MANIFOLDS AND CELL COMPLEXES

${\rm SL}(2,5)$ Has No Smooth Effective One-fixed-point Action on S^8

by

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Dedicated to Professor Masaharu Morimoto on the occasion of his 60th birthday

Summary. We prove that there is no effective smooth one-fixed-point action of SL(2, 5), the special linear group of 2×2 matrices over \mathbb{Z}_5 , on the 8-dimensional sphere. The method of proof involves the intersection form.

1. Introduction. It is well known that there is no linear action of any finite group on the *n*-dimensional sphere S^n with exactly one fixed point. In the middle forties Montgomery and Samelson [MS] asked if there is a smooth one-fixed-point action on S^n . A first example of such an action was given by E. Stein [S] in 1977. He showed that there exists a smooth SL(2,5)-action with one fixed point on S^7 , moreover he constructed such actions as well for groups $G = SL(2,5) \times \mathbb{Z}_r$ where (120,r) = 1. If the *n*-dimensional sphere S^n has an effective topological one-fixed-point *G*-action then by taking the reduced suspension, S^{n+1} also has such an exotic topological *G*-action. Hence there are effective topological one-fixed-point SL(2,5)-actions on S^n whenever $n \geq 7$. Next, T. Petrie [P] proved in 1982 that a finite, odd order abelian group having at least three noncyclic Sylow subgroups, e.g. $\mathbb{Z}_{pqr} \times \mathbb{Z}_{pqr}$, where p, q and r are distinct odd primes, has a smooth one-fixed-point action on some sphere. Petrie also established existence of smooth one-fixed-point action on some sphere.

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tions for nonsolvable groups SL(2,q) and PSL(2,q), where $q \ge 5$ is an odd prime power. In 1995, M. Morimoto, E. Laitinen and K. Pawałowski [LMP] described smooth one-fixed-point G-actions on spheres in case when G is any nonsolvable group. Later, M. Morimoto and E. Laitinen [LM] constructed smooth G-actions on spheres with exactly one fixed point for any Oliver group G, proving that a finite group G acts smoothly on a sphere with exactly one fixed point if and only if G is an Oliver group. On the other hand M. Furuta [F], Buchdahl–Kwasik–Schultz [BKS] and DeMichelis [DM] showed that S^n does not have a smooth one-fixed-point action of any finite group when $0 \le n \le 5$. For $n \ge 6$ it has been known for about a decade that the standard *n*-dimensional sphere S^n has a smooth one-fixed-point action of some finite group if $n \neq 8$. Lately, A. Bak and M. Morimoto [BM] showed that there are smooth one-fixed-point actions of the alternating group of degree 5, A_5 , on the 8-dimensional sphere, thus completing research stretching over several decades to determine which spheres admit this kind of action. For the survey on actions of A_5 on spheres see for example |M|.

The method used for constructing actions on spheres was equivariant surgery theory. To prove that there is no smooth action with exactly one fixed point various *ad hoc* methods were used. In this paper, the intersection form is a tool for obtaining the following theorems:

THEOREM 1.1. There is no effective smooth SL(2,5)-action on any 8-dimensional \mathbb{Z} -homology sphere with exactly one fixed point.

The next theorem gives us some information on submodules of the tangent module if the action of SL(2,5) has at least three fixed points.

THEOREM 1.2. Let G = SL(2,5), let X be a Z-homology sphere of dimension n with a smooth G-action, and let $x \in X^G$.

- (i) If $3 \le |X^G| < \infty$ then $T_x(X)$ contains a G-submodule isomorphic to U_4 or U_5 .
- (ii) If $|X^G|$ is an odd integer ≥ 3 then $T_x(X)$ contains a G-submodule isomorphic to $U_{3,1}$ or $U_{3,2}$.

The modules U_i and $U_{i,j}$ are described in Section 3.

In Section 2 we will recall some helpful information on SL(2, 5) and its properties, the character table and subgroups. In Section 3 we give the tables of fixed point dimensions over \mathbb{C} and \mathbb{R} ; these results base on information from Section 2. In Section 4 we recall the Slice Theorem and some helpful lemmas. Section 5 states basic facts about the intersection number. In Section 6 we prove Theorems 1.1 and 1.2.

One can expect that the intersection form and its modification may be helpful for answering further questions of determining dimensions of the spheres on which a given finite group can not act in an effective and smooth way with exactly one fixed point.

