

# ON THE GROUP OF LAGRANGIAN BISECTIONS OF A SYMPLECTIC GROUPOID

TOMASZ RYBICKI

*Department of Applied Mathematics, University of Mining and Metallurgy  
 Mickiewicza 30, 30-059 Kraków, Poland  
 E-mail: tomasz@uci.agh.edu.pl*

**Abstract.** The group of lagrangian bisections of a symplectic groupoid extends the concept of the symplectomorphism group. The flux homomorphism is a basic invariant of this group. It is shown that this group is a regular Lie group. The group of exact (hamiltonian) bisections is also studied. The existence of the flux homomorphism enables a characterization of exact isotopies.

**1. Introduction.** The aim of this note is to prove that bisection groups related to a symplectic groupoid admit a structure of regular Lie group. In view of this fact we show the existence of the flux homomorphism and some further consequences, e.g. concerning exact bisection isotopies, quite similar to properties of the symplectomorphism group. We indicate also the integrability of some Lie algebras associated with the Poisson structure on the space of units of a symplectic groupoid.

Observe that the flux homomorphism for symplectic groupoids and some properties of the group of lagrangian bisections have been studied independently by P. Dazord [5] and P. Xu [22] without considering a Lie group structure on this group but rather exploiting some “weak” Lie theories (see below). However, by means of a chart at  $e$  we are able to obtain also the local form of the flux, which is essential for a characterization of exact isotopies.

We will use the definition of a Lie group from the convenient setting of the infinite dimensional Lie theory [8] due to A. Kriegl and P. Michor. The convenient setting is based on Boman’s theorem which states that a mapping  $f : \mathbb{R}^n \rightarrow \mathbb{R}$  is smooth whenever  $f \circ c$  is smooth for any smooth curve  $c : \mathbb{R} \rightarrow \mathbb{R}^n$ . Consequently, a mapping between two possibly infinite dimensional manifolds is smooth if, by definition, it sends smooth

---

2000 *Mathematics Subject Classification*: Primary 22E65, 53D05.

*Key words and phrases*: symplectic groupoid, lagrangian bisection, group of bisections, flux homomorphism, Lie group.

Supported in part by the AGH grant n. 11.420.04.

The paper is in final form and no version of it will be published elsewhere.

curves to smooth curves. Furthermore, for modelling manifolds a special type of LCTVS is in use, namely so-called convenient vector spaces which fulfil some weak completeness condition.

Recall that a convenient Lie group is called *regular* if for  $\mathfrak{g} = T_e G$  there exists a smooth bijective evolution map

$$\text{evol}_G^r : C^\infty(\mathbb{R}, \mathfrak{g}) \rightarrow C^\infty((\mathbb{R}, 0), (G, e)).$$

The right logarithmic derivative  $\delta_G^r$  is then the inverse of  $\text{evol}_G^r$ . Frequently one encounters the situation that there is a closed subgroup  $H \subset G$  and a Lie algebra  $\mathfrak{h}$  such that smooth curves with values in  $\mathfrak{h}$  are sent bijectively by  $\text{evol}_G^r$  to isotopies with values in  $H$ . However we would like to emphasize that such a bijection does not yield a Lie group structure on  $H$ .

It is a characteristic feature of the convenient setting that  $\text{Diff}(M)$  for  $M$  open is still a regular Lie group, but its identity component consists only of compactly supported diffeomorphisms. So in our results the assumption on the compactness of the space of units (cf. [22]) is superfluous.

We would like also to indicate that there are some "weak" settings of the infinite dimensional Lie theory and that they usually do not correspond strictly to each other. One example is the notion of diffeological groups due to J. M. Souriau [20]. A smooth structure is there defined by establishing sets of local smooth mappings from  $\mathbb{R}^n$  to  $G$ ,  $n = 1, 2, \dots$ , and by imposing some conditions on them. As another example of a "weak" setting can serve the concept of generalized Lie groups of H. Omori [11]. The definition is based on a continuous mapping  $\exp : G \rightarrow \mathfrak{g}$  between a topological group  $G$  and a topological Lie algebra  $\mathfrak{g}$  with some conditions which mimics essential properties of the exponential map. A common feature of such theories is that any closed subgroup of a Lie group is a Lie subgroup (which in a sense measures a lack of subtlety of them). Consequently, analogues of the presented results in those settings are rather trivial.

**2. Preliminaries.** We adopt the notation for groupoids from [3] rather than from [9].

**DEFINITION.** A *groupoid structure* on a set  $\Gamma$  is given by two surjections (the source and target)  $\alpha, \beta : \Gamma \rightarrow M \subset \Gamma$ , by a multiplication  $m : \Gamma_2 \rightarrow \Gamma$ , where  $\Gamma_2 = \{(x, y) \in \Gamma \times \Gamma : \alpha(x) = \beta(y)\}$ , and by an inversion  $i : \Gamma \rightarrow \Gamma$  such that the following axioms are fulfilled:

(Ass) If one of the products  $m(x, m(y, z))$  and  $m(m(x, y), z)$  is defined then so is the other and they are equal.

(Id) The products  $m(\beta(x), x)$ ,  $m(x, \alpha(x))$  are defined and equal to each other.

(Inv)  $m(x, i(x))$  is defined and equal to  $\beta(x)$ , and  $m(i(x), x)$  is defined and equal to  $\alpha(x)$ .

The elements of  $M$  are called *unities*. For simplicity we write  $x.y$  for  $m(x, y)$  and  $x^{-1}$  for  $i(x)$ . We will use the symbol  $\Gamma \rightrightarrows M$  for the groupoid  $(\Gamma, M, \alpha, \beta, m, i)$ .

Next, a groupoid  $\Gamma$  is said to be a Lie groupoid if  $\Gamma$  is a smooth ( $C^\infty$ ) manifold (not necessarily separated),  $M$  is a separated paracompact submanifold,  $\alpha$  and  $\beta$  are submersions,  $m$  is a smooth mapping, and  $i$  is a diffeomorphism. Notice that  $\Gamma$  is separated iff  $M$  is closed in  $\Gamma$ .

For  $u \in M$  the set  $\alpha(\beta^{-1}(u)) = \beta(\alpha^{-1}(u))$  is an orbit. The family of orbits forms a generalized foliation  $\mathcal{F}_\Gamma$  of  $M$  (cf.[3]).  $\Gamma$  is called *transitive* if it has only one orbit  $M$ .

EXAMPLES. 1. Lie groups coincide with Lie groupoids with a unique unity.

2. Another extreme example are manifolds:  $\Gamma = M$ .

3. If  $\alpha = \beta$  then for all  $u \in M$  the fiber  $\alpha^{-1}(u)$  carries a Lie group structure. Any vector bundle is a Lie groupoid of this type.

4. For any set  $M$  put  $\Gamma = M \times M$ ,  $\alpha((x, y)) = y$ ,  $\beta((x, y)) = x$ ,  $m((z, y), (y, x)) = (z, x)$  and  $i((x, y)) = (y, x)$ . We get the coarse groupoid with the space of units  $M \simeq \Delta_M$ .

5. Given a principal fiber bundle  $P(M, \pi, G)$  one defines the equivalence relation  $\sim$  on  $P \times P$  by  $(p_1, p_2) \sim (q_1, q_2)$  iff  $\exists a \in G$   $p_i a = q_i$ . Letting denote  $\Gamma = P \times P / \sim$ ,  $\alpha([(p_1, p_2)]) = \pi(p_2)$ ,  $\beta([(p_1, p_2)]) = \pi(p_1)$ , we get the gauge groupoid (with obvious  $m$  and  $i$ ).  $\Gamma$  is identified with the set of equivariant bundle morphisms over  $\text{id}_M$ .

