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ON THE STOKES AND NAVIER-STOKES FLOWS IN A PERTURBED HALF-SPACE

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Abstract. We give the L_p - L_q estimate for the Stokes semigroup in a perturbed half-space and some global in time existence theorems for small solutions to the Navier-Stokes equation.

1. Background. The non-stationary Stokes system is given by the equations:

(S)
$$\begin{cases} \vec{u}_t - \Delta \vec{u} + \nabla \pi = \vec{f}, & \text{div} \, \vec{u} = 0, & \text{in} \, (0, T) \times \Omega, \\ \vec{u}_{|_{\partial \Omega}} = 0, & \vec{u}_{|_{t=0}} = \vec{a} \end{cases}$$

with unknown velocity $\vec{u} = {}^{T}(u_1, \ldots, u_n)$ and pressure π (scalar function) in some domain $\Omega \subset \mathbb{R}^n$ $(n \geq 2)$, whose boundary is denoted by $\partial\Omega$ and assumed to be a $C^{1,1}$ hypersurface at least. Here and hereafter, ${}^{T}M$ means the transposed M and n-vectors of functions are denoted by letters with arrow. If we define the spaces $J_p(\Omega)$ and $G_p(\Omega)$ by the relations:

$$J_p(\Omega) = \text{the closure of } \{ \vec{u} \in C_0^{\infty}(\Omega)^n \mid \text{div } \vec{u} = 0 \text{ in } \Omega \} \text{ in } L_p(\Omega)^n, G_p(\Omega) = \{ \nabla \pi \in L_p(\Omega)^n \mid \pi \in L_{p,\text{loc}}(\overline{\Omega}) \},$$

we know the unique decomposition (so called Helmholtz decomposition)

(HD)
$$L_p(\Omega)^n = J_p(\Omega) \oplus G_p(\Omega)$$

with a linear continuous projection $P: L_p(\Omega)^n \to J_p(\Omega)$ for many types of domains (cf. Fujiwara and Morimoto [18], Farwig and Sohr [16], [17], Galdi [19], Miyakawa [32], Simader and Sohr [37] and references therein). Then, we can define the Stokes operator

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A by

(SO)
$$A = P(-\Delta)$$

with definition domain:

(SD)
$$D_p(A) = \{ \vec{u} \in J_p(\Omega) \cap W_p^2(\Omega)^n \mid \vec{u}|_{\partial\Omega} = 0 \}.$$

Having the Stokes operator A in hand, the non-stationary Stokes equation (S) can be formulated as an ordinary differential equation in the Banach space $J_p(\Omega)$:

(O)
$$\vec{u}'(t) + A\vec{u}(t) = P\vec{f}(t), \ \vec{u}(0) = \vec{a}.$$

Hence, the question is whether A generates an analytic semigroup. Through the Laplace transform, this question is related to the resolvent estimate:

(R)
$$|\lambda| \| (\lambda + A)^{-1} \vec{f} \|_{L_p(\Omega)} + \| (\lambda + A)^{-1} \vec{f} \|_{W_p^2(\Omega)} \le C_{\epsilon, p} \| \vec{f} \|_{L_p(\Omega)}$$

for $\lambda \in \Sigma_{\epsilon} = \{z \in \mathbb{C} \setminus \{0\} \mid |\arg z| \le \pi - \epsilon\}$ with some $\epsilon \in (0, \pi/2)$, where 1 . In fact, once obtaining (R), we have the representation formula:

(Rp)
$$T(t)\vec{f} = \frac{1}{2\pi i} \int_{\Gamma} e^{\lambda t} (\lambda + A)^{-1} \vec{f} \, d\lambda, \quad \vec{f} \in J_p(\Omega)$$

where $\Gamma = \{\lambda = e^{i\theta}s \mid s \ge \epsilon\} \cup \{\lambda = e^{-i\theta}s \mid s \ge \epsilon\} \cup \{\lambda = \epsilon e^{is} \mid -\theta \le s \le \theta\}$ with some $\theta \in (\pi/2, \pi)$ and $\epsilon > 0$, which combined with (R) implies not only the generation of the analytic semigroup $\{T(t)\}_{t\ge 0}$ by A but also the semigroup estimates:

(SE)
$$||T(t)\vec{a}||_{L_p(\Omega)} \le C_p e^{\epsilon t} ||\vec{a}||_{L_p(\Omega)},$$

 $||T(t)\vec{a}||_{W_p^2(\Omega)} \le C_p e^{\epsilon t} t^{-1} ||\vec{a}||_{L_p(\Omega)}$

for any t > 0 (cf. Pazy [33]).

