

An extension of a multiplicity theorem by Ricceri with an application to a class of quasilinear equations

by

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Abstract. A recent multiplicity result by Ricceri, stated for equations in Hilbert spaces, is extended to a wider class of Banach spaces. Applications to nonlinear boundary value problems involving the p -Laplacian are presented.

1. Introduction. In [5, Theorem 1], B. Ricceri has established a multiplicity theorem for the critical points of a continuously Gateaux differentiable functional J over a Hilbert space X , satisfying

$$(1) \quad \limsup_{\|x\| \rightarrow \infty} \frac{J(x)}{\|x\|^2} \leq 0.$$

Ricceri's result ensures that, for each real r within the range of J and $x_0 \in J^{-1}(]-\infty, r[)$, either the functional

$$x \mapsto \|x - x_0\|^2/2 - \lambda J(x) \quad (\text{for some } \lambda > 0)$$

admits at least three critical points, or the set $J^{-1}([r, \infty[)$ has a unique point minimizing the distance from x_0 . Then he proves that, under very general hypotheses (namely, the nonconvexity of $J^{-1}([r, \infty[)$), for some x_0 in a convex dense subset of X and some positive λ , the first case occurs, thus obtaining a multiplicity result. To this end, he employs a result of Tsar'kov ([6, Corollary 2]) dealing with the problem of best approximation and Chebyshev sets, which sharpens a previous result of Efimov and Stechkin ([2, Theorem 3]).

For our purposes, Tsar'kov's result can be stated as follows: in a Hilbert space, let M be a nonconvex, sequentially weakly closed set and S be a convex, dense set; then there exists a point $x_0 \in S$ admitting at least two points of best approximation in M .

Both in [5] and in [6], an interesting link is established between best approximation theory and critical point theory, as solutions of boundary

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value problems are found as critical points of functionals of the type above. Namely, in [5] it is shown that, whenever g is a continuous, nonconstant and nondecreasing real-valued function on \mathbb{R} (with suitable asymptotic behavior to make (1) true), there exist $w_0 \in C_0^\infty(]0, 1[)$ and a positive λ such that the two-point Dirichlet problem

$$\begin{cases} -u'' = \lambda g(u) - w_0(x) & \text{in }]0, 1[, \\ u(0) = u(1) = 0, \end{cases}$$

has at least three classical solutions.

The aim of the present paper is to prove an analogous result for a more general class of problems, built on partial differential equations involving the p -Laplacian: namely, let g be a continuous function on $\Omega \times \mathbb{R}$ (where $\Omega \subset \mathbb{R}^N$ is a bounded domain with smooth boundary), satisfying standard growth conditions and a certain asymptotic assumption (see Section 3 for more details); moreover, let $g(x, \cdot)$ be nondecreasing for all $x \in \Omega$. We shall prove that, for an arbitrary convex, dense subset S of $W_0^{1,p}(\Omega)$, there exist $u_0 \in S$ and $\lambda > 0$ such that the Dirichlet problem

$$(P) \quad \begin{cases} -\Delta_p u = \lambda g(x, u + u_0(x)) & \text{in } \Omega, \\ u = 0 & \text{in } \partial\Omega, \end{cases}$$

has at least three weak solutions.

The same approach leads to a multiplicity theorem for the Neumann problem as well: namely, under the same assumptions on Ω and g , for an arbitrary convex, dense subset S' of $W^{1,p}(\Omega)$, there exist $u_0 \in S'$ and $\lambda > 0$ such that the Neumann problem

$$(Q) \quad \begin{cases} -\Delta_p u + |u|^{p-2}u = \lambda g(x, u + u_0(x)) & \text{in } \Omega, \\ \partial u / \partial n = 0 & \text{in } \partial\Omega, \end{cases}$$

(where n denotes the outward unit normal to $\partial\Omega$) has at least three weak solutions.

Notice that u_0 and λ are not explicitly determined.

Solutions of (P) (resp. (Q)) are found as critical points of a certain functional on $W_0^{1,p}(\Omega)$ (resp. $W^{1,p}(\Omega)$), so we need to extend Ricceri's theorem to a class of Banach spaces wide enough to embrace this case. Moreover, it will be necessary to refer to a more general form of Tsar'kov's result:

THEOREM A ([6, Theorem 2], [2, Lemma 1]). *Let X be a uniformly convex Banach space with strictly convex topological dual, and M a sequentially weakly closed and nonconvex subset of X . Then, for any convex, dense subset S of X , there exists $x_0 \in S$ such that the set*

$$\{y \in M : \|y - x_0\| = d(x_0, M)\}$$

has at least two points.

