

The minimal displacement problem in subspaces of the space of continuous functions of finite codimension

by

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Abstract. We show that every subspace of finite codimension of the space $C[0, 1]$ is extremal with respect to the minimal displacement problem.

1. Introduction. In 1930 Schauder [14] proved that convex and compact subsets of Banach spaces have the fixed point property (fpp for short) for continuous mappings. Kakutani [10] was probably the first to give examples of bounded, closed and convex subsets in infinite-dimensional Banach spaces without fpp for continuous (even lipschitzian) mappings. Much stronger results concerning the failure of Schauder's theorem have been obtained by Klee [11], Nowak [13], Benyamini and Sternfeld [3] and Sternfeld and Lin [12].

In 1973 Goebel [8] introduced the notion of minimal displacement. Let C be a bounded, closed and convex subset of an infinite-dimensional Banach space X , and let $T : C \rightarrow C$. The *minimal displacement* of T is the number

$$d_T = \inf\{\|x - Tx\| : x \in C\}.$$

Goebel showed that d_T can be positive for lipschitzian mappings and he proved a basic property of the minimal displacement for lipschitzian mappings:

$$d_T \leq (1 - 1/k)r(C) \quad \text{for } k \geq 1,$$

where

$$r(C) = \inf\{\sup\{\|x - y\| : y \in C\} : x \in C\}$$

is the Chebyshev radius of C and k is a Lipschitz constant of T . There are some spaces and sets for which $d_T = (1 - 1/k)r(C)$. Goebel also introduced the so called *minimal displacement characteristic* of X . This is a function

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defined for $k \geq 1$ as

$$\psi_X(k) = \sup\{d_T : T : B \rightarrow B, T \in L(k)\},$$

where B is the closed unit ball in X and $L(k)$ denotes the class of lipschitzian mappings with constant k . It is known that

$$\psi_X(k) \leq 1 - 1/k$$

for any space X . There exist some "extremal" spaces for which $\psi_X(k) = 1 - 1/k$. Examples of such spaces are $C[0, 1], c_0$ and some others [9]. We show that the class of extremal spaces contains all subspaces of $C[0, 1]$ of finite codimension.

Such spaces are also important because of the retraction problem. It is known that in every infinite-dimensional Banach space there exists a lipschitzian retraction $R : B \rightarrow S$, where S denotes the unit sphere (see [3], [13]). But it is still an open problem to find a minimal Lipschitz constant of such a retraction for a given infinite-dimensional Banach space X . Some authors constructed lipschitzian retraction of the unit ball onto the unit sphere with relatively small Lipschitz constant using lipschitzian mappings with positive displacement (see [7], [5], [6] and [1]). Using such methods, the best known upper bound of the retraction constant is in "extremal spaces".

2. Results. We start with two technical lemmas [4].

LEMMA 1. *For every $k > 1$ there exists a mapping $T : B \rightarrow S$ of class $L(k)$ with $d_T = 1 - 1/k$ and such that*

$$(Tx)(0) = -1 \quad \text{and} \quad (Tx)(1) = 1$$

for every $x \in B$.

Proof. Define $T_1 : B \rightarrow C[0, 1]$ by $(T_1x)(t) = x(t) + 4t - 2$ and $T : B \rightarrow S$ by $(Tx)(t) = f((T_1x)(t))$, where the function $f : \mathbb{R} \rightarrow [-1, 1]$ is given for positive k as

$$f(t) = \begin{cases} -1 & \text{if } t \in (-\infty, -1/k), \\ kt & \text{if } t \in [-1/k, 1/k], \\ 1 & \text{if } t \in (1/k, \infty). \end{cases}$$