Concerning the references for (R), when $\Omega = \mathbb{R}^n$, since the Helmholtz projection commutes with the Laplacian, the resolvent estimate (R) is reduced to that for the Laplacian. The case of the half-space $\Omega = \mathbb{R}^n_+$ was settled by McCracken [30], where

$$\mathbb{R}^{n}_{+} = \{ x = (x_{1}, \dots, x_{n}) \in \mathbb{R} \mid x_{n} > 0 \}$$

and the case of bounded domains by Giga [20] and Solonnikov [38]. The case of exterior domains was treated by Borchers and Sohr [7], Farwig and Sohr [16], Borchers and Varnhorn [9] and Varnhorn [42]. When Ω is a perturbed half-space which is a domain such that $\Omega \cap B^R = \mathbb{R}^n_+ \cap B^R$ for some R > 0 where $B^R = \{x \in \mathbb{R}^n \mid |x| > R\}$, (R) was proved by Farwig and Sohr [16]. The case of cones in \mathbb{R}^3 was settled by Deuring [15]. The case of aperture domains was settled by Farwig and Sohr [17]. The case of infinite layers like $\mathbb{R}^{n-1} \times (-1, 1)$ was settled by Wiegner [5] and Abe and Shibata [1] and [2]. The case of the asymptotically flat layer was settled by Abels [4].

To obtain $L_p - L_q$ estimates:

(1)
$$\|T(t)\vec{a}\|_{L_q(\Omega)} \le C_{p,q} e^{\epsilon t} t^{-\frac{n}{2} \left(\frac{1}{p} - \frac{1}{q}\right)} \|\vec{a}\|_{L_p(\Omega)},$$

(2)
$$\|\nabla T(t)\vec{a}\|_{L_{q}(\Omega)} \leq C_{p,q} e^{\epsilon t} t^{-\frac{n}{2}\left(\frac{1}{p}-\frac{1}{q}\right)-\frac{1}{2}} \|\vec{a}\|_{L_{p}(\Omega)},$$

for t > 0 and $1 \le p \le q \le \infty$ $(p \ne \infty, q \ne 1)$, we combine (SE) with the Sobolev inequality:

(3)
$$\|u\|_{W^{j}_{q}(\Omega)} \leq C \|\nabla^{m}u\|_{L_{p}(\Omega)}^{a} \|u\|_{L_{p}(\Omega)}^{1-a} + \|u\|_{L_{p}(\Omega)}$$

provided that $0 \le j < m, 1 \le p < \infty, m-j-n/p$ is not non-negative integer, $j/m < a \le 1$ and $1/q = j/n + 1/p - am/n \ge 0$. The estimates (1) and (2) play an important role in the study of Navier-Stokes equation. In fact, by using the Stokes semigroup, we can reduce the Navier-Stokes equation:

(NS)
$$\begin{cases} \vec{u}_t + (\vec{u} \cdot \nabla)\vec{u} = \nabla\pi + \Delta \vec{u}, & \text{div } \vec{u} = 0 \text{ in } (0, T) \times \Omega \\ \vec{u}|_{\partial\Omega} = 0, & \vec{u}|_{t=0} = \vec{a} \end{cases}$$

to the integral equation:

(I)
$$\vec{u}(t) = T(t)\vec{a} - \int_0^t T(t-s)P((\vec{u}(s)\cdot\nabla)\vec{u}(s))\,ds,$$

where we have set

$$(\vec{v}\cdot\nabla)\vec{w} = {}^T\Big(\Big(\sum_{j=1}^n v_j\partial_j\Big)w_1,\ldots,\Big(\sum_{j=1}^n v_j\partial_j\Big)w_n\Big), \ \partial_j = \partial/\partial x_j,$$

for the vectors of functions $\vec{v} = {}^{T}(v_1, \ldots, v_n)$ and $\vec{w} = {}^{T}(w_1, \ldots, w_n)$. Employing the argument due to Kato [24] and using (1) and (2) we can prove the locally in time existence theorem of (I). More precisely, we see that for any initial data $\vec{a} \in J_n(\Omega)$ there exists a time $t_0 > 0$ such that the integral equation (I) admits a unique solution $\vec{u}(t) \in C^0([0, t_0), J_n(\Omega))$ with $\nabla \vec{u}(t) \in C^0((0, t_0), L_n(\Omega))$ (cf. Giga and Miyakawa [21]).

