

## THE RUELLE ROTATION OF KILLING VECTOR FIELDS

BY

KONSTANTIN ATHANASSOPOULOS (Iraklion)

**Abstract.** We present an explicit formula for the Ruelle rotation of a nonsingular Killing vector field of a closed, oriented, Riemannian 3-manifold, with respect to Riemannian volume.

Let  $M$  be a closed, oriented Riemannian 3-manifold and  $X$  be a nonsingular Killing vector field on  $M$  with trivial normal bundle. The plane bundle  $E$  orthogonal to  $X$  is then spanned by two globally defined orthogonal unit vector fields  $Y$  and  $Z$  such that  $\{X(x), Y(x), Z(x)\}$  is a positively oriented basis of the tangent space at  $x \in M$ . Once we have chosen the unit vector field  $Z$  orthogonal to  $X$ , there is only one choice of a unit vector field  $Y$  such that  $\{X, Y, Z\}$  is a positively oriented orthogonal frame on  $M$ . The flow  $(\phi_t)_{t \in \mathbb{R}}$  of  $X$  is a one-parameter group of isometries of  $M$ , and thus  $\phi_{t*}(x)(E_x) = E_{\phi_t(x)}$  for every  $t \in \mathbb{R}$  and  $x \in M$ . The matrix of  $\phi_{t*}(x)|_{E_x}$  with respect to the bases  $\{Y(x), Z(x)\}$  and  $\{Y(\phi_t(x)), Z(\phi_t(x))\}$  is a rotation, denoted by  $f(t, x)$ . The resulting function  $f : \mathbb{R} \times M \rightarrow \text{SO}(2, \mathbb{R})$  is a smooth cocycle of the flow, by the chain rule, and can be lifted to a smooth cocycle  $\tilde{f} : \mathbb{R} \times M \rightarrow \mathbb{R}$ .

From the ergodic theorem for isometric systems (see [4]), the limit

$$F(x) = \lim_{t \rightarrow \infty} \frac{\tilde{f}(t, x)}{t}$$

exists uniformly for every  $x \in M$ . If  $\omega$  is the normalized Riemannian volume, the integral

$$\varrho(X) = \int_M F \omega = \int_M \tilde{f}(1, \cdot) \omega$$

is the Ruelle rotation number of  $X$  with respect to the trivialization  $\{Y, Z\}$  of  $E$ . If  $\{\bar{Y}, \bar{Z}\}$  is another trivialization of  $E$  as above and  $\bar{\varrho}(X)$  is the corresponding Ruelle rotation number of  $X$ , it follows from Proposition 3.4

2000 *Mathematics Subject Classification*: 37A20, 37E45, 53C20.

*Key words and phrases*: Killing vector field, Ruelle rotation.

in [2] that

$$\varrho(X) - \bar{\varrho}(X) = \int_M h^* \left( \frac{d\theta}{2\pi} \right) \wedge i_X \omega,$$

where  $d\theta/2\pi$  is the natural representative of the standard generator of  $H^1(\text{SO}(2, \mathbb{R}); \mathbb{Z})$  and  $h : M \rightarrow \text{SO}(2, \mathbb{R})$  is the smooth function such that the matrix  $h(x)$  gives the change of basis from  $\{Y(x), Z(x)\}$  to  $\{\bar{Y}(x), \bar{Z}(x)\}$  in  $E_x$ . Since  $X$  preserves the Riemannian volume,  $i_X \omega$  is closed. If it is exact,  $X$  is called *homologically trivial*, and in this case  $\varrho(X) = \bar{\varrho}(X)$ , that is, the Ruelle rotation number of  $X$  does not depend on the trivialization of  $E$ .

David Ruelle defined what we now call the Ruelle rotation in [5] for any nowhere vanishing smooth vector field with trivial normal bundle on a closed, oriented, smooth 3-manifold, with respect to a trivialization of the normal bundle and an invariant Borel probability measure. If the manifold is a homology 3-sphere, then the Ruelle rotation does not depend on the choice of the trivialization of the normal bundle [2].

In this note we present an explicit formula for  $\varrho(X)$  and make some remarks. More precisely, we prove the following.