The mapping T_1 is nonexpansive and the function f is lipschitzian with constant k , which implies that $T \in L(k)$. Observe that $(Tx)(0) = -1$ and $(Tx)(1) = 1$ for every $x \in B$. Moreover, if $(T_1x)(1/2) \geq 0$, then from the condition $(T_1x)(0) \leq -1$ for every $x \in B$ we infer that there exists $t_0 \in (0, 1/2)$ such that $(T_1x)(t_0) = -1/k$. From this equality we obtain

$$x(t_0) > (T_1x)(t_0) = -1/k > -1 = (Tx)(t_0),$$

which implies $\|x - Tx\| > 1 - 1/k$. Analogously if $(T_1x)(1/2) < 0$, the condition $(T_1x)(1) \geq 1$ implies that there exists $t_1 \in (1/2, 1)$ for which

$(T_1x)(t_1) = 1/k$. This yields

$$x(t_1) < (T_1x)(t_1) = 1/k < 1 = (Tx)(t_1),$$

and further $\|x - Tx\| > 1 - 1/k$. This combined with the basic property of the minimal displacement implies that $d_T = 1 - 1/k$, which ends the proof. ■

REMARK 2. From the above proof we conclude that the infimum in the definition of the minimal displacement is not attained for any $x \in B$.

REMARK 3. For $k = 1$ the map T will be given by

$$(Tx)(t) = \max\{-1, \min\{1, (T_1x)(t)\}\}.$$

This map is fixed point free because $(Tx)(t) > x(t)$ for some $t > 1/2$ or $(Tx)(t) < x(t)$ for some $t < 1/2$.

From Lemma 1 and the two remarks above, and from the fact that the spaces $C[\alpha, \beta]$ and $C[0, 1]$ are isometric, we deduce the following lemma.

LEMMA 4. *Let $0 \leq \alpha < \beta \leq 1$. Then for every $k \geq 1$ there exists a mapping $T_{[\alpha, \beta]} : B \rightarrow S$ of class $L(k)$ such that for every $x \in B$,*

$$(T_{[\alpha, \beta]}x)(t) = 0 \quad \text{for every } t \in [0, \alpha] \cup [\beta, 1]$$

and

$$\max_{t \in [\alpha, \beta]} |x(t) - (T_{[\alpha, \beta]}x)(t)| > 1 - 1/k.$$

Proof. If $0 < \alpha < \beta < 1$ we choose $\alpha < \gamma < \delta < \beta$ and apply Lemma 1 to the space $C[\gamma, \delta]$. Then there exists a map $\bar{T} : B_{C[\gamma, \delta]} \rightarrow S_{C[\gamma, \delta]}$ of class $L(k)$ such that

$$\max_{t \in [\gamma, \delta]} |x(t) - (\bar{T}x)(t)| > 1 - 1/k, \quad (\bar{T}x)(\gamma) = -1 \quad \text{and} \quad (\bar{T}x)(\delta) = 1$$

for every $x \in B_{C[\gamma, \delta]}$. Now we can define $T_{[\alpha, \beta]} : B \rightarrow S$ by $(T_{[\alpha, \beta]}x)(t) = (\bar{T}x)(t)$ if $t \in [\gamma, \delta]$, $(T_{[\alpha, \beta]}x)(t) = 0$ for any $t \in [0, \alpha] \cup [\beta, 1]$, and on the intervals (α, γ) and (δ, β) we define $T_{[\alpha, \beta]}$ as an affine map so as to obtain a continuous map. It is easy to check that this map satisfies the desired conditions. If $\alpha = 0$ or $\beta = 1$ then the proof is very similar. For instance if $\alpha = 0$ and $\beta < 1$ we define $(T_{[\alpha, \beta]}x)(\alpha) = 0$ and on the intervals (α, γ) , $[\gamma, \delta]$, (δ, β) and $[\beta, 1]$ we define $T_{[\alpha, \beta]}$ as in the case $0 < \alpha < \beta < 1$. ■

After these technical lemmas we consider the minimal displacement problem in subspaces of codimension one of $C[0, 1]$. From the Riesz Theorem it is known that each such subspace can be written as

$$C_\mu[0, 1] = \left\{ x \in C[0, 1] : \int_{[0, 1]} x d\mu = 0 \right\},$$

where μ is bounded, real Borel signed measure on $[0, 1]$. Let $\mu = \mu^+ - \mu^-$ be the Jordan decomposition of μ .

