Absolute-valued algebras with an involution

by

K. Urbanik (Wrocław)

An algebra A over the real field R is a vector space over R which is closed with respect to a product xy which is linear in both x and y and satisfies the condition $\lambda(xy) = (\lambda x)y = x(\lambda y)$ for any $\lambda \in R$ and $x, y \in A$. The product is not necessarily associative. An algebra is called absolute-valued if it is a normed space under a multiplicative norm $|\cdot|$, i.e. a norm satisfying in addition to the usual requirements the condition |xy| = |x||y| for any x and y. It is known ([3]) that an absolute-valued algebra with a unit element is isomorphic to either the real field, the complex field, the quaternion algebra or the Cayley-Dickson algebra. A. A. Albert ([1]) has previously established this result under the restriction that the algebra is algebraic, in the sense that every element generates a finite-dimensional subalgebra and F. B. Wright ([4]) has shown that an absolute-valued division algebra is algebraic. On the other hand, infinite-dimensional absolute-valued algebras are known ([3]).

An operation * defined on an absolute-valued algebra A is called an *involution* if it satisfies the following conditions:

- (i) $(\lambda x + \mu y)^* = \lambda x^* + \mu y^*$,
- (ii) $x^{**} = x$,
- (iii) $xx^* = x^*x$,
- (iv) $(xy)^* = y^*x^*$,
- (v) $|x^*| = |x|$

for any λ , $\mu \in R$ and $x, y \in A$.

Any absolute-valued algebra which is complete and admits an involution is said to be an absolute-valued *-algebra. Using the well-known process of embedding linear normed spaces in Banach ones, we can prove that any absolute-valued algebra with an involution can be extended to an absolute-valued *-algebra. Therefore we shall be discussing only absolute-valued *-algebras.

As well-known examples of absolute-valued *-algebras we quote the real field and the complex field with the identity transformation as an involution and the complex field, the quaternion algebra and the Cayley-Dickson algebra with the natural involution $(\lambda + \mu i + ...)^* = \lambda$

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 $-\mu i-\dots$ $(\lambda, \mu, \dots \in R)$. Now we shall give simple examples of infinite dimensional absolute-valued *-algebras.

Let X be an infinite dimensional real Hilbert space with an orthonormal basis $\{e_t\}_{t\in T}$. By Zermelo's axiom of choice the set T of indices can be decomposed into three disjoint sets T_1, T_2 , and T_3 such that $1 \leqslant \overline{T}_1 \leqslant \overline{T}_2 = \overline{T}$, where \overline{B} denotes the power of the set B. Let φ be a one-to-one correspondence of the class of all two-point subsets of T (i.e. non-ordered pairs $\{t_1, t_2\}$, where $t_1 \neq t_2$, $t_1, t_2 \in T$) onto the set T_2 . Further, let ψ be a function defined on the set of all ordered pairs $\langle t_1, t_2 \rangle$ ($t_1 \neq t_2, t_1, t_2 \in T$) assuming the values 1 and -1 such that $\psi(\langle t_1, t_2 \rangle) + \psi(\langle t_2, t_1 \rangle) = 0$ both if $t_1, t_2 \in T_1$ and if $t_1, t_2 \notin T_1$ and $\psi(\langle t_1, t_2 \rangle) = 1$ otherwise. For example, if the set T is ordered by a relation \prec , we put $\psi(\langle t_1, t_2 \rangle) = 1$ or -1, whenever $t_1 \prec t_2$ or $t_2 \prec t_1$ respectively and $t_1, t_2 \in T_1$ or $t \in T_1$. Let $\varepsilon(t) = 1$ or -1 according as $t \in T_1$ or $t \notin T_1$.

Let us fix an element $t_0 \in T_1$. It is clear that to define a multiplication and an involution on X it is sufficient to define them on the basis $\{e_i\}_{i \in T}$. We define the multiplication and the involution of elements of the basis by means of the formulas

$$e_t^2 = \varepsilon(t) e_{t_0}, \quad e_{t_1} e_{t_2} = \psi(\langle t_1, t_2 \rangle) e_{\varphi((t_1, t_2))} \quad \text{if} \quad t_1 \neq t_2, \\ e_t^* = \varepsilon(t) e_t.$$

These operations together with the usual addition and scalar-multiplication make X an absolute-valued *-algebra, which will be denoted by $X(T_1, T_2, T_3, \varphi, \psi)$. Indeed, setting (1)

$$x = \sum_{t \in T} \lambda_t e_t, \quad y = \sum_{t \in T} \mu_t e_t$$

we have the equality

where the sum is running over all non-ordered pairs $\{t_1, t_2\}$ satisfying the condition $t_1 \neq t_2$. Hence, taking into account the equality

$$\varepsilon(t_1)\varepsilon(t_2) + \psi(\langle t_1, t_2 \rangle)\psi(\langle t_2, t_1 \rangle) = 0 \qquad (t_1 \neq t_2),$$



 $|xy| = \left[\left(\sum_{t \in T} \lambda_t \mu_t \varepsilon(t) \right)^2 + \sum_{t_1 \neq t_2} \left(\psi(\langle t_1, t_2 \rangle) \lambda_{t_1} \mu_{t_2} + \psi(\langle t_2, t_1 \rangle) \lambda_{t_2} \mu_{t_1} \right)^2 \right]^{1/2}$ $\left(\sum_{t \in T} \gamma^2 \cdot 2^{1/2} \cdot \left(\sum_{t \in T} \gamma^2 \right)^{1/2} \cdot \left(\sum_{t \in T} \gamma^2 \right)^{1/2}$