Here we denote by $d(x_0, M)$ the distance between x_0 and the set M .

A further condition on the space arises from the need that the functional $x \mapsto \|x\|^p$ ($p > 1$) be continuously Gateaux differentiable (which is trivial in the case of Hilbert spaces with $p = 2$): for this purpose, it is sufficient to require that the norm be Fréchet differentiable on the unit sphere (see [1] and Section 2 for more details). This assumption places our space somewhere between the classes of “very smooth” and of “uniformly smooth” Banach spaces. Notice that such a space, provided it is reflexive, has a strictly convex topological dual ([1, Theorem 1 and Corollary 1, Section 1, Chapter 2]).

In the proof of our abstract result, we will refer to the following minimax theorem:

THEOREM B ([4, Theorem 1 and Remark 1]). *Let X be a topological space, I a real interval, and $f : X \times I \rightarrow \mathbb{R}$ a function satisfying the following conditions:*

- (c₁) *for every $x \in X$, the function $f(x, \cdot)$ is quasi-concave and continuous;*
- (c₂) *for every $\lambda \in I$, the function $f(\cdot, \lambda)$ is lower semicontinuous and each of its local minima is a global minimum;*
- (c₃) *there exist $\varrho_0 > \sup_I \inf_X f$ and $\lambda_0 \in I$ such that the set*

$$\{x \in X : f(x, \lambda_0) \leq \varrho_0\}$$

is compact.

Then

$$\sup_I \inf_X f = \inf_X \sup_I f.$$

2. Abstract results. Before stating our results, we need the following definition.

Let X be a Banach space. After [1], we define a *support mapping* as a function $\varphi : X \setminus \{0\} \rightarrow X^* \setminus \{0\}$ satisfying:

- (SM₁) $\|\varphi(x)\|_{X^*} = 1 = \langle \varphi(x), x \rangle$ for all $x \in S(X)$, where $S(X)$ is the unit sphere in X ;
- (SM₂) $\varphi(\varrho x) = \varrho \varphi(x)$ for all $\varrho > 0$ and $x \in X \setminus \{0\}$.

Our main result reads as follows:

THEOREM 1. *Let X be a real uniformly convex Banach space with Fréchet differentiable norm on $S(X)$, $p > 1$, and J be a nonconstant, continuously Gateaux differentiable functional with compact derivative, satisfying*

$$(2) \quad \limsup_{\|x\| \rightarrow \infty} \frac{J(x)}{\|x\|^p} \leq 0.$$

Then for every $r \in]\inf_X J, \sup_X J[$ and every $x_0 \in J^{-1}(]-\infty, r])$ one of the following conditions is true:

- (a) there exists $\lambda > 0$ such that the functional defined on X by

$$x \mapsto \|x - x_0\|^p/p - \lambda J(x)$$

admits at least three critical points;

- (b) there exists $y \in J^{-1}(r)$ such that

$$\|x - x_0\| > \|y - x_0\|$$

for all $x \in J^{-1}(]r, \infty[)$ with $x \neq y$.

Proof. First of all, we show that condition (a) is meaningful.

From [1, Theorem 1, Section 2, Chapter 2] it follows that, since the norm of X is Fréchet differentiable on $S(X)$, there exists a support mapping φ which is norm-to-norm continuous from $S(X)$ to $S(X^*)$. It is easily seen that, actually, φ is continuous on $X \setminus \{0\}$ and the functional $x \mapsto \|x\|$ is continuously Gateaux differentiable on $X \setminus \{0\}$ with derivative given by

$$x \mapsto \varphi(x)/\|x\|.$$

Thus, for every $x_0 \in X$, the functional $x \mapsto \|x - x_0\|^p/p$ is continuously Gateaux differentiable in X and its derivative is the operator $A : X \rightarrow X^*$ defined by

$$A(x) = \begin{cases} \|x - x_0\|^{p-2}\varphi(x - x_0) & \text{if } x \neq x_0, \\ 0 & \text{if } x = x_0. \end{cases}$$

Now we can prove our result. Fix r, x_0 as in the statement, and assume that (a) does not hold: we shall prove that (b) is true.

