CONVEX AND FRACTAL GEOMETRY BANACH CENTER PUBLICATIONS, VOLUME 84 INSTITUTE OF MATHEMATICS POLISH ACADEMY OF SCIENCES WARSZAWA 2009

OPTIMAL ISOMETRIES FOR A PAIR OF COMPACT CONVEX SUBSETS OF \mathbb{R}^n

IRMINA HERBURT

Department of Mathematics and Information Science, Warsaw University of Technology Pl. Politechniki 1, 00-661 Warszawa, Poland E-mail: herbir@mini.pw.edu.pl

MARIA MOSZYŃSKA

Institute of Mathematics, University of Warsaw Banacha 2, 02-097 Warszawa, Poland E-mail: mariamos@mimuw.edu.pl

Abstract. In 1989 R. Arnold proved that for every pair (A, B) of compact convex subsets of \mathbb{R}^n there is an Euclidean isometry optimal with respect to L_2 metric and if f_0 is such an isometry, then the Steiner points of $f_0(A)$ and B coincide. In the present paper we solve related problems for metrics topologically equivalent to the Hausdorff metric, in particular for L_p metrics for all $p \geq 2$ and the symmetric difference metric.

Problems of approximation theory for hyperspaces of convex bodies (with different metrics) and their subspaces have been studied, e.g., in [2], [1], [8], [5], [6], [4].

In particular, the paper [2] concerns isometries optimal for a given pair in \mathcal{K}^n (the family of nonempty, compact, convex subsets of \mathbb{R}^n), with respect to the L_2 metric. Let us recall that for any real $p \geq 1$, the L_p metric, ϱ_p , is defined by

$$\varrho_p(A,B) := \left(\int_{S^{n-1}} |h_A(u) - h_B(u)|^p d\sigma(u) \right)^{\frac{1}{p}},$$

where $h_A, h_B: S^{n-1} \to \mathbb{R}$ are the support functions of A, B.

An isometry $f_0 : \mathbb{R}^n \to \mathbb{R}^n$ is optimal for (A, B) with respect to a metric ϱ in \mathcal{K}^n provided that for every isometry $f : \mathbb{R}^n \to \mathbb{R}^n$

$$\varrho(f_0(A), B) \le \varrho(f(A), B)$$

²⁰⁰⁰ Mathematics Subject Classification: 52A20, 52A99, 41A65, 41A99.

Key words and phrases: convex bodies, Hausdorff metric, L_p metric, symmetric difference metric, optimal isometry, selector.

The paper is in final form and no version of it will be published elsewhere.

In 1989, R. Arnold ([2]) proved the following two statements:

- 1. If an isometry $f_0 : \mathbb{R}^n \to \mathbb{R}^n$ is optimal for (A, B) with respect to ϱ_2 , then the Steiner points of $f_0(A)$ and B coincide.
- 2. For every pair (A, B) of nonempty compact convex subsets of \mathbb{R}^n there exists an isometry $f_0 : \mathbb{R}^n \to \mathbb{R}^n$ optimal for (A, B) with respect to ϱ_2 .

We are interested in the following problems raised at the problem session of the conference "On the border of geometry and topology" held in Będlewo, Poland, in 2002:

PROBLEM 1. Let ϱ be an arbitrary metric in \mathcal{K}^n topologically equivalent to ϱ_2 . Does there exist a selector $s : \mathcal{K}^n \to \mathbb{R}^n$ equivariant under the isometries and such that for every $A, B \in \mathcal{K}^n$, if an isometry f_0 is optimal for (A, B) with respect to ϱ , then $s(f_0(A)) = s(B)$?

PROBLEM 2. Let ρ be an arbitrary metric in \mathcal{K}^n topologically equivalent to ρ_2 . Does every pair in \mathcal{K}^n have an isometry optimal with respect to ρ ?

Let us note that Arnold in [2] applies his statement 1 to prove statement 2.

In Section 2 we solve Problem 1: we prove that a required selector does not exist for the Hausdorff metric not only for $\mathcal{K}^n \times \mathcal{K}^n$ but also for a very narrow subclass of it (Theorem 2.4).

In Section 3 we solve Problem 2: we prove that generally the answer to the question is negative (Remark 3.1 and Example 3.2) and we present positive results under additional assumptions (Theorems 3.6 and 3.8; Corollaries 3.7 and 3.9).

