# Generic linear cocycles over a minimal base 

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#### Abstract

We prove that a generic linear cocycle over a minimal base dynamics of finite dimension has the property that the Oseledets splitting with respect to any invariant probability coincides almost everywhere with the finest dominated splitting. Therefore the restriction of the generic cocycle to a subbundle of the finest dominated splitting is uniformly subexponentially quasiconformal. This extends a previous result for SL $(2, \mathbb{R})$-cocycles due to Avila and the author.


## 1. Introduction

1.1. Statement of the result. Let $X$ be a compact Hausdorff space, and let $\mathbb{E}$ be a real vector bundle with base space $X$. We will always assume that the fibers $\mathbb{E}(x)$ have constant finite dimension.

Let $T: X \rightarrow X$ be a homeomorphism. A vector bundle automorphism covering $T$ is a map $A: \mathbb{E} \rightarrow \mathbb{E}$ whose restriction to an arbitrary fiber $\mathbb{E}(x)$ is a linear isomorphism onto the fiber $\mathbb{E}(T x)$; this isomorphism will be denoted by $A(x)$. Let $\operatorname{Aut}(\mathbb{E}, T)$ be the set of those automorphisms. When the vector bundle is trivial, an automorphism is usually called a linear cocycle.

We endow $\mathbb{E}$ with a Riemannian metric, and $\operatorname{Aut}(\mathbb{E}, T)$ with the uniform topology, that is, the topology induced by the distance

$$
d(A, B):=\sup _{x \in X}\|A(x)-B(x)\|,
$$

where $\|\cdot\|$ denotes the operator norm induced by the Riemannian metric.
Given $A \in \operatorname{Aut}(\mathbb{E}, T)$, an (ordered) splitting of the vector bundle

$$
\mathbb{E}=\mathbb{E}_{1} \oplus \cdots \oplus \mathbb{E}_{k}
$$

is called dominated (or exponentially separated) if it is $A$-invariant and there are constants $c>0$ and $\tau>1$ such that for all $x \in X$ and all unit vectors

[^0]$v_{1} \in \mathbb{E}_{1}(x), \ldots, v_{k} \in \mathbb{E}_{k}(x)$, we have
$$
\frac{\left\|A^{n}(x) \cdot v_{i}\right\|}{\left\|A^{n}(x) \cdot v_{i+1}\right\|}>c \tau^{n}, \quad \forall n \geq 0
$$
(In fact, it is always possible to choose an adapted Riemannian metric so that $c=1$; see [Go.)

There exists a unique such splitting into a maximal number $k$ of bundles, which is called the finest dominated splitting of $A$. If $k=1$, this is just a trivial splitting. The finest dominated splitting refines any other dominated splitting of $A$. (See e.g. BDV for these and other properties of dominated spittings.)

Given $A \in \operatorname{Aut}(\mathbb{E}, T)$, the Oseledets theorem (see e.g. $\widehat{\mathrm{Ar}}$ ) provides a set $R \subset X$ of full probability (i.e., such that $\mu(R)=1$ for every $T$-invariant probability measure $\mu$ ) such that each fiber $\mathbb{E}(x)$ over a point $x \in R$ splits into subspaces having the same Lyapunov exponents. This Oseledets splitting is $A$-invariant, measurable, but in general not continuous. For example, the dimensions of the subbundles may depend on the basepoint. Notice that the Oseledets splitting always refines the finest dominated splitting, since domination forces a gap between Lyapunov exponents.

It is shown in [BV] that for any ergodic measure $\mu$, the generic automorphism $A$ has the property that the Oseledets splitting coincides $\mu$-almost everywhere with the finest dominated splitting above the support of the measure. In this paper we obtain this property simultaneously for all measures, under suitable assumptions:

We say the space $X$ has finite dimension if it is homeomorphic to a subset of some Euclidean space. For instance, subsets of manifolds (assumed as usual to be Hausdorff and second countable) have finite dimension. We say that the homeomorphism $T$ is minimal if every orbit is dense.

Main Theorem 1.1. Let $T: X \rightarrow X$ be a minimal homeomorphism of a compact space $X$ of finite dimension, and let $\mathbb{E}$ be a vector bundle over $X$. Let $\mathcal{R}$ be the set of $A \in \operatorname{Aut}(\mathbb{E}, T)$ with the following property: for every $T$-invariant probability measure $\mu$, the Oseledets splitting with respect to $\mu$ coincides $\mu$-almost everywhere with the finest dominated splitting of $A$. Then $\mathcal{R}$ is a residual subset of $\operatorname{Aut}(\mathbb{E}, T)$.

Thus if $A \in \mathcal{R}$ has a finest dominated splitting into $k$ subbundles, then at almost every point $x$ with respect to each invariant probability measure, there are exactly $k$ different Lyapunov exponents. Of course, these values are a.e. constant if the measure is ergodic; they may however depend on the measure.

Since a minimal homeomorphism may have uncountably many ergodic measures, Theorem 1.1 is not a consequence of the aforementioned result
of $\overline{\mathrm{BV}}$. Actually, the theorem was proved first in the case of $\mathrm{SL}(2, \mathbb{R})$ cocycles in AB .

It is evident that the minimality assumption is necessary for the validity of Theorem 1.1; it is easy to see that it cannot be replaced e.g. by transitivity. An example from [AB] shows that it is not sufficient to assume that $T$ has a unique minimal set. As in AB , we do not know whether the assumption that $X$ has finite dimension is actually necessary.
1.2. Uniform properties. As a consequence of Main Theorem 1.1, the Oseledets splitting of a generic automorphism varies continuously; moreover the time needed to see a definite separation between expansion rates along different Oseledets subbundles is uniform. All these properties are much stronger than those provided by the Oseledets theorem itself.

Let us discuss another uniform property that follows from Theorem 1.1, and that depends on information on all invariant measures.

If $L$ is a linear automorphism between inner product vector spaces, define the mininorm of $L$ as

$$
\mathfrak{m}(L):=\left\|L^{-1}\right\|^{-1}
$$

and the quasiconformal distortion of $L$ as

$$
\begin{equation*}
\kappa(L):=\log \left(\frac{\|L\|}{\mathfrak{m}(L)}\right) \tag{1.1}
\end{equation*}
$$

For an interpretation of this quantity in terms of angle distortion, see [BV, Lemma 2.7].

Let us say that an automorphism $A \in \operatorname{Aut}(\mathbb{E}, T)$ is uniformly subexponentially quasiconformal if for every $\varepsilon>0$ there exists $c_{\varepsilon}>0$ such that

$$
\kappa\left(A^{n}(x)\right) \leq c_{\varepsilon}+\varepsilon n \quad \text { for all } x \in X, n \geq 0
$$

Then, as an addendum to the Main Theorem 1.1, we have:
Proposition 1.2. The elements of $\mathcal{R}$ are exactly the automorphisms $A \in \operatorname{Aut}(\mathbb{E}, T)$ whose restrictions $A \mid \mathbb{E}_{i}$ to each bundle of the finest dominated splitting $\mathbb{E}_{1} \oplus \cdots \oplus E_{k}$ are uniformly subexponentially quasiconformal.
1.3. Applications. It is shown in $\operatorname{BN}$ that if $A \in \operatorname{Aut}(\mathbb{E}, T)$ is uniformly subexponentially quasiconformal then for every $\varepsilon>0$, there is a Riemannian metric on $\mathbb{E}$ with respect to which the quasiconformal distortion is less than $\varepsilon$; moreover if $\varepsilon$ is small then a perturbation of $A$ is conformal with respect to this metric. Putting these results together with Main Theorem 1.1, one can show the following:

Theorem 1.3 ([BN, Thm. 2.4]). Let $T: X \rightarrow X$ be a minimal homeomorphism of a compact space $X$ of finite dimension, and let $\mathbb{E}$ be a vector
bundle over $X$. Then there exists a dense subset $\mathcal{D} \subset \operatorname{Aut}(\mathbb{E}, T)$ with the following properties: For every $A \in \mathcal{D}$ there exists a Riemannian metric on the vector bundle $\mathbb{E}$ with respect to which the subbundles of the finest dominated splitting of $A$ are orthogonal, and the restriction of $A$ to each of these subbundles is conformal. Moreover, this metric is adapted in the sense of GO.

This result is used in the proof of the following:
THEOREM $1.4([\overline{\mathrm{Bo}}])$. Let $T: X \rightarrow X$ be a minimal diffeomorphism of a compact manifold $X$, and let $\mathbb{E}$ be a vector bundle over $X$ whose fibers have dimension $d \geq 3$. Let $\mathcal{O}$ be the (open) set formed by the automorphisms $A \in \operatorname{Aut}(\mathbb{E}, T)$ that have a dominated splitting. Let $\mathcal{C} \subset \operatorname{Aut}(\mathbb{E}, T)$ be a homotopy class. Then $\mathcal{C} \cap \mathcal{O}$ is either empty or dense in $\mathcal{C}$.
1.4. Comments on the proof and organization of the paper. To prove Theorem 1.1 we use ideas and tools developed in $A B$ to deal with the $\mathrm{SL}(2, \mathbb{R})$ case. The basic strategy for mixing different expansion rates on higher dimensions is similar to that from $\overline{B V}$, but uses a characterization of domination from [BG] to find suitable places to perturb. As in [BV], the desired residual set is obtained as the set of continuity points of some semicontinuous function.

Despite these overlaps, dealing simultaneously with several Lyapunov exponents with respect to all invariant measures presents substantial new difficulties. We introduce an especially convenient semicontinuous function $Z$ to measure quasiconformal distortion. This function was in fact suggested by some ideas from $[\mathrm{BB}]$. The proof that the mixing mechanism actually produces a discontinuity of $Z$ is also more delicate: It is essential not to be too greedy, and instead attack only the points on $X$ where the distortion is comparatively large. This is explained in 93.2 .