THEOREM 5. *Let $C_\mu[0, 1]$ be a subspace of $C[0, 1]$ of codimension one. Then for every $0 \leq \alpha < \beta \leq 1$ and $k \geq 1$ there exists a mapping $T : B \rightarrow S$ of class $L(k)$ such that for every $x \in B$,*

$$(Tx)(t) = 0 \quad \text{for } t \in [0, \alpha] \cup [\beta, 1]$$

and

$$\max_{t \in [\alpha, \beta]} |x(t) - (Tx)(t)| > 1 - 1/k.$$

Proof. Let $0 \leq \alpha < \beta \leq 1$ and let $|\mu|$ denote the absolute value of the measure μ , i.e. $|\mu| = \mu^+ + \mu^-$. We consider two cases.

(i) If there exists an interval $[c, d] \subset [\alpha, \beta]$ such that $|\mu|([c, d]) = 0$, then we define $T = T_{[c, d]}$ (see Lemma 4).

(ii) If (i) does not hold then $|\mu|([a, b]) \neq 0$ for any subinterval $[a, b]$ of $[\alpha, \beta]$. This implies that there exists $[a, b] \subset (\alpha, \beta)$ such that $\mu([a, b]) \neq 0$. Without loss of generality we can assume that $\mu([a, b]) > 0$. Observe that it is possible to find an interval $[c, d] \subset (\alpha, \beta)$ disjoint from $[a, b]$ and such that $|\mu|([c, d]) < \mu([a, b])$. Let $T_{[c, d]}$ satisfy the conditions of Lemma 4. Proceeding to the second part of the construction observe that there exists $\delta > 0$ for which $[a - \delta, b + \delta]$ is contained in (α, β) and disjoint from $[c, d]$ and the following condition holds:

$$\begin{aligned} |\mu|([a - \delta, a] \cup (b, b + \delta] \cup [c, d]) \\ = |\mu|([a - \delta, a]) + |\mu|((b, b + \delta]) + |\mu|([c, d]) < \mu([a, b]). \end{aligned}$$

Now for $h \in [-1, 1]$ consider a mapping $d_h : [0, 1] \rightarrow [-1, 1]$ defined as: $d_h(t) = h$ if $t \in [a, b]$, and $d_h(t) = 0$ if $t \notin [a - \delta, b + \delta]$. On $[a - \delta, a]$ and $(b, b + \delta]$ we define d_h as an affine map so that the function d_h is continuous. For the function x and $h \in [-1, 1]$ let us consider the expression

$$\begin{aligned} I(h) &= \int_0^1 ((T_{[c, d]}x)(t) + d_h(t)) d\mu(t) \\ &= \int_{[a - \delta, a]} d_h(t) d\mu(t) + h\mu([a, b]) + \int_{(b, b + \delta]} d_h(t) d\mu(t) \\ &\quad + \int_{[c, d]} (T_{[c, d]}x)(t) d\mu(t). \end{aligned}$$

Observe that for $h = -1$ we have

$$I(-1) \leq |\mu|([a - \delta, a]) - \mu([a, b]) + |\mu|((b, b + \delta]) + |\mu|([c, d]) < 0.$$

Analogously for $h = 1$ we get

$$I(1) \geq -|\mu|([a - \delta, a]) + \mu([a, b]) - |\mu|((b, b + \delta]) - |\mu|([c, d]) > 0.$$

Thus there exists a constant $h = h_x$ for which $I(h_x) = 0$, which means that $d_{h_x} + T_{[c, d]}x \in C_\mu[0, 1]$. We prove that the notation $h = h_x$ is justified, i.e.

the constant h for which $I(h) = 0$ is unique. Suppose that $I(h_1) = I(h_2) = 0$ for $h_1 \neq h_2$. Then

$$\int_{[0,1]} d_{h_1}(t) d\mu(t) = \int_{[0,1]} d_{h_2}(t) d\mu(t),$$

which means that

$$\int_{[a-\delta,a)\cup(b,b+\delta]} d_{h_1}(t) d\mu(t) + h_1\mu([a, b]) = \int_{[a-\delta,a)\cup(b,b+\delta]} d_{h_2}(t) d\mu(t) + h_2\mu([a, b]).$$