However, in proving a globally in time existence of solutions to (I) at least with small initial data as well as in the study of time-asymptotic behaviour, we have to show (1) and (2) without $e^{\epsilon t}$. To show this, we need more precise analysis of $(\lambda + A)^{-1}$ near $\lambda = 0$. That $\lambda = 0$ is in the resolvent set was derived in the bounded domain case by Giga [20] and Solonnikov [38], and in the infinite layer case by Abe and Shibata [2], which implies that (1) and (2) hold, replacing $e^{\epsilon t}$ by e^{-ct} with some constant c > 0.

When $\Omega = \mathbb{R}^n$, applying the Young inequality to the concrete solution formula, we have (1) and (2) without $e^{\epsilon t}$, namely

(4)
$$\|T(t)\vec{a}\|_{L_q(\Omega)} \le C_{p,q}t^{-\frac{n}{2}\left(\frac{1}{p}-\frac{1}{q}\right)}\|\vec{a}\|_{L_p(\Omega)}, \quad \forall t > 0,$$

(5)
$$\|\nabla T(t)\vec{a}\|_{L_q(\Omega)} \le C_{p,q} t^{-\frac{n}{2}\left(\frac{1}{p} - \frac{1}{q}\right) - \frac{1}{2}} \|\vec{a}\|_{L_p(\Omega)}, \quad \forall t > 0,$$

for $1 \leq p \leq q \leq \infty$ $(p \neq \infty, q \neq 1)$. When $\Omega = \mathbb{R}^n_+$, applying the Fourier multiplier theorem to the concrete solution formula obtained by Ukai [41] and using the Sobolev inequality:

(6)
$$\|\nabla^{j}u\|_{L_{q}(\mathbb{R}^{n}_{+})} \leq C \|\nabla^{m}u\|_{L_{p}(\mathbb{R}^{n}_{+})}^{a} \|u\|_{L_{p}(\mathbb{R}^{n}_{+})}^{1-a}$$

provided that $0 \le j < m, 1 \le p < \infty, m-j-n/p$ is not non-negative integer, $j/m < a \le 1$ and $1/q = j/n + 1/p - am/n \ge 0$, we have (4) and (5) for $1 \le p \le q \le \infty$ $(p \ne \infty, q \ne 1)$ (cf. Borchers and Miyakawa [8] and Desch, Hieber and Prüss [14]).

When Ω is an exterior domain, (4) holds for $1 \le p \le q \le \infty$ $(p \ne \infty, q \ne 1)$ but (5) holds only for $1 \le p \le q \le n$ $(q \ne 1)$. This result was first proved by Iwashita [23] for $1 in (4) and <math>1 in (5) when <math>n \ge 3$. The refinement of his result was done by the following authors: Chen [10] $(n = 3, q = \infty)$, Shibata [35] $(n = 3, q = \infty)$, Borchers and Varnhorn [9] (n = 2, (4) for p = q), Dan and Shibata [11], [12] (n = 2), Dan, Kobayashi and Shibata [13] (n = 2, 3), and Maremonti and Solonnikov [31] $(n \ge 2)$. Especially, that Iwashita's restriction: $q \le n$ in (5) is unavoidable was shown by Maremonti and Solonnikov [31].

When Ω is an aperture domain, Abels [3] proved (4) for $1 and (5) for <math>1 when <math>n \ge 3$; and Hishida [22] proved (4) for $1 \le p \le q \le \infty$ and (5) for $1 \le p \le q \le n$ ($q \ne 1$) and $1 \le p < n < q < \infty$ when $n \ge 3$.

Moreover, (I) was solved globally in time for small initial data in $J_n(\Omega)$ by using (4) and (5) in the following papers: Kato [24] in the whole space case; Ukai [41] and Borchers and Miyakawa [8] in the half-space case; Iwashita [23] and Dan and Shibata [11] in the exterior domain cases; Abe and Shibata [2] in the infinite layer case; Hishida [22] in the aperture domain case.

In this paper, we report on the results about (4) and (5) and the related topics in the perturbed half-space cases. And also, we report on some results on the Navier-Stokes flow in the perturbed half-space case. The detailed proofs of the results stated below are found in the papers due to Kubo and Shibata [28] and [29].