6. Assume that a Lie group  $G$  acts on a manifold  $M$ . Then we set:  $\Gamma = G \times M$ ,  $\alpha((g, x)) = g.x$ ,  $\beta((g, x)) = x$ ,  $(g', x').(g, x) = (g'g, x)$ , and  $(g, x)^{-1} = (g^{-1}, g.x)$ . We say that  $\Gamma$  is a transformation groupoid.

7. For any Lie groupoid  $\Gamma$  the tangent space  $T\Gamma = (T\Gamma \rightrightarrows TM, T\alpha, T\beta, \oplus, I)$  possesses a structure of Lie groupoid. Here the multiplication  $\oplus$  is given by

$$X \oplus Y = \left( \frac{d}{dt}(x(t).y(t)) \right) \Big|_{t=0},$$

where  $X = \frac{dx}{dt}|_{t=0}$ ,  $Y = \frac{dy}{dt}|_{t=0}$ ,  $\alpha(x(t)) = \beta(y(t))$ , and the inversion  $IX = \frac{dx}{dt}x(t)^{-1}|_{t=0}$  if  $X = \frac{dx}{dt}|_{t=0}$ .

A *bisection* of a Lie groupoid  $\Gamma$  is a submanifold  $B$  of  $\Gamma$  such that  $\alpha|_B$  and  $\beta|_B$  are diffeomorphisms onto  $M$ . Let  $\text{Bis}(\Gamma)$  be the set of all bisections. It is a group endowed with the product law

$$B_1.B_2 = \{x_1.x_2 | \alpha(x_1) = \beta(x_2)\}.$$

Notice that bisections of the coarse groupoid  $\Gamma = M \times M$  (Ex. 4) coincide with diffeomorphisms on  $M$ , i.e. groups of bisections constitute a generalization of diffeomorphism groups.  $\text{Bis}(\Gamma)$  has natural left and right representations in  $\Gamma$  given by

$$\begin{aligned} \psi^l : \text{Bis}(\Gamma) \ni B &\mapsto \psi^l(B) := \{x \mapsto B.x\} \in \text{Diff}(\Gamma), \\ \psi^r : \text{Bis}(\Gamma) \ni B &\mapsto \psi^r(B) := \{x \mapsto x.B\} \in \text{Diff}(\Gamma). \end{aligned}$$

Next there are the left and right representations in the unit space  $(M, \mathcal{F}_\Gamma)$

$$\begin{aligned} \phi^l : \text{Bis}(\Gamma) \ni B &\mapsto \phi^l(B) := \beta \circ \psi^l(B)|_M \in \text{Diff}(M, \mathcal{F}_\Gamma), \\ \phi^r : \text{Bis}(\Gamma) \ni B &\mapsto \phi^r(B) := \alpha \circ \psi^r(B)|_M \in \text{Diff}(M, \mathcal{F}_\Gamma), \end{aligned}$$

where  $\text{Diff}(M, \mathcal{F}_\Gamma)$  is the group of leaf preserving diffeomorphisms.  $\text{Bis}(\Gamma)_c$  will stand for the subgroup of all compactly controlled elements, that is, all  $B$  such that  $\phi^l(B)$ , or equivalently  $\phi^r(B)$ , has compact support. In general, compactly controlled bisections need not have compact support, e.g. in Example 3.

It is well known (J. Pradines [14], [15]) that to any Lie groupoid  $\Gamma \rightrightarrows M$  is assigned the associated algebroid  $\mathcal{A}(\Gamma)$ , namely  $\mathcal{A}(\Gamma) = (\ker T\beta, [[, ]], T\alpha)$ , where  $[[, ]]$  is a Lie algebra

bracket on  $\text{Sect}(\ker T\beta)$  introduced by means of left invariant vector fields and of the identification  $T\Gamma|_M/TM \simeq \ker T\beta$ .

**THEOREM 2.1.** *The groups  $\text{Bis}(\Gamma)$  and  $\text{Bis}(\Gamma)_c$  are regular Lie groups with the same Lie algebra  $\text{Sect}_c(\ker T\beta)$ .*

The proof follows that for diffeomorphisms in [8], and makes use of the Tubular Neighborhood Theorem and the identification  $T\Gamma|_M/TM \simeq \ker T\beta$ . The topology of  $\text{Bis}(\Gamma)$  is the identification topology by charts of a Lie group structure of  $\text{Bis}(\Gamma)$ . In particular, all bisections in the identity component are compactly controlled.

To show the regularity of  $\text{Bis}(\Gamma)$  for any  $u \in M$  and  $B \in \text{Bis}(\Gamma)$  we denote by  $B^\beta(u)$  the unique point in  $B$  such that  $\beta(B^\beta(u)) = u$ . Now given a smooth isotopy  $B_t$  in  $\text{Bis}(\Gamma)$  (which is a concept without problem) with  $B_0 = M$  there is a unique time-dependent family of vector fields  $\hat{X}_t$  along  $B_t^\beta$  corresponding to  $B_t$ , i.e. for all  $u \in M$

$$(2.1) \quad \hat{X}_t(B_t^\beta(u)) = \frac{d}{ds} B_s^\beta(u)|_{s=t}.$$

By definition,  $\hat{X}_t$  are tangent to the fibers of  $\beta$ .

Let  $u \in M$  and  $B \in \text{Bis}(\Gamma)$ . We have a diffeomorphism  $\sigma_u^B : \beta^{-1}(u) \rightarrow \beta^{-1}(u)$  given by

$$\sigma_u^B(x) = x.B^\beta(\alpha(x)).$$

Then clearly  $\sigma_u^B(u) = B^\beta(u)$ . By gluing-up the tangent mappings  $T\sigma_u^B$  of diffeomorphisms  $\sigma_u^B$  we get the canonical identification

$$(2.2) \quad \sigma^B : \ker T\beta \simeq T\Gamma|_M/TM \simeq T\Gamma|_B/TB.$$

We have also the canonical identification  $TB^\beta : TM \simeq TB$ . By combining it with (2.2) we get

$$(2.3) \quad \tilde{\sigma}^B : T\Gamma|_M \simeq T\Gamma|_B,$$

for any  $B \in \text{Bis}(\Gamma)$ . Now by using the identifications (2.2) for any smooth bisection isotopy  $B_t$  with  $B_0 = M$  we get a unique smooth curve  $X_t$  in  $\text{Sect}_c(\ker T\beta)$  such that

$$(2.4) \quad \sigma^{B_t} X_t = \hat{X}_t.$$

Then  $\text{evol}_{\text{Bis}(\Gamma)}^r(X_t) = B_t$ , and  $\delta_{\text{Bis}(\Gamma)}^r(B_t) = X_t$ . Clearly  $\hat{X}_t = X_t = \tilde{X}_t$  on  $M$ .

### 3. Symplectic groupoids and algebroids

**DEFINITION.** A Lie groupoid  $\Gamma$  equipped with a symplectic form  $\omega$  is called *symplectic* if the graph of multiplication  $\text{graph}(m)$  is a lagrangian submanifold of  $(-\Gamma) \times \Gamma \times \Gamma$ . Here  $-\Gamma$  means the symplectic manifold  $(\Gamma, -\omega)$ .

