

## FIXED POINT THEOREMS FOR SET-VALUED $Y$ -CONTRACTIONS

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**Abstract.** The purpose of this paper is to present several fixed point theorems for the so-called set-valued  $Y$ -contractions. Set-valued  $Y$ -contractions in ordered metric spaces, set-valued graphic contractions, set-valued contractions outside a bounded set and set-valued operators on a metric space with cyclic representations are considered.

### 1. Introduction

**1.1. Basic notions and notation.** Throughout this paper, the standard notation and terminology in nonlinear analysis are used. For the convenience of the reader we recall some of them.

Let  $(X, d)$  be a metric space and  $f : X \rightarrow X$  an operator. By  $\text{Fix } f := \{x \in X : x = f(x)\}$  we will denote the fixed point set of the operator  $f$  and by  $\tilde{B}(x_0, r)$  the closed ball centered in  $x_0 \in X$  with radius  $r > 0$ .

We will also use the following symbols:

$$P(X) := \{Y \subset X : Y \text{ is nonempty}\}, \quad P_{\text{cl}}(X) := \{Y \in P(X) : Y \text{ is closed}\},$$
$$P_{\text{cp}}(X) := \{Y \in P(X) : Y \text{ is compact}\}, \quad P_{\text{b}}(X) := \{Y \in P(X) : Y \text{ is bounded}\}.$$

In normed spaces,  $P_{\text{cv}}(X) := \{Y \in P(X) : Y \text{ is convex}\}$ .

Let  $A$  and  $B$  be nonempty subsets of the metric space  $(X, d)$ . The *gap* between these sets is

$$D(A, B) = \inf\{d(a, b) : a \in A, b \in B\}.$$

In particular,  $D(x_0, B) = D(\{x_0\}, B)$  (where  $x_0 \in X$ ) is called the *distance* from the point  $x_0$  to the set  $B$ .

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The *Pompeiu–Hausdorff generalized distance* between the nonempty closed subsets  $A$  and  $B$  of the metric space  $(X, d)$  is defined by the formula

$$H(A, B) := \max\{\sup_{a \in A} \inf_{b \in B} d(a, b), \sup_{b \in B} \inf_{a \in A} d(a, b)\}.$$

If  $A$  and  $B$  are nonempty and bounded subsets of the metric space  $(X, d)$ , then one defines

$$\delta(A, B) := \sup\{d(a, b) : a \in A, b \in B\}.$$

The symbol  $T : X \multimap Y$  means  $T : X \rightarrow P(Y)$ , i.e.,  $T$  is a set-valued operator from  $X$  to  $Y$ . We will denote by  $\mathbb{M}^0(X, Y)$  the set of all set-valued operators  $T : X \multimap Y$ . If  $X = Y$  then  $\mathbb{M}^0(Y) := \mathbb{M}^0(Y, Y)$ . For  $K \in P(X)$ ,  $T(K) := \bigcup_{x \in K} T(x)$  will denote the *image* of the set  $K$ , while  $\text{Graf}(T) := \{(x, y) \in X \times Y : y \in T(x)\}$  is the *graph* of  $T$ . Recall that the set-valued operator is called *closed* if  $\text{Graf}(T)$  is closed in  $X \times Y$ . If  $X$  and  $Y$  are Hausdorff topological spaces then  $T^+(U) := \{x \in X : T(x) \subset U\}$ , for  $U \in P(Y)$ . The set-valued operator  $T : X \rightarrow P(Y)$  is said to be *upper semi-continuous* on  $X$  (briefly *u.s.c.*) if and only if  $T^+(U)$  is open in  $X$  for each open subset  $U$  of  $Y$ .

For  $T : X \rightarrow P(X)$  the set of all nonempty invariant subsets of  $X$  will be denoted by  $I(T)$ , i.e.  $I(T) := \{Y \in P(X) : T(Y) \subset Y\}$ . Also  $\text{Fix}(T) := \{x \in X : x \in T(x)\}$  denotes the *fixed point set* of the set-valued operator  $T$ , while  $\text{SFix}(T) := \{x \in X : \{x\} = T(x)\}$  is the *strict fixed point set* of  $T$ .

If  $(X, d)$  is a metric space, recall that  $T : X \rightarrow P_{\text{cl}}(X)$  is called a *set-valued  $a$ -contraction* if  $a \in ]0, 1[$  and  $H(T(x_1), T(x_2)) \leq a \cdot d(x_1, x_2)$ , for each  $x_1, x_2 \in X$ . In the same setting, an operator  $T : X \rightarrow P_{\text{cl}}(X)$  is a *multivalued weakly Picard operator* (briefly *MWP operator*) (see [25]) if for each  $x \in X$  and each  $y \in T(x)$  there exists a sequence  $(x_n)_{n \in \mathbb{N}}$  in  $X$  such that:

- (i)  $x_0 = x, x_1 = y$ ;
- (ii)  $x_{n+1} \in T(x_n)$  for all  $n \in \mathbb{N}$ ;
- (iii) the sequence  $(x_n)_{n \in \mathbb{N}}$  is convergent and its limit is a fixed point of  $T$ .