Set $I = [0, \infty[$ and define $f : X \times I \rightarrow \mathbb{R}$ by putting

$$f(x, \lambda) = \|x - x_0\|^p/p + \lambda(r - J(x)).$$

We are going to apply Theorem B to f , endowing X with the weak topology, so let us check the hypotheses. Condition (c₁) is trivial. Since $r < \sup_X J$, it is immediately seen that $\sup_I \inf_X f < \infty$, so condition (c₃) is obviously fulfilled with $\lambda_0 = 0$.

The discussion of condition (c₂) is more complex. Fix $\lambda \geq 0$. Observe that $f(\cdot, \lambda)$ is sequentially weakly lower semicontinuous (l.s.c.), as it is the sum of $x \mapsto \|x - x_0\|^p/p$, which is weakly l.s.c., and of $x \mapsto \lambda(r - J(x))$, which is sequentially weakly continuous since J' is compact and X is reflexive (see [7, Corollary 41]).

Moreover, we prove that $f(\cdot, \lambda)$ is coercive: in fact, for every $\varepsilon \in]0, 1/p\lambda[$ it follows from (2) that there exists $\delta > 0$ such that

$$J(x) < \varepsilon \|x\|^p \quad \text{whenever} \quad \|x\| \geq \delta;$$

thus, for all $x \in X$ with $\|x\| \geq \max\{\delta, \|x_0\|\}$,

$$\begin{aligned} f(x, \lambda) &> \|x\|^p \left(\frac{\|x - x_0\|^p}{p\|x\|^p} - \lambda\varepsilon \right) + \lambda r \\ &\geq \|x\|^p \left(\frac{(\|x\| - \|x_0\|)^p}{p\|x\|^p} - \lambda\varepsilon \right) + \lambda r, \end{aligned}$$

and the latter goes to ∞ as $\|x\| \rightarrow \infty$. As a consequence of the Eberlein–Shmul’yan Theorem, $f(\cdot, \lambda)$ is weakly l.s.c.

We need to verify that every local minimum of $f(\cdot, \lambda)$ is a global minimum: with this aim in mind, we first observe that $f(\cdot, \lambda)$ is a continuously Gateaux differentiable functional with derivative $A - \lambda J'$. Then we prove that $f(\cdot, \lambda)$ satisfies the Palais–Smale condition.

Let $\{z_n\}$ be a *Palais–Smale sequence*, that is, a sequence in X such that

- (PS₁) $\{f(z_n, \lambda)\}$ is bounded;
- (PS₂) $\lim_n \|A(z_n) - \lambda J'(z_n)\|_{X^*} = 0$.

From (PS₁), together with the coercivity of $f(\cdot, \lambda)$, it follows that $\{z_n\}$ is bounded, that is, there exists a positive constant M such that $\|z_n\| \leq M$ for all n , hence we find a subsequence, which we still denote $\{z_n\}$, weakly convergent to a point $z_0 \in X$. Then, again by compactness of J' , we can assume that $\{J'(z_n)\}$ converges to some $\psi \in X^*$.

Let us prove that $\{z_n\}$ is strongly convergent to z_0 .

By (PS₂), for every $\varepsilon > 0$ we can find $\nu \in \mathbb{N}$ such that for all $n > \nu$,

$$\|A(z_n) - \lambda J'(z_n)\|_{X^*} < \frac{\varepsilon}{M + \|z_0\|}$$

so in particular

$$\langle A(z_n) - \lambda J'(z_n), z_n - z_0 \rangle < \varepsilon.$$

Due to the convergence of $\{J'(z_n)\}$ to ψ ,

$$\lim_n \langle J'(z_n), z_n - z_0 \rangle = 0,$$

so we get

$$\lim_n \langle A(z_n), z_n - z_0 \rangle = 0;$$

moreover, by the weak convergence of $\{z_n\}$ to z_0 ,

$$(3) \quad \lim_n \langle A(z_n) - A(z_0), z_n - z_0 \rangle = 0.$$

To avoid trivial cases, we assume that $z_n \neq x_0$ for all n and $z_0 \neq x_0$; then we have