1. Preliminaries. In principle, we follow the terminology and notation of [11], except for the definition of a convex body: by a convex body we understand a compact convex subset of \mathbb{R}^n with nonempty interior, while in [11] the notion of convex body is identified with that of nonempty compact convex set.

As usual, \mathcal{C}^n , \mathcal{K}^n , and \mathcal{K}^n_0 are, respectively, the family of all nonempty compact subsets of \mathbb{R}^n , the family of convex elements of \mathcal{C}^n , and the family of convex bodies; further, \mathcal{O}^n is the family of strictly convex sets, that is, elements of \mathcal{K}^n with no segments on the boundary, and \mathcal{O}^n_0 the family of strictly convex bodies.

Let us recall that the Hausdorff metric ρ_H in \mathcal{C}^n is defined by

$$\varrho_H(A,B) := \max\{ \vec{\varrho_H}(A,B), \vec{\varrho_H}(B,A) \},\$$

where

$$\vec{\varrho_H}(A,B) := \sup_{a \in A} \inf_{b \in B} \|a - b\| = \inf \left\{ \alpha > 0 \mid A \subset B + \alpha B^n \right\}.$$

$$(1.1)$$

As was proved by R. Vitale in [12] p. 286, on \mathcal{K}^n the Hausdorff metric ϱ_H is topologically equivalent to each L_p metric ϱ_p , and all the corresponding metric spaces are finitely compact, that is, they satisfy the following (equivalent) conditions (see, e.g., [10]):

- every bounded sequence has a convergent subsequence,
- every closed, bounded subset is compact,
- the balls are compact.

Let $A \in \mathcal{K}_0^n$. For any $x \in A$, let $R_A(x)$ be the radius of the smallest ball with centre x containing A and $r_A(x)$ the radius of a biggest ball with centre x contained in A.

The functions $R_A, r_A : A \to \mathbb{R}_+$ can be extended, respectively, to $\overline{R}_A, \overline{r}_A : \mathbb{R}^n \to \mathbb{R}$, such that for every $x \in \mathbb{R}^n$

$$\overline{R}_A(x) = \inf \{ \alpha > 0 \mid x + \alpha B^n \supset A \}$$

and for $x \in \mathbb{R}^n \setminus A$

$$\overline{r}_A(x) = -\operatorname{dist}(x, A),$$

where dist $(x, A) := \inf\{ ||x - a|| | a \in A \}$ (see [3] or [9]).

Let us recall that a selector of a given family of sets is a function selecting a point from every member of this family (see, e.g., [11]).

DEFINITION 1.1. Let \mathcal{X} be a subfamily of \mathcal{C}^n . A selector $s : \mathcal{X} \to \mathbb{R}^n$ is said to be associated with a metric ρ in \mathcal{X} if for every $A, B \in \mathcal{X}$ and an isometry f_0 optimal for (A, B) with respect to ρ ,

$$s(f_0(A)) = s(B)$$

A selector s is equivariant under a transformation g of \mathbb{R}^n provided that

$$s(g(A)) = g(s(A))$$

(see [11]).

We shall restrict our considerations to selectors equivariant under the Euclidean isometries.

In view of the result of Arnold [2], there is a selector associated with the L_2 metric, ρ_2 , namely the Steiner point map. As is well known, this selector is equivariant under the isometries.

2. Looking for a selector associated with the Hausdorff metric. As was already mentioned, we shall restrict the class of selectors to those equivariant under the isometries.

We are going to prove that Problem 1 has a negative solution even for pairs of strictly convex bodies (Theorem 2.4). We begin with two examples.

Let (e_1, \ldots, e_n) be the canonical basis of \mathbb{R}^n . Let lin be the linear hull; in particular, $\lim x = \{tx \mid t \in \mathbb{R}\}$ for any $x \in \mathbb{R}^n$.