A sequence  $(x_n)_{n \in \mathbb{N}}$  in  $X$  satisfying the condition (ii) from the previous definition is called the *sequence of successive approximations of  $T$  starting from  $x_0 \in X$* .

(Here  $\mathbb{N}$  denotes the set of all nonnegative integers. The set of all positive integers will be denoted by  $\mathbb{N}^*$ .)

Let  $X$  be a nonempty set. By definition (see [20]), the triple  $(X, S(X), M^0)$  is a *fixed point structure* (briefly *f.p.s.*) if:

- (i)  $S(X) \subset P(X)$ ,  $S(X) \neq \emptyset$ ;
- (ii)  $M^0 : P(X) \multimap \bigcup_{Y \in P(X)} \mathbb{M}^0(Y)$ , with  $Y \multimap M^0(Y) \subset \mathbb{M}^0(Y)$  is a mapping such that if  $Z \subset Y$ ,  $Z \neq \emptyset$  then  $M^0(Z) \supset \{T|_Z : T \in M^0(Y), Z \in I(T)\}$ ;
- (iii) every  $Y \in S(X)$  has the fixed point property with respect to  $M^0(Y)$ .

Let  $X$  be a nonempty set. Define  $s(X) := \{(x_n)_{n \in \mathbb{N}} : x_n \in X, n \in \mathbb{N}\}$ .

Let  $c(X) \subset s(X)$  be a subset of  $s(X)$  and  $\text{Lim} : c(X) \rightarrow X$  an operator. By definition the triple  $(X, c(X), \text{Lim})$  is called an *L-space* (Fréchet [4]) if the following conditions are

satisfied:

- (i) If  $x_n = x$  for each  $n \in \mathbb{N}$ , then  $(x_n)_{n \in \mathbb{N}} \in c(X)$  and  $\text{Lim}(x_n)_{n \in \mathbb{N}} = x$ .
- (ii) If  $(x_n)_{n \in \mathbb{N}} \in c(X)$  and  $\text{Lim}(x_n)_{n \in \mathbb{N}} = x$ , then for all subsequences,  $(x_{n_i})_{i \in \mathbb{N}}$ , of  $(x_n)_{n \in \mathbb{N}}$  we have  $(x_{n_i})_{i \in \mathbb{N}} \in c(X)$  and  $\text{Lim}(x_{n_i})_{i \in \mathbb{N}} = x$ .

By definition an element of  $c(X)$  is a convergent sequence and  $x := \text{Lim}(x_n)_{n \in \mathbb{N}}$  is the limit of this sequence and we write  $x_n \rightarrow x$  as  $n \rightarrow \infty$ .

In what follow we denote an L-space by  $(X, \rightarrow)$ . Hausdorff topological spaces, metric spaces, generalized metric spaces ( $d(x, y) \in \mathbb{R}_+^m$ , or  $d(x, y) \in \mathbb{R}_+ \cup \{+\infty\}$ , or  $d(x, y) \in K$ ,  $K$  a cone in an ordered Banach space, or  $d(x, y) \in E$ ,  $E$  an ordered linear space with a notion of linear convergence, etc.), gauge spaces, 2-metric spaces, D-R-spaces, probabilistic metric spaces, syntopogenous spaces, are examples of L-spaces.

**1.2. The aim of the paper.** The purpose of this work is to consider the following open question of I. A. Rus [21]:

I. Let  $(X, d)$  be a metric space and  $Y \subseteq X \times X$ . The operator  $T : X \rightarrow P_{cl}(X)$  is called a set-valued  $(Y, a)$ -contraction if

$$a \in ]0, 1[ \text{ and } H(T(x_1), T(x_2)) \leq a \cdot d(x_1, x_2) \text{ for each } (x_1, x_2) \in Y. \tag{1.1}$$

Construct a fixed point theory for set-valued  $(Y, a)$ -contractions.