$$\begin{aligned}
 \langle A(z_n) - A(z_0), z_n - z_0 \rangle &= \langle \|z_n - x_0\|^{p-2} \varphi(z_n - x_0) - \|z_0 - x_0\|^{p-2} \varphi(z_0 - x_0), z_n - z_0 \rangle \\
 &= \langle \|z_n - x_0\|^{p-2} \varphi(z_n - x_0) - \|z_0 - x_0\|^{p-2} \varphi(z_0 - x_0), \\
 &\qquad\qquad\qquad (z_n - x_0) + (x_0 - z_0) \rangle \\
 &\geq (\|z_n - x_0\|^{p-1} - \|z_0 - x_0\|^{p-1})(\|z_n - x_0\| - \|z_0 - x_0\|).
 \end{aligned}$$

It is well known that there exists a constant k_p such that

$$\begin{aligned}
 (\|z_n - x_0\|^{p-1} - \|z_0 - x_0\|^{p-1})(\|z_n - x_0\| - \|z_0 - x_0\|) \\
 \geq k_p (\|z_n - x_0\| - \|z_0 - x_0\|)^{\bar{p}},
 \end{aligned}$$

where $\bar{p} = \max\{p, 2\}$. Then, from (3) it follows that

$$\lim_n \|z_n - x_0\| = \|z_0 - x_0\|$$

and hence $\{z_n\}$ is strongly convergent to z_0 , that is, the Palais–Smale condition is fulfilled.

We can now check condition (c_2) , arguing by contradiction: suppose that $f(\cdot, \lambda)$ admits a local, nonglobal minimum; also being coercive, it also has a global minimum too, that is, it has two strong local minima. Applying the Pucci–Serrin Mountain Pass Theorem, we deduce the existence of a third critical point for $f(\cdot, \lambda)$; thus, the functional of condition (a) would have three critical points, contrary to our assumption.

Now Theorem B ensures that

$$(4) \qquad \sup_{\lambda \in I} \inf_{x \in X} f(x, \lambda) = \inf_{x \in X} \sup_{\lambda \in I} f(x, \lambda) =: \alpha.$$

Notice that the function $\lambda \mapsto \inf_{x \in X} f(x, \lambda)$ is upper semicontinuous on I , and tends to $-\infty$ as $\lambda \rightarrow \infty$ (since $r < \sup_X J$); thus, it attains its supremum at some $\lambda^* \in I$, that is,

$$(5) \qquad \alpha = \inf_{x \in X} \left(\frac{\|x - x_0\|^p}{p} + \lambda^*(r - J(x)) \right).$$

The infimum on the right hand side of (4) is easily determined as

$$\alpha = \inf_{x \in J^{-1}([r, \infty])} \frac{\|x - x_0\|^p}{p} = \frac{\|y - x_0\|^p}{p}$$

for some $y \in J^{-1}([r, \infty])$.

Actually we have $y \in J^{-1}(r)$: in fact, if $J(y) > r$, there would exist a point z belonging to the segment joining x_0 and y such that $J(z) = r$ and

$$\|x_0 - z\| < d(x_0, J^{-1}([r, \infty])),$$

which is a contradiction. Hence

$$(6) \qquad \alpha = \inf_{x \in J^{-1}(r)} \frac{\|x - x_0\|^p}{p} \quad (\text{in particular } \alpha > 0).$$

By (5) and (6) it follows that

$$(7) \quad \inf_{x \in X} \left(\frac{\|x - x_0\|^p}{p} - \lambda^* J(x) \right) = \inf_{x \in J^{-1}(r)} \left(\frac{\|x - x_0\|^p}{p} - \lambda^* J(x) \right).$$

We deduce that $\lambda^* > 0$: if $\lambda^* = 0$, then (7) becomes $\alpha = 0$, contrary to (6).

Now we can prove (b). Arguing by contradiction, let $z \in J^{-1}([r, \infty]) \setminus \{y\}$ be such that $\|z - x_0\| = \|y - x_0\|$. As above, we see that $z \in J^{-1}(r)$, and so both z and y are global minima of the functional

$$x \mapsto \|x - x_0\|^p/p - \lambda^* J(x)$$

on $J^{-1}(r)$, and so by (7) on X . Thus, the Pucci–Serrin Mountain Pass Theorem shows that this functional has at least three critical points, contrary to the assumption that (a) does not hold (recall that λ^* is positive).