2. Basic properties of SL(2,5). In this section we assume throughout that G = SL(2,5). Denote in G,

$$\mathbf{1} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}, \quad \mathbf{z} = \begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix}, \quad \mathbf{c} = \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix}, \\ \mathbf{d} = \begin{bmatrix} 1 & 0 \\ 3 & 1 \end{bmatrix}, \quad \mathbf{a} = \begin{bmatrix} 3 & 0 \\ 0 & 2 \end{bmatrix}, \qquad \mathbf{b} = \begin{bmatrix} 3 & -1 \\ 2 & 3 \end{bmatrix}.$$

Then G has nine conjugacy classes (1), (z), (c), (d), (zc), (zd), (a), (b) and (b^2) , as listed in Table 1; Table 2 is the complex character table of G.

Table 1. The sizes of the conjugacy classes of SL(2,5) and orders of elements in SL(2,5)

						\mathbf{zd}			
(x)	1	1	12	12	12	12	30	20	20
x	1	2	5	5	10	10	4	6	3

χ_V	V	1	\mathbf{z}	с	\mathbf{d}	zc	\mathbf{zd}	а	b	\mathbf{b}^2
1_G	\mathbb{C}	1	1	1	1	1	1	1	1	1
η_1	$V_{2,1}$	2	-2	$-\frac{1-\sqrt{5}}{2}$	$-\frac{1+\sqrt{5}}{2}$	$\frac{1-\sqrt{5}}{2}$	$\frac{1+\sqrt{5}}{2}$	0	1	-1
η_2	$V_{2,2}$	2	-2	$-\frac{1+\sqrt{5}}{2}$	$-\frac{1-\sqrt{5}}{2}$	$\frac{1+\sqrt{5}}{2}$	$\frac{1-\sqrt{5}}{2}$	0	1	-1
ξ_1	$V_{3,1}$	3	3	$\frac{1+\sqrt{5}}{2}$	$\frac{1-\sqrt{5}}{2}$	$\frac{1+\sqrt{5}}{2}$	$\frac{1-\sqrt{5}}{2}$	-1	0	0
ξ_2	$V_{3,2}$	3	3	$\frac{1-\sqrt{5}}{2}$	$\frac{1+\sqrt{5}}{2}$	$\frac{1-\sqrt{5}}{2}$	$\frac{1+\sqrt{5}}{2}$	-1	0	0
$ heta_1$	$V_{4,1}$	4	-4	-1	-1	1	1	0	-1	1
θ_2	$V_{4,2}$	4	4	$^{-1}$	$^{-1}$	-1	-1	0	1	1
ψ	V_5	5	5	0	0	0	0	1	-1	-1
χ	V_6	6	-6	1	1	-1	-1	0	0	0

Table 2. The irreducible characters of SL(2,5)

A more general case is considered in [D].

The centre of G consists of $\mathbf{1}$ and $-\mathbf{1}$. The special projective group PSL(2,5) is isomorphic to A_5 . The normal subgroups of G are $\{\mathbf{1}\}, \{\mathbf{1}, \mathbf{z}\}$ and G. Hence G is not a simple group but it is a perfect group. Next we will recall the conjugacy classes of subgroups of G.

Let $Q_{4m} = \{ \langle x, y \rangle \mid y^m = x^2, y^{2m} = 1, x^{-1}yx = y^{-1} \}$ be the generalized quaternion group of order 4m, and C_n the cyclic group of order n. We denote, in G,

$$\mathbf{a}' = \begin{bmatrix} 0 & 4 \\ 1 & 0 \end{bmatrix}, \quad \mathbf{x} = \begin{bmatrix} 1 & 2 \\ 1 & 3 \end{bmatrix}.$$

Following [H] one can directly check that SL(2,5) has the following twelve subgroups up to conjugacy:

$$SL(2,3) \cong \langle \mathbf{a}, \mathbf{a}', \mathbf{x} | \mathbf{a}^2 = \mathbf{a}'^2, \mathbf{a}^4 = 1, \mathbf{a}'^{-1}\mathbf{a}\mathbf{a}' = \mathbf{a}^{-1}, \\ \mathbf{x}\mathbf{a}\mathbf{x}^{-1} = \mathbf{a}', \mathbf{x}\mathbf{a}'\mathbf{x}^{-1} = \mathbf{a}\mathbf{a}' \rangle, \\ Q_{20} = \langle \mathbf{a}, \mathbf{z}\mathbf{c} \rangle, \ Q_{12} = \langle \mathbf{a}, \mathbf{b} \rangle, \ Q_8 = \langle \mathbf{a}, \mathbf{a}' \rangle, \ C_{10} = \langle \mathbf{z}\mathbf{c} \rangle, \ C_6 = \langle \mathbf{b} \rangle, \ C_5 = \langle \mathbf{c} \rangle, \\ C_4 = \langle \mathbf{a} \rangle, \ C_3 = \langle \mathbf{b}^2 \rangle, \ C_2 = \langle \mathbf{z} \rangle, \ \{e\} = \{\mathbf{1}\}.$$

In the above presentations we list only generators, skipping the obvious relations. The subgroups are shown in the Hasse diagram below, with A denoting SL(2,3).