EXAMPLE 2.1. Let $X = B^n \cap E^+$, where

$$E^+ := \{ (x_1, \dots, x_n) \in \mathbb{R}^n \mid x_n \ge 0 \}.$$

We calculate the Hausdorff distance $\rho_H(X, B^n + te_n)$ for arbitrary $t \in \mathbb{R}$. By Lemma 2.1 in [5],

$$\varrho_H(X, B^n + te_n) = \max\{\bar{R}_X(te_n) - 1, 1 - \bar{r}_X(te_n)\}.$$
(2.1)

If $t \leq 0$, then by easy calculation, $\bar{R}_X(te_n) = 1 + |t| = 1 - t$ and $\bar{r}_X(te_n) = t$, whence

$$\bar{R}_X(te_n) - 1 < 1 - \bar{r}_X(te_n).$$
 (2.2)

If $t \in [0,1]$, then $\bar{R}_X(te_n) = \sqrt{1+t^2}$ and

$$\bar{r}_X(te_n) = \begin{cases} t & \text{if } t \le \frac{1}{2}, \\ 1-t & \text{if } t \ge \frac{1}{2}; \end{cases}$$

thus, by a simple calculation, condition (2.2) is satisfied.

If $t \ge 1$, then $\bar{R}_X(te_n) = \sqrt{1+t^2}$ and $\bar{r}_X(te_n) = 1-t$; thus, again (2.2) holds. Hence by (2.1),

$$\varrho_H(X, B^n + te_n) = 1 - \bar{r}_X(te_n) = \begin{cases} 1 - t & \text{if } t \le \frac{1}{2}, \\ t & \text{if } t \ge \frac{1}{2}. \end{cases}$$

Thus $\inf_{t \in \mathbb{R}} \varrho_H(X, B^n + te_n)$ is attained for $t = \frac{1}{2}$, that is, for $te_n = \hat{c}(X)$, the centre of the inscribed ball of X.

EXAMPLE 2.2. Let X be as in Example 2.1. We calculate the Hausdorff distance $\varrho_H(X, \frac{1}{2}B^n + te_n)$ for arbitrary $t \in \mathbb{R}$.

As before, by Lemma 2.1 in [5],

$$\varrho_H\left(X, \frac{1}{2}B^n + te_n\right) = \max\left\{\bar{R}_X(te_n) - \frac{1}{2}, \frac{1}{2} - \bar{r}_X(te_n)\right\}.$$
(2.3)

<u>If $t \leq 0$ </u>, then $\bar{R}_X(te_n) - \frac{1}{2} = \frac{1}{2} - t = \frac{1}{2} - \bar{r}_X(te_n)$.

If $0 < t \leq 1$, then

$$\bar{R}_X(te_n) - \frac{1}{2} = \sqrt{1+t^2} - \frac{1}{2} > \left|\frac{1}{2} - t\right| = \frac{1}{2} - \bar{r}_X(te_n).$$

If $t \geq 1$, then

$$\bar{R}_X(te_n) - \frac{1}{2} = \sqrt{1+t^2} - \frac{1}{2} > t - \frac{1}{2} = \frac{1}{2} - \bar{r}_X(te_n).$$

Hence by (2.3),

$$\varrho_H\left(X, \frac{1}{2}B^n + te_n\right) = \bar{R}_X(te_n) - \frac{1}{2} = \begin{cases} \frac{1}{2} - t & \text{if } t \le 0, \\ \sqrt{1 + t^2} - \frac{1}{2} & \text{if } t \ge 0, \end{cases}$$

and thus $\inf_{t \in \mathbb{R}} \varrho_H(X, \frac{1}{2}B^n + te_n)$ is attained for t = 0, that is, for $te_n = \check{c}(X)$, the Čebyšev centre of X.

The proof of the following simple lemma is left to the reader.

LEMMA 2.3. Let ϕ and ϕ_k , for $k \in \mathbb{N}$, be continuous real functions on \mathbb{R} or an interval (bounded or unbounded). If the sequence $(\phi_k)_{k\in\mathbb{N}}$ is uniformly convergent to ϕ and $\phi > 0$, then there is a k_0 such that $\phi_k > 0$ for all $k \ge k_0$.

THEOREM 2.4. There is no selector for \mathcal{O}_0^n equivariant under the isometries and associated with the Hausdorff metric.

Proof. We shall first prove the assertion for a slightly bigger family UIB which consists of all convex bodies with a unique inscribed ball with the maximal radius.

CLAIM 1. There is no selector for UIB equivariant under the isometries and associated with ϱ_H .

Suppose to the contrary that there exists such a selector s. That is, s is equivariant under the isometries and for every $A, B \in \text{UIB}$, if an isometry f_0 satisfies the condition

$$\varrho_H(f_0(A), B) \le \varrho_H(f(A), B)$$
 for every isometry f ,

then $s(f_0(A)) = s(B)$.