 $= \left(\sum_{t_1,t_2 \in T} \lambda_{t_1}^2 \mu_{t_2}^2\right)^{1/2} = \left(\sum_{t \in T} \lambda_{t}^2\right)^{1/2} \cdot \left(\sum_{t \in T} \mu_{t}^2\right)^{1/2} = |x| |y|.$

Properties (i), (ii) and (v) of the involution are evident. From (1) we obtain the formula

$$(xy)^* = \left(\sum_{t \in T} \lambda_t \mu_t \varepsilon(t)\right) e_{t_0} + \\ + \sum_{t_1 \neq t_2} \varepsilon(\varphi(\lbrace t_1, t_2 \rbrace)) \left(\psi(\langle t_1, t_2 \rangle) \lambda_{t_1} \mu_{t_2} + \psi(\langle t_2, t_1 \rangle) \lambda_{t_2} \mu_{t_1}\right) e_{\varphi(\langle t_1, t_2 \rangle)},$$

$$y^*x^* = \left(\sum_{t \in T} \lambda_t \mu_t \varepsilon(t)\right) e_{t_0} + \\ + \sum_{t_1 \neq t_2} \left(\psi(\langle t_1, t_2 \rangle) \varepsilon(t_1) \mu_{t_1} \varepsilon(t_2) \lambda_{t_2} + \psi(\langle t_2, t_1 \rangle) \varepsilon(t_2) \mu_{t_2} \varepsilon(t_1) \lambda_{t_1}\right) e_{\varphi(\langle t_1, t_2 \rangle)}.$$

Since, for any $t_1 \neq t_2$, $\varepsilon(t_1)\varepsilon(t_2)\psi(\langle t_1, t_2 \rangle) = -\psi(\langle t_2, t_1 \rangle)$ and $\varepsilon(t_1)\varepsilon(t_2)\psi(\langle t_2, t_1 \rangle) = -\psi(\langle t_1, t_2 \rangle)$, we get the equality $(xy)^* = y^*x^*$. Further, according to the equality

$$\psi(\langle t_1, t_2 \rangle) \varepsilon(t_2) + \psi(\langle t_2, t_1 \rangle) \varepsilon(t_1) = \psi(\langle t_1, t_2 \rangle) \varepsilon(t_1) + \psi(\langle t_2, t_1 \rangle) \varepsilon(t_2)$$
,

we have the formula

$$\begin{split} xx^* &= \left(\sum_{t \in T} \lambda_t^2\right) e_{t_0} + \sum_{t_1 \neq t_2} \lambda_{t_1} \lambda_{t_2} \left(\psi\left(\langle t_1, \ t_2 \rangle\right) \varepsilon\left(t_2\right) + \right. \\ &\left. + \psi\left(\langle t_2, \ t_1 \rangle\right) \varepsilon\left(t_1\right) \right) e_{\varphi\left(\langle t_1, t_2 \rangle\right)} = x^*x \,, \end{split}$$

which completes the proof.

We note that if U is a linear isometry on A which commutes with the involution, then A remains an absolute-valued *-algebra with respect to the new product $x \circ y = U(xy)$. This fact suggests the following definition: two absolute-valued *-algebras A and A' are said to be similar if they are isomorphic as normed spaces with an involution: $A \sim A'$ and the multiplication xy in A is defined in terms of the multiplication $x' \circ y'$ in A' by the relation $xy \sim U(x' \circ y')$, whenever $x \sim x'$, $y \sim y'$, where U is a fixed invertible linear isometry on A' which commutes with the involution.

It is not difficult to prove that two algebras $X(T_1, T_2, T_3, \varphi, \psi)$, $X'(T_1, T_2, T_3, \varphi', \psi')$ are similar if and only if $\overline{T}_1 = \overline{T}_1'$, $\overline{T}_2 = \overline{T}_2'$ and $\overline{T}_3 = \overline{T}_3'$. Therefore we shall call an absolute-valued *-algebra $X(T_1, T_2, T_3, \varphi, \psi)$ a $\langle \mathfrak{m}_1, \mathfrak{m}_2, \mathfrak{m}_3 \rangle$ -algebra, where $\mathfrak{m}_1 = \overline{T}_1$, $\mathfrak{m}_2 = \overline{T}_2$ and $\mathfrak{m}_3 = \overline{T}_3$.

For any pair $x, y \in A$ we set

$$((x,y)) = \frac{1}{2}(xy^* + yx^*).$$

⁽¹⁾ We write $x=\sum_{t\in T}x_t$, if for every positive number ε there exists a finite set $J_0\subset T$ of indices such that $|x-\sum_{t\in J}x_t|<\varepsilon$ whenever J is a finite set of indices containing J_0 .