Let us recall that a Poisson structure on  $M$  can be introduced by a bivector  $\Lambda$  such that  $[\Lambda, \Lambda] = 0$ , where  $[\cdot, \cdot]$  is the Schouten-Nijenhuis bracket (cf. [19]). Then the rank of  $\Lambda_x$  may vary but it is even everywhere. We have the 'musical' bundle homomorphism  $\Lambda^\sharp$  associated with  $\Lambda$  by

$$\Lambda^\sharp : T^*M \rightarrow TM, \quad \beta(\Lambda^\sharp \alpha) = \Lambda(\alpha, \beta).$$

In case  $\Lambda$  is nondegenerate (i.e.  $\text{rank}(\Lambda) = \dim(M)$ ), we get a symplectic structure  $\omega$ , and  $\Lambda^\sharp$  is an isomorphism, denoted by  $\omega^\sharp$ . The distribution  $\Lambda^\sharp(T_x^*M)$ ,  $x \in M$ , integrates to a generalized foliation such that  $\Lambda$  restricted to any leaf induces a symplectic structure. This foliation is called symplectic and denoted by  $\mathcal{F}_\Lambda$ . If the dimension of its leaves is constant, the Poisson structure  $\Lambda$  is called regular.

PROPOSITION 3.1 [3]. *If  $(\Gamma, \omega)$  is a symplectic groupoid then:*

(i) *the inversion  $i$  is an antisymplectomorphism (i.e.  $i^*\omega = -\omega$ ), and  $M$  is a lagrangian submanifold;*

(ii) *the foliations by fibers of  $\alpha$  and  $\beta$  are  $\omega$ -orthogonal;*

(iii) *the space of units  $M$  admits a Poisson structure  $\Lambda$  such that its symplectic foliation  $\mathcal{F}_\Lambda$  coincides with  $\mathcal{F}_\Gamma$ .*

(iv)  *$\alpha$  (resp.  $\beta$ ) is a Poisson morphism (resp. anti-morphism).*

*Such a groupoid will be usually denoted by  $(\Gamma, \omega) \rightrightarrows (M, \Lambda)$ .*

Observe that the set of all lagrangian bisections  $\text{Bis}(\Gamma, \omega)$  is a subgroup of  $\text{Bis}(\Gamma)$ . This group has natural left and right representations in  $(\Gamma, \omega)$ :

$$\psi^l : \text{Bis}(\Gamma, \omega) \ni C \mapsto \psi^l(C) = \{x \mapsto C.x\} \in \text{Symp}(\Gamma, \omega),$$

$$\psi^r : \text{Bis}(\Gamma, \omega) \ni C \mapsto \psi^r(C) = \{x \mapsto x.C\} \in \text{Symp}(\Gamma, \omega).$$

Now the corresponding representations  $\phi^l$  and  $\phi^r$  take their values in  $\text{Diff}(M, \Lambda)$ , the automorphism group of  $(M, \Lambda)$ .

EXAMPLES. 8. The coarse groupoid  $\Gamma = X \times X$  with  $(-\omega) \oplus \omega$  is a symplectic groupoid. Then  $\text{Bis}(\Gamma, \omega) = \text{Symp}(X)$ .

9. If  $M$  is a manifold then  $T^*M$ , where  $m$  is the addition in fibers and  $\pi_M = \alpha = \beta$ , is a Lie groupoid (Ex. 3).  $T^*M$  endowed with the canonical symplectic form  $\omega_M = -d\lambda_M$  is also a symplectic groupoid. In fact, the graph of  $m$

$$\text{graph}(m) = \{(x_3, x_2, x_1) : x_1 + x_2 - x_3 = 0\}.$$

This is the image of  $\mathcal{N}\Delta_M$ , the normal bundle of the diagonal  $\Delta_M \subset M^3$  in  $(T^*M)^3$ , into  $(T^*M)^3$  by the mapping  $(x_3, x_2, x_1) \mapsto (-x_3, x_2, x_1)$ . Notice that  $\mathcal{N}\Delta_M$  is lagrangian in  $(T^*M)^3$ , and the mapping is symplectic. So  $T^*M$  is indeed a symplectic groupoid.

10. Let  $\Gamma \rightrightarrows M$  be a Lie groupoid. Then the cotangent space  $T^*\Gamma$  equipped with  $\omega_\Gamma = -d\lambda_\Gamma$  carries a structure of symplectic groupoid with  $\mathcal{N}^*M$ , the conormal bundle of  $M$  in  $\Gamma$ , being the space of units. Here the multiplication, denoted  $\oplus$  as in Ex. 7, is determined by the equality

$$< \xi \oplus \eta, X \oplus Y > = < \xi, X > + < \eta, Y >, \quad \text{for } X, Y \in T\Gamma, \xi, \eta \in T^*\Gamma,$$

where  $<, >$  is the canonical pairing. Furthermore, the canonical projection  $p : T^*\Gamma \rightarrow \Gamma$  is an epimorphism of groupoids.

11. If  $G$  is a Lie group,  $T^*G$  admits two symplectic groupoid structures. The first one is given as above, and the second is the structure of transformation groupoid (Ex. 6), where  $G$  acts on  $g^*$  by the coadjoint action. As these structures obey a compatibility condition,  $T^*G$  carries a structure of *double* groupoid, cf. [3].

Let us recall the following concept:

DEFINITION. A Lie algebroid  $(T^*M, \{\cdot, \cdot\}, \rho)$  over  $M$  is called *symplectic* if the following conditions are fulfilled:

- (i) the  $(2,0)$ -tensor  $\Lambda$  given by  $\Lambda(\alpha, \beta) = \beta(\rho(\alpha))$ ,  $\forall \alpha, \beta \in \Omega_c^1(M)$ , is skew-symmetric;
- (ii) the space of all closed forms is a Lie subalgebra of  $(\text{Sect}(T^*M), \{\cdot, \cdot\})$ .

Clearly there is a one-to-one correspondence between symplectic algebroids over  $M$  and Poisson structures on  $M$ . Here  $\rho = \Lambda^\sharp$  and

$$\{\alpha, \beta\} = \iota_{\Lambda^\sharp(\alpha)} d\beta - \iota_{\Lambda^\sharp(\beta)} d\alpha + d\Lambda(\alpha, \beta).$$

PROPOSITION 3.2. *If  $(\Gamma, \omega) \rightrightarrows (M, \Lambda)$  is a symplectic groupoid then its associated algebroid  $\mathcal{A}(\Gamma)$  is identified with  $(T^*M, \{\cdot, \cdot\}, \Lambda^\sharp)$ , the symplectic algebroid of  $(M, \Lambda)$ . In particular,  $T^*M \simeq T\Gamma|_M/TM \simeq \ker T\beta$ .*

It is remarkable that any Poisson manifold can be represented as the space of units of a local symplectic groupoid, and that Proposition 3.2 still holds for local symplectic groupoids. Consequently, there is a bijection between symplectic algebroids and local symplectic groupoids [4], a local non-linear version of the third Lie theorem.

**4.  $\text{Bis}(\Gamma, \omega)$  as a Lie group.** The construction of a chart for  $\text{Bis}(\Gamma, \omega)$  at  $e = M$  starts by an observation that there are no topological restrictions in a small neighborhood of  $M$  in  $\Gamma$ .