Let X be as in Examples 2.1 and 2.2. Consider first the pair (B^n, X) . Then, evidently, for every isometry f_0 the image $f_0(B^n)$ is a translate of B^n .

If the translation by x is optimal for this pair, then $s(X) = s(B^n + x) = x$, because s is associated with ρ_H and equivariant under reflection at x. Hence $x \in \lim e_n$, because s is equivariant under the reflection at $\lim e_n$ and X is symmetric with respect to this line. Thus $s(X) = te_n$ for some $t \in \mathbb{R}$.

Therefore, it suffices to consider $\inf_t \varrho_H(B^n + te_n, X)$. By Example 2.1, this infimum is attained for the centre $\hat{c}(X)$ of the ball inscribed in X. Thus $s(X) = \hat{c}(X)$.

Consider now the pair $(\frac{1}{2}B^n, X)$. By the same reasoning as above, the infimum of the Hausdorff distance between $\frac{1}{2}B^n + x$ and X is attained for $x \in \lim e_n$. Thus, in view of Example 2.2, it is attained for $x = \check{c}(X)$, the Čebyšev centre of X, which evidently is different from $\hat{c}(X)$, a contradiction.

CLAIM 2. There is no selector $s : \mathcal{O}_0^n \to \mathbb{R}^n$ equivariant under the isometries and associated with ϱ_H .

The idea is to approximate the convex body X by a strictly convex body so close to X that inequalities for big and small radii are preserved.

Let X_k be the intersection of two balls:

$$X_k := B^n \cap \left(ke_n + \sqrt{1 + k^2 B^n}\right) \tag{2.4}$$

for every natural k. Then the intersection of the boundaries of these balls is $S^{n-1} \cap (ke^n + \sqrt{1+k^2}S^{n-1})$, which is equal to the intersection of S^{n-1} and the hyperplane $\ln(e_1, \ldots, e_{n-1})$.

Evidently, each X_k is strictly convex, being the intersection of strictly convex bodies. Notice that

$$\varrho_H(X_k, X) = \sqrt{1+k^2} - k,$$

whence, by easy calculation, $\lim_{H} X_k = X$. Thus, by Lemma 3.2 in [9], $\bar{R}_{X_k} \to \bar{R}_X$ and $\bar{r}_{X_k} \to \bar{r}_X$, uniformly.

To apply Lemma 2.3, let us now define the functions ϕ_k and ϕ by the formulae

$$\phi_k(t) := 2 - \left(\bar{R}_{X_k}(te_n) + \bar{r}_{X_k}(te_n)\right) \text{ and } \phi(t) := 2 - \left(\bar{R}_X(te_n) + \bar{r}_X(te_n)\right)$$

In view of Example 2.1, the function $\phi : \mathbb{R} \to \mathbb{R}$ is positive and thus by Lemma 2.3, there is a k_1 such that $\phi_k > 0$ for every $k \ge k_1$. Equivalently, for $k \ge k_1$,

$$\underline{R}_{X_k}(te_n) - 1 < 1 - \underline{r}_{X_k}(te_n)$$
 for every t.

Thus, by (2.1), for every t,

$$\varrho_H(X_k, te_n + B^n) = 1 - \bar{r}_{X_k}(te_n),$$

whence the minimizer of this distance is a maximizer of $\bar{r}_{X_k}(te_n)$, i.e., it is the centre of the inscribed ball of X_k . Thus $s(X_k) = \hat{c}(X_k)$ for $k \ge k_1$.

Similarly, we define ψ_k and ψ by the formulae

 $\psi_k(t) := \bar{R}_{X_k}(te_n) + \bar{r}_{X_k}(te_n) - 1 \text{ and } \psi(t) := \bar{R}_X(te_n) + \bar{r}_X(te_n) - 1.$