This concludes the proof. ■

COROLLARY 1. *Let X, J, p be as in Theorem 1 and let S be a convex, dense subset of X . Then for every $r \in]\inf_X J, \sup_X J[$ such that $J^{-1}([r, \infty])$ is not convex there exist $x_0 \in J^{-1}(]-\infty, r]) \cap S$ and $\lambda > 0$ such that the functional on X defined by*

$$x \mapsto \|x - x_0\|^p/p - \lambda J(x)$$

admits at least three critical points.

Proof. First of all, since X has a norm Fréchet differentiable on $S(X)$ and is reflexive (as seen in the Introduction), it follows that X^* is strictly convex. Moreover, $J^{-1}([r, \infty])$ is sequentially weakly closed.

By Theorem A, for some $x_0 \in J^{-1}(]-\infty, r]) \cap S$ there exist two distinct points $y_1, y_2 \in J^{-1}([r, \infty])$ satisfying

$$\|y_1 - x_0\| = \|y_2 - x_0\| = d(x_0, J^{-1}([r, \infty])).$$

Thus, condition (b) of Theorem 1 is false, so there exists $\lambda > 0$ such that $x \mapsto \|x - x_0\|^p/p - \lambda J(x)$ has at least three critical points in X . ■

3. An application to PDE. Throughout the following, Ω will denote a bounded domain in \mathbb{R}^N with C^1 boundary, p a real number with $1 < p < N$, $g : \Omega \times \mathbb{R} \rightarrow \mathbb{R}$ a continuous function satisfying the growth condition

$$(8) \quad |g(x, \xi)| \leq a|\xi|^{q-1} + b(x) \quad \text{for all } x \in \Omega, \xi \in \mathbb{R}$$

for some $a > 0, q \in]1, p^*[$ (p^* being the critical Sobolev exponent), and $b \in L^{q'}(\Omega)$. We define $G : \Omega \times \mathbb{R} \rightarrow \mathbb{R}$ by putting

$$G(x, \xi) = \int_0^\xi g(x, \eta) d\eta.$$

We denote by X the space $W_0^{1,p}(\Omega)$ endowed with the norm

$$\|u\| = \left(\int_{\Omega} |\nabla u(x)|^p dx \right)^{1/p},$$

and recall that for all $q \in]1, p^*[$, X is compactly embedded in $L^q(\Omega)$ (we denote by c_q the embedding constant).

By classical results, the functional $J : X \rightarrow \mathbb{R}$ defined by

$$J(u) = \int_{\Omega} G(x, u(x)) dx$$

is continuously Gateaux differentiable with compact derivative given by

$$\langle J'(u), v \rangle = \int_{\Omega} g(x, u(x))v(x) dx$$

for all $u, v \in X$.

THEOREM 2. *Let $\Omega \subset \mathbb{R}^N$, g, p be as above and let (8) be satisfied. Moreover assume:*

- (g₁) $g(x, \cdot)$ is nondecreasing for all $x \in \Omega$;
- (g₂) there exists $x_0 \in \Omega$ such that $g(x_0, \cdot)$ is not constant;
- (g₃) $\lim_{|\xi| \rightarrow \infty} \sup_{x \in \Omega} \frac{G(x, \xi)}{|\xi|^p} = 0$.

Then, for every $r \in]\inf_X J, \sup_X J[$ and every convex, dense subset S of X there exist $u_0 \in S$ with $J(u_0) < r$ and $\lambda > 0$ such that problem (P) has at least three weak solutions.

Proof. We observe that X is a uniformly convex Banach space and its norm is continuously Gateaux differentiable over $X \setminus \{0\}$. *A fortiori*, it is Fréchet differentiable on $S(X)$.

We claim that J satisfies (2). Fix $\varepsilon > 0$. By (g₃), there exists $\delta > 0$ such that

$$\sup_{x \in \Omega} \frac{G(x, \xi)}{|\xi|^p} < \frac{\varepsilon}{2c_p^p}$$

whenever $|\xi| \geq \delta$.