Of course, in the previous definition, one can imagine generalized type conditions for  $T$ , such as

there exists  $\varphi : \mathbb{R}_+^5 \rightarrow \mathbb{R}_+$  such that

$$H(T(x_1), T(x_2)) \leq \varphi(d(x_1, x_2), D(x_1, T(x_1)), D(x_2, T(x_2)), D(x_1, T(x_2)), D(x_2, T(x_1)))$$

for each  $(x_1, x_2) \in Y$ . (1.2)

In connection with the above problem one can consider

II. Let  $(X, d)$  be a metric space and  $Y \subseteq X \times X$ . The operator  $T : X \rightarrow P_b(X)$  is called a set-valued  $(Y, a)$ - $\delta$ -contraction if

$$a \in ]0, 1[ \text{ and } \delta(T(x_1), T(x_2)) \leq a \cdot d(x_1, x_2) \text{ for each } (x_1, x_2) \in Y. \tag{1.3}$$

Construct a fixed point theory for set-valued  $(Y, a)$ - $\delta$ -contractions.

III. Let  $(X, d)$  be a metric space and  $Y \subseteq X \times X$ . The operator  $T : X \rightarrow P_{cl}(X)$  is called a set-valued  $(Y, a)$ -Gap-contraction if

$$a \in ]0, 1[ \text{ and } D(T(x_1), T(x_2)) \leq a \cdot d(x_1, x_2) \text{ for each } (x_1, x_2) \in Y. \tag{1.4}$$

Construct a fixed point theory for set-valued  $(Y, a)$ -Gap-contractions.

Obviously, as in case I, generalized type conditions on  $T$  can be also considered.

The following examples are in connection with the above problems.

EXAMPLE 1.1. Let  $(X, d)$  be a metric space and  $Y := X \times X$ . Then a set-valued  $(Y, a)$ -contraction is a set-valued  $a$ -contraction ([1], [2], [3], [6], [8], [11], [16], [21], [26], etc.).

EXAMPLE 1.2. Let  $(X, d)$  be a metric space,  $T : X \rightarrow P_{cl}(X)$  and  $Y := \text{Graf}(T)$ . Then a set-valued  $(Y, a)$ -contraction is a set-valued  $a$ -graphic contraction ([17], [18]).

EXAMPLE 1.3. Let  $(X, d)$  be a metric space,  $x_0 \in X$  and  $r > 0$ . Consider  $Y := \tilde{B}(x_0, r) \times \tilde{B}(x_0, r)$ . Then for  $T : X \rightarrow P_{cl}(X)$  the set-valued  $(Y, a)$ -contraction condition means that the following Frigon–Granas type condition (see [5], [12]) holds:

$$\text{there is } a \in ]0, 1[ \text{ such that } H(T(x), T(y)) \leq a \cdot d(x, y) \text{ for all } x, y \in \tilde{B}(x_0, r). \quad (1.5)$$

EXAMPLE 1.4. Let  $(X, d)$  be a metric space,  $Z \in P_b(X)$  and  $Y := (X \setminus Z) \times (X \setminus Z)$ . Then a set-valued  $(Y, a)$ -contraction is a set-valued  $a$ -contraction outside a bounded subset, see [21], [19].

EXAMPLE 1.5. Let  $(X, d, \leq)$  be an ordered metric space. Consider  $Y := \{(x, y) \in X \times X : x \leq y \text{ or } y \leq x\}$ . Then  $T : X \rightarrow P_{cl}(X)$  is a set-valued  $(Y, a)$ -contraction if (see also [15], [13]) if

$$a \in ]0, 1[ \text{ and } H(T(x), T(y)) \leq a \cdot d(x, y), \text{ for all } x, y \in X, x \leq y. \quad (1.6)$$

EXAMPLE 1.6. Let  $(X, d)$  be a metric space,  $T : X \rightarrow P_{cl}(X)$  and  $A_i \in P(X)$ ,  $i \in \{1, 2, \dots, m\}$ . Suppose that  $X = \bigcup_{i=1}^m A_i$  is a cyclic representation with respect to the set-valued operator  $T$ , i.e.  $T(A_i) \subset A_{i+1}$ ,  $i \in \{1, 2, \dots, m\}$  (where  $A_{m+1} = A_1$ ).

Consider  $Y := \bigcup_{i=1}^m (A_i \times A_{i+1})$ . Then  $T$  is a set-valued  $(Y, a)$ -contraction ([9], [23]) if

$$a \in ]0, 1[ \text{ and } H(T(x), T(y)) \leq a \cdot d(x, y) \text{ for all } x \in A_i \text{ and all } y \in A_{i+1}, i \in \{1, 2, \dots, m\}. \quad (1.7)$$

**2. Set-valued  $(Y, a)$ -contractions in ordered metric spaces.** Let  $(X, \leq)$  be a partially ordered set. Let  $X_{\leq} := \{(x, y) \in X \times X : x \leq y \text{ or } y \leq x\}$ . Also, if  $x, y \in X$  with  $x \leq y$ , then by  $[x, y]_{\leq}$  we will denote the ordered segment joining  $x$  and  $y$ , i.e.  $[x, y]_{\leq} := \{z \in X : x \leq z \leq y\}$ .