The paper is organized as follows:
In §2 we explain several preliminaries, and reduce the proof of Main Theorem 1.1 to a result (Lemma 2.9) on the existence of discontinuities of a certain function (related to $Z$ ).

In $\S 3$ we prove Lemma 3.1, which produces suitable perturbations along a segment of orbit.

In $\$ 4$ we explain how to patch those local perturbations to prove Lemma 2.9 and thus conclude the proof.
2. Initial considerations. In this section, $X$ is a compact Hausdorff space $X$, the map $T: X \rightarrow X$ is at least continuous, and $\mathbb{E}$ is a vector bundle over $X$ of dimension $d$.

We denote the set of all $T$-invariant probability measures by $\mathcal{M}(T)$. A Borel set $B \subset X$ is said to have zero probability (resp. full probability) with respect to a continuous map $T: X \rightarrow X$ if $\mu(B)$ is 0 (resp. 1) for every $T$-invariant probability measure $\mu$.
2.1. Semi-uniform subadditive ergodic theorem. Proposition 1.2 yields equivalence between a uniform property on $\mathcal{M}(T)$ and a uniform property on $X$. The following Theorem 2.1 is often useful to obtain equivalences of this kind.

Recall that a sequence of functions $f_{n}: X \rightarrow \mathbb{R}$ is called subadditive if $f_{n+m} \leq f_{n}+f_{m} \circ T^{n}$.

Theorem 2.1 (Semi-uniform subadditive ergodic theorem; [Sc, Thm. 1], [SS, Thm. 1.7]). Let $T: X \rightarrow X$ be a continuous map of a compact Hausdorff space $X$. Let $f_{n}: X \rightarrow \mathbb{R}$ be continuous functions forming a subadditive sequence. Then

$$
\sup _{\mu \in \mathcal{M}(T)} \lim _{n \rightarrow \infty} \frac{1}{n} \int_{X} f_{n} d \mu=\lim _{n \rightarrow \infty} \frac{1}{n} \sup _{x \in X} f_{n}(x)
$$

Notice that by Fekete's lemma both limits above can be replaced by inf's. Also recall that for every $\mu \in \mathcal{M}(T)$, by Kingman's subadditive ergodic theorem the sequence $f_{n}(x) / n$ actually converges to a value in $[-\infty, \infty)$ for every point $x$ on a full probability subset.
2.2. Maximal asymptotic distortion. Recall the definition (1.1) of the quasiconformal distortion $\kappa$. Notice that $\kappa$ is subadditive, meaning that if $L_{i}: E_{i} \rightarrow E_{i+1}(i=1,2)$ are isomorphisms between inner product spaces then $\kappa\left(L_{2} L_{1}\right) \leq \kappa\left(L_{2}\right)+\kappa\left(L_{1}\right)$.

Given an automorphism $A \in \operatorname{Aut}(\mathbb{E}, T)$, define

$$
\begin{equation*}
K(A):=\inf _{n \geq 1} \frac{1}{n} \sup _{x \in X} \kappa\left(A^{n}(x)\right) \tag{2.1}
\end{equation*}
$$

(By Fekete's lemma, the inf can be replaced by a limit.) Being an infimum of continuous functions, $K: \operatorname{Aut}(A, \mathbb{E}) \rightarrow[0, \infty)$ is upper semicontinuous.

Notice that $A$ is uniformly subexponentially quasiconformal (as defined in the Introduction) if and only if $K(A)=0$.

If $L$ is an isomorphism between inner product vector spaces of dimension $d$, its singular values (i.e., the eigenvalues of $\left(L^{*} L\right)^{1 / 2}$ ) will be written as $\mathfrak{s}_{1}(L) \geq \cdots \geq \mathfrak{s}_{d}(L) ;$ so $\mathfrak{s}_{1}(L)=\|L\|$ and $\mathfrak{s}_{d}(L)=\mathfrak{m}(L)$.

Given $A \in \operatorname{Aut}(\mathbb{E}, T)$, the following Lyapunov exponents exist for every $x$ in a full probability subset of $X$ :

$$
\chi_{i}(A, x):=\lim _{n \rightarrow \infty} \frac{1}{n} \log \mathfrak{s}_{i}\left(A^{n}(x)\right) \quad(i=1, \ldots, d)
$$

Let us denote their averages with respect to some $\mu \in \mathcal{M}(T)$ by

$$
\chi_{i}(A, \mu):=\int_{X} \chi_{i}(A, x) d \mu(x)
$$

It follows from Theorem 2.1 that

$$
\begin{equation*}
K(A)=\sup _{\mu \in \mathcal{M}(T)}\left[\chi_{1}(A, \mu)-\chi_{d}(A, \mu)\right] \tag{2.2}
\end{equation*}
$$

In particular, $A$ is uniformly subexponentially quasiconformal if and only if for every point $x$ in a full probability subset, all Lyapunov exponents of $A$ at $x$ are equal.
2.3. Distortion inside the bundles of a dominated splitting. Let us review the basic robustness property of dominated splittings:

Proposition 2.2. Suppose that the automorphism $A \in \operatorname{Aut}(\mathbb{E}, T)$ has a dominated splitting $\mathbb{E}_{1} \oplus \cdots \oplus \mathbb{E}_{k}$. Then every automorphism $\tilde{A}$ sufficiently close to $A$ has a dominated splitting $\tilde{\mathbb{E}}_{1} \oplus \cdots \oplus \tilde{\mathbb{E}}_{k}$ such that, for each $i=$ $1, \ldots, k$, the fibers of $\tilde{\mathbb{E}}_{i}$ have the same dimension and are uniformly close to the fibers of $\mathbb{E}_{i}$.

We call $\tilde{\mathbb{E}}_{1} \oplus \cdots \oplus \tilde{\mathbb{E}}_{k}$ the continuation of the original dominated splitting for $A$. We remark that the continuation of a finest dominated splitting is not necessarily finest.

For any $A \in \operatorname{Aut}(\mathbb{E}, T)$, define

$$
K_{\text {fine }}(A):=\max _{i} K\left(A \mid \mathbb{E}_{i}\right)
$$

where $\mathbb{E}_{1} \oplus \cdots \oplus \mathbb{E}_{k}$ is the finest dominated splitting of $A$.
Notice that if $A \in \operatorname{Aut}(\mathbb{E}, T)$ and $\mathbb{F} \subset \mathbb{E}$ is an $A$-invariant subbundle, then $K(A) \geq K(A \mid \mathbb{F})$. In particular, we have:

Proposition 2.3. $K_{\text {fine }}(A) \leq K(A)$.
We use this to show the following:
Proposition 2.4. The map $K_{\text {fine }}: \operatorname{Aut}(\mathbb{E}, T) \rightarrow[0, \infty)$ is upper semicontinuous.

Proof. Let $A \in \operatorname{Aut}(\mathbb{E}, T)$ have finest dominated splitting $\mathbb{E}_{1} \oplus \cdots \oplus \mathbb{E}_{k}$, and let $\varepsilon>0$. Let $\tilde{A}$ be a perturbation of $A$, and let $\tilde{\mathbb{E}}_{1} \oplus \cdots \oplus \tilde{\mathbb{E}}_{k}$ be the continuation of the splitting, as given by Proposition 2.2. Each restriction $\tilde{A} \mid \tilde{\mathbb{E}}_{i}$ is conjugate to a perturbation of $A \mid \mathbb{E}_{i}$. Since $K$ is upper semicontinuous and invariant under conjugation, we have $K\left(\tilde{A} \mid \tilde{\mathbb{E}}_{i}\right) \leq K\left(A \mid \tilde{\mathbb{E}}_{i}\right)+\varepsilon$. Since the finest dominated splitting of $\tilde{A}$ refines $\tilde{\mathbb{E}}_{1} \oplus \cdots \oplus \tilde{\mathbb{E}}_{k}$, it follows from Proposition 2.3 that $K_{\text {fine }}(\tilde{A}) \leq K_{\text {fine }}(A)+\varepsilon$.

Notice that the set $\mathcal{R}$ from the statement of Main Theorem 1.1 (or from Proposition 1.2, which is now obvious) is precisely

$$
\left\{A \in \operatorname{Aut}(\mathbb{E}, T) ; K_{\text {fine }}(A)=0\right\}
$$

which by the proposition above is a $G_{\delta}$ set. The hard part of the proof of the Main Theorem is to show that $\mathcal{R}$ is dense.

Actually, we will see later that $\mathcal{R}$ is the set of points of continuity of $K_{\text {fine }}$, and therefore it is a residual set. However, it is not convenient to work with $K_{\text {fine }}$ directly. We will introduce alternative ways of measuring quasiconformal distortion that will turn out to be more appropriate.
2.4. Another measure of quasiconformal distortion. Let $E$ and $F$ be inner product spaces of dimension $d$, and let $L: E \rightarrow F$ be an isomorphism. Recall that $\mathfrak{s}_{1}(L) \geq \cdots \geq \mathfrak{s}_{d}(L)$ denote the singular values of $L$. Let $\lambda_{i}(L):=\log \mathfrak{s}_{i}(L)$. Define also

$$
\sigma_{0}(L):=0 \quad \text { and } \quad \sigma_{i}(L):=\lambda_{1}(L)+\cdots+\lambda_{i}(L) \quad \text { for } i=1, \ldots, d
$$

In particular, $\sigma_{1}(L)=\log \|L\|$ and $\sigma_{d}(L)=\log |\operatorname{det} L|$.
Consider the graph of the function $i \in\{0,1, \ldots, d\} \mapsto \sigma_{i}(L) \in \mathbb{R}$. By affine interpolation we obtain a graph over the interval $[0, d]$, which we call the $\sigma$-graph of $L$. The fact that the sequence $\lambda_{i}(L)$ is nonincreasing means that this graph is concave. In particular, the $\sigma$-graph of $L$ is above the line joining $(0,0)$ and $\left(d, \sigma_{d}(L)\right)$. Let us define $\zeta(L)$ as the area between this line and the $\sigma$-graph (see Figure 1). This amounts to

$$
\begin{equation*}
\zeta(L)=\sigma_{1}(L)+\cdots+\sigma_{d-1}(L)-\frac{d-1}{2} \sigma_{d}(L) \tag{2.3}
\end{equation*}
$$



Fig. 1. The upper curve is the $\sigma$-graph of some $L$. The shaded area is $\zeta(L)$. The area of the marked triangle is $\gamma_{3}(L)$.