The operation ((x, y)) will be called a *-product. It imitates an inner product. More precisely, we have the equalities

$$\begin{split} \big((x, \, x) \big) &= 0 \quad \text{if and only if} \quad x = 0 \;, \\ \big((\lambda x_1 + \, \mu x_2 , \, y) \big) &= \lambda \big((x_1, \, y) \big) + \mu \big((x_2, \, y) \big) \;, \\ \big((x, \, y) \big) &= \big((y \, , \, x) \big) \end{split}$$

Moreover, the *-product is invariant under the involution, i.e.

$$\{(x, y)\}^* = \{(x, y)\}.$$

An absolute-valued *-algebra is said to be regular if

(2)
$$((xy, zu)) = ((xz^*, y^*u))$$

for any x, y, z, and u. It is very easy to verify that the real field and the complex field (with $x^* = x$ or $x^* = \overline{x}$) regarded as *-algebras are regular. Now we shall show that all $\langle m_1, m_2, m_3 \rangle$ -algebras are also regular. To prove this it is sufficient to show that all elements of the orthonormal basis $\{e_t\}_{t \in T}$ satisfy equality (2). By the definition of the involution in $\langle m_1, m_2, m_3 \rangle$ -algebras, equality (2) can be written in the following form:

(3)
$$((e_{t_1}e_{t_2}, e_{t_3}e_{t_4})) = \varepsilon(t_2)\,\varepsilon(t_3)\,((e_{t_1}e_{t_3}, e_{t_2}e_{t_4})) \qquad (t_1, t_2, t_3, t_4 \in T) .$$

If $t_2 = t_3$, then the last equality is obvious. Therefore we may suppose that $t_2 \neq t_3$.

If
$$t_1 = t_2$$
 and $t_3 = t_4$, then we have the equalities
$$((e_{t_1}e_{t_2}, e_{t_3}e_{t_4})) = ((e_{t_2}^2, e_{t_3}^2)) = \varepsilon(t_2)\varepsilon(t_3) ((e_{t_0}, e_{t_0})) = \varepsilon(t_2)\varepsilon(t_3) e_{t_0} ,$$

$$((e_{t_1}e_{t_3}, e_{t_2}e_{t_4})) = ((e_{t_2}e_{t_3}, e_{t_2}e_{t_3})) = ((e_{\varphi(\{t_2, t_3\})}, e_{\varphi(\{t_2, t_3\})}))$$

$$= e_{\varphi(\{t_0, t_2\})} e_{\pi(\{t_0, t_2\})}^* = e_{t_0} .$$

which imply formula (3).

If $t_1=t_2$ and $t_3\neq t_4$, then, taking into account the relations $t_0\in T_1$ and $\varphi(\{t_3,t_4\})\notin T_1$, we get the equality

$$\begin{split} \left((e_{t_1} e_{t_2}, \, e_{t_3} e_{t_4}) \right) &= \psi(\langle t_3, \, t_4 \rangle) \left((e_{t_2}^2, \, e_{\varphi(\{t_3, t_4\})}) \right) \\ &= \varepsilon(t_2) \psi(\langle t_3, \, t_4 \rangle) \left((e_{t_0}, \, e_{\varphi(\{t_3, t_4\})}) \right) \\ &= \frac{1}{2} \varepsilon(t_2) \psi(\langle t_3, \, t_4 \rangle) (-e_{t_0} e_{\varphi(\{t_3, t_4\})} + e_{\varphi(\{t_3, t_4\})} e_{t_0}) = 0 \end{split}.$$

Further, if $t_2 = t_4$, we have the formula

$$\begin{split} \left((e_{t_1}e_{t_2},\,e_{t_2}e_{t_4}) \right) &= \left((e_{t_2}e_{t_3},\,e_{t_3}^2) \right) \\ &= \varepsilon\left(t_2 \right) \psi\left(\langle t_2,\,t_3 \rangle \right) \left((e_{\varphi(\{t_2,t_3\}\}},\,e_{t_0}) \right) \\ &= \frac{1}{2} \varepsilon(t_2) \psi\left(\langle t_2,\,t_3 \rangle \right) \left(e_{\varphi(\{t_2,t_3\})},\,e_{t_0} - e_{t_0}e_{\varphi(\{t_2,t_3\})} \right) = 0 \;. \end{split}$$

If $t_2 \neq t_4$, then the relations $\varphi(\{t_2,\,t_3\}) \neq \varphi(\{t_2,\,t_4\}),\, \varphi(\{t_2,\,t_3\}),\, \varphi(\{t_2,\,t_4\}) \notin T_1$ imply the equality

$$e_{\varphi(\{t_2,t_3\})}\,e_{\varphi(\{t_2,t_4\})} = -\,e_{\varphi(\{t_2,t_4\})}\,e_{\varphi(\{t_2,t_3\})}\,.$$



Hence we get the equality

Consequently, equality (3) is proved in the case $t_1 = t_2$ and $t_3 \neq t_4$. The case $t_1 \neq t_2$ and $t_3 = t_4$, in view of the commutativity of *-products, is reduced to the previous case.

Now let us assume that $t_1 = t_3$ and $t_2 = t_4$. Then we have

whence equality (3) follows.

Finally we suppose that $t_1 \neq t_2$, $t_3 \neq t_4$ and $\{t_1, t_2\} \neq \{t_3, t_4\}$. Then taking into account the relation $\varphi(\{t_1, t_2\}), \varphi(\{t_3, t_4\}) \notin T_1$, we have the equality

$$e_{\varphi(\{t_1,t_2\})}e_{\varphi(\{t_3,t_4\})} = -e_{\varphi(\{t_3,t_4\})}e_{\varphi(\{t_1,t_2\})}$$

and, consequently,

$$\begin{split} \big((e_{t_1}e_{t_2},\,e_{t_3}e_{t_4}) \big) &= \psi(\langle t_1,\,t_2 \rangle) \psi(\langle t_3,\,t_4 \rangle) \big((e_{\varphi(\{t_1,t_2\})},\,e_{\varphi(\{t_3,t_4\})}) \big) \\ &= \frac{1}{2} \psi(\langle t_1,\,t_2 \rangle) \psi(\langle t_3,\,t_4 \rangle) \big(-e_{\varphi(\{t_1,t_2\})}e_{\varphi(\{t_3,t_4\})}e_{\varphi(\{t_1,t_2\})} \big) \\ &\qquad \qquad -e_{\varphi(\{t_3,t_4\})}e_{\varphi(\{t_1,t_2\})} \big) = 0 \;. \end{split}$$