LEMMA 4.1 [3]. *Let  $N$  be a not necessarily separated manifold, and let  $M \subset N$  be a separated paracompact manifold such that a submersion  $p : N \rightarrow M$  exists. Then there is a neighborhood  $U$  of  $M$  in  $N$  which is separated and with  $p$ -connected fibers.*

By a local addition we mean a diffeomorphism  $\mu : T^*M \supset U \rightarrow V \subset \Gamma$  such that  $\mu(0_u) = u$ ,  $\forall u \in M$ . In our case the existence of a local addition is ensured by the identification  $T\Gamma|_M/TM \simeq T^*M$ , and by the exponential mapping coming from a Riemannian metric.

LEMMA 4.2. *Let  $M \subset N$  be a closed submanifold, and let  $\omega_0, \omega_1$  be symplectic forms on  $N$  which are equal along  $M$ . Then there is a diffeomorphism  $\phi : U \rightarrow V$ , where  $U, V$  are open neighborhoods of  $M$  in  $N$  such that  $\phi^*\omega_1 = \omega_0$ ,  $\phi|_M = \text{id}_M$  and  $\phi_*|_{TN|_M} = \text{id}_{TN|_M}$ .*

The proof uses Moser's argument and the relative Poincaré lemma. For details, see [8, 43.11].

Any  $\theta \in \Omega^1(M)$  can be regarded as a section  $\theta : M \rightarrow T^*M$ , and  $T^*M$  is endowed with  $\omega_M = -d\lambda_M$ , where  $\lambda_M$  is the canonical 1-form on  $T^*M$ . The following is well-known.

PROPOSITION 4.3. *Under the above identification,  $\theta^*\lambda_M = \theta$ . Moreover,  $\theta(M)$  is lagrangian in  $T^*M$  iff  $d\theta = 0$ .*

For the regularity of  $\text{Bis}(\Gamma, \omega)$  the following is needed.

LEMMA 4.4 [8, 38.7]. *Let  $H$  be a topological Lie subgroup of a regular Lie group  $G$ . If there are an open neighborhood  $U \subset G$  of  $e$  and a smooth mapping  $p : U \rightarrow E$ , where  $E$  is a convenient vector space, such that  $p^{-1}(0) = U \cap H$  and  $p$  is constant on left cosets  $Hg \cap U$ , then  $H$  is regular.*

THEOREM 4.5. *Given a symplectic groupoid  $(\Gamma, \omega) \rightrightarrows (M, \Lambda)$ , the group  $\text{Bis}(\Gamma, \omega)$  is a closed subgroup of  $\text{Bis}(\Gamma)$  and a regular Lie group. Its Lie algebra coincides with  $Z\Omega_c^1(M)$ , the subalgebra of closed 1-forms on  $M$ .*

*Proof.* (See also [8], 43.12.) We fix a local addition  $\mu : T^*M \supset U_0 \rightarrow V_0 \subset \Gamma$ . We have two symplectic structures on  $U_0$ , namely the canonical one  $\omega_0 = \omega_M|_{U_0}$ , where  $\omega_M = -d\lambda_M$ , and  $\omega_1 = \mu^*\omega$ . Each of them has the vanishing pullback on the zero section  $0_{T^*M}$ . In view of Lemma 4.2 we have to show that, by shrinking  $U_0$  and  $V_0$  and modifying the  $\omega_i$ , we may get  $\omega_0|_{0_{T^*M}} = \omega_1|_{0_{T^*M}}$ .

To this end we observe that there is a vector bundle isomorphism  $\psi_0 : T(T^*M)|_{0_{T^*M}} \rightarrow T(T^*M)|_{0_{T^*M}}$  over  $\text{id}_{0_{T^*M}}$  such that  $\psi_0 = \text{id}_{T(0_{T^*M})}$  and  $\psi_0$  sends  $\omega_0$  to  $\omega_1$  on each fiber. Due to the partition of unity it suffices to construct  $\psi_0$  locally, and this is accomplished by considering lagrangian subbundles  $L_i$  complementary to  $T(0_{T^*M})$  with respect to  $\omega_i$ . When having  $\psi_0$  we define a diffeomorphism  $\psi : U_1 \rightarrow U_2$ , where  $U_1, U_2$  are open neighborhoods of  $0_{T^*M}$  in  $T^*M$ , such that  $T\psi|_{0_{T^*M}} = \psi_0$ . This is done by using a tubular neighborhood of  $0_{T^*M}$ .

Now, in view of 4.2, we get a diffeomorphism  $\phi$  of an open neighborhood of  $0_{T^*M}$  in  $T^*M$  onto another such a neighborhood which satisfies  $\phi^*\omega_1 = \omega_0$ ,  $\phi|_M = \text{id}_M$  and  $\phi_*|_{T(T^*M)|_{0_{T^*M}}} = \text{id}_{T(T^*M)|_{0_{T^*M}}}$ . We set

$$\rho := \mu \circ \phi : T^*M \supset U \rightarrow V \subset \Gamma.$$

Let  $\mathcal{U}$  be a neighborhood of  $e = M$  in  $\text{Bis}(\Gamma)$  consisting of all submanifolds  $B \subset \Gamma$  such that  $B^\beta : M \rightarrow \Gamma$  is compactly supported,  $B^\beta(M) \subset V$ , and so small that  $\mu^{-1}(B)$  is still the image of a  $\beta$ -section. We define a chart at  $e = M$  as follows

$$(4.1) \quad \begin{aligned} \Phi : \text{Bis}(\Gamma) \supset \mathcal{U} &\rightarrow \mathcal{V} \subset \Omega_c^1(M) \\ \Phi(B) &:= \rho^{-1} \circ B^\beta \circ (\pi \circ \rho^{-1} \circ B^\beta)^{-1}. \end{aligned}$$

Due to Proposition 4.3  $B \in \mathcal{U} \cap \text{Bis}(\Gamma, \omega)$  if and only if  $d\Phi(B) = 0$ . Therefore  $(\mathcal{U}, \Phi)$  is a submanifold chart at  $e = M$  for  $\text{Bis}(\Gamma, \omega)$  modelled on the subspace  $Z\Omega_c^1(M)$  of all closed forms on  $M$  with compact support.

Next for arbitrary  $C \in \text{Bis}(\Gamma, \omega)$  we get a submanifold chart at  $C$  as follows:  $\mathcal{U}_C := \{B : B.C^{-1} \in \mathcal{U}\}$  and  $\Phi_C(B) := \Phi(B.C^{-1})$ . Thus  $\text{Bis}(\Gamma, \omega)$  is a closed submanifold of  $\text{Bis}(\Gamma)$  and a Lie group.

Let  $C_t$  be a smooth isotopy in  $\text{Bis}(\Gamma, \omega)$  and  $X_t \in \text{Sect}_c(\ker T\beta)$  be defined by (3.4). By definition there is a time-dependent 1-form  $\theta_t$  on  $M$  such that

$$(4.2) \quad \mathbf{1}(X_t)\omega|_{T\Gamma|_M} = \theta_t.$$

Now if we set

$$c_t := \psi^r(C_t) \quad \text{and} \quad \tilde{X}_t := \delta_{\text{Symp}(\Gamma, \omega)}^r(c_t),$$

the smooth curve of vector fields  $\tilde{X}_t$  on  $\Gamma$  satisfies (cf. (3.3) and (3.4))  $\tilde{\sigma}^{C_t}X_t = \tilde{X}_t$ . Clearly,  $\tilde{X}_t$  are tangent to the  $\beta$ -fibers, and  $c_t$  are  $\beta$ -fibers preserving. Also,  $c_t|_M = C_t^\beta, \forall t$ .