By Example 2.2, $\psi(t) > 0$ for every t > 0 and $\psi(t) = 0$ for $t \le 0$. Thus we can apply Lemma 2.3 only to the restrictions $\psi|(0,\infty)$ and $\psi_k|(0,\infty)$. We obtain $\psi_k(t) > 0$ for t > 0and sufficiently large k. It remains to show that $\psi_k(t) > 0$ also for $t \le 0$ and k large enough. To this end, let us notice that for $t \le 0$

$$\bar{R}_{X_k}(te_n) = \bar{R}_X(te_n) \text{ and } \bar{r}_{X_k}(te_n) > \bar{r}_X(te_n),$$

whence there is a k_2 such that for $k \ge k_2$

$$\psi_k(t) = \bar{r}_{X_k}(te_n) - \bar{r}_X(te_n) > 0 \text{ for } t \le 0.$$

Let $k_0 = \max\{k_1, k_2\}$. Then for $k \ge k_0$, the set X_k is a strictly convex body such that

- inf $\rho_H(X_k, te_n + B^n)$ is attained for $te_n = \hat{c}(X_k)$ and thus $s(X_k) = \hat{c}(X_k)$,
- inf $\rho_H(X_k, te_n + \frac{1}{2}B^n)$ is attained for $te_n = \check{c}(X_k)$ and thus $s(X_k) = \check{c}(X_k)$,

a contradiction. \blacksquare

REMARK 2.5. In fact we proved that a selector equivariant under isometries and associated with ρ_H does not exist even for some pairs with one member being a ball and the other being a strictly convex body.

3. Optimal isometries. Let Iso be the group of isometries of \mathbb{R}^n . For any $A \subset \mathbb{R}^n$, let

$$\mathcal{F}(A) = \{ f(A) \mid f \in \text{Iso} \}.$$
(3.1)

Let us note the following obvious fact.

REMARK 3.1. Let \mathcal{X} be a nonempty subfamily of \mathcal{C}^n invariant under Iso and let ρ be a metric on \mathcal{X} . Then for every pair (A, B) in \mathcal{X} the following conditions are equivalent:

(i) there exists $f \in$ Iso optimal for (A, B) with respect to ρ ;

(ii) for every sequence $(A_k)_{k\in\mathbb{N}}$ in $\mathcal{F}(A)$ with $(\varrho(A_k, B))_{k\in\mathbb{N}}$ decreasing, there exists $A_0 \in \mathcal{F}(A)$ such that $\varrho(A_0, B) \leq \varrho(A_k, B)$ for every k.

We are now going to show that in view of Remark 3.1 generally the answer to the question in Problem 1 is negative: there exists a metric ρ on \mathcal{K}^n topologically equivalent to ρ_H (and thus to ρ_2) and a pair (A, B) of convex bodies with no optimal isometry with respect to ρ .

EXAMPLE 3.2. We define $\rho: \mathcal{K}^n \times \mathcal{K}^n \to \mathbb{R}_+$ by the formula

$$\varrho(A_1, A_2) := \begin{cases} \varrho_H(A_1, A_2) & \text{if } \varrho_H(A_1, A_2) \le 2, \\ 1 + \frac{3}{1 + \varrho_H(A_1, A_2)} & \text{if } \varrho_H(A_1, A_2) > 2. \end{cases}$$

The function ρ is a metric topologically equivalent to ρ_H .

Let $A = B^n$ and $B = 4B^n$. Then

$$\inf \left\{ \varrho_H(f(A), B) \mid f \in \operatorname{Iso} \right\} = \varrho_H(A, B) = 3.$$

Since, evidently, for every $f \in \text{Iso there is } v \in \mathbb{R}^n$ such that f(A) = A + v, it follows that $\varrho_H(f(A), B) = 3 + ||v|| > 2$, whence

$$\varrho(f(A), B) = 1 + \frac{3}{4 + \|v\|} > 1.$$
(3.2)

Consider now the sequence $(A+ku)_{k\in\mathbb{N}}$ for some $u\in S^{n-1}$. Evidently, $\varrho(A+ku, B) = 1+\frac{3}{k+4}$, that is, the sequence $(\varrho(A+ku, B))_{k\in\mathbb{N}}$ is decreasing. However, by (3.2), there is no $f_0 \in$ Iso with $\varrho(f_0(A), B) \leq 1$. Thus, by Remark 3.1, the pair (A, B) has no optimal isometry with respect to ϱ .

We now pass to positive results. We shall need a particular case of the following lemma.