If $t_1 \neq t_3$ and $t_2 \neq t_4$, then, in view of the assumption $t_2 \neq t_3$ and $\{t_1, t_2\}$ $\neq \{t_3, t_4\}$, we have the inequality $\{t_1, t_3\} \neq \{t_2, t_4\}$ and

$$\begin{split} \left((e_{i_1}e_{l_3},\,e_{t_2}e_{l_4}) \right) &= \psi(\langle t_1,\,t_3 \rangle) \psi(\langle t_2,\,t_4 \rangle) \left((e_{\varphi(\{l_1,l_2\})},\,e_{\varphi(\{l_2,l_4\})}) \right) \\ &= \frac{1}{2} \psi(\langle t_1,\,t_3 \rangle) \psi(\langle t_2,\,t_4 \rangle) (-e_{\varphi(\{l_1,l_2\})}e_{\varphi(\{l_2,l_4\})} - \\ &- e_{\varphi(\{l_2,l_4\})}e_{\varphi(\{l_1,l_2\})}) = 0 \;. \end{split}$$

If $t_1 = t_3$, then from the assumption $\{t_1, t_2\} \neq \{t_3, t_4\}$ we get the inequality $t_2 \neq t_4$ and, consequently,

$$\begin{aligned} \big((e_{t_1}e_{t_3}, \, e_{t_2}e_{t_4}) \big) &= \big((e_{t_2}^2, \, e_{t_2}e_{t_4}) \big) = \varepsilon(t_3) \, \psi(\langle t_2, \, t_4 \rangle) \big((e_{t_0}, \, e_{\varphi(\langle t_2, t_4 \rangle)}) \big) \\ &= \frac{1}{2} \varepsilon(t_3) \, \psi(\langle t_2, \, t_4 \rangle) \big(-e_{t_0}e_{\varphi(\langle t_2, t_4 \rangle)} + e_{\varphi(\langle t_2, t_4 \rangle)}e_{t_0} \big) = 0 \ . \end{aligned}$$

By the commutativity of the *-product, the case $t_2 = t_4$ is reduced to the previous case. Consequently, equality (3) holds for any system of indices $t_1, t_2, t_3, t_4 \in T$. In other words, we have proved that $\langle m_1, m_2, m_3 \rangle$ -algebras are regular.

We remark that an absolute-valued *-algebra similar to a regular one is also regular.

In the present paper we shall represent regular absolute-valued *-algebras. Namely, we shall prove the following theorem, which is an answer to a problem raised by F. B. Wright.

Theorem. A regular absolute-valued *-algebra is similar to either the real field, the complex field (with $x^*=x$ or $x^*=\overline{x}$) or a $\langle m_1, m_2, m_3 \rangle$ -algebra, where m_1, m_2 and m_3 are cardinals satisfying the inequalities $1 \leqslant m_1 \leqslant m_2$, $m_3 \leqslant m_2$ and $m_2 \geqslant s_0$.

Before proving the theorem we shall prove some lemmas. In the sequel A will denote an absolute-valued *-algebra. By A_a we shall denote the set of all self-adjoint elements of A, i.e. the set of all elements x satisfying the equality $x^* = x$. By A_s we shall denote the set of all skew elements of A, i.e. the set of all elements x satisfying the equality $x^* = -x$. Obviously, both A_a and A_s are linear subspaces of A and $A_a \cap A_s = \{0\}$. It is very easy to prove that every element $x \in A$ may be represented in one and only one manner as the sum $x_1 + x_2$, x_1 and x_2 being self-adjoint and skew respectively. Moreover, the equalities $x_1 = \frac{1}{2}(x + x^*)$ and $x_2 = \frac{1}{2}(x - x^*)$ hold. In other words, A is the direct sum of the subspace A_a and A_s .

LEMMA 1. Self-adjoint elements commute with skew elements.

Proof. Let $x \in A_a$ and $y \in A_s$. By property (iii), we have the equality

$$0 = (x+y)*(x+y) - (x+y)(x+y)*$$

= $(x-y)(x+y) - (x+y)(x-y) = 2(xy-yx),$

which implies the assertion of the Lemma.

LEMMA 2. For any $x \in A_a$ and $y \in A_s$ we have the equality

$$|x+y|^2 = |x|^2 + |y|^2$$
.

Proof. If either x or y is equal to 0, then our statement is obvious. Therefore we may suppose that $x \neq 0$ and $y \neq 0$. Let B be the linear set spanned by x and y. Since $x^* = x$ and $y^* = -y$, B is invariant under the involution. By Lemma 1, the elements of B commute with one another. Therefore for every pair z_1 , z_2 of elements of B we have $(z_1 + z_2)^2 - (z_1 - z_2)^2 = 4z_1z_2$. Consequently, for $|z_1| = |z_2| = 1$, we get the inequality

$$|z_1+z_2|^2+|\,z_1-z_2|^2=[(z_1+z_2)^2]+|(z_1-z_2)^2|\geqslant 4|\,z_1|\,|\,z_2|\,=\,4\;.$$

Hence, according to Schoenberg's Theorem ([2]), B is an inner product space over R. There are then a number λ and an element $y_0 \in B$ orthogonal to x such that $y = \lambda x + y_0$. Since by (v) the involution is an isometry on B, the element y_0^* is also orthogonal to x. From the equality $y = \frac{1}{2}(y - y^*) = \frac{1}{2}(\lambda x + y_0 - \lambda x - y_0) = \frac{1}{2}(y_0 - y_0^*)$ it follows that y and x are orthogonal. The statement of the Lemma is a direct consequence of the orthogonality of x and y.

