

On the identity of Morrey-Calkin and Schauder-Sobolev spaces

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§1. Introduction. In direct methods of the calculus of variations for quadratic functionals, and in applications of Hilbert space theory to the boundary value problems for second order elliptic equations (Friedrichs' method) a fundamental part is played by a class of W_a^1 -spaces, which were first defined by J. Schauder. The study of those spaces was next developed by Sobolev [4] and his school.

On the other hand a class of \mathfrak{P}_a -spaces was discovered by Ch. B. Morrey jr. and Calkin [3]. This class was next applied by Morrey [2] in his fundamental research in connection with the calculus of variations and second order quasilinear elliptic equations.

Several months ago K. Maurin stated the hypothesis that the spaces \mathfrak{P}_2 and W_2^1 are the same. The paper which I am going to present goes still farther. It proves the identity of W_a^1 and \mathfrak{P}_a for a>1.

The theories of spaces \mathfrak{P}_a and W_a^1 have been developed independently. There are theorems whose proofs are trivial in the theory of W_a^1 -spaces (e. g. those of completeness) and rather difficult in \mathfrak{P}_a , but there are more theorems that are trivial in \mathfrak{P}_a but not in W_a^1 (we think this to be a consequence of the fact that \mathfrak{P}_a -spaces are better known than

 W_a^1). The theorem which will be proved in this paper gives us a possibility of simplifying some proofs and enriches the theory of Schauder-Sobolev spaces by new theorems.

§ 2. Notation and definitions. In our considerations we shall denote by G a fixed and bounded domain of N-dimensional arithmetical space. The points of this domain will be denoted by small letters of latin alphabet. Consequently we have $x=(x_1,\ldots,x_N),\ y=(y_1,\ldots,y_N),\$ and for $x_1,\ldots,x_{k-1},x_{k+1},\ldots,x_N$ we shall write x_k' . We use the symbol [ab] to denote the N-dimensional $cell,\ i.e.$ a set of points x for which $a_i\leqslant x_i\leqslant b_i$ $(i=1,2,\ldots,N)$. Similarly, $[a_k',b_k']$ is a set of points x for which $a_i\leqslant x_i\leqslant b_i$ $(i=1,2,\ldots,k-1,k+1,\ldots,N),\$ and (x_k',a_k) is the point $(x_1,\ldots,x_{k-1},u_k,x_{k+1},\ldots,x_N).$

Definition 1. A function f(x) which is defined on the region G is of class $\mathfrak{P}(G)$ if

1° f is summable on each cell $[ab] \subset G$,

2° there exist functions v_1, \ldots, v_N , satisfying 1°, such that

$$\smallint_a^b v_k(x) \, dx = \smallint_{a_k'}^{b'} \left(f(x_k', b_k) - f(x_k', a_k) \right) \, dx_k'$$

holds for almost all interior cells of G (i. e. for all cells [ab] for which the point (ab) does not belong to the set of 2N-dimensional measure zero).

Definition 2. The generalized partial derivative $D_{x_k}f$ (in the sense of Morrey-Calkin) with respect to x_k of the function f of class $\mathfrak{P}(G)$ is a Lebesgue derivative of the set function $\int v_k(x) dx$.

It is clear that the equality $D_{x_k} t = v_k$ holds almost everywhere.

Definition 3. A function f is of class $\mathfrak{P}_a(G)$ if

1º f is of class $\mathfrak{P}(G)$,

 $2^{\circ} f$ and $D_{x_k} f(k=1,2,\ldots,N)$ are of class $L^{\alpha}(G)$.

In consequence of condition $2^{\rm o}$ of definition 3 we can define in $\mathfrak{P}_a(G)$ a norm

$$||f||^a = \int_G \left\{ |f(x)|^a + \left[\sum_{k=1}^N (D_{x_k} f(x))^2 \right]^{a/2} \right\} dx.$$

It has been proved by Morrey and Calkin that with this norm $\mathfrak{P}_{\alpha}(G)$ is a Banach space (the addition and the multiplication by numbers being defined in the ordinary way). In the case of $\alpha=2$ it is a Hilbert space.