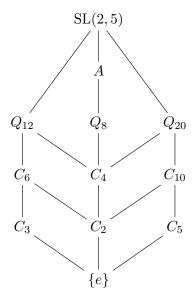


Fig. 1. The subgroups of SL(2,5) up to isomorphism

Let p be a prime. A finite group K is called a p-group if $|K| = p^s$ for some integer $s \ge 0$. The set of all p-subgroups of a group G is denoted by $\mathcal{P}(G)$. A finite group K is called a mod-p-cyclic group if K contains a normal subgroup P such that P is a p-group and K/P is cyclic. The set of all mod-p-cyclic subgroups of a group G is denoted by $\mathcal{PC}(G)$.

For G = SL(2,5), *p*-subgroups and mod-*p*-cyclic subgroups up to conjugacy classes are as follows:

$$\mathcal{P}(G) = \{\{e\}, \langle \mathbf{z} \rangle, \langle \mathbf{a} \rangle, \langle \mathbf{b}^2 \rangle, \langle \mathbf{c} \rangle, \langle \mathbf{a}, \mathbf{a}' \rangle \} = \{\{e\}, C_2, C_4, C_3, C_5, Q_8\}, \\ \mathcal{PC}(G) = P(G) \cup \{\langle \mathbf{b} \rangle, \langle \mathbf{z} \mathbf{c} \rangle, \langle \mathbf{a}, \mathbf{b} \rangle, \langle \mathbf{a}, \mathbf{z} \mathbf{c} \rangle, \langle \mathbf{a}, \mathbf{a}', \mathbf{x} \rangle \} \\ = P(G) \cup \{C_6, C_{10}, Q_{12}, Q_{20}, A\}.$$

3. Fixed point sets over \mathbb{C} and \mathbb{R} . The following theorems and definitions are well known facts [D], [CR].

THEOREM 3.1. If U_i is an irreducible $\mathbb{C}G$ -module, κ_i an irreducible character associated with U_i , and H_j a representative of the conjugacy class of a subgroup of G. Then

$$\dim U_i^{H_j} = \frac{1}{|H_j|} \sum_{g \in H_j} \kappa_i(g)$$

where $U_i^{H_j}$ is the H_j -fixed point set of U_i .

Applying the complex character table of SL(2,5) to the formula in Theorem 3.1, one can calculate the fixed point dimension. The results of this straightforward computation are gathered in Table 3.

Н	$\{e\}$	C_2	C_3	C_4	C_5	C_6	C_{10}	Q_8	Q_{12}	Q_{20}	Α	\overline{G}
$\dim \mathbb{C}$	1	1	1	1	1	1	1	1	1	1	1	1
$\dim V_{2,1}$	2	0	0	0	0	0	0	0	0	0	0	0
$\dim V_{2,2}$	2	0	0	0	0	0	0	0	0	0	0	0
$\dim V_{3,1}$	3	3	1	1	1	1	1	0	0	0	0	0
$\dim V_{3,2}$	3	3	1	1	1	1	1	0	0	0	0	0
$\dim V_{4,1}$	4	0	2	0	0	0	0	0	0	0	0	0
$\dim V_{4,2}$	4	4	2	2	0	2	0	1	1	0	1	0
$\dim V_5$	5	5	1	3	1	1	1	2	1	1	0	0
$\dim V_6$	6	0	2	0	2	0	0	0	0	0	0	0

Table 3. The fixed point dimension over \mathbb{C} for SL(2,5)

To get the fixed point dimension over \mathbb{R} the Frobenius–Schur theorem is needed.