Define $k = \sup_{x \in \Omega, |\xi| \leq \delta} |G(x, \xi)|$ (without loss of generality we may assume $k > 0$). Choose $u \in X$ with

$$\|u\| > \left(\frac{2k|\Omega|}{\varepsilon} \right)^{1/p}$$

and put

$$\Omega_1 = \{x \in \Omega : |u(x)| \leq \delta\} \quad \text{and} \quad \Omega_2 = \Omega \setminus \Omega_1.$$

Then we have

$$\begin{aligned} J(u) &\leq \int_{\Omega_1} |G(x, u(x))| dx + \int_{\Omega_2} \frac{\varepsilon}{2c_p^p} |u(x)|^p dx \\ &\leq k|\Omega_1| + \frac{\varepsilon}{2c_p^p} \|u\|_{L^p(\Omega)}^p \leq k|\Omega| + \frac{\varepsilon}{2} \|u\|^p. \end{aligned}$$

Hence,

$$\frac{J(u)}{\|u\|^p} \leq \frac{k|\Omega|}{\|u\|^p} + \frac{\varepsilon}{2} < \varepsilon,$$

which is our claim.

We now prove that J is not constant. By (g_1) and (g_2) there exist α' and α'' with $\alpha' < \alpha''$ such that

$$g(x_0, \alpha') < g(x_0, \alpha'').$$

Assume, for instance, that $g(x_0, \alpha') \neq 0$.

Arguing by contradiction, suppose that J is constant. Then

$$\langle J'(u), v \rangle = \int_{\Omega} g(x, u(x))v(x) dx = 0$$

for all $u, v \in X$, and in particular, $g(x, u(x)) = 0$ for all $u \in X$ and a.e. x in Ω . Choose $w \in C_0^1(\Omega)$ such that $w(x_0) = \alpha'$. We deduce that $g(x, w(x)) = 0$ for all $x \in \Omega$, and so in particular $g(x_0, \alpha') = 0$, a contradiction.

Thus, we may choose $r \in]\inf_X J, \sup_X J[$ and prove that $J^{-1}(]r, \infty[)$ is not convex: first of all, by (g_1) , $G(x, \cdot)$ is a convex function over \mathbb{R} for all $x \in \Omega$, which implies that J is a convex functional over X ; then $J^{-1}(]-\infty, r])$ is convex, so our claim is equivalent to the nonconvexity of $J^{-1}(r)$. We will assume by contradiction that $J^{-1}(r)$ is convex.

By the continuity of g , we can find $\varepsilon \in]0, (\alpha'' - \alpha')/2[$ such that

$$(9) \quad g(x_0, \xi') < g(x_0, \xi'') \quad \text{for all } \xi' \in]\alpha' - \varepsilon, \alpha' + \varepsilon[, \xi'' \in]\alpha'' - \varepsilon, \alpha'' + \varepsilon[.$$

We recall that $C_0^\infty(\Omega)$ is everywhere dense in X so since $J^{-1}(]-\infty, r])$ and $J^{-1}(]r, \infty[)$ are nonempty open sets in X , there exist $v_1, v_2 \in C_0^\infty(\Omega)$ such that

$$J(v_1) := r_1 < r < r_2 := J(v_2).$$

Define

$$K = \sup \{ |G(x, \xi)| : x \in \Omega, |\xi| \leq \max(|\alpha'|, \|v_1\|_{L^\infty(\Omega)}, \|v_2\|_{L^\infty(\Omega)}) \}.$$

Notice that $K > 0$. Fix $\sigma \in \mathbb{R}$ such that $r_1 + \sigma < r < r_2 - \sigma$. Since the functions $G(\cdot, v_i(\cdot))$ ($i = 1, 2$) belong to $L^1(\Omega)$, there exists $\delta > 0$ such that

$$\left| \int_A G(x, v_i(x)) dx \right| < \frac{\sigma}{2} \quad (i = 1, 2)$$

for all subsets A of Ω with $|A| < \delta$.

Denote by B a closed ball centered at x_0 whose measure satisfies

$$|B| < \min \left\{ \frac{\sigma}{2K}, \delta \right\}.$$

By classical results, it is possible to construct continuous functions $w_i : \mathbb{R}^N \rightarrow \mathbb{R}$ ($i = 1, 2$) such that

$$w_i(x) = \begin{cases} \alpha' & \text{if } x = x_0, \\ v_i(x) & \text{if } x \in \Omega \setminus B, \\ 0 & \text{if } x \in \mathbb{R}^N \setminus \Omega, \end{cases}$$

and $\|w_i\|_{L^\infty(\mathbb{R}^N)} \leq \max\{|\alpha'|, \|v_i\|_{L^\infty(\Omega)}\}$.