Of course, $\zeta(L) \geq 0$, and equality holds if and only if all singular values of $L$ are equal, i.e., $L$ is conformal. (Actually, it is not difficult to show that
for every fixed dimension $d$, each quantity $\kappa$ and $\zeta$ is bounded by a uniform multiple of the other.)

Like $\kappa$, the functions just defined enjoy the property of subadditivity:
Proposition 2.5. The functions $\sigma_{1}, \ldots, \sigma_{d-1}$ and $\zeta$ are subadditive, and the function $\sigma_{d}$ is additive.

Proof. We recall some facts about exterior powers (see e.g. [Ar, § 3.2.3]). Let $\bigwedge^{i} E$ denote the $i$ th exterior power of $E$. The inner product in $E$ induces an inner product on $\bigwedge^{i} E$; actually if $\left\{e_{1}, \ldots, e_{d}\right\}$ is an orthonormal basis of $E$ then $\left\{e_{j_{1}} \wedge \cdots \wedge e_{j_{i}} ; 1 \leq j_{1}<\cdots<j_{i} \leq d\right\}$ is an orthonormal basis of $\bigwedge^{i} E$. The isomorphism $L: E \rightarrow F$ induces an isomorphism $\bigwedge^{i} L: \bigwedge^{i} E \rightarrow \bigwedge^{i} F$, and its norm is:

$$
\left\|\bigwedge^{i} L\right\|=\exp \sigma_{i}(L)
$$

Since operator norms are submultiplicative, it follows that $\sigma_{i}(\cdot)$ is subadditive. Moreover, since $\bigwedge^{d} E$ is 1 -dimensional, $\sigma_{d}(\cdot)$ is additive. It follows from the definition 2.3 that $\zeta(\cdot)$ is subadditive.

Let us introduce other quantities that will be used later, namely the following "half-gaps" between the $\lambda$ 's:

$$
\gamma_{i}(L):=\frac{\lambda_{i}(L)-\lambda_{i+1}(L)}{2}=\frac{-\sigma_{i-1}(L)+2 \sigma_{i}(L)-\sigma_{i+1}(L)}{2} \quad(1 \leq i<d)
$$

Geometrically, these numbers are the areas of the triangles determined by three consecutive vertices in the $\sigma$-graph: see Figure 1. In particular, $\gamma_{i}(L) \leq \zeta(L)$ for each $i$. On the other hand, the maximal half-gap is comparable to $\zeta(L)$, as the following lemma shows:

Lemma 2.6. If $L$ is an isomorphism between inner product spaces of dimension $d \geq 2$, then

$$
\max _{i \in\{1, \ldots, d-1\}} \gamma_{i}(L) \geq b_{d} \zeta(L)
$$

where $b_{d} \in(0,1]$ is a constant depending only on $d$.
Proof. A calculation shows that $\zeta(L)=\sum_{i=1}^{d-1} i(d-i) \gamma_{i}(L)$. Therefore the conclusion holds with

$$
b_{d}:=\left(\sum_{i=1}^{d-1} i(d-i)\right)^{-1}=\frac{6}{d\left(d^{2}-1\right)}
$$

Of course, Lemma 2.6 is just a property of concave graphs. Despite its simplicity, this property will play a significant role here, as it does (to a lesser extent) in BB.
2.5. Maximal quantities. Given $A \in \operatorname{Aut}(\mathbb{E}, T)$, we define

$$
\begin{equation*}
Z(A):=\inf _{n \geq 1} \frac{1}{n} \sup _{x \in X} \zeta\left(A^{n}(x)\right) \tag{2.4}
\end{equation*}
$$

Then the function $Z: \operatorname{Aut}(\mathbb{E}, T) \rightarrow[0, \infty)$ is upper semicontinuous.
The analog of formula $(2.2)$ for $Z$ is

$$
\begin{equation*}
Z(A)=\sup _{\mu \in \mathcal{M}(T)} \zeta\left(\operatorname{diag}\left(\chi_{1}(A, \mu), \ldots, \chi_{d}(A, \mu)\right)\right) \tag{2.5}
\end{equation*}
$$

For any $A \in \operatorname{Aut}(\mathbb{E}, T)$, define

$$
Z_{\text {fine }}(A):=\max _{i} Z\left(A \mid \mathbb{E}_{i}\right)
$$

where $\mathbb{E}_{1} \oplus \cdots \oplus \mathbb{E}_{k}$ is the finest dominated splitting of $A$.
Proposition 2.7. $Z_{\text {fine }}(A) \leq Z(A)$ for every $A \in \operatorname{Aut}(\mathbb{E}, T)$.
Proof. Let $A \in \operatorname{Aut}(\mathbb{E}, T)$, and let $E_{1} \oplus \cdots \oplus E_{k}$ be the finest dominated splitting of $A$. Take $i$ such that $K\left(A \mid \mathbb{E}_{i}\right)=K_{\text {fine }}(A)$. Let $m:=\operatorname{dim}\left(\mathbb{E}_{1} \oplus\right.$ $\cdots \oplus \mathbb{E}_{i-1}$ ) and $\ell:=\operatorname{dim} \mathbb{E}_{i}$. Applying 2.5 to the automorphism $A \mid \mathbb{E}_{i}$, we have

$$
Z\left(A \mid \mathbb{E}_{i}\right)=\sup _{\mu \in \mathcal{M}(T)} \zeta\left(\operatorname{diag}\left(\chi_{m+1}(A, \mu), \ldots, \chi_{m+\ell}(A, \mu)\right)\right)
$$

It follows from the interpretation of $\zeta$ as area that

$$
\zeta\left(\operatorname{diag}\left(\chi_{m+1}(A, \mu), \ldots, \chi_{m+\ell}(A, \mu)\right)\right) \leq \zeta\left(\operatorname{diag}\left(\chi_{1}(A, \mu), \ldots, \chi_{d}(A, \mu)\right)\right)
$$

for every $\mu \in \mathcal{M}(T)$. Therefore $Z\left(A \mid \mathbb{E}_{i}\right) \leq Z(A)$, as we wanted to show.
Using Proposition 2.7 instead of Proposition 2.3, the same argument that proved Proposition 2.4 yields:

Proposition 2.8. The map $Z_{\text {fine }}: \operatorname{Aut}(\mathbb{E}, T) \rightarrow[0, \infty)$ is upper semicontinuous.

Of course, $Z$ (resp. $Z_{\text {fine }}$ ) vanishes if and only if $K$ (resp. $K_{\text {fine }}$ ) vanishes. Actually the main conclusions of $\S \$ 2.2$ and 2.3 could have been obtained using the functions $Z$ and $Z_{\text {fine }}$ instead; but we have preferred the proofs that seemed more natural.
2.6. Setting up the proof. In the next sections, we will prove the following:

LEmma 2.9. Let $T$ be a minimal homeomorphism of a space of finite dimension. Then for every $\varepsilon>0$ there exists $\tilde{A} \in \operatorname{Aut}(\mathbb{E}, T)$ such that $\|\tilde{A}(x)-A(x)\|<\varepsilon$ for each $x \in X$ and

$$
Z_{\text {fine }}(\tilde{A})<a_{d} Z_{\text {fine }}(A)+\varepsilon,
$$

where $a_{d} \in(0,1)$ is a constant depending only on the dimension $d$.

An immediate consequence of Lemma 2.9 is that $A$ is a point of continuity of the function $Z_{\text {fine }}(\cdot)$ if and only if $Z_{\text {fine }}(A)=0$. Since the points of continuity of a semicontinuous function on a Baire space form a residual set, Main Theorem 1.1 follows.

Therefore we are reduced to proving Lemma 2.9. Actually, if suffices to prove it in the particular case that $A$ has no nontrivial dominated splitting:

Proof of the general case assuming the particular case. Assume that Lemma 2.9 is already proved for automorphisms of bundles of any dimension without nontrivial dominated splittings, thus providing a sequence $\left(a_{d}\right)$. Replacing each $a_{d}$ with $\max \left(a_{1}, \ldots, a_{d}\right)$, we can assume that this sequence is nondecreasing.

Let $A \in \operatorname{Aut}(\mathbb{E}, T)$, and let $\mathbb{E}_{1} \oplus \cdots \oplus \mathbb{E}_{k}$ be the finest dominated splitting of $A$. Let $\varepsilon>0$, and take a positive $\varepsilon^{\prime} \ll \varepsilon$. Each restriction $A \mid \mathbb{E}_{i}$ is an automorphism with no dominated splitting and therefore, by the particular case, there exists an $\varepsilon^{\prime}$-perturbation $B_{i} \in \operatorname{Aut}\left(\mathbb{E}_{i}, T\right)$ such that $Z\left(B_{i}\right)<$ $a_{d} Z\left(A \mid \mathbb{E}_{i}\right)+\varepsilon^{\prime}$. Let $\tilde{A} \in \operatorname{Aut}(\mathbb{E}, T)$ be such that $\tilde{A} \mid \mathbb{E}^{i}=B_{i}$; then $\tilde{A}$ is $\varepsilon$-close to $A$. The finest dominated splitting of $\tilde{A}$ refines $\mathbb{E}_{1} \oplus \cdots \oplus \mathbb{E}_{k}$, and thus by Proposition 2.7,

$$
Z_{\text {fine }}(\tilde{A}) \leq \max _{i} Z\left(\tilde{A} \mid \mathbb{E}_{i}\right) \leq \max _{i}\left(a_{d} Z\left(\mathbb{E}_{i}\right)+\varepsilon\right)=a_{d} Z_{\text {fine }}(A)+\varepsilon
$$

REMARK 2.10. The validity of Lemma 2.9 is equivalent to the validity of an analogous statement for $K_{\text {fine }}$. The reason why $Z_{\text {fine }}$ is more convenient to work with is that we know how to prove (the particular case of) Lemma 2.9 with a single perturbation, while producing a discontinuity of $K_{\text {fine }}$ would probably require a more complicated procedure.