THEOREM 3.2 (Frobenius–Schur theorem). Let G be a finite group and V an irreducible $\mathbb{C}G$ -module. There exists an irreducible $\mathbb{R}G$ -module U such that $V \cong \mathbb{C} \otimes_{\mathbb{R}} U$ if and only if

$$B_V := \frac{1}{|G|} \sum_{g \in G} \chi_V(g^2) = 1.$$

If $B_V = 1$ then the $\mathbb{C}G$ -module V is called of real type, if $B_V = 0$ of complex type, and if $B_V = -1$ of quaternionic type. Therefore the irreducible $\mathbb{C}G$ -modules with character 1_G , ψ , θ_2 , ξ_1 or ξ_2 are of real type, and those with character χ , θ_1 , η_1 or η_2 are of quaternionic type.

Let V be an $\mathbb{R}G$ -module. Then $\mathbb{C} \otimes_{\mathbb{R}} V$ is a $\mathbb{C}G$ -module. We call $c(V) := \mathbb{C} \otimes_{\mathbb{R}} V$ the *complexification* of V.

Let V be a $\mathbb{C}G$ -module. The vector space V over \mathbb{C} can be considered as a vector space over \mathbb{R} , and it is denoted by $V_{\mathbb{R}}$. If $\{v_1, \ldots, v_m\}$ is a basis of V over \mathbb{C} , then $\{v_1, iv_1, \ldots, v_m, iv_m\}$ is a basis of $V_{\mathbb{R}}$ over \mathbb{R} and $\dim_{\mathbb{R}} V_{\mathbb{R}} =$ $2 \dim_{\mathbb{C}} V$. We call $r(V) := V_{\mathbb{R}}$ the *realification* of V.

Hence, $\dim_{\mathbb{C}} V = \dim_{\mathbb{R}} U$ when V is of real type and V = c(U), while $\dim_{\mathbb{C}} V = \frac{1}{2} \dim_{\mathbb{R}} U$ when V is of complex or quaternionic type and $U = V_{\mathbb{R}}$.

Table 4 shows $\dim_{\mathbb{R}} \overline{U}^H$ for irreducible $\mathbb{R}G$ -modules \overline{U} ; the \mathbb{R} in the table stands for the trivial module.

Н	$\{e\}$	C_2	C_3	C_4	C_5	C_6	C_{10}	Q_8	Q_{12}	Q_{20}	A	G
$\dim \mathbb{R}$	1	1	1	1	1	1	1	1	1	1	1	1
$\dim U_{3,1}$	3	3	1	1	1	1	1	0	0	0	0	0
$\dim U_{3,2}$	3	3	1	1	1	1	1	0	0	0	0	0
$\dim U_4$	4	4	2	2	0	2	0	1	1	0	1	0
$\dim U_5$	5	5	1	3	1	1	1	2	1	1	0	0
$\dim W_{4,1}$	4	0	0	0	0	0	0	0	0	0	0	0
$\dim W_{4,2}$	4	0	0	0	0	0	0	0	0	0	0	0
$\dim W_8$	8	0	4	0	0	0	0	0	0	0	0	0
$\dim W_{12}$	12	0	4	0	4	0	0	0	0	0	0	0

Table 4. The fixed point dimension over \mathbb{R} for SL(2,5)

4. Euler–Poincaré characteristic restrictions. In order to apply the intersection form to prove Theorem 1.1 we need the following results:

DEFINITION 4.1. Let G be a finite group. For a G-fixed point x of a smooth G-manifold X, let $T_x(X)$ denote the tangent space of X at x. Then $T_x(X)$ inherits a linear G-action from the G-action on X. This linear G-action will be referred to as the tangential G-representation of X at x or the tangent G-module.

THEOREM 4.2 (Slice Theorem). Let G be a finite group, M a smooth G-manifold, and $x_0 \in M^G$. Then there exists a G-invariant neighbourhood U_{x_0} of x_0 in M and a G-diffeomorphism from the G-module $T_{x_0}(M)$ onto U_{x_0} .

According to the above theorem, the G-action on the manifold M around the point x_0 is equivalent to the linear action defined by the G-module $T_{x_0}(M)$.

LEMMA 4.3. If a finite mod-p-cyclic group H acts on a \mathbb{Z}_p -acyclic finite complex X, then $\chi(X^H) = 1$.

Now we are ready to prove the following lemma:

LEMMA 4.4. If a mod-p-cyclic group H acts smoothly on a \mathbb{Z}_p -homology sphere X with $x_1 \in X^H$, then $\chi(X^H) = 1 + (-1)^{\dim T_{x_1}(X)^H}$.