**THEOREM.** *Let  $X$  be a nonsingular Killing vector field with trivial normal bundle  $E$  on an oriented, Riemannian, closed 3-manifold  $M$  with normalized Riemannian volume element  $\omega$ . Let  $\{Y, Z\}$  be an orthonormal frame trivializing  $E$  such that  $\{X, Y, Z\}$  is a positively oriented orthogonal frame on  $M$ . Then the Ruelle rotation number of  $X$  with respect to the given trivialization of  $E$  is given by the formula*

$$\varrho(X) = \frac{1}{2\pi} \int_M \langle [X, Z], Y \rangle \omega.$$

*Proof.* Let  $(\phi_t)_{t \in \mathbb{R}}$  be the flow of  $X$ . For every  $t \in \mathbb{R}$  we have

$$\begin{aligned} \phi_{t*}(x)Y(x) &= \cos 2\pi \tilde{f}(t, x) Y(\phi_t(x)) + \sin 2\pi \tilde{f}(t, x) Z(\phi_t(x)), \\ \phi_{t*}(x)Z(x) &= -\sin 2\pi \tilde{f}(t, x) Y(\phi_t(x)) + \cos 2\pi \tilde{f}(t, x) Z(\phi_t(x)). \end{aligned}$$

From [3, p. 235 and p. 245] we have

$$\tau_0^t \circ \phi_{t*}(x) = \exp(t(\nabla.X)_x),$$

where  $\tau_0^t$  is the parallel translation along the orbit of  $x$  from  $\phi_t(x)$  to  $x$ . So,

$$(*) \quad \begin{aligned} \cos 2\pi \tilde{f}(t, x) &= \langle \exp(t(\nabla.X)_x)Y(x), \tau_0^t(Y(\phi_t(x))) \rangle, \\ \sin 2\pi \tilde{f}(t, x) &= \langle \exp(t(\nabla.X)_x)Y(x), \tau_0^t(Z(\phi_t(x))) \rangle. \end{aligned}$$

Differentiating the second equation with respect to  $t$  we get

$$\tilde{f}'(t, x) = \frac{1}{2\pi \langle \phi_{t*}(x)Y(x), Y(\phi_t(x)) \rangle} \cdot \frac{d}{dt} \langle \exp(t(\nabla.X)_x)Y(x), \tau_0^t(Z(\phi_t(x))) \rangle$$

for  $t \in \mathbb{R}$  with  $\langle \phi_{t*}(x)Y(x), Y(\phi_t(x)) \rangle \neq 0$  and

$$\begin{aligned} \frac{d}{dt} \langle \exp(t(\nabla_X)_x)Y(x), \tau_0^t(Z(\phi_t(x))) \rangle &= \langle \exp(t(\nabla_X)_x)(\nabla_{Y(x)}X), \tau_0^t(Z(\phi_t(x))) \rangle \\ &\quad + \left\langle \exp(t(\nabla_X)_x)Y(x), \frac{d}{dt}(\tau_0^t(Z(\phi_t(x)))) \right\rangle \\ &= \langle (\tau_0^t \circ \phi_{t*}(x))(\nabla_{Y(x)}X), \tau_0^t(Z(\phi_t(x))) \rangle \\ &\quad + \langle (\tau_0^t \circ \phi_{t*}(x))Y(x), \tau_0^t(\nabla_{X(\phi_t(x))}Z) \rangle \\ &= \langle \phi_{t*}(x)(\nabla_{Y(x)}X), Z(\phi_t(x)) \rangle + \langle \phi_{t*}(x)Y(x), \nabla_{X(\phi_t(x))}Z \rangle. \end{aligned}$$

So we have

$$\tilde{f}'(t, x) = \frac{\langle \phi_{t*}(x)(\nabla_{Y(x)}X), Z(\phi_t(x)) \rangle + \langle \phi_{t*}(x)Y(x), \nabla_{X(\phi_t(x))}Z \rangle}{2\pi \langle \phi_{t*}(x)Y(x), Y(\phi_t(x)) \rangle}.$$

Since  $Z$  has constant unit length,  $2\langle \nabla_X Z, Z \rangle = X\langle Z, Z \rangle = 0$ . Therefore

$$\nabla_X Z = \langle \nabla_X Z, Y \rangle Y + \frac{\langle \nabla_X Z, X \rangle}{\|X\|^2} X$$

and

$$\langle \phi_{t*}(x)Y(x), \nabla_{X(\phi_t(x))}Z \rangle = \langle \nabla_{X(\phi_t(x))}Z, Y(\phi_t(x)) \rangle \cdot \langle \phi_{t*}(x)Y(x), Y(\phi_t(x)) \rangle.$$