LEMMA 3.3. Let $A \in C^n$ and $f_k : A \to \mathbb{R}^n$ continuous for $k \in \mathbb{N}$. If $(f_k)_{k \in \mathbb{N}}$ is uniformly convergent to an f, then

$$f(A) = \lim_{H} f_k(A). \tag{3.3}$$

Proof. Condition (3.3) is equivalent to the conjunction of the following two (see [11] Theorem 1.8.7 and Note 3 p. 57):

(i) for every $x \in f(A)$ there exists a convergent sequence $(x_k)_{k \in \mathbb{N}}$ with $x_k \in f_k(A)$ and $\lim x_k = x$;

(ii) if a sequence $(i_k)_{k\in\mathbb{N}}$ is increasing and $(x_{i_k})_{k\in\mathbb{N}}$ with $x_{i_k} \in f_{i_k}(A)$ is convergent, then $\lim x_{i_k} \in f(A)$.

Since for a compact domain the uniform convergence is equivalent to the continuous convergence (see [7], p. 109), condition (i) is satisfied.

To verify (ii), let $x = \lim x_{i_k}$ and $x_{i_k} = f_{i_k}(a_k)$ for $a_k \in A$. We may assume (passing to a suitable subsequence) that $(a_k)_{k \in \mathbb{N}}$ is convergent to an $a \in A$ and thus (by continuous convergence), $x = f(a) \in f(A)$, which proves (ii).

We shall also use the following simple fact.

LEMMA 3.4. Let F be a nonempty closed subset of a metric space (X, ϱ) and let $a_0 \in X$. If some ball with centre a_0 has a nonempty and compact intersection with F, then there exists a point in F nearest to a_0 with respect to ϱ .

Proof. Let B_0 be a ball in (X, ϱ) with centre a_0 such that $B_0 \cap F$ is nonempty and compact. Evidently, a possible nearest point cannot be outside of B_0 , i.e.,

$$\inf_{x \in F} \varrho(x, a_0) = \inf_{x \in B_0 \cap F} \varrho(x, a_0).$$

Since $B_0 \cap F$ is compact and the function $x \mapsto \varrho(x, a_0)$ is continuous, the infimum is attained at some point $x_0 \in B_0 \cap F$.

PROPOSITION 3.5. For every $A \in \mathcal{C}^n$ the set $\mathcal{F}(A)$ is closed in $(\mathcal{C}^n, \varrho_H)$.

Proof. Let $(f_k(A))_{k\in\mathbb{N}}$ be a convergent sequence in $(\mathcal{C}^n, \varrho_H)$ for $f_k \in$ Iso. Let $A' = \lim_{H \to 0} f_k(A)$. We have to prove that $A' \in \mathcal{F}(A)$, i.e., there exists an isometry f_0 with $A' = f_0(A)$.

Since $f_k = \bar{f}_k + f_k(0)$ for some $\bar{f}_k \in O(n)$, it follows that for every k $f_k(A) = \bar{f}_k(A) + f_k(0)$.

The sequences $(f_k(A))_{k\in\mathbb{N}}$ and $(\bar{f}_k)_{k\in\mathbb{N}}$ are bounded, because the first one is convergent and the second has elements in the compact set O(n). Thus $(f_k(0))_{k\in\mathbb{N}}$ is bounded. Consequently, there is an increasing sequence of indices, $(i_k)_{k\in\mathbb{N}}$, such that $(\bar{f}_{i_k})_{k\in\mathbb{N}}$ is convergent to an $\bar{f}_0 \in O(n)$ and $f_{i_k}(0)$ is convergent to a point $x_0 \in \mathbb{R}^n$. By Lemma 3.3,

$$\bar{f}_0(A) = \lim_H \bar{f}_{i_k}(A).$$

Let us define f_0 by $f_0 := \overline{f}_0 + x_0$. Then

$$\varrho_H(A', f_0(A)) = \varrho_H(A' - x_0, \bar{f}_0(A)) = \lim \varrho_H(A' - f_{i_k}(0), \bar{f}_{i_k}(A))$$
$$= \varrho_H(\lim_H f_k(A), \lim_H f_{i_k}(A)) = 0,$$

whence $A' = f_0(A)$. This completes the proof.

THEOREM 3.6. Let ϱ be a metric on \mathbb{C}^n topologically equivalent to ϱ_H . If the space (\mathbb{C}^n, ϱ) is finitely compact, then for every $A, B \in \mathbb{C}^n$ there exists a Euclidean isometry of \mathbb{R}^n optimal for the pair (A, B) with respect to ϱ .