Remark 2.11. Other upper semicontinuous functions on $\operatorname{Aut}(\mathbb{E}, T)$ that suggest themselves are

$$
\Sigma_{i}(A):=\inf _{n \geq 1} \frac{1}{n} \sup _{x \in X} \sigma_{i}\left(A^{n}(x)\right), \quad i=1, \ldots, d
$$

At first sight, these may seem the "right" functions to consider, especially since the proof from $[\mathrm{BV}]$ consists in finding a discontinuity of an analogous function (where the sup is replaced by an integral). However, it is not clear how to actually use these functions to prove Main Theorem 1.1.
3. Reducing nonconformality along segments of orbit. This section is devoted to the proof of the following result, which plays a role similar to Lemma 2 in AB :

Main Lemma 3.1. Suppose that $T$ is minimal and without periodic orbits, $A \in \operatorname{Aut}(\mathbb{E}, T)$ has no nontrivial dominated splitting, and $\varepsilon>0$. Then there exists $N \in \mathbb{N}$ with the following properties: For every $x \in X$ and every
$n \geq N$, there exists a sequence of linear maps

$$
\mathbb{E}(x) \xrightarrow{L_{0}} \mathbb{E}(T x) \xrightarrow{L_{1}} \cdots \xrightarrow{L_{n-1}} \mathbb{E}\left(T^{n} x\right)
$$

with $\left\|L_{j}-A\left(T^{j}(x)\right)\right\|<\varepsilon$ for each $j$ and such that

$$
\frac{1}{n} \zeta\left(L_{n-1} \cdots L_{0}\right)<a_{d} Z(A)+\varepsilon
$$

where $a_{d} \in(0,1)$ is a constant depending only on the dimension $d$.
3.1. Preliminary lemmas. If $\mathbb{E}_{1} \oplus \cdots \oplus E_{k}$ is a nontrivial dominated splitting for some $A \in \operatorname{Aut}(\mathbb{E}, T)$, then its indices are the numbers

$$
\operatorname{dim}\left(\mathbb{E}_{1}\right), \operatorname{dim}\left(\mathbb{E}_{1} \oplus \mathbb{E}_{2}\right), \ldots, \operatorname{dim}\left(\mathbb{E}_{1} \oplus \cdots \oplus \mathbb{E}_{k-1}\right) .
$$

We will need the following implicit characterization of these indices:
Theorem 3.2 ([BG, Thm. A]). An automorphism $A \in \operatorname{Aut}(\mathbb{E}, T)$ has a dominated splitting of index $i$ if and only if there exist $c>0$ and $\tau>1$ such that

$$
\frac{\mathfrak{s}_{i}\left(A^{n}(x)\right)}{\mathfrak{s}_{i+1}\left(A^{n}(x)\right)}>c \tau^{n} \quad \text { for all } x \in X \text { and } n \geq 0
$$

In other words, the indices of domination correspond to exponentially large gaps between singular values.

Absence of domination permits us to significantly change the orbits of vectors by performing small perturbations. One operation of this kind is described by the following lemma:

Lemma 3.3. Assume that $A \in \operatorname{Aut}(\mathbb{E}, T)$ has no dominated splitting of index $i$. Then for every $\varepsilon>0$ there exist $m \in \mathbb{N}$ and a nonempty open set $W \subset X$ with the following properties: For every $x \in W$ and every pair of subspaces $E \subset \mathbb{E}(x)$ and $F \subset \mathbb{E}\left(T^{m} x\right)$ with respective dimensions $i$ and $d-i$, there exists a sequence of linear maps

$$
\mathbb{E}(x) \xrightarrow{L_{0}} \mathbb{E}(T x) \xrightarrow{L_{1}} \cdots \xrightarrow{L_{m-1}} \mathbb{E}\left(T^{m} x\right)
$$

with $\left\|L_{j}-A\left(T^{j} x\right)\right\|<\varepsilon$ for each $j$ and such that

$$
L_{m-1} \cdots L_{0}(E) \cap F \neq\{0\} .
$$

For the proof, we will need the following standard result, which can be shown by the same arguments as in the proof of [BV, Prop. 7.1].

Lemma 3.4. For any $C>0$ and $\alpha>0$, there exists $k \in \mathbb{N}$ with the following properties. If $L_{0}, L_{1}, \ldots, L_{k-1} \in \mathrm{GL}(d, \mathbb{R})$ satisfy $\left\|L_{k}^{ \pm 1}\right\| \leq C$, and $v, w \in \mathbb{R}^{d}$ are nonzero vectors such that

$$
\frac{\left\|L_{k-1} \cdots L_{0} w\right\| /\|w\|}{\left\|L_{k-1} \cdots L_{0} v\right\| /\|v\|}>\frac{1}{2}
$$

then there exist nonzero vectors $u_{0}, u_{1}, \ldots, u_{k} \in \mathbb{R}^{d}$ such that $u_{0}=v$,

$$
\begin{aligned}
u_{k}=L_{k-1} \cdots & L_{0}(w), \text { and } \\
& \measuredangle\left(u_{j+1}, L_{j}\left(u_{j}\right)\right)<\alpha \quad \text { for each } j=0, \ldots, k-1
\end{aligned}
$$

Proof of Lemma 3.3. Suppose $A \in \operatorname{Aut}(\mathbb{E}, T)$ has no dominated splitting of index $i$. Let $\varepsilon>0$ be given. Let $C>1$ be such that $\left\|A(x)^{ \pm 1}\right\| \leq C$ for all $x \in X$. Fix a positive $\alpha \ll \varepsilon$, and let $k=k(C, \alpha) \in \mathbb{N}$ be given by Lemma 3.4. Define open sets

$$
W(m):=\left\{x \in M ; \frac{\mathfrak{s}_{i+1}\left(A^{m}(x)\right)}{\mathfrak{s}_{i}\left(A^{m}(x)\right)}>C^{2 k}(1 / 2)^{m / k-1}\right\}
$$

Notice that if $W(m)=\emptyset$ for all sufficiently large $m$, then by Theorem 3.2 there is a dominated splitting of index $i$, contradicting the hypothesis. Therefore we can fix $m>k$ such that $W=W(m) \neq \emptyset$.

Now fix a point $x \in W$ and spaces $E \subset \mathbb{E}(x), F \subset \mathbb{E}\left(T^{m} x\right)$ with respective dimensions $i$ and $d-i$. For simplicity, write $P=A^{m}(x)$.

Claim 3.5. There exist unit vectors $v \in E$ and $w \in P^{-1}(F)$ such that $\|P v\| \leq \mathfrak{s}_{i}(P)$ and $\|P w\| \geq \mathfrak{s}_{i+1}(P)$.

Proof of the claim. Let $\left\{e_{1}, \ldots, e_{d}\right\}$ be a basis of $\mathbb{E}(x)$ formed by eigenvectors of $\left(P^{*} P\right)^{1 / 2}$ corresponding to the eigenvalues $\mathfrak{s}_{1}(P) \geq \cdots \geq \mathfrak{s}_{d}(P)$. Let $\tilde{E}$ be the space spanned by $e_{i}, \ldots, e_{d}$. Since $\operatorname{dim} E=i$, the intersection $E \cap \tilde{E}$ contains a unit vector $v$. Then $\|P v\| \leq \mathfrak{s}_{i}(P)$, proving the first part of the claim. The proof of the second part is analogous.

Claim 3.6. There exists $\ell$ with $0 \leq \ell<m-k$ such that

$$
\frac{\left\|A^{k+\ell}(x) \cdot w\right\| /\left\|A^{\ell}(x) \cdot w\right\|}{\left\|A^{k+\ell}(x) \cdot v\right\| /\left\|A^{\ell}(x) \cdot v\right\|}>\frac{1}{2}
$$

Proof of the claim. Assume the contrary. Then

$$
\frac{\mathfrak{s}_{i+1}(P)}{\mathfrak{s}_{i}(P)} \leq \frac{\|P w\|}{\|P v\|} \leq\left(\frac{1}{2}\right)^{\lfloor m / k\rfloor} C^{2 k}
$$

which contradicts the fact that $x \in W$.
Next we apply Lemma 3.4 to the vectors $\tilde{v}=A^{\ell}(x) \cdot v, \tilde{w}=A^{\ell}(x) \cdot w$ and the linear maps $\tilde{L}_{0}=A\left(T^{\ell} x\right), \ldots, \tilde{L}_{k-1}=A\left(T^{\ell+k-1} x\right)$. We obtain nonzero vectors $u_{0}, \ldots, u_{k}$ such that $u_{0}=v, u_{k}=A^{\ell+k}(x) \cdot w$, and $\measuredangle\left(u_{j+1}, A\left(T^{\ell+j} x\right) \cdot u_{j}\right)<\alpha$ for each $j=0, \ldots, k-1$.

To conclude the proof, we need to define the linear maps $L_{0}, \ldots, L_{m-1}$. Since $\alpha$ is small, for each $j=0, \ldots, k-1$ we can find an $\varepsilon$-perturbation $L_{\ell+j}$ of $A\left(T^{\ell+j} x\right)$ such that $L_{j}\left(u_{j}\right)$ and $u_{j+1}$ are collinear. We define the remaining maps as

$$
L_{j}=A\left(T^{j} x\right) \quad \text { if } 0 \leq j \leq \ell \text { or } \ell+k \leq j \leq m
$$

Then $L_{m-1} \cdots L_{0}(v)$ is collinear to $A^{m}(w)$. This proves Lemma 3.3.