Definition 4. A function f is of class $C_c^{\infty}(G)$ if

1° h is of class $C^{\infty}(G)$,

2° a support of h is compact in G (i. e. a closure of the set of points x for which $h(x) \neq 0$ is compact in G).

Definition 5. The space $W'_a(G)$, a>1, is defined as the *completion* (i. e. the space of classes of all fundamental and equivalent sequences) of $C^{\infty}(G)$ in the sense of the norm

$$||h||^{\alpha} = \int_{G} \left\{ |h(x)|^{\alpha} + \left[\sum_{k=1}^{N} \left(\frac{\partial h(x)}{\partial x_{k}} \right)^{2} \right]^{\alpha/2} \right\} dx.$$

Definition 6. A function f of the class $L^a(G)$ is differentiable with respect to x_k in the sense of Sobolev if there exists a function g of the class $L^a(G)$ such that the equality

$$\int_{G} f(x) \frac{\partial h(x)}{\partial x_{k}} dx = -\int_{G} g(x) h(x) dx$$

holds for all functions $h \in C_0^{\infty}(G)$.



Therefore $g_{\overline{det}} \partial [f(x)]/\partial x_k$ is a partial derivative of f with respect to x_k in the sense of Sobolev.

§ 3. Fundamental theorem. In this section we shall give a proof of the following theorem.

THEOREM. The spaces $\mathfrak{P}_a(G)$ and $W^1_a(G)$ are equivalent in the following sense: if $f \in \mathfrak{P}_a(G)$, then $f \in W^1_a(G)$ and inversely. Moreover, the existence of derivatives of f in the Morrey-Calkin sense is equivalent to the existence of corresponding derivatives in the sense of Sobolev and the equality $\partial [f]/\partial x_k = D_{x_k} f$ holds almost everywhere in G.

Proof. In proving this theorem we shall use the following well-known results:

THEOREM 1 (Morrey-Calkin (v. [2] and [3])). The necessary and sufficient condition that f be of class $\mathfrak{P}(G)$ is that it satisfy 1° of definition 1 and that for each cell $[ab] \subset G$ there exist summable functions $v_k(x)$ and a sequence $\{f_p(x)\}$, each f_p satisfying a uniform Lipschitz condition on [ab], such that

$$\lim_{p\to\infty}\int_a^b \left\{ |f_p(x)-f(x)| + \sum_{k=1}^N \left| \frac{\partial f_p(x)}{\partial x_k} - v_k \right| \right\} dx = 0.$$

THEOREM 2 (Sobolev)¹). $W^1_a(G)$ is the space of all functions of class $L^a(G)$ which are differentiable in the sense of Sobolev with respect to x_k for $k=1,2,\ldots,N$.

From theorem 1 it immediately follows that $W_a^1(G) \subset \mathfrak{P}_a(G)$. Indeed, let $f \in W_a^1(G)$ and $\{f_n\}$ be a sequence of $f_n \in C^{\infty}(G)$ such that

$$\lim_{p\to\infty}||f_p-f||_{W_a^1}=0.$$

This sequence satisfies of course the conditions of theorem 1. Let in the space L^a

$$v_k = \lim_{p \to \infty} \frac{\partial f_p}{\partial x_k}.$$

From the inequality of Hölder we get

$$\int_{a}^{b} |f(x) - f_{p}(x)| \ dx \leqslant \sqrt[p]{\int_{a}^{b} |f(x) - f_{p}(x)| \ dx} \cdot \sqrt[p]{|ab|} \leqslant ||f - f_{p}||_{W_{a}^{1}} \sqrt[p]{|ab|}.$$

¹⁾ See [4]; this follows also from Friedrichs' theorem [1].