2. Notation. Before stating our main theorem precisely, we outline our notation used throughout the paper. If X is a subset in the complex number field \mathbb{C} or functional space, then X^n denotes the *n*-th product:

$$X^{n} = \{ (x_{1}, \dots, x_{n}) \mid x_{j} \in X, \ j = 1, \dots, n \}.$$

If X be a subset of \mathbb{C} , then $X \setminus (-\infty, 0]$ is defined by

$$X \setminus (-\infty, 0] = X \setminus \{x + i0 \in \mathbb{C} \mid -\infty < x \le 0\}.$$

Given an *n*-vector of functions $\vec{v} = T(v_1, \ldots, v_n)$ and point $x = (x_1, \ldots, x_n) \in \mathbb{R}^n$ we set

$$\vec{v}' = {}^T(v_1, \dots, v_{n-1}), \quad x' = (x_1, \dots, x_{n-1}).$$

The dot \cdot stands for the usual inner products both of \mathbb{R}^n and of \mathbb{R}^{n-1} . Given R > 0, we set

$$B_R = \{x \in \mathbb{R}^n \mid |x| < R\}, \ B^R = \{x \in \mathbb{R}^n \mid |x| > R\}, \ B^+_R = B_R \cap \mathbb{R}^n_+.$$

For the differentiation, we use the symbols:

$$\partial_x^{\alpha} u = \partial_1^{\alpha_1} \cdots \partial_n^{\alpha_n} u \text{ for } \alpha = (\alpha_1, \dots, \alpha_n) \in \mathbb{N}_0^n, \\ \partial_{x'}^{\alpha'} u = \partial_1^{\alpha_1} \cdots \partial_{n-1}^{\alpha_{n-1}} u \text{ for } \alpha' = (\alpha_1, \dots, \alpha_{n-1}) \in \mathbb{N}_0^{n-1}, \\ \partial_x^{\alpha} \vec{u} = {}^T (\partial_x^{\alpha} u_1, \dots, \partial_x^{\alpha} u_n), \quad \partial_{x'}^{\alpha'} \vec{u} = {}^T (\partial_{x'}^{\alpha'} u_1, \dots, \partial_{x'}^{\alpha'} u_n)$$

where $\mathbb{N}_0 = \mathbb{N} \cup \{0\}$ and \mathbb{N} is the set of all natural numbers, and moreover we set

$$\nabla^{j} u = (\partial_{x}^{\alpha} u \mid |\alpha| = j), \ \nabla u = \nabla^{1} u, \ \nabla^{j} \vec{u} = {}^{T} (\nabla^{j} u_{1}, \dots, \nabla^{j} u_{n}).$$

Sobolev spaces of vector-valued functions are used as well as of scalar functions. Thus, given a domain D in \mathbb{R}^n , $\|\cdot\|_{L_p(D)}$ denotes the usual L_p norm on D and we set

$$\|u\|_{W_{p}^{m}(D)} = \sum_{|\alpha| \le m} \|\partial_{x}^{\alpha}u\|_{L_{p}(D)}, \ \|\vec{u}\|_{L_{p}(D)} = \sum_{j=1}^{n} \|u_{j}\|_{L_{p}(D)}, \ \|\vec{u}\|_{W_{p}^{m}(D)} = \sum_{j=1}^{m} \|u_{j}\|_{W_{p}^{m}(D)}.$$

 $L_p(D)$ denotes the usual L_p space on D and $C_0^{\infty}(D)$ the set of all functions in $C^{\infty}(\mathbb{R}^n)$ whose support is compact and contained in D. Moreover, we set

$$L_{p,R}(D) = \{ u \in L_p(D) \mid u(x) = 0 \text{ for } x \notin B_R \},\$$

$$W_{p,\text{loc}}^m(\overline{D}) = \{ u \in L_{p,\text{loc}}(\overline{D}) \mid \partial_x^\alpha u \in L_{p,\text{loc}}(\overline{D}), |\alpha| \le m \},\$$

$$\hat{W}_p^1(D) = \{ u \in L_{p,\text{loc}}(\overline{D}) \mid \partial_j u \in L_p(D), \ j = 1, \dots, n \},\$$

$$W_p^m(D) = \{ u \in L_p(D) \mid \partial_x^\alpha u \in L_p(D), |\alpha| \le m \}.$$

By $C_{A,B,\cdots}$ we denote the constants depending on the quantities A, B, \ldots . For two Banach spaces X and $Y, \mathscr{L}(X,Y)$ denotes the set of all bounded linear operators from X into $Y. \mathscr{A}(U_{\epsilon}, X)$ denotes the set of all X-valued holomorphic functions defined on $U_{\epsilon} = \{z \in \mathbb{C} \mid |z| < \epsilon\}$. BC(I; X) and $C^{k}(I; X)$ denote the set of all X-valued bounded continuous functions and C^{k} functions defined on I, respectively.

3. Main results about Stokes flow in the perturbed half-space. In this section, we will state our main results concerning the Stokes system (S) in the half-space and the perturbed half-space, which is defined as follows.