Proof. By the Slice Theorem we can take an *H*-linear-disc neighbourhood N of x_1 in X. Set

$$Y = X/(X \setminus \text{Interior}(N)) \quad (= N/\partial N).$$

Then $Y \cong S(\mathbb{R} \oplus T_{x_1}(X))$. Let $f: X \to Y$ denote the pinching map. Since the induced map $f_*: H_n(X, \mathbb{Z}_p) \to H_n(Y, \mathbb{Z}_p)$ is an isomorphism, where $n = \dim X$, f is a \mathbb{Z}_p -homology equivalence. Thus the mapping cone

 $C_f := \{ (X \times [0,1]) \cup Y / \langle (x,1) \sim f(x) \rangle \} / (X \times \{0\})$

is a \mathbb{Z}_p -acyclic finite complex with an *H*-action. Hence by Lemma 4.3 we get $\chi((C_f)^H) = 1$. The equalities

$$\chi((C_f)^H) = \chi(Y^H) - \chi(X^H) + 1,$$

$$\chi(Y^H) = 1 + (-1)^{\dim Y^H}$$

yield $\chi(X^H) = 1 + (-1)^{\dim T_{x_1}(X)^H}$.

COROLLARY 4.5. Let X and H be as in the lemma above. Then for arbitrary $x_1, x_2 \in X$,

$$\dim T_{x_1}(X)^H \equiv \dim T_{x_2}(X)^H \mod 2.$$

5. Intersection number. Following Davis–Kirk [DK], we recall basic information on the intersection number that is needed in this paper.

Recall that an *orientation* of a real finite-dimensional vector space V is an equivalence class of bases of V where two bases are considered equivalent if the determinant of the change of basis matrix is positive.

Suppose that V and W are oriented subspaces of an oriented vector space Z, and that $\dim(V) + \dim(W) = \dim(Z)$. Suppose V and W are transverse, that is, $V \cap W = \{0\}$. Let \mathcal{B}_V , \mathcal{B}_W and \mathcal{B}_Z denote bases in the given equivalence classes. Then the *intersection number of* V and W is -1or 1, depending on the sign of the determinant of the change of basis matrix from the basis $\{\mathcal{B}_V, \mathcal{B}_W\}$ of Z to \mathcal{B}_Z .

Suppose that A and B are smooth, compact, connected, oriented submanifolds of dimensions a and b of a compact oriented manifold M of dimension m, where a + b = m. Assume that A and B are transverse, i.e. at each point $p \in A \cap B$, the tangent subspaces T_pA and T_pB span T_pM . Moreover assume that the boundary of A is embedded in the boundary of M, the boundary of B is empty, and B is contained in the interior of M. Since A and B are transverse and compact, their intersection consists of a finite number of points. We define the *intersection number of* A and B to be the integer

$$A \cdot B = \sum_{p \in A \cap B} \eta_p$$

where η_p is the intersection number of the oriented subspaces T_pA and T_pB in T_pM .

Since A and B are oriented manifolds, they have fundamental classes $[A, \partial A] \in H_a(A, \partial A)$, $[B] \in H_b(B)$. Let $i_B \colon A \subset M$ and $i_B \colon B \subset M$ denote the inclusion maps. Then $i_A([A, \partial A]) \in H_a(M, \partial M)$ and $i_B([B]) \in H_b(M)$. We have the following theorem:

THEOREM 5.1. Let $\alpha \in H^b(M)$ be the Poincaré dual to $i_A([A, \partial A])$, and $\beta \in H^a([M, \partial M])$ the Poincaré dual to $i_B([B])$, i.e.

$$\alpha \cap [M, \partial M] = i_A([A, \partial A]) \quad and \quad \beta \cap [M, \partial M] = i_B([B]).$$

Then

$$A \cdot B = \langle \alpha \cup \beta, [M, \partial M] \rangle$$

where \langle , \rangle denotes the Kronecker pairing.

We call the cup product

$$H^b(M) \times H^a(M, \partial M) \xrightarrow{\cup} H^m(M, \partial M)$$

the *intersection pairing*. The *intersection form* is the cup product in the middle dimensional cohomology.

6. Proofs of Theorems 1.1 and 1.2. Henceforth, G denotes SL(2,5), and A is the subgroup of G isomorphic to SL(2,3).

Proof of Theorem 1.1. By the character table, any faithful real G-module of dimension 8 is isomorphic to $W_{4,i} \oplus W_{4,j}, W_{4,i} \oplus U_4$, or W_8 , where i, j = 1, 2. Suppose Σ is an 8-dimensional \mathbb{Z} -homology sphere with a smooth one-fixedpoint action of G. Let $T_{x_0}(\Sigma)$ denote the tangential G-module at the fixed point x_0 of Σ .