LEMMA 3. If $A_s \neq \{0\}$, then there exists one and only one idempotent $e \in A_a$ such that

$$x^2 = |x|^2 e$$
, $y^2 = -|y|^2 e$

for any $x \in A_a$ and $y \in A_s$.

Proof. Let $x \in A_a$ and $y \in A_s$. Since, by Lemma 1, x commutes with y, we have the equality $(xy)^* = y^*x^* = -yx = -xy$. Consequently, $xy \in A_s$. Further, we have the equality $(x^2 + y^2)^* = (x^*)^2 + (y^*)^2 = x^2 + y^2$, which implies the relation $x^2 + y^2 \in A_a$. Hence, with the aid of the formula $(x+y)^2 = x^2 + y^2 + 2xy$ as well as Lemma 2, we obtain the following equality

$$|x+y|^4 = |(x+y)^2|^2 = |x^2+y^2|^2 + 4|x|^2|y|^2.$$

But $|x+y|^2 = |x|^2 + |y|^2$ and, consequently, we have the equality

$$(4) \quad |x^2+y^2| = \left((|x|^2+|y|^2)^2-4|x|^2\,|y|^2\right)^{1/2} = \left||x|^2-|y|^2\right| \quad (x\in A_a,\ y\in A_s)\ .$$

By the assumption there exists a skew element y_0 , with $|y_0| = 1$. Putting $e = -y_0^2$, we have $e^* = (-y_0^2)^* = -y_0^2 = e$, |e| = 1 and, in view of (4),

$$|x^2 - |x|^2 e| = |x^2 + (|x|y_0)^2| = ||x|^2 - |x|^2 |y_0|^2| = 0$$

for any $x \in A_a$. Thus

$$(5) x^2 = |x|^2 e (x \in A_a).$$

In particular, $e^2 = e$. The last equality and formula (4) imply the equation

$$||y|^2e + y^2| = |(|y|e)^2 + y^2| = ||y|^2|e|^2 - |y|^2| = 0$$

for any $y \in A_s$. Thus $y^2 = -|y|^2 e$ for all skew elements y. The uniqueness of the idempotent e follows from equality (5). The lemma is thus proved.

LEMMA 4. Every absolute-valued *-algebra with $A_s \neq \{0\}$ is a real Hilbert space.

Proof. Let z_1 , z_2 be a pair of elements of A, with $|z_1| = |z_2| = 1$. Writing $z_1 = x_1 + y_1$, $z_2 = x_2 + y_2$, where x_1 , $x_2 \in A_a$ and y_1 , $y_2 \in A_s$, we have, according to Lemma 2,

(6)
$$|x_1|^2 + |y_1|^2 = 1$$
, $|x_2|^2 + |y_2|^2 = 1$.

Moreover, in view of Lemma 2, we have the equalities

$$|z_1 - z_2|^2 = |x_1 - x_2|^2 + |y_1 - y_2|^2, \quad |z_1 + z_2|^2 = |x_1 + x_2|^2 + |y_1 + y_2|^2.$$

Using Lemma 3 we obtain the inequalities

$$\begin{split} &|x_1-x_2|^2+|x_1+x_2|^2=|(x_1-x_2)^2+|(x_1+x_2)^2|\\ &\geqslant |(x_1-x_2)^2+(x_1+x_2)^2|=2|x_1^2+x_2^2|=2\left|(|x_1|^2+|x_2|^2)\,e\right|=2\left(|x_1|^2+|x_2|^2\right),\\ &|y_1-y_2|^2+|y_1+y_2|^2=|(y_1-y_2)^2|+|(y_1+y_2)^2|\\ &\geqslant |(y_1-y_2)^2+(y_1+y_2)^2|=2|y_1^2+y_2^2|=2\left|-(|y_1|^2+|y_2|^2)\,e\right|=2\left(|y_1|^2+|y_2|^2\right). \end{split}$$

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Hence and from (6) and (7) we get the inequality

$$|z_1-z_2|^2+|z_1+z_2|^2\geqslant 2\left(|x_1|^2+|x_2|^2+|y_1|^2+|y_2|^2\right)=4\;.$$

Thus, according to Schoenberg's Theorem ([2]), we know that A is an inner product space over R and, consequently, a real Hilbert space.

For any $x \in A_a \cup A_s$, $x \neq 0$ we set $\delta(x) = 1$ or -1 according as $x \in A_a$ or $x \in A_s$ and $\delta(0) = 0$.

LEMMA 5. If $A_s \neq \{0\}$, then for any pair of orthogonal elements $x, y \in A_a \cup A_s$ we have the equality

$$xy + \delta(x)\delta(y)yx = 0$$
.

Proof. If $\delta(x)\delta(y)=0$, then our assertion is obvious. Further, if $\delta(x)\delta(y)=-1$, then one element of the pair belongs to A_a and the other belongs to A_s . Consequently, by Lemma 1, xy-yx=0. Now let us suppose that $\delta(x)\delta(y)=1$, i.e. both elements x and y belong to either A_a or A_s . From the orthogonality of x and y and from Lemma 3 we get the equality

$$\begin{split} \left| \delta(x) (|x|^2 + |y|^2) e \right| &= |x|^2 + |y|^2 = |x \pm y|^2 = |(x \pm y)^2| \\ &= |x^2 + y^2 \pm (xy + yx)| = \left| \delta(x) (|x|^2 + |y|^2) e \pm (xy + yx) \right|. \end{split}$$

Hence, xy + yx = 0, which completes the proof of the Lemma.