We get the equality

$$(4.3) \quad \mathbf{1}(\tilde{X}_t)\omega = \beta^*\theta_t$$

on the whole  $\Gamma$ . Consequently,  $\theta_t$  is closed, as  $\beta^*\theta_t$  is closed.

Therefore, for any  $B_t \in C^\infty((\mathbb{R}, 0), (\text{Bis}(\Gamma), e))$  and  $X_t = \text{evol}_{\text{Bis}(\Gamma, \omega)}^r(B_t)$  we get by the regularity of  $\text{Symp}(\Gamma, \omega)$ , and by Prop. 3.2, the equivalence

$$B_t \in C^\infty((\mathbb{R}, 0), (\text{Bis}(\Gamma, \omega), e)) \Leftrightarrow \theta_t = \omega^\sharp X_t \in C^\infty(\mathbb{R}, Z\Omega_c^1(M)),$$

which ensures that the Lie algebra of  $\text{Bis}(\Gamma, \omega)$  is  $Z\Omega_c^1(M)$ , that is, that the restriction of  $\text{evol}_{\text{Bis}(\Gamma)}^r$  to  $Z\Omega_c^1(M)$  identifies with  $\text{evol}_{\text{Bis}(\Gamma, \omega)}^r$ .

Finally, let us consider  $p : \text{Bis}(\Gamma) \rightarrow \Omega^2(\Gamma)$  given by  $p(B) = \psi^r(B)^*\omega - \omega$ . It follows from Lemma 4.4 that  $\text{Bis}(\Gamma, \omega)$  is regular. ■

Since the neighborhood  $\Phi(\mathcal{U})$  above can be chosen convex we can state the following

**COROLLARY 4.6.** *The group  $\text{Bis}(\Gamma)$  is locally contractible and, consequently, locally arcwise connected.*

**REMARK.** Plausibly the monomorphisms  $\psi^l$  and  $\psi^r$  enable to introduce a Lie group structure on  $\text{Bis}(\Gamma, \omega)$  in another way, namely as a Lie subgroup of  $\text{Symp}(\Gamma, \omega)$ . This would make easier all reasonings concerning the flux and lagrangian bisection isotopies. However, this is impossible unless  $\Gamma$  is compact. The reason is that no isotopy of the form  $c_t = \psi_t^l(C_t)$  or  $c_t = \psi_t^r(C_t)$  is contained in  $\text{Symp}(\Gamma, \omega)_0$  (in our framework). Nonetheless, these representations are indispensable in section 5 and 6.

**5. The flux homomorphism.** The concept of the flux homomorphism was introduced by E. Calabi [2]. It is a basic invariant not only of the symplectomorphism groups, but also of some other transformation groups, cf. [17], [18]. The flux is still meaningful for the group of Lagrangian bisections (cf. [5], [22]). In light of Theorem 4.5 one can obtain the flux also in its local form which is necessary for a characterization of exact isotopies.

Let us fix the notation. For any locally arcwise connected topological group  $G$  its universal cover group  $\tilde{G}$  is the set of all pairs  $(g, \{g_t\})$ , where  $\{g_t\}$  is the homotopy rel. endpoints class of the path  $g_t$  in  $G$  such that  $g_0 = e$  and  $g_1 = g$ , endowed with the pointwise multiplication. By  $G_0$  we denote the component of  $e$  in  $G$ . Clearly  $\tilde{G}_0/\pi_1(G_0) = G_0$ , where  $\pi_1$  is the first homotopy group.

The multiplication in  $\tilde{G}$  can be also thought of as the juxtaposition of representants. The latter means that  $\{g_t\} \cdot \{f_t\} = \{g_t * f_t\}$  where

$$g_t * f_t = \begin{cases} f_{2t}, & \text{for } 0 \leq t \leq \frac{1}{2} \\ g_{2t-1} \circ f_1, & \text{for } \frac{1}{2} \leq t \leq 1. \end{cases}$$

These multiplications are the same on the homotopy level.

Given a symplectic groupoid  $(\Gamma, \omega) \rightrightarrows (M, \Lambda)$ , by using (4.2) and (4.3) we have the mapping

$$C^\infty(\mathbb{R}, \text{Bis}(\Gamma, \omega)) \ni C_t \mapsto \theta_t \in C^\infty(\mathbb{R}, Z\Omega_c^1(M))$$

which induces the flux homomorphism.

**THEOREM 5.1.** *The mapping  $\tilde{\mathcal{S}}_\Gamma : \widetilde{\text{Bis}(\Gamma, \omega)}_0 \rightarrow H_c^1(M)$  defined by*

$$\tilde{\mathcal{S}}_\Gamma(\{C_t\}) = \left[ \int_0^1 \theta_t dt \right]$$



is a well-defined continuous epimorphism (with the abelian structure on  $H^1(M)$ ), called the flux homomorphism for the symplectic groupoid  $\Gamma$ . If  $\Gamma$ , in addition, is compact then the relation between  $\tilde{\mathcal{S}}_\Gamma$  and  $\tilde{\mathcal{S}}$ , the flux for the symplectomorphism group  $\text{Symp}(\Gamma, \omega)$ , can be visualized in the following commutative diagram

$$\begin{array}{ccc} \widetilde{\text{Bis}(\Gamma, \omega)}_0 & \xrightarrow{\psi^r} & \widetilde{\text{Symp}(\Gamma, \omega)}_0 \\ \tilde{\mathcal{S}}_\Gamma \downarrow & & \downarrow \tilde{\mathcal{S}} \\ H_c^1(M) & \xrightarrow{\beta^*} & H_c^1(\Gamma) \end{array}$$

The proof is similar to that for symplectomorphisms. We emphasize the existence of  $\tilde{\mathcal{S}}_\Gamma$  for an arbitrary symplectic groupoid (not necessarily with  $M$  compact as in [22]). However, the diagram makes sense for  $\Gamma$  compact only, since otherwise no  $c_t = \psi^r(C_t)$  lies in  $\text{Symp}(\Gamma, \omega)_0$ .

EXAMPLES. 1. If  $\Gamma = M \times M$  is the coarse groupoid then  $\tilde{\mathcal{S}}_\Gamma$  is the usual flux for  $\text{Symp}(M, \omega)$ .

2. If  $\Gamma = T^*M$  then  $\text{Bis}(\Gamma)$  identifies with the space of all closed 1-forms, and  $\tilde{\mathcal{S}}_\Gamma$  assigns to 1-form its cohomology class.

In analogy with the symplectic case (cf. [2,10]) Theorem 4.5 enables us to define the local flux homomorphism.