DEFINITION 2.1. Let  $X$  be a nonempty set. Then, by definition  $(X, d, \leq)$  is an *ordered metric space* if and only if:

- (i)  $(X, d)$  is a metric space;
- (ii)  $(X, \leq)$  is a partially ordered set;
- (iii)  $(x_n)_{n \in \mathbb{N}} \rightarrow x$ ,  $(y_n)_{n \in \mathbb{N}} \rightarrow y$  and  $x_n \leq y_n$  for each  $n \in \mathbb{N} \Rightarrow x \leq y$ .

The main result of this section is

THEOREM 2.2. *Let  $(X, d, \leq)$  be an ordered complete metric space and  $T : X \rightarrow P_{cl}(X)$  a set-valued operator. Suppose that the following assertions hold:*

- (i) *there exists  $x_0 \in X$  such that if  $y \in T(x_0)$  then  $(x_0, y) \in X_{\leq}$ ;*
- (ii) *for each  $x, y \in X$ , with  $(x, y) \notin X_{\leq}$ , there exists  $c(x, y) \in X$  such that  $(x, c(x, y))$  and  $(y, c(x, y))$  belong to  $X_{\leq}$ ;*
- (iii)  *$(x, y) \in X_{\leq}$  implies  $(u \in T(x) \text{ and } v \in T(y) \text{ then } (u, v) \in X_{\leq}$ );*
- (iv)  *$T$  is a closed set-valued operator;*
- (v)  *$T$  is a set-valued  $(X_{\leq}, a)$ -contraction.*

Then for each  $x \in X$  there is a sequence  $(x_n)_{n \in \mathbb{N}}$  of successive approximations of  $T$  starting from  $x$  that converges to a fixed point of  $T$ .

*Proof.* Let  $q > 1$  and  $x_1 \in T(x_0)$  be arbitrary. Then there exists  $x_2 \in T(x_1)$  such that  $d(x_1, x_2) \leq q \cdot H(T(x_0), T(x_1))$ . From (i) we have  $(x_0, x_1) \in X_{\leq}$ . Using (v) we obtain  $H(T(x_0), T(x_1)) \leq a \cdot d(x_0, x_1)$ . As a consequence,  $d(x_1, x_2) \leq q \cdot a \cdot d(x_0, x_1)$ . Taking (iii) into account we get  $(x_1, x_2) \in X_{\leq}$ . Inductively we can construct a sequence  $(x_n)_{n \in \mathbb{N}}$  having the following two properties:

- (a)  $x_{n+1} \in T(x_n)$  for  $n \in \mathbb{N}$ ;
- (b)  $d(x_{n+1}, x_n) \leq q \cdot a \cdot d(x_n, x_{n-1})$  for  $n \in \mathbb{N}^*$ .

If we choose  $q \in ]1, a^{-1}[$  then, by standard methods, we obtain the convergence of the sequence  $(x_n)_{n \in \mathbb{N}}$  to some  $x^* \in X$ . From (iv) it follows that  $x^* \in F_T$ . Hence  $\text{Fix}(T) \neq \emptyset$ .

We will prove now that for each  $x \in X$  and each  $y \in T(x)$  there exists a sequence  $(z_n)_{n \in \mathbb{N}}$  of successive approximations for  $T$  starting from  $(x, y) \in \text{Graf}(T)$  such that  $(z_n)$  converges to a fixed point of  $T$ .

*Case A.* Let  $z_0 \in X$  such that  $(x_0, z_0) \in X_{\leq}$ . Then there exists  $z_1 \in T(z_0)$  such that  $d(x_1, z_1) \leq q \cdot H(T(x_0), T(z_0)) \leq q \cdot a \cdot d(x_0, z_0)$ . Since  $(x_1, z_1) \in X_{\leq}$  we can continue this procedure and obtain a sequence  $(z_n)_{n \in \mathbb{N}}$  such that  $z_{n+1} \in T(z_n)$  for  $n \in \mathbb{N}$  and  $d(x_{n+1}, z_{n+1}) \leq q \cdot a \cdot d(x_n, z_n)$ . Choosing  $q \in ]1, a^{-1}[$  we deduce that  $(z_n) \rightarrow x^* \in T(x^*)$ .