By (x, y) we shall denote the inner product of two elements x and y $(x, y \in A)$.

LEMMA 6. If $A_s \neq \{0\}$, then for any pair $z_1, z_2 \in A$ we have the equality

$$((z_1, z_2)) = (z_1, z_2) e$$
.

Proof. Let $z_1, z_2 \in A$. Since $A_a \cap A_s = \{0\}$, the subspaces A_a and A_s are orthogonal. Consequently, writing $z_1 = x_1 + y_1$, $z_2 = x_2 + y_2$, where $x_1, x_2 \in A_a$ and $y_1, y_2 \in A_s$ we have the equality

(8)
$$(z_1, z_2) = (x_1, x_2) + (y_1, y_2).$$

Further, since by Lemma 1 self-adjoint elements commute with skew elements, we have the equalities

$$\begin{aligned} \big((x_1, y_2) \big) &= \frac{1}{2} (x_1 y_2^* + y_2 x_1^*) = \frac{1}{2} (-x_1 y_2 + y_2 x_1) = 0 , \\ \big((y_1, x_2) \big) &= \frac{1}{2} (y_1 x_2^* + x_2 y_1^*) = \frac{1}{2} (y_1 x_2 - x_2 y_1) = 0 . \end{aligned}$$

Consequently,

(9)
$$((z_1, z_2)) = ((x_1, x_2)) + ((y_1, y_2)).$$

Let us represent the elements x_2 and y_2 in the form

$$x_2 = \lambda x_1 + x_3, \quad y_2 = \mu y_1 + y_3,$$

where λ and μ are real numbers, x_3 is a self-adjoint element orthogonal to x_1 and y_3 is a skew element orthogonal to y_1 . Obviously, $(x_1, x_2) = \lambda |x_1|^2$, $(y_1, y_2) = \mu |y_1|^2$ and, by Lemma 5, $x_1x_3 + x_3x_1 = 0$, $y_1y_3 + y_3y_1 = 0$. Hence, in view of Lemma 3, we get the equalities

$$\begin{array}{l} \left((x_1,x_2)\right) = \frac{1}{2}(x_1x_2 + x_2x_1) = \frac{1}{2}(\lambda x_1^2 + x_1x_3 + \lambda x_1^2 + x_3x_1) = \lambda |x_1|^2 e = (x_1,x_2) \, e \, , \\ \left((y_1,y_2)\right) = -\frac{1}{2}(y_1y_2 + y_2y_1) = -\frac{1}{2}(\mu y_1^2 + y_1y_3 + \mu y_1^2 + y_3y_1) = \mu |y_1|^2 e = (y_1,y_2) \, e \, . \end{array}$$

Taking into account equalities (8) and (9) we get the assertion of the Lemma.

LEMMA 7. Let A be a regular absolute-valued *-algebra and $A_s \neq \{0\}$. For any system z_1, z_2, z_3, z_4 of orthogonal elements belonging to $A_a \cup A_s$ the products $z_{j_1}z_{j_2}$ and $z_{j_3}z_{j_4}$ are orthogonal, whenever the sets of indices $\{j_1, j_2\}$, $\{j_3, j_4\}$ are different and $j_1 \neq j_2$, $j_3 \neq j_4$ $(j_1, j_2, j_3, j_4 = 1, 2, 3, 4)$.

Proof. First we suppose that $\{j_1, j_2\} \cap \{j_3, j_4\} \neq 0$. Using Lemma 5 we can write

$$(z_{j_1}z_{j_2}, z_{j_3}z_{j_4}) = \pm (z_k z_{s_1}, z_k z_{s_2}),$$

where $s_1 \neq s_2$. Hence and from the equality

$$\begin{split} \langle z_k z_{s_1}, z_k z_{s_2} \rangle &= \tfrac{1}{4} (|z_k z_{s_1} + z_k z_{s_2}|^2 - |z_k z_{s_1} - z_k z_{s_2}|^2) \\ &= \tfrac{1}{4} |z_k|^2 (|z_{s_1} + z_{s_2}|^2 - |z_{s_1} - z_{s_2}|^2) = |z_k|^2 (z_{s_1}, z_{s_2}) = 0 \;, \end{split}$$

we get the orthogonality of $z_{j_1}z_{j_2}$ and $z_{j_3}z_{j_4}$.

Now let us assume that $\{j_1,j_2\} \cap \{j_3,j_4\} = 0$, i.e. the system j_1,j_2,j_3,j_4 is a permutation of 1,2,3,4. Without loss of generality we may suppose that both z_2 and z_3 belong to either A_{α} or A_s . Moreover, we may assume that

(10)
$$\delta(z_1) \neq 0 \quad \text{and} \quad \delta(z_2) \, \delta(z_3) = 1 \,,$$

because in the opposite case $z_1 = 0$, $z_2 = 0$ or $z_3 = 0$ and the orthogonality of $z_{j_1}z_{j_2}$ and $z_{j_3}z_{j_4}$ is evident.