This leads to a contradiction:

$$\begin{aligned} |h_1 - h_2|\mu([a, b]) &= \left| \int_{[a-\delta,a)\cup(b,b+\delta]} (d_{h_1}(t) - d_{h_2}(t)) d\mu(t) \right| \\ &\leq \int_{[a-\delta,a)\cup(b,b+\delta]} |d_{h_1}(t) - d_{h_2}(t)| d\mu(t) \\ &\leq |h_1 - h_2| \mu([a - \delta, a) \cup (b, b + \delta]) \\ &< |h_1 - h_2|\mu([a, b]). \end{aligned}$$

Now we can define a map $T : B \rightarrow S$ by

$$Tx = d_{h_x} + T_{[c,d]}x.$$

Observe that indeed $\|Tx\| = 1$ for any $x \in B$ because $\|T_{[c,d]}x\| = 1$ and $\text{supp } d_h \cap \text{supp } T_{[c,d]} = \emptyset$.

We show that $T \in L(k)$. Observe that it is sufficient to show that $Dx := d_{h_x} \in L(k)$ (because $\text{supp } d_h \cap \text{supp } T_{[c,d]} = \emptyset$). It is easy to see that $\|Dx - Dy\| = |h_x - h_y|$. Suppose that $D \notin L(k)$. Then there exist $x, y \in B$ and a constant $k_1 > k$ such that $\|Dx - Dy\| = k_1\|x - y\|$. Recall that for all $x, y \in B$ we have

$$\int_{[0,1]} ((Dx)(t) + (T_{[c,d]}x)(t)) d\mu(t) = \int_{[0,1]} ((Dy)(t) + (T_{[c,d]}y)(t)) d\mu(t) = 0.$$

This can be written equivalently as

$$\begin{aligned} \int_{[a-\delta,a)\cup(b,b+\delta]} Dx d\mu + \int_{[c,d]} T_{[c,d]}x d\mu + h_x\mu([a, b]) \\ = \int_{[a-\delta,a)\cup(b,b+\delta]} Dy d\mu + \int_{[c,d]} T_{[c,d]}y d\mu + h_y\mu([a, b]), \end{aligned}$$

which implies

$$\begin{aligned} |h_x\mu([a, b]) - h_y\mu([a, b])| \\ = \left| \int_{[a-\delta,a)\cup(b,b+\delta]} (Dx - Dy) d\mu + \int_{[c,d]} (T_{[c,d]}x - T_{[c,d]}y) d\mu \right|. \end{aligned}$$

We obtain

$$\begin{aligned} |h_x\mu([a, b]) - h_y\mu([a, b])| &= |h_x - h_y|\mu([a, b]) \\ &= \mu([a, b])\|Dx - Dy\| \\ &= k_1\mu([a, b])\|x - y\|, \end{aligned}$$

and on the other hand

$$\begin{aligned} &\left| \int_{[a-\delta, a] \cup (b, b+\delta]} (Dx - Dy) d\mu + \int_{[c, d]} (T_{[c, d]}x - T_{[c, d]}y) d\mu \right| \\ &\leq \int_{[a-\delta, a] \cup (b, b+\delta]} \|Dx - Dy\| d|\mu| + \int_{[c, d]} \|T_{[c, d]}x - T_{[c, d]}y\| d|\mu| \\ &\leq k_1|\mu|([a - \delta, a] \cup (b, b + \delta])\|x - y\| + k|\mu|([c, d])\|x - y\| \\ &< k_1\mu([a, b])\|x - y\|. \end{aligned}$$

This contradiction shows that $D \in L(k)$.