COROLLARY 5.2. *If  $\omega$  is exact, i.e.  $\omega = -d\lambda$ , then  $\tilde{\mathcal{S}}_\Gamma(\{C_t\}) = [\lambda|_{TM} - (C_1^\beta)^*\lambda] = [(\lambda - c_1^*\lambda)|_{TM}]$ , where  $c_t = \psi^r(C_t)$ . In particular, the group of periods  $\Xi_\Gamma := \tilde{\mathcal{S}}_\Gamma(\pi_1(\text{Bis}(\Gamma, \omega)_0))$  is zero.*

*Proof.* Let  $X_t = \text{evol}_{\text{Bis}(\Gamma, \omega)}^r(C_t)$ ,  $X_t = \omega^\# \theta_t$ ,  $c_t = \psi^r(C_t)$ , and  $\tilde{X}_t := \delta_{\text{Symp}(\Gamma, \omega)}^r(c_t)$ . By composing each side of (4.2) with  $\beta^*$  we get and

$$\begin{aligned} \beta^* \theta_t &= c_t^* \beta^* \theta_t = c_t^* \beta^* 1_{X_t} \omega|_{T\Gamma|_M} = c_t^* 1_{\tilde{X}_t} \omega \\ &= -c_t^* 1_{\tilde{X}_t} d\lambda = -c_t^* L_{\tilde{X}_t} \lambda = -\frac{d}{dt} c_t^* \lambda. \end{aligned}$$

Hence

$$\int_0^1 \beta^* \theta_t = \lambda - c_1^* \lambda$$

holds on  $\Gamma$ . By restricting this equality to  $TM$  we get

$$\int_0^1 \theta_t = (\lambda - c_1^* \lambda)|_{TM},$$

as  $\beta^* \theta|_{TM} = \theta$ . In view of  $C_t^\beta = c_t|_M$  this yields the required equalities. ■

DEFINITION. Let  $\Phi : \mathcal{U} \rightarrow \mathcal{V}$  be a chart for  $\text{Bis}(\Gamma, \omega)$  at  $e = M$ . If  $C_t$  is a lagrangian isotopy such that  $C_t \in \mathcal{U}$  for any  $t$  then

$$\tilde{\mathcal{S}}_\Gamma^\Phi(\{C_t\}) := -[\theta_1] \in H_c^1(M),$$

where  $\theta_t = \Phi(C_t)$ .  $\tilde{\mathcal{S}}_\Gamma^\Phi$  is called the local flux homomorphism for  $\text{Bis}(\Gamma, \omega)$ .

PROPOSITION 5.3.  $\tilde{\mathcal{S}}_\Gamma^\Phi$  does not depend on the choice of  $\Phi$  and extends  $\tilde{\mathcal{S}}_\Gamma$ .

*Proof.* Let  $C_t$  be a lagrangian bisection isotopy. Then  $\theta_t$  is a lagrangian bisection isotopy in  $U \subset T^*M$  with respect to the canonical symplectic form  $\omega_M = -d\lambda_M$ . Let  $\tilde{\mathcal{S}}_M$  be the flux homomorphism for the symplectic groupoid  $T^*M$  (Ex. 9). Then

$$\tilde{\mathcal{S}}_M(\{\theta_t\}) = \tilde{\mathcal{S}}_M(\{\Phi(C_t)\}) = \phi_{C_t}^* \tilde{\mathcal{S}}_\Gamma(\{C_t\}) = \tilde{\mathcal{S}}_\Gamma(\{C_t\}),$$

where  $\phi_{C_t} = \pi_M \circ \rho \circ C_t^\beta$ , by the homotopy invariance. But in view of Cor. 5.2 and Prop. 4.3 we get

$$\tilde{\mathcal{S}}_M(\{\theta_t\}) = [\lambda_M|_{T(0_{T^*M})} - \theta_1^* \lambda_M] = [0_{T^*M}^* \lambda_M - \theta_1^* \lambda_M] = -[\theta_1],$$

as required. ■

**6. A characterization of exact isotopies.** A lagrangian bisection isotopy  $C_t$  is called *exact* if  $(C_t) = \omega^\sharp du_t$  for some smooth curve  $u_t$  in  $C_c^\infty(M)$ . Let  $\text{Bis}^{ex}(\Gamma, \omega)$  be the set of all exact lagrangian bisections. That is, by definition  $C \in \text{Bis}^{ex}(\Gamma, \omega)$  iff it can be joined with  $e = M$  by an exact lagrangian bisection isotopy.

**PROPOSITION 6.1.** *A lagrangian isotopy  $C_t$  is exact iff  $\delta_{\text{Symp}(\Gamma, \omega)}^r(c_t) = \omega^\sharp \beta^*(du_t)$ , where  $c_t = \psi^r(C_t)$ .*

Indeed, it follows from the fact that  $\beta$  is a Poisson anti-morphism.

**PROPOSITION 6.2.**  *$\text{Bis}^{ex}(\Gamma, \omega)$  is a path-connected normal subgroup of  $\text{Bis}(\Gamma, \omega)$ .*

*Proof.* First we check that  $\text{Bis}^{ex}(\Gamma, \omega)$  is a group. Let  $B_t, C_t$  be exact isotopies, that is  $(B_t) = \omega^\sharp(dv_t)$ ,  $(C_t) = \omega^\sharp(du_t)$  for some smooth families of  $C^\infty$ -functions  $u_t$  and  $v_t$ . If  $\psi^r(B_t) = b_t$ , and  $\psi^r(C_t) = c_t$  then  $\psi^r(B_t.C_t) = c_t \circ b_t$ . It is apparent that

$$\delta_{\text{Symp}(\Gamma, \omega)}^r(c_t \circ b_t) = \omega^\sharp d(\beta^* u_t + \beta^* v_t \circ c_t^{-1}) = \omega^\sharp d.(\beta^* u_t + \beta^* v_t).$$

The second equality holds by  $\beta \circ c_t = \beta$ . In view of Prop. 6.1  $B_t.C_t$  is still exact. To get that  $C_t^{-1}$  is exact we use the equality

$$\delta_{\text{Symp}(\Gamma, \omega)}^r(c_t^{-1}) = \omega^\sharp d(-u_t \circ c_t) = \omega^\sharp d(-u_t).$$

It follows that  $\text{Bis}^{ex}(\Gamma, \omega)$  is a group. Finally,  $\text{Bis}^{ex}(\Gamma, \omega)$  is normal since

$$\delta_{\text{Symp}(\Gamma, \omega)}^r(b^{-1} \circ c_t \circ b) = \omega^\sharp d(u_t \circ b). \quad \blacksquare$$

Now by repeating an argument for the symplectomorphism group (cf. [10]) it is possible to relate lagrangian bisection isotopies and  $\tilde{\mathcal{S}}_\Gamma$ . Consequently, under some assumption it is introduced a regular Lie group structure on  $\text{Bis}^{ex}(\Gamma, \omega)$  (Theorem 6.8).

**PROPOSITION 6.3.**  *$C_t$  is an exact isotopy iff  $\tilde{\mathcal{S}}_\Gamma(\{C_\tau\}_{0 \leq \tau \leq t}) = 0$ ,  $\forall t$ .*

*Proof.* ( $\Rightarrow$ ) It follows by the definition of  $\tilde{\mathcal{S}}_\Gamma$ . ( $\Leftarrow$ ) Notice that  $C_t$  is exact for  $t$  small due to the local definition of  $\tilde{\mathcal{S}}_\Gamma$ . Next we extend  $t$  by replacing successively  $\phi_t$  by  $C_t.C_{t_0}^{-1}$  with  $t - t_0$  small enough. ■

**PROPOSITION 6.4.** *If  $C \in \text{Bis}(\Gamma, \omega)_0$  then  $C$  is an exact bisection if and only if there is a lagrangian bisection isotopy  $C_t$  with  $C_0 = M$  and  $C_1 = C$  such that  $\tilde{\mathcal{S}}_\Gamma(\{C_t\}) = 0$ . Furthermore, if  $\tilde{\mathcal{S}}_\Gamma(\{B_t\}) = 0$ ,  $B_t \in \text{Bis}(\Gamma, \omega)$ , then  $B_t$  is homotopic with fixed endpoints to an exact isotopy.*

*Proof.* If  $C$  is exact then there is an exact isotopy  $C_t$  joining  $C$  with  $M$ . Then  $\mathbf{1}(X_t)\omega = dv_t$  for  $v_t \in C_c^\infty(M)$ , where  $X_t = \delta_{\text{Bis}(\Gamma, \omega)}^r(C_t)$ . Hence  $\tilde{\mathcal{S}}_\Gamma(\{C_t\}) = 0$  as  $[dv_t] = 0$ .