The next lemma indicates how the perturbations provided by Lemma 3.3 can be used to manipulate singular values. For simplicity of notation, we state the lemma in terms of matrices instead of bundle maps.

Lemma 3.7. Let $P, Q \in \mathrm{GL}(d, \mathbb{R})$ and $i \in\{1, \ldots, d-1\}$. Then there are subspaces $E, F \subset \mathbb{R}^{d}$ with respective dimensions $i, d-i$ and with the following property: If $R \in \mathrm{GL}(d, \mathbb{R})$ satisfies $R(E) \cap F \neq\{0\}$, then

$$
\sigma_{i}(Q R P) \leq \sigma_{i}(P)+\sigma_{i}(Q)-2 \min \left\{\gamma_{i}(P), \gamma_{i}(Q)\right\}+c_{d} \max \{1, \log \|R\|\}
$$

where $c_{d}>0$ depends only on $d$.
A similar estimate appears in the proof of [BV, Prop. 4.2].
Proof. Let $P, Q$, and $i$ be given. Fix an orthonormal basis $\left\{e_{1}, \ldots, e_{d}\right\}$ of eigenvectors of $\left(P P^{*}\right)^{1 / 2}$ corresponding to the eigenvalues $\mathfrak{s}_{1}(P), \ldots$, $\mathfrak{s}_{d}(P)$, and let $E$ be the subspace spanned $e_{1}, \ldots, e_{i}$. Analogously, fix an orthonormal basis $\left\{f_{1}, \ldots, f_{d}\right\}$ of eigenvectors of $\left(Q^{*} Q\right)^{1 / 2}$ corresponding to the eigenvalues $\mathfrak{s}_{1}(Q), \ldots, \mathfrak{s}_{d}(Q)$, and let $F$ be the subspace spanned by $f_{i+1}, \ldots, f_{d}$.

Now take $R \in \mathrm{GL}(d, \mathbb{R})$ such that $R(E) \cap F \neq\{0\}$.
Define also $\bar{e}_{j}:=\mathfrak{s}_{j}(P) P^{-1}\left(e_{j}\right)$ and $\bar{f}_{j}:=\left(\mathfrak{s}_{j}(Q)\right)^{-1} Q\left(e_{j}\right)$, for $j=$ $1, \ldots, d$. Then $\left\{\bar{e}_{1}, \ldots, \bar{e}_{d}\right\}$ and $\left\{\bar{f}_{1}, \ldots, \bar{f}_{d}\right\}$ are orthonormal bases formed by eigenvectors of $\left(P^{*} P\right)^{1 / 2}$ and $\left(Q Q^{*}\right)^{1 / 2}$, respectively.

As in the proof of Lemma 2.5, we will use exterior powers. Consider the following subsets of $\bigwedge^{i} \mathbb{R}^{d}$ :

$$
\begin{aligned}
& \mathcal{B}_{0}=\left\{\bar{e}_{j_{1}} \wedge \cdots \wedge \bar{e}_{j_{i}} ; 1 \leq j_{1}<\cdots<j_{i} \leq d\right\} \\
& \mathcal{B}_{1}=\left\{e_{j_{1}} \wedge \cdots \wedge e_{j_{i}} ; 1 \leq j_{1}<\cdots<j_{i} \leq d\right\} \\
& \mathcal{B}_{2}=\left\{f_{j_{1}} \wedge \cdots \wedge e_{j_{i}} ; 1 \leq j_{1}<\cdots<j_{i} \leq d\right\} \\
& \mathcal{B}_{3}=\left\{\bar{f}_{j_{1}} \wedge \cdots \wedge \bar{f}_{j_{i}} ; 1 \leq j_{1}<\cdots<j_{i} \leq d\right\}
\end{aligned}
$$

each endowed with the lexicographical order. These are all orthonormal bases of $\bigwedge^{i} \mathbb{R}^{d}$. We represent the maps $\bigwedge^{i} P, \bigwedge^{i} R, \bigwedge^{i} Q$ as $\binom{d}{i} \times\binom{ d}{i}$ matrices $\mathbf{P}, \mathbf{R}, \mathbf{Q}$ with respect to these bases

$$
\left(\bigwedge^{i} \mathbb{R}^{d}, \mathcal{B}_{0}\right) \xrightarrow{\bigwedge^{i} P}\left(\bigwedge^{i} \mathbb{R}^{d}, \mathcal{B}_{1}\right) \xrightarrow{\bigwedge^{i} R}\left(\bigwedge^{i} \mathbb{R}^{d}, \mathcal{B}_{2}\right) \xrightarrow{\bigwedge^{i} Q}\left(\bigwedge^{i} \mathbb{R}^{d}, \mathcal{B}_{3}\right) .
$$

Then the matrices $\mathbf{P}$ and $\mathbf{Q}$ are diagonal with positive diagonal entries. The largest and second largest entries of $\mathbf{P}$ are respectively

$$
\mathbf{P}_{11}=\mathfrak{s}_{1}(P) \cdots \mathfrak{s}_{i}(P) \quad \text { and } \quad \mathbf{P}_{22}=\mathfrak{s}_{1}(P) \cdots \mathfrak{s}_{i-1}(P) \mathfrak{s}_{i+1}(P)
$$

Analogously, the largest and second largest entries of $\mathbf{Q}$ are respectively

$$
\mathbf{Q}_{11}=\mathfrak{s}_{1}(Q) \cdots \mathfrak{s}_{i}(Q) \quad \text { and } \quad \mathbf{Q}_{22}=\mathfrak{s}_{1}(Q) \cdots \mathfrak{s}_{i-1}(Q) \mathfrak{s}_{i+1}(Q)
$$

## Claim 3.8. $\mathbf{R}_{11}=0$.

Proof of the claim. By assumption, there exists a nonzero vector $w \in$ $E \cap R^{-1}(F)$. Choose $\ell \in\{1, \ldots, i\}$ such that $\left\{e_{1}, \ldots, e_{\ell-1}, w, e_{\ell+1}, \ldots, e_{i}\right\}$ is a basis for $E$. Therefore the first element of the basis $\mathcal{B}_{1}$ is a multiple of $\xi:=e_{1} \wedge \cdots \wedge e_{\ell-1} \wedge w \wedge e_{\ell+1} \wedge \cdots \wedge e_{i}$. We have

$$
\left(\bigwedge^{i} R\right)(\xi)=R\left(e_{1}\right) \wedge \cdots \wedge R\left(e_{\ell-1}\right) \wedge R(w) \wedge R\left(e_{\ell+1}\right) \wedge \cdots \wedge R\left(e_{i}\right)
$$

Write each $R\left(e_{j}\right)$ as a linear combination of vectors $f_{1}, \ldots, f_{d}$, write $R(w)$ (which is in $F$ ) as a linear combination of vectors $f_{i+1}, \ldots, f_{d}$, and substitute in the expression above. We obtain a linear combination of the vectors $f_{j_{1}} \wedge \cdots \wedge f_{j_{i}}$ where $f_{1} \wedge \cdots \wedge f_{i}$ does not appear. This means that the first coordinate of $\left(\bigwedge^{i} R\right)(\xi)$ with respect to the basis $\mathcal{B}_{2}$ is zero. Therefore $\mathbf{R}_{11}=0$.

Now let $\mathbf{M}=\mathbf{Q R P}$, i.e., the matrix that represents $\bigwedge^{i}(Q R P)$ with respect to the bases $\mathcal{B}_{0}$ and $\mathcal{B}_{3}$. Then the norm of $\mathbf{M}$ is $\exp \sigma_{i}(Q R P)$. This norm is comparable to $\max _{\alpha, \beta}\left|\mathbf{M}_{\alpha \beta}\right|$. We estimate each entry as follows:

$$
\left|\mathbf{M}_{\alpha \beta}\right|=\mathbf{Q}_{\alpha \alpha}\left|\mathbf{R}_{\alpha \beta}\right| \mathbf{P}_{\beta \beta} \leq\left|\mathbf{R}_{\alpha \beta}\right| \max \left\{\mathbf{Q}_{11} \mathbf{P}_{22}, \mathbf{Q}_{22} \mathbf{P}_{11}\right\} .
$$

On one hand, $\max _{\alpha, \beta}\left|\mathbf{R}_{\alpha \beta}\right|$ is comparable to $\|\mathbf{R}\|=e^{\sigma_{i}(R)} \leq\|R\|^{i}$. On the other hand,

$$
\begin{aligned}
\log \left(\mathbf{Q}_{11} \mathbf{P}_{22}\right) & =\sigma_{i}(P)+\sigma_{i}(Q)-2 \gamma_{i}(P), \\
\log \left(\mathbf{Q}_{22} \mathbf{P}_{11}\right) & =\sigma_{i}(P)+\sigma_{i}(Q)-2 \gamma_{i}(Q),
\end{aligned}
$$

and so the lemma follows.
3.2. Proof of Main Lemma 3.1. First, let us give an outline of the proof. If the segment $\left\{x, T x, \ldots, T^{n-1} x\right\}$ of the orbit is long, then by minimality it will regularly visit the sets from Lemma 3.3 where the lack of domination is manifest. We will choose a single one of those visits, and then perform a perturbation of the kind given by Lemma 3.3 on a relatively short subsegment, in order to obtain by Lemma 3.7 a drop in one $\sigma_{i}$ value of the long product. We have to ensure that this drop is a significant one.