Finally, observe that

$$\max_{t \in [\alpha, \beta]} |x(t) - (Tx)(t)| \geq \max_{t \in [c, d]} |x(t) - (T_{[c, d]}x)(t)| > 1 - 1/k. \blacksquare$$

Now we generalize this theorem to all subspaces of $C[0, 1]$ of finite codimension. Recall that each such subspace can be written as

$$C_{\mu_1, \dots, \mu_n}[0, 1] = \left\{ x \in C[0, 1] : \int_{[0, 1]} x d\mu_i = 0, i = 1, \dots, n \right\},$$

where the μ_i are independent, bounded real Borel measures on $[0, 1]$.

THEOREM 6. *Let $C_{\mu_1, \dots, \mu_n}[0, 1]$ be a subspace of $C[0, 1]$ of finite codimension. Then for $0 \leq \alpha < \beta \leq 1$ and for any $k \geq 1$ there exists a mapping $T : B \rightarrow S$ of class $L(k)$ such that for every $x \in B$,*

$$(Tx)(t) = 0 \quad \text{for every } t \in [0, \alpha] \cup [\beta, 1]$$

and

$$\max_{t \in [\alpha, \beta]} |x(t) - (Tx)(t)| > 1 - 1/k.$$

Proof. We argue by induction on n . If $n = 1$, then the conclusion is Theorem 5. Now let μ_1, \dots, μ_{n+1} be independent measures on $[0, 1]$. For brevity set, for any $l \in \mathbb{N}$,

$$B_l = B_{C_{\mu_1, \dots, \mu_l}[0, 1]}, \quad S_l = S_{C_{\mu_1, \dots, \mu_l}[0, 1]}.$$

Let $0 \leq \alpha < \beta \leq 1$ and assume that for all γ, δ such that $\alpha < \gamma < \delta < \beta$ there exists a lipschitzian mapping $\bar{T} : B_n \rightarrow S_n$ with constant $k \geq 1$ such that for any $x \in B_n$,

$$(\bar{T}x)(t) = 0 \quad \text{for any } t \in [0, \gamma] \cup [\delta, 1]$$

and

$$\max_{t \in [\gamma, \delta]} |x(t) - (\overline{T}x)(t)| > 1 - 1/k.$$

Let us consider two cases.

(i) There exists an interval $[a, b] \subset (\alpha, \beta)$ such that $\int_{[a, b]} \overline{T}x \, d\mu_{n+1} = 0$ for every $x \in B_{n+1}$. Then we can define $T : B_{n+1} \rightarrow S_{n+1}$ to be \overline{T} , where $\gamma = a, \delta = b$. Observe that $T \in L(k)$ and moreover

$$\max_{t \in [\alpha, \beta]} |x(t) - (Tx)(t)| \geq \max_{t \in [a, b]} |x(t) - (\overline{T}x)(t)| > 1 - 1/k.$$

(ii) If (i) does not hold then there exists an interval $[a, b] \subset (\alpha, \beta)$ and a function $x_0 \in B_{n+1}$ with $\text{supp } \overline{T}x_0 \subset [a, b]$ (it is enough to take $\gamma = a, \delta = b$) such that $\int_{[a, b]} \overline{T}x_0 \, d\mu_{n+1} \neq 0$. Without loss of generality we may assume that $\int_{[a, b]} \overline{T}x_0 \, d\mu_{n+1} > 0$. Now we can choose an interval $[c, d] \subset (\alpha, \beta)$ disjoint from $[a, b]$ and such that

$$|\mu_{n+1}|([c, d]) < \int_{[a, b]} \overline{T}x_0 \, d\mu_{n+1}.$$

From the induction assumption we know that there exists a mapping $\tilde{T} : B_n \rightarrow S_n$ of class $L(k), k \geq 1$, such that for every $x \in B_n$,

$$(\tilde{T}x)(t) = 0 \quad \text{for every } t \in [0, c] \cup [d, 1]$$

and

$$\max_{t \in [c, d]} |x(t) - (\tilde{T}x)(t)| > 1 - 1/k.$$

For any $x \in B_{n+1}$ and every $h \in [-1, 1]$ define $T_h x = h\overline{T}x_0 + \tilde{T}x$. Observe that for $h = -1$ we have

$$\begin{aligned} \int_{[0, 1]} T_{-1}x \, d\mu_{n+1} &= - \int_{[a, b]} \overline{T}x_0 \, d\mu_{n+1} + \int_{[c, d]} \tilde{T}x \, d\mu_{n+1} \\ &\leq - \int_{[a, b]} \overline{T}x_0 \, d\mu_{n+1} + |\mu_{n+1}|([c, d]) < 0. \end{aligned}$$