In order to show the converse let  $C_t = \text{evol}_{\text{Bis}(\Gamma, \omega)}^r(X_t)$  be such that  $\tilde{\mathcal{S}}_\Gamma(\{C_t\}) = 0$ , that is  $\int_0^1 \iota(X_t)\omega dt = dv$ ,  $v \in C_c^\infty(M)$ . Here  $v$  can be chosen compactly supported as all  $\text{supp } X_t$  are in a fixed compact subset. Let  $C_t^v$  be the isotopy of  $X_v = \omega^\# dv$ . It suffices to consider  $(C_1^v)^{-1}.C$  instead of  $C$ . Thus, reparametrizing if necessary, we may assume that  $\int_0^1 X_t dt = 0$  as  $\mathbf{1}(\int_0^1 X_t dt)\omega = 0$ .

Next we set  $Y_t = -\int_0^t X_\tau d\tau$ . Then if  $s \mapsto B_t^s$  be the isotopy of  $Y_t$  we get for  $\hat{C}_t = B_t^1.C_t$  that  $C_1 = \hat{C}_1$  and  $\tilde{\mathcal{S}}_\Gamma(\{\hat{C}_\tau\}_{0 \leq \tau \leq t}) = 0$  for any  $t$ . In fact,

$$\tilde{\mathcal{S}}_\Gamma(\{B_\tau^1\}_{0 \leq \tau \leq t}) = \tilde{\mathcal{S}}_\Gamma(\{B_t^s\}_{0 \leq s \leq 1}) = [\mathbf{1}(Y_t)\omega]$$

in view of the homotopy rel. endpoints invariance. Therefore

$$\begin{aligned} \tilde{\mathcal{S}}_\Gamma(\{\hat{C}_\tau\}_{0 \leq \tau \leq t}) &= \tilde{\mathcal{S}}_\Gamma(\{B_\tau^1\}_{0 \leq \tau \leq t}) + \tilde{\mathcal{S}}_\Gamma(\{C_\tau\}_{0 \leq \tau \leq t}) \\ &= [\mathbf{1}(Y_t)\omega] + \left[ \int_0^t \mathbf{1}(X_\tau)\omega d\tau \right] = 0. \end{aligned}$$

By Prop. 6.3 this proves the first assertion, and the proof of the second can be deduced from the above argument. ■

Let  $\Xi_\Gamma = \tilde{\mathcal{S}}_\Gamma(\pi_1(\text{Bis}(\Gamma, \omega)))$ . In the symplectic case  $\Xi_\Gamma$  is called the *group of periods*. Observe that  $\Xi_\Gamma$  is countable since  $\pi_1(\text{Bis}(\Gamma, \omega))$  is countable. This follows from the fact that  $\text{Bis}(\Gamma, \omega)$  has the homotopy type of a countable simplicial complex ([12]).

Notice that the form  $\theta_1 = \Phi(C_1)$ , where  $\Phi: \mathcal{U} \rightarrow \mathcal{V}$  is a chart for  $\text{Bis}(\Gamma, \omega)$  at  $e$ , need not be exact even if  $C_t$  is an exact isotopy and  $C_1 \in \mathcal{U}$ . However we have the following

**PROPOSITION 6.5.**  *$C \in \text{Bis}(\Gamma, \omega) \cap \mathcal{U}$  if and only if  $[\Phi(C)] \in \Xi_\Gamma$ .*

*Proof.* ( $\Rightarrow$ ) We define the lagrangian bisection isotopy  $B_t$  by  $\Phi(B_t) = t\theta$ , where  $\theta = \Phi(C)$  ( $B_1 = C$ ). But there is an exact isotopy  $C_t$  joining  $C = C_1$  with  $M = C_0$ . Then for the loop  $C_{1-t} * B_t$ , one gets  $[\theta] = -\tilde{\mathcal{S}}_\Gamma(\{B_t\}) = \tilde{\mathcal{S}}_\Gamma(\{C_t\}) - \tilde{\mathcal{S}}_\Gamma(\{B_t\}) = -\tilde{\mathcal{S}}_\Gamma(\{C_{1-t} * B_t\}) \in \Xi_\Gamma$ .

( $\Leftarrow$ ) We use Prop. 6.4. There is a lagrangian bisection loop  $C_t$  such that  $\tilde{\mathcal{S}}_\Gamma(\{C_t\}) = -[\Phi(C)]$ . Then  $\tilde{\mathcal{S}}_\Gamma(\{D_t\}) = 0$ , where  $D_t = B_t * C_t$  and  $\Phi(B_t) = [(1-t)\Phi(C)]$ . Therefore  $D_t$  is homotopic to an exact bisection isotopy joining  $M$  with  $C$ . Thus  $C \in \text{Bis}^{ex}(\Gamma, \omega)$ . ■

**PROPOSITION 6.6.** *Every smooth curve  $C_t$  in  $\text{Bis}^{ex}(\Gamma, \omega)$  is an exact bisection isotopy.*

*Proof.* For  $t \leq \epsilon$  one has  $C_t \in \mathcal{U}$ . It follows by Prop. 6.5 that  $[\theta_t] \in \Xi_\Gamma$  for small  $t$ , where  $\theta_t = \Phi(C_t)$ . This means that  $[\theta_t] = 0$  as  $\theta_0 = 0$  and  $\Xi_\Gamma$  is countable. Therefore we have  $\tilde{\mathcal{S}}_\Gamma(\{C_\tau\}_{0 \leq \tau \leq t}) = 0$  for  $t \leq \epsilon$ . Thanks to Prop. 6.3 the  $C_t$  is an exact isotopy for  $t \leq \epsilon$ . By taking  $C_t.C_\epsilon^{-1}$  instead of  $C_t$  this procedure extends the argument for all  $t$ . ■

Since  $\text{Bis}(\Gamma, \omega)_0 = \widetilde{\text{Bis}(\Gamma, \omega)_0} / \pi_1(\text{Bis}(\Gamma, \omega)_0)$  the flux  $\tilde{\mathcal{S}}_\Gamma$  induces another homomorphism  $\mathcal{S}_\Gamma: \text{Bis}(\Gamma, \omega)_0 \rightarrow H_c^1(M) / \Xi_\Gamma$ .

**COROLLARY 6.7.**  *$\text{Ker}(\mathcal{S}_\Gamma)$  coincides with  $\text{Bis}^{ex}(\Gamma, \omega)$ .*

Indeed, it follows from the local form of the flux and Prop. 6.5 for any  $C$  sufficiently near  $M$ . This can be extended to the whole  $\text{Bis}(\Gamma, \omega)_0$  by the same argument as in Prop. 6.4.

Now we are in a position to define a Lie group structure on  $\text{Bis}^{ex}(\Gamma, \omega)$ .