The previous conditions yield

$$(10) \quad \int_{\Omega} G(x, w_1(x)) \, dx = \int_B G(x, w_1(x)) \, dx + J(v_1) - \int_B G(x, v_1(x)) \, dx < K|B| + r_1 + \sigma/2 < r_1 + \sigma < r.$$

In a similar way

$$(11) \quad \int_{\Omega} G(x, w_2(x)) \, dx > r.$$

Let $\{\varrho_n\}$ be a mollifier sequence and h_n^i ($i = 1, 2$) the convolution

$$h_n^i = \varrho_n * w_i.$$

By the theory of convolution h_n^i belongs to $C_0^\infty(\mathbb{R}^N)$ and in particular to X (for n large enough). Moreover $\{h_n^i\}$ uniformly converges to w_i on compact sets of \mathbb{R}^N . Thus,

$$\lim_n J(h_n^i) = \int_{\Omega} G(x, w_i(x)) \, dx,$$

so by (10) and (11) and the uniform convergence we can choose m so large that $J(h_m^1) < r < J(h_m^2)$ and $|h_m^i(x_0) - \alpha'| < \varepsilon$ for $i = 1, 2$. The set

$$\Gamma = \{u \in C_0^\infty(\Omega) : |u(x_0) - \alpha'| < \varepsilon\}$$

is convex. So the segment joining h_m^1 and h_m^2 is contained in Γ ; moreover by the continuity of J , there exists a point u' of the segment such that $J(u') = r$. Analogously there exists $u'' \in C_0^\infty(\Omega)$ such that $|u''(x_0) - \alpha''| < \varepsilon$ and $J(u'') = r$.

Since $J^{-1}(r)$ is assumed to be convex, the function $\mu \mapsto J(\mu u' + (1-\mu)u'')$ is constant on $[0, 1]$. Hence its derivative is zero, that is,

$$\langle J'(\mu u' + (1-\mu)u''), u' - u'' \rangle = 0$$

for all $\mu \in [0, 1]$. In particular

$$\int_{\Omega} [g(x, u'(x)) - g(x, u''(x))](u'(x) - u''(x)) \, dx = 0,$$

and by (g₁) we get

$$[g(x, u'(x)) - g(x, u''(x))](u'(x) - u''(x)) = 0$$

for all $x \in \Omega$.

On the other hand,

$$\alpha' - \varepsilon < u'(x_0) < \alpha' + \varepsilon < \alpha'' - \varepsilon < u''(x_0) < \alpha'' + \varepsilon,$$

and so $g(x_0, u'(x_0)) = g(x_0, u''(x_0))$ contrary to (9).

We have thus proved that $J^{-1}([r, \infty[)$ is not convex. By Corollary 1, there exist $u_0 \in S$ with $J(u_0) < r$ and $\lambda > 0$ such that the functional $u \mapsto \|u - u_0\|^p/p - \lambda J(u)$ has at least three critical points in X . Since for such critical point $u \in X$, $u - u_0$ is a weak solution of (P), the proof is concluded. ■

If our assumptions are fulfilled for $p = 2 < N$ and we choose $u_0 \in C_0^\infty(\Omega)$, then due to the linearity of the Laplacian operator, problem (P) is in a sense equivalent to the following:

$$(P') \quad \begin{cases} -\Delta u = \lambda g(x, u) - \Delta u_0(x) & \text{in } \Omega, \\ u = 0 & \text{in } \partial\Omega. \end{cases}$$

In fact, it is immediately seen that u is a weak solution of (P) iff $u + u_0$ is a weak solution of (P'). Thus, the next result follows at once from Theorem 2:

COROLLARY 2. *Let $\Omega \subset \mathbb{R}^N$ and g be as above and let (8) and (g₁)–(g₃) be satisfied for $p = 2$. Then for every $r \in]\inf_X J, \sup_X J[$ and every convex, dense subset S of $C_0^\infty(\Omega)$ there exist $u_0 \in S$ with $J(u_0) < r$ and $\lambda > 0$ such that problem (P') has at least three weak solutions.*