It follows that

$$\tilde{f}'(t, x) = \frac{\langle \phi_{t*}(x)(\nabla_{Y(x)}X), Z(\phi_t(x)) \rangle}{2\pi \langle \phi_{t*}(x)Y(x), Y(\phi_t(x)) \rangle} + \frac{1}{2\pi} \langle \nabla_{X(\phi_t(x))}Z, Y(\phi_t(x)) \rangle$$

for  $t \in \mathbb{R}$  with  $\langle \phi_{t*}(x)Y(x), Y(\phi_t(x)) \rangle \neq 0$ . If we differentiate the first equation in (\*) with respect to  $t$  and use the fact that  $\langle \nabla_X Y, Z \rangle = -\langle \nabla_X Z, Y \rangle$ , we get

$$\tilde{f}'(t, x) = -\frac{\langle \phi_{t*}(x)(\nabla_{Y(x)}X), Y(\phi_t(x)) \rangle}{2\pi \langle \phi_{t*}(x)Y(x), Z(\phi_t(x)) \rangle} + \frac{1}{2\pi} \langle \nabla_{X(\phi_t(x))}Z, Y(\phi_t(x)) \rangle$$

for  $t \in \mathbb{R}$  with  $\langle \phi_{t*}(x)Y(x), Z(\phi_t(x)) \rangle \neq 0$ . The last two formulas are the same for  $t \in \mathbb{R}$  with  $\langle \phi_{t*}(x)Y(x), Y(\phi_t(x)) \rangle \cdot \langle \phi_{t*}(x)Y(x), Z(\phi_t(x)) \rangle \neq 0$ , because

$$\begin{aligned} &\langle \phi_{t*}(x)Y(x), Y(\phi_t(x)) \rangle \cdot \langle \phi_{t*}(x)(\nabla_{Y(x)}X), Y(\phi_t(x)) \rangle \\ &\quad + \langle \phi_{t*}(x)Y(x), Z(\phi_t(x)) \rangle \cdot \langle \phi_{t*}(x)(\nabla_{Y(x)}X), Z(\phi_t(x)) \rangle \\ &= \langle \phi_{t*}(x)(\nabla_{Y(x)}X), \phi_{t*}(x)Y(x) \rangle = \langle \nabla_{Y(x)}X, Y(x) \rangle = 0, \end{aligned}$$

since  $X$  is Killing. Now  $\phi_{t*}Y = \langle \phi_{t*}Y, Y \rangle Y + \langle \phi_{t*}Y, Z \rangle Z$  and so

$$\frac{1}{\langle \phi_{t*}Y, Y \rangle} \nabla_{\phi_{t*}Y} X = \nabla_Y X + \frac{\langle \phi_{t*}Y, Z \rangle}{\langle \phi_{t*}Y, Y \rangle} \nabla_Z X,$$

from which it follows that

$$\begin{aligned} \frac{\langle \nabla_{\phi_{t*}Y}X, Z \rangle}{\langle \phi_{t*}Y, Y \rangle} &= \langle \nabla_Y X, Z \rangle = -\langle \nabla_Z X, Y \rangle = -\frac{\langle \nabla_{\phi_{t*}Y}X, Y \rangle}{\langle \phi_{t*}Y, Z \rangle} \\ &= \langle [X, Z] - \nabla_X Z, Y \rangle, \end{aligned}$$

since  $X$  is a Killing vector field. Consequently, for every  $t \in \mathbb{R}$  we have

$$\tilde{f}'(t, x) = \frac{1}{2\pi} \langle [X, Z](\phi_t(x)), Y(\phi_t(x)) \rangle,$$

and so

$$\tilde{f}(t, x) = \frac{1}{2\pi} \int_0^t \langle [X, Z](\phi_s(x)), Y(\phi_s(x)) \rangle ds.$$

Hence

$$F(x) = \lim_{t \rightarrow \infty} \frac{1}{2\pi t} \int_0^t \langle [X, Z](\phi_s(x)), Y(\phi_s(x)) \rangle ds.$$

By Fubini's theorem and the invariance of the Riemannian volume we get

$$\varrho(X) = \frac{1}{2\pi} \int_M \langle [X, Z], Y \rangle \omega,$$

as asserted.