**THEOREM 6.8.** *If  $\Xi_\Gamma \subset H_c^1(M)$  is discrete (or  $0$  is an isolated point in  $\Xi_\Gamma$ ) then  $\text{Bis}^{ex}(\Gamma, \omega)$  is a regular Lie group with  $B\Omega_c^1(M)$ , the space of exact compactly supported 1-forms on  $M$ , as its Lie algebra.*

*Proof.* Assume the notation of the proof of Theorem 4.5, and let

$$\Phi : \text{Bis}(\Gamma) \supset \mathcal{U} \rightarrow \mathcal{V} \subset \Omega_c^1(M)$$

be a chart at  $e$  given by (4.1). If  $C \in \text{Bis}^{ex}(\Gamma, \omega) \cap \mathcal{U}$  then  $\theta = \Phi(C) \in Z\Omega_c^1(M)$  and  $[\theta] \in \Xi_\Gamma$  (Prop. 6.5). By the assumption, taking possibly a smaller  $\mathcal{U}$ , we have  $C \in \text{Bis}^{ex}(\Gamma, \omega) \cap \mathcal{U}$  if and only if  $\theta = \Phi(C)$  is exact. Proceeding as in the proof of 4.5 we see that  $\text{Bis}^{ex}(\Gamma, \omega)$  is a submanifold of  $\text{Bis}(\Gamma, \omega)$ , and since the composition and inversion are smooth by restriction, it is a Lie group.

By definition of  $\text{Bis}^{ex}(\Gamma, \omega)$  the restriction of  $\text{evol}_{\text{Bis}(\Gamma, \omega)}^r$  to  $\text{Bis}^{ex}(\Gamma, \omega)$  is  $\text{evol}_{\text{Bis}^{ex}(\Gamma, \omega)}^r$ . Thus  $B\Omega_c^1(M)$  is identified as the Lie algebra of  $\text{Bis}^{ex}(\Gamma, \omega)$ . Finally, setting  $p = \mathcal{S}_\Gamma$  it follows from Cor. 6.7 and Lemma 4.4 that  $\text{Bis}^{ex}(\Gamma, \omega)$  is regular. ■

**7. Final remarks.** The third theorem of Lie asserts that any finite dimensional Lie algebra is actually the Lie algebra of a Lie group. Since the paper by van Est and Korthagen [6] it is well known that, in general, this theorem is no longer true in the infinite dimensional case. Nevertheless, there are several generalizations of the third Lie theorem. First of all, some basic facts can be carried over from Lie groups to Lie or symplectic groupoids, cf. [14], [15], [4]. Next, the third Lie theorem still holds for remarkable infinite dimensional Lie algebras, e.g. the Poisson algebra of any symplectic or locally conformal symplectic manifold ([1], [7]).

Notice that Theorem 4.5 and 6.8 can be interpreted as follows. A Poisson manifold  $(M, \Lambda)$  is called integrable if it can be realized as the space of units of a symplectic groupoid. Given a symplectic groupoid  $(\Gamma, \omega) \rightrightarrows (M, \Lambda)$  such that  $\Xi_\Gamma = \pi_1(\text{Bis}(\Gamma, \omega)_0)$  is discrete, the exact sequence of Lie algebras

$$0 \rightarrow B\Omega_c^1(M) \rightarrow Z\Omega_c^1(M) \rightarrow H_c^1(M) \rightarrow 0,$$

where  $H_c^1(M)$  is regarded as an abelian Lie algebra, can be integrated to the exact sequence of regular Lie groups

$$1 \rightarrow \text{Bis}^{ex}(\Gamma, \omega) \rightarrow \text{Bis}(\Gamma, \omega)_0 \rightarrow H_c^1(M)/\Xi_\Gamma \rightarrow 0.$$

In [19] it has been shown that for any (regular) foliation or any Poisson structure with regular symplectic foliation the related Lie algebras of vector fields (tangent to the foliation) can be integrated analogously as in the transitive case. Unfortunately these results do not encompass the singular case. Let us also remark that the regular transitive case cannot be treated in terms of groupoid bisections, i.e. the leaf preserving diffeomorphisms cannot be expressed, in general, in terms of bisections. The reason is that in view of the "holonomic imperative" of a groupoid over a foliated manifold ([16], [13]) to any bisection

of such a groupoid is attached its holonomy class. Consequently, Lie groups considered in [19] are modelled on the space of foliated 1-forms, rather than on the space of ordinary 1-forms.

### References

- [1] A. Banyaga and P. Donato, *Some remarks on the integration of the Poisson algebra*, J. Geom. Phys. 19 (1996), 368–378.
- [2] E. Calabi, *On the group of automorphisms of a symplectic manifold*, in: Problems in Analysis (symposium in honour of S. Bochner), Princeton University Press, 1970, 1–26.
- [3] A. Coste, P. Dazord and A. Weinstein, *Groupoïdes symplectiques*, Publ. Dpt. Math. Univ. C. Bernard - Lyon 1 2/A (1987), 1–62.
- [4] P. Dazord, *Groupoïdes symplectiques et troisième théorème de Lie “non-linéaire”*, Géométrie Symplectique et Mécanique, Lect. Notes in Math. 1416, Springer, 39–74.
- [5] P. Dazord, *Lie groups and algebras in infinite dimension: A new approach*, Contemporary Math. 179 (1994), 17–44.
- [6] W. T. van Est and T. J. Korthagen, *Non enlargible Lie algebra*, Indag. Math. 26 (1964), 15–31.
- [7] S. Haller and T. Rybicki, *Integrability of the Poisson algebra on a locally conformal symplectic manifold*, Rend. Circ. Mat. Palermo Suppl. 63 (2000), 89–96.
- [8] A. Kriegl and P. W. Michor, *The Convenient Setting of Global Analysis*, Mathematical Surveys and Monographs 53, Amer. Math. Soc., 1997.
- [9] K. Mackenzie, *Lie Groupoids and Lie Algebroids in Differential Geometry*, LMS Lecture Notes Series, 124, Cambridge Univ. Press, 1987.
- [10] D. McDuff and D. Salamon, *Introduction to Symplectic Topology*, Clarendon Press, Oxford, 1995.
- [11] H. Omori, *Infinite-Dimensional Lie Groups*, Transl. Math. Monographs, A.M.S., 1997.
- [12] R. Palais, *Homotopy theory of infinite dimensional manifolds*, Topology 5 (1966), 1–16.
- [13] J. Phillips, *The holonomic imperative and the homotopy groupoid of a foliated manifold*, Rocky Mountain J. Math. 17 (1987), 151–165.
- [14] J. Pradines, *Théorie de Lie pour les groupoïdes différentiables*, C. R. Acad. Sci. Paris 263 (1966), 907–910.
- [15] J. Pradines, *Troisième théorème de Lie sur les groupoïdes différentiables*, C. R. Acad. Sci. Paris 267 (1968), 21–23.
- [16] J. Pradines, *Feuilletages: Holonomie et graphes locaux*, C. R. Acad. Sci. Paris 289 (1984), 297–300.
- [17] T. Rybicki, *On the flux homomorphism for regular Poisson manifolds*, Rend. Circ. Mat. Palermo Suppl. 54 (1998), 91–99.
- [18] T. Rybicki, *The flux homomorphism in the foliated case*, in: Differential Geometry and Applications, Satellite Conference of ICM, Berlin, 1998, Brno, Masaryk University, 1999, 413–418.
- [19] T. Rybicki, *On foliated, Poisson and Hamiltonian diffeomorphisms*, Diff. Geom. Appl. 15 (2001), 33–46.
- [20] J. M. Souriau, *Groupes différentiels de physique mathématique*, South Rhone seminar on geometry, II, Travaux en Cours, Hermann, Paris, 1984, 73–119.
- [21] I. Vaisman, *Lectures on the Geometry of Poisson Manifolds*, Progress in Math. 118, Birkhäuser, Basel, 1994.
- [22] P. Xu, *The flux homomorphism on symplectic groupoids*, Math. Z. 226 (1997), 575–597.