Since the algebra A is regular, we have, according to Lemma 6,

$$(z_{j_1}z_{j_2}, z_{j_3}z_{j_4}) = (z_{j_1}z_{j_3}, z_{j_2}z_{j_4}).$$

Hence and from Lemma 5 it follows that

$$(2j_1z_{j_2}, z_{j_3}z_{j_4}) = \pm (z_1z_2, z_3z_4)$$

for any permutation j_1 , j_2 , j_3 , j_4 of integers 1, 2, 3, 4.

Put $u=(z_2+z_3)(z_1+z_4)$. By the orthogonality of z_1 , z_2 , z_3 and z_4 we have the relation

(12)
$$|u|^2 = (|z_2|^2 + |z_3|^2)(|z_1|^2 + |z_4|^2).$$

Further, from Lemma 5 we infer that all the elements z_2z_1 , z_2z_4 , z_3z_1 and z_3z_4 are skew. Hence we get the equality

$$\begin{split} -u^2 &= \big((z_2 z_1, \, z_2 z_1) \big) + \big((z_2 z_4, \, z_2 z_4) \big) + \big((z_3 z_1, \, z_3 z_1) \big) + \big((z_3 z_4, \, z_3 z_4) \big) + \\ &\quad + 2 \left((z_2 z_1, \, z_2 z_4) \right) + 2 \left((z_2 z_1, \, z_3 z_1) \right) + 2 \left((z_2 z_1, \, z_3 z_4) \right) + \\ &\quad + 2 \left((z_2 z_4, \, z_3 z_1) \right) + 2 \left((z_2 z_4, \, z_3 z_4) \right) + 2 \left((z_3 z_1, \, z_3 z_4) \right). \end{split}$$

Replacing in the last formula, in view of Lemma 6, the *-product by the inner product, we get the equality

$$\begin{aligned} -u^2 &= \left(|z_2|^2 \, |z_1|^2 + |z_2|^2 \, |z_4|^2 + |z_3|^2 \, |z_1|^2 + |z_3|^2 |z_4|^2 + \right. \\ &\quad + 2 \, (z_2 z_1, \, z_2 z_4) + 2 \, (z_2 z_1, \, z_3 z_4) + 2 \, (z_2 z_1, \, z_3 z_4) + \\ &\quad + 2 \, (z_2 z_4, \, z_3 z_4) + 2 \, (z_2 z_4, \, z_3 z_4) + 2 \, (z_3 z_1, \, z_3 z_4) \right) e \, . \end{aligned}$$

Since $u = z_2 z_1 + z_2 z_4 + z_3 z_1 + z_3 z_4$ and, consequently, is a skew element, we have, in virtue of Lemma 3, the equality $-u^2 = |u|^2 e$. Hence and from (12) and (13) we get the relation

$$\begin{split} (z_2z_1,\,z_2z_4) + (z_2z_1,\,z_3z_1) + (z_2z_1,\,z_3z_4) + \\ + (z_2z_4,\,z_3z_1) + (z_2z_4,\,z_3z_4) + (z_3z_1,\,z_3z_4) = 0 \; . \end{split}$$

By the first part of the proof we have the equality

$$(z_2z_1, z_2z_4) = (z_2z_1, z_3z_1) = (z_2z_4, z_3z_4) = (z_3z_1, z_3z_4) = 0$$
.

Thus

$$(14) (z_2 z_1, z_3 z_4) + (z_2 z_4, z_3 z_1) = 0.$$

By Lemma 5, we have the equalities $z_2z_1=-\delta(z_1)\delta(z_2)z_1z_2$, $z_3z_1=-\delta(z_1)\delta(z_3)z_1z_3$. Hence we get the formulas

$$\begin{aligned} (z_2 z_1, z_3 z_4) &= -\delta(z_1) \delta(z_2) (z_1 z_2, z_3 z_4) \,, \\ (z_3 z_1, z_2 z_4) &= -\delta(z_1) \delta(z_3) (z_1 z_3, z_2 z_4) \,. \end{aligned}$$

Further, from the regularity of A it follows that $(z_1z_3, z_2z_4) = (z_1z_2, z_3z_4)$. Consequently, according to (10) and (14), $(z_1z_2, z_3z_4) = 0$. Thus, in view of (11), $z_{j_1}z_{j_2}$ and $z_{j_3}z_{j_4}$ are orthogonal.

Proof of the Theorem. First let us suppose that $A_s = \{0\}$, i.e. the involution is the identity transformation. Taking into account property (iv) of the involution we infer that A is a commutative absolute-valued algebra. Consequently, it is isomorphic to either the real field, the complex field or the algebra of complex numbers with the product of x and y defined as \overline{xy} (see [3]). But the last algebra is similar to the complex field (as an isometry U we take $x \rightarrow \overline{x}$).

Now let us suppose that $A_s \neq \{0\}$. By Lemmas 3 and 4, A is at least a two-dimensional Hilbert space. Let A be finite-dimensional and let $\{e, e_1, e_2, ..., e_n\}$ be an orthonormal basis for A consisting of elements

belonging to $A_a \cup A_s$, where e is the idempotent defined by Lemma 3. If $n \geq 2$, then, by Lemma 7, e_1e_2 is orthogonal to ee_1 , ee_2 , ..., ee_n . Moreover, by Lemma 5, e_1e_2 is a skew element and, consequently, it is orthogonal to e. But the set $\{e, ee_1, ee_2, ..., ee_n\}$ is also a basis for A. Thus $e_1e_2=0$, which is impossible. We have proved that any finite-dimensional absolute-valued *-algebra with a non-trivial involution is two-dimensional. Hence it follows that every element $x \in A$ can be written in the form $x=\lambda e+\mu e_1$, where $e_1\in A_s$, $|e_1|=1$ and λ , $\mu\in R$. Since, by Lemma 5, $ee_1\in A_s$ and $|ee_1|=1$, we have either $ee_1=e_1$ or $ee_1=-e_1$. Further, by Lemma 3, $e_1^2=-e$. Thus A is isomorphic to the complex field if $ee_1=e_1$ and is similar to the complex field if $ee_1=-e_1$ (as an isometry U we take the involution).