We have also

$$\begin{split} \int\limits_a^b \left| v_k(x) - \frac{\partial f_p(x)}{\partial x_k} \right| \, dx \leqslant & \sqrt[3]{\int\limits_a^b \left| v_k(x) - \frac{\partial f_p(x)}{\partial x_k} \right| \, dx} \cdot \sqrt[\beta]{|ab|} \leqslant \|f - f_p\|_{\mathcal{W}_a^1} \sqrt[\beta]{|ab|} \; , \\ & \frac{1}{a} + \frac{1}{\beta} = 1 \; , \end{split}$$

and this, by the definition of functions v_k , completes the proof of our inclusion.

We shall now prove the inverse inclusion. For this purpose we shall prove the following lemmas:

LEMMA 1. If $f \in L^a(G)$ is differentiable with respect to x_k in the sense of Lebesgue (i. e. if there exists a function f_{x_k} such that $f(x) = \int f_{x_k}(x) dx_k + O$), and the derivative in the sense of Lebesgue of f with respect to x_k is of class $L^a(G)$, then f is differentiable with respect to x_k in the sense of Sobolev and the respective derivatives are equal almost everywhere in G.

Proof. Let $h \in C_c^{\infty}(G)$ and D be the support of h in G. We shall restrict ourselves to the case where D is a normal domain with respect to the hyperplane $x_k = 0$. In other cases we divide D into normal domains.

We use the Lebesgue theorem on integrating by parts. We have

$$\int_{\mathcal{G}} f(x) \frac{\partial h(x)}{\partial x_k} dx = \int_{\mathcal{D}} f(x) \frac{\partial h(x)}{\partial x_k} dx = \int_{\mathcal{D}_k} \int_{a(x'_k)}^{b(x'_k)} f(x'_k, x_k) \frac{\partial h(x'_k, x_k)}{\partial x_k} dx'_k$$

$$= \int_{\mathcal{D}_k} \left[f(x'_k, x_k) h(x'_k, x_k) \right]_{a(x'_k)}^{b(x'_k)} dx'_k - \int_{\mathcal{G}} f_{x_k}(x) h(x) dx,$$

where $a(x'_k)$ and $b(x'_k)$ are the points at which the line (x'_k,t) intersects the boundary of domain D, and D_k is the projection of D on the hyperplane $x_k=0$; we denote by f_{x_k} the Lebesgue derivative of f with respect to x_k .

The condition h(x) = 0 on the boundary of domain D gives us the assertion

$$\int_{\mathcal{G}} f(x) \frac{\partial h(x)}{\partial x_k} dx = -\int_{\mathcal{G}} h(x) g(x) dx, \quad \text{where} \quad g = \frac{\partial f}{\partial x_k}.$$

LEMMA 2. If $f \in \mathfrak{P}_a(G)$, then f is differentiable in the sense of Lebesgue with respect to x_k $(k=1,2,\ldots,N)$ and the derivatives of Lebesgue are equal almost everywhere to those of Morrey-Calkin.

Proof. From the condition 2° of definition 1 and from a theorem of Fubini it follows that there exists such a number a_k that the equality

$$\int\limits_{a_k'}^{b_k'} \int\limits_{a_k}^{x_k} v(x) \, dx = \int\limits_{a_k'}^{b_k'} \left(f(x_k', x_k) - f(x_k', a_k) \right) dx_k'$$



holds for almost all x_k and for almost all (N-1) dimensional cells $[a'_kb'_k]$ for which $\lceil ab \rceil \subset G$. Hence it follows that

$$\int_{a_k}^{x_k} v(x) dx_k = f(x_k', x_k) + C, \quad \text{q. e. d.}$$

From the condition 2° of definition 3 we have $D_{x_k} f \in L^a(G)$ and by lemma 1 and theorem 2 the proof of inclusion $\mathfrak{P}_*(G) \subset W^1_*(G)$ is completed.

The proof presented here gives also the equality almost everywhere of the derivatives of Morrey-Calkin and of Sobolev. This completes the proof of the theorem.

