weakened to precompactness in Theorem 2. More exactly, an h_{\sup} -precompact family of β -contractions need not have a β -condensing union. To see this, simply take the radial projection ρ onto the closed unit ball in an infinite-dimensional Banach space and the family $\{L \cdot \rho\}_{0 \le L < 1}$ of β -contractive maps.

However, there still remains an open question: does the h_{sup} -compact family of β -contractions have a β -contractive union? We only make some observation in this direction.

One can associate with a multifunction $\varphi : X \multimap X$ its β -contractivity constant

$$L(\varphi) = \inf\{L > 0 : \beta[\varphi(A)] \le L \cdot \beta(A) \text{ for all } A \subset X\}.$$

It has the following property:

PROPOSITION 4. The extended real valued function $\mathcal{BM}(X, X) \ni \varphi \mapsto L(\varphi) \in [0, \infty]$ is lower semicontinuous.

Proof. Let $h_{\sup}(\varphi_n, \varphi) \to 0$ as $n \to \infty$ and $A \subset X$ be bounded, i.e. $\beta(A) < \infty$. For every $\varepsilon > 0$ there exists m such that $\varphi(A) \subset \mathcal{O}_{\varepsilon}\varphi_n(A)$ for all $n \geq m$. Therefore

$$\beta[\varphi(A)] \le \inf_{n \ge m} \beta[\varphi_n(A)] + \varepsilon \le \inf_{n \ge m} L(\varphi_n) \cdot \beta(A) + \varepsilon,$$

$$\beta[\varphi(A)] \le \sup_{m} \inf_{n \ge m} L(\varphi_n) \cdot \beta(A);$$

so $L(\varphi) \leq \liminf_{n \to \infty} L(\varphi_n)$, which shows the lower semicontinuity (see e.g. [HP]). \blacksquare

Thus every h_{sup} -compact family of β -contractions contains one with the minimal β -contractivity constant. We do not know any counterexample to the conjecture that the maximal constant is also attained.

5. Application to iterated function systems. Iterated function systems (IFS) have been extensively studied at various levels of generality ([Hu], [SV], [Ha], [JGP], [H], [AF], [AG], [W], [E], [LM], [K]). Two streams of research could be singled out: set-theoretical and topological. However, such

divisions would be unsuitable, because of the natural interplay between order and topology (see [CoV]).

Below we collect some necessary definitions from [L1] and [L2]. A family $\{\varphi_t : X \multimap X\}_{t \in T}$ of multifunctions is said to be a multivalued iterated function system, and the operator $F : 2^X \to 2^X$, $F(A) = \bigcup_{t \in T} \varphi_t(A)$ for $A \in 2^X$, is called its Barnsley-Hutchinson operator. In the case of a finite family $\{\varphi_1, \ldots, \varphi_k : X \multimap X\}$ one can always replace it with a singleton $\{\varphi : X \multimap X\}$, where $\varphi(x) = \bigcup_{i=1}^k \varphi_i(x)$. Many properties of multifunctions, like compactness and contractivity, are preserved under finite unions. Notice also that a fixed point A_* of F generated by $\varphi : X \multimap X$ need not be completely invariant under φ , although $\overline{\varphi(A_*)} = A_*$.

We say that a set M attracts $A \subset X$ under φ if for every $\varepsilon > 0$ there exists n_0 such that $F^n(A) \subset \mathcal{O}_{\varepsilon}M$ for all $n \ge n_0$ (F^n denotes the *n*-fold composition of F). A minimal closed set M attracting all subsets of X (equivalently: attracting the whole space X) is called an *attractor* (see [L2]). We point out that the attractor M always has the form $M = \bigcap_{n \in \mathbb{N}} F^n(X)$, and that our notion differs slightly from the usual concept of global attractor. (The intersection $\bigcap_n F^n(X)$ is not always an attractor: to see this, just consider the time one map for an appropriate continuous flow on a halfplane).

A good example of a condensing map is provided by multivalued weak contraction with compact values. This enables us to apply our results to weakly contractive IFS's (comp. [H], [W], [AF]).

Let $\eta : [0, \infty) \to [0, \infty)$ be a nondecreasing right-continuous function such that $\eta(0) = 0$, $\eta(r) < r$ for r > 0.

A multifunction $\varphi : X \multimap X$ is a *weak contraction* provided there exists a function η as above such that

$$h[\varphi(x_1),\varphi(x_2)] \le \eta(d(x_1,x_2)) \quad \text{for all } x_1, x_2 \in X.$$

PROPOSITION 5. If $\varphi : X \multimap X$ is a multivalued weak contraction with compact values, then it is β -condensing.

Proof. Fix $r > \beta(A) > 0$ and $\varepsilon > 0$. Next, find a finite r-net for A, i.e., $\bigcup_i B(x_i, r) \supset A$. Observing that $\varphi[B(x_i, r)] \subset \mathcal{O}_{\eta(r)+\varepsilon}\varphi(x_i)$ we obtain

$$\varphi(A) \subset \bigcup_{i} \varphi[B(x_i, r)] \subset \bigcup_{i} \mathcal{O}_{\eta(r) + \varepsilon} \varphi(x_i).$$

Now, put $K = \bigcup_i \varphi(x_i)$, and cover it by a finite family of balls, $K \subset \bigcup_j B(z_j, \varepsilon)$. Hence we infer $\beta[\varphi(A)] \leq \eta(r) + 2\varepsilon$. Finally, since r and ε were arbitrary,

$$\beta[\varphi(A)] \leq \lim_{r \to \beta(A)} \, \eta(r) = \eta[\beta(A)] < \beta(A).$$

Additionally, if $\beta(A) = 0$ then $\beta[\varphi(A)] = 0$, by continuity of φ .