*Case B.* Let  $z_0 \in X$  such that  $(x_0, z_0) \notin X_{\leq}$ . Then, from (ii) there exists  $c(x_0, z_0) \in X$  such that

$$(1) \quad (x_0, c(x_0, z_0)) \in X_{\leq}$$

and

$$(2) \quad (z_0, c(x_0, z_0)) \in X_{\leq}.$$

From (1), using the method from Case A, we can construct a sequence of successive approximations for  $T$  starting from  $c(x_0, z_0)$  which converges to  $x^*$ . From (2) and the above conclusion, we deduce in the same manner as in Case A that there exists a sequence  $(z_n)$  of successive approximations for  $T$  starting from  $z_0$  such that  $(z_n) \rightarrow x^*$ . This finishes the proof. ■

REMARK 2.3. It is an open question whether  $T$  satisfying the hypotheses of Theorem 2.2 is a MWP operator.

**3. Set-valued graphic contractions.** Let  $(X, d)$  be a complete metric space and  $T : X \rightarrow P_b(X)$  be a set-valued operator. If there exist  $a, b, c \in \mathbb{R}_+$  with  $a + b + c < 1$  such that

$$\delta(T(x), T(y)) \leq a \cdot d(x, y) + b \cdot \delta(x, T(x)) + c \cdot \delta(y, T(y)) \text{ for each } x \in X \text{ and } y \in T(x),$$

then the problem is to study when  $\text{Fix}(T) = \text{SFix}(T) \neq \emptyset$ .

In connection with the above problem we have:

EXAMPLE 3.1. Let  $(X, d)$  be a metric space and  $X = X_1 \cup \dots \cup X_m$  be a partition of  $X$ . For each  $i \in \{1, 2, \dots, m\}$ , let  $x_i \in X_i$  be given elements. Consider  $T : X \rightarrow P_b(X)$

defined by  $T(x) := \{x_i\}$ , if  $x \in X_i$ . Then  $T$  satisfies the above condition and  $\text{Fix}(T) = \text{SFix}(T) = \{x_1, \dots, x_m\}$ .

The first result of this section is the following strict fixed point theorem for a set-valued operator satisfying to a certain contractive type condition on its graph.

**THEOREM 3.2.** *Let  $(X, d)$  be a complete metric space and  $T : X \rightarrow P_b(X)$  be a closed set-valued operator. Suppose that*

*there exist  $a, b, c \in \mathbb{R}_+$  with  $a + b + c < 1$  such that*

$$\delta(T(x), T(y)) \leq a \cdot d(x, y) + b \cdot \delta(x, T(x)) + c \cdot \delta(y, T(y))$$

*for each  $(x, y) \in \text{Graf}(T)$ . (3.1)*

*Then  $\text{Fix}(T) = \text{SFix}(T) \neq \emptyset$ .*

*Proof.* Let  $q > 1$  and  $x_0 \in X$  be arbitrary. Then there exists  $x_1 \in T(x_0)$  such that  $\delta(x_0, T(x_0)) \leq q \cdot d(x_0, x_1)$ . We have  $\delta(x_1, T(x_1)) \leq \delta(T(x_0), T(x_1)) \leq a \cdot d(x_0, x_1) + b \cdot \delta(x_0, T(x_0)) + c \cdot \delta(x_1, T(x_1)) \leq ad(x_0, x_1) + bqd(x_0, x_1) + c \cdot \delta(x_1, T(x_1))$ . Hence  $\delta(x_1, T(x_1)) \leq \frac{a+bq}{1-c} \cdot d(x_0, x_1)$ . By this procedure, we can obtain the sequence  $(x_n)_{n \in \mathbb{N}}$  having the property  $d(x_n, x_{n+1}) \leq (\frac{a+bq}{1-c})^n \cdot d(x_0, x_1)$  for each  $n \in \mathbb{N}$ . If we choose  $q > \frac{b}{1-a-c}$  then  $\frac{a+bq}{1-c} < 1$ . Hence  $(x_n)_{n \in \mathbb{N}}$  is a Cauchy sequence in the complete metric space  $(X, d)$ . Denote by  $x^*$  the limit of the sequence  $(x_n)_{n \in \mathbb{N}}$ . Since  $\text{Graf}(T)$  is a closed set in  $X \times X$  we obtain the first conclusion  $x^* \in T(x^*)$ .