Similar strategies are used in AB and $[\mathrm{BV}]$. In BV$]$, the short perturbative subsegment is chosen basically halfway along the segment; that this is a suitable position for perturbation is a consequence of the Oseledets theorem. In the minimal $\mathrm{SL}(2, \mathbb{R})$ situation considered in AB , the middle position is not necessarily the most convenient one, but nevertheless it is easy to see that there exists a suitable position that produces a big drop.

The considerations here are more delicate. We actually apply Lemma 3.3 and Lemma 3.7 to the index $i_{0}$ which maximizes the half-gap $\gamma_{i_{0}}\left(A^{n}(x)\right)$ and so is likely to produce a bigger drop in the $\zeta$-area (see Fig. 1). Suppose we
break $A^{n}(x)=Q P$ into left and right unperturbed subsegments (disregarding the short middle term). Similarly to $[\mathrm{AB}$, we choose the breaking point so that $\gamma_{i_{0}}(P) \simeq \gamma_{i_{0}}(Q)$. Then we need to estimate the drop in $\zeta$. By subadditivity, $\sigma_{i}\left(A^{n}(x)\right) \leq \sigma_{i}(P)+\sigma_{i}(Q)$ for each $i$. On the other hand, since the lengths $k$ and $n-k$ of $P$ and $Q$ are big, the values $k^{-1} \zeta(P)$ and $(n-k)^{-1} \zeta(Q)$ are essentially bounded by $Z(A)$. We can assume that for the point $x$ under consideration, the value $n^{-1} \zeta\left(A^{n}(x)\right)$ is already sufficiently close to $Z(A)$, because otherwise no perturbation is needed. It follows that $\zeta\left(A^{n}(x)\right) \simeq \zeta(P)+\zeta(Q)$ and therefore $\sigma_{i}\left(A^{n}(x)\right) \simeq \sigma_{i}(P)+\sigma_{i}(Q)$ for each $i$. This allows us to recover an "Oseledets-like" situation and carry on the estimates easily. The actual argument is more subtle, because in order to prove the Main Lemma we need to consider points $x$ such that $n^{-1} \zeta\left(A^{n}(x)\right)$ is close, but not extremely close, to $Z(A)$. We proceed with the formal proof.

Proof of the Main Lemma. Let $b=b_{d}$ be given by Lemma 2.6, and define

$$
\begin{equation*}
a=a_{d}:=\frac{1}{1+b / 2} \tag{3.1}
\end{equation*}
$$

Let $A \in \operatorname{Aut}(\mathbb{E}, T)$ be without nontrivial dominated splitting, and let $\varepsilon>0$. Take a positive number $\delta \ll \varepsilon$; how small it needs to be will become apparent along the proof.

For each $i=1, \ldots, d-1$, we apply Lemma 3.3 and thus obtain an integer $m_{i}$ and a nonempty open set $W_{i} \subset X$ with the following property: along segments of orbits of length $m_{i}$ starting from $W_{i}$, we can $\varepsilon$-perturb the linear maps in order to make any given $i$-dimensional space intersect any given $(d-i)$-dimensional space.

Since $T$ is minimal, there exists $m^{\prime} \in \mathbb{N}$ such that

$$
\begin{equation*}
\bigcup_{j=0}^{m^{\prime}} T^{j}\left(W_{i}\right)=X \quad \text { for each } i=1, \ldots, d-1 \tag{3.2}
\end{equation*}
$$

Let also $m^{\prime \prime} \in \mathbb{N}$ be such that

$$
\begin{equation*}
j \geq m^{\prime \prime} \Rightarrow \zeta\left(A^{j}(y)\right)<(Z(A)+\delta) j, \forall y \in X \tag{3.3}
\end{equation*}
$$

Take

$$
\begin{equation*}
N \geq \delta^{-1} \max \left\{m_{1}, \ldots, m_{d-1}, m^{\prime}, m^{\prime \prime}\right\} \tag{3.4}
\end{equation*}
$$

Fix any point $x \in X$ and any $n \geq N$. We can assume that

$$
\begin{equation*}
\frac{1}{n} \zeta\left(A^{n}(x)\right) \geq a Z(A) \tag{3.5}
\end{equation*}
$$

because otherwise the unperturbed maps $L_{j}=A\left(T^{j}(x)\right)$ satisfy the conclusion of the Main Lemma.

Let $i_{0} \in\{1, \ldots, d-1\}$ be such that $\gamma_{i_{0}}\left(A^{n}(x)\right)=\max _{i} \gamma_{i}\left(A^{n}(x)\right)$. Thus, by Lemma 2.6 ,

$$
\begin{equation*}
\gamma_{i_{0}}\left(A^{n}(x)\right) \geq b \zeta\left(A^{n}(x)\right) \tag{3.6}
\end{equation*}
$$

Let us write $m_{0}=m_{i_{0}}$, for simplicity. Given an integer $k \in\left[0, n-m_{0}\right]$, we factorize $A^{n}(x)$ as $Q_{k} R_{k} P_{k}$, where

$$
P_{k}:=A^{k}(x), \quad R_{k}:=A^{m_{0}}\left(T^{k} x\right), \quad Q_{k}:=A^{n-k-m_{0}}\left(T^{k+m_{0}} x\right)
$$

In what follows, we will use big O notation; the comparison constants are allowed to depend only on $A$ (and $d$ ).

Claim 3.9. There exists $k \in\left[m^{\prime \prime}, n-m_{0}-m^{\prime \prime}\right]$ such that $T^{k} x \in W_{i_{0}}$ and

$$
\begin{equation*}
\left|\gamma_{i_{0}}\left(P_{k}\right)-\gamma_{i_{0}}\left(Q_{k}\right)\right| \leq O(\delta n) \tag{3.7}
\end{equation*}
$$

Proof of the claim. Notice the following facts:

- $\left|\gamma_{i_{0}}\left(A^{j+1}(x)\right)-\gamma_{i_{0}}\left(A^{j}(x)\right)\right| \leq O(1)$ for every $j$.
- So, letting $\Delta_{j}:=\gamma_{i_{0}}\left(A^{j}(x)\right)-\gamma_{i_{0}}\left(A^{n-j}\left(T^{j} x\right)\right)$, we have $\left|\Delta_{j+1}-\Delta_{j}\right|$ $\leq O(1)$.
- Since $\Delta_{0}=-\Delta_{n}$, there exists $j_{0} \in[0, n]$ such that $\left|\Delta_{j_{0}}\right| \leq O(1)$.
- So there exists $j_{1} \in\left[m^{\prime \prime}, n-m_{0}-m^{\prime \prime}\right]$ such that $\left|\Delta_{j_{1}}\right| \leq O\left(m^{\prime \prime}+m_{0}\right)$.
- So, by (3.2), there exists $k \in\left[m^{\prime \prime}, n-m_{0}-m^{\prime \prime}\right]$ such that $T^{k} x \in W_{i_{0}}$ and $\left|\Delta_{k}\right| \leq O\left(m^{\prime \prime}+m_{0}+m^{\prime}\right)$.

Since the left hand side of (3.7) is $\leq\left|\Delta_{k}\right|+O\left(m_{0}\right)$, the claim follows from (3.4).

Let $k$ be fixed from now on, and write $P=P_{k}, R=R_{k}, Q=Q_{k}$.
Let $E \subset \mathbb{E}\left(T^{k} x\right)$ and $F \subset \mathbb{E}\left(T^{k+m_{0}} x\right)$ be the subspaces with respective dimensions $i_{0}$ and $d-i_{0}$ obtained by applying Lemma 3.7 to the maps $P$ and $Q$. Since $T^{k} x \in W_{i_{0}}$, we can apply Lemma 3.3 and find linear maps $\tilde{L}_{j}: \mathbb{E}\left(T^{k+j} x\right) \rightarrow \mathbb{E}\left(T^{k+j+1} x\right)$ (where $j=0, \ldots, m_{0}-1$ ) each $\varepsilon$-close to the respective $A\left(T^{k+j} x\right)$, whose product $\tilde{R}:=\tilde{L}_{m_{0}-1} \cdots \tilde{L}_{0}$ satisfies $\tilde{R}(E) \cap F \neq\{0\}$. The maps $L_{j}(j=0, \ldots, n-1)$ that we are looking for are $L_{j}=\tilde{L}_{j-k}$ if $k \leq j<k+m_{0}$, and $L_{j}=A\left(T^{j} x\right)$ otherwise. So their product is $L_{n-1} \cdots L_{0}=Q \tilde{R} P$. Notice that $\|\tilde{R}\| \leq O\left(m_{0}\right) \leq O(\delta n)$. Therefore Lemma 3.7 gives

$$
\begin{equation*}
\sigma_{i_{0}}(Q \tilde{R} P) \leq \sigma_{i_{0}}(P)+\sigma_{i_{0}}(Q)-2 \min \left\{\gamma_{i_{0}}(P), \gamma_{i_{0}}(Q)\right\}+O(\delta n) \tag{3.8}
\end{equation*}
$$

To conclude the proof, we need to estimate $\zeta(Q \tilde{R} P)$. Begin by noticing that, as a consequence of (3.3),

$$
\begin{equation*}
\zeta(P)+\zeta(Q) \leq Z(A) n+O(\delta n) \tag{3.9}
\end{equation*}
$$

Also, since $\sigma_{i}(R) \leq O\left(m_{0}\right) \leq O(\delta n)$, subadditivity and additivity give

$$
\sigma_{i}(P)+\sigma_{i}(Q) \begin{cases}\geq \sigma_{i}\left(A^{n}(x)\right)-O(\delta n) & \text { for each } i=1, \ldots, d-1,  \tag{3.10}\\ \leq \sigma_{d}\left(A^{n}(x)\right)+O(\delta n) & \text { for } i=d .\end{cases}
$$

Claim 3.10. The following inequality holds:

$$
\begin{equation*}
\zeta(P)+\zeta(Q)-\zeta\left(A^{n}(x)\right) \geq-\gamma_{i_{0}}(P)-\gamma_{i_{0}}(Q)+\gamma_{i_{0}}\left(A^{n}(x)\right)-O(\delta n) \tag{3.11}
\end{equation*}
$$

REMARK 3.11. Since (3.11) is an important estimate in the proof, it is worthwhile to interpret it geometrically. Consider the concave graphs of $\sigma_{i}\left(A^{n}(x)\right)$ and $\sigma_{i}(P)+\sigma_{i}(Q)$. By (3.10), modulo a small error, the first graph is below the second one and their endpoints meet. The quantities $\gamma_{i_{0}}\left(A^{n}(x)\right)$ and $\gamma_{i_{0}}(P)+\gamma_{i_{0}}(Q)$ are the areas of triangles touching the corresponding graphs, as in Fig. 1. Now, if the first quantity is substantially greater than the second, then concavity forces the existence of a large hole between the two graphs, and therefore the $\zeta$-area of the second graph is substantially larger than the $\zeta$-area of the first one.