Proof. Let $\mathcal{F}(A) = \{f(A) \mid f \in \text{Iso}\}$ (see (3.1)). In view of Proposition 3.5, the set $\mathcal{F}(A)$ is closed in (\mathcal{C}^n, ϱ) . Since the space (\mathcal{C}^n, ϱ) is finitely compact, it satisfies the assumptions of Lemma 3.4. This completes the proof. \blacksquare

Since, evidently, Theorem 3.6 will remain valid if C^n is replaced by \mathcal{K}^n , in view of the result by R. Vitale (see Preliminaries), this theorem yields the following.

COROLLARY 3.7. If ρ is either the Hausdorff metric on \mathcal{K}^n or any of the L_p metrics, then for every pair (A, B) in \mathcal{K}^n there exists an isometry optimal with respect to ρ .

Another positive result is the following.

THEOREM 3.8. Let \mathcal{X} be a nonempty subfamily of \mathcal{C}^n invariant under Iso and let ϱ be a metric on \mathcal{X} topologically equivalent to ϱ_H . If $A, B \in \mathcal{X}$ and there exists an $f_0 \in$ Iso such that

$$f_0(A) \cap B \neq \emptyset \quad and \quad \varrho(f_0(A), B) \le \varrho(A, B),$$

$$(3.4)$$

then there exists an isometry optimal for (A, B) with respect to ϱ .

Proof. Consider the set $\mathcal{F}_0(A)$ defined by

$$\mathcal{F}_0(A) := \{ C \in \mathcal{F}(A) \mid C \cap B \neq \emptyset \}.$$

It is easy to see that $\mathcal{F}_0(A)$ is bounded and closed in $(\mathcal{C}^n, \varrho_H)$ and thus it is a compact subset of \mathcal{C}^n (with any of the metrics ϱ_H and ϱ). By (3.4), this set is nonempty and the function $\varrho(\cdot, B)$ attains its infimum in this set. This completes the proof.

We shall now consider the metric δ^S on the space \mathcal{K}_0^n of convex bodies in \mathbb{R}^n , the so called *symmetric difference metric* (see [11], p. 58). It is defined by the formula

$$\delta^S(A,B) := V_n(A - B),$$

where $A - B := (A \cup B) \setminus (A \cap B)$ and V_n is the *n*-dimensional Lebesgue measure.

This metric is topologically equivalent to the Hausdorff metric, but evidently $(\mathcal{K}_0^n, \delta^S)$ is not finitely compact. Nevertheless, by Theorem 3.8 we obtain the following.

COROLLARY 3.9. For every pair (A, B) of convex bodies in \mathbb{R}^n , there exists an optimal isometry with respect to δ^S .

REMARK 3.10. In fact, R. Arnold in [2] deals with rigid motions (i.e. orientation preserving isometries). Let us note that in our Proposition 3.5 and consequently in Theorem 3.6 and Corollary 3.7, the group O(n) of linear isometries can be replaced by its arbitrary nonempty closed subset, in particular by the group SO(n) of linear rigid motions.

4. The uniqueness problem. It is easy to see that generally an isometry optimal for a given pair (A, B) with respect to ρ_H is not unique and even an isometric copy of Anearest to B is not unique. Moreover, it may happen that for two nearest copies A_1, A_2 of A there is no self-isometry f_0 of B onto $f_0(A_1) = A_2$ (see Example 4.2.)

LEMMA 4.1. Let $A, A' \in \mathcal{K}^n$, diam A' = diam $A =: \alpha$, and $\varepsilon \ge 0$. Let $\{x, y\}$ be a unique pair of points in A and $\{x', y'\}$ a unique pair of points in A' such that $||x - y|| = \alpha = ||x' - y'||$. If

$$\{x, y\} \neq \{x', y'\},\tag{4.1}$$

then $\varrho_H(A, A' + \varepsilon B^n) > \varepsilon$.

Proof. Suppose, to the contrary, that $\rho_H(A, A' + \varepsilon B^n) =: \varepsilon_0 \leq \varepsilon$. Then, by (1.1), $A' + \varepsilon B^n \subset A + \varepsilon_0 B^n$ and thus by the cancellation law,

$$A' + (\varepsilon - \varepsilon_0) B^n \subset A. \tag{4.2}$$

If $\varepsilon_0 < \varepsilon$, then from (4.2) it follows that diam A' < diam A, a contradiction.