Let us establish now the relation  $\text{Fix}(T) = \text{SFix}(T)$ . It is enough to prove that  $\text{Fix}(T) \subset \text{SFix}(T)$ . For, let  $x \in \text{Fix}(T)$  be arbitrary. Then, using the hypothesis (with  $y = x \in T(x)$ ) we get successively:  $\delta(T(x)) \leq (b + c) \cdot \delta(x, T(x)) \leq (b + c) \cdot \delta(T(x))$ . Suppose, by absurdum, that  $\text{card} T(x) > 1$ . Then  $\delta(T(x)) > 0$  and using the above relation we get  $1 \leq b + c$ , a contradiction. Hence  $\delta(T(x)) = 0$  and so  $\{x\} = T(x)$ . ■

**REMARK 3.3.** Theorem 3.2 is an extension of some results given in S. Reich [16] and I. A. Rus [21].

Moreover, condition (3.1) can be replaced with a more general one, namely: there exist  $a \in [0, 1[$  such that

$$\delta(T(x), T(y)) \leq a \cdot \delta(x, T(x)) \text{ for each } (x, y) \in \text{Graf}(T),$$

since  $d(x, y) \leq \delta(x, T(x))$  and  $\delta(y, T(y)) \leq \delta(T(x), T(y))$ .

Next, we present a strict fixed point theorem.

**THEOREM 3.4.** *Let  $(X, d)$  be a complete metric space, and  $T : X \rightarrow P_b(X)$  be a set-valued operator. Suppose that*

*there exist  $a, b \in \mathbb{R}_+$  with  $a + b < 1$  such that for each  $x \in X$*

$$\text{there exists } y \in T(x) \text{ with } \delta(y, T(y)) \leq a \cdot d(x, y) + b \cdot \delta(x, T(x)). \quad (3.2)$$

*If the map  $f : X \rightarrow \mathbb{R}_+$ , defined by  $f(x) := \delta(x, T(x))$ , is lower semicontinuous, then  $\text{SFix}(T) \neq \emptyset$ .*

*Proof.* From (3.2), for each  $x \in X$  there is a  $y \in T(x)$  such that  $\delta(y, T(y)) \leq (a + b) \times \delta(x, T(x))$ . Then, for each  $x_0 \in X$  we can construct inductively a sequence  $(x_n)_{n \in \mathbb{N}}$  of successive approximations for  $T$  starting from  $x_0$ , having the property  $\delta(x_n, T(x_n)) \leq (a + b)^n \cdot \delta(x_0, T(x_0))$ . Hence, we will obtain  $d(x_n, x_{n+1}) \leq \delta(x_n, T(x_n)) \rightarrow 0$  as  $n \rightarrow +\infty$ . As a consequence, the sequence  $(x_n)_{n \in \mathbb{N}}$  is Cauchy. Denote by  $x^* \in X$  the limit of this sequence.

If we denote  $f(x_n) := \delta(x_n, T(x_n))$ , then using the lower semicontinuity of  $f$  we can write:

$$0 \leq f(x^*) \leq \liminf_{n \rightarrow +\infty} f(x_n) = 0.$$

So,  $f(x^*) = 0$  and the conclusion  $\{x^*\} = T(x^*)$  follows. ■

REMARK 3.5. If, instead of the lower semicontinuity of  $f$ , we suppose that  $\text{Graf}(T)$  is closed, then, since  $(x_n)_{n \in \mathbb{N}}$  is a sequence of successive approximations for  $T$ , we immediately get that  $x^* \in T(x^*)$ . So, the conclusion of the above result is  $\text{Fix}(T) \neq \emptyset$ . It is an open question if the above fixed point is a strict fixed point for  $T$ .

REMARK 3.6. In Theorem 3.4 condition (3.2) can be replaced with a more general one: there exists  $a \in [0, 1[$  such that for each  $x \in X$  there exists  $y \in T(x)$  with  $\delta(y, T(y)) \leq a \cdot \delta(x, T(x))$ , since again  $d(x, y) \leq \delta(x, T(x))$ .

REMARK 3.7. An open problem is to construct a fixed point theory for set-valued  $Y$ -contractions in  $K$ -metric spaces (see [27]).

**4. Set-valued contractions outside a bounded set.** Let  $X$  be a Banach space and  $T : X \rightarrow P_b(X)$ . By definition (see [10], [7]), the operator  $T$  is called *quasi-bounded* if there exist  $m, M > 0$  such that

$$\|y\| \leq m \cdot \|x\| + M \text{ for each } (x, y) \in \text{Graf}(T). \tag{4.1}$$

The number

$$|T| := \inf\{m > 0 : \text{there exists } M > 0 \text{ such that relation (4.1) holds}\},$$

is called the *quasi-norm* of  $T$ .

Let us denote by  $\alpha_K$  the Kuratowski measure of noncompactness on  $X$  and let  $\varphi : \mathbb{R}_+ \rightarrow \mathbb{R}_+$  be a comparison function (i.e.  $\varphi$  is non-decreasing and  $(\varphi^n(t))_{n \in \mathbb{N}}$  goes to 0, for each  $t \geq 0$  as  $n \rightarrow +\infty$ ). An operator  $T : X \rightarrow P_b(X)$  is said to be an  $(\alpha_K, \varphi)$ -contraction if  $T$  is a bounded operator,  $\varphi$  is a comparison function and  $\alpha_K(T(A)) \leq \varphi(\alpha_K(A))$  for each  $A \in P_b(X) \cap I(T)$ .