First consider the case where $T_{x_0}(\Sigma) \cong W_{4,i} \oplus W_{4,j}$. Let P be any nontrivial p-subgroup of G. According to Table 4, Σ^P is of dimension 0. Then by the Smith theorem, Σ^P is a \mathbb{Z}_p -homology sphere and therefore consists of exactly two points. Let H be an arbitrary proper subgroup of G, that is, $H \neq \{e\}, G$. Note that H is mod-p-cyclic. For all $\{e\} \neq P \subset H$ we have $\Sigma^G \subseteq \Sigma^H \subseteq \Sigma^P$, therefore dim $\Sigma^H = 0$, and by Lemma 4.4, $|\Sigma^H| = \chi(\Sigma^H) = 0$ or 2. Since Σ^G consists of one point, $|\Sigma^H| = 2$. Thus $\Sigma^H = \Sigma^P$. Since $\langle \mathbf{z} \rangle \subset A$ and $\langle \mathbf{z} \rangle \subset Q_{20}$, we have

$$\Sigma^A = \Sigma^{\mathbf{Z}} = \Sigma^{Q_{20}},$$

and consequently $\Sigma^G = \Sigma^{\mathbf{z}}$. This is a contradiction.

Second, consider the case $T_{x_0}(\Sigma) \cong W_{4,i} \oplus U_4$. Then $\Sigma^{\mathbf{z}}$ is a \mathbb{Z}_2 -homology sphere of dimension 4 and the intersection form on $H_2(\Sigma_{\mathbf{z}}, \mathbb{Z}_2)$ is trivial. There exist $a, b \in A_5$ of order 3 such that $A_5 = \langle a, b \rangle$. Since $(\Sigma^{\mathbf{z}})^{A_5}$ consists of exactly one point, the intersection number in \mathbb{Z}_2 of $(\Sigma^{\mathbf{z}})^a$ and $(\Sigma^{\mathbf{z}})^b$ is equal to 1. This is a contradiction. Third, consider the case $T_{x_0}(\Sigma) \cong W_8$. Then the intersection form on $H_4(\Sigma, \mathbb{Z}_2)$ is also trivial. There exist $a, b \in SL(2, 5)$ of order 3 such that SL(2, 5) is generated by these elements. Then the intersection number in \mathbb{Z}_2 of Σ^a and Σ^b is 1, a contradiction.

We fix an epimorphism $\pi: SL(2,5) \to A_5$. We tabulate the fixed point dimension of irreducible A_5 -representations [BM].

Н	$\{e\}$	C_2	C_3	C_5	D_4	D_6	D_{10}	A_4	A_5
$\dim U_{3,1}$	3	1	1	1	0	0	0	0	0
$\dim U_{3,2}$	3	1	1	1	0	0	0	0	0
$\dim U_4$	4	2	2	0	1	1	0	1	0
$\dim U_5$	5	3	1	1	2	1	1	0	0

Table 5. Fixed point dimension over \mathbb{R} for A_5

One can regard the irreducible real A_5 -modules $U_{3,1}$, $U_{3,2}$, U_4 and U_5 as real SL(2, 5)-modules via π . There are four irreducible complex SL(2, 5)-modules which are faithful and moreover of quaternionic type. These give four faithful irreducible real SL(2, 5)-modules, namely $W_{4,1}$, $W_{4,2}$, W_8 , W_{12} . Values of the *H*-fixed-point dimension, where *H* is a subgroup of SL(2, 5), are listed in Table 4.

Proof of Theorem 1.2. (i) By the Smith theorem, X^{Q_8} is a \mathbb{Z}_2 -homology sphere. By assumption $|X^G| \geq 3$, dim $X^{Q_8} > 0$ and hence X^{Q_8} is connected. Thus dim $T_x(X)^{Q_8} > 0$, which implies that $T_x(X) \supset U_4$ or $T_x(X) \supset U_5$.

(ii) Suppose that $T_x(X)$ does not contain a *G*-submodule isomorphic to $U_{3,1}$ or $U_{3,2}$. Note that

$$\dim T_x(X)^{C_4} = \dim T_x(X)^{Q_8} + \dim T_x(X)^{Q_{12}}.$$

Since X^{C_2} is a \mathbb{Z}_2 -homology sphere, the mod-2 intersection number of X^{Q_8} and $X^{Q_{12}}$ is 0. But this is not possible because $X^{Q_8} \cap X^{Q_{12}} = X^G$ consists of an odd number of points.

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