DEFINITION 1. (1) The half-space \mathbb{R}^n_+ is defined by

$$\mathbb{R}^{n}_{+} = \{ x = (x_{1}, \dots, x_{n}) \in \mathbb{R}^{n} \mid x_{n} > 0 \}.$$

(2) Let Ω be a domain in \mathbb{R}^n . We call Ω a perturbed half-space if there exists a number R > 0 such that

(7)
$$\Omega \cap B^R = \mathbb{R}^n_+ \cap B^R$$

As we already stated in section 1, when Ω is a perturbed half-space, Farwig and Sohr [16] proved the Helmholtz decomposition (HD) and the resolvent estimate (R) on Ω . Therefore, we know that the Stokes operator (SO) with domain (SD) generates the analytic semigroup $\{T(t)\}_{t\geq 0}$ on $J_p(\Omega)$. Then, we have the following theorem.

THEOREM 1. Let Ω be a perturbed half-space in \mathbb{R}^n $(n \geq 2)$ whose boundary $\partial \Omega$ is a $C^{1,1}$ hypersurface. Then, the Stokes semigroup $\{T(t)\}_{t\geq 0}$ satisfies the following two estimates:

(8)
$$\|T(t)\vec{a}\|_{L_{q}(\Omega)} \leq C_{p,q} t^{-\frac{n}{2}\left(\frac{1}{p} - \frac{1}{q}\right)} \|\vec{a}\|_{L_{p}(\Omega)},$$

(9)
$$\|\nabla T(t)\vec{a}\|_{L_{q}(\Omega)} \leq C_{p,q}t^{-\frac{n}{2}\left(\frac{1}{p}-\frac{1}{q}\right)-\frac{1}{2}}\|\vec{a}\|_{L_{p}(\Omega)},$$

for any $\vec{a} \in J_p(\Omega)$, t > 0 and $1 \le p \le q \le \infty$ $(p \ne \infty, q \ne 1)$.

The main step in our proof of Theorem 1 is to show the following local energy decay estimate.

THEOREM 2. Let Ω be a perturbed half-space in \mathbb{R}^n $(n \geq 2)$ whose boundary $\partial \Omega$ is a $C^{1,1}$ hypersurface. Let 1 and R be a number such that (7) holds. Then, the Stokes

semigroup $\{T(t)\}_{t>0}$ satisfies the following estimate:

(10)
$$\|\partial_t^j T(t) P \vec{a}\|_{W^2_p(\Omega \cap B_R)} \le C_{p,R} t^{-\frac{n+1}{2}-j} \|\vec{a}\|_{L_p(\Omega)}$$

for any $t \geq 1$, $j \in \mathbb{N}_0$ and $\vec{a} \in L_{p,R}(\Omega)$.

If we consider the Stokes system in the half-space:

(11)
$$\vec{v}_t - \Delta \vec{v} + \nabla \pi = 0, \text{ div } \vec{v} = 0 \text{ in } (0, \infty) \times \mathbb{R}^n_+,$$

 $\vec{v}|_{x_n=0} = 0, \quad \vec{v}|_{t=0} = \vec{b},$

then we know by Ukai [41] and Borchers and Miyakawa [8] that the solution \vec{v} of (11) satisfies the L_p-L_q estimate:

(12)
$$\|\vec{v}(t)\|_{L_{q}(\mathbb{R}^{n}_{+})} \leq C_{p,q} t^{-\frac{n}{2}\left(\frac{1}{p} - \frac{1}{q}\right)} \|\vec{b}\|_{L_{p}(\mathbb{R}^{n}_{+})}$$

(13)
$$\|\nabla \vec{v}(t)\|_{L_q(\mathbb{R}^n_+)} \le C_{p,q} t^{-\frac{n}{2}\left(\frac{1}{p} - \frac{1}{q}\right) - \frac{1}{2}} \|\vec{b}\|_{L_p(\mathbb{R}^n_+)}$$

for any t > 0 and $1 \le p \le q \le \infty$ $(p \ne \infty, q \ne 1)$. Since

$$\|\vec{v}(t)\|_{L_p(B_R^+)} \le C_R \|\nabla \vec{v}(t)\|_{L_p(B_R^+)}$$

as follows from the boundary condition: $\vec{v}|_{x_n=0} = 0$, using (13) and Theorem 2, we have

(14)
$$||T(t)P\vec{a}||_{W_{p}^{2}(\Omega\cap B_{R})} \leq C_{p,R}t^{-\frac{n}{2p}-\frac{1}{2}}||\vec{a}||_{L_{p}(\Omega)}$$

for any $\vec{a} \in L_p(\Omega)$ and $t \ge 1$. Combining (12), (13) and (14) by the cut-off technique and following the argument due to Hishida [22, the proof of Theorem 2.1], we can show Theorem 1.