REMARK 1. Note that since  $X$  is a Killing vector field, we have

$$\begin{aligned} \langle [X, Z], X \rangle &= \langle \nabla_X Z, X \rangle + \langle \nabla_X X, Z \rangle = X \langle Z, X \rangle = 0, \\ \langle [X, Z], Z \rangle &= \langle \nabla_X Z, Z \rangle - \langle \nabla_Z X, Z \rangle = \frac{1}{2} X(\|Z\|^2) = 0. \end{aligned}$$

So  $[X, Z] = \langle [X, Z], Y \rangle Y$ , and if for every  $x \in M$  we let

$$\varepsilon(x) = \begin{cases} +1 & \text{if } \omega_x(X(x), [X, Z](x), Z(x)) > 0, \\ -1 & \text{if } \omega_x(X(x), [X, Z](x), Z(x)) < 0, \\ 0 & \text{if } [X, Z](x) = 0, \end{cases}$$

then

$$\varrho(X) = \frac{1}{2\pi} \int_M (\varepsilon \cdot \|[X, Z]\|) \omega.$$

If  $\eta$  is the dual 1-form of  $Z$  with respect to the Riemannian metric, then it is not hard to see that  $\|X\| \cdot \eta \wedge d\eta = \text{vol}(M) \langle [X, Z], Y \rangle \omega$ . Therefore

$$\varrho(X) = \frac{1}{2\pi \text{vol}(M)} \int_M \|X\| \cdot \eta \wedge d\eta.$$

REMARK 2. If  $H^1(M; \mathbb{Z}) = 0$ , the function  $F$  does not depend on the trivialization  $\{Y, Z\}$  of  $E$ . Indeed, let  $\{Y_1, Z_1\}$  and  $\{Y_2, Z_2\}$  be two trivializations of  $E$  as at the beginning. There exists a smooth function

$g : M \rightarrow \text{SO}(2, \mathbb{R})$  such that  $Y_2(x) = g(x)(Y_1(x))$  and  $Z_2(x) = g(x)(Z_1(x))$  for every  $x \in M$ . Since  $H^1(M; \mathbb{Z}) = 0$ , there is a smooth function  $\theta : M \rightarrow \mathbb{R}$  such that  $g(x)$  is the rotation by the angle  $\theta(x)$ . Thus,

$$\begin{aligned} Y_2(x) &= \cos \theta(x) \cdot Y_1(x) + \sin \theta(x) \cdot Z_1(x), \\ Z_2(x) &= -\sin \theta(x) \cdot Y_1(x) + \cos \theta(x) \cdot Z_1(x), \end{aligned}$$

and

$$\begin{aligned} \langle [X, Z_2], Y_2 \rangle &= \langle -\sin \theta [X, Y_1] - X(\sin \theta) Y_1 + \cos \theta [X, Z_1] + X(\cos \theta) Z_1, \cos \theta Y_1 + \sin \theta Z_1 \rangle \\ &= \langle [X, Z_1], Y_1 \rangle - X(\theta) = \langle [X, Z_1], Y_1 \rangle - \frac{\partial(\theta \circ \phi)}{\partial t}. \end{aligned}$$

If  $f_1$  and  $f_2$  are the corresponding cocycles, we get

$$\tilde{f}'_1 - \tilde{f}'_2 = \frac{1}{2\pi} \cdot \frac{\partial(\theta \circ \phi)}{\partial t}$$

and

$$\tilde{f}_1(t, x) - \tilde{f}_2(t, x) = \frac{1}{2\pi} [\theta(\phi_t(x)) - \theta(x)],$$

that is, the two cocycles are cohomologous, and therefore  $F_1 = F_2$ .

According to the topological classification of nonsingular Killing vector fields on Riemannian 3-manifolds, given in [1], if  $M$  is a homology 3-sphere, the orbits of  $X$  are periodic and  $M$  is a Seifert manifold. If  $T(x) > 0$  denotes the period of the orbit of  $x$ , then

$$F(x) = \frac{1}{2\pi T(x)} \int_0^{T(x)} \langle [X, Z](\phi_s(x)), Y(\phi_s(x)) \rangle ds$$

and  $F$  is smooth except at a finite number of orbits, the exceptional fibers of the Seifert fibration.

#### REFERENCES

- [1] Y. Carrière, *Flots riemanniens*, Astérisque 116 (1984), 31–52.
- [2] É. Ghys et J.-M. Gambaudo, *Enlacements asymptotiques*, Topology 36 (1997), 1355–1379.
- [3] S. Kobayashi and K. Nomizu, *Foundations of Differential Geometry*, Vol. 1, Interscience, New York, 1963.
- [4] U. Krengel, *Ergodic Theorems*, de Gruyter, Berlin, 1985.
- [5] D. Ruelle, *Rotation numbers for diffeomorphisms and flows*, Ann. Inst. H. Poincaré Phys. Théor. 42 (1985), 109–115.

Department of Mathematics  
University of Crete  
GR-71409 Iraklion, Greece  
E-mail: athanako@math.uoc.gr

Received 22 January 2008;  
revised 3 February 2009

(5006)