- § 4. Some applications of the proved theorem. The fundamental theorem makes it possible to transfer the known properties of Morrey-Calkin spaces to the theory of Schauder-Sobolev and inversely. The proofs of some theorems are simplified in that way.
- 1. From the definition of W_a^1 -space we have drawn a not very obvious conclusion about the completeness of the \mathfrak{P}_a -space.
- 2. We think that it would be very interesting to transfer the so-called "substitution theorem" to the theory of Schauder-Sobolev.

Let f be of class $W^1_a(G)$, $D \subset G$ and $g \in W^1_a(D)$ where g = f on the boundary of D. Then the function h defined as

$$h = \begin{cases} f(x) & \text{if} & x \in G - D, \\ g(x) & \text{if} & x \in D, \end{cases}$$

is of class $W^1_{\alpha}(G)$ and

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ight]}{\partial x_k} & ext{if} & x\,\epsilon\,G-D, \ rac{\partial \left[g\left(x
ight)
ight]}{\partial x_k} & ext{if} & x\,\epsilon\,D, \end{cases} k=1,2,\ldots,N.$$

3. In the theory of Morrey-Calkin a remarkable part is played by theorems, introduced by Rademacher, on the change of variables by so-called "transformations of class K". We transfer these theorems to the theory of Schauder-Sobolev:

THEOREM (Generalization of a theorem of Evans). If $f \in W'_a(G)$ and g(y) = f(x(y)) where x(y) is a regular transformation of domain H on domain G, then $G \in W^1_a(H)$.

THEOREM. Weak convergence is preserved by transformations of class K, i. e. if $f_n \rightarrow f$ on G in $W^1_a(G)$ and x = x(y) is the transformation of class K, of the domain H on G, and if $g_n(y) = f_n(x(y))$ and g(y) = f(x(y)), then $g_n \rightarrow g$ on H in $W^1_a(H)$.

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Invariant subspaces of completely continuous operators in locally convex linear topological spaces

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Recently N. Aronszajn and K. T. Smith [2] have proved the following Theorem. Let X be a Banach space and U a linear completely

continuous operator in X. There exist proper invariant subspaces of U.

The purpose of this note is to prove that any linear completely con-

The purpose of this note is to prove that any linear completely continuous operator in a locally convex linear topological space possesses the same property.

The proof of this statement is based on the above theorem and on a method developed in the paper [1].

Let X be a locally convex linear topological space, i. e. a linear space on which a topology is imposed in such a fashion that the postulated operations of addition and multiplication by real numbers are continuous in the topology. The local convexity means that for every neighbourhood \mathfrak{U}_x of the element $x \in X$ there exists a convex neighbourhood \mathfrak{V}_x such that $\mathfrak{V}_x \subset \mathfrak{U}_x$.

A linear operator U having its domain and range in X is said to be completely continuous if there exists a neighbourhood $\mathfrak V$ of 0 such that the image $U(\mathfrak V)$ is compact in the sense that every infinite subset has a cluster point (i. e. non-isolated point).

It is known (for references see [1]) that the space X is isomorphic to a certain (B_a) -space in which a class of pseudonorms $|x|_{\theta}$, where $\vartheta \in \Phi$, is defined (Φ is an abstract set and $\overline{\Phi} = \mathbf{x}_a$). The system of neighbourhoods of zero consists of the sets of all elements x such that $|x|_{\theta_i} < \varepsilon$ $(i=1,2,\ldots,k), \ \varepsilon > 0$.

LEMMA. Let U be a linear completely continuous operator. Then there exists a pseudonorm $|x| = \sup_i |x|_{\theta_i}$ $(i=1,2,\ldots,n)$ such that for every $\vartheta \in \Phi$ there is a number M_{ϑ} satisfying the inequality $|U(x)|_{\vartheta} \leqslant M_{\vartheta} |x|^1$.

¹⁾ For the proof see [2], p. 196.