Proof of the claim. Since the functions $\gamma_{i_{0}}$ and $\zeta$ are invariant under composition with homotheties, we can assume for simplicity that $\sigma_{d}=0$, i.e., $|\operatorname{det}|=1$, for all the linear maps involved. Notice that for any $L$ with $|\operatorname{det} L|=1$, we have

$$
\zeta(L)+\gamma_{i_{0}}(L)=\sum_{i=1}^{d-1} u_{i} \sigma_{i}(L), \quad \text { where } \quad u_{i}:= \begin{cases}1 & \text { if }\left|i-i_{0}\right|>1 \\ 1 / 2 & \text { if }\left|i-i_{0}\right|=1 \\ 2 & \text { if } i=i_{0}\end{cases}
$$

In particular,

$$
\begin{aligned}
\zeta(P)+\gamma_{i_{0}}(P)+\zeta(Q) & +\gamma_{i_{0}}(Q)-\zeta\left(A^{n}(x)\right)-\gamma_{i_{0}}\left(A^{n}(x)\right) \\
& =\sum_{i=1}^{d-1} u_{i} \underbrace{\left[\sigma_{i}(P)+\sigma_{i}(Q)-\sigma_{i}\left(A^{n}(x)\right)\right]}_{\geq-\delta n(\text { by } \sqrt{3.10})} \geq-d \delta n
\end{aligned}
$$

which completes the proof of (3.11).
Next, we estimate

$$
\begin{array}{rlr}
\gamma_{i_{0}}(P)+\gamma_{i_{0}}(Q) & \geq \gamma_{i_{0}}\left(A^{n}(x)\right)+\zeta\left(A^{n}(x)\right)-\zeta(P)-\zeta(Q)-O(\delta n) \text { by } \\
& \geq(b+1) \zeta\left(A^{n}(x)\right)-\zeta(P)-\zeta(Q)-O(\delta n) & \\
& \geq(b+1) a Z(A) n-Z(A) n-O(\delta n) & \text { by } \\
& =(a b+a-1) Z(A) n-O(\delta n) . &
\end{array}
$$

Therefore, using (3.7),

$$
\begin{aligned}
2 \min \left\{\gamma_{i_{0}}(P), \gamma_{i_{0}}(Q)\right\} & =\gamma_{i_{0}}(P)+\gamma_{i_{0}}(Q)-\left|\gamma_{i_{0}}(P)-\gamma_{i_{0}}(Q)\right| \\
& \geq(a b+a-1) Z(A) n-O(\delta n)
\end{aligned}
$$

Substituting this into (3.8) we obtain

$$
\sigma_{i_{0}}(Q \tilde{R} P) \leq \sigma_{i_{0}}(P)+\sigma_{i_{0}}(Q)-(a b+a-1) Z(A) n+O(\delta n) .
$$

So it follows from (3.10) that

$$
\zeta(Q \tilde{R} P) \leq \zeta(P)+\zeta(Q)-(a b+a-1) Z(A) n+O(\delta n) .
$$

Using (3.9) we obtain

$$
\zeta(Q \tilde{R} P) \leq \underbrace{(2-a b-a)}_{=a(\text { by } \sqrt{3.11})} Z(A) n+\underbrace{O(\delta n)}_{<\varepsilon n} .
$$

This concludes the proof of the Main Lemma.
4. Patching the perturbations. Here we will use Main Lemma 3.1 to prove Lemma 2.9 and therefore the Main Theorem. The arguments are essentially the same as in $\widehat{\mathrm{AB}}$.

To begin, we recall some results from $[\mathrm{AB}]$ on zero probability sets.
Theorem 4.1 ( $\widehat{\mathrm{AB}}$, Lemma 3]). Let $X$ be a compact space of finite dimension, and let $T: X \rightarrow X$ be a homeomorphism without periodic orbits. Then there exists a basis of the topology of $X$ consisting of sets $U$ such that $\partial U$ has zero probability.

This is the only place where we use the assumption that $X$ has finite dimension. (Actually, the proof of the theorem consists in finding sets $U$ such that no point in $X$ visits $\partial U$ more than $\operatorname{dim} X$ times.)

The next result follows from a simple Krylov-Bogoliubov argument:
Lemma 4.2 ( $(\widehat{\mathrm{AB}}$, Lemma 7$])$. Let $T: X \rightarrow X$ be a continuous mapping of a compact space $X$. If $K \subset X$ is a compact set with zero probability then for every $\varepsilon>0$, there exist an open set $V \supset K$ and $n_{*} \in \mathbb{N}$ such that

$$
x \in X, n \geq n_{*} \Rightarrow \#\left\{x, T x, \ldots, T^{n-1} x\right\} \cap V<\varepsilon n .
$$

We also need the following result that decomposes the space into two Rokhlin towers:

Lemma 4.3 ( $\widehat{\mathrm{AB}}$, Lemma 6]). Let $X$ be a nondiscrete compact space, and let $T: X \rightarrow X$ be a minimal homeomorphism. Then for any $N \in \mathbb{N}$, there exists an open set $B \subset X$ such that:

- the return time from $B$ to itself under iterations of $T$ assumes only the values $N$ and $N+1$;
- $\partial B$ has zero probability.

Since we are working with not necessarily trivial vector bundles $\mathbb{E}$, we need to introduce local coordinates.

Let us fix a finite open cover $\left\{\hat{D}_{m}\right\}$ of $X$ by trivializing domains, together with bundle charts $\xi_{m}: \hat{D}_{m} \times \mathbb{R}^{d} \rightarrow \mathbb{E}$. For each $x \in \hat{D}_{m}$, the map $H_{m}(x):=$
$\xi_{m}(x, \cdot)$ is an isomorphism from $\mathbb{R}^{d}$ to $\mathbb{E}(x)$. We can assume that there is a finer cover $\left\{D_{m}\right\}$ of $X$ with $\bar{D}_{m} \subset \hat{D}_{m}$ for each $m$.

It is convenient to fix a constant $C>0$ such that

$$
\begin{equation*}
\left\|\left(H_{m}(x)\right)^{ \pm 1}\right\| \leq C \quad \text { and } \quad \zeta\left(H_{m}(x)\right) \leq C, \quad \forall m, \forall x \in D_{m} \tag{4.1}
\end{equation*}
$$

Any $B \in \operatorname{Aut}(\mathbb{E}, X)$ can be represented in local coordinates by a family of (uniformly continuous) maps $B^{\left(m, m^{\prime}\right)}: X_{m} \cap T^{-1}\left(X_{m^{\prime}}\right) \rightarrow \mathrm{GL}(d, \mathbb{R})$ defined by:

$$
\begin{equation*}
B^{\left(m, m^{\prime}\right)}(x):=\left(H_{m^{\prime}}(T x)\right)^{-1} \circ B(x) \circ H_{m}(x), \quad x \in X_{m} \cap T^{-1}\left(X_{m^{\prime}}\right) \tag{4.2}
\end{equation*}
$$

Let us call this the $\left(m, m^{\prime}\right)$-local representation of $B(x)$.
Now we have all the tools we need to conclude the proof.
Proof of Lemma 2.9. As explained in 2.6 , it is sufficient to consider the particular case where the automorphism $A \in \operatorname{Aut}(\mathbb{E}, T)$ has no nontrivial dominated splitting. If the space $X$ is discrete then it consists of a single periodic orbit, and it follows that $Z(A)=0$. So we can assume that $X$ is nondiscrete, i.e., $T$ has no periodic orbits.

Fix $\varepsilon>0$; we can assume that

$$
\begin{equation*}
\varepsilon<\inf _{x \in X} \mathfrak{m}(A(x)) \tag{4.3}
\end{equation*}
$$

As a consequence, if a linear map $L: \mathbb{E}(x) \rightarrow \mathbb{E}(T x)$ has $\|L-A(x)\|<\varepsilon$, then it is invertible; moreover $\zeta(L)$ is bounded by some $C_{0}=C_{0}(A, \varepsilon)$. Let $\varepsilon^{\prime}>0$ be small enough that

$$
\begin{align*}
\left(1+C_{0}\right) \varepsilon^{\prime} & <\varepsilon / 3  \tag{4.4}\\
C^{2}\left(C^{2}+1\right) \varepsilon^{\prime} & <\varepsilon \tag{4.5}
\end{align*}
$$

where $C$ is as in 4.1. Let $N=N\left(A, \varepsilon^{\prime}\right) \in \mathbb{N}$ be given by Main Lemma 3.1. We can assume that $N$ is large enough that

$$
\begin{equation*}
2 C / N<\varepsilon / 3 \tag{4.6}
\end{equation*}
$$

Recall that $\left\{D_{m}\right\}$ is a cover of $X$ by trivializing domains. By uniform continuity of the local representations (4.2), there exists $\rho>0$ such that

$$
\begin{equation*}
x, y \in D_{m} \cap T^{-1}\left(D_{m^{\prime}}\right), d(x, y)<\rho \Rightarrow\left\|A^{\left(m, m^{\prime}\right)}(x)-A^{\left(m, m^{\prime}\right)}(y)\right\|<\varepsilon^{\prime} \tag{4.7}
\end{equation*}
$$

Choose an open cover $\left\{W_{i}\right\}_{i=1, \ldots, k}$ of $X$ with the following properties:

- it refines the cover $\left\{D_{m_{0}} \cap T^{-1}\left(D_{m_{1}}\right) \cap \cdots \cap T^{-N-1}\left(D_{m_{N+1}}\right)\right\}_{m_{0}, \ldots, m_{N+1}}$;
- $\operatorname{diam} T^{j}\left(W_{i}\right)<\rho$ for each $i=1, \ldots, k$ and $j=0,1, \ldots, N+1$;
- the sets $\partial W_{i}$ have zero probability.
(To guarantee the last requirement we use Theorem 4.1.) For each $i=$ $1, \ldots, k$ and each $j=0,1, \ldots, N+1$, we fix an index $m(i, j)$ such that $T^{j}\left(W_{i}\right) \subset D_{m(i, j)}$.