If $\varepsilon_0 = \varepsilon$, then $A = A' + \varepsilon B^n$ and thus $x', y' \in A$. Then, by the assumption of the uniqueness of the pairs of points that attain the common diameter of A and A', it follows that $\{x, y\} = \{x', y'\}$, contrary to (4.1).

EXAMPLE 4.2. We adopt the natural convention that any sum over an empty set of indices is equal to 0.

Consider the following three half-ellipsoids:

$$E_{0} = \left\{ (x_{1}, \dots, x_{n}) \in \mathbb{R}^{n} \mid \frac{x_{1}^{2}}{16} + \sum_{i=2}^{n-1} x_{i}^{2} + \frac{x_{n}^{2}}{4} \le 1, \ x_{n} \ge 0 \right\},\$$

$$E_{1} = \left\{ (x_{1}, \dots, x_{n}) \in \mathbb{R}^{n} \mid \frac{x_{1}^{2}}{16} + \sum_{i=2}^{n} x_{i}^{2} \le 1, \ x_{n} \le 0 \right\},\$$

$$E_{2} = \left\{ (x_{1}, \dots, x_{n}) \in \mathbb{R}^{n} \mid \frac{x_{1}^{2}}{16} + \sum_{i=2}^{n-1} x_{i}^{2} + \frac{x_{n}^{2}}{9} \le 1, \ x_{n} \le 0 \right\}.$$

Let $A = E_0 \cup E_2$, $A' = E_0 \cup E_1$, and $B = A' + 2B^n$ (for n = 2 see Fig. 1). It is easy to check that A and B are strictly convex bodies.

Let $L = \lim(e_1, \ldots, e_{n-1})$. If $f_0 : \mathbb{R}^n \to \mathbb{R}^n$ is a self-isometry of B, then $-3e_n$ and $4e_n$ are fixed points of f_0 , whence f_0 restricted to $\Delta(-3e_n, 4e_n)$ is the identity. Thus no self-isometry of B maps B onto $\sigma_L(B)$, the image of B under the reflection at L.



Evidently, $\rho_H(A, B) = 2 = \rho_H(\sigma_L(A), B)$. Moreover, from Lemma 4.1 it follows that for every isometry f, if $id \neq f \neq \sigma_L$, then $\rho_H(f(A), B) > 2$; hence, A and $\sigma_L(A)$ are two isometric copies of A nearest to B.

References

- O. Aichholzer, H. Alt and G. Rote, *Matching shapes with a reference point*, Int. J. Comp. Geom. Appl. 7 (1997), 349–363.
- R. Arnold, Zür L²-Bestapproximation eines konvexen Körpers durch einen bewegten konvexen Körper, Mh. Math. 108 (1989), 277–293.
- [3] I. Bárány, On the minimal ring containing the boundary of a convex body, Acta Sci. Math. (Szeged) 52 (1988), 93–100.
- [4] A. Bogdewicz, R. Dawson and M. Moszyńska, Čebyšev sets in hyperspaces over a Minkowski space, Glasnik Mat. 42 (62) (2007), 57–67.
- [5] A. Bogdewicz and M. Moszyńska, Čebyšev sets in the space of convex bodies, Rend. Circ. Mat. Palermo Suppl. 77 (2006), 19–39.
- [6] R. Dawson and M. Moszyńska, $\tilde{C}eby\check{s}ev$ sets in hyperspaces over \mathbb{R}^n , Canadian J. Math., to appear.
- [7] K. Kuratowski, *Topologie*, Vol. I, 1952.
- [8] A. S. Lakhtin and V. N. Ushakov, Minimization of the Hausdorff distance between convex polyhedrons, J. Math. Sci. 126 (6) (2005), 1553–1559.
- [9] M. Moszyńska, Remarks on the minimal rings of convex bodies, Studia Sci. Math. Hungarica 35 (1999), 155–174.
- [10] M. Moszyńska, Selected Topics in Convex Geometry, Birkhäuser, 2005.
- [11] R. Schneider, Convex Bodies: the Brunn-Minkowski Theory, Cambridge University Press, 1993.
- [12] R. Vitale, L_p metrics for compact, convex sets, J. Approx. Theory 45 (1985), 280–287.