Finally let us suppose that A is infinite-dimensional. Let $\{e_i\}_{i\in T}$ be an orthonormal basis of A consisting of elements belonging to $A_a \cup A_s$ and containing the idempotent e defined by Lemma 3. By T_1 we denote the subset of indices such that $\{e_i\}_{i\in T_1}$ is a basis or A_a . Evidently, $\{e_i\}_{i\in T\setminus T_1}$ is a basis of A_s . Let B be the linear subspace spanned by all products $e_{t_1}e_{t_2}$, where $t_1\neq t_2$ and $t_1,t_2\in T$. Since, by Lemmas 1 and 5, all those products are skew, B is a subspace of A_s . Using the axiom of choice, we can decompose the set of indices $T\setminus T_1$ into disjoint sets T_2 and T_3 , where \overline{T}_2 is the dimension of B and \overline{T}_3 is the dimension of the orthogonal complement of B in $A_s(^2)$. By definition, there exists an index $t_0\in T$ such that $e_{t_0}=e$. Further, let φ, ψ be a pair of functions satisfying the requirements given in the definition of $\langle m_1, m_2, m_3 \rangle$ -algebras. To prove our theorem it is sufficient to show that the *-algebra A is similar to the algebra $A(T_1, T_2, T_3, \varphi, \psi)$.

It is very easy to see that the formula $e_{t_1}e_{t_2} \sim \psi(\langle t_1, t_2 \rangle) \, e_{\varphi(\langle t_1, t_2 \rangle)}$ defines a one-to-one correspondence between the family $\{e_{t_1}e_{t_2}\}$ $(t_1 \neq t_2; t_1, t_2 \in T)$, which, by Lemma 7, is an orthonormal basis of B, and the orthonormal family $\{e_i\}_{i \in T_2}$. This correspondence and the identity transformation of A_a can be extended to a unitary transformation U of the whole space A. Obviously, A_a and A_s are invariant under the transformation U. Hence, in particular, it follows that the transformation U commutes with the involution in the algebra $A(T_1, T_2, T_3, \varphi, \psi)$. Denoting by \circ the product in $A(T_1, T_2, T_3, \varphi, \psi)$ we have the equalities

$$\begin{split} U(e_t \circ e_t) &= U\left(\varepsilon(t)\,e\right) = \varepsilon(t)\,e = e_t^2 \qquad (t \, \epsilon \, T) \, , \\ U(e_{t_1} \circ e_{t_2}) &= U\left(\psi(\langle t_1, t_2 \rangle)\,e_{\phi(\{t_1, t_2\})}\right) = e_{t_1}e_{t_2} \qquad (t_1 \neq t_2 \, ; \, t_1, \, t_2 \, \epsilon \, T) \, . \end{split}$$

Consequently, $U(x \circ y) = xy$ for any x and y in A. In other words, the algebras A and $A(T_1, T_2, T_3, \varphi, \psi)$ are similar.

⁽²⁾ The dimension of a subspace B is the power of its basis.

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Nilpotent free groups

by

A. Włodzimierz Mostowski (Warszawa)

The following theorem, proved by A. I. Malcev in [3], will be denoted further by (M).

(M) Let G be a nilpotent free group of class c, and X a subset of G of the cardinality |X| > 1. Then X is a nilpotent free generating system for some subgroup of G, of the same class c, if and only if X is linearly independent modulo the derived subgroup G'.

This paper consists of two parts. The first is devoted to a group theoretical proof of (M). The proof is based on the following theorem.

(T) If $x_1, ..., x_i, ...$ is a free, or nilpotent free, generating system of a free, or nilpotent free, group G, then a system $x_1^{n_1} \cdot x_1', ..., x_i^{n_i} \cdot x_i', ...$ is free, or nilpotent free, for any $x_i' \in G'$, and for any positive integers n_i .

The proof of (T) essentially needs M. Hall's theory of basic commutators exposed, for example, in [1].

The second part contains theorems that can be derived from (M):

THEOREM 1. A subgroup H of a nilpotent free group G is a nilpotent free group if and only if it satisfies the condition $H' = H \cap G'$ or is a cyclic group. (H' and G' are the derived subgroups of H and G.)

THEOREM 2. Every retract of a nilpotent free group G, is a nilpotent free factor of G and a nilpotent free subgroup of G.

The analogous statement fails for retracts of free or solvable free groups, see [4].

THEOREM 3. An endomorphism of a nilpotent free group G is an automorphism of that group if and only if it induces an automorphism of G/G'.

The terminology of the paper is the same as that in the book of M. Hall [1]. Some basic notions concerning varieties of nilpotent groups are listed in an introductory part. They can be found partly in papers [2], [5] and [6], and partly in the book quoted.

1. We define recursively the simple commutators as: $(x_1) = x_1$, $(x_1, x_2) = x_1^{-1} \cdot x_2^{-1} \cdot x_1 \cdot x_2$, and $(x_1, ..., x_{n+1}) = ((x_1, ..., x_n), x_{n+1})$. A group