Let $B$ be the set given by Lemma 4.3. Let $B_{\ell}$ be the set of points in $B$ whose first return to $B$ occurs in time $\ell$. Then $B_{N}=B \cap T^{-N}(B)$ and $B_{N+1}=B \backslash B_{N}$, and in particular $\partial B_{\ell}$ has zero probability. Let

$$
\begin{aligned}
& B_{\ell, i}:=B_{\ell} \cap W_{i} \backslash\left(W_{1} \cup \ldots \cup W_{i-1}\right) \\
& \quad \text { for each }(\ell, i) \in\{N, N+1\} \times\{1, \ldots, k\} .
\end{aligned}
$$

Let $I$ be the set of pairs $(\ell, i)$ such that $B_{\ell, i} \neq \emptyset$. Let also $J$ be the set of $(\ell, i, j)$ such that $(\ell, i) \in I$ and $0 \leq j \leq \ell-1$. For each $\alpha=(\ell, i, j) \in J$, let $X_{\alpha}:=T^{j}\left(B_{\ell, i}\right)$. Notice that $\left\{X_{\alpha}\right\}_{\alpha \in J}$ is a finite partition of $X$. Moreover, each $\partial X_{\alpha}$ has zero probability, and so by Lemma 4.2 there exist an open set $V \supset \bigcup_{\alpha \in J} \partial X_{\alpha}$ and $n_{*} \in \mathbb{N}$ such that

$$
\begin{equation*}
x \in X, n \geq n_{*} \Rightarrow \#\left\{x, T x, \ldots, T^{n-1} x\right\} \cap V<\frac{\varepsilon^{\prime} n}{N+1} . \tag{4.8}
\end{equation*}
$$

For each $(\ell, i) \in I$, choose $y_{\ell, i} \in B_{\ell, i}$. For each $j=0,1, \ldots, \ell$, let $y_{\ell, i, j}:=T^{j}\left(y_{\ell, i}\right)$. Applying Main Lemma 3.1, we find $L_{\ell, i, 0}, \ldots, L_{\ell, i, \ell-1}$ so that

$$
\begin{align*}
\left\|L_{\ell, i, j}-A\left(y_{\ell, i, j}\right)\right\| & <\varepsilon^{\prime} \quad \forall j=0,1, \ldots, \ell-1, \text { and }  \tag{4.9}\\
\zeta\left(L_{\ell, i, \ell-1} \cdots L_{\ell, i, 0}\right) & <\left(a Z(A)+\varepsilon^{\prime}\right) \ell \tag{4.10}
\end{align*}
$$

where $a=a_{d} \in(0,1)$ is a constant.
For each $\alpha=(\ell, i, j) \in J$, let $\left\{\tilde{A}_{\alpha}(x): \mathbb{E}(x) \rightarrow \mathbb{E}(T x)\right\}_{x \in X_{\alpha}}$ be the family of linear maps uniquely characterized by the following properties:

- $\tilde{A}_{\alpha}\left(y_{\alpha}\right)=L_{\alpha}$;
- letting $m=m(i, j)$ and $m^{\prime}=m(i, j+1)$, the local representation $\tilde{A}_{\alpha}^{\left(m, m^{\prime}\right)}(x)$ does not depend on $x \in X_{\alpha}$.
It follows from (4.9) and (4.1) that

$$
\left\|\tilde{A}_{\alpha}^{\left(m, m^{\prime}\right)}\left(y_{\alpha}\right)-A_{\alpha}^{\left(m, m^{\prime}\right)}\left(y_{\alpha}\right)\right\|<C^{2} \varepsilon^{\prime} .
$$

So, by 4.7),

$$
\left\|\tilde{A}_{\alpha}^{\left(m, m^{\prime}\right)}\left(y_{\alpha}\right)-A_{\alpha}^{\left(m, m^{\prime}\right)}(x)\right\|<\left(C^{2}+1\right) \varepsilon^{\prime} \quad \text { for all } x \in X_{\alpha} .
$$

It follows that

$$
\begin{equation*}
\left\|\tilde{A}_{\alpha}(x)-A(x)\right\|<\underbrace{\left.C^{2}\left(C^{2}+1\right) \varepsilon^{\prime}\right)}_{<\varepsilon(\text { by }} \quad \text { for all } x \in X_{\alpha} . \tag{4.11}
\end{equation*}
$$

For every $x \in B_{\ell, i}$, the products

$$
\tilde{A}_{\ell, i, \ell-1}\left(T^{\ell-1} x\right) \cdots \tilde{A}_{\ell, i, 0}(x) \quad \text { and } \quad L_{\ell, i, \ell-1} \cdots L_{\ell, i, 0}
$$

have the same $(m(i, 0), m(i, \ell))$-local representation. It follows from 4.10) and (4.1) that

$$
\begin{equation*}
x \in B_{\ell, i} \Rightarrow \zeta\left(\tilde{A}_{\ell, i, \ell-1}\left(T^{\ell-1} x\right) \cdots \tilde{A}_{\ell, i, 0}(x)\right)<\left(a Z(A)+\varepsilon^{\prime}\right) \ell+2 C . \tag{4.12}
\end{equation*}
$$

Now consider the open cover $\{V\} \cup\left\{\operatorname{int} X_{\alpha}\right\}_{\alpha \in J}$ of $X$. Since $X$ is compact Hausdorff, we can find a continuous partition of unity $\{\psi\} \cup\left\{\varphi_{\alpha}\right\}_{\alpha \in J}$ subordinate to this cover. For each $x \in X$, define a linear map $\tilde{A}(x): \mathbb{E}(x) \rightarrow \mathbb{E}(T x)$ by

$$
\tilde{A}(x):=\psi(x) A(x)+\sum_{\alpha \in J} \varphi_{\alpha}(x) \tilde{A}_{\alpha}(x)
$$

By (4.11), we have $\|\tilde{A}(x)-A(x)\|<\varepsilon$, and it follows from (4.3) that $\tilde{A}(x)$ is invertible. Thus $\tilde{A} \in \operatorname{Aut}(\mathbb{E}, T)$. Also, $\zeta(\tilde{A}(x)) \leq C_{0}$ for every $x$.

Take $n$ large enough so that

$$
\begin{equation*}
n \geq n_{*} \quad \text { and } \quad 2 C_{0} N<(\varepsilon / 3) n \tag{4.13}
\end{equation*}
$$

We will give a uniform upper bound for $\zeta\left(\tilde{A}^{n}(x)\right)$. Fix $x \in X$ and write

$$
n=p+\ell_{1}+\cdots+\ell_{r}+q
$$

in such a way that the points

$$
x_{1}=T^{p}(x), x_{2}=T^{p+\ell_{1}}(x), \ldots, x_{r+1}=T^{p+\ell_{1}+\cdots+\ell_{r}}(x)
$$

are exactly the points in the orbit segment $x, T(x), \ldots, T^{n-1}(x)$ that belong to $B$. Then $p, q \in[0, N]$ and $\ell_{1}, \ldots, \ell_{r} \in[N, N+1]$.

The points $x_{j}$ such that $j \neq r+1$ and $\left\{x_{j}, T x_{j}, \ldots, T^{\ell_{j}-1} x_{j}\right\} \cap V=\emptyset$ will be called good. By subadditivity,

$$
\zeta\left(\tilde{A}^{n}(x)\right) \leq \sum_{x_{j} \text { is good }} \zeta\left(\tilde{A}^{\ell_{j}}\left(x_{j}\right)\right)+C_{0}\left(n-\sum_{x_{j} \text { is good }} \ell_{j}\right)
$$

Notice the following estimates:

- If $x_{j}$ is good then $\zeta\left(\tilde{A}^{\ell_{j}}\left(x_{j}\right)\right)$ is less than the right hand side of 4.12) with $\ell=\ell_{j}$.
- There are at most $r \leq N^{-1} n$ good points.
- By 4.8), the number in large brackets is at most $2 N+\varepsilon^{\prime} n$; equality may only hold in case each segment

$$
\left\{x_{j}, T x_{j}, \ldots, T^{\ell_{j}-1} x_{j}\right\} \quad(\text { for } j=1, \ldots, r)
$$

contains at most one point of $V$.
Then we obtain

$$
\zeta\left(\tilde{A}^{n}(x)\right) \leq\left(a Z(A)+\varepsilon^{\prime}\right) n+2 C N^{-1} n+C_{0}\left(2 N+\varepsilon^{\prime} n\right)
$$

Using (4.4), 4.6), and 4.13, we conclude that $\zeta\left(\tilde{A}^{n}(x)\right)<(a Z(A)+\varepsilon) n$. So $Z(\tilde{A})<a Z(A)+\varepsilon$, as we wanted to prove.

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