On the other hand for $h = 1$ we get

$$\begin{aligned} \int_{[0, 1]} T_1x \, d\mu_{n+1} &= \int_{[a, b]} \overline{T}x_0 \, d\mu_{n+1} + \int_{[c, d]} \tilde{T}x \, d\mu_{n+1} \\ &\geq \int_{[a, b]} \overline{T}x_0 \, d\mu_{n+1} - |\mu_{n+1}|([c, d]) > 0. \end{aligned}$$

Those two facts imply that there exists $h \in (-1, 1)$ such that

$$\int_{[0, 1]} T_h x \, d\mu_{n+1} = 0,$$

so that $T_h x \in C_{\mu_1, \dots, \mu_{n+1}}[0, 1]$. We show that for every $x \in B_{n+1}$ there exists a unique constant $h = h_x$ for which the above condition is satisfied. Suppose there are constants $h_1 \neq h_2$ such that

$$\int_{[0,1]} T_{h_1} x \, d\mu_{n+1} = \int_{[0,1]} T_{h_2} x \, d\mu_{n+1} = 0.$$

This can be written as

$$\int_{[a,b]} h_1 \bar{T}x_0 \, d\mu_{n+1} + \int_{[c,d]} \tilde{T}x \, d\mu_{n+1} = \int_{[a,b]} h_2 \bar{T}x_0 \, d\mu_{n+1} + \int_{[c,d]} \tilde{T}x \, d\mu_{n+1},$$

which means

$$0 = \int_{[a,b]} (h_1 - h_2) \bar{T}x_0 \, d\mu_{n+1} = (h_1 - h_2) \int_{[a,b]} \bar{T}x_0 \, d\mu_{n+1},$$

a contradiction.

Now define $T : B_{n+1} \rightarrow S_{n+1}$ by

$$Tx = h_x \bar{T}x_0 + \tilde{T}x.$$

Because $\|\tilde{T}x\| = 1$ for any $x \in B_{n+1}$ and $\text{supp } \bar{T}x_0 \cap \text{supp } \tilde{T}x = \emptyset$, it follows that $\|Tx\| = 1$.

To show that $T \in L(k)$, we should prove that

$$|h_x - h_y| \leq k \|x - y\|$$

for all $x, y \in B_{n+1}$. Let $M = \int_{[a,b]} \bar{T}x_0 \, d\mu_{n+1}$. We have

$$\begin{aligned} 0 &= \int_{[0,1]} Tx \, d\mu_{n+1} = \int_{[a,b]} h_x \bar{T}x_0 \, d\mu_{n+1} + \int_{[c,d]} \tilde{T}x \, d\mu_{n+1} \\ &= h_x \int_{[a,b]} \bar{T}x_0 \, d\mu_{n+1} + \int_{[c,d]} \tilde{T}x \, d\mu_{n+1} \\ &= h_x M + \int_{[c,d]} \tilde{T}x \, d\mu_{n+1}. \end{aligned}$$

From this we get

$$\begin{aligned} |h_x - h_y| &= M^{-1} \left| \int_{[c,d]} (\tilde{T}x - \tilde{T}y) \, d\mu_{n+1} \right| \\ &\leq M^{-1} \int_{[c,d]} k \|x - y\| \, d\mu_{n+1} \\ &= k M^{-1} |\mu_{n+1}|([c, d]) \|x - y\| \\ &\leq k \|x - y\|. \end{aligned}$$

Finally, observe that

$$\max_{t \in [\alpha, \beta]} |x(t) - (Tx)(t)| \geq \max_{t \in [c, d]} |x(t) - (\tilde{T}x)(t)| > 1 - 1/k. \quad \blacksquare$$

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