In order to prove Theorem 2, we need some precise information about solutions to the resolvent problem in \mathbb{R}^n_+ :

(15)
$$(\lambda - \Delta)\vec{w} + \nabla\theta = \vec{f}, \text{ div } \vec{w} = 0 \text{ in } \mathbb{R}^n_+, \\ \vec{w}|_{x_n=0} = 0,$$

which is stated in the following two theorems.

THEOREM 3. Let $R(\lambda)$ and $\Pi(\lambda)$ denote the solution operators of (15) which are defined by

$$\vec{w} = R(\lambda)\vec{f} = {}^T(R_1(\lambda)\vec{f}, \dots, R_n(\lambda)\vec{f}) \text{ and } \theta = \Pi(\lambda)\vec{f}$$

for $\lambda \in \mathbb{C} \setminus (-\infty, 0]$. Let R > 0, 1 and set

$$\mathscr{B}^{j}_{p,R} = \mathscr{L}(L_{p,R}(\mathbb{R}^{n}_{+})^{n}, W^{j}_{p}(B^{+}_{R}))$$

for j = 1, 2. Then there exist operators $G_j^k(\lambda) \in \mathscr{A}(U_{1/16}, \mathscr{B}_{p,R}^2)$, k = 1, 2, 3, j = 1, ..., n, and $G_{\pi}^k(\lambda) \in \mathscr{B}_{p,R}^1$, k = 1, 2, 3 such that

(16)
$$\begin{aligned} R_j(\lambda)\vec{f} &= \lambda^{\frac{n-1}{2}}G_j^1(\lambda)\vec{f} + (\lambda^{\frac{n}{2}}\log\lambda)G_j^2(\lambda)\vec{f} + G_j^3(\lambda),\\ \Pi(\lambda)\vec{f} &= \lambda^{\frac{n-1}{2}}G_\pi^1(\lambda)\vec{f} + (\lambda^{\frac{n}{2}}\log\lambda)G_\pi^2(\lambda)\vec{f} + G_\pi^3(\lambda), \end{aligned}$$

in B_R^+ when $n \ge 2$ and n is even; and

(17)
$$\begin{aligned} R_j(\lambda)\vec{f} &= \lambda^{\frac{n}{2}}G_j^1(\lambda)\vec{f} + (\lambda^{\frac{n-1}{2}}\log\lambda)G_j^2(\lambda)\vec{f} + G_j^3(\lambda),\\ \Pi(\lambda)\vec{f} &= \lambda^{\frac{n}{2}}G_\pi^1(\lambda)\vec{f} + (\lambda^{\frac{n-1}{2}}\log\lambda)G_\pi^2(\lambda)\vec{f} + G_\pi^3(\lambda), \end{aligned}$$

 $in \ B_R^+ \ when \ n \geq 3 \ and \ n \ is \ odd, \ provided \ that \ \lambda \in U_{1/16} \setminus (-\infty, 0] \ and \ \vec{f} \in L_{p,R}(\Omega).$

THEOREM 4. Let $1 , <math>0 < \epsilon < \pi/2$, and let $R(\lambda)$ and $\Pi(\lambda)$ be the operators given in Theorem 3 for $\lambda \in \mathbb{C} \setminus (-\infty, 0]$. Let Σ_{ϵ} be the set in \mathbb{C} defined by

(18)
$$\Sigma_{\epsilon} = \{\lambda \in \mathbb{C} \setminus \{0\} \mid |\arg \lambda| \le \pi - \epsilon\}.$$

Then, there exist operators $R(0) \in \mathscr{L}(L_{p,R}(\mathbb{R}^n_+)^n, W^2_{p,\text{loc}}(\mathbb{R}^n_+)^n)$ and $\Pi(0) \in \mathscr{L}(L_{p,R}(\mathbb{R}^n_+)^n, W^1_{p,\text{loc}}(\mathbb{R}^n_+))$ which satisfy the following three conditions:

(i) Given
$$\vec{f} \in L_{p,R}(\mathbb{R}^n_+)$$
, $\vec{v} = R(0)\vec{f}$ and $\theta = \Pi(0)\vec{f}$ satisfy the equation:

(19)
$$-\Delta \vec{v} + \nabla \theta = \vec{f}, \quad \operatorname{div} \vec{v} = 0 \quad \operatorname{in} \mathbb{R}^n_+, \quad \vec{v}|_{x_n=0} = 0.$$

(ii)

$$\|R(\lambda)\vec{f} - R(0)\vec{f}\,\|_{W^{1}_{p}(B^{+}_{R})} + \|\Pi(\lambda)\vec{f} - \Pi(0)\vec{f}\,\|_{_{L_{p}(B^{+}_{R})}} \leq C_{p,R,\epsilon}|\lambda|^{\frac{1}{4}}\|\vec{f}\,\|_{_{L_{p}(\mathbb{R}^{n})}}$$

for any $\vec{f} \in L_{p,R}(\mathbb{R}^n_+)$ and $\lambda \in \Sigma_{\epsilon}$ with $|\lambda| \leq 1/16$, where $C_{p,R,\epsilon}$ is a constant independent of \vec{f} and λ .