We will need

THEOREM 3 (on attractors of condensing maps). Let X be a complete space, $\varphi : X \multimap X$ a bounded β -condensing multifunction, and F the Barnsley-Hutchinson operator associated with φ . Then there exists a compact attractor M and a maximal fixed point A_* of F such that $A_* \subset M$. If additionally φ is uniformly Hausdorff upper semicontinuous, then $A_* = M$.

This improvement on [L1] and [L2] can be obtained by applying the observations made in [S] and Lemma 1.6.11 of [AKPRS].

Now, combining Theorems 3 and 2 we arrive at the following theorem which is an improvement and partial generalization of some results from [W] and [K].

THEOREM 4 (on attractors of compact families of condensing maps). Let $\Phi = \{\varphi_t : X \multimap X\}_t \subset \mathcal{BM}(X, X)$ be an h_{\sup} -compact family of bounded β -condensing multifunctions, and let F be the Barnsley-Hutchinson operator associated with Φ . Then Φ has a compact attractor M and F has a maximal fixed point A_* such that $A_* \subset M$. Moreover, if all φ_t are uniformly Hausdorff upper semicontinuous, then $A_* = M$.

Finally, note that all the results from Sections 1, 3 and 4 can be reformulated for multifunctions which are not necessarily selfmaps.

Acknowledgments. I would like to thank Professors L. Górniewicz, W. Kryszewski and D. Miklaszewski for their constructive comments.

References

 Sadovskiĭ, Measures of Noncompactness and Condensing Opera Novosibirsk, 1986 (in Russian). [AF] J. Andres and J. Fišer, Metric and Topological Multivalued Fract J. Bifur. Chaos 14 (2004), to appear. 	ators, Nauka, tals, Internat. ciple for mul- ematical Eco- 1-23
 [AF] Novosibirsk, 1986 (in Russian). [AF] J. Andres and J. Fišer, Metric and Topological Multivalued Fract J. Bifur. Chaos 14 (2004), to appear. 	tals, Internat. ciple for mul- ematical Eco-
 [AF] J. Andres and J. Fišer, Metric and Topological Multivalued Fract J. Bifur. Chaos 14 (2004), to appear. 	tals, Internat. ciple for mul- ematical Eco- 1-23
J. Bifur. Chaos 14 (2004), to appear.	ciple for mul- ematical Eco-
	ciple for mul- ematical Eco- 1-23
[AG] J. Andres and L. Górniewicz, On the Banach contraction princ	ematical Eco- 1–23
tivalued mappings, in: Approximation, Optimization and Mathe	1-23
nomics, M. Lassonde, (ed.), Physica-Verlag and Springer, 2001,	1 40.
[CV] C. Castaing and M. Valadier, Convex Analysis and Measurable M	Iultifunctions,
Lecture Notes in Math. 580, Springer, Berlin, 1977.	
[CoV] C. Costantini and P. Vitolo, Decomposition of topologies on law	ttices and hy-
perspaces, Dissertationes Math. 381 (1999).	
[D] K. Deimling, Nonlinear Functional Analysis, Springer, Berlin, 1	.985.
[E] A. Edalat, Dynamical systems, measures and fractals via doma	in theory, In-
form. and Comput. 120 (1995), 32–48.	
[H] M. Hata, On some properties of set-dynamical systems, Proc.	Japan Acad.
Ser. A Math. Sci. 61 (1985), 99–102.	
[Ha] S. Hayashi, Self-similar sets as Tarski's fixed points, Publ. RIMS	3 Kyoto Univ.
21 (1985), 1059-1066.	

8	K. Leśniak
[HP]	S. Hu and N. S. Papageorgiou, Handbook of Multivalued Analysis, Volume I:
[TT]	<i>Theory</i> , Math. Appl., Kluwer, Dordrecht, 1997.
[Hu]	J. E. Hutchinson, Fractals and self similarity, Indiana Univ. Math. J. 30 (1981), 713–747.
[JGP]	J. Jachymski, L. Gajek and P. Pokarowski, <i>The Tarski–Kantorovitch principle and the theory of iterated function systems</i> , Bull. Austral. Math. Soc. 61 (2000), 247–261.
[K]	B. Kieninger, Iterated Function Systems on Compact Hausdorff Spaces, Berichte Math., Shaker-Verlag, Aachen, 2002.
[LM]	A. Lasota and J. Myjak, <i>Attractors of multifunctions</i> , Bull. Polish Acad. Sci. Math. 48 (2000), 319–334.
[L1]	K. Leśniak, <i>Extremal sets as fractals</i> , Nonlinear Anal. Forum 7 (2002), 199–208.
[L2]	-, Stability and invariance of multivalued iterated function systems, Math. Slovaca 53 (2003), 393–405.
[S]	V. Šeda, On condensing discrete dynamical systems, Math. Bohem. 125 (2000), 275–306.
[SV]	J. Soto-Andrade and F. J. Varela, Self-reference and fixed points: A discussion and an extension of Lawyere's theorem, Acta Appl. Math. 2 (1984), 1–19.
[W]	K. R. Wicks, <i>Fractals and Hyperspaces</i> , Lecture Notes in Math. 1492, Springer, Berlin, 1991.
K. Leśni	ak
Faculty	of Mathematics and Computer Science
Nicolaus	Copernicus University
Chapipa	19/19

Nicolaus Copernicus University Chopina 12/18 87-100 Toruń, Poland E-mail: much@mat.uni.torun.pl

> Received 2.7.2003; received in final form 19.12.2003

(7345)