The first main result of this section is

**THEOREM 4.1.** *Let  $X$  be a Banach space,  $Z \in P_b(X)$  and  $T : X \rightarrow P_{\text{cp,cv}}(X)$ . Suppose that the following assertions hold:*

- (i)  *$T$  is u.s.c. and compact (i.e.  $T$  sends bounded sets into relatively compact sets);*
- (ii) *there exists  $a \in ]0, 1[$  such that*

$$H(T(x_1), T(x_2)) \leq a \cdot \|x_1 - x_2\| \text{ for each } (x_1, x_2) \in (X \setminus Z) \times (X \setminus Z).$$

*Then  $\text{Fix}(T) \neq \emptyset$ .*

*Proof.* From (ii) the operator  $T$  is quasi-bounded with the quasi-norm  $|T| = a < 1$ . For, consider first  $x \in Z$ . Then  $\|T(x)\| := \sup_{y \in T(x)} \|y\| \leq \|T(Z)\| < +\infty$ . If  $x \in X \setminus Z$  then consider an arbitrary but fixed  $x_0 \in X \setminus Z$ . We have  $\|T(x)\| = H(T(x), \{0\}) \leq H(T(x), T(x_0)) + H(T(x_0), \{0\}) \leq a \cdot \|x - x_0\| + \|T(x_0)\| \leq a \cdot \|x\| + a \cdot \|x_0\| + \|T(x_0)\|$ . Hence, for all  $x \in X$  we get  $\|T(x)\| \leq a \cdot \|x\| + \max(a \cdot \|x_0\| + \|T(x_0)\|, \|T(Z)\|)$ . From Lemma 2.1 in [10] (p. 59) there exists  $R > 0$  such that  $T(\tilde{B}(0, R)) \subset \tilde{B}(0, R)$ . If we take into account that  $T(\tilde{B}(0, R))$  is an invariant subset for  $T$ , the proof follows now from the Bohnenblust–Karlin fixed point theorem (see [20] and the references therein). ■

A more general result of this type is

**THEOREM 4.2.** *Let  $X$  be a Banach space,  $Z \in P_b(X)$  and  $T : X \rightarrow P_{cp,cv}(X)$ . Suppose that the following assertions hold:*

- (i)  $T$  is an u.s.c.  $(\alpha_K, \varphi)$ -contraction;
- (ii) there exists  $a \in ]0, 1[$  such that

$$H(T(x_1), T(x_2)) \leq a \cdot \|x_1 - x_2\| \text{ for each } (x_1, x_2) \in (X \setminus Z) \times (X \setminus Z).$$

Then  $\text{Fix}(T) \neq \emptyset$ .

*Proof.* The proof runs in a similar way to the above one, with the only difference that, instead of the Bohnenblust–Karlin fixed point theorem, we use Theorem 4.7 in [20]. ■

In terms of the fixed point structures we can prove the following abstract result.

**THEOREM 4.3.** *Let  $(X, S(X), M^0)$  be a f.p.s. on a Banach space  $X$ ,  $T : X \multimap X$  and  $Z \in P_b(X)$ . We suppose that*

- (i)  $\tilde{B}(0, R) \in S(X)$  for each  $R > 0$ ;
- (ii)  $T \in M^0(Y)$  for each  $Y \in S(X)$ ;
- (iii) there exists  $a \in ]0, 1[$  such that

$$H(T(x_1), T(x_2)) \leq a \cdot \|x_1 - x_2\| \text{ for each } (x_1, x_2) \in (X \setminus Z) \times (X \setminus Z).$$

Then  $\text{Fix}(T) \neq \emptyset$ .

The above considerations give rise to the following open question:

**PROBLEM 4.4.** *Which generalized set-valued contractions  $T : X \rightarrow P_{b,cl,cv}(X)$  are quasi-bounded with the quasi-norm  $|T| < 1$ ?*

For the single-valued case see [24] (p. 20) and the references therein (M. C. Anisiu (1983), F. Aldea (2002)).

**5. Cyclic representation of an invariant subset with respect to a set-valued operator.** Let us observe first that the results in Kirk, Srinivasan, Veeramani [9] and I. A. Rus [23] give rise to the following concept:

**DEFINITION 5.1.** Let  $X$  be a nonempty set and  $T : X \rightarrow P(X)$  a set-valued operator. By definition,  $X = \bigcup_{i=1}^m X_i$  (where  $X_i \subset X$  for each  $i \in \{1, 2, \dots, m\}$ ) is a *cyclic representation* of  $X$  with respect to  $T$  if  $T(X_1) \subset X_2, \dots, T(X_{m-1}) \subset X_m, T(X_m) \subset X_1$ .



EXAMPLE 5.2. Let  $X$  be a nonempty set and  $T : X \rightarrow P(X)$  a set-valued operator. We suppose that there exist  $A \subset X$  and  $n_0 \in \mathbb{N}^*$  such that  $T^{n_0}(A) \subset A$ . Then  $B := \bigcup_{i=1}^{n_0-1} T^i(A)$  is a cyclic representation of  $B$  with respect to  $T$ . Moreover  $B \in I(T)$ .

REMARK 5.3. If  $X := \bigcup_{i=1}^m X_i$  is a cyclic representation of  $X$  with respect to  $T : X \rightarrow P(X)$ , then  $X_i$  ( $i \in \{1, 2, \dots, m\}$ ) are invariant subsets for  $T^m$ .

The following abstract result is important in our considerations.

THEOREM 5.4. Let  $(X, \rightarrow)$  be an  $L$ -space,  $T : X \rightarrow P(X)$  a set-valued operator and  $X := \bigcup_{i=1}^m X_i$  be a cyclic representation of  $X$  with respect to  $T$ . Suppose that

- (i)  $X_i \in P_{cl}(X)$  for each  $i \in \{1, 2, \dots, m\}$ ;
- (ii) there exists a convergent sequence  $(x_n)_{n \in \mathbb{N}}$ , where  $x_n \in X$ ,  $x_{n+1} \in T(x_n)$  for each  $n \in \mathbb{N}$ .

Then  $\bigcap_{i=1}^m X_i \neq \emptyset$ .

*Proof.* Denote by  $x^*$  the limit of the sequence  $(x_n)_{n \in \mathbb{N}}$ . Because  $x_n \in \bigcup_{i=1}^m X_i$  for each  $n \in \mathbb{N}$ , it follows that infinitely many elements of this sequence lie in each  $X_i$ ,  $i \in \{1, 2, \dots, m\}$ . From (i) one sees that  $x^* \in X_i$ ,  $i \in \{1, 2, \dots, m\}$ . Hence  $\bigcap_{i=1}^m X_i \neq \emptyset$ . ■

As consequence of the above result we have

THEOREM 5.5. Let  $(X, S(X), M^0)$  be a fixed point structure, where  $(X, \rightarrow)$  is an  $L$ -space. Let  $A_i \in P_{cl}(X)$  for each  $i \in \{1, 2, \dots, m\}$ . Define  $Y := \bigcup_{i=1}^m A_i$  and consider  $T : Y \rightarrow P(Y)$ . Suppose that

- (i)  $Y := \bigcup_{i=1}^m A_i$  is a cyclic representation of  $Y$  with respect to  $T$ ;
- (ii) there exists a convergent sequence  $(x_n)_{n \in \mathbb{N}}$ , where  $x_n \in X$ ,  $x_{n+1} \in T(x_n)$  for each  $n \in \mathbb{N}$ ;

(iii) if  $A := \bigcap_{i=1}^m A_i \neq \emptyset$  then  $A \in S(X)$  and  $T|_A \in M(A)$ .

Then  $\text{Fix}(T) \neq \emptyset$ .

*Proof.* From (i), (ii) and Theorem 5.4 it follows that  $A \neq \emptyset$ . From the definition of the fixed point structure and using the assertion (iii) we have  $\text{Fix}(T) \neq \emptyset$ . ■

THEOREM 5.6. Let  $(X, S(X), M^0)$  be a fixed point structure, where  $X$  is a nonempty set. Let  $A_i \in P(X)$  for each  $i \in \{1, 2, \dots, m\}$ . Define  $Y := \bigcup_{i=1}^m A_i$  and consider  $T : Y \rightarrow P(Y)$ . Suppose that

- (i)  $(A_i)_{i \in \{1, 2, \dots, m\}}$  is a cyclic representation of  $Y$  with respect to  $T$ ;
- (ii)  $A_i \in S(X)$  for some  $i \in \{1, 2, \dots, m\}$ ;
- (iii)  $G_1, G_2 \in M^0$  implies  $G_1 \circ G_2 \in M^0$ .

Then  $\text{Fix}(T^m) \neq \emptyset$ .

*Proof.* Let, for example,  $A_i \in S(X)$ . From Definition 5.1 and (iii) it follows that  $T^m \in M^0(A_i)$ . The proof follows now from Remark 5.3. ■

Some applications of the above results can be obtained by taking in Theorems 5.5 and 5.6 some particular fixed point structures (see I. A. Rus [20]).

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