REMARK 1. If, in addition to the hypotheses of Theorem 2, we assume that $g(x, \cdot)$ is positively homogeneous with some exponent $\beta \neq p - 1$ for all $x \in \Omega$, we can “hide” the parameter λ . Let V be a dense linear subspace of X , and fix $r \in]\inf_X J, \sup_X J[$; then we find $u_0 \in V$ and $\lambda > 0$ such that problem (P) has at least three solutions. Now put $\gamma = 1/(\beta + 1 - p)$ and $v_0 = \lambda^\gamma u_0$ (v_0 still belongs to V); then the problem

$$(P'') \quad \begin{cases} -\Delta_p v = g(x, v + v_0(x)) & \text{in } \Omega, \\ v = 0 & \text{in } \partial\Omega, \end{cases}$$

has at least three solutions. In fact, for each solution $u \in X$ of (P), the function $v = \lambda^\gamma u$ is a solution of (P''). Notice that $J(v_0) < \lambda^{\gamma(\beta+1)}r$.

REMARK 2. There exist a sequence $\{u_n\} \subset S$ and a sequence $\{\lambda_n\} \subset]0, \infty[$ such that the problem

$$(P_n) \quad \begin{cases} -\Delta_p u = \lambda_n g(x, u + u_n(x)) & \text{in } \Omega, \\ u = 0 & \text{in } \partial\Omega, \end{cases}$$

has at least three solutions for all $n \in \mathbb{N}$, $n \geq 0$. In fact, the existence of a first pair u_0, λ_0 is ensured by Theorem 2, and the result can be generalized by induction: once u_i is determined for $i = 0, \dots, n$, there exists a subset S_{n+1} of S , convex and everywhere dense in S (hence in X), not containing the points u_i (see [6, Remark 1]); then it suffices to apply Theorem 2 to S_{n+1} to find a new function $u_{n+1} \in S_{n+1}$ and a positive λ_{n+1} such that problem (P_{n+1}) has at least three solutions.

EXAMPLE 1. The above results allow us to establish that the uniqueness of solution of boundary value problems can be unstable: that is, a problem admitting exactly one nontrivial solution can be perturbed in infinitely many ways so that each of the perturbed problems has at least three nontrivial solutions.

Namely, let Ω be as above, $q \in]0, 1[$ and $g : \mathbb{R} \rightarrow \mathbb{R}$ be defined by

$$g(\xi) = \begin{cases} 0 & \text{if } \xi \leq 0, \\ \xi^q & \text{if } \xi > 0. \end{cases}$$

Then it is well known that the problem

$$\begin{cases} -\Delta u = g(u) & \text{in } \Omega, \\ u = 0 & \text{in } \partial\Omega, \end{cases}$$

has exactly one nontrivial solution.

Notice that g satisfies all hypotheses of Corollary 2 and Remark 1 (with $\beta = q$); thus, recalling Remark 2, we observe that, choosing $S = C_0^\infty(\Omega)$, there exists a sequence $\{u_n\} \subset C_0^\infty(\Omega)$ ($u_n \neq 0$ for all $n \in \mathbb{N}$) such that for all $n \in \mathbb{N}$ the problem

$$\begin{cases} -\Delta u = g(u) - \Delta u_n(x) & \text{in } \Omega, \\ u = 0 & \text{in } \partial\Omega, \end{cases}$$

has at least three solutions (each of them is obviously different from zero).

Finally, we observe that a similar result can be proved for the problem (Q) , as pointed out in the Introduction. Under the same hypotheses on Ω , p, g , set $Y = W^{1,p}(\Omega)$, endowed with the norm

$$\|u\| = \left(\int_{\Omega} (|\nabla u(x)|^p + |u(x)|^p) dx \right)^{1/p}.$$

Notice that Y has all the properties we need, and contains $C^\infty(\overline{\Omega})$ as a dense linear subspace. Let $G, J : Y \rightarrow \mathbb{R}$ be defined as above. Then the following result holds:

THEOREM 3. *Let $\Omega \subset \mathbb{R}^N$, g, p be as above and let (8) and $(g_1)-(g_3)$ be satisfied. Then for every $r \in]\inf_Y J, \sup_Y J[$ and every convex, dense subset S' of Y there exist $u_0 \in S'$ with $J(u_0) < r$ and $\lambda > 0$ such that problem (Q) has at least three weak solutions.*

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