(iii)

$$\begin{split} |[R(0)\vec{f}](x)| &\leq C_{p,R}|x|^{-(n-1)} \|\vec{f}\|_{L_{p}(\mathbb{R}^{n}_{+})},\\ |\nabla[R(0)\vec{f}](x)| &\leq C_{p,R}|x|^{-(n-1)} \|\vec{f}\|_{L_{p}(\mathbb{R}^{n}_{+})},\\ |[\Pi(0)\vec{f}](x)| &\leq C_{p,R}|x|^{-(n-1)} \|\vec{f}\|_{L_{p}(\mathbb{R}^{n}_{+})}, \end{split}$$

for any $\vec{f} \in L_{p,R}(\mathbb{R}^n_+)$ and $x \in \mathbb{R}^n_+$ with $|x| \ge 2\sqrt{2}R$, where $C_{p,R}$ is a constant independent of \vec{f} and x.

Constructing a parametrix of the resolvent problem in a perturbed half-space, we can derive from Theorem 3 and Theorem 4 that the resolvent operator $(\lambda + A)^{-1}$ has the expansion formula of the same type near $\lambda = 0$ in the space $\mathscr{L}(L_{p,R}(\Omega)^n, W_p^2(\Omega \cap B_R)^n)$ as in the half-space case, which is applied to (Rp) implies Theorem 2. The detailed proof of Theorems 1 and 2 is given in Kubo and Shibata [29] and that of Theorems 3 and 4 in Kubo-Shibata [28]. The fundamental idea of the proofs of Theorems 1 and 2 by using Theorems 3 and 4 goes back to a paper due to Shibata [34].

4. The Navier-Stokes flow in a perturbed half-space. Following the arguments due to Kato [24], Kozono [25], Hishida [22] and Wiegner [43] and using Theorem 1 we can show the following theorem.

THEOREM 5. Let $n \geq 2$. There exists a constant $\delta = \delta(\Omega, n) > 0$ with the following property: if $\vec{a} \in J^n(\Omega)$ satisfies $\|\vec{a}\|_{L_n(\Omega)} \leq \delta$, then the integral equation

$$\vec{u}(t) = T(t)\vec{a} - \int_0^t T(t-s)P((\vec{u}(s)\cdot\nabla)\vec{u}(s))ds$$

admits a unique strong solution $\vec{u}(t) \in BC([0,\infty); J_n(\Omega))$ with $\nabla \vec{u}(t) \in C^0((0,\infty); L_n(\Omega))$. Moreover as $t \to \infty$,

$$\begin{split} \|\vec{u}(t)\|_{L_r(\Omega)} &= o(t^{-\frac{1}{2} + \frac{n}{2r}}) \qquad for \quad n \le r \le \infty, \\ |\nabla \vec{u}(t)\|_{L_r(\Omega)} &= o(t^{-1 + \frac{n}{2r}}) \qquad for \quad n \le r < \infty. \end{split}$$

THEOREM 6. Let $n \geq 2$. There exists a constant $\eta = \eta(\Omega, n) \in (0, \delta]$ with the following property: if $\vec{a} \in L_1(\Omega) \cap J_n(\Omega)$ satisfies $\|\vec{a}\|_{L_n(\Omega)} \leq \eta$, then the solution $\vec{u}(t)$ obtained in Theorem 5 satisfies the estimates:

$$\begin{aligned} \|\vec{u}(t)\|_{L_{r}(\Omega)} &= O(t^{-(n-\frac{n}{r})/2}) \quad \text{for } 1 < r \le \infty, \\ \|\nabla \vec{u}(t)\|_{L_{r}(\Omega)} &= O(t^{-(n-\frac{n}{r})/2-\frac{1}{2}}) \quad \text{for } 1 < r < \infty, \end{aligned}$$

as $t \to \infty$.

5. On the periodic solution of the Navier-Stokes equation in the perturbed half-space. We can show that if the incompressible fluid in the perturbed half-space is governed by the periodic external force, the Navier-Stokes equations have a periodic strong solution with the same period as the external force. Let Ω be a domain in $\mathbb{R}^n (n \geq 3)$. Let us consider the following Navier-Stokes equations in Ω :

(NSP)
$$\begin{cases} \frac{\partial \vec{u}}{\partial t} - \Delta \vec{u} + \vec{u} \cdot \nabla \vec{u} + \nabla \pi = \vec{f}, & x \in \Omega, \ t \in \mathbb{R}, \\ & \text{div } \vec{u} = 0, \quad x \in \Omega, \ t \in \mathbb{R}, \\ & \vec{u}|_{\partial\Omega} = 0. \end{cases}$$

Applying the projection operator P_r to both sides of the first equation of (NSP), we have

(E)
$$\frac{d\vec{u}}{dt} + A_r \vec{u} + P_r (\vec{u} \cdot \nabla \vec{u}) = P_r \vec{f}$$

on $J_r(\Omega)$ for $t \in \mathbb{R}$. The above (E) can be further transformed to the following integral equation:

(I-E)
$$\vec{u}(t) = \int_{-\infty}^{t} T(t-s)P_r\vec{f}(s)ds - \int_{-\infty}^{t} T(t-s)P_r((\vec{u}\cdot\nabla)\vec{u}(s))ds.$$

Concerning the external force f, we impose the following assumption:

Assumption 1. Let the exponents r and q be such as 2 < r < n, $\frac{n}{2} < q < n$. When $n \ge 4$, we assume that

(20)
$$\vec{f} \in BC(\mathbb{R}; L_p(\Omega) \cap L_\ell(\Omega))$$

for $1 < p, \ell < \infty$ with $1/r + 2/n < 1/p, 1/q < 1/\ell < 1/q + 1/n$.

When n = 3, we assume that

(21)
$$P_p \vec{f}(s) = A_p^s \vec{g}(s) \ (s \in \mathbb{R}) \text{ with some } \vec{g} \in BC(\mathbb{R}; D(A_p^s))$$

for $1 and <math>\delta > 0$ satisfying $3/2p + \delta \ge \max(1 + 3/2r, 1/2 + 3/2q)$ and that

$$\vec{f} \in BC(\mathbb{R}; L_{\ell}(\Omega))$$

for $1/q < 1/\ell < 1/q + 1/3$.

Using the method due to Kozono and Nakao [26], we can show the following two theorems in the perturbed half-space case.

THEOREM 7. Let Ω and \vec{f} satisfy Assumption 1. Suppose that $\vec{f}(t) = \vec{f}(t+\omega)$ for all $t \in \mathbb{R}$ with some $\omega > 0$. Then there is a constant $\eta = \eta(n, r, q, p, \ell, \delta) > 0$ such that if

$$\begin{split} \sup_{s\in\mathbb{R}} \|P_p \vec{f}(s)\|_{L_p(\Omega)} + \sup_{s\in\mathbb{R}} \|P_\ell \vec{f}(s)\|_{L_\ell(\Omega)} &\leq \eta \text{ when } n \geq 4, \\ \sup_{s\in\mathbb{R}} \|\vec{g}(s)\|_{L_p(\Omega)} + \sup_{s\in\mathbb{R}} \|P_\ell \vec{f}(s)\|_{L_\ell(\Omega)} &\leq \eta \text{ when } n = 3, \end{split}$$

we have a periodic solution \vec{u} of (I-E) with the same period ω as \vec{f} in the class $BC(\mathbb{R}; J_r(\Omega))$ with $\nabla \vec{u} \in BC(\mathbb{R}; L_q(\Omega))$.

Such a solution \vec{u} is unique within this class provided $\sup_{s \in \mathbb{R}} \|\vec{u}(s)\|_{L_r(\Omega)} + \sup_{s \in \mathbb{R}} \|\nabla \vec{u}(s)\|_{L_q(\Omega)}$ is sufficiently small.

THEOREM 8. In addition to the hypotheses of Theorem 7, let us assume furthermore that \vec{f} is a Hölder continuous function on \mathbb{R} with values in $L_n(\Omega)$. Then the periodic solution \vec{u} given by Theorem 7 has the following additional properties:

- (i) $\vec{u} \in BC(\mathbb{R}; J_n(\Omega)) \cap C^1(\mathbb{R}; J_n(\Omega));$
- (ii) $\vec{u}(t) \in D(A_n)$ for all $t \in \mathbb{R}$ and $A_n \vec{u} \in C^0(\mathbb{R}; J_n(\Omega));$
- (iii) \vec{u} satisfies (E) in $J_n(\Omega)$ for all $t \in \